dog_app

December 28, 2020

1 Convolutional Neural Networks

1.1 Project: Write an Algorithm for a Dog Identification App

In this notebook, some template code has already been provided for you, and you will need to implement additional functionality to successfully complete this project. You will not need to modify the included code beyond what is requested. Sections that begin with '(IMPLEMENTATION)' in the header indicate that the following block of code will require additional functionality which you must provide. Instructions will be provided for each section, and the specifics of the implementation are marked in the code block with a 'TODO' statement. Please be sure to read the instructions carefully!

Note: Once you have completed all of the code implementations, you need to finalize your work by exporting the Jupyter Notebook as an HTML document. Before exporting the notebook to html, all of the code cells need to have been run so that reviewers can see the final implementation and output. You can then export the notebook by using the menu above and navigating to **File -> Download as -> HTML (.html)**. Include the finished document along with this notebook as your submission.

In addition to implementing code, there will be questions that you must answer which relate to the project and your implementation. Each section where you will answer a question is preceded by a 'Question X' header. Carefully read each question and provide thorough answers in the following text boxes that begin with 'Answer:'. Your project submission will be evaluated based on your answers to each of the questions and the implementation you provide.

Note: Code and Markdown cells can be executed using the **Shift + Enter** keyboard shortcut. Markdown cells can be edited by double-clicking the cell to enter edit mode.

The rubric contains *optional* "Stand Out Suggestions" for enhancing the project beyond the minimum requirements. If you decide to pursue the "Stand Out Suggestions", you should include the code in this Jupyter notebook.

Step 0: Import Datasets

Make sure that you've downloaded the required human and dog datasets:

Note: if you are using the Udacity workspace, you *DO NOT* need to re-download these - they can be found in the /data folder as noted in the cell below.

- Download the dog dataset. Unzip the folder and place it in this project's home directory, at the location /dog_images.
- Download the human dataset. Unzip the folder and place it in the home directory, at location /lfw.

Note: If you are using a Windows machine, you are encouraged to use 7zip to extract the folder. In the code cell below, we save the file paths for both the human (LFW) dataset and dog dataset in the numpy arrays human_files and dog_files.

Step 1: Detect Humans

In this section, we use OpenCV's implementation of Haar feature-based cascade classifiers to detect human faces in images.

OpenCV provides many pre-trained face detectors, stored as XML files on github. We have downloaded one of these detectors and stored it in the haarcascades directory. In the next code cell, we demonstrate how to use this detector to find human faces in a sample image.

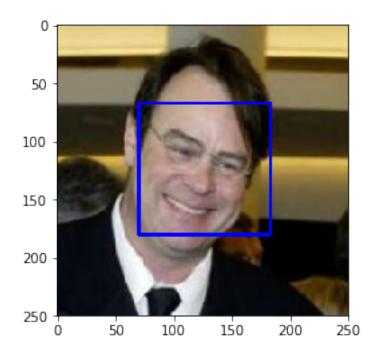
```
In [44]: import cv2
    import matplotlib.pyplot as plt
    %matplotlib inline

# extract pre-trained face detector
    face_cascade = cv2.CascadeClassifier('haarcascades/haarcascade_frontalface_alt.xml')

# load color (BGR) image
    img = cv2.imread(human_files[0])
    # convert BGR image to grayscale
    gray = cv2.cvtColor(img, cv2.COLOR_BGR2GRAY)

# find faces in image
```

Number of faces detected: 1



Before using any of the face detectors, it is standard procedure to convert the images to grayscale. The detectMultiScale function executes the classifier stored in face_cascade and takes the grayscale image as a parameter.

In the above code, faces is a numpy array of detected faces, where each row corresponds to a detected face. Each detected face is a 1D array with four entries that specifies the bounding box of the detected face. The first two entries in the array (extracted in the above code as x and y) specify the horizontal and vertical positions of the top left corner of the bounding box. The last two entries in the array (extracted here as w and h) specify the width and height of the box.

1.1.1 Write a Human Face Detector

We can use this procedure to write a function that returns True if a human face is detected in an image and False otherwise. This function, aptly named face_detector, takes a string-valued file path to an image as input and appears in the code block below.

1.1.2 (IMPLEMENTATION) Assess the Human Face Detector

Question 1: Use the code cell below to test the performance of the face_detector function.

- What percentage of the first 100 images in human_files have a detected human face?
- What percentage of the first 100 images in dog_files have a detected human face?

Ideally, we would like 100% of human images with a detected face and 0% of dog images with a detected face. You will see that our algorithm falls short of this goal, but still gives acceptable performance. We extract the file paths for the first 100 images from each of the datasets and store them in the numpy arrays human_files_short and dog_files_short.

Answer:

Percentage of detected human faces in human_files_short 99.0% Percentage of detected human faces in dog_files_short 18.0%

```
In [4]: from tqdm import tqdm
        human_files_short = human_files[:100]
        dog_files_short = dog_files[:100]
        #-#-# Do NOT modify the code above this line. #-#-#
        ## TODO: Test the performance of the face_detector algorithm
        ## on the images in human_files_short and dog_files_short.
        human_files_short_human_face_count = 0
        dog_files_short_human_face_count = 0
        for human_img in human_files_short:
            if face_detector(human_img):
                human_files_short_human_face_count += 1
        for dog_img in dog_files_short:
            if face_detector(dog_img):
                dog_files_short_human_face_count += 1
        print(f"Percentage of detected human faces in human_files_short "
              f"{human_files_short_human_face_count/len(human_files_short) * 100}% \n"
```

```
f"Percentage of detected human faces in dog_files_short "
f"{dog_files_short_human_face_count/len(dog_files_short) * 100}%")
Percentage of detected human faces in human_files_short 99.0%
Percentage of detected human faces in dog_files_short 18.0%
```

We suggest the face detector from OpenCV as a potential way to detect human images in your algorithm, but you are free to explore other approaches, especially approaches that make use of deep learning:). Please use the code cell below to design and test your own face detection algorithm. If you decide to pursue this *optional* task, report performance on human_files_short and dog_files_short.

```
In [5]: ### (Optional)
        ### TODO: Test performance of anotherface detection algorithm.
        ### Feel free to use as many code cells as needed.
        face_cascade_default = cv2.CascadeClassifier('haarcascades/haarcascade_frontalface_defau
        # returns "True" if face is detected in image stored at img_path
        def face_detector_default(img_path):
            img = cv2.imread(img_path)
            gray = cv2.cvtColor(img, cv2.COLOR_BGR2GRAY)
            faces = face_cascade_default.detectMultiScale(gray)
            return len(faces) > 0
        human_files_short_human_face_count_default = 0
        dog_files_short_human_face_count_default = 0
        for human_img in human_files_short:
            if face_detector_default(human_img):
                human_files_short_human_face_count_default += 1
        for dog_img in dog_files_short:
            if face_detector_default(dog_img):
                dog_files_short_human_face_count_default += 1
        print(f"Percentage of detected human faces in human_files_short with haarcascade_frontal
              f"{human_files_short_human_face_count_default/len(human_files_short) * 100}% \n"
              f"Percentage of detected human faces in dog_files_short with haarcascade_frontalfa
              f"{dog_files_short_human_face_count_default/len(dog_files_short) * 100}%")
```

Percentage of detected human faces in human_files_short with haarcascade_frontalface_default 100 Percentage of detected human faces in dog_files_short with haarcascade_frontalface_default 51.0%

In this section, we use a pre-trained model to detect dogs in images.

^{##} Step 2: Detect Dogs

1.1.3 Obtain Pre-trained VGG-16 Model

The code cell below downloads the VGG-16 model, along with weights that have been trained on ImageNet, a very large, very popular dataset used for image classification and other vision tasks. ImageNet contains over 10 million URLs, each linking to an image containing an object from one of 1000 categories.

```
In [35]: import torch
    import torchvision.models as models

# define VGG16 model
    VGG16 = models.vgg16(pretrained=True)

# check if CUDA is available
    use_cuda = torch.cuda.is_available()

# move model to GPU if CUDA is available
    if use_cuda:
        VGG16 = VGG16.cuda()
```

Downloading: "https://download.pytorch.org/models/vgg16-397923af.pth" to /root/.torch/models/vgg100%|| 553433881/553433881 [00:20<00:00, 26545950.13it/s]

Given an image, this pre-trained VGG-16 model returns a prediction (derived from the 1000 possible categories in ImageNet) for the object that is contained in the image.

1.1.4 (IMPLEMENTATION) Making Predictions with a Pre-trained Model

In the next code cell, you will write a function that accepts a path to an image (such as 'dogImages/train/001.Affenpinscher/Affenpinscher_00001.jpg') as input and returns the index corresponding to the ImageNet class that is predicted by the pre-trained VGG-16 model. The output should always be an integer between 0 and 999, inclusive.

Before writing the function, make sure that you take the time to learn how to appropriately pre-process tensors for pre-trained models in the PyTorch documentation.

```
Index corresponding to VGG-16 model's prediction
111
## TODO: Complete the function.
## Load and pre-process an image from the given img_path
## Return the *index* of the predicted class for that image
img_transforms = transforms.Compose([transforms.Resize(255),
                                       transforms.CenterCrop(224),
                                       transforms.ToTensor(),
                                       transforms.Normalize([0.485, 0.456, 0.406],
                                                            [0.229, 0.224, 0.225])])
img = Image.open(img_path)
img = img_transforms(img).float()
img = img.requires_grad_(True)
img = img.unsqueeze(0)
if use_cuda:
    img = img.cuda()
output = VGG16(img)
if use_cuda:
    output = output.cpu()
return np.argmax(output.detach().numpy()) # predicted class index
```

1.1.5 (IMPLEMENTATION) Write a Dog Detector

While looking at the dictionary, you will notice that the categories corresponding to dogs appear in an uninterrupted sequence and correspond to dictionary keys 151-268, inclusive, to include all categories from 'Chihuahua' to 'Mexican hairless'. Thus, in order to check to see if an image is predicted to contain a dog by the pre-trained VGG-16 model, we need only check if the pre-trained model predicts an index between 151 and 268 (inclusive).

Use these ideas to complete the dog_detector function below, which returns True if a dog is detected in an image (and False if not).

1.1.6 (IMPLEMENTATION) Assess the Dog Detector

Question 2: Use the code cell below to test the performance of your dog_detector function.

- What percentage of the images in human_files_short have a detected dog?
- What percentage of the images in dog_files_short have a detected dog?

Answer:

Percentage of detected dog faces in human_files_short 0.0%

Percentage of detected dog faces in dog_files_short 96.0%

```
In [9]: ### TODO: Test the performance of the dog_detector function
        ### on the images in human_files_short and dog_files_short.
        human_files_short_dog_face_count = 0
        dog_files_short_dog_face_count = 0
        for human_img in human_files_short:
            if dog_detector(human_img):
                human_files_short_dog_face_count += 1
        for dog_img in dog_files_short:
            if dog_detector(dog_img):
                dog_files_short_dog_face_count += 1
        print(f"Percentage of detected dog faces in human_files_short "
              f"{human_files_short_dog_face_count/len(human_files_short) * 100}% \n"
              f"Percentage of detected dog faces in dog_files_short "
              f"{dog_files_short_dog_face_count/len(dog_files_short) * 100}%")
Percentage of detected dog faces in human_files_short 0.0%
Percentage of detected dog faces in dog_files_short 96.0%
```

We suggest VGG-16 as a potential network to detect dog images in your algorithm, but you are free to explore other pre-trained networks (such as Inception-v3, ResNet-50, etc). Please use the code cell below to test other pre-trained PyTorch models. If you decide to pursue this *optional* task, report performance on human_files_short and dog_files_short.

```
img_transforms = transforms.Compose([transforms.Resize(255),
                                                    transforms.CenterCrop(224),
                                                    transforms.ToTensor(),
                                                    transforms.Normalize([0.485, 0.456, 0.406],
                                                                         [0.229, 0.224, 0.225])])
             img = Image.open(img_path)
             img = img_transforms(img).float()
             img = img.requires_grad_(True)
             img = img.unsqueeze(0)
             output = ShuffleNet(img)
             return np.argmax(output.detach().numpy())
In [12]: def dog_detector_shuffle(img_path):
             pred_index = shufflenet_predict(img_path)
             return pred_index >= 151 and pred_index <= 268</pre>
In [13]: human_files_short_dog_face_count_shuffle = 0
         dog_files_short_dog_face_count_shuffle = 0
         for human_img in human_files_short:
             if dog_detector_shuffle(human_img):
                 human_files_short_dog_face_count_shuffle += 1
         for dog_img in dog_files_short:
             if dog_detector_shuffle(dog_img):
                 dog_files_short_dog_face_count_shuffle += 1
         print(f"Percentage of detected dog faces in human_files_short with shufflenet "
               f"{human_files_short_dog_face_count_shuffle/len(human_files_short) * 100}% \n"
               f"Percentage of detected dog faces in dog_files_short with shufflenet "
               f"{dog_files_short_dog_face_count_shuffle/len(dog_files_short) * 100}%")
Percentage of detected dog faces in human_files_short with shufflenet 14.00000000000000002%
```

Step 3: Create a CNN to Classify Dog Breeds (from Scratch)

Now that we have functions for detecting humans and dogs in images, we need a way to predict breed from images. In this step, you will create a CNN that classifies dog breeds. You must create your CNN *from scratch* (so, you can't use transfer learning *yet*!), and you must attain a test accuracy of at least 10%. In Step 4 of this notebook, you will have the opportunity to use transfer learning to create a CNN that attains greatly improved accuracy.

We mention that the task of assigning breed to dogs from images is considered exceptionally challenging. To see why, consider that *even a human* would have trouble distinguishing between a Brittany and a Welsh Springer Spaniel.

```
Brittany Welsh Springer Spaniel
```

It is not difficult to find other dog breed pairs with minimal inter-class variation (for instance, Curly-Coated Retrievers and American Water Spaniels).

```
Curly-Coated Retriever American Water Spaniel
```

Likewise, recall that labradors come in yellow, chocolate, and black. Your vision-based algorithm will have to conquer this high intra-class variation to determine how to classify all of these different shades as the same breed.

```
Yellow Labrador Chocolate Labrador
```

We also mention that random chance presents an exceptionally low bar: setting aside the fact that the classes are slightly imabalanced, a random guess will provide a correct answer roughly 1 in 133 times, which corresponds to an accuracy of less than 1%.

Remember that the practice is far ahead of the theory in deep learning. Experiment with many different architectures, and trust your intuition. And, of course, have fun!

1.1.7 (IMPLEMENTATION) Specify Data Loaders for the Dog Dataset

Use the code cell below to write three separate data loaders for the training, validation, and test datasets of dog images (located at dog_images/train, dog_images/valid, and dog_images/test, respectively). You may find this documentation on custom datasets to be a useful resource. If you are interested in augmenting your training and/or validation data, check out the wide variety of transforms!

```
transforms RandomHorizontalFlip(),
                                       transforms.RandomVerticalFlip(),
                                       transforms.ToTensor(),
                                       transforms.Normalize([0.485, 0.456, 0.406],
                                                             [0.229, 0.224, 0.225])])
test_transforms = transforms.Compose([transforms.Resize(255),
                                      transforms.CenterCrop(224),
                                      transforms.ToTensor(),
                                      transforms.Normalize([0.485, 0.456, 0.406],
                                                            [0.229, 0.224, 0.225])])
image_path = 'data/dog_images'
if not os.path.isdir(image_path):
    image_path = '/' + image_path
train_path = os.path.join(image_path, 'train')
val_path = os.path.join(image_path, 'valid')
test_path = os.path.join(image_path, 'test')
train_dataset = datasets.ImageFolder(train_path, train_transforms)
val_dataset = datasets.ImageFolder(val_path, train_transforms)
test_dataset = datasets.ImageFolder(test_path, test_transforms)
train_loader = torch.utils.data.DataLoader(train_dataset, batch_size=32, shuffle=True)
val_loader = torch.utils.data.DataLoader(val_dataset, batch_size=32, shuffle=True)
test_loader = torch.utils.data.DataLoader(test_dataset, batch_size=32, shuffle=True)
loaders_scratch = {'train': train_loader, 'valid': val_loader, 'test': test_loader}
```

Question 3: Describe your chosen procedure for preprocessing the data. - How does your code resize the images (by cropping, stretching, etc)? What size did you pick for the input tensor, and why? - Did you decide to augment the dataset? If so, how (through translations, flips, rotations, etc)? If not, why not?

Answer:

I scaled images to a square (255, 255), then cropped them to 224x224px. I picked these sizes because many pretrained models also use these sizes. Then I transformed the images to tensors.

I normalized the train, validation, and test data again following the pattern of many pretrained models. However I augmented the train and validation datasets by randomizing the resize and crop. I also added random horizontal and vertical flipping.

1.1.8 (IMPLEMENTATION) Model Architecture

Create a CNN to classify dog breed. Use the template in the code cell below.

```
In [5]: import torch.nn as nn
    import torch.nn.functional as F
```

```
def calc_w_conv_out(conv, pool_stride = 1):
   return (((conv["W"] - conv["F"] + (2*conv["P"])) / conv["S"]) + 1) / pool_stride
conv1_w_in = 224
conv1 = {"W": conv1_w_in, "D": 3, "K": 16, "F": 3, "P": 1, "S": 1}
conv1_w_out = calc_w_conv_out(conv1)
conv2 = {"W": conv1_w_out, "D": conv1["K"], "K": 24, "F": 3, "P": 1, "S": 1}
conv2_w_out = calc_w_conv_out(conv2, 7)
conv3 = {"W": conv2_w_out, "D": conv2["K"], "K": 32, "F": 3, "P": 1, "S": 1}
conv3_w_out = calc_w_conv_out(conv3)
conv4 = {"W": conv3 w out, "D": conv3["K"], "K": 48, "F": 3, "P": 1, "S": 1}
conv4_w_out = calc_w_conv_out(conv4, 4)
conv5 = {"W": conv4_w_out, "D": conv4["K"], "K": 56, "F": 3, "P": 1, "S": 1}
conv5_w_out = calc_w_conv_out(conv5)
conv6 = {"W": conv5_w_out, "D": conv5["K"], "K": 64, "F": 3, "P": 1, "S": 1}
conv6_w_out = calc_w_conv_out(conv6, 4)
conv7 = {"W": conv6_w_out, "D": conv6["K"], "K": 176, "F": 3, "P": 1, "S": 1}
conv7_w_out = calc_w_conv_out(conv7)
conv8 = {"W": conv7_w_out, "D": conv7["K"], "K": 192, "F": 3, "P": 1, "S": 1}
conv8_w_out = calc_w_conv_out(conv8, 2)
conv9 = {"W": conv8 w out, "D": conv8["K"], "K": 208, "F": 3, "P": 1, "S": 1}
conv9_w_out = calc_w_conv_out(conv9)
conv10 = {"W": conv9_w_out, "D": conv9["K"], "K": 224, "F": 3, "P": 1, "S": 1}
conv10_w_out = calc_w_conv_out(conv10, 2)
conv_features_out = conv6_w_out**2 * conv6["K"]
#print(conv1_w_out, conv2_w_out, conv3_w_out, conv4_w_out, conv5_w_out,
      conv6_w_out, conv7_w_out, conv8_w_out, conv9_w_out, conv10_w_out, conv_features_c
print(conv1_w_out, conv2_w_out, conv3_w_out, conv4_w_out, conv_features_out)
def make_nn_conv(conv):
    return nn.Conv2d(conv["D"], conv["K"], conv["F"], padding=conv["P"], stride=conv["S"
# define the CNN architecture
class Net(nn.Module):
```

```
### TODO: choose an architecture, and complete the class
def __init__(self):
    super(Net, self).__init__()
    ## Define layers of a CNN
    ## Layer 1
    self.conv1 = make_nn_conv(conv1)
    self.conv2 = make_nn_conv(conv2)
    ## Layer 2
    self.conv3 = make_nn_conv(conv3)
    self.conv4 = make_nn_conv(conv4)
    ## Layer 3
    self.conv5 = make_nn_conv(conv5)
    self.conv6 = make_nn_conv(conv6)
    ## Layer 4
    #self.conv7 = make_nn_conv(conv7)
    #self.conv8 = make_nn_conv(conv8)
    ## Layer 5
    \#self.conv9 = make_nn_conv(conv9)
    #self.conv10 = make_nn_conv(conv10)
    ## Layer 6
    self.fc1 = nn.Linear(int(conv_features_out), 133)
    ## Layer 7
    \#self.fc2 = nn.Linear(4096, 256)
    ## Layer 8
    \#self.fc3 = nn.Linear(256, 133)
def forward(self, x):
    ## Define forward behavior
    batch_size = x.size()[0]
    # layer 1
    x = F.dropout(F.relu(self.conv1(x)), 0.2)
    x = F.dropout(F.max_pool2d(F.relu(self.conv2(x)), 7, 7), 0.2)
    # layer 2
    x = F.dropout(F.relu(self.conv3(x)), 0.2)
    x = F.dropout(F.max_pool2d(F.relu(self.conv4(x)), 4, 4), 0.2)
    # layer 3
    x = F.dropout(F.relu(self.conv5(x)), 0.2)
    x = F.dropout(F.max_pool2d(F.relu(self.conv6(x)), 4, 4), 0.2)
    # layer 4
    \#x = F.dropout(F.relu(self.conv7(x)), 0.2)
    \#x = F.dropout(F.max_pool2d(F.relu(self.conv8(x)), 2, 2), 0.2)
    \#x = F.dropout(F.relu(self.conv9(x)), 0.2)
    \#x = F.dropout(F.max_pool2d(F.relu(self.conv10(x)), 2, 2), 0.2)
    x = x.view(batch_size, -1)
```

```
\#x = F.dropout(F.relu(self.fc1(x)), 0.2)
                \#x = F.dropout(F.relu(self.fc2(x)), 0.2)
                \#x = F.log\_softmax(self.fc3(x))
                x = self.fc1(x)
                return x
        #-#-# You so NOT have to modify the code below this line. #-#-#
        # instantiate the CNN
        model_scratch = Net()
        # move tensors to GPU if CUDA is available
        if use_cuda:
            model scratch.cuda()
224.0 32.0 32.0 8.0 256.0
In [11]: model_scratch
Out[11]: Net(
           (conv1): Conv2d(3, 16, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
           (conv2): Conv2d(16, 24, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
           (conv3): Conv2d(24, 32, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
           (conv4): Conv2d(32, 48, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
           (conv5): Conv2d(48, 56, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
           (conv6): Conv2d(56, 64, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
           (fc1): Linear(in_features=256, out_features=133, bias=True)
         )
In [12]: #!nvidia-smi
         #!sudo fuser -v /dev/nvidia*
         #!sudo kill -9 85
```

Question 4: Outline the steps you took to get to your final CNN architecture and your reasoning at each step.

Answer:

My architecture is a take on the VGG architecture. Each of the convolutional layers consists of 2 conv steps and a max pool step. The classification layer set consists of 1 fully connected layer. I tried to maximize depth without exhausting my resources. I went through many iterations (commented above), for instance I have tested batch sizes from 4 to 128, conv layers of 1 to 5, and fully connected layers from 1 to 3. In the end I settled on 1 fc layer, and 3 conv layers. I also tested different methods of spatial dimentionality reduction, larger and smaller pool and conv strides for instance. The above model and batch size demonstrated good performance while not exhausting my GPU memory.

As I step through each feature extraction layer, I reduce the spatial dimentionality and increase the depth. Since we have many complex features to learn, I opted for a deeper network.

The classification layers simply reduces the features output by the feature extraction layers into 133 prediction outputs. Much of the detail is output above.

1.1.9 (IMPLEMENTATION) Specify Loss Function and Optimizer

Use the next code cell to specify a loss function and optimizer. Save the chosen loss function as criterion_scratch, and the optimizer as optimizer_scratch below.

```
In [6]: import torch.optim as optim
    ### TODO: select loss function
    criterion_scratch = nn.CrossEntropyLoss()

### TODO: select optimizer
    optimizer_scratch = optim.SGD(model_scratch.parameters(), lr=0.01, momentum=0.9)
```

1.1.10 (IMPLEMENTATION) Train and Validate the Model

Train and validate your model in the code cell below. Save the final model parameters at filepath 'model_scratch.pt'.

```
In [12]: def train(n_epochs, loaders, model, optimizer, criterion, use_cuda, save_path):
             """returns trained model"""
             # initialize tracker for minimum validation loss
             valid_loss_min = np.Inf
             for epoch in range(1, n_epochs+1):
                 # initialize variables to monitor training and validation loss
                 train_loss = 0.0
                 valid_loss = 0.0
                 ###################
                 # train the model #
                 ###################
                 model.train()
                 for batch_idx, (data, target) in enumerate(loaders['train']):
                     # move to GPU
                     if use cuda:
                         data, target = data.cuda(), target.cuda()
                     ## find the loss and update the model parameters accordingly
                     ## record the average training loss, using something like
                     \#\# train_loss = train_loss + ((1 / (batch_idx + 1)) * (loss.data - train_loss)
                     optimizer.zero_grad()
                     output = model(data)
```

loss = criterion(output, target)

loss.backward()

```
train_loss += loss.item()*data.size(0)
                 train_loss = train_loss/len(loaders['train'].sampler)
                 ########################
                 # validate the model #
                 #####################
                 model.eval()
                 for batch_idx, (data, target) in enumerate(loaders['valid']):
                     # move to GPU
                     if use cuda:
                         data, target = data.cuda(), target.cuda()
                     ## update the average validation loss
                     output = model(data)
                     loss = criterion(output, target)
                     valid_loss += loss.item()*data.size(0)
                 valid_loss = valid_loss/len(loaders['valid'].sampler)
                 # print training/validation statistics
                 print('Epoch: {} \tTraining Loss: {:.6f} \tValidation Loss: {:.6f}'.format(
                     epoch,
                     train_loss,
                     valid_loss
                     ))
                 \#\# TODO: save the model if validation loss has decreased
                 if valid loss < valid loss min:
                     print(f'Saved model, validation decresed: {valid_loss_min} => {valid_loss}'
                     valid_loss_min = valid_loss
                     torch.save(model.state_dict(), save_path)
             # return trained model
             return model
In [14]: # train the model
         model_scratch = train(50, loaders_scratch, model_scratch, optimizer_scratch,
                               criterion_scratch, use_cuda, 'model_scratch.pt')
         # load the model that got the best validation accuracy
         model_scratch.load_state_dict(torch.load('model_scratch.pt'))
Epoch: 1
                 Training Loss: 4.886349
                                                 Validation Loss: 4.874956
Saved model_scratch.pt, validation decresed: inf => 4.874955803762653
                                                 Validation Loss: 4.856403
                 Training Loss: 4.871458
Epoch: 2
```

optimizer.step()

```
Saved model_scratch.pt, validation decresed: 4.874955803762653 => 4.856402617585873
                Training Loss: 4.844694
                                                 Validation Loss: 4.824011
Saved model_scratch.pt, validation decresed: 4.856402617585873 => 4.824011480023048
                 Training Loss: 4.817443
                                                 Validation Loss: 4.797559
Epoch: 4
Saved model_scratch.pt, validation decresed: 4.824011480023048 => 4.797558997491163
                 Training Loss: 4.774604
Epoch: 5
                                                 Validation Loss: 4.759784
Saved model_scratch.pt, validation decresed: 4.797558997491163 => 4.7597839144175635
Epoch: 6
                 Training Loss: 4.745781
                                                 Validation Loss: 4.738268
Saved model_scratch.pt, validation decresed: 4.7597839144175635 => 4.738268052175373
                 Training Loss: 4.716604
Epoch: 7
                                                 Validation Loss: 4.710740
Saved model_scratch.pt, validation decresed: 4.738268052175373 => 4.7107401162564395
                 Training Loss: 4.676164
                                                 Validation Loss: 4.681243
Saved model_scratch.pt, validation decresed: 4.7107401162564395 => 4.681243339127409
                 Training Loss: 4.617986
                                                 Validation Loss: 4.667093
Saved model_scratch.pt, validation decresed: 4.681243339127409 => 4.667092974885495
                  Training Loss: 4.573935
                                                  Validation Loss: 4.585720
Epoch: 10
Saved model_scratch.pt, validation decresed: 4.667092974885495 => 4.585719639098573
                                                  Validation Loss: 4.488469
                  Training Loss: 4.531621
Epoch: 11
Saved model_scratch.pt, validation decresed: 4.585719639098573 => 4.488468882851972
Epoch: 12
                  Training Loss: 4.491057
                                                  Validation Loss: 4.527221
                  Training Loss: 4.433595
Epoch: 13
                                                  Validation Loss: 4.532133
                  Training Loss: 4.378784
Epoch: 14
                                                  Validation Loss: 4.420561
Saved model_scratch.pt, validation decresed: 4.488468882851972 => 4.4205613890093955
                  Training Loss: 4.353498
Epoch: 15
                                                  Validation Loss: 4.308159
Saved model_scratch.pt, validation decresed: 4.4205613890093955 => 4.3081587277486655
                  Training Loss: 4.313212
Epoch: 16
                                                  Validation Loss: 4.312609
                  Training Loss: 4.259010
                                                  Validation Loss: 4.365662
Epoch: 17
Epoch: 18
                  Training Loss: 4.238743
                                                  Validation Loss: 4.269065
Saved model_scratch.pt, validation decresed: 4.3081587277486655 => 4.269064992916085
Epoch: 19
                  Training Loss: 4.183247
                                                  Validation Loss: 4.250778
Saved model_scratch.pt, validation decresed: 4.269064992916085 => 4.250778046054041
Epoch: 20
                  Training Loss: 4.166183
                                                  Validation Loss: 4.319319
Epoch: 21
                  Training Loss: 4.127019
                                                  Validation Loss: 4.151792
Saved model_scratch.pt, validation decresed: 4.250778046054041 => 4.15179211450908
                  Training Loss: 4.082067
Epoch: 22
                                                  Validation Loss: 4.211116
Epoch: 23
                  Training Loss: 4.042719
                                                  Validation Loss: 4.105904
Saved model_scratch.pt, validation decresed: 4.15179211450908 => 4.105903582087534
Epoch: 24
                  Training Loss: 4.034509
                                                  Validation Loss: 4.173188
                  Training Loss: 4.022800
Epoch: 25
                                                  Validation Loss: 4.071308
Saved model_scratch.pt, validation decresed: 4.105903582087534 => 4.07130839125125
                  Training Loss: 3.964795
Epoch: 26
                                                  Validation Loss: 4.074127
                  Training Loss: 3.919819
Epoch: 27
                                                  Validation Loss: 3.950540
Saved model_scratch.pt, validation decresed: 4.07130839125125 => 3.9505399475554506
                  Training Loss: 3.889702
                                                  Validation Loss: 3.909950
Saved model_scratch.pt, validation decresed: 3.9505399475554506 => 3.909949774370936
Epoch: 29
                  Training Loss: 3.870314
                                                  Validation Loss: 3.959555
                  Training Loss: 3.859976
Epoch: 30
                                                  Validation Loss: 3.932009
Epoch: 31
                  Training Loss: 3.813756
                                                 Validation Loss: 3.988577
```

```
Validation Loss: 4.013737
Epoch: 32
                  Training Loss: 3.795176
Epoch: 33
                  Training Loss: 3.770210
                                                   Validation Loss: 3.841450
Saved model_scratch.pt, validation decresed: 3.909949774370936 => 3.8414497872312627
                  Training Loss: 3.755823
                                                  Validation Loss: 4.000259
Epoch: 34
Epoch: 35
                  Training Loss: 3.718831
                                                  Validation Loss: 4.004603
                  Training Loss: 3.703429
                                                  Validation Loss: 3.893162
Epoch: 36
Epoch: 37
                  Training Loss: 3.712983
                                                  Validation Loss: 3.844040
Epoch: 38
                  Training Loss: 3.675443
                                                  Validation Loss: 3.784656
Saved model_scratch.pt, validation decresed: 3.8414497872312627 => 3.7846560572435757
Epoch: 39
                  Training Loss: 3.646301
                                                  Validation Loss: 3.848840
Epoch: 40
                  Training Loss: 3.646254
                                                  Validation Loss: 3.844699
Epoch: 41
                  Training Loss: 3.611488
                                                  Validation Loss: 3.800444
                  Training Loss: 3.611060
                                                  Validation Loss: 3.873859
Epoch: 42
Epoch: 43
                  Training Loss: 3.623455
                                                  Validation Loss: 3.868454
Epoch: 44
                  Training Loss: 3.579911
                                                  Validation Loss: 3.828724
                                                  Validation Loss: 3.867723
Epoch: 45
                  Training Loss: 3.613435
Epoch: 46
                  Training Loss: 3.603369
                                                  Validation Loss: 3.780542
Saved model_scratch.pt, validation decresed: 3.7846560572435757 => 3.780542138665022
Epoch: 47
                  Training Loss: 3.597731
                                                  Validation Loss: 3.822047
Epoch: 48
                  Training Loss: 3.554749
                                                  Validation Loss: 3.780447
Saved model_scratch.pt, validation decresed: 3.780542138665022 => 3.780446781512506
Epoch: 49
                  Training Loss: 3.529535
                                                   Validation Loss: 3.700819
Saved model_scratch.pt, validation decresed: 3.780446781512506 => 3.700818885586219
                  Training Loss: 3.586106
Epoch: 50
                                                  Validation Loss: 3.778319
```

1.1.11 (IMPLEMENTATION) Test the Model

Try out your model on the test dataset of dog images. Use the code cell below to calculate and print the test loss and accuracy. Ensure that your test accuracy is greater than 10%.

```
In [18]: def test(loaders, model, criterion, use_cuda):
    # monitor test loss and accuracy
    test_loss = 0.
    correct = 0.
    total = 0.

model.eval()
    for batch_idx, (data, target) in enumerate(loaders['test']):
        # move to GPU
        if use_cuda:
            data, target = data.cuda(), target.cuda()
            # forward pass: compute predicted outputs by passing inputs to the model output = model(data)
            # calculate the loss
            loss = criterion(output, target)
            # update average test loss
```

Step 4: Create a CNN to Classify Dog Breeds (using Transfer Learning)

You will now use transfer learning to create a CNN that can identify dog breed from images. Your CNN must attain at least 60% accuracy on the test set.

1.1.12 (IMPLEMENTATION) Specify Data Loaders for the Dog Dataset

Use the code cell below to write three separate data loaders for the training, validation, and test datasets of dog images (located at dogImages/train, dogImages/valid, and dogImages/test, respectively).

If you like, **you are welcome to use the same data loaders from the previous step**, when you created a CNN from scratch.

1.1.13 (IMPLEMENTATION) Model Architecture

Use transfer learning to create a CNN to classify dog breed. Use the code cell below, and save your initialized model as the variable model_transfer.

```
In [8]: import torchvision.models as models
   import torch.nn as nn
```

```
model_transfer = models.vgg19(pretrained=True)
        for param in model_transfer.features.parameters():
            param.requires_grad_(False)
Downloading: "https://download.pytorch.org/models/vgg19-dcbb9e9d.pth" to /root/.torch/models/vgg
100%|| 574673361/574673361 [00:07<00:00, 77889513.18it/s]
Out[8]: VGG(
          (features): Sequential(
            (0): Conv2d(3, 64, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
            (1): ReLU(inplace)
            (2): Conv2d(64, 64, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
            (3): ReLU(inplace)
            (4): MaxPool2d(kernel_size=2, stride=2, padding=0, dilation=1, ceil_mode=False)
            (5): Conv2d(64, 128, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
            (6): ReLU(inplace)
            (7): Conv2d(128, 128, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
            (8): ReLU(inplace)
            (9): MaxPool2d(kernel_size=2, stride=2, padding=0, dilation=1, ceil_mode=False)
            (10): Conv2d(128, 256, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
            (11): ReLU(inplace)
            (12): Conv2d(256, 256, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
            (13): ReLU(inplace)
            (14): Conv2d(256, 256, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
            (15): ReLU(inplace)
            (16): Conv2d(256, 256, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
            (17): ReLU(inplace)
            (18): MaxPool2d(kernel_size=2, stride=2, padding=0, dilation=1, ceil_mode=False)
            (19): Conv2d(256, 512, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
            (20): ReLU(inplace)
            (21): Conv2d(512, 512, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
            (22): ReLU(inplace)
            (23): Conv2d(512, 512, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
            (24): ReLU(inplace)
            (25): Conv2d(512, 512, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
            (26): ReLU(inplace)
            (27): MaxPool2d(kernel_size=2, stride=2, padding=0, dilation=1, ceil_mode=False)
            (28): Conv2d(512, 512, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
            (29): ReLU(inplace)
            (30): Conv2d(512, 512, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
            (31): ReLU(inplace)
            (32): Conv2d(512, 512, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
            (33): ReLU(inplace)
            (34): Conv2d(512, 512, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
```

TODO: Specify model architecture

```
(35): ReLU(inplace)
            (36): MaxPool2d(kernel_size=2, stride=2, padding=0, dilation=1, ceil_mode=False)
          (classifier): Sequential(
            (0): Linear(in_features=25088, out_features=4096, bias=True)
            (1): ReLU(inplace)
            (2): Dropout(p=0.5)
            (3): Linear(in_features=4096, out_features=4096, bias=True)
            (4): ReLU(inplace)
            (5): Dropout(p=0.5)
            (6): Linear(in_features=4096, out_features=1000, bias=True)
          )
        )
In [9]: in_features = model_transfer.classifier[6].in_features
        output_fc_layer = nn.Linear(in_features, 133)
        model_transfer.classifier[6] = output_fc_layer
        if use_cuda:
            model_transfer = model_transfer.cuda()
        model_transfer
Out[9]: VGG(
          (features): Sequential(
            (0): Conv2d(3, 64, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
            (1): ReLU(inplace)
            (2): Conv2d(64, 64, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
            (3): ReLU(inplace)
            (4): MaxPool2d(kernel_size=2, stride=2, padding=0, dilation=1, ceil_mode=False)
            (5): Conv2d(64, 128, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
            (6): ReLU(inplace)
            (7): Conv2d(128, 128, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
            (8): ReLU(inplace)
            (9): MaxPool2d(kernel_size=2, stride=2, padding=0, dilation=1, ceil_mode=False)
            (10): Conv2d(128, 256, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
            (11): ReLU(inplace)
            (12): Conv2d(256, 256, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
            (13): ReLU(inplace)
            (14): Conv2d(256, 256, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
            (15): ReLU(inplace)
            (16): Conv2d(256, 256, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
            (17): ReLU(inplace)
            (18): MaxPool2d(kernel_size=2, stride=2, padding=0, dilation=1, ceil_mode=False)
            (19): Conv2d(256, 512, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
            (20): ReLU(inplace)
```

```
(21): Conv2d(512, 512, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
    (22): ReLU(inplace)
    (23): Conv2d(512, 512, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
    (24): ReLU(inplace)
    (25): Conv2d(512, 512, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
    (26): ReLU(inplace)
    (27): MaxPool2d(kernel_size=2, stride=2, padding=0, dilation=1, ceil_mode=False)
    (28): Conv2d(512, 512, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
    (29): ReLU(inplace)
    (30): Conv2d(512, 512, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
    (31): ReLU(inplace)
    (32): Conv2d(512, 512, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
    (33): ReLU(inplace)
    (34): Conv2d(512, 512, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
    (35): ReLU(inplace)
    (36): MaxPool2d(kernel_size=2, stride=2, padding=0, dilation=1, ceil_mode=False)
  (classifier): Sequential(
    (0): Linear(in_features=25088, out_features=4096, bias=True)
    (1): ReLU(inplace)
    (2): Dropout(p=0.5)
    (3): Linear(in_features=4096, out_features=4096, bias=True)
    (4): ReLU(inplace)
    (5): Dropout(p=0.5)
    (6): Linear(in_features=4096, out_features=133, bias=True)
  )
)
```

Question 5: Outline the steps you took to get to your final CNN architecture and your reasoning at each step. Describe why you think the architecture is suitable for the current problem.

Answer:

Similar to the reasoning in my scratch model, I opted for a deeper network to maximize feature extraction. My only addition was the custom output layer to respect the number of outputs required to solve our problem.

1.1.14 (IMPLEMENTATION) Specify Loss Function and Optimizer

Use the next code cell to specify a loss function and optimizer. Save the chosen loss function as criterion_transfer, and the optimizer as optimizer_transfer below.

1.1.15 (IMPLEMENTATION) Train and Validate the Model

Train and validate your model in the code cell below. Save the final model parameters at filepath 'model_transfer.pt'.

```
In [23]: # train the model
         model_transfer.load_state_dict(torch.load('model_transfer.pt'))
         model_transfer = train(50, loaders_transfer, model_transfer, optimizer_transfer,
                                criterion_transfer, use_cuda, 'model_transfer.pt')
         # load the model that got the best validation accuracy (uncomment the line below)
         model_transfer.load_state_dict(torch.load('model_transfer.pt'))
Epoch: 1
                 Training Loss: 2.440045
                                                 Validation Loss: 1.933388
Saved model, validation decresed: inf => 1.9333875885980571
                 Training Loss: 2.101694
                                                 Validation Loss: 1.831920
Saved model, validation decresed: 1.9333875885980571 => 1.831920090692486
Epoch: 3
                 Training Loss: 1.994816
                                                 Validation Loss: 1.812513
Saved model, validation decresed: 1.831920090692486 => 1.812513408546676
Epoch: 4
                 Training Loss: 1.916495
                                                 Validation Loss: 1.672239
Saved model, validation decresed: 1.812513408546676 => 1.672239061886679
                 Training Loss: 1.848945
                                                 Validation Loss: 1.646405
Saved model, validation decresed: 1.672239061886679 => 1.6464046883012007
Epoch: 6
                 Training Loss: 1.804890
                                                 Validation Loss: 1.731276
Epoch: 7
                 Training Loss: 1.772146
                                                 Validation Loss: 1.678199
                 Training Loss: 1.742338
                                                 Validation Loss: 1.593539
Epoch: 8
Saved model, validation decresed: 1.6464046883012007 => 1.5935393957320803
Epoch: 9
                 Training Loss: 1.687611
                                                 Validation Loss: 1.603921
Epoch: 10
                  Training Loss: 1.654356
                                                  Validation Loss: 1.626794
                                                  Validation Loss: 1.550525
Epoch: 11
                  Training Loss: 1.629365
Saved model, validation decresed: 1.5935393957320803 => 1.5505245928992768
Epoch: 12
                  Training Loss: 1.598305
                                                  Validation Loss: 1.564545
Epoch: 13
                  Training Loss: 1.586382
                                                  Validation Loss: 1.505549
Saved model, validation decresed: 1.5505245928992768 => 1.5055486672652696
Epoch: 14
                  Training Loss: 1.561946
                                                  Validation Loss: 1.543798
                                                  Validation Loss: 1.535505
Epoch: 15
                  Training Loss: 1.578767
                  Training Loss: 1.515793
                                                  Validation Loss: 1.462840
Epoch: 16
Saved model, validation decresed: 1.5055486672652696 => 1.4628396194138213
Epoch: 17
                  Training Loss: 1.553354
                                                  Validation Loss: 1.505737
Epoch: 18
                  Training Loss: 1.529435
                                                  Validation Loss: 1.459117
Saved model, validation decresed: 1.4628396194138213 => 1.4591167906801144
                  Training Loss: 1.480919
Epoch: 19
                                                  Validation Loss: 1.586827
Epoch: 20
                  Training Loss: 1.464608
                                                  Validation Loss: 1.445554
Saved model, validation decresed: 1.4591167906801144 => 1.4455540545686276
Epoch: 21
                  Training Loss: 1.468181
                                                  Validation Loss: 1.550692
Epoch: 22
                  Training Loss: 1.462875
                                                  Validation Loss: 1.575371
                  Training Loss: 1.440352
Epoch: 23
                                                  Validation Loss: 1.436228
Saved model, validation decresed: 1.4455540545686276 => 1.4362275693231
Epoch: 24
                  Training Loss: 1.413724
                                                  Validation Loss: 1.554304
Epoch: 25
                  Training Loss: 1.411300
                                                  Validation Loss: 1.442014
Epoch: 26
                                                  Validation Loss: 1.504286
                  Training Loss: 1.408343
Epoch: 27
                  Training Loss: 1.391556
                                                  Validation Loss: 1.453332
```

```
Validation Loss: 1.390759
Epoch: 28
                  Training Loss: 1.371108
Saved model, validation decresed: 1.4362275693231 => 1.3907590637306968
                  Training Loss: 1.374468
                                                   Validation Loss: 1.491788
Epoch: 29
Epoch: 30
                  Training Loss: 1.348547
                                                   Validation Loss: 1.452440
Epoch: 31
                  Training Loss: 1.352558
                                                   Validation Loss: 1.452513
Epoch: 32
                  Training Loss: 1.333859
                                                   Validation Loss: 1.461971
Epoch: 33
                  Training Loss: 1.334603
                                                   Validation Loss: 1.488666
Epoch: 34
                  Training Loss: 1.328539
                                                   Validation Loss: 1.442902
Epoch: 35
                  Training Loss: 1.325614
                                                   Validation Loss: 1.461992
Epoch: 36
                  Training Loss: 1.302224
                                                   Validation Loss: 1.376617
Saved model, validation decresed: 1.3907590637306968 => 1.3766168343092866
Epoch: 37
                  Training Loss: 1.317673
                                                   Validation Loss: 1.488859
Epoch: 38
                  Training Loss: 1.273219
                                                   Validation Loss: 1.398614
Epoch: 39
                  Training Loss: 1.290325
                                                   Validation Loss: 1.392804
Epoch: 40
                  Training Loss: 1.280754
                                                   Validation Loss: 1.366158
Saved model, validation decresed: 1.3766168343092866 => 1.366158004292471
Epoch: 41
                  Training Loss: 1.227731
                                                   Validation Loss: 1.350499
Saved model, validation decresed: 1.366158004292471 => 1.3504994914917174
Epoch: 42
                  Training Loss: 1.238393
                                                   Validation Loss: 1.453760
Epoch: 43
                  Training Loss: 1.257587
                                                   Validation Loss: 1.417194
Epoch: 44
                  Training Loss: 1.258255
                                                   Validation Loss: 1.449541
Epoch: 45
                  Training Loss: 1.252617
                                                   Validation Loss: 1.459572
Epoch: 46
                  Training Loss: 1.222234
                                                   Validation Loss: 1.436493
Epoch: 47
                  Training Loss: 1.225767
                                                   Validation Loss: 1.543634
Epoch: 48
                  Training Loss: 1.194729
                                                   Validation Loss: 1.399152
Epoch: 49
                  Training Loss: 1.224239
                                                   Validation Loss: 1.392043
                  Training Loss: 1.252902
                                                   Validation Loss: 1.415003
Epoch: 50
```

1.1.16 (IMPLEMENTATION) Test the Model

Try out your model on the test dataset of dog images. Use the code cell below to calculate and print the test loss and accuracy. Ensure that your test accuracy is greater than 60%.

Test Loss: 0.503427

Test Accuracy: 85% (711/836)

1.1.17 (IMPLEMENTATION) Predict Dog Breed with the Model

Write a function that takes an image path as input and returns the dog breed (Affenpinscher, Afghan hound, etc) that is predicted by your model.

```
In [49]: ### TODO: Write a function that takes a path to an image as input
         ### and returns the dog breed that is predicted by the model.
         model_transfer.load_state_dict(torch.load('model_transfer.pt'))
         # list of class names by index, i.e. a name can be accessed like class_names[0]
         class_names = [item[4:].replace("_", " ") for item in test_dataset.classes]
         def predict_breed_transfer(img_path):
             # load the image and return the predicted breed
             model_transfer.eval()
             img = Image.open(img_path)
             img = test_transforms(img).float()
             img = img.requires_grad_(True)
             img = img.unsqueeze(0)
             if use_cuda:
                 img = img.cuda()
             output = model_transfer(img)
             if use_cuda:
                 output = output.cpu()
             return class_names[np.argmax(output.detach().numpy())]
```

Step 5: Write your Algorithm

Write an algorithm that accepts a file path to an image and first determines whether the image contains a human, dog, or neither. Then, - if a **dog** is detected in the image, return the predicted breed. - if a **human** is detected in the image, return the resembling dog breed. - if **neither** is detected in the image, provide output that indicates an error.

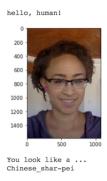
You are welcome to write your own functions for detecting humans and dogs in images, but feel free to use the face_detector and human_detector functions developed above. You are required to use your CNN from Step 4 to predict dog breed.

Some sample output for our algorithm is provided below, but feel free to design your own user experience!

1.1.18 (IMPLEMENTATION) Write your Algorithm

```
In [70]: ### TODO: Write your algorithm.
    ### Feel free to use as many code cells as needed.

def run_app(img_path):
    ## handle cases for a human face, dog, and neither found_dog = dog_detector(img_path)
    found_human = face_detector(img_path)
    img = cv2.imread(img_path)
    cv_rgb = cv2.cvtColor(img, cv2.COLOR_BGR2RGB)
```



Sample Human Output

```
plt.imshow(cv_rgb)
if not found_dog and not found_human:
    print("Hmmm, hold on a minute...")
    plt.show()
    print("I don't know what I'm looking at...! Can you try again?\n\n")
else:
    pred_breed = predict_breed_transfer(img_path)
    print(f"Hello, {'dog' if found_dog else 'human'}!")
    plt.show()
    print(f"You {'are' if found_dog else 'look like'} a...")
    print(f"{pred_breed}\n")
```

Step 6: Test Your Algorithm

In this section, you will take your new algorithm for a spin! What kind of dog does the algorithm think that *you* look like? If you have a dog, does it predict your dog's breed accurately? If you have a cat, does it mistakenly think that your cat is a dog?

1.1.19 (IMPLEMENTATION) Test Your Algorithm on Sample Images!

Test your algorithm at least six images on your computer. Feel free to use any images you like. Use at least two human and two dog images.

Question 6: Is the output better than you expected :) ? Or worse :(? Provide at least three possible points of improvement for your algorithm.

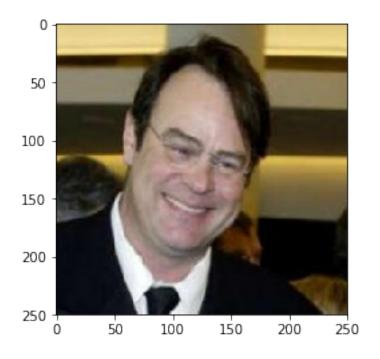
Answer: (Three possible points for improvement)

The model performed better than I expected. There are however points where it could be improved:

- The algorithm only supports single subject predictions, I would have liked to predict more
 than just one subject per image. For instance, it could be nice to draw a square around each
 human/dog face in the image and plot the appropriate prediction as a label.
- The algorithm is too dull for human images, it would be better to provide a reference image for human predictions, i.e "You look like THIS Pharoah hound!" It would be even better if the selected refrence image was one that closly matched the weights of the human image.

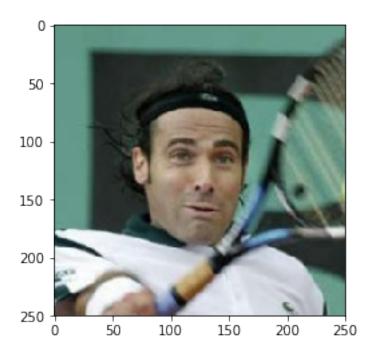
• The algorithm is limited to dogs, I would prefer an algorithm that could match many species of animals.

Hello, human!



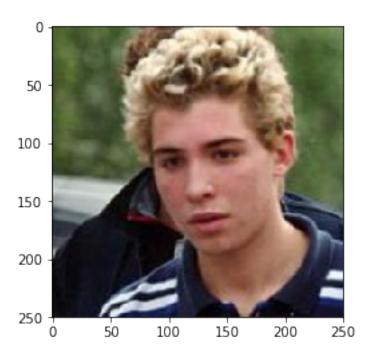
You look like a...
Pharaoh hound

Hello, human!



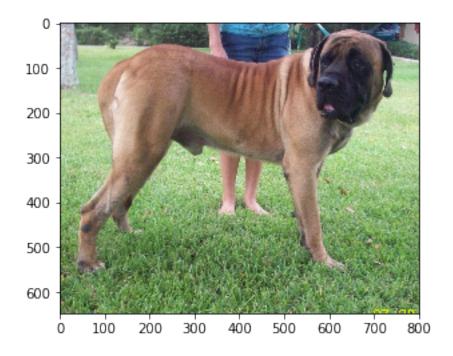
You look like a...
Dogue de bordeaux

Hello, human!



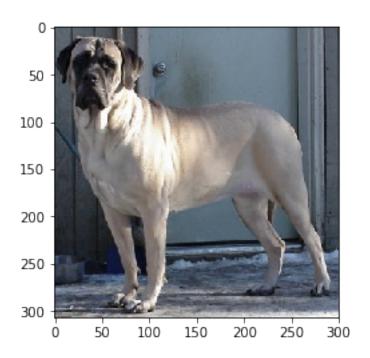
You look like a... Dogue de bordeaux

Hello, dog!



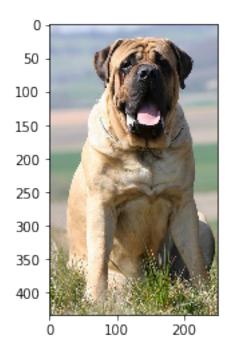
You are a...
Mastiff

Hello, dog!



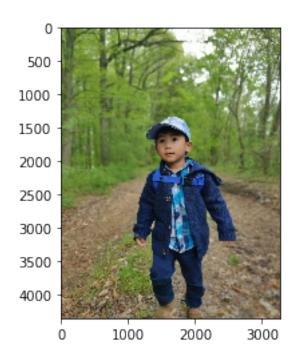
You are a...
Mastiff

Hello, dog!



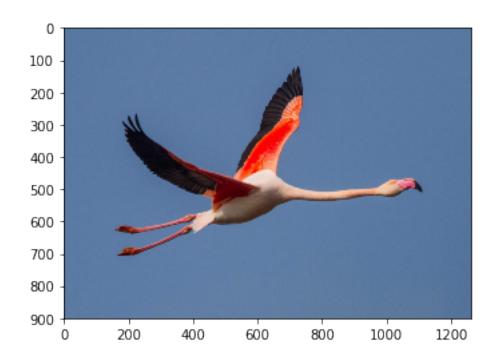
```
You are a...
Mastiff
```

Hello, human!



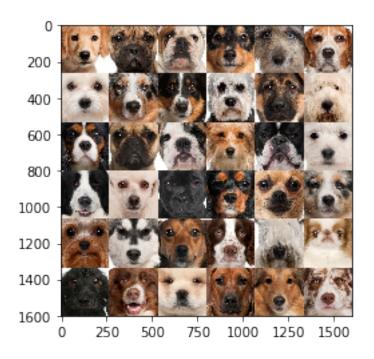
You look like a... Labrador retriever

 ${\tt Hmmm,\ hold\ on\ a\ minute...}$



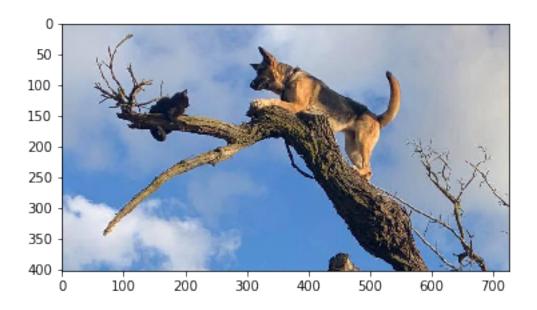
I don't know what I'm looking at...! Can you try again?

Hello, human!



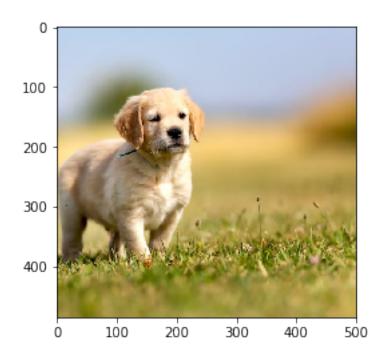
You look like a... Smooth fox terrier

Hello, dog!



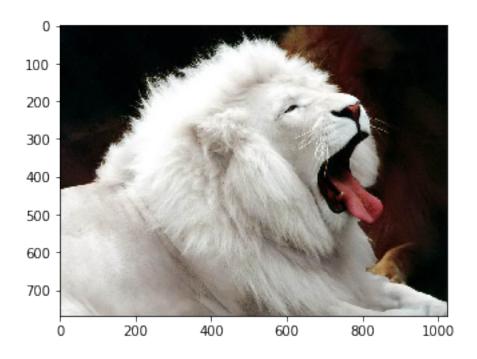
You are a...
German shepherd dog

Hello, dog!



You are a...
Golden retriever

Hello, dog!



```
You are a...
American eskimo dog
```

In []: