

Project Skynet

Software Code : Project_Skynet/FormControl.cs



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```
using System;
using System.Collections.Generic;
using System.ComponentModel;
using System.Data;
using System.Drawing;
using System.Linq;
using System.Text;
using System.Threading.Tasks;
using System.Windows.Forms;
using System.IO.Ports;

namespace Project_Skynet
{
    public partial class FormControl : Form
    {
        FormMain frmM = null;
        int AmmoLeft = 400;
        public FormControl(FormMain frmM)
        {
            this.frmM = frmM; //form main control
            this.Hide();
            InitializeComponent();
        }

        private void FormControl_Load(object sender, EventArgs e)
        {
            try
            {

                prg_Ammo.Maximum = 400;
                prg_Ammo.Value = 400;
                prg_Overheat.Maximum = 35;
                btn_LowAmmo.Visible = false;

                serialPort1.PortName = this.frmM.Text;
                serialPort1.BaudRate = 57600;
                serialPort1.Open();

                txt_Status.Text = "Status = StandBy";

                if (serialPort1.IsOpen)
                {
                    this.Show();
                }
                else //when serial is not connected
                {
                    MessageBox.Show("Cannot Connect");
                    this.Show();
                }
            }
            catch (Exception ex)
            {
            }
        }
    }
}
```

```
this.frmM.redscreen();
this.frmM.WriteCMD(Environment.NewLine + "ERROR >> " + ex.Message);
    }
}

#region Normal Events

private void txt_CMD_KeyDown(object sender, KeyEventArgs e)
{
    try
    {
        if (e.KeyCode == Keys.Up)
        {
            Write("u", "");
            btn_Up.ForeColor = Color.Lime;
        }
        if (e.KeyCode == Keys.Down)
        {
            Write("d", "");
            btn_Down.ForeColor = Color.Lime;
        }
        if (e.KeyCode == Keys.Left)
        {
            Write("e", "");
            btn_Left.ForeColor = Color.Lime;
        }
        if (e.KeyCode == Keys.Right)
        {
            Write("t", "");
            btn_Right.ForeColor = Color.Lime;
        }
        if (e.KeyCode == Keys.Space)
        {
            Fire();
        }
        ///////////////////////////////////
    }
    catch (Exception ex)
    {
        this.frmM.redscreen();
        this.frmM.WriteCMD(Environment.NewLine + "ERROR >> " + ex.Message);
    }
}

#endregion

private void txt_CMD_KeyUp(object sender, KeyEventArgs e)
{
    try
    {
        if (e.KeyCode == Keys.Up || e.KeyCode == Keys.Down || e.KeyCode ==
            Keys.Left || e.KeyCode == Keys.Right)
        {
            KeyReset();
        }
    }
}
```

```
    }
    else if (e.KeyCode == Keys.Space)
    {
        Write("f", "");
        timer_Ammo.Stop();
        prg_Overheat.Value = 0;
        if (AmmoLeft <= 30)
        {
            txt_CMD.AppendText(Environment.NewLine + "Ammo Low");
        }
    }
}
catch (Exception ex)
{
    this.frmM.redscreen();
    this.frmM.WriteCMD(Environment.NewLine + "ERROR >> " + ex.Message);
}
}
```

```
private void btn_ScanOn_Click(object sender, EventArgs e)
{
    try
    {
        Write("S", "Scan Mode Activated");
        btn_ScanOff.BackColor = Color.DarkGray;
        btn_ScanOn.BackColor = Color.Lime;
    }
    catch (Exception ex)
    {
        this.frmM.redscreen();
        this.frmM.WriteCMD(Environment.NewLine + "ERROR >> " + ex.Message);
    }
}
```

```
private void btn_ScanOff_Click(object sender, EventArgs e)
{
    try
    {
        Write("s", "Scan Mode Deactivated");
        btn_ScanOn.BackColor = Color.DarkGray;
        btn_ScanOff.BackColor = Color.Lime;
    }
    catch (Exception ex)
    {
        this.frmM.redscreen();
        this.frmM.WriteCMD(Environment.NewLine + "ERROR >> " + ex.Message);
    }
}
```

```
private void btn_LaserOn_Click(object sender, EventArgs e)
{
    try
```

```
{
    Write("Z", "Laser : ON");
    btn_LaserOff.BackColor = Color.DarkGray;
    btn_LaserOn.BackColor = Color.Lime;
}
catch (Exception ex)
{
    this.frmM.redscreen();
    this.frmM.WriteCMD(Environment.NewLine + "ERROR >> " + ex.Message);
}
}

private void btn_LaserOff_Click(object sender, EventArgs e)
{
    try
    {
        Write("z", "Laser = OFF");
        btn_LaserOn.BackColor = Color.DarkGray;
        btn_LaserOff.BackColor = Color.Lime;
    }
    catch (Exception ex)
    {
        this.frmM.redscreen();
        this.frmM.WriteCMD(Environment.NewLine + "ERROR >> " + ex.Message);
    }
}

private void btn_LightOn_Click(object sender, EventArgs e)
{
    try
    {
        Write("L", "Lights : ON");
        btn_LightOff.BackColor = Color.DarkGray;
        btn_LightOn.BackColor = Color.Lime;
    }
    catch (Exception ex)
    {
        this.frmM.redscreen();
        this.frmM.WriteCMD(Environment.NewLine + "ERROR >> " + ex.Message);
    }
}

private void btn_LightOff_Click(object sender, EventArgs e)
{
    try
    {
        Write("l", "Lights : OFF");
        btn_LightOn.BackColor = Color.DarkGray;
        btn_LightOff.BackColor = Color.Lime;
    }
    catch (Exception ex)
    {
        this.frmM.redscreen();
    }
}
```



```
        this.frmM.WriteCMD(Environment.NewLine + "ERROR >> " + ex.Message);
    }
}

private void btn_ReloadOn_Click(object sender, EventArgs e)
{
    try
    {
        Write("R", "Reload Mode Activated");
        btn_ReloadOff.BackColor = Color.DarkGray;
        btn_ReloadOn.BackColor = Color.Lime;
    }
    catch (Exception ex)
    {
        this.frmM.redscreen();
        this.frmM.WriteCMD(Environment.NewLine + "ERROR >> " + ex.Message);
    }
}

private void btn_ReloadOff_Click(object sender, EventArgs e)
{
    try
    {
        Write("r", "Reload Mode Deactivated");
        btn_ReloadOn.BackColor = Color.DarkGray;
        btn_ReloadOff.BackColor = Color.Lime;
    }
    catch (Exception ex)
    {
        this.frmM.redscreen();
        this.frmM.WriteCMD(Environment.NewLine + "ERROR >> " + ex.Message);
    }
}

private void btn_Manual_Click(object sender, EventArgs e)
{
    try
    {
        Write("M", "Firing Mode Set To : MANUAL");
        btn_Auto.BackColor = Color.DarkGray;
        btn_Manual.BackColor = Color.Lime;
    }
    catch (Exception ex)
    {
        this.frmM.redscreen();
        this.frmM.WriteCMD(Environment.NewLine + "ERROR >> " + ex.Message);
    }
}

private void btn_Auto_Click(object sender, EventArgs e)
{
    try
    {
```

```
        Write("A", "Firing Mode Set To : AUTO");
        btn_Manual.BackColor = Color.DarkGray;
        btn_Auto.BackColor = Color.Lime;
    }
    catch (Exception ex)
    {
        this.frmM.redscreen();
        this.frmM.WriteCMD(Environment.NewLine + "ERROR >> " + ex.Message);
    }
}

private void Fire()
{
    try
    {
        Write("F", "Firing");
        txt_Status.ForeColor = Color.Red;
        txt_Status.Text = "Status = FIRING";
        timer_Ammo.Interval = 200;
        timer_Ammo.Start();
    }
    catch (Exception ex)
    {
        this.frmM.redscreen();
        this.frmM.WriteCMD(Environment.NewLine + "ERROR >> " + ex.Message);
    }
}

private void KeyReset() //sets all keys to darkgray
{
    btn_Up.ForeColor = Color.DarkGray;
    btn_Down.ForeColor = Color.DarkGray;
    btn_Left.ForeColor = Color.DarkGray;
    btn_Right.ForeColor = Color.DarkGray;
}

public void Write(string a, string b) //sends char by serial and prints string
to txt_CMD
{
    try
    {
        if (this.frmM.CheckPrgMode() == 1)
        {
            serialPort1.Write(a);
            this.frmM.WriteSerial(a);
            txt_Serial.AppendText(Environment.NewLine + DateTime.Now + ">>" +
b);

            if (b != "")
            {
                txt_CMD.AppendText(Environment.NewLine + b);
            }
            else //if b == "" ignore -->for up,down,left,right btns.

```

```
{
    }
}
else
{
    //ignore
}
}
catch (Exception ex)
{
    if (this.frmM.z == 1) //Programming Mode On
    {
        //ignore
    }
    else if (this.frmM.z == 0) //Programming Mode Off
    {
        this.frmM.redscreen();

        this.frmM.WriteCMD(Environment.NewLine + "ERROR >> " + ex.Message);
    }
}
}

public void Disconn() //FormMain.Disconnect button
{
    serialPort1.Close();
    this.frmM.WriteCMD("Serial Disconnected");
}

private void timer_Ammo_Tick(object sender, EventArgs e)
{
    try
    {
        prg_Ammo.Value--;
        prg_Overheat.Value += 3;
        AmmoLeft--;
        txt_Ammo.Text = AmmoLeft.ToString();
        if (AmmoLeft <= 0)
        {
            btn_LowAmmo.Visible = true;
        }
        if (prg_Overheat.Value >= 30)
        {
            Write("f", "");
            txt_CMD.AppendText(Environment.NewLine + "Turret Overheated >>
            Cooling. . .");
            timer_Ammo.Stop();
        }
    }
}
catch (Exception Ex)
```



```
    {  
        txt_CMD.AppendText(Environment.NewLine + Ex Message).  
    }  
}  
}
```