Parametric Gröbner basis Computation and Elimination

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- Gröbner basis was first proposed as a special basis of polynomial ideals by Buchberger (1965), where he also gave an algorithm to construct it.
- Comprehensive Gröbner system(CGS) and comprehensive Gröbner basis(CGB) were proposed by Weispfenning(1992) for parametric polynomial systems.
- Parametric Gröbner basis was proposed independently by Kapur (1994).

Main Applications of Comprehensive Gröbner System

- solving systems of parametric polynomials under various specializations.
- grouping together structurally similar polynomial systems under various specializations.
- study the solution structure, such as dimension, leading terms, of a parametric system.
- automatic geometric theorem proving and geometric theorem discovery.
- geometric reasoning in model based scene analysis and image understanding.
- o program analysis automatic generation of loop invariants.
- analysis of equalities appearing in a problem formulated in the theory of real closed field.



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- Different specializations lead to different systems.



What is a Gröbner Basis?

Given a polynomial ideal generated by a basis $\{f, g, h\}$, its Gröbner basis is a special basis with very nice properties:

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- Every polynomial simplifies to a unique normal form (also called the canonical form) of the polynomial based on the term ordering used.

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- If a polynomial system has no solution, its Gröbner basis consists of a nonzero constant.

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- Generate new rules/polynomials from existing polynomials using superpositions (S-polynomials) and simplification to achieve confluence.

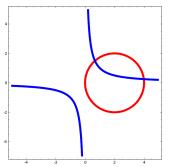
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- Upon termination algorithm gives a Gröbner basis.

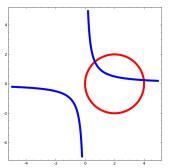


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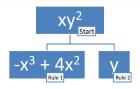
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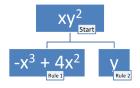
 Computing intersection points of the curves (which is the same as common solutions).

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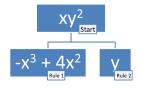


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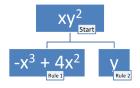
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- 3. $y \to -x^3 + 4x^2$.
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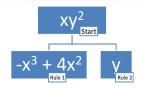
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- First polynomial simplifies to 0 using 2 and 3. $\{4. \quad x^4 - 4x^3 + 1, 3. \quad y + x^3 - 4x^2\}$ is a Groebner basis.

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- x and y coordinates of the four intersection points can be obtained from 4th and 3rd polynomials, resp.



Termination of Gröbner basis Algorithm

The process of generating additional rules always terminate because of a very elegant and simple combinatorial result from number theory:

Dickson's Lemma

Every infinite subset of N^k has at least two comparable k-tuples where comparison is done component-wise. $(a,b) \ge (c,d)$ iff $a \ge c \land b \ge d$.

Parametric Polynomial Systems

Example

Let $F = \langle ax^2 + by^2, cx^2 + y^2, ax - cy \rangle$ where $\{x, y\}$ are unknowns and $\{a, b, c\}$ are parameters.

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- Different specializations lead to different systems.
 - The Gröbner basis for $\sigma_{(0,1,0)}(F) = (y^2)$ is $\{y^2\}$.
 - The Gröbner basis for $\sigma_{(1,2,1)}(F) = (x^2 + 2y^2, x^2 + y^2, x y)$ is $\{x y, y^2\}$.

Comprehensive (Parametric) Gröbner Basis

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It is desirable to have $CGB \subset \langle F \rangle$.

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• Identify groups of specializations σ 's that share the same Gröbner basis for the specialized ideal $\sigma(\langle F \rangle)$.

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- For each such set of specialization, compute the respective Gröbner basis.

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Comprehensive Gröbner System and Basis

• Comprehensive Gröbner system(CGS): $\{(A_1, G_1), \dots, (A_l, G_l)\}$ for a finite basis F of a parametric ideal $\langle F \rangle$, where $\mathbb{C}^3 = A_1 \cup \dots \cup A_l$ and $G_1, \dots, G_l \subset \mathbb{Q}[a, b, c][x, y]$, s.t. $\sigma_{\alpha}(G_i)$ is a Gröbner basis for $\langle \sigma_{\alpha}(F) \rangle$ for $\forall \alpha \in A_i$. Each A_i is specified by a finite set of polynomial equality constraints and a finite set of polynomial disequality constraints over the parameters.

$$\{(A_i,G_i)\} = \left\{ \begin{array}{ccc} \mathbb{C}^3 \setminus V(abc-a^2), & \{ax-cy,(bc-a)y^2\} \\ & V(a) \setminus V(c), & \{cy,cx^2+y^2\} \\ & V(a,c), & \{y^2\} \\ & V(bc-a) \setminus V(ab^2+ac), & \{ax-cy,(b^2+c)y^2\} \\ & V(bc-a,b^2+c,ab+c^2,c^3+a^2) \setminus V(ac), & \{c^2x+bcy\} \end{array} \right.$$

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 - Such a case analysis gives possibly many branches.
- Repeat this process until all branches have been generated (i.e., all possible parametric specializations have been considered).

Key Idea of Kapur, Sun and Wang's algorithm (ISSAC 2010)

Among a set of polynomials which are candidates for inclusion in a Gröbner basis of a branch, it suffices to consider only those polynomials whose leading terms in **variables** are minimal and noncomparable to each others (since polynomials with leading comparable terms can be used to simplify each other).

Illustration

Example

Let $F := \{ax^2 + by^2, cx^2 + y^2, ax - cy\} \subset \mathbb{Q}[a, b, c][x, y]$ where $\{x, y\}$ are variables and $\{a, b, c\}$ are parameters.

• Gröbner basis for $\langle F \rangle \subset \mathbb{Q}[x,y,a,b,c]$ w.r.t. $x,y \gg a,b,c$.

$$G = \{ax - cy, (bc - a)y^2, (ab + c^2)y^2, (c^3 + a^2)y^2,$$

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Let $G_1 := \{ax - cy, (bc - a)y^2\} \subset G$. Theorem 4.3 in (Kapur et al. 2010) shows $\sigma_{\alpha}(G_1)$ is a Gröbner basis for $\langle \sigma_{\alpha}(F) \rangle$ for $\forall \alpha \in A_1 = \mathbb{C}^3 \setminus V(abc - a^2)$, which is the same as $a \neq 0 \land (bc - a) \neq 0$.

Then (A_1, G_1) is a branch of CGS for F.



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- Similarly, to generate additional branches, make c = 0, and so on.



Comprehensive Gröbner system(CGS):

$$\{(A_{i}, G_{i})\} = \begin{cases} \mathbb{C}^{3} \setminus V(a(abc - a)), & \{ax - cy, (bc - a)y^{2}\} \\ V(a) \setminus V(c), & \{cy, cx^{2} + y^{2}\} \end{cases}$$

$$V(a, c), & \{y^{2}\}$$

$$V(bc - a) \setminus V(a(b^{2} + c)), & \{ax - cy, (b^{2} + c)y^{2}\}$$

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$$\{(A_i, G_i)\} = \begin{cases} \mathbb{C}^3 \setminus V(a(abc-a)), & \{ax - cy, (bc - a)y^2\} \\ V(a) \setminus V(c), & \{cy, cx^2 + y^2\} \end{cases}$$

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- Split a polynomial into two parts, nonzero part and zero part under a specialization or more precisely, along a branch component.

New technique

Given $A_i \subset \mathbb{C}^3$ and $f \in \langle F \rangle$,

- $\circ \sigma_{\alpha}(\bar{p}) = 0 \text{ for } \forall \alpha \in A_i.$

Tuple Representation of Polynomials

New technique

Given $A_i \subset \mathbb{C}^3$ and $f \in \langle F \rangle$,

E.g. $A_2 = V(a) \setminus V(c)$, then $ax - cy \in F \longmapsto (-cy, ax)$.

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Modified KSW's Algorithm and CGB Computation

 The new technique is applied to the algorithm in (Kapur et al. 2010) to compute comprehensive Gröbner bases.

Exa.	heuristics(Reduce)	Suzuki-Sato(Risa/Asir)	New(Singular)
F6	0.590	error	0.310
F8	> 1h	0.6708	0.650
S1	> 1h	error	0.120
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 ANY algorithm for computing CGS can use this new technique to compute CGB.



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 - CGB is made monic in K[U, X], i.e. $LC_U(CGB)$ are monic.



Example

Given an ideal

 $I=\langle -2ux^2-vxy,-4vy^2+(-2u+2v)\subseteq \rangle K[u,v][x,y]$ and a lexicographical term order > with $x>y\gg u>v$.

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A branch is represented by $(E = \{e_1, \dots, e_k\}, N = \{n\})$, which defines the set of specializations V(E) - V(N).



GB vs. CGB

	Gröbner Basis	Comprehensive Gröbner
minimal	Proper subsets not GB	Proper subsets not CGB.
monic	LC(g)=1	LC(g) is monic.
reduced	polynomials in normal form	
canonical	GB is reduced.	

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- Starting with KSWCGB, compute a minimal CGB (MCGB), with a goal of achieving the canonical CGB (CGB) which is both minimal and reduced.

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- Result: a CGB of I which contains only essential polynomials, i.e. a minimal CGB of I.

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Example

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 - For $\sigma: u = v = 0$, $\sigma(I) = \langle x, x + 1 \rangle$, implying $1 \in \sigma(I)$. Neither $\sigma(f)$ nor $\sigma(g)$ can reduce it to 0, implying that h = g - f is essential $(\sigma(h) = 1)$.

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 - In each branch (A_i, G_i) , $f \in G_i$: look for a covering of f by $CGB G_i$ in A_i (i.e. under all specializations in A_i):
 - a) $\sigma_i(\mathbf{G}_i)$ is minimal for $\forall \sigma_i \in \mathbf{A}_i$: enough to check if $LT(\sigma_i(f)) \in LT(\sigma_i(CGB G_i))$.
 - b1) If there is no such a covering in A_i , then f is essential w.r.t. CGB, and the algorithm terminates.
 - b2) Otherwise, check the next branch where *f* appears in the corresponding Gröbner basis.



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- Given $f \in CGB$, to check if f is essential (w.r.t. CGB):
 - Goal: find a non-empty subset B of the parameter space such that f has no covering by CGB – {f} in B.
 - Only need to consider branches of the form $(A_i, G_i) \in CGS$ with $f \in G_i$.
 - For any branch (A_j, G_j) with $f \notin G_j$, there is no need to check if f is covered by $G_j \subseteq CGB \{f\}$ since A_j, A_i are disjoint.
 - In each branch (A_i, G_i) , $f \in G_i$: look for a covering of f by $CGB G_i$ in A_i (i.e. under all specializations in A_i):
 - a) $\sigma_i(G_i)$ is minimal for $\forall \sigma_i \in A_i$: enough to check if $LT(\sigma_i(f)) \in LT(\sigma_i(CGB G_i))$.
 - b1) If there is no such a covering in A_i , then f is essential w.r.t. CGB, and the algorithm terminates.
 - b2) Otherwise, check the next branch where *f* appears in the corresponding Gröbner basis.
 - If f has a covering in each of such branches, then f is non-essential (redundant).

Example

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First, compute CGS and CGB using the KSW algorithm:

	branch	basis	LT
1	$3u-2v\neq 0 \land v\neq 0$	$\{g_1, g_2\}$	$\{y, x^2\}$
2	$v = 0 \land u \neq 0$	$\{g_2, g_5\}$	$\{y, x^2\}$
3	$u=0 \wedge v=0$	$\{g_{2}\}$	{ y }
4	$3u-2v=0 \land v\neq 0$	$\{g_5, g_4\}$	$\{z,x^2\}$

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$$CGB = \{g_1 = (u - (2/3)v)y + (-(4/3)u^2 - (1/2)uv + (4/3)v^2)z,$$

$$g_2 = vx^2 - 3y + (4u + (11/2)v)z,$$

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Example 3 (contd.)

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- g_5 appears in A_2 with LT x^2 : g_4 covers it with LT x^2 ;
- g₅ appears in A₄ with LT z: g₁ covers it with LT z.



When a Polynomial Is Non-Essential

- $f \in CGB$ is non-essential w.r.t. CGB:
 - Update CGS by substituting f's covering for each occurrence of f;
 - Remove f from CGB.
- In Example 3, g₅ is non-essential w.r.t. CGB:

Example

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• g_4 appears in A_2 with LT x^2 : $CGB - G_2 = \{g_1\}$ doesn't cover g_4 in A_2 .



Example 3 (result)

Finally, we achieve a minimal CGB of / w.r.t. >:

$$\begin{split} M &= \{g_1 = (u - (2/3)v)y + (-(4/3)u^2 - (1/2)uv + (4/3)v^2)z, \\ g_2 &= vx^2 - 3y + (4u + (11/2)v)z, \\ g_3 &= ux^2 - 2y + (4u + 4v)z\}. \end{split}$$

GB vs. CGB

	Gröbner Basis	Comprehensive Gröbner
minimal	Proper subsets not GB	Proper subsets not CGB
monic	LC(g) = 1	LC(g) is monic.
reduced	polynomials in normal form	simplification violates CGBness
canonical	GB is reduced.	CGB is minimal and reduced

Towards a Canonical CGB (CCGB)

- There can be multiple MCGBs of the same parametric ideal.
 - In Example 3, besides *M*, it's easy to check that both

$$M_1 = \{g_1, g_2, g_4\}$$

and

$$M_2 = \{g_1, g_2, g_5\}$$

are MCGBs of I.

These MCGBs are comparable using the set ordering w.r.t.
 :

$$M < M_1 < M_2$$

since $g_1 < g_2 < g_3 < g_4 < g_5$.

 The least MCGB under the set ordering w.r.t. > since this is a total ordering.



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- For each specialization σ of a parametric ideal I, for every minimal headterm of specialized polynomials in $\sigma(I)$, pick the least polynomial in I which under σ has this headterm. Let S be the set of all such polynomials.

$$S = \bigcup_{\sigma} \{ \text{the least } p \in I \mid LT(\sigma(p)) \text{ is minimal } \in LT(\sigma(I)) \}$$

Lemma: S is finite and is a CGB.

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Theorem (Kapur, JSSC 2017) Let $C \subseteq S$ be a subset of polynomials after removing from S all redundant polynomials in the descending order. C is the least CGB among all CGBs of I and is unique.

A completion Procedure for cgb MCGB directly from a parametric basis

See Kapur and Yang in ISSAC 2016,

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- Integrate into an SMT solver.
- Study its effectiveness.

