# yler N. **Morrison**

### Graduate Research Assistant | PhD Candidate

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### Education



#### The Ohio State University

Ph.D. Candidate in Mechanical Engineering

- GPA: 4.00/4.00
- Dissertation: Computational Design Methods for Compliant Robotic Ankle Prostheses
- Distinguished University Fellow



#### The University of Tulsa

B.S. Mechanical Engineering

- GPA: 4.00/4.00
- Chapman Presidential Scholar
- Vision Scholar



Columbus, OH, USA

Tulsa, OK, USA

Aug. 2013 — May 2017

Aug. 2017 — estim. Dec. 2021

### **Experience**

### Design, Innovation and Simulation Lab (DISL)

The Ohio State University, Columbus, OH

August 2017 — Present Graduate Research Assistant • Developed simulation tools for powered ankle prosthesis design using trajectory optimization for human gait adaptation prediction.

Modeled, tested, and analyzed variable stiffness robotic arm links for use in physical human-robot interaction.

- Developed software for, planned, conducted, analyzed, and interpreted experiments for interdisciplinary research on attention to preview in human drivers.
- Mentored high school, undergraduate, and MS student research projects.
- Administered and maintained lab server and rapid-prototyping equipment.
- Communicated research findings in conference sessions, workshops, and in published peer-reviewed journal articles.
- Peer-reviewed journal articles for multiple international journals and conferences.

#### NSF Interfaces and Surfaces REU

Clemson University, Clemson, SC

**REU Research Assistant** • Conducted numerical simulations of hydrogel membranes under illumination.

Modeled and implemented code for numerical simulation of magnetically heated gels with cooling effects.

Mentored incoming MS student on simulation software and high-performance-computing.

#### **Biological Robotics at Tulsa Lab (BRAT Lab)**

The University of Tulsa, Tulsa, OK

*May 2015 — July 2017* 

*May 2016 — August 2016* 

Undergraduate Research Assistant

- Pursued independent research on grasping and manipulation with quadruped robots.
- Developed optimal foot-shuffle algorithm for quadruped stabilization under disturbances and body-position constraints.
- Developed interactive software to model quadruped kinematics and tip-over stability.

### The Tulsa Children's Museum Mechanical Engineering Senior Project

Tulsa, OK

• Team designed and built a 15 foot steel auger ball-lift system for an exhibit at the children's museum.

• Elected project MVP. Our project was voted second best by our class.

Video of the project before it was installed in the museum: https://youtu.be/jlg1ikz-zHM

#### The University of Tulsa Mechanical Engineering Department

Student Grader

Tulsa, OK, USA

Spring 2016 — Spring 2017

October 2016 — May 2017

Mechanics of Materials (ME 3023); Instrumentation and Measurement (ME 3053)

### Burns and McDonnell — Aviation and Federal Division

Kansas City, MO

Mechanical Engineering Intern

Summer 2015

 Assisted in designing HVAC and plumbing systems at Tinker Air Force Base, Portland International Airport, the Sampson School at Guantanamo Bay Naval Base, and the Kansas City National Security Campus.

### **Journal Articles**

**Tyler Morrison**, Richard Jagacinski, Jordan Petrov. *Drivers' Attention to Preview and Its Momentary Persistence*. 2021. «In Review».

**Tyler Morrison**, Emanuele Rizzi, Omer Turkkan, Richard Jagacinski, Hai-Jun Su, Junmin Wang. *Drivers' Spatio-Temporal Attentional Distributions Are Influenced by Vehicle Dynamics and Displayed Point of View*. Human Factors. 2021. «Published». DOI: 10.1177/0018720820902879

**Tyler Morrison**, Hai-Jun Su. *Stiffness Modeling of a Variable Stiffness Compliant Link*. Mechanism and Machine Theory. 2020. «Published». DOI: 10.1016/j.mechmachtheory.2020.104021

Richard Jagacinski, Emanuele Rizzi, Benjamin Bloom, Omer Turkkan, **Tyler Morrison**, Hai-Jun Su, Junmin Wang. *Drivers' Attentional Instability on a Winding Roadway*. IEEE Transactions on Human-Machine Systems. 2019. «Published». DOI: 10.1109/THMS.2019.2906612

Oksana Savchak, Konstantin Kornev, **Tyler Morrison**, Olga Kuksenok. *Controlling Deformations of Gel-based Composites by Electromagnetic Signals within GHz Frequency Range*. Soft Matter. 2018. «Published». DOI: 10.1039/C8SM01207E

# **Conference Papers**

**Tyler Morrison**, Hai-Jun Su. *Human Walking Gait Prediction For Design Evaluation of Complex Robotic Lower-Limb Prostheses*. 2022. «Submitted».

**Tyler Morrison**, Dylan Trainor, Hai-Jun Su. *Optimization of the Compliant Drive Mechanism for a Prosthetic Ankle*. ASME IDETC-CIE. *St. Louis, MO, USA*. August 2020. «Published». DOI: 10.1115/DETC2020-22442

**Tyler Morrison**, Chunhui Li, Xu Pei, Hai-Jun Su. *A Novel Rotating Beam Link for Variable Stiffness Robotics Arms*. IEEE International Conference on Robotics and Automation. *Montreal, CA*. May 2019. «Published». DOI: 10.1109/ICRA.2019.8793833

### **Research Presentations**

**Tyler Morrison**, Richard Jagacinski, Jordan Petrov. *Attention and Visual Sensory Memory in Simulated Driving*. Psychonomic Society Annual Meeting. *Virtual*. November 2021. «Oral».

**Tyler Morrison**, Richard Jagacinski, Jordan Petrov. *Measuring the Range of Attention to Preview and Its Momentary Persistence in Simulated Driving*. International Symposium on Aviation Psychology. *Oregon State University*. May 2021. «Oral».

Richard Jagacinski, Emanuele Rizzi, Benjamin Bloom, O. Anil Turkkan, **Tyler Morrison**, Hai-Jun Su, Junmin Wang. *The shape of attention when tracking a winding roadway*. Midwest Cognitive Science Conference. *Columbus*, *OH*. May 2019. «Oral».

Xianpai Xeng, **Tyler Morrison**, Hai-Jun Su. *Mechanical Solutions to Variable Stiffness Robotic Arms*. IEEE ICRA Workshop on Physical Human-Robot Interaction. *Montreal, CA*. May 2019. «Poster + Oral».

**Tyler Morrison**, Joshua Schultz. *Optimal shuffles to prevent quadruped tipover during cooperation*. Robotics: Science and Systems Workshop on Design and Control of Small Legged Robots. *Pittsburgh, PA, USA*. June 2018. «Poster + Oral».

Oksana Sachak, Yao Xiong, **Tyler Morrison**, Konstantin Kornev, Olga Kuksenok. *Magnonics in hydrogels: modeling and magne-tomechanical effects in GHz frequency range*. MRS Spring Meeting: Computer-Based Modeling and Experiment for the Design of Soft Materials Symposium. *Phoenix, AZ, USA*. April 2017. «Oral».

### **Honors & Awards**

### Graduate

2017 2017	Distinguished University Fellow, The Ohio State University  Department Supplementary Fellowship Award, The Ohio State University	Columbus, OH, USA Columbus, OH, USA
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2017	College of Engineering and Natural Sciences Steven J. Bellovich Medal, The University of Tulsa	Tulsa, OK, USA
2017	Sidney Born Award in Mechanical Engineering, The University of Tulsa	Tulsa, OK, USA
2017	Senior Project - Most Valuable Team Member, The University of Tulsa, Mech. Eng. Dept.	Tulsa, OK, USA
2016	Putnam Competition Team Member, The University of Tulsa, Math Dept.	Tulsa, OK, USA
2017	Best Senior Project Team: Runner-Up, The University of Tulsa Mechanical Engineering Senior	Tulsa, OK, USA
2016	Projects  Naminae National Bayer Coldwater Scholarship. The University of Tyles	Tulas OK LICA
2016	Nominee, National Barry Goldwater Scholarship, The University of Tulsa	Tulsa, OK, USA
2013 —	President's Honor Roll, The University of Tulsa	Tulsa, OK, USA
2017		, ,
2013	National Merit Finalist, National Merit Scholarship Corporation	
2013	Presidential Scholar, The University of Tulsa	Tulsa, OK, USA

#### Other

2011 **Eagle Scout**, Boy Scouts of America

Kansas, USA

### **Selected Graduate Coursework**

**Robotics/Al** Machine Learning for Engineers – Mechanical Control of Robots – Design of Smart Products

**Design** Advanced Kinematics and Mechanisms – Optimal Design of Structures – Form Synthesis and Analysis **Control** Lumped Parameter Systems – Digital Control Engineering – Design and Control of Mechatronic Systems

# Skills and Previous Experience.

**Programming** MATLAB, Python, Java, C/C++, Mathematica, Powershell, LaTeX, Git, GitHub,

CasADi, Ipopt, Visual Studio, Cmake, make

Modeling & Design Software Solidworks, AutoCAD, Adobe Illustrator, Revit

**Simulation** OpenSim, ANSYS, ABAQUS, Solidworks Simulation, SPSS

Hardware Arduino, Raspberry Pi, DC Motors, Lidar, Basic Circuit Design, Compliant Mechanisms

**Rapid Prototyping** 3D-Printing, Laser Cutting, Plasma Cutting

**Algorithms** Fourier Analysis, Wavelet Analysis, Regression, Machine Learning,

Trajectory Optimization, Nonlinear Programming

Misc. Experiment Design, Debugging, Code Optimization, Parallel Computing, Research Ethics

## **Other Presentations**

Abdulhamid Aljaber, Sultan Al-Nabhani, Nick Criser, Brian Hall, Joel Kapp, **Tyler Morrison**, Drake Norman, Alex Price, Tommy Weissert. *The Tulsa Children's Museum Petroleum Exhibit Ball Lift*. The University of Tulsa Senior Projects. *Tulsa, OK, USA*. April 2017. «Oral».

Brian Hall, **Tyler Morrison**, Alex Price. *The Tulsa Children's Museum Auger Ball Lift*. The University of Tulsa Department of Mechanical Engineering Advisory Board Meeting. *Tulsa*, *OK*, *USA*. March 2017. «Oral».

**Tyler Morrison**, Joshua Schultz. *Algorithms for Shuffling Foot Placements to Maintain Stability of a Quadruped Robot Engaged in a Cooperative Task*. The University of Tulsa Student Research Colloquium Mechanical: Engineering Session. *Tulsa, OK, USA*. March 2017. «Oral».

**Tyler Morrison**, Olga Kuksenok. *Numerical Simulations of NIPA Gel Membranes Exposed to Heat and Light*. Clemson Undergraduate Research Symposium. *Clemson, SC, USA*. July 2016. «Poster».

Tyler Morrison, Joshua Schultz. Investigation into Coordinated Gaits of Quadruped Robots Engaged in Grasping and Manipulation with Applications in Search and Rescue. The University of Tulsa Student Research Colloquium: Mechanical Engineering Session. Tulsa, OK, USA. March 2016. «Oral».

# Extracurricular Activity \_\_\_\_\_

Tau Beta Pi Tulsa, OK, USA

Involved Member of Oklahoma Beta Chapter

• Helped lead initiation of new members and organize induction ceremonies and fellowship activities.

#### **Mathematical Association of America Putnam Competition**

Tulsa, OK, USA

2015 - 2017

University of Tulsa Team Member and Individual Competitor

2014, 2015

• Personal best score of 11, ranks in top 21% of mathematicians in North America. (World-wide median score is zero points).

#### **Boy Scouts of America**

Kansas City, KS, USA

**Eagle Scout** 

2001 — 2013

- Eagle Scout service project: leading and organizing a team to build bookshelves for a library system for a local children's home.
  Member of U.S. BSA delegation to the 2011 World Scout Jamboree in Sweden.

### Attended Conferences

- International Symposium on Aviation Psychology; May 18-21, 2021; Online
- ASME IDETC-CIE; August 17-19, 2020; Online
- IEEE International Conference on Robotics and Automation; May 20-24, 2019; Montreal, QC, CA
- Robotics: Science and Systems; June 26-30, 2018; Pittsburgh, PA, USA

### Peer-Review Assistance\_

• IROS 2018, Mechanism and Machine Theory, RoboSoft 2020

### Passions \_\_\_

• Running and Biking, Dog Fostering and Training, Medical Spouse