Implementation of Uniform Interpolation Algorithms

by

José Abel Castellanos Joo

B.Tech., Universidad de las Américas Puebla, 2015

THESIS

Submitted in Partial Fulfillment of the
Requirements for the Degree of

Master of Science
Computer Science

The University of New Mexico

Albuquerque, New Mexico

October, 2020

Dedication

To my family.

Acknowledgments

First, I express immense gratitude to my advisor Prof. Deepak Kapur for his guidance and support during the development of my thesis work. His attention on intuitive examples and work of high quality has reshaped my approach towards research in general.

My appreciation for the committee members cannot be quantified in the standard model of numbers. I appreciate their patience towards me. In particular, I would like to thank Dr. Mark Marron of Microsoft Research for discussions regarding the performance of my implementation and how to show evidence that the implementation work can outperform other existing implementations if the code were to be designed correctly. Additionally, I would like to express my appreciation towards Prof. Veroff, who kindly pointed out how to improve several details in the write-up, which were incorrect.

I would like to acknowledge Prof. Naijun Zhang for his support and hospitality during a short academic staying at the Institute of Software Chinese Academy of Sciences, where I initially started working on the implementation work using the C++ language.

Finally, I would like to thank my family and friends whose unconditional love and support where the motivation for me to keep working on the project.

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Abstract

This thesis discusses algorithms for the uniform interpolation problem and presents their implementation for the following theories: (quantifier-free) equality with uninterpreted functions (EUF), unit two variable per inequality (UTVPI), and theoretic aspects for the combination of the two previous theories. The uniform interpolation algorithms implemented in this thesis were originally proposed in [28].

Refutational proof-based solutions are the usual approach of many interpolation algorithms [22, 37, 36]. The approach taken in [28] relies on quantifier-elimination heuristics to construct a uniform interpolant using one of the two formulas involved in the interpolation problem. The latter makes it possible to study the complexity of the algorithms obtained compared to refutational-based solution which rely on the efficiency of SMT solvers.

It is not always possible to find a uniform interpolant for every formula in the combined theory of EUF and UTVPI [9]. Hence, the thesis work implements an algorithm for a subset of formulas in the combined theory which the existence of uniform interpolants is guaranteed. Additionally, the thesis work implements a Nelson-Oppen

interpolation framework [50] to combine the uniform interpolating algorithms in previous sections.

The implementation uses Z3 [17] for parsing purposes and satisfiability checking in the combination component of the thesis. Minor modifications were applied to Z3's enode data structure in order to label and distinguish formulas efficiently (i.e. distinguish A-part, B-part). The project can easily be integrated into the Z3 solver to extend its functionality for verification purposes using the Z3 plug-in module.

The major results of the project are the following:

- Implementation of Kapur's uniform interpolating algorithm for theories EUF and UTVPI.
- Modification and implementation of the Phase III in Kapur's uniform interpolation algorithm for EUF. As a byproduct, an application in membership testing in conjunction of Horn clauses is obtained.
- Experimental evidence of uniform interpolants is provided as well as performance results of the implemented systems.
- An partially sound uniform interpolation algorithm for the combined theory of EUF and UTVPI is proposed and proven correct for a suitable fragment of the aforementioned combined theory.

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Chapter 1

Introduction

Modern society is witness to the tremendous impact computer software has had in recent years. The benefits of this massive automation is endless. On the other hand, when software fails, it becomes a catastrophe ranging from economic loss to threats to human life.

Due to strict and ambitious schedules and emphasis on profitability, many software products are shipped with unseen and unintentional bugs which might potentially put at risk people's lives. Several approaches have been used to improve software quality. However, many of these approaches offer partial coverage or might take an abysmal amount of human effort. Thus, these approaches cannot be considered practical. Formal methods aim to bring a unique combination of automation, rigor, and efficiency (whenever efficient algorithms exit for the verification task). This thesis discusses a particular problem in software verification known as *the interpolation problem* for the theories of the quantifier-free fragment of equality with uninterpreted functions (EUF) and unit two variable per inequality (UTVPI) and their combination. These two theories have been studied extensively and researchers have found several applications including verification of hardware [6] and useful abstract interpretation domains [39].

1.1 Problem Statement

An interpolant of a mutually inconsistent pair of logical formulas (α, β) is a logical formula γ such that α implies γ, $\beta \wedge \gamma$ is logically inconsistent, and γ only has common symbols of α and β. Informally this means that the interpolant 'belongs' to the consequence of α, and 'avoids' being part of the consequence of β. Not surprisingly, this intuition is in software verification routines where the first formula models a desirable state/property (termination, correctness) of a computer program, and the second formula models the set of undesirable states (non-termination, errors, crashes) of such software. In Chapter 2, an extensive review of the formal concept is provided.

Even though interpolants are not an immediate concern in verification problems, their use is found in the core algorithms of the following two applications:

- Refinement of abstract models: In order to improve coverage and decrease the complexity in verification problems, abstract interpretation has become an effective technique to accomplish the latter together with model checking. Despite the fact that the methodology provides sound results, it is certainly not complete. Several abstractions do not capture the semantics of programs due to the *over-approximation* approach. Interpolation techniques can be used to strengthen predicate abstractions by using interpolants constructed from valid traces in the abstract model [13, 35, 26].

- Invariant generation: following the same idea as in the previous case, *if a fixed point* [27] *is obtained in the refinement process*, we can obtain a logical invariant of computer programs. The interpolation generation approach in this application can be understood as a *lazy framework* similar to SAT/SMT algorithms. The former is about the production of interpolants, the latter is for assignments/models respectively. Both *block/learn* new formulas in order to find their results.

1.2 Related work

There are several existing interpolation algorithms for the theories discussed in the thesis work. On the one hand, there are algorithms relying on refutational proofs. The interpolant is constructed using a recursive function over the structure of the proof tree. In [36, 37] the author defines an interpolation calculus. This particular approach uses a proof tree produced by the SMT solver Z3 and does not need to modify any of Z3's internal mechanisms. Among the advantages of this approach is that theory combination is given for free since the SMT solver takes care of this problem. On the other hand, the decision procedures involved in Z3 are not sufficiently integrated with its proof-producing mechanism in the sense that it is possible to find intermediate formulas in a proof-tree without explanation introduced as lemmas. The latter impairs the interpolation calculus aforementioned because it derives an interpolant by following specific rules of inference.

In [50] the authors introduced a Nelson-Oppen framework to compute interpolants. For the convex-case, the approach only exchanges equalities as required by the Nelson-Oppen framework. For the non-convex case, the authors require a resolution-based refutation proof to compute interpolants using Pudlak's algorithm. They introduced a special class of theories known as *equality interpolating theories.* A theory $\mathcal{T}$ belongs to this class if whenever $\mathcal{T}$ a mixed equality $a = b$ (an equality which contains symbols from the two formulas in the interpolating problem) is proved, then there exists a common term t in the language of $\mathcal{T}$ (known as the interpolating-term) such that $\mathcal{T} \models a = t$ and $\mathcal{T} \models t = b$. The property facilitates formula-splitting for interpolation purposes. In [22] the authors modify a resolution-based refutation proof by introducing common-terms in the proof in order to produce interpolants in what is called colorable-proofs, which are proof trees which do not contain AB-mixed literals. This is pointed as an improvement to the approach followed in [50] which executes a similar idea but it is done progressively as the proof-tree is built and does not require *equality propagating* theory solvers [1]. However, this result is not generalizable to non-convex theories due to internal constraints.

Reduction-based approaches transforms the interpolation problem into a query for some solver related to the theory. An example of this approach can be found in [47] where the authors use a linear-inequality solver to provide an interpolant for the theory of linear inequalities over the rational/real numbers ($LIA(\mathbb{Q})/LIA(\mathbb{R})$). Additionally, they integrate the procedure with a *hierarchical reasoning* approach in order to incorporate the signature of a theory for (quantifier-free) equalities with uninterpreted functions.

1.3 Outline of the thesis

- Chapter 2 provides background of definitions and descriptions of the decision procedures used in the thesis work.
- Chapters 3 discusses Kapur's uniform interpolating algorithm for the theory of EUF. A modification to the Phase III of Kapur's algorithm is proposed by introducing a data structure for Horn clause processing. Complexity results concerning the modification proposed are reviewed. One application of this

[1] The authors in [50] require that the theory solvers keep track of the interpolating-term and propagate this term whenever possible

data structure is discussed concerning the membership checking of ground Horn clauses in the theory of ground Horn clauses. The chapter provides experimental evaluation of the implementation of Kapur's algorithm using a randomized benchmark.

- Chapter 4 explains Kapur's uniform interpolating algorithm for the UTVPI theory. A description of the implementation work introduces an indexing data structure to efficiently represent an UTVPI formula. Experimental evaluation is provided at the end of the chapter using a randomized benchmark for the latter.

- Since the combined theory of EUF and UTVPI does not have the uniform interpolation property [9], Chapter 5 discusses the implementation of a theory combination algorithm for the theories EUF and UTVPI using the uniform interpolation algorithm from Chapter 3 and 4. Additionally, an algorithm for computing uniform interpolants is proposed which is sound if the input formula satisfies a certain property.

1.4 Contributions

The contributions of the thesis can be summarized as follows:

1. Implementation of the uniform interpolation algorithm for the theory EUF proposed in [28].

2. Formulation and implementation of a new procedure for checking unsatisfiability of grounded equations in Horn clauses using a congruence closure algorithm with explanations used in the implementation of item 1.

3. Implementation of the uniform interpolation algorithm for the theory UTVPI proposed in [28].

4. Implementation of the combination procedure for the interpolating algorithm proposed in [50] in order to combine the implementations of the uniform interpolation algorithm for EUF and UTVPI.

Chapter 2

Preliminaries

This chapter reviews basic concepts from first-order logic that are used in the rest of this thesis. We will pay particular attention to their language and semantics since these are fundamental concepts necessary to understand the algorithmic constructions to compute interpolants. For a comprehensive treatment on the topic, the reader is suggested the following references [38, 21].

2.1 First-Order Predicate Logic

2.1.1 Language

A language is a collection of symbols of different sorts equipped with rules of composition that effectively tells us how to recognize elements that belong to the language [48]. In particular, a first-order language is a language that expresses boolean combinations of predicates using terms (constant symbols and function applications). In mathematical terms,

Definition 2.1.1. *A first-order language (also denoted signature) is a triple* $\langle \mathfrak{C}, \mathfrak{P}, \mathfrak{F} \rangle$

of non-logical symbols where:

- $\mathfrak{C}$ *is a collection of constant symbols*
- $\mathfrak{P}$ *is a collection of n-place predicate symbols, with* $n \geq 0$
- $\mathfrak{F}$ *is a collection of n-place function symbols, with* $n > 0$

including logical symbols like quantifiers(universal ($\forall$), *existential*($\exists$)), *auxiliary symbols like parenthesis, propositional connectives (implication* ($\rightarrow$), *conjunction* ($\wedge$), *disjunction* ($\vee$), *negation* ($\neg$)), *and a countable number of variables* Vars *(i.e.* $\mathrm{Vars} = \{v_1, v_2, \dots\}$).

The rules of composition distinguish two objects, terms *and* formulas, *which are defined recursively as follows:*

- *Any variable symbol or constant symbol is a term.*
- *If* $t_1, \dots, t_n$ *are terms and* f *is an n-ary function symbol, where* $n > 0$, *then* $f(t_1, \dots, t_n)$ *is also a term.*
- *If* $t_1, \dots, t_n$ *are terms and* P *is an n-ary predicate symbol, then* $P(t_1, \dots, t_n)$ *is formula.*
- *If* x *is a variable and* ψ, φ *are formulas, then* $(\neg\psi), (\forall x.\psi), (\exists x.\psi)$ *and* $(\psi \Box \varphi)$ *are formulas where* $\Box \in \{\rightarrow, \wedge, \vee\}$
- *No other expression in the language can be considered terms nor formulas if such expressions are not obtained by the previous rules.*

For notational purposes, we compactly represent a tuple $\langle x_1, \dots, x_n \rangle$ *of variables as* $\underline{x}$. *Abusing the notation, a formula of the form* $\forall \underline{x}.\phi(\underline{x})$ *(resp.* $\exists \underline{x}.\phi(\underline{x})$) *denotes the formula* $\forall x_1.\forall x_2 \dots \forall x_n.\phi(x_1, \dots, x_n)$ *(resp.* $\exists x_1.\exists x_2 \dots \exists x_n.\phi(x_1, \dots, x_n)$).

2.1.2 Semantics

In order to define a notion of truth in a first-order language, it is necessary to associate for each non-logical symbol (since logical symbols have classical semantics from propositional logic and first order logic) a denotation or mathematical object and an *assignment* to the collection of variables. The two previous components are part of a *structure* [21] (or interpretation [48]) for a first-order language.

Definition 2.1.2. *Given a first-order language $\mathfrak{L}$, an interpretation $\mathfrak{I}$ is a pair $(\mathfrak{A}, \mathfrak{J})$, where $\mathfrak{A}$ is a non-empty domain (set of elements) and $\mathfrak{J}$ is a map that associates to the non-logical symbols from $\mathfrak{L}$ the following elements:*

- *$\mathfrak{I}$ assigns to each constant symbol c an elements $c^{\mathfrak{A}} \in \mathfrak{A}$*
- *$\mathfrak{I}$ assigns to each n-place predicate symbol P, where $n \geq 0$, an n-ary relation $P^{\mathfrak{A}} \subseteq \mathfrak{A}^n$*
- *$\mathfrak{I}$ assigns to each n-place function symbol f, where $n > 0$, an n-ary operation $f^{\mathfrak{A}}$ on $\mathfrak{A}$, i.e. $f^{\mathfrak{A}} : \mathfrak{A}^n \to \mathfrak{A}$*

An assignment $s : Vars \to \mathfrak{A}$ is a map between variables to elements from the domain of the interpretation.

With the definition of interpretation $\mathfrak{I}$ and assignment s, we can recursively define a notion of *satisfiability* (denoted by the symbol $\models_{\mathfrak{I},s}$) as a free extension from atomic predicates (function application of predicates) to general formulas as described in [21]. For the latter, we need to extend the assignment function to all terms in the language.

Definition 2.1.3. *Let $\mathfrak{I} = (\mathfrak{A}, \mathfrak{J})$ be an interpretation and s an assignment for a given language, Let $\bar{s} : Terms \to A$ be defined recursively as follows:*

- $\bar{s}(c) = c^{\mathfrak{I}}$
- $\bar{s}(f(t_1, \ldots, t_n)) = f^{\mathfrak{I}}(\bar{s}(t_1), \ldots, \bar{s}(t_n))$

Notice that the extension of s depends on the interpretation used.

Definition 2.1.4. *Given an interpretation $\mathfrak{I} = (\mathfrak{A}, \mathfrak{J})$, an assignment s, and ψ a formula, we define $\mathfrak{I} \models_s \psi$ (read ψ is satisfiable under interpretation $\mathfrak{I}$ and assignment s) recursively as follows:*

- $\models_{\mathfrak{I},s} P(t_1, \ldots, t_n)$ *if and only if* $\langle \bar{s}(t_1), \ldots, \bar{s}(t_n) \rangle \in P^{\mathfrak{I}}$
- $\models_{\mathfrak{I},s} \neg\psi$ *if and only if it is not the case that* $\models_{\mathfrak{I},s} \psi$
- $\models_{\mathfrak{I},s} \psi \wedge \varphi$ *if and only if* $\models_{\mathfrak{I},s} \psi$ *and* $\models_{\mathfrak{I},s} \varphi$
- $\models_{\mathfrak{I},s} \psi \vee \varphi$ *if and only if* $\models_{\mathfrak{I},s} \psi$ *or* $\models_{\mathfrak{I},s} \varphi$
- $\models_{\mathfrak{I},s} \psi \rightarrow \varphi$ *if and only if* $\models_{\mathfrak{I},s} \neg\psi$ *or* $\models_{\mathfrak{I},s} \varphi$
- $\models_{\mathfrak{I},s} \forall x.\psi$ *if and only if for every* $d \in \mathfrak{A}$, $\models_{\mathfrak{I},s_{x\mapsto d}} \psi$, *where* $s_{x\mapsto d} : Vars \rightarrow \mathfrak{A}$ *is defined as*

$$s_{x\mapsto d}(y) = \begin{cases} s(y) & \text{if } y \neq x \\ d & \text{if } y = x \end{cases}$$

- $\models_{\mathfrak{I},s} \exists x.\psi$ *if and only if exits* $d \in \mathfrak{A}$, $\models_{\mathfrak{I},s_{x\mapsto d}} \psi$, *where* $s_{x\mapsto d}$ *is defined as in the previous item.*

If an interpretation and assignment satisfies a formula, then we say that the interpretation and the assignment are a model for the respective formula. A collection of formulas is satisfied by an interpretation and assignment if these model each formula in the collection. A formula ψ is said to be a valid *formula of the interpretation $\mathfrak{I}$ when $\models_{\mathfrak{I},s} \psi$ for all possible assignments s.*

Additionally, if all the models $(\mathfrak{I}, s)$ *in a language of a collection of formulas* Γ *satisfy a formula* ψ*, then we say that* Γ *logically implies* ψ *(written* $\Gamma \models \psi$*). For the latter,* ψ *is said to be a* valid *formula of the model* $(\mathfrak{I}, s)$*.*

2.2 Decision Procedures

Given a theory $\mathcal{T}$ and a formula ψ in the language of $\mathcal{T}$, is it possible to know $\models_{\mathcal{T}} \psi$? The last question is known as the decision problem for $\mathcal{T}$. This question has been studied extensively for many theories of interest [4].

Regarding the decidability of the theories discussed in the thesis work, it is known that the quantified EUF theory is undecidable [4] Nonetheless, the quantifier-free fragment of EUF and the restriction imposed in the decision problem for the UTVPI theory allow efficient algorithms to decide validity and satisfiability in their respective theories [42, 20, 34]. The ordered abelian group theory is decidable as well [21].

In the rest of this section we review some decision problems and provide references to their respective decision procedures used in the implementation work of the thesis.

2.2.1 Satisfiability and Satisfiability Modulo Theories

The satisfiability problem consists of finding a propositional assignment for a propositional formula. This problem is at the core level of complexity theory, defining an important class of problems known as NP, which includes problems whose algorithms seem to be intractable. Developments in algorithms and heuristics [30, 40] have made it possible to use satisfiability algorithms to solve real-world problems in verification [1].

[1]These advances do not provide an answer to the well-known P vs. NP problem. There are results indicating a class of problem instances for many of the SAT algorithms which

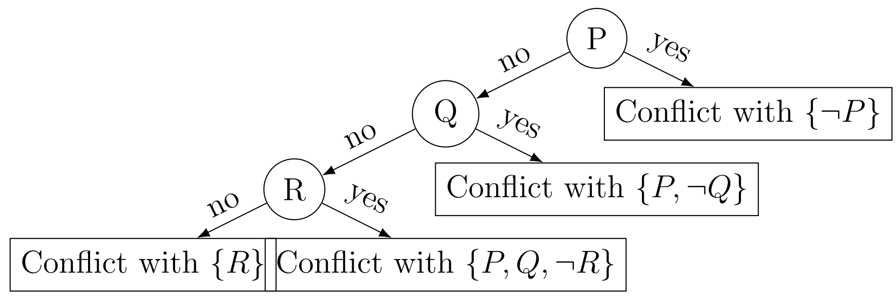

Figure 2.1: Example of DPLL execution on $\{\{\neg P\}, \{P, Q, \neg R\}, \{R\}, \{P, \neg Q\}\}$

The DPLL algorithm [16] (and other extensions) is the algorithm found in many SAT solvers. Fundamentally, it is a search-based algorithm which implements operators (decide, unit-propagation, backtrack) to find a satisfiable assignment. If the algorithm is not able to find a satisfying assignment for a formula, then it is possible to extract a *resolution proof* based on the traces of the search operations.

We can extend this approach to work not only with propositional variables but with terms of more complex signatures [33]. If we are given a boolean combination of formulas from any theory that is capable of deciding the satisfiability of any conjunction of formulas in the theory, by using a *lazy framework* integration with a SAT solver it is possible to find either a model or declare unsatisfiable such boolean combination as follows: (i) first abstract the literals in the boolean combination to (pseudo) boolean propositions; (ii) find a satisfying assignment (using a SAT solver) of the (pseudo) boolean propositions; (iii) using the theory solver, test if the collection of positive and negative literals induced by the pseudo boolean variables is satisfiable; (iv) if it is then declare the formula satisfiable, otherwise *learn* (or block) the pseudo boolean clause obtained (by negating the conjunction of boolean constraints) in the SAT solver and repeat from step (ii); (v) if it is not possible to find a satisfying assignment for the pseudo boolean variables, declare the original formula to be unsatisfiable.

cannot be solved in less that $\mathcal{O}(2^n)$ steps [30].

These algorithms are used in the last section of the thesis work. The implementation for the interpolation combination method in [50] requires a resolution-based proof in order to compute partial interpolants by integrating Pudlak's algorithm.

2.2.2 Congruence Closure

The congruence closure problem consists of given a conjunction of equalities and disequalities ψ determine if an equality $u = v$ follows from the consequence generated by $\models_{EUF} \psi$.

As noted in [14], it is just sufficient to compute the minimal relation containing the initial relation defined by the equalities in ψ closed under reflexivity, symmetry, transitivity and congruence considering all the sub-terms in the formulas ψ and $u = v$.

The authors in [20, 42] independently formulated an optimized version of the algorithm afore mentioned. Their key observation was to introduce a list of pointers keeping track of the antecedents nodes in the abstract syntax tree induced by the formulas. The latter allows a fast signature checking in order to determine if two nodes are equivalent under the equivalence relation of the formulas. The algorithm in [20] has better runtime complexity $\mathcal{O}(n \log n)$ since it also implements a 'modify the smaller half' (using the union-find data structure). The congruence closure algorithm in [20] has a runtime complexity of $\mathcal{O}(n^2)$. Nonetheless, the authors reported no significant advantage of the first approach because, for verification purposes, the list of antecedents is usually small. Both approaches provide the FIND, MERGE operations.

In [45], the authors introduced a Union-Find data structure that supports the additional Explanation operation. This operation receives as input an equation between constants. If the input equation is a consequence of the current equivalence relation defined in the Union Find data structure, the Explanation operation returns the minimal sequence of equations used to build such equivalence relation, otherwise it returns 'Not provable'. A proper implementation of this algorithm extends the traditional Union-Find data structure with a *proof-forest*, which consists of an additional representation of the underlying equivalence relation that does not compress paths whenever a call to the Find operation is made. For efficiency reasons, the Find operation uses path compression and weighted union.

The main observation in [45] is that, in order to recover an explanation between two terms, by traversing the path between the two nodes in the proof tree, the last edge in the path is guaranteed to be part of the explanation. Intuitively, this follows because only the last Union operation was responsible for merging the two classes into one. Hence, we can recursively recover the rest of the explanation by recursively traversing the sub-paths found.

Additionally, the authors in [45] extended the Congruence Closure algorithm [44] using the above data structure to provide Explanations for the theory of EUF. The congruence closure algorithm is a simplification of the congruence closure algorithm in [20]. The latter combines the traditional *pending* and *combine* list into one single list, hence removing the initial *combination* loop in the algorithm in [20].

The implementation work utilizes the latter congruence closure with explanations for the interpolation algorithm of the theory EUF. The idea was to use the explanation operator to construct uncommon-free Horn clauses.

2.2.3 Satisfiability of Horn clauses with ground equations

In [24] it was proposed an algorithm for testing the unsatisfiability of ground Horn clauses with equality. The main idea was to interleave two algorithms: *implicational propagation* (propositional satisfiability of Horn clauses) that updates the truth value of equations in the antecedent of the input Horn clauses [19]; and *equational propagation* (congruence closure for grounded equations) to update the state of a Union-Find data structure [23] that keeps the minimal equivalence relation defined by grounded equations in the input Horn clauses.

The author in [24] defined two variations of his algorithms by adapting the Congruence Closure algorithms in [20, 42]. Additionally, modifications in the data structures used by the original algorithms were needed to make the interleaving mechanism more efficient.

Our implementation uses the equality propagation mechanism in the algorithm proposed by Gallier when we have to deal with Horn clauses with ground equations. In addition, we also needed to design some modifications of the original formulation so it can integrate with the congruence closure with explanation algorithm mentioned in the previous section.

2.2.4 Nelson-Oppen framework for theory and interpolation combination

The theory combination problem consists on taking a formula from the union of two (or more) disjoint languages and tell if such formula is satisfiable or not in the combined theory, i.e. a theory resulting after putting together two (or more) axiomatizations.

In [41] the authors defined a procedure to achieve the above problem. The key idea is to *purify* the sub-formulas by including additional constant symbols equating sub-terms such that the resulting formula can be splitted into components of the appropriate language for each theory solvers to work with. The separation naturally will hide relevant information to the solvers, and they might not be able to decide satisfiability correctly. The authors noticed that to solve the above problem it is enough to share disjunction of equalities between the combined theories of shared terms. In addition, they proved that some theories have the following property:

Definition 2.2.1. *Let $\mathcal{T}$ be a theory. We say that $\mathcal{T}$ is a* convex theory *if a finite conjunction of formulas in $\mathcal{T}$ $\psi = \bigwedge_{i=1}^{m} \psi_i$ satisfies $\psi \models_{\mathcal{T}} \bigvee_{j=1}^{n} x_j = y_j$, then exists $k \in \{1, \ldots, n\}$ such that $\psi \models_{\mathcal{T}} x_k = y_k$.*

Hence, it is important to detect whether the theories involved are convex or not since this can improve performance since convex theories do not need to share disjunctions of equalities as mentioned before (since all these disjunctions imply a single equality).

Example 2.2.1.1.

- *The conjunctive fragment of equality logic is an example of a convex theory since it can always decide the membership of an equation in the equivalence relation.*
- *The theory of UTVPI over the integers is an example of non-convex theory. To see the latter consider $1 \leq x \wedge x \leq 2 \models_{UTVPI(\mathbb{Z})} 1 = x \vee 2 = x$. However, it is not the case that $1 \leq x \wedge x \leq 2 \models_{UTVPI(\mathbb{Z})} 1 = x$ nor $1 \leq x \wedge x \leq 2 \models_{UTVPI(\mathbb{Z})} 2 = x$.*

An interpolation combination framework as proposed in [50] follow the same idea towards theory combination. Inductively, they define *partial interpolants* for each shared equality/disjunction of equalities until some theory reaches the unsatisfiable state, which is expected since an interpolant is a pair a mutually contradicting formulas.

This framework was implemented in the thesis work. This framework was chosen in particular since it allows working with non-convex theories (in our case for the theory of UTVPI over $\mathbb{Z}$).

2.3 Mathematical Theories

A theory $\mathcal{T}$ is a collection of formulas that are closed under logical implication, i.e. if $\mathcal{T} \models \psi$ then $\psi \in \mathcal{T}$. This concept is quite relevant for our thesis work since we will focus on two theories, the quantifier-free fragment of the theory of equality with uninterpreted functions (EUF), and the theory of unit two variable per inequality (UTVPI).

For some theories it is enough to provide a collection of formulas (known as the axioms of the theory). For the case of the theories of interest for the thesis, the axiomatization is the following:

2.3.1 Equality with uninterpreted functions

Definition 2.3.1. *Let $\mathfrak{L}_{EUF} = \{\{c_1, \ldots, c_m\}, \{=\}, \{f_1, \ldots, f_n\}\}$ be the language of EUF. The axioms of the theory are:*

- *(Reflexivity)* $\forall x. x = x$
- *(Symmetry)* $\forall x. \forall y. x = y \rightarrow y = x$
- *(Transitivity)* $\forall x. \forall y. \forall z. (x = y \wedge y = z) \rightarrow x = z$
- *(Congruence) For every function f term of n-arity, where $n > 0$ and $2n$ variables $x_1, \ldots, x_n, y_1, \ldots, y_n$ we have that* $\forall x_1 \ldots \forall x_n . \forall y_1 \ldots \forall y_n . (x_1 = y_1 \wedge \cdots \wedge x_n = y_n) \rightarrow f(x_1, \ldots, x_n) = f(y_1, \ldots, y_n)$

2.3.2 Ordered abelian groups

In order to describe the UTVPI theory we will first introduce the language and theory of an ordered abelian group.

Definition 2.3.2. *Let* $\mathfrak{L}_{Ord-G} = \{\{0\}, \{=, \leq\}, \{+, -\}, \}$ *be the language of an ordered abelian group* G*. The axioms of the theory are:*

- $\forall x.\forall y.\forall z.x + (y + z) = (x + y) + z$
- $\forall x.\forall y.x + y = y + x$
- $\forall x.x + 0 = x$
- $\forall x.x + (-x) = 0$
- $\forall x.\forall y.\forall z.x \leq y \rightarrow x + z \leq y + z$
- $0 \neq 1 \wedge 0 \leq 1$

2.4 Interpolants

Following the notation in [50], we denote $\mathcal{V}(\psi)$ to be the set of non-logical symbols, variables and constants of formula ψ. Given an instance for the interpolation problem (A, B) [2], we distinguish the following categories:

- ψ is *A-local* if $\mathcal{V}(\psi) \subseteq \mathcal{V}(A) \setminus (\mathcal{V}(A) \cap \mathcal{V}(B))$
- ψ is *B-local* if $\mathcal{V}(\psi) \subseteq \mathcal{V}(B) \setminus (\mathcal{V}(A) \cap \mathcal{V}(B))$
- ψ is *AB-common* if $\mathcal{V}(\psi) \subseteq \mathcal{V}(A) \cap \mathcal{V}(B)$
- ψ is *A-pure* when either $\mathcal{V}(\psi) \subseteq \mathcal{V}(A)$
- ψ is *B-pure* when either $\mathcal{V}(\psi) \subseteq \mathcal{V}(B)$

[2] For the rest of the thesis, we will denote the first formula of an interpolation problem as the A-part and the second component as the B-part.

- ψ is *AB-pure* when either ψ is A-pure or ψ is B-pure, otherwise ψ is *AB-mixed*

Example 2.4.0.1. *Consider the following interpolation pair:* $(f(a+2)+1 = c + 1 \wedge f(a+2) = 0, f(c) \leq b \wedge b < f(0))$. *With respect to the previous pair of formulas, we can tell that:*

- *The formula* $f(a+2) = c$ *is AB-pure but not A-local nor B-local nor AB-common*
- *The formula* $\neg(a \leq f(f(b)+1))$ *is an AB-mixed literal*
- *The formula* $a+1 = 1$ *is A-local.*
- *The formula* $c = 0$ *is AB-common.*
- *In general,* $AB-common$ *formulas are not* $AB-pure$ *formulas.*

2.4.1 Craig interpolation theorem

Let α, β, γ be logical formulas in a given theory. If $\models_{\mathcal{T}} \alpha \rightarrow \beta$, we say that γ is an interpolant for the interpolation pair (α, β) if the following conditions are met:

- $\models_{\mathcal{T}} \alpha \rightarrow \gamma$
- $\models_{\mathcal{T}} \gamma \rightarrow \beta$
- Every non-logical symbol in γ occurs both in α and β.

The *interpolation problem* can be stated naturally as follows: given two logical formulas α, β such that $\models_{\mathcal{T}} \alpha \rightarrow \beta$, find the interpolant for the pair (α, β).

In his celebrated result [15], Craig proved that for every pair (α, β) of formulas in first-order logic such that $\models \alpha \rightarrow \beta$, an interpolation formula exists. Nonetheless, there are many logics and theories for which this result does not hold [31].

Usually, we see the interpolation problem defined differently in the literature, where it is considered β' to be $\neg\beta$ and the problem requires that the pair (α, β') be mutually contradictory (unsatisfiable). This definition was popularized by McMillan [36]. This shift of attention explains partially the further development in interpolation generation algorithms since many of these relied on SMT solvers that provided refutation proofs in order to (re)construct interpolants for different theories (and their combination) [32, 11, 37].

Relaxed definitions are considered for the interpolation problem when dealing with specific theories [50], permitting interpreted functions to be included in the interpolant. The latter is justified since otherwise, many interpolation formulas might not exist in different theories or the interpolants obtained might not be relevant (for example, lisp programs). This is formalized as follows:

Definition 2.4.1. *[50] Let $\mathcal{T}$ be a first-order theory of a signature Σ and let $\mathcal{L}$ be the class of quantifier-free Σ formulas. Let $\Sigma_{\mathcal{T}} \subseteq \Sigma$ denote a designated set of interpreted symbols in $\mathcal{T}$. Let A, B be formulas in $\mathcal{L}$ such that $A \wedge B \models_{\mathcal{T}} \bot$. A* theory-specific *interpolant for (A, B) in $\mathcal{T}$ is a formula I in $\mathcal{L}$ such that $A \models_{\mathcal{T}} I$, $B \wedge I \models_{\mathcal{T}} \bot$, and I refers only to AB-common symbols and symbols in $\Sigma_{\mathcal{T}}$.*

Example 2.4.1.1. *In example 2.4.0.1 we can tell $c + 1 = 1$ is not an interpolant simplify because the symbol 1 only appears on the A-part. However, if $\Sigma_{\mathcal{LIA}(\mathbb{Z})}$ contains the interpreted symbols of $LIA(\mathbb{Z})$ (i.e. $+, *, 0, 1, 2, \dots$), then $c+1 = 1$ becomes a* theory-specific *interpolant.*

Notice that $c = 0$ is an interpolant even if the set of interpreted symbols used for interpolation is empty.

2.4.2 Uniform Interpolant

A uniform interpolant is a particular kind of interpolant for an inconsistent pair of formulas. Introduced in [46] as a construction to provide an interpretation for second order intuitionistic propositional logic IpC^2 [3] using intuitionistic propositional logic IpC. Our notion of uniform interpolant is taken from [25] where the authors provide the following definition:

Definition 2.4.2. *Given a theory $\mathcal{T}$ and an existential formula $\exists \underline{e}.\phi(\underline{e}, \underline{z})$, a quantifier-free formula $\psi(\underline{y})$ is said to be a $\mathcal{T}$-*uniform interpolant* of $\exists \underline{e}.\phi(\underline{e}, \underline{z})$ if*

- $\mathcal{T} \models \exists \underline{e}\phi(\underline{e}, \underline{y}) \to \psi(\underline{y})$
- *$\psi(\underline{y})$ is the strongest interpolant (modulo $\mathcal{T}$), i.e. if $\mathcal{T} \models \exists \underline{e}\phi(\underline{e}, \underline{y}) \to \theta(\underline{z}, \underline{y})$, then $\mathcal{T} \models \psi(\underline{y}) \to \theta(\underline{z}, \underline{y})$.*

A theory T has the Uniform Interpolation Property *if every existential formula $\exists \underline{e}.\phi(\underline{e}, \underline{y})$ has a T-uniform interpolant.*

Example 2.4.2.1. *Let us consider $\alpha = \{f(x_1) \neq f(x_2)\}$ with the set of symbols to eliminate $U = \{f\}$ in the EUF theory.*

We can prove that the EUF-uniform interpolant of α is $x_1 \neq x_2$. It is clear that $f(x_1) \neq f(x_2) \models x_1 \neq x_2$. Additionally, by the following lemma we show $x_1 \neq x_2$ is the strongest interpolant:

Lemma 2.4.1. *$x_1 \neq x_2$ implies any θ such that $f(x_1) \neq f(x_2) \models \theta$*

Proof. By induction on the C.N.F. formula θ

[3] I.e. IpC^2 quantifies over propositional variables.

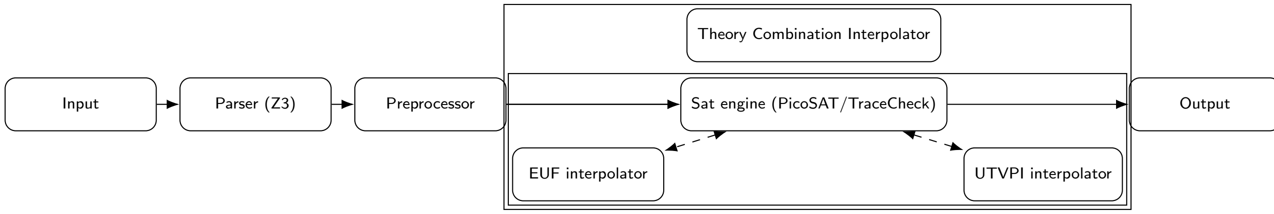

Figure 2.2: General System Diagram

- Base case: $f(x_1) \neq f(x_2) \models x_1 \neq x_2 \wedge x_1 = x_1 \wedge x_2 = x_2$ and no other literal involving x_1, x_2 in EUF are provable by $f(x_1) \neq f(x_2)$.

- Inductive step:

  - Case $f(x_1) \neq f(x_2) \models \psi \wedge \phi :$ Thus, $f(x_1) \neq f(x_2) \models \psi$, $f(x_1) \neq f(x_2) \models \phi$. By IH. $x_1 \neq x_2 \rightarrow \psi$ and $x_1 \neq x_2 \rightarrow \phi$ Therefore, $x_1 \neq x_2 \rightarrow \psi \wedge \phi$

  - Case $f(x_1) \neq f(x_2) \models \psi \vee \phi :$ We can use a congruence closure algorithm to check if an equality belongs or not in any EUF theory, thus we can check if $f(x_1) \neq f(x_2) \models \psi$ or $f(x_1) \neq f(x_2) \models \phi$. Let say W.L.O.G. that $f(x_1) \neq f(x_2) \models \phi$. By IH. $x_1 \neq x_2 \rightarrow \phi$. Thus, $x_1 \neq x_2 \rightarrow \psi \vee \phi$.

□

2.5 General system description

The algorithms implemented in this thesis used the C++ programming language. The overall architecture of the system is the following:

All the decision procedures mentioned in this chapter were implemented except for the SAT/SMT algorithms. For the latter, PicoSAT/TraceCheck[2] and Z3 [17] were chosen as the libraries to work with these algorithms. The rest of this section

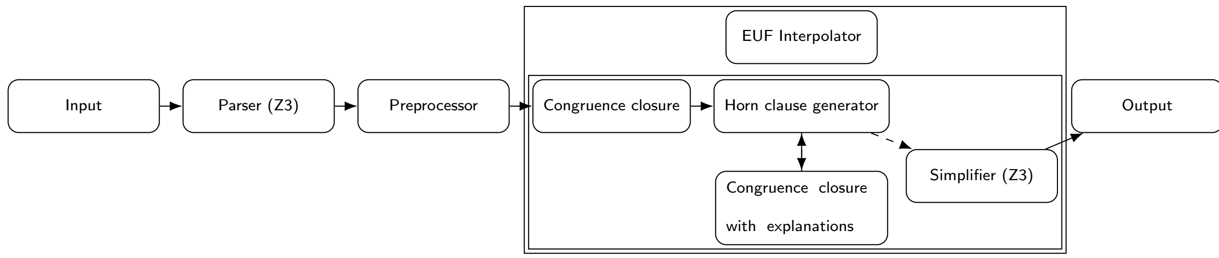

Figure 2.3: EUF Interpolator Diagram

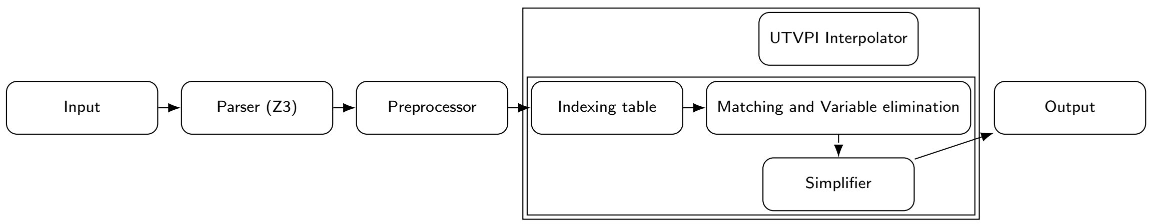

Figure 2.4: UTVPI Interpolator Diagram

discusses some minor modifications implemented in the above mentioned Z3 and the proof format output by PicoSAT/TraceCheck.

2.5.1 Minor modifications to Z3

Z3 standard input is SMTLib2 [1]. This grammar does not provide a standard specification regarding a suitable format to work with interpolants. Interpolation software read interpolant formulas based on the order of appearance in a conjunction [37]. In our case we require two conjuncts of conjunctions of literals in the EUF theory, UTVPI theory or combined theory.

As we can notice in figures 2.2, 2.3, and 2.4, there is preprocessor component which prefixes the names of uninterpreted symbols with the strings a_, b_, c_ to indicate that the symbol name is either an A-local, B-local, or common symbol respectively. We extended Z3's API with functions that test if a formula is A-local, B-local, AB-pure, AB-common based of the definitions in [50] because it is necessary to constantly check this conditions for splitting purposes. Another reason for the latter is justified because the implemented congruence closure algorithm takes as an additional criterion to maintain as representative term an AB-common term. A similar change was implemented in the congruence closure implementation of Z3. Nonetheless, it was irrelevant since Z3's internal structure separates the abstract syntax tree, which is part of its API with the enode data structures, which does not allow the super to modify it. This is the reason why it was not possible to work directly with Z3 congruence closure implementation and a separate implementation was necessary.

2.5.2 PicoSAT/TraceCheck Proof Format

We used PicoSAT/TraceCheck to reconstruct a resolution-based proof necessary for Pudlak's algorithm in the interpolation combination component. Given that Z3 provides a user-friendly proof-producing API [18], why did the implementation work require another SAT solver to obtain the resolution-proof?

There are several reasons for the latter. First, the author of the thesis was not able to find an appropriate configuration of parameters for the SMT solver to provide such proofs. In order to grasp an idea of the latter, it was implemented a Z3 proof parser that generates a pdf compiled by LaTeX. Many examples indicated that Z3 selects more convenient theories to work with some problems. For instance, the formula in pure propositional logic shown in figure 2.5 used proof rules from EUF [4].

Thus, we opted to use the PicoSAT SAT solver which implements the DPLL algorithm. PicoSAT, as many SAT solvers, take as input a DIMACS cnf file which consists of a straightforward language to denote clauses. (Optional) Lines starting

[4] Z3 uses the term monotonicity instead of congruence

```
(declare-fun x1 () Bool)
(declare-fun x2 () Bool)
(declare-fun x3 () Bool)

(assert (or x1 x2))
(assert (or x1 (not x2)))
(assert (or (not x1) x3))
(assert (or (not x1) (not x3)))
(assert x1)
(check-sat)
```

Figure 2.5: Problematic SMT query for resolution proofs

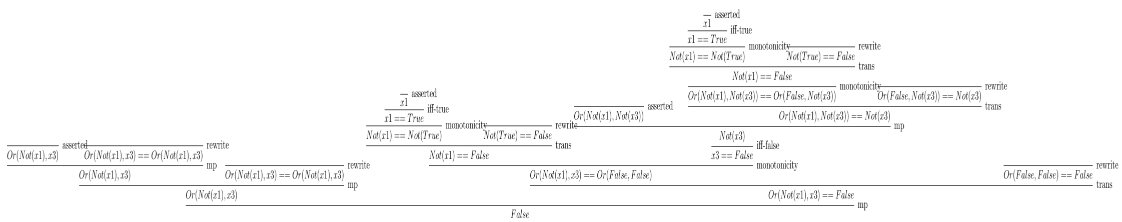

Figure 2.6: Z3 proof of figure 2.5

with the character ‘c’ denote comments, and a single line starting the string ‘p cnf’ followed by two positive integers denote the number of variables and number of clauses respectively. The next lines encode clauses. Each line is a list of integers numbers terminating with 0. Positive number encode non-negated literals whose identifier is the number, and negative numbers encode the negated literal whose identifier is the absolute value of the number.

The proof format produced by PicoSAT consists of an ordered list of clauses which are either from the input problem (facts) or learned during the search. Each line is encoded following the DIMACS format, but extended to include an identifying number at the beginning of each line (which identifies the clause), and a second list of integers after the terminating zero of the clause which denotes the non-ordered list of clause identifiers involved in a hyper resolution step; the resulting clause obtained from this step is precisely the clauses encoded by the line. An additional zero is used to terminate the second list of integers.

Example 2.5.0.1. *The following extended proof trace is obtained after running the PicoSAT solver on the cnf file encoding the formula in example 2.1:*

$$\begin{array}{cccccc}
1 & -1 & 0 & 0 & & \\
2 & -3 & 2 & 1 & 0 & 0 \\
3 & 3 & 0 & 0 & & \\
4 & 1 & -2 & 0 & 0 & \\
6 & -2 & 0 & 1 & 4 & 0 \\
7 & 0 & 1 & 6 & 2 & 3
\end{array}$$

Figure 2.7: Example of extended proof trace by PicoSAT for problem 2.1

As we can notice, the first four lines encode the original input clauses; 1 denotes variable P, 2 denotes variable Q, and 3 denotes variable R. Also, these lines do not include any clause identifier in the second list of number since they are facts. The last two lines denote clauses with identifier 6 and 7. Clause 6 is $\neg Q$, which is obtained after the hyper resolution step using clauses 1 and 4. The last line does not contain elements in the first list since this encodes the contradiction clause.

From the previous example we can observe the list of clause identifiers for the hyper resolution step are not ordered in the sense that we cannot produce multiple resolution steps from the representation. In order to obtain the latter one can implement a unit propagation algorithm and discover such ordering.

TraceCheck is a tool incorporated in the previous version of PicoSAT [43] to verify proof traces. It is also able to obtain a pure resolution proof. The presentation of the proof trace is restricted to contain only two clause identifiers in the second list for each clause.

Example 2.5.0.2. *The following extended proof trace is obtained after running the TraceCheck on the previous proof trace:*

3	3	0	0			
2	1	2	−3	0	0	
4	1	−2	0	0		
1	−1	0	0			
6	−2	0	1	4	0	
7	2	−3	0	1	2	0
8	−3	0	7	6	0	
9	0	8	3	0		

Figure 2.8: Example of extended proof trace by PicoSAT for problem 2.1

Chapter 3

Uniform Interpolation algorithm for the theory of EUF

Interpolation algorithms for the theory of equality with uninterpreted functions are relevant as the core component of verification algorithms. Bounded/unbounded model checking and invariant generation benefit from interpolation algorithms. In [7], the authors introduced a methodology to debug and verify the control logic of pipelined microprocessors by encoding the hardware and its specification into an EUF solver.

Previous work addressing the interpolation problem for EUF has involved techniques ranging from interpolant-extraction from refutational proof trees [36, 37, 49], and colored congruence closure graphs [22]. Kapur's algorithm for computing uniform interpolants employs a different approach using approximated quantifier-elimination, a procedure that given a formula, it produces a logically equivalent formula without some variables [21].

3.1 Kapur's Uniform Interpolation Generation Algorithm for EUF

Kapur's uniform interpolation algorithm for the EUF theory uses quantifier elimination techniques to remove symbols of a given formula. The input problem is a conjunction of equalities and disequalities in the EUF theory and a set of symbols to be eliminated from the input formula, denoted as uncommon symbols from the context of interpolation. In preparation to discuss Kapur's algorithm we need to provide the following definitions.

Definition 3.1.1. *Let f be an $n-ary$ function symbol and $a_1, \ldots, a_n, b$ terms from the EUF language. We say*

$$f(a_1, \ldots, a_n) = b$$

is an $f-equation$ if the terms $a_1, \ldots, a_n, b$ are constants in the EUF language. We refer to the outermost symbol of the $f-equation$ as the function symbol appearing in such $f-equation$.

$f-equations$ are used in Kapur's algorithm to simplify the structure of terms. As part of the input of Kapur's algorithm, there is a set of uncommon symbols. The following definition extends the concept of uncommon symbols to uncommon terms.

Definition 3.1.2. *A term t in the EUF language is* uncommon *if:*

- *Case 1. t is constant: t is an uncommon term if t as a symbol is uncommon*
- *Case 2. t is a function application of the form $f(t_1, \ldots, t_n)$: t is an uncommon term whenever f is an uncommon symbol or any t_i, where $1 \leq i \leq n$, is an uncommon term*

Similarly, we can extend the notion of uncommon terms to uncommon predicates in the EUF language as follows:

- *Let t_1, t_2 be terms in the EUF language. $t_1 = t_2$, $t_1 \neq t_2$ are uncommon predicates if either t_1 or t_2 are uncommon terms.*
- *Let ψ, φ be predicates in the EUF language. $\psi \star \varphi$ are uncommon predicates if either ψ or φ are uncommon predicates where $\star \in \{\wedge, \vee, \rightarrow\}$.*

A term (resp. predicate) which is not uncommon is a common term (resp. predicate). Regarding extensions of the language with new constants, the *common* property is preserved under equalities. Formally, we mean the following:

Definition 3.1.3. *Let $\mathfrak{L}$ be a EUF language and $\mathfrak{a}$ a constant symbol not belonging to $\mathfrak{L}$. We say $\mathfrak{a}$ is a* common constant under the theory $\mathcal{T}$ in the extended language $\mathfrak{L} \cup \{\mathfrak{a}\}$ *if there exists a common term t in the language $\mathfrak{L}$ such that $\models_{\mathcal{T}} t = \mathfrak{a}$, otherwise $\mathfrak{a}$ is an* uncommon constant*.*

A congruence closure algorithm is used in Kapur's algorithm to keep track of representative terms [1] in the equivalence class induced by $f - equations$. We introduce the following definition for notation purposes:

Definition 3.1.4. *Let $\mathcal{E}$ be an equivalence relation between grounded terms of some language $\mathfrak{A}$. The function $repr_{\mathcal{E}} : \mathfrak{A} \rightarrow \mathfrak{A}, repr_{\mathcal{E}} : a \mapsto b$ where b is the representative element in $\mathcal{E}$ for a, i.e. $a \cong_{\mathcal{E}} b$.*

The interpolating formula produced by Kapur's algorithm is a conjunction of equations and Horn clauses. A Horn clause is a disjunction of literals which contain at most one non-negated literal. Using propositional logic, we can rewrite Horn clauses into *implication form* as follows:

[1] common terms whenever it is possible.

	Disjunction form	Implication form
Definite clause	$\neg p_1 \vee \cdots \vee \neg p_n \vee q$	$p_1 \wedge \cdots \wedge p_n \rightarrow q$
Fact	p	p
Goal clause	$\neg p_1 \vee \cdots \vee \neg p_n$	$p_1 \wedge \cdots \wedge p_n \rightarrow \perp$

For a Horn clause h, we denote $antecedent(h)$ to be the conjunction of disequations in the disjunction of h and $head(h)$ to be either the equation in the disjunction if such is present in h or the particle $\perp$ otherwise.

Given an input formula ψ of a conjunction of n equalities and disequalities in the EUF language and a set of symbols U to be eliminated [2], the main steps in Kapur's algorithm for uniform interpolant generation for the EUF theory are the following:

- **Phase 0 - Flattening:** For each sub-term t in ψ, the algorithm assigns a fresh unique constant $\mathfrak{a}_t$, replaces t by $\mathfrak{a}_t$ in ψ, and conjoins to ψ new equations of the form:

  - $c = \mathfrak{a}_c$, if t is a constant c
  - $f(\mathfrak{a}_{t_1}, \ldots, \mathfrak{a}_{t_m}) = \mathfrak{a}_{f(t_1,\ldots,t_n)}$, if t is a function application of the form $f(t_1, \ldots, t_m)$, where $\mathfrak{a}_{t_i}$ is the constant introduced for the term t_i for each $1 \leq i \leq m$

  For all disequalities of the form $\mathfrak{a} \neq \mathfrak{b}$, the algorithm conjoins a Horn clause $\mathfrak{a} = \mathfrak{b} \rightarrow \perp$ to ψ.

  Clearly, this step generates $f - equations$ from equations in the input formula and Horn clauses from disequalities. The complexity time of this step is $\mathcal{O}(n)$ since flattening requires a linear scan of the input formula.

[2]Common and uncommon terms in the description of the algorithm will be with respect to U

- **Phase I - Elimination of uncommon terms using congruence closure:**

  This step builds an equivalence relation $\mathcal{E}$ of the $f-equations$ introduced in the Flattening step using a congruence closure algorithm such that the representatives terms are common terms whenever possible. Uncommon terms appearing in the current conjunction of equations are replaced by their representatives.

  There are at most $\mathcal{O}(n)$ $f - equations$, hence this step takes $\mathcal{O}(n \log n)$ time to be accomplished.

- **Phase II - Horn clause generation by exposure:** For all pairs of $f - equations$ in ψ with identical outermost symbol, i.e. of the $(f(\mathfrak{a}_1, \ldots, \mathfrak{a}_m) = \mathfrak{c}, f(\mathfrak{b}_1, \ldots, \mathfrak{b}_m) = \mathfrak{d})$, this step conjoins to ψ the following Horn clause

  $\bigwedge_{i=1}^{m} repr_{\mathcal{E}}(\mathfrak{a}_i) = repr_{\mathcal{E}}(\mathfrak{b}_i) \rightarrow repr_{\mathcal{E}}(\mathfrak{c}) = repr_{\mathcal{E}}(\mathfrak{d})$

  when either of the following situations happen [3]:

  - The outermost symbol of the $f - equations$ is an uncommon symbol
  - There is at least one constant argument in any of the $f - equations$ that is an uncommon constant

  There are at most $\mathcal{O}(n)$ $f-equations$, and the complexity time for each $repr_{\mathcal{E}}$ operation takes $\mathcal{O}(1)$ amortized time, thus this step requires $\mathcal{O}(n^2)$ time.

- **Phase III - Conditional elimination:** The algorithm applies the following procedure to all the Horn clauses $h := \bigwedge_i (c_i = d_i) \rightarrow a = b$ in ψ such that $antecedent(h)$ is a common conjunction and $head(h)$ is uncommon:

  - if a and b are both uncommon terms: replace the equation $a = b$ appearing in the antecedents of all the current Horn clauses in ψ by $antecedent(h)$.

[3] Trivial equations in the antecedent of a Horn clause are removed; if the head equation of Horn clause produced by this step is trivial, then such Horn clause is discarded

  - if either a is common and b uncommon: replace b by a in all the current Horn clauses in ψ h' and append $antecedent(h)$ to $antecedent(h')$.
  - if either a is uncommon and b common: Proceed similarly as in the previous case.

  We repeat this step until we cannot produce any new Horn clauses.

- **Phase IV - Conditional replacement:** For each Horn clause in ψ of the form $\bigwedge_i(a_i = b_i) \to u = c$ where the antecedent is common, the term u in its head equation is an uncommon term, and the term c is a common term, conjoin to ψ a Horn clause for each $f - equation$ ϕ in ψ containing u with antecedent $\bigwedge_i a_i = b_i$ and head the resulting equation from replacing u by c in ϕ.

  Return the conjunction of common formulas in ψ as the interpolant. This step together with Phase III can take up to $\mathcal{O}(2^n)$ time to be computed.

If the user is not interested in an explicit uniform interpolant, we can present a **lazy/ pseudo uniform interpolant**, which is an ordered sequence of the original equations together with the Horn clauses produced in Phase II using an appropriate order between the uncommon terms. Using this approach, the complexity time of Phase III and Phase IV reduces to $\mathcal{O}(n^2)$. In order to provide a description of a procedure for the latter we need to introduce the following definitions:

Definition 3.1.5. *Let $\prec$ be a partial order between terms such that $a \prec b$ whenever a is common and b is uncommon. A* dependency pair *for a Horn clause $h := \bigwedge_i(a_i = b_i) \to c = d$ is a pair $(min(c, d, \prec), \{max(c, d, \prec)\} \cup \{u | u$ is an uncommon term appearing in antecedent(h) $\})$. The first element of a dependency pair is denoted as the target of h and the second element the source of h.*

A valid dependency pair *is a dependency pair for some Horn clause h which its target is not included in its source.*

We can notice from definition 3.1.5 than even for equations, its source is never empty.

Definition 3.1.6. *Let $\prec$ be a partial order between terms such that $a \prec b$ whenever a is common and b is uncommon. Given a set of Horn clauses H, a* dependency graph for H *is the directed graph $G_H = (V, E)$ where*

- $V := \{(target_i, source_i) | (target_i, source_i)$ *is a valid dependency pair from* $H\}$
- $E := \{(target_i, source_i) \to (target_j, source_j) | \{target_i\} \cup source_i \subseteq source_j\}$

Using *valid dependency pairs* of the Horn clauses produced in Phase II we can construct an acyclic directed graph as shown by the following theorem:

Theorem 3.1.1. *For any set of Horn clauses H, its dependency graph never contains a cycle between its nodes.*

Proof. Suppose there exists a sequence of n nodes such that $(target_1, source_1) \to \cdots \to (target_n, source_n) \to (target_1, source_1)$. Since $\subseteq$ is transitive we can conclude that $target_1 \in source_1$, which leads to a contradiction since all the nodes in a dependency graph are valid dependency pairs. □

Thus, given a set of Horn clauses H, we can compute its dependency graph and use a topological sort algorithm to produce the ordered sequence required in a lazy uniform interpolant representation. Lazy uniform interpolants avoid the possible exponential size of the formal uniform interpolant. This presentation is useful because it provides a more compact representation of the uniform interpolant that quicker to obtain. Additionally, if the application of the uniform interpolant might focuses a particular sub-formula of the uniform interpolant, the latter representation offers a way to quickly unravel the lazy uniform interpolant. This algorithm allows a flexible implementation which can lead several optimizations based on the nature and applications of the uniform interpolant.

In order to work efficiently with Horn clauses during and after the conditional elimination step in Kapur's algorithm, it was introduced in [29] a *conditional congruence closure* data structure as an extension of the congruence closure generated by a conjunction of equalities. This data structure includes Horn clauses in the set of consequences of the theory induced by the input formulas, allowing membership checking of Horn clauses as well.

Definition 3.1.7. *Let S be a set of equations in the EUF language $\mathfrak{L}$, and $CC(S)$ the set of consequences of S using congruence closure. Then the* conditional congruence closure of S*, abbreviated as $CCC(S)$, is defined as follows:*

$$H \to a = b \in CCC(S) \textit{ if and only if } a = b \in CC(S \cup H)$$

where H is a conjunction of equations in $\mathfrak{L}$ and a, b are terms in $\mathfrak{L}$.

3.2 Implementation

The description of the uniform interpolation algorithm presented in the previous section suggests a straight forward implementation of the first two stages using well-known algorithms [42, 20] and data structures from the SMT solver Z3 [17] to represent elements from the EUF language. One particular change was required in the congruence closure algorithm since Kapur's algorithm keeps common terms as representatives whenever common terms belong to a partition of terms induced by the equivalence relation.

The algorithm in [20] uses a union-find data structure to encode the equivalence classes of the nodes in the abstract syntax tree of the input formula with a 'modify the smaller subtree' strategy. This means that when two nodes u, v in the abstract syntax tree are meant to be merged, the representative of the new combined equivalence class is the node which has a bigger number of predecessors nodes in the abstract syntax tree pointing to the equivalence class of the node. The idea was to update the least amount of nodes that possibly can change representatives due to the most recent merge operation of the equivalence classes and congruence.

Notation 3.2.1. *Given a theory $\mathcal{E}$ and a term u in the language of $\mathcal{E}$, we can indicate by $[u]$ the equivalence class induced by $\mathcal{E}$, i.e. $[u]_{\mathcal{E}} = \{v \in TERMS | \models_{\mathcal{E}} u = v\}$.* [4]

Our algorithm uses a different partial order to maintain common terms as representatives of the equivalence classes. The non-reflexive relation $\succ_{common}$ [5] is defined for all nodes u, v in the abstract syntax tree of terms as:

$$u \succ_{common} v = \begin{cases} |list(u)| > |list(v)| & \text{if } (u \text{ is a common term} \Leftrightarrow \\ & v \text{ is a common term}) \\ \text{u is a common term} & \text{otherwise} \end{cases}$$

where $list(u) = \{f(u_1, \ldots, u_n) \in \text{TERMS} | \exists i \in \{1, \ldots, n\} \text{ such that } u_i \in [u]\}$

In the next section we will discuss changes proposed to Phase III in Kapur's algorithm.

[4] If the theory is clear from context, the notation $[u]$ denotes the equivalence class of u.

[5] The reflexive relation $u \succeq_{common} v$ is defined as $u = v \lor u \succ_{common} v$, where the equality between nodes is defined as $|list(u)| = |list(v)| \land u$ is a common term $\iff v$ is a common term.

3.2.1 New conditional elimination step in Kapur's algorithm

The modification of Phase III implemented in this thesis work combines and extends the algorithms and data structures introduced in [24, 45]. The algorithm in [24] is a direct extension of [19] which adapts a congruence closure algorithm from [42, 20] in order to update the union-find data structure maintaining the equivalence relation between all the sub-terms in the input formula. The implementation of the congruence closure algorithm in [45] extends the usual $Find, Merge$ operations on the union-find data structure with the $Explain$ operator, which accomplishes the following:

> $Explain(e, e^{'})$: if a sequence U of unions of pairs (previous Merge operations) $(e_1, e^{'}_1), \ldots, (e_p, e^{'}_p)$ has taken place, it returns a subset E of U if $(e, e^{'})$ belongs to the equivalence relation generated by E and it returns $\perp$ otherwise.

The implementation of the Explain operator requires a *proof-tree* P, which is a graph data structure of disjoint trees of pointers of the elements in the underlying equivalence relation connected by a directed edge if there was a Merge operation between the nodes, i.e. $a \to b \in edges(P)$ if and only $Merge(a, b)$ or $Merge(b, a)$ belongs to the sequence of operations executed on the union-find data structure. Particularly, our implementation for Phase III only uses the representatives constant terms from Phase II as nodes for the proof-tree.

After a $Merge(a, b)$ operation is executed between two nodes a, b on the union-find data structure, the proof-tree needs to be updated as follows:

- Reverse all the edges from a to the root of the tree containing a
- Add an edge between a and b

If two nodes are congruent, then they belong to the same tree in the proof-tree data structure. From [45], given two congruent nodes a, b in the union-find data structure, $Explain(a, b)$ can be computed by obtaining the common ancestor c of a and b from the respective tree t in the proof-tree data structure; thus, the sequence of unions in the explanation are the edges in the path from a to c in t and the path from b to c in t.

Example 3.2.0.1. *Let $\{a, b, c, d, e, f, g\}$ be nodes in a union-find data structure and let us consider the following sequence of merge operations: 1. Merge(b,d), 2. Merge(e,g), 3. Merge(a,c), 4. Merge(h,i), 5. Merge(a,b), 6. Merge(e,f), 7. Merge(a, e).*

The proof-tree P obtained after processing the above Merge operations is:

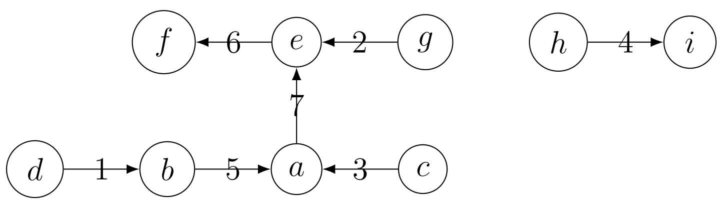

Figure 3.1: Example of proof-tree data structure

Using the above proof-tree data structure we can answer the following queries:

- *Explain(c, g) = 2. Merge(e, g), 3. Merge(a, c), 7. Merge(a, e)*
- *Explain(c, d) = 1. Merge(b, d), 3. Merge(a, c), 5. Merge(a, b)*
- *Since h and b are not congruent, the trees containing h and b are disjoint.*

If the EUF signature of the input equations does not contain functional symbols, the *Explain* operation from [45] returns the minimal subset of E. Nonetheless, such assertion is not guaranteed when the signature includes functional symbols.

The motivation behind the combination of Gallier's data structure and the congruence closure algorithm with explanations is twofold:

1. We merge the nodes in an equivalence relation corresponding to the left hand side and right hand side terms of common equations inside the antecedents of the Horn clauses obtained in Phase II. Additionally, we update the equivalence relation structure by using the equation propagation mechanism from the congruence closure algorithm and the implicational propagation component from Gallier's structure.

2. The Explain operator from [45] is recursively used to construct the antecedent of Horn clauses during the conditional replacement step. Thus, the MERGE operation in [24] updates the proof-tree data structure from [45] as well.

The thesis work accomplishes the previous points by implementing the following:

1. The data structures used are the following:

- Union-find data structure: a set of disjoint trees which root serves as the representative element for each equivalence class.
- Proof-tree data structure: a directed graph of pointers of elements in the union-fund data structure.
- Graph of terms: a abstract syntax tree encoding information about the terms in the input formula.
- Graph of Horn clauses: a directed graph of equations where two nodes a, b are connected if there exists a Horn clause h in input formula such that $a \in antecedent(h)$ and $b = head(h)$. Following [24], this data structure uses for

each Horn clause h: a field number *numargs* keeping track of the number of equations $a = b$ in the antecedent of h such that a and b do not belong to the same equivalence class; a field equation *poslit* which stores the head equation of the Horn clause h. For each equation $a = b$ in the abstract syntax tree of the input formula, there is an array of Horn clauses *clauselist* which keeps track of the Horn clauses h such that $a = b \in antecedent(h)$. in the antecedent

2. The implemented C++ class for the congruence closure with explanation [6] includes a pointer as data member to the class implementation for the Gallier data structure in order to propagate the equational information achieved during merges and updates due to congruence. The modified algorithms appear below in pseudo-code notation (Algorithm 1, Algorithm 2, and Algorithm 3):

3. We implemented the *ExtendedExplain* procedure, which given as input an equation $a = b$ and a temporal equivalence relation $\mathcal{E}$ obtained from a set of equations and a set of Horn clauses in an EUF language $\mathfrak{L}$, it returns a set C of non-trivial common equations [7] in $\mathfrak{L}$ such that $\models_{\mathcal{E}} (\bigwedge_{h \in C} h) \to a = b$ if the equation $a = b$ belongs to the temporal equivalence relation $\mathcal{E}$; it returns an empty set otherwise. The pseudo-code for the ExtendedExplain procedure is shown below (Algorithm 4):

Using the data structures aforementioned we compute a (union-find) equivalence class data structure, denoted *temporal equivalence class* that together with the Horn clauses in ψ obtained from Phase II will help us to obtain common Horn clauses. The input of this procedure is the Horn clauses H in ψ. The procedure is the following:

Temporal Equivalence Class Algorithm:

[6] A fragment of the actual code is shown at Section 6.3.

[7] We denote a trivial equation to be an equation of the form $x = x$ for any term x in some EUF language.

Algorithm 1 Modified Unsatisfiability Testing for Ground Horn Clauses

```
procedure SATISFIABLE(var H : Hornclause; var queue, combine: queuetype;
var GT(H) : Graph; var consistent : boolean)
    while queue not empty do
        node := pop(queue);
        for clause_1 in H[node].clauselist do
            if numargs[clause_1] = 0 then
                nextnode := poslitlist[clause_1];
                if ¬ H[nextnode].val then
                    if nextnode ≠ ⊥ then
                        queue := push(nextnode, queue);
                        H[nextnode].val := true;
                        u := left(H[nextnode].atom);
                        v := right(H[nextnode].atom);
                        if FIND(R, u) ≠ FIND(R, v) then
                            combine := push((u, v), combine);
                        end if
                    else
                        consistent := false;
                    end if
                end if
            end if
        end for
        if queue is empty then
            closure(combine, queue, R);
        end if
    end while
end procedure

procedure CLOSURE(var combine, queue : queuetype; var R : partition)
    while combine is not empty do
        (u, v) = pop(combine)
        MERGE(R, u, v, queue)
    end while
end procedure
```

Step 1. Let $\mathcal{E}$ be the collection of equivalence classes for each distinct term in the abstract syntaxt tree of the Horn clauses in H.

Step 2. Insert all the Horn clauses in H to the Gallier data structure.

Step 3. Merge the nodes in the temporal equivalence class $\mathcal{E}$ corresponding to the left hand side term and right hand side term of the common equations appearing in the antecedent of the Horn clauses $h \in H$. Update Gallier's data

Algorithm 2 Modified Congruence Closure with Explanation Algorithms - Merge

procedure MERGE(R : partition, u, v : node; queue, combine : queuetype)
  if u and v are constants a and b **then**
    add $a = b$ to Pending;
    Propagate();
  else ▷ $u = v$ is of the form $apply(a_1, a_2) = a$
    if $Lookup(Representative(a_1), Representative(a_2))$ is some $apply(b_1, b_2) = b$ **then**
      add $(apply(a_1, a_2) = a, apply(b_1, b_2) = b)$ to Pending;
      Propagate();
    else
      set Lookup(Representative(a_1), Representative(a_2)) to $apply(a_1, a_2)$=a;
      add $apply(a_1, a_2)$=a to UseList(Representative(a_1)) and to UseList(Representative(a_2));
    end if
  end if
end procedure

structure accordingly.

Step 4. Return $\mathcal{E}$ as the temporal equivalence class for H.

Example 3.2.0.2. *Let us consider a simple example where the input of Horn clause is* $H = \{1.a = b \wedge c = d \rightarrow a = c, 2.c = e \rightarrow e = d\}$*;* $\{d, f\}$ *are uncommon symbols.*

The initial temporal equivalence class is $\{\{a\}, \{b\}, \{c\}, \{d\}, \{e\}, \{f\}\}$.

Since $a = b$ *and* $c = e$ *are common equations, the temporal equivalence class updates to* $\{\{a, b\}, \{c, e\}, \{d\}, \{f\}\}$*. The second Horn clause in* H *reaches the numargs to 0, hence the antecedent of such Horn clause is added to the temporal equivalence class resulting in the following:* $\{\{a, b\}, \{c, e, d\}, \{f\}\}$.

Since $c = d$*, then the numargs field of the first Horn clauses reaches 0, thus the equation* $a = f$ *is processed by the algorithm. The final temporal equivalence class is* $\{\{a, b, f\}, \{c, e, d\}\}$.

The Find and Merge operation takes $\mathcal{O}(1)$ amortized cost. Thus, the amount of work related to the temporal equivalence class in the proposed algorithm take

Algorithm 3 Modified Congruence Closure with Explanation Algorithms - Propagate

procedure PROPAGATE( )
  while Pending is non-empty **do**
    Remove E of the form a=b or (apply(a_1, a_2) = a, apply(b_1, b_2) = b) from Pending
    if Representative(a) $\neq$ Representative(b) and w.l.o.g. |ClassList(Representative(a))| $\leq$ |ClassList(Representative(b))| **then**
      old_{repr_a} := Representative(a);
      Insert edge $a \rightarrow b$ labelled with E into the proof forest;
      for each c in ClassList(old_{repr_a}) **do**
        set Representative(c) to Representative(b)
        move c from ClassList(old_{repr_a}) to ClassList(Representative(b))
        for each pointer L in ClassList(u) **do**
          if H[L].val = false **then**
            set the field H[L].lclass or H[L].rclass pointed to by p to Representative(b)
            if H[L].lclass = H[L].rclass **then**
              queue := push(L, queue);
              H[L].val := true
            end if
          end if
        end for
      end for
      for each apply(c_1, c_2) = c in UseList(old_{repr_a}) **do**
        if Lookup(Representative(c_1), Representative(c_2)) is some apply(d_1, d_2) = d **then**
          add (apply(c_1, c_2) = c, apply(d_1, d_2) = d) to Pending;
          remove apply(c_1, c_2) = c from UseList(old_{repr_a});
        else
          set Lookup(Representative(c_1), Representative(c_2)) to apply(c_1, c_2) = c;
          move apply(c_1, c_2) = c from UseList(old_{repr_a}) to UseList(Representative(b));
        end if
      end for
    end if
  end while
end procedure

$\mathcal{O}(n \log n)$ time complexity where n denotes the number of equations in the graph term of the Horn clauses H. However, the amount of work required by the *unionupdate* operation of Gallier data structure is $\mathcal{O}((2m+n)\lfloor \log n \rfloor + 1)$ where m is the

Algorithm 4 Auxiliary function - ExtendedExplain

procedure ExtendedExplain(t_1 : TERMS, t_2 : TERMS, H : Horn clauses, $\mathcal{E}$: Conditional Equivalence Relation)
  if $Find(t_1, \mathcal{E}) \neq Find(t_2, \mathcal{E})$ **then**
    throw Error: t_1, t_2 do not belong to the same equivalence class
  end if
  if $t_1.id() = t_2.id()$ **then**
    return $\{\}$
  end if
  $\{c, u\}$ = Explain(t_1, t_2, $\mathcal{E}$) where c is a list of common equation and u is a list of uncommon equations
  return $c \cup \bigcup\{ExtendedExplain(a, b, H, \mathcal{E}) | consequent \in u, a = b \in antecedent, (\bigwedge antecedent) \to consequent \in H\}$
end procedure

number of nodes in the graph representation of the Horn clauses H. In the setting of replacing Phase III of the algorithm for uniform interpolation, there can be at most $O(n^2)$ of these Horn clauses due to Phase II of Kapur's algorithm. Therefore, the time complexity of the conditional congruence closure algorithm proposed is $\mathcal{O}((m^2 + n) \log n)$.

Remark: the only equations asserted into the temporal equivalence class of the algorithm above are only the common equations from antecedents in Horn clauses from H.

3.2.2 Invariants of the proposed conditional elimination step

For the next lemmas, unless stated otherwise, let H be the Horn clauses obtained after executing Phase II of Kapur's algorithm, and $\mathcal{E}$ be the temporal equivalence class computed by 3.2.1 using the Horn clauses H.

If the equation $t_1 = t_2$ belongs to the temporal equivalence class E, we can prove that ExtendedExplain returns a set of common equations C such that $\models_{\mathcal{E}} (\bigwedge_{h \in C} h) \to a = b$ using the axiomatization introduced in 2.3.1 as inference rules with the following lemmas:

Lemma 3.2.1. *Let $\mathcal{L}$ be some EUF language, and t_1, t_2 terms in $\mathcal{L}$ such that $\models_{\mathcal{E}} t_1 = t_2$. If there is an uncommon equation $a = b \in Explain(t_1, t_2)$, then there exists $h \in H$ such that h is of the form $\bigwedge_i (c_i = d_i) \to a = b$.*

Proof. Let us suppose by contradition that there is no $h \in H$ with the above description. By the definition of the Explain operator in 3.2.1, we see that the such operator will return a list of all the asserted equations in the equivalence relation, thus $a = b$ belongs to the temporal equivalence class. By inspection of the proposed algorithm, assertions into the temporal equivalence relation only happen in two places: when an equation in the antecedent of a Horn clause of H is common, or when asserting the head equation of a Horn clause $h \in H$ such that its *numargs* field becomes zero. Since there is no Horn clause with head equaiton $a = b$, then $a = b$ was added when the algorithm processed common equations in the antecedent of some Horn clause. But that implies that $a = b$ is a common equation. Contradiction, thus there exists a Horn clause $h \in H$ containing $a = b$ in its head equation. □

Lemma 3.2.2. *Let $\mathcal{L}$ be some EUF language and t_1, t_2 terms in $\mathcal{L}$ such that $\models_{\mathcal{E}} t_1 = t_2$. The list of equations returned by ExtendedExplain$(t_1, t_2, H, \mathcal{E})$ contains only common equations.*

Proof. If $t_1 = t_2$ belongs to the temporal equivalence class $\mathcal{E}$, then there is a derivation in with $t_1 = t_2$ as the last formula in the derivation sequence. Let us prove the statement by induction on the length n of the derivation sequence:

- Case $n = 1$. We distinguish two cases:
  - t_1, t_2 are the same terms: In line 6, the ExtendedExplain algorithm will return the empty set. Hence, the statement holds true.
  - t_1, t_2 are different terms: Then the equation $t_1 = t_2$ was introduced as a fact in the induced theory, i.e. the equation $t_1 = t_2$ was added to

the temporal equivalence class as a common equation belonging to the antecedent of some Horn clause $h \in H$ during the procedure building the temporal equivalence class. Line 8 of the ExtendedExplain procedure does not contain uncommon equations. Line 9 returns only the set c of common equations.

- Case $n > 1$. Then Line 8 in the ExtendedExplain algorithm sets $\{c, u\}$ to be the common equations (c) and uncommon equations (u) from the Explanation of t_1, t_2. Pick an uncommon equation $a = b$ from the previous list. By lemma 3.2.1, there exists a Horn clause $h \in H$ such that $head(h)$ is $a = b$. Since $a = b$ belongs to the temporal conditional equivalence class, then there exists a derivation for this equation which is shorter that the derivation for $t_1 = t_2$. Applying the inductive hypothesis we see that ExtendedExplain returns a set of common equations for $ExtendedExplain(a, b, H, \mathcal{E})$. Applying the latter to the rest of uncommon equations in u we obtain a set of common equations, which is the result of Line 9 of the ExtendedExplain procedure.

□

Corollary 3.2.2.1. *Let H be a set of Horn clauses produced by Phase II of Kapur's algorithm, $\mathcal{E}$ the equivalence relation obtained in Phase I of Kapur's algorithm, and $\mathcal{E}'$ the temporal equivalence relation obtained after the modified conditional elimination algorithm. Then $H \models_{\mathcal{E}'} a = b$ if and only if $\exists$ common $x \subseteq \bigcup_{h \in H} antecedent(h)$ such that $H \models_{\mathcal{E}} \bigwedge x \to a = b$.*

Example 3.2.0.3. *Let us consider the input equations* $\{$ $1.f(f(f(f(x)))) = f(f(f(f(f(x))))), 2.x = f(f(x)), 3.f(a) \neq a\}$ *with the set of symbols to eliminate to be* $\{f\}$. *Flattening introduces the following new equisatisfiable equations:* $\{4.f(x) = e_1, 5.f(e_1) = e_2, 6.f(e_2) = e_3, 7.f(e_3) = e_4, 8.f(e_4) = e_5, 9.f(a) = e_6, 10.x = e_2, 11.e_4 = e_5, 12.e_6 = a \to \bot\}$. *Phase I simplifies the above* *set of equations using congruence closure and replacing subterms by representatives. The equations produced are the following:* $\{12.e_6 = a \to \bot, 13.f(x) = x, 14.f(a) = e_6\}$. *Phase II introduces the following Horn clauses* H: $\{12.e_6 = a \to \bot, 13.f(x) = x, 15.x = a \to x = e_6, \}$.

Our algorithm notices that Horn clause 15 contains the common equation $x = a$ *in the antecedent. Hence, the nodes representing the nodes of the terms* x *and* a *are merged in the temporal equivalence relation* $\mathcal{E}$. *With the latter, the nodes representing* x *and* e_3 *is also merged because the* numargs *of Horn clause 15 reaches 0. By transitivity, our algorithm merges the nodes for the terms* e_3 *and* a *in* $\mathcal{E}$ *since both* $x = e_3, x = a$ *belong to* $\mathcal{E}$. *The last equation decreases the* numargs *entry of the Horn clause 12. Thus,* $\bot$ *in* $\mathcal{E}$ *since the* numargs *of Horn clause 12 reaches 0.*

Since $\bot$ *is considered a common symbol, we can find a common Horn clause* h *in* $\mathcal{E}$ *which contains common equations in its antecedent. Since Horn clause 12 has* $\bot$ *as head, we compute ExtendedExplain on its antecedent as follows:*

$$
\begin{aligned}
h &:= (ExtendedExplain(e_6 = a) \to \bot) \\
&= (\bigwedge\{ExtendedExplain(x = e_3), ExtendedExplain(x = a)\} \to \bot) \\
&= (\bigwedge(\{x = a\} \cup \{x = a\}) \to \bot) \\
&= (x = a \to \bot)
\end{aligned}
$$

Hence the common Horn clause obtained from H *is* $(x = a \to \bot)$.

3.2.3 New conditional replacement step in Kapur's algorithm

Once the temporal equivalence relation is built after the execution of the previous step, we can compute conditional replacements as follows. For the latter, we will require the following auxiliary functions:

Algorithm 5 Auxiliary function - Candidates

procedure CANDIDATES(z3::expr const & t)
    if t is common **then**
        return $\{t\}$
    else
        return $\{t^{'} | t^{'} \in Class(t), t^{'}$ is common$\}$
    end if
end procedure

Algorithm 6 Auxiliary function - allCandidates

procedure ALLCANDIDATES(z3::expr const & t)
    if t is a constant **then**
        undefined
    end if
    if t has f-symbol uncommon **then**
        return $\{\{\}\}$;
    end if
    if t has f-symbol common and is of the form $f(t_1, \ldots, t_n)$ **then**
        return $\{Candidates(t_1), \ldots, Candidates(t_n)\}$;
    end if
end procedure

By inspection is easy to notice that *Candidates* and *allCandidates* return a set of common terms and a set of sets of common terms respectively.

The proposed conditional replacement step produces common Horn clauses from previous uncommon equations and uncommon Horn clauses obtained in Phase II of Kapur's algorithm. The pseudo-code of the algorithms to process the original equations are shown below:

Lemma 3.2.3. *Let* $Eqs := \{f(\mathfrak{a}_{i,1}, \ldots, \mathfrak{a}_{i,n}) = \mathfrak{a}_i\}$ *be the set of equations produced in Phase I of Kapur's algorithms, H the set of Horn clauses obtained in Phase II, and*

Algorithm 7 Conditional Replacement - Part 1

procedure CONDITIONAL REPLACEMENT(z3::expr const & x, z3::expr const & y, H : Horn clauses, $\mathcal{E}$: conditional equivalence relation)
  if x is constant and y is constant **then**
    for σ_x in Candidates(x) **do**
      for σ_y in Candidates(y) **do**
        horn_clause.add(ExtendedExplain(x, σ_x, H, $\mathcal{E}$) + ExtendedExplain(y, σ_y, H, $\mathcal{E}$), $\sigma_x = \sigma_y$)
      end for
    end for
  end if
  if x is constant and y is of the form $f_y(t_1^{'}, \ldots, t_{k_2}^{'})$ **then**
    for σ_x in Candidates(x) **do**
      for σ_{f_y} in Candidates($f_y(t_1^{'}, \ldots, t_{k_2}^{'})$) **do**
        horn_clause.add(ExtendedExplain(x, σ_x, H, $\mathcal{E}$) + ExtendedExplain($f_y(t_1^{'}, \ldots, t_{k_2}^{'}$, H, $\mathcal{E}$), σ_y), $\sigma_x = \sigma_{f_y}$)
      end for
      for $arguments_{f_y}$ in CartesianProd(AllCandidates($f_y(t_1^{'}, \ldots, t_{k_2}^{'})$)) **do**
        horn_clause.add(ExtendedExplain(x, σ_x, H, $\mathcal{E}$) + $\sum_{i=1}^{k_2}$ ExtendedExplain($t_i^{'}$, $arguments_{f_y}[i]$, H, $\mathcal{E}$), $\sigma_x = f_y(arguments_{f_y})$)
      end for
    end for
  end if
  if x is of the form $f_x(t_1, \ldots, t_{k_1})$ and y is a constant **then**
    return CONDITIONAL ELIMINATION(y, x);
  end if
end procedure

$\mathcal{E}^{'}$ the temporal equivalence relation obtained by the proposed conditional replacement step. Executing the proposed conditional elimination step on $Eqs, H, \mathcal{E}^{'}$ produces common Horn clauses.

Proof. By inspecting the conditional replacement algorithm in 3.2.3, we noticed the antecedents of the Horn clauses constructed are obtained using the ExtendedExplain procedure, which from lemma 3.2.2 it produces a set of common equations.

Additionally, the equations in the consequent part of the Horn clauses produced in the conditional replacement procedure are of the form:

- $\sigma_x = \sigma_y$, where $\exists t_1, t_2 \in TERMS$ such that $\sigma_x \in Candidates(t_1)$ and $\sigma_y \in$

Algorithm 8 Conditional Replacment - Part 2

procedure CONDITIONAL REPLACEMENT(z3::expr const & x, z3::expr const & y, H : Horn clauses, $\mathcal{E}$: conditional equivalence relation)
  if x is of the form $f_x(t_1, \ldots, t_{k_1})$ and y is of the form $f_y(t^{'}_1, \ldots, t^{'}_{k_2})$ **then**
    for σ_{f_x} in Candidates($f_x(t_1, \ldots, t_{k_1})$) **do**
      for σ_{f_y} in Candidates($f_y(t^{'}_1, \ldots, t^{'}_{k_2})$) **do**
        horn_clause.add(ExtendedExplain($f_x(t_1, \ldots, t_{k_1})$, σ_{f_x}, H, $\mathcal{E}$) + ExtendedExplain($f_y(t^{'}_1, \ldots, t^{'}_{k_2})$, σ_y, H, $\mathcal{E}$), $\sigma_{f_x} = \sigma_{f_y}$)
      end for
      for $arguments_{f_y}$ in CartesianProd(AllCandidates($f_y(t^{'}_1, \ldots, t^{'}_{k_2})$)) **do**
        horn_clause.add(ExtendedExplain($f_x(t_1, \ldots, t_{k_1})$, σ_{f_x}, H, $\mathcal{E}$) + $\sum_{i=1}^{k_2}$ ExtendedExplain($t^{'}_i$, $arguments_{f_y}[i]$, H, $\mathcal{E}$), $\sigma_{f_x} = f_y(arguments_{f_y})$)
      end for
    end for
    for $arguments_{f_x}$ in CartesianProd(AllCandidates($f_x(t_1, \ldots, t_{k_1})$)) **do**
      for σ_{f_y} in Candidates($f_y(t^{'}_1, \ldots, t^{'}_{k_2})$) **do**
        horn_clause.add($\sum_{i=1}^{k_1}$ ExtendedExplain(t_i, $arguments_{f_x}[i]$, H, $\mathcal{E}$) + ExtendedExplain($f_y(t^{'}_1, \ldots, t^{'}_{k_2})$, σ_y, H, $\mathcal{E}$), $f_x(arguments_{f_x}) = \sigma_{f_y}$)
      end for
      for $arguments_{f_y}$ in CartesianProd(AllCandidates($f_y(t^{'}_1, \ldots, t^{'}_{k_2})$)) **do**
        horn_clause.add($\sum_{i=1}^{k_1}$ ExtendedExplain(t_i, $arguments_{f_x}[i]$, H, $\mathcal{E}$) + $\sum_{i=1}^{k_2}$ ExtendedExplain($t^{'}_i$, $arguments_{f_y}[i]$, H, $\mathcal{E}$), $f_x(arguments_{f_x}) = f_y(arguments_{f_y})$)
      end for
    end for
  end if
end procedure

$Candidates(t_2)$. Since the function $Candidates$ returns a set of common equations, then all the above equations are common.

- $\sigma_x = f(arguments_f)$, where $\exists t, f(t_1, \ldots, t_n) \in TERMS$ with f a common symbol, such that $\sigma_x \in Candidates(t)$ and $f(arguments_f) \in \{f(\hat{t_1}, \ldots, \hat{t_n}) | \hat{t_i} \in Candidates(t_i) \text{ for } 1 \leq i \leq n\}$. Similarly to the previous case, the function $Candidates$ returns a set of common terms, thus the elements returned by this case are common as well.

- $f_x(arguments_x) = f_y(arguments_y)$, using the same definition for $f(arguments_f)$ from the previous item.

It is easy to see that the above equations are common if any of the involved sets are not empty. Therefore, the algorithm only produces common Horn clauses. □

In order to process Horn clauses obtained from Phase II of Kapur's algorithm, we apply the conditional replacement step for equations over the equations in the consequent of all the Horn clauses which *numargs* entries are equal to 0.

Lemma 3.2.4. *Let H be the set of Horn clauses obtained at the end of Phase II of Kapur's algorithm with numargs entry equal to 0 and $\mathcal{E}'$ the associated temporal equivalence relation obtained at the end of the conditional elimination procedure. If $h \in H$ is of the form $\bigwedge_i (a_i = b_i) \to c = d$, then the Horn clauses $\{\bigwedge_i ExtendedExplain(a_i, b_i, H, \mathcal{E}') \to h' | h' \in ConditionalReplacement(c, d, H, \mathcal{E}')\}$ are common Horn clauses.*

Proof. We observe that if the *numargs* entry of a Horn clause $h \in H$ is equal to 0, then all the equations in the antecedent of h belong to the temporal equivalence relation. Thus, there exists a proof in $\mathcal{E}'$ for each of these equations. From the latter, the consequent of h also belongs to the temporal equivalence relation. Using Lemmas 3.2.2 and 3.2.3 we can conclude that the Horn clause in the statement is a common Horn clause. □

3.2.4 An additional application: checking membership of ground Horn clauses with Explanations

By adding common equations from the antecedent of the Horn clauses during the conditional elimination step we are able to extend an equivalence relation to a conditional equivalence relation that includes the set of consequences of the aforementioned common equations. In a more general setting, we can specify an arbitrary set of equations, or property, that are meant to enlarge the theory to a temporal equivalence relation for specific purposes. To reuse the ExtendedExplain procedure and associated lemmas, we replace the *common* predicate for any predicate of interest.

In particular, given an equivalence relation $\mathcal{E}$, a set of Horn clauses H, and Horn clause h of the form $\bigwedge(a_i = b_i) \to c = d$, we can find an explanation to the query $H \models_{\mathcal{E}} h$ by conditionally extending H with the equations from the antecedent of h and then retrieving an explanation of the membership of the consequent of h in the conditional equivalence relation.

Lemma 3.2.5. *Let H be a set of Horn clauses, h a Horn clause of the form $(\bigwedge_i a_i = b_i) \to c = d$, $\mathcal{E}$ an equivalence relation between terms of a language in EUF, and $\mathcal{E}'$ the associated temporal equivalence relation obtained from extending $\mathcal{E}$ with the equations in the antecedent of h.*

If there exists an explanation $\mathfrak{p} := \{\mathfrak{a}_1 = \mathfrak{b}_1, \ldots, \mathfrak{a}_n = \mathfrak{b}_n\}$ for the query $H \models_{\mathcal{E}'} c = d$, then the explanation $\mathfrak{p}'$ for the query $H \models_{\mathcal{E}} (\bigwedge_i a_i = b_i) \to c = d$ is the subset of $\mathfrak{p}$ that does not contain equations from $\bigcup_{i=1}\{a_i = b_i\}$, i.e. the explanation $\mathfrak{p}'$ does not contain the equations from the antecedent of the Horn clause h.

Proof. If there exists an explanation $\mathfrak{p}$ for $H \models_{\mathcal{E}'} c = d$ then there exists a proof tree with $c = d$ as root node and the equations from $\mathfrak{p}$ as leaves. From lemma 3.2.1 and the definition 3.2.1 we notice that $\mathfrak{p}$ only contains equations derived from $\mathcal{E}$ and the antecedent of h.

Using the *discharge rule* from basic propositional logic, i.e. $\dfrac{\begin{array}{c}[A]\\ \vdots \\ B\end{array}}{A \to B}$, then we can obtain a proof tree with leaves only containing terms that do not belong to the antecedent of h.

Hence, the new proof tree will have $(\bigwedge_{i=1}^{m} a_i' = b_i') \to c = d$ as root node and derived equations from $\mathcal{E}$ as leaves, where $\{a_i^{'} = b_i^{'}\} \subseteq antecedent(h)$ for each $1 \leq i \leq m$. Thus, $\models antecedent(h) \rightarrow a_i^{'} = b_i^{'}$ for each $1 \leq i \leq m$. Let $\mathfrak{p}^{'}$ be $\mathfrak{p} \setminus \bigcup_{i=1}^{m} \{a_i = b_i\}$. Therefore, by transitivity, we have that $\mathfrak{p}^{'}$ is an explanation in $\mathcal{E}$ for $H \models_{\mathcal{E}} h$.

□

The time complexity of this algorithm follows the reasoning as the complexity analysis for the conditional congruence closure algorithm previously proposed. If n is the number of terms in graph of terms and m is the number of nodes in the graph representation of the Horn clauses H, then the algorithm runs in $\mathcal{O}((m+n)\log n)$ time.

3.3 Evaluation

3.3.1 Detailed evaluation of examples

In this section we discuss in full detail the execution trace of the implementation of some examples.

Symbol elimination example

Let us consider the following example from [28] $\alpha_1 = \{f(z_1, v) = s_1, f(z_2, v) = s_2, f(f(y_1, v), f(y_2, v)) = t\}$ with the set of symbols to eliminate $U_1 = \{v\}$. The implementation produces the following trace (slightly modified for presentation purposes) in order to compute the interpolant of $\alpha_1; U_1$:

```
Before conditionalEliminationEqs
Horn clauses produced
0. 0x5618a6c9c740 (Leader) (= c_y1 (c_f c_y1 a_v)) and (= a_v (c_f c_y2 a_v)) -> (= c_t (c_f c_y1 a_v))
1. 0x5618a6c9c410 (Leader) (= c_z2 (c_f c_y1 a_v)) and (= a_v (c_f c_y2 a_v)) -> (= c_s2 c_t)
2. 0x5618a6c7c6a0 (Leader) (= c_z2 c_y1) -> (= c_s2 (c_f c_y1 a_v))
```

```
3. 0x5618a6c4db90 (Leader) (= c_y2 (c_f c_y1 a_v)) and (= a_v (c_f c_y2 a_v)) -> (= c_t (c_f c_y2 a_v))
4. 0x5618a6c9cd30 (Leader) (= a_v (c_f c_y2 a_v)) and (= c_z1 (c_f c_y1 a_v)) -> (= c_s1 c_t)
5. 0x5618a6ca0c10 (Leader) (= c_z1 c_y2) -> (= c_s1 (c_f c_y2 a_v))
6. 0x5618a6ca0b50 (Leader) (= c_z1 c_y1) -> (= c_s1 (c_f c_y1 a_v))
7. 0x5618a6c9c6b0 (Leader) (= c_y1 c_y2) -> (= (c_f c_y1 a_v) (c_f c_y2 a_v))
8. 0x5618a6c7c710 (Leader) (= c_z2 c_y2) -> (= c_s2 (c_f c_y2 a_v))
9. 0x5618a6ca0960 (Leader) (= c_z1 c_z2) -> (= c_s1 c_s2)
Number of horn clauses: 10
Executing conditionalElimination
After conditionalEliminationEqs/Before conditionalEliminationHcs
Horn clauses produced
0. 0x5618a6ca4340 (Leader) (= c_z1 c_y1) and (= c_z1 c_y2) and (= c_z1 c_y1) and (= c_z2 c_y1) -> (= c_t (c_f c_s1 c_s2))
1. 0x5618a6ca0960 (Leader) (= c_z1 c_z2) -> (= c_s1 c_s2)
2. 0x5618a6ca0270 (Leader) (= c_z2 c_y1) and (= c_z1 c_y2) and (= c_z1 c_y1) and (= c_z2 c_y1) -> (= c_t (c_f c_s2 c_s2))
3. 0x5618a6c7c710 (Leader) (= c_z2 c_y2) -> (= c_s2 (c_f c_y2 a_v))
4. 0x5618a6c9c6b0 (Leader) (= c_y1 c_y2) -> (= (c_f c_y1 a_v) (c_f c_y2 a_v))
5. 0x5618a6ca5b80 (Leader) (= c_z2 c_y1) and (= c_z1 c_y2) -> (= c_t (c_f c_s2 c_s1))
6. 0x5618a6ca0b50 (Leader) (= c_z1 c_y1) -> (= c_s1 (c_f c_y1 a_v))
7. 0x5618a6ca0c10 (Leader) (= c_z1 c_y2) -> (= c_s1 (c_f c_y2 a_v))
8. 0x5618a6c4db90 (Leader) (= c_y2 (c_f c_y1 a_v)) and (= a_v (c_f c_y2 a_v)) -> (= c_t (c_f c_y2 a_v))
9. 0x5618a6c7c6a0 (Leader) (= c_z2 c_y1) -> (= c_s2 (c_f c_y1 a_v))
10. 0x5618a6ca55a0 (Leader) (= c_z1 c_y1) and (= c_z2 c_y1) -> (= c_s1 c_s2)
11. 0x5618a6c9c410 (Leader) (= c_z2 (c_f c_y1 a_v)) and (= a_v (c_f c_y2 a_v)) -> (= c_s2 c_t)
12. 0x5618a6c9cd30 (Leader) (= a_v (c_f c_y2 a_v)) and (= c_z1 (c_f c_y1 a_v)) -> (= c_s1 c_t)
13. 0x5618a6ca62c0 (Leader) (= c_z1 c_y1) and (= c_z1 c_y2) -> (= c_t (c_f c_s1 c_s1))
14. 0x5618a6c9c740 (Leader) (= c_y1 (c_f c_y1 a_v)) and (= a_v (c_f c_y2 a_v)) -> (= c_t (c_f c_y1 a_v))
Number of horn clauses: 15
Executing conditionalEliminationfor Horn clauses
After conditionalEliminationHcs
Horn clauses produced
0. 0x5618a6cabb10 (Leader) (= c_y1 c_y2) and (= c_z2 c_y1) and (= c_z1 c_y2) -> (= c_s1 c_s2)
1. 0x5618a6c9fac0 (Leader) (= c_y1 c_y2) and (= c_z1 c_y1) and (= c_z1 c_y2) and (= c_z1 c_y1) and (= c_z2 c_y1) -> (= c_s1 c_s2)
2. 0x5618a6ca4340 (Leader) (= c_z1 c_y1) and (= c_z1 c_y2) and (= c_z1 c_y1) and (= c_z2 c_y1) -> (= c_t (c_f c_s1 c_s2))
3. 0x5618a6cab830 (Leader) (= c_z2 c_y1) and (= c_z1 c_y1) -> (= c_s1 c_s2)
4. 0x5618a6ca0960 (Leader) (= c_z1 c_z2) -> (= c_s1 c_s2)
5. 0x5618a6ca0270 (Leader) (= c_z2 c_y1) and (= c_z1 c_y2) and (= c_z1 c_y1) and (= c_z2 c_y1) -> (= c_t (c_f c_s2 c_s2))
6. 0x5618a6c7c710 (Leader) (= c_z2 c_y2) -> (= c_s2 (c_f c_y2 a_v))
7. 0x5618a6c9c6b0 (Leader) (= c_y1 c_y2) -> (= (c_f c_y1 a_v) (c_f c_y2 a_v))
8. 0x5618a6ca5b80 (Leader) (= c_z2 c_y1) and (= c_z1 c_y2) -> (= c_t (c_f c_s2 c_s1))
9. 0x5618a6ca0b50 (Leader) (= c_z1 c_y1) -> (= c_s1 (c_f c_y1 a_v))
10. 0x5618a6ca0c10 (Leader) (= c_z1 c_y2) -> (= c_s1 (c_f c_y2 a_v))
11. 0x5618a6c4db90 (Leader) (= c_y2 (c_f c_y1 a_v)) and (= a_v (c_f c_y2 a_v)) -> (= c_t (c_f c_y2 a_v))
12. 0x5618a6ca65b0 (Leader) (= c_z1 c_y2) and (= c_z1 c_y2) and (= c_z1 c_y1) and (= c_z2 c_y1) -> (= c_s1 c_s2)
13. 0x5618a6c7c6a0 (Leader) (= c_z2 c_y1) -> (= c_s2 (c_f c_y1 a_v))
14. 0x5618a6ca55a0 (Leader) (= c_z1 c_y1) and (= c_z2 c_y1) -> (= c_s1 c_s2)
15. 0x5618a6ca6300 (Leader) (= c_z2 c_y2) and (= c_z1 c_y2) -> (= c_s1 c_s2)
16. 0x5618a6c9c410 (Leader) (= c_z2 (c_f c_y1 a_v)) and (= a_v (c_f c_y2 a_v)) -> (= c_s2 c_t)
17. 0x5618a6c9cd30 (Leader) (= a_v (c_f c_y2 a_v)) and (= c_z1 (c_f c_y1 a_v)) -> (= c_s1 c_t)
18. 0x5618a6ca62c0 (Leader) (= c_z1 c_y1) and (= c_z1 c_y2) -> (= c_t (c_f c_s1 c_s1))
19. 0x5618a6c9c740 (Leader) (= c_y1 (c_f c_y1 a_v)) and (= a_v (c_f c_y2 a_v)) -> (= c_t (c_f c_y1 a_v))
Number of horn clauses: 20
Horn clauses produced
0. 0x5618a6cabb10 (Not leader) (= c_y1 c_y2) and (= c_z2 c_y1) and (= c_z1 c_y2) -> (= c_s1 c_s2)
1. 0x5618a6c9fac0 (Not leader) (= c_y1 c_y2) and (= c_z1 c_y1) and (= c_z1 c_y2) and (= c_z1 c_y1) and (= c_z2 c_y1) -> (= c_s1 c_s2)
2. 0x5618a6ca4340 (Leader) (= c_z1 c_y1) and (= c_z1 c_y2) and (= c_z1 c_y1) and (= c_z2 c_y1) -> (= c_t (c_f c_s1 c_s2))
3. 0x5618a6cab830 (Not leader) (= c_z2 c_y1) and (= c_z1 c_y1) -> (= c_s1 c_s2)
4. 0x5618a6ca0960 (Leader) (= c_z1 c_z2) -> (= c_s1 c_s2)
5. 0x5618a6ca0270 (Leader) (= c_z2 c_y1) and (= c_z1 c_y2) and (= c_z1 c_y1) and (= c_z2 c_y1) -> (= c_t (c_f c_s2 c_s2))
```

```
6. 0x5618a6ca5b80 (Leader) (= c_z2 c_y1) and (= c_z1 c_y2) -> (= c_t (c_f c_s2 c_s1))
7. 0x5618a6ca65b0 (Not leader) (= c_z1 c_y2) and (= c_z1 c_y2) and (= c_z1 c_y1) and (= c_z2 c_y1) -> (= c_s1 c_s2)
8. 0x5618a6ca55a0 (Not leader) (= c_z1 c_y1) and (= c_z2 c_y1) -> (= c_s1 c_s2)
9. 0x5618a6ca6300 (Not leader) (= c_z2 c_y2) and (= c_z1 c_y2) -> (= c_s1 c_s2)
10. 0x5618a6ca62c0 (Leader) (= c_z1 c_y1) and (= c_z1 c_y2) -> (= c_t (c_f c_s1 c_s1))
Number of horn clauses: 11
Interpolant:
(ast-vector
  (=> (and (= z1 y1) (= z1 y2) (= z1 y1) (= z2 y1)) (= t (f s1 s2)))
  (=> (= z1 z2) (= s1 s2))
  (=> (and (= z2 y1) (= z1 y2) (= z1 y1) (= z2 y1)) (= t (f s2 s2)))
  (=> (and (= z2 y1) (= z1 y2)) (= t (f s2 s1)))
  (=> (and (= z1 y1) (= z1 y2)) (= t (f s1 s1))))
```

The final output of our implementation is $(((z_1 = y_1) \wedge (z_1 = y_2) \wedge (z_1 = y_1) \wedge (z_2 = y_1)) \rightarrow (t = f(s_1, s_2))) \wedge ((z_1 = z_2) \rightarrow (s_1 = s_2)) \wedge (((z_2 = y_1) \wedge (z_1 = y_2) \wedge (z_1 = y_1) \wedge (z_2 = y_1)) \rightarrow (t = f(s_2, s_2))) \wedge (((z_2 = y_1) \wedge (z_1 = y_2)) \rightarrow (t = f(s_2, s_1))) \wedge (((z_1 = y_1) \wedge (z_1 = y_2)) \rightarrow (t = f(s_1, s_1)))$.

Simple example with dis-equality

Let us consider another example from [28] $\alpha_2 = \{f(x_1) \neq f(x_2)\}$ with the set of symbols to eliminate $U_2 = \{f\}$. The implementation produces the following trace for $\alpha_2; U_2$:

```
Before conditionalEliminationEqs
Horn clauses produced
0. 0x5648882bc710 (Leader) (= c_x2 c_x1) -> (= (a_f c_x2) (a_f c_x1))
1. 0x5648882d7dd0 (Leader) (= (a_f c_x2) (a_f c_x1)) -> false
Number of horn clauses: 2
Executing conditionalElimination
After conditionalEliminationEqs/Before conditionalEliminationHcs
Horn clauses produced
0. 0x5648882bc710 (Leader) (= c_x2 c_x1) -> (= (a_f c_x2) (a_f c_x1))
1. 0x5648882d7dd0 (Leader) (= (a_f c_x2) (a_f c_x1)) -> false
Number of horn clauses: 2
Executing conditionalEliminationfor Horn clauses
After conditionalEliminationHcs
Horn clauses produced
0. 0x5648882bc710 (Leader) (= c_x2 c_x1) -> (= (a_f c_x2) (a_f c_x1))
1. 0x5648882d7dd0 (Leader) (= (a_f c_x2) (a_f c_x1)) -> false
Number of horn clauses: 2
Horn clauses produced
0. 0x5648882deea0 (Leader) (= c_x2 c_x1) -> false
Number of horn clauses: 1
```

```
(ast-vector
  (=> (= x2 x1) false))
```

The final output of our implementation is $x_1 = x_2 \to \perp$.

Comparison of Craig Interpolants and Uniform Interpolants

The interface offered by SMT solvers with interpolation features require an inconsistent pair of formulas A and B. This section compares the Craig Interpolants obtained by Z3 and Mathsat for contradicting pairs of formulas and the uniform interpolant obtained by our implementation such that the symbols to eliminate are the same for each input problem for our implementation.

A-part: $f(z_1, v) = s_1 \wedge f(z_2, v) = s_2 \wedge f(f(y_1, v), f(y_2, v)) = t$		
SMT Solvers	B-parts	
	$z_1 = z_2 \wedge z_2 = y_1$ $\wedge z_2 = y_2 \wedge f(s_2, s_1) \neq t$	$z_1 = z_2 \wedge z_1 = y_1$ $\wedge z_2 = y_2 \wedge f(s_1, s_2) \neq t$
	Interpolants	
Z3	$((f(s_2, s_1) = t) \vee (\neg(z_2 = z_1))$ $\vee((\neg(s_1 = s_2)) \wedge ((s_2 = s_1) \vee$ $(\neg(z_2 = z_1)))) \vee (\neg(y_1 = z_1))$ $\vee(\neg(y_2 = z_1)))$	$((f(s_1, s_2) = t) \vee ((\neg(s_1 = s_2))$ $\wedge((s_2 = s_1) \vee (\neg(z_2 = z_1)))) \vee$ $(\neg(z_2 = z_1)) \vee (\neg(y_1 = z_1))$ $\vee(\neg(y_2 = z_1)))$
Mathsat	$\neg((\neg(t = f(s_2, s_1))) \wedge ((= z_2 y_1)$ $\wedge((= z_1 z_2) \wedge (= z_2 y_2))))$	$\neg((\neg(t = f(s_1, s_2))) \wedge (((= z_1 z_2)$ $\wedge(= z_1 y_1)) \wedge (= z_1 y_2)))$
Our implementation	$(((z_1 = y_1) \wedge (z_1 = y_2) \wedge (z_1 = y_1) \wedge (z_2 = y_1)) \to (t = f(s_1, s_2)))$ $((\mathrm{z}_1 = z_2) \to (s_1 = s_2))$ $(((\mathrm{z}_2 = y_1) \wedge (z_1 = y_2) \wedge (z_1 = y_1) \wedge (z_2 = y_1)) \to (t = f(s_2, s_2)))$ $(((\mathrm{z}_2 = y_1) \wedge (z_1 = y_2)) \to (t = f(s_2, s_1)))$ $(((\mathrm{z}_1 = y_1) \wedge (z_1 = y_2)) \to (t = f(s_1, s_1)))$	

Table 3.1: Comparing Craig Interpolants and Uniform Interpolants for $\{f(z_1, v) = s_1 \wedge f(z_2, v) = s_2 \wedge f(f(y_1, v), f(y_2, v)) = t, \{v\}\}$.

Using Z3, we verified our implementation result implies the Craig interpolants obtained by Z3 and Mathsat.

3.3.2 Performance comparison with iZ3 and MathSat

This section discusses a benchmark of interpolant generation for the EUF theory, which it will allow us to test our implementation and contrast the execution time with other interpolant generation algorithms from Z3 and Mathsat.

Benchmark description

The benchmark uses the following parameters:

- i stands for the number of constants
- j stands for the number of function symbols with arity between 2 and 3
- k stands for limit for random terms to consider in the problem
- n stands for the equations/dis-equations in the A-part

The benchmark generates a pair of two unsatisfiable formulas in the EUF language from a fixed theory with the following parameters:

$$S = \{c_1, \ldots, c_i, f_1, \ldots, f_j\}$$

where i, j are random integer numbers. Using the S, we enumerate the grounded terms G in S and assign a natural number to each number denoting its position in the enumeration.

We generate n random equations/dis-equations from the signature S such that this collection of formulas is consistent for the $A - part$ of the input problem. The latter is implemented using a $z3 :: solver$ to ensure this condition. The equations/dis-equations are of the form:

$$position(k_1, S) = position(k_2, S) \text{ , or } position(k_1, S) \neq position(k_2, S)$$

where $position(k, S)$ denotes the k^{th} element in G. The integers k_1, k_2 are chosen uniformly at random from a distribution of integer values $\{0, \ldots, k\}$, where k is a parameter of the benchmark.

Next we randomly generate a second set of consistent equations/dis-equations (B-Part) until the $A-part$ and the $B-part$ are inconsistent using a second $z3 :: solver$.

Experimental results

We designed this problem because it is not trivial to compute a uniform/interpolant due to randomness of the problem. This problem was executed 100 times with parameters (i = 10, j = 5, k = 100, n = 10) and (i = 20, j = 10, k = 100, n = 40) using a computer desktop equipped with an Intel i7-9700 @ 4.70 GHz processor and 16 GB of RAM.

The following graph reports the time needed by our implementation, iZ3, and the interpolation generation algorithm from Mathsat. It is well known that both iZ3 and Mathsat does not compute uniform interpolants. Regardless, the benchmark was used with the purpose to compare their execution time on normal interpolants.

The time was measured using a bash script which takes the difference of the output produced by the UNIX utility $date + \text{`}\%s.\%N'$ at the beginning and at the end of the execution of the tested algorithms.

```
A part formulas:
(ast-vector
  (distinct (f_0 x_6 x_0 x_0 x_0) (f_0 x_9 x_8 x_0 x_0))
  (= (f_0 x_8 x_1 x_0 x_0) (f_0 x_1 x_0 x_0 x_0))
  (= (f_0 x_5 x_2 x_0 x_0) (f_0 x_4 x_5 x_0 x_0))
  (distinct (f_0 x_6 x_2 x_0 x_0) (f_0 x_9 x_3 x_0 x_0))
  (distinct (f_0 x_4 x_7 x_0 x_0) x_7)
  (= (f_0 x_5 x_5 x_0 x_0) (f_0 x_8 x_1 x_0 x_0))
  (= (f_0 x_2 x_6 x_0 x_0) (f_0 x_9 x_3 x_0 x_0))
  (= x_7 (f_0 x_1 x_6 x_0 x_0))
  (= (f_0 x_1 x_4 x_0 x_0) (f_0 x_6 x_3 x_0 x_0))
(= x_8 (f_0 x_2 x_6 x_0 x_0)))
B part formulas:
(ast-vector
  (= (f_0 x_6 x_8 x_0 x_0) (f_0 x_9 x_7 x_0 x_0))
  (distinct (f_0 x_2 x_6 x_0 x_0) (f_0 x_7 x_0 x_0 x_0))
  (distinct (f_0 x_7 x_7 x_0 x_0) x_4)
  (distinct (f_0 x_6 x_6 x_0 x_0) (f_0 x_3 x_8 x_0 x_0))
  (= (f_0 x_2 x_5 x_0 x_0) (f_0 x_7 x_6 x_0 x_0))
  (= (f_0 x_6 x_0 x_0 x_0) (f_0 x_2 x_3 x_0 x_0))
  (= (f_0 x_3 x_3 x_0 x_0) (f_0 x_6 x_5 x_0 x_0))
  (distinct (f_0 x_8 x_8 x_0 x_0) (f_0 x_5 x_1 x_0 x_0))
  (distinct (f_0 x_7 x_8 x_0 x_0) (f_0 x_9 x_1 x_0 x_0))
  (= (f_0 x_8 x_8 x_0 x_0) (f_0 x_7 x_2 x_0 x_0))
  (distinct (f_0 x_2 x_1 x_0 x_0) (f_0 x_3 x_2 x_0 x_0))
  (= (f_0 x_5 x_3 x_0 x_0) (f_0 x_7 x_4 x_0 x_0))
  (distinct (f_0 x_1 x_2 x_0 x_0) (f_0 x_5 x_3 x_0 x_0))
  (= (f_0 x_1 x_7 x_0 x_0) (f_0 x_3 x_6 x_0 x_0))
  (distinct (f_0 x_3 x_2 x_0 x_0) (f_0 x_8 x_7 x_0 x_0))
  (= (f_0 x_2 x_8 x_0 x_0) x_4)
  (= (f_0 x_2 x_2 x_0 x_0) (f_0 x_8 x_3 x_0 x_0))
  (= (f_0 x_1 x_1 x_0 x_0) (f_0 x_8 x_8 x_0 x_0))
  (distinct (f_0 x_3 x_2 x_0 x_0) (f_0 x_8 x_3 x_0 x_0))
  (= (f_0 x_2 x_8 x_0 x_0) (f_0 x_6 x_3 x_0 x_0))
  (distinct (f_0 x_5 x_6 x_0 x_0) (f_0 x_0 x_1 x_0 x_0))
  (= (f_0 x_7 x_3 x_0 x_0) (f_0 x_7 x_0 x_0 x_0))
  (distinct (f_0 x_0 x_3 x_0 x_0) (f_0 x_8 x_3 x_0 x_0))
  (distinct (f_0 x_8 x_2 x_0 x_0) (f_0 x_2 x_7 x_0 x_0))
  (distinct (f_0 x_9 x_1 x_0 x_0) (f_0 x_5 x_0 x_0 x_0))
  (distinct (f_0 x_0 x_4 x_0 x_0) (f_0 x_0 x_5 x_0 x_0))
  (distinct (f_0 x_5 x_5 x_0 x_0) (f_0 x_2 x_8 x_0 x_0))
  (= (f_0 x_6 x_3 x_0 x_0) (f_0 x_3 x_0 x_0 x_0))
  (= (f_0 x_3 x_8 x_0 x_0) (f_0 x_0 x_8 x_0 x_0))
  (distinct (f_0 x_8 x_0 x_0 x_0) (f_0 x_5 x_5 x_0 x_0))
  (= (f_0 x_6 x_6 x_0 x_0) (f_0 x_4 x_5 x_0 x_0))
  (distinct (f_0 x_4 x_3 x_0 x_0) x_5)
  (distinct x_8 (f_0 x_3 x_3 x_0 x_0))
  (= (f_0 x_6 x_3 x_0 x_0) (f_0 x_3 x_6 x_0 x_0))
  (= (f_0 x_4 x_1 x_0 x_0) (f_0 x_5 x_6 x_0 x_0))
  (= x_7 (f_0 x_0 x_3 x_0 x_0))
  (distinct (f_0 x_1 x_3 x_0 x_0) (f_0 x_8 x_2 x_0 x_0))
  (= (f_0 x_2 x_1 x_0 x_0) (f_0 x_6 x_8 x_0 x_0))
  (= x_3 (f_0 x_9 x_7 x_0 x_0))
  (= (f_0 x_3 x_7 x_0 x_0) x_8)
(= (f_0 x_3 x_7 x_0 x_0) (f_0 x_6 x_2 x_0 x_0)))
```

Figure 3.2: Typical example of benchmark used

3.4 Conclusions

This chapter discussed the new approach for uniform interpolant generation introduced by Prof. Kapur for the EUF theory. We proposed a modification of his algorithm and proved its correctness. The implementation and testing work confirm that the approach produces stronger interpolants compared to other interpolant generation algorithms (iZ3, Mathsat).

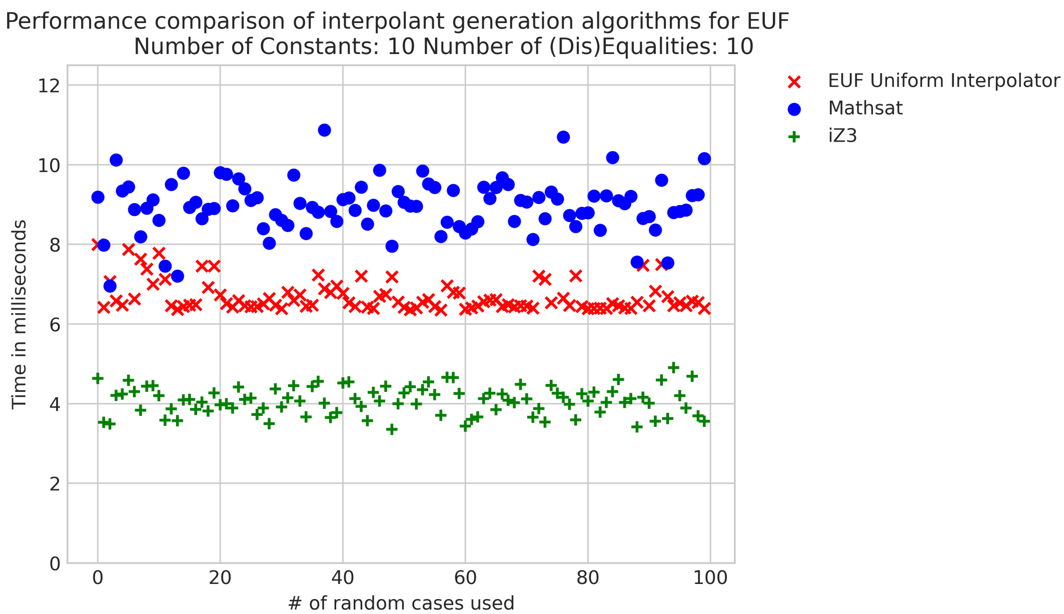

Figure 3.3: Performance comparison graph of EUF interpolant generation algorithms for the benchmark (i = 10, j = 5, k = 100, n = 10)

The performance comparison section indicates that of our implementation is slower than iZ3. On the other hand, it is important to highlight that the algorithms have different output specification since Prof. Kapur algorithm computes uniform interpolants.

The current implementation can be improved. Currently, the data structures for flattening introduce additional constants that might not be needed since the implementation used a recursive scan of the arguments for each expression without checking term sharing. Moreover, the explanation mechanism can be improved or changed by the proof producing mechanism already available in Z3.

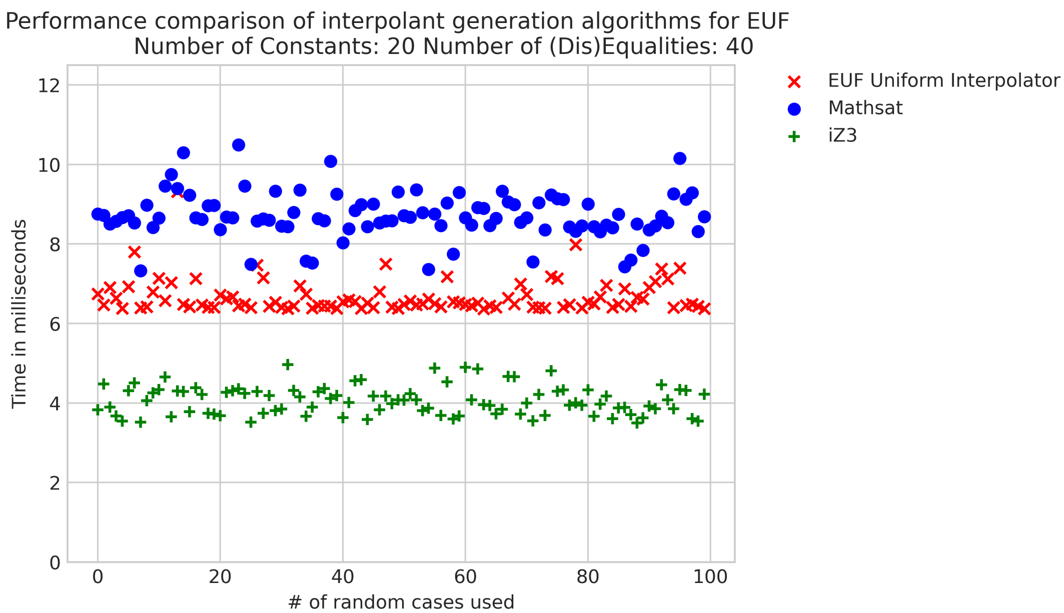

Figure 3.4: Performance comparison graph of EUF interpolant generation algorithms for the benchmark (i = 20, j = 10, k = 100, n = 40)

Chapter 4

Uniform Interpolation algorithm for UTVPI Formulas

This theory appears heavily in formal methods dealing with abstract domains, introduced in [39], which have been useful for efficient linear invariant discovery, safety analysis, and static analysis of programs. The decision problem consists of checking the satisfiability of a particular fragment of $LIA(\mathbb{Z})$. The fragment consists on conjunctions of inequalities with at most two variables which integers coefficients are restricted to $\{-1, 0, 1\}$. Efficient algorithms are found in the literature for both the satisfiability problem [34] and as well as for interpolation [12] of the theory.

The algorithm in [28] follows a similar approach to the uniform interpolation algorithm for EUF in the sense that the attention is given to one of the formulas in the interpolation pair [1]. Other approaches towards interpolation follow graph-based algorithms which idea combines the reduction of UTVPI formulas to difference logic [39] and a cycle detection of maximal size [12].

[1]This implementation uses the first formula of the pair.

4.1 Kapur's Uniform Interpolant Algorithm for the UTVPI theory

The algorithm proposed [28] uses inference rules to obtain the normal form of the conjunction of inequalities of octagon formulas as well as eliminating the uncommon variables from the A-part of the input formula. The rules are the following:

$$\frac{ax + ax \leq c \qquad a \in \{-1, 0, 1\} \text{ and } x \in Vars}{ax \leq \lfloor \frac{c}{2} \rfloor} \text{ Normalize}$$

$$\frac{s_1x_1 + s_2x_2 \leq c_1 \qquad -s_2x_2 + s_3x_3 \leq c_2}{s_1x_1 + s_3x_3 \leq c_1 + c_2} \text{ Elim}$$

The algorithm normalizes the inequalities at the beginning as a preprocessing step and applies the Normalize and Elim rule whenever it is possible until no more uncommon variables remain in the input formula. Hence, having an efficient representation of the inequalities and match detection (similar to detecting pivots for resolution in SAT) is important for an efficient implementation.

4.2 Implementation

The signature used by the implementation to encode UTVPI formulas is $\{x_0, x_1, \ldots, x_n, +, -, \leq\}$, thus all the variables are indexed by a natural number. The variable x_0 is a *dummy variable* that acts as a place-holder for 0.

The thesis work introduces the following data structures in order to obtain an efficient implementation:

- Indexing data structure which encodes inequalities of the input formula using natural numbers. The latter is obtained by introducing an effective enumeration on the UTVPI terms in a given UTVPI signature. The latter is represented with a function $Position :$ UTVPI term $\to \mathbb{N}$.

- Array of numbers *Bounds* indexed by the numeral representation of the inequalities representing the minimum bound of the encoded inequality, i.e. given an UTVPI inequality $a_1x_1 + a_2x_2 \leq c$, then $Bounds[Position(a_1x_1 + a_2x_2)] = c$

- Data structure to keep track of the signs of variables to be eliminated in the inequalities for efficient matching.

- Data structure to represent an UTVPI term in normal form endowed with addition and subtraction operations and the *Position* function mentioned in the first item.

4.2.1 Normal Forms and Ordering of UTVPI terms

Normal forms helps us to avoid the ambiguity introduced by the commutativity of addition and neutrality of adding by 0. Also, normal forms allow the data structures mentioned above to keep track of less UTVPI terms. The normal form of a UTVPI term is simply defined by the following function:

$$norm(\pm x_m \pm x_n) = \begin{cases} \pm x_{max(m,n)} \pm x_{min(m,n)} & \text{if } m \neq n \\ \pm x_n + x_0 & otherwise \end{cases}$$

In order to obtain a bijection between UTVPI terms and natural numbers, first we define an ordering on the normal forms of UTVPI terms. We encode the UTVPI term $\pm x_m \pm x_n$ using the point $(\pm m, \pm n) \in \mathbb{Z}^2$ and let $TermToPoint$ be a map such that $\pm x_m \pm x_n \mapsto (\pm m, \pm n)$. We define the following orderings relevant to the UTVPI term ordering:

Definition 4.2.1. *Let $\succ_m$ be an ordering on the integers such that $a \succ_m b$ if and only $|a| > |b|$ or ($|a| = |b|$ and $a > b$) where $>$ is the standard ordering on integers.*

Let $\succ_p$ be an ordering on pair of integers such that $(m_1, n_1) \succ_p (m_2, n_2)$ if and only if $m_1 \succ_m m_2$ or ($m_1 = m_2$ and $n_1 \succ_m n_2$).

Let $\succ_t$ be an ordering on UTVPI terms of the form $\pm x_m \pm x_n$ such that $t_1 \succ_t t_2$ if and only if $TermToPoint(t_1) \succ_p TermToPoint(t_2)$.

Example 4.2.1.1. *The first 32 elements (in ascending order w.r.t. $\prec_t$) of UTVPI terms are the following:*

- $x_0 + x_0$
- $-x_1 + x_0, x_1 + x_0$
- $-x_2 + x_0, -x_2 - x_1, -x_2 + x_1, x_2 + x_0, x_2 - x_1, x_2 + x_1$
- $-x_3 + x_0, -x_3 - x_1, -x_3 + x_1, -x_3 - x_2, -x_3 + x_2, x_3 + x_0, x_3 - x_1, x_3 + x_1, x_3 - x_2, x_3 + x_2,$

4.2.2 Bijection between normalized UTVPI terms and natural numbers

Let T be the set of normalized UTVPI terms. Using the previous ordering $\succ_t$ on T makes clear that, since $|T| \leq |\mathbb{Z}^2|$, then T is countable and thus there exists a bijection between T and $\mathbb{N}$. In order to construct an explicit bijection, we notice the following facts.

We can arrange ordered partitions P of T such that two normalized UTVPI terms $\pm x_{m_1} \pm x_{m_2}$ and $\pm x_{n_1} \pm x_{n_2}$ belong to the same partition if $|m_1| = |m_2|$.

The example 4.2.1.1 arranged the normalized UTVPI terms into this ordered partitions listing them by items. We notice that each partition contains $2(1+2(i-1))$ elements except the partition containing $x_0 + x_0$ using the following lemma.

Lemma 4.2.1. *The i^{th} ordered partition of P contains $2(1 + 2(i - 1))$ elements.*

Proof. Let A be the i^{th} ordered partition from P. We notice that A contains two disjoint subsets with the same number of elements. The first one is $\{-x_i + x_0\} \cup \{-x_i \pm x_j | 1 \leq j < i\}$ and the second one is $\{x_i + x_0\} \cup \{x_i \pm x_j | 1 \leq j < i\}$. The cardinality of each of these subsets of A is $1 + 2(i - 1)$. Thus, $|A| = 2(1 + 2(i - 1))$. Hence, the assertion holds true. $\square$

Using the previous lemma, it is easy to see that the first element of the i^{th} ordered partition is $2(i-1)^2+1$ by taking the sums of all the cardinalities of all the previous ordered partitions and including the first ordered partition $\{x_0 + x_0\}$. Let t be the n^{th} normalized UTVPI term. The latter means that t belongs to the $\lfloor\sqrt{\frac{n-1}{2}} + 1\rfloor^{th}$ ordered partition. Let $i = \lfloor\sqrt{\frac{n-1}{2}} + 1\rfloor$. Hence, t is of the form $\pm x_i \pm x_j$ for some $j < i$. To find the signs of and index j of t, we can check if $d := n - 2(i - 1)^2 - 1$ (the distance between the t and the first element of its ordered partition) if greater than or equal to $1 + 2(i - 1)$. The last condition just detects if t belongs to the second half or to the first half of the i^{th} ordered partition, which will indicate the first sign of t. The second sign and index j can be obtained by checking the parity of d and by computing $(d - 1)/2$. The formal algorithm for this construction is shown in Algorithm 9 of this subsection.

Similarly, given a normalized UTVPI term $\pm x_m \pm x_n$ we can compute its position in the enumeration using the signs and index information using the previous formulas. The formal algorithm for this construction is shown in Algorithm 10 of this subsection.

This explicit bijection allows us to implement a data structure *Bounds* based on an array of integers extended with $\pm\infty$ to encode upper bounds indexed by the natural number representing the normalized UTVPI term from an UTVPI inequality. For initialization purposes, all the entries in this vector are set to $+\infty$ and these values are updated accordingly to keep track of the minimum possible value for the inequality after the application of the inference rules mentioned at the introduction of the section.

Example 4.2.1.2. *Let us consider the input formula* $\alpha_1 = \{x_1 - x_2 \geq -4, -x_2 - x_3 \geq 5, x_2 + x_5 \geq 4, x_2 + x_4 \geq -3\}$

The normalized input is $\{-x_2 + x_1 \geq -4, -x_3 - x_2 \geq 5, x_5 + x_2 \geq 4, x_4 + x_2 \geq -3\}$.

With the above information, the data structure Bounds initially contains the following entries:

$$Bounds[5] = -4, \; since \; position(-x_2 + x_1) = 5$$

$$Bounds[12] = 5, \; since \; position(-x_3 - x_2) = 12$$

$$Bounds[46] = 4, \; since \; position(x_5 + x_2) = 46$$

$$Bounds[30] = -3, \; since \; position(x_4 + x_2) = 30$$

$$Bounds[i] = +\infty, \; where \; i \in \mathbb{N} \setminus \{5, 12, 46, 30\}$$

4.3 Evaluation

4.3.1 Detailed evaluation of examples

Let us consider the following example: $\alpha_1 = \{x_1 - x_2 \geq -4, -x_2 - x_3 \geq 5, x_2 + x_6 \geq 4, x_2 + x_5 \geq -3\}; \beta_1 = \{-x_1 + x_3 \geq -2, -x_4 - x_6 \geq 0, -x_5 + x_4 \geq 0\}$.

Algorithm 9 UTVPI constructor

procedure UTVPI CONSTRUCTOR(position : integer)
  coefficient1 = 0
  coefficient2 = 0
  varindex1 = 0
  varindex2 = 0
  if position = 0 **then**
    return
  end if
  varindex1 = $\sqrt{\frac{position-1}{2}} + 1$
  initial_group_position = $2 * (varindex1 - 1)^2 + 1$
  half_size_group = $2 * varindex1 - 1$
  if position ≤ initial_group_position + half_size_group **then**
    coefficient1 = -1
    if position = initial_group_position **then**
      coefficient2 = 0
      varindex2 = 0
      return
    end if
    separation = position - initial_group_position
    varindex2 = $\frac{separation-1}{2} + 1$
    if mod separation 2 = 0 **then**
      coefficient2 = 1
      return
    end if
    coefficient2 = -1
    return
  end if
  coefficient1 = 1
  if position = initial_group_position + half_size_group + 1 **then**
    coefficient2 = 0
    varindex2 = 0
    return
  end if
  separation = position - initial_group_position - half_size_group - 1
  varindex2 = $\frac{separation-1}{2} + 1$
  if mod separation 2 = 0 **then**
    coefficient2 = 1
    return
  end if
  coefficient2 = -1
  return
end procedure

The output obtained by our implementation is (and (≤ (- (- x6) x1) 0) (≤ (+ (- x6) x3) (- 9)) (≤ (- (- x5) x1) 7) (≤ (+ (- x5) x3) (- 2)))) and produced the following trace for this problem:

Algorithm 10 UTVPI position

```
procedure UTVPI POSITION( s_1 x_{m_1} + s_2 x_{m_2} : UTVPI term)
    initial_group_position = 2 * (m_1 - 1)^2 + 1
    if s_1 = -1 then
        sign_a_offset = 0
    else
        if s_1 = 0 then
            return 0
        else
            if s_1 = 1 then
                sign_a_offset = 2 * (m_1 - 1) + 1
            end if
        end if
    end if
    if s_2 = -1 then
        sign_b_offset = 1 + 2 * (m_2 - 1)
    else
        if s_2 = 0 then
            sign_b_offset = 0
        else
            if s_2 = 1 then
                sign_b_offset = 2 * m_2
            end if
        end if
    end if
    return initial_group_position + sign_a_offset + sign_b_offset
end procedure
```

```
Processing
(+ (- c_x1) a_x2)
Updating structure with
x_2 - x_1 <= 4
Processing
(+ a_x2 c_x3)
Updating structure with
x_3 + x_2 <= -5
Processing
(- (- a_x2) c_x6)
Updating structure with
- x_4 - x_2 <= -4
Processing
(- (- a_x2) c_x5)
Updating structure with
- x_5 - x_2 <= 3
Removing this var: x_0
Removing this var: x_1
Removing this var: x_2
Reducing x_2 - x_1 and - x_4 - x_2
Result: - x_4 - x_1
Reducing x_2 - x_1 and - x_5 - x_2
Result: - x_5 - x_1
Reducing x_3 + x_2 and - x_4 - x_2
Result: - x_4 + x_3
```

```
Reducing x_3 + x_2 and - x_5 - x_2
Result: - x_5 + x_3
Removing this var: x_3
Removing this var: x_4
Removing this var: x_5
Interpolant:
(ast-vector
  (<= (- (- x6) x1) 0)
  (<= (+ (- x6) x3) (- 9))
  (<= (- (- x5) x1) 7)
  (<= (+ (- x5) x3) (- 2)))
```

The Z3 SMT solver provides mechanisms to modify the arithmetic engine and several plug-ins to specialize algorithm for specific theories. It contains a proper specialization to work with UTVPI queries for satisfiability checking. However, the interpolation APIs do not include mechanisms to specialize the interpolation algorithm for UTPVI formulas, i.e. Z3 does produce interpolant in the UTVPI theory. Thus, the interpolant obtained by Z3 for the above problem is : (and (≤ 9 (+ (* (-1) x3) (* 2 x6) x1)) (≤ (- 5) (+ (* (- 1) x3) (* 2 x5) x1))). We can notice by the coefficients in the result that the interpolant is not a UTVPI formula, thus Z3 must have reduced the problem to linear integer arithmetic.

The result obtained by Mathsat is (and (≤ (- 5) (+ x1 (+ (* (- 1) x3) (* 2 x5)))) (≤ 9 (+ x1 (+ (* (- 1) x3) (* 2 x6))))) which is the same as Z3 modulo the commutativity of the additions in the expression. Despite this difference, the following query to Z3 verifies that the interpolation produced by our implementation implies the interpolation produced by the SMT solver above mentioned; at the same time, the interpolant produced by the SMT solver does not imply our interpolant.

```
(declare-fun x1 () Int)
(declare-fun x3 () Int)
(declare-fun x5 () Int)
(declare-fun x6 () Int)

(define-fun implementation_interpolant () Bool
(and
(<= (- (- x6) x1) 0)
(<= (+ (- x6) x3) (- 9))
(<= (- (- x5) x1) 7)
(<= (+ (- x5) x3) (- 2))
```

```
)
)

(define-fun z3_interpolant () Bool
(and
(<= 9 (+ (* (- 1) x3) (* 2 x6) x1))
(<= (- 5) (+ (* (- 1) x3) (* 2 x5) x1))
)
)

(push)
(assert (not (implies  z3_interpolant implementation_interpolant)))
(check-sat) ;; This check returns sat, i.e. z3_interpolant does not imply implementation_interpolant
(pop)
(push)
(assert (not (implies implementation_interpolant z3_interpolant)))
(check-sat) ;; This check returns unsat, i.e. implementation_interpolant implies z3_interpolant
(pop)
```

For the next example, let us consider $\alpha_2 = \{-x_2 - x_1 + 3 \geq 0, x_1 + x_3 + 1 \geq 0, -x_3 - x_4 - 6 \geq 0, x_5 + x_4 + 1 \geq 0\}; \beta_2 = \{x_2 + x_3 + 3 \geq 0, x_6 - x_5 - 1 \geq 0, x_4 - x_6 + 4 \geq 0\}$.

Our implementation produced the following output (and (≤ (+ (- x3) x2) 4) (≤ (+ x4 x3) (- 6)) (≤ (- (- x5) x4) 1)) and obtained the following trace:

```
Processing
(+ c_x2 a_x1)
Updating structure with
x_2 + x_1 <= 3
Processing
(- (- c_x3) a_x1)
Updating structure with
- x_3 - x_2 <= 1
Processing
(+ c_x4 c_x3)
Updating structure with
x_4 + x_3 <= -6
Processing
(- (- c_x5) c_x4)
Updating structure with
- x_5 - x_4 <= 1
Removing this var: x_0
Removing this var: x_1
Removing this var: x_2
Reducing x_2 + x_1 and - x_3 - x_2
Result: - x_3 + x_1
Removing this var: x_3
Removing this var: x_4
Removing this var: x_5
(ast-vector
  (<= (+ (- x3) x2) 4)
  (<= (+ x4 x3) (- 6))
```

```
(<= (- (- x5) x4) 1))
```

The interpolant obtained by Z3 is (and (≤ (- 4) (+ x3 (* (- 1) x2))) (≤ (+ x3 x4) (- 6)) (≥ (+ x4 x5) (- 1))); and the interpolant produced by Mathsat is (≤ (+ x2 (+ x3 (+ x4 (* (- 1) x5)))) (- 7)). Using Z3, we were able to verify that:

- the interpolantion obtained by our implementation is equivalent to the interpolant obtained by Z3.
- the interpolant obtained by our implementation implies the interpolant obtained by Mathsat, but the converse does not hold.

```
(declare-fun x1 () Int)
(declare-fun x2 () Int)
(declare-fun x3 () Int)
(declare-fun x4 () Int)
(declare-fun x5 () Int)
(declare-fun x6 () Int)

(define-fun implementation_interpolant () Bool
(and
(<= (+ (- x3) x2) 4)
(<= (+ x4 x3) (- 6))
(<= (- (- x5) x4) 1))
)

(define-fun z3_interpolant () Bool
(and
(<= (- 4) (+ x3 (* (- 1) x2)))
(<= (+ x3 x4) (- 6))
(>= (+ x4 x5) (- 1)))
)

(define-fun mathsat_interpolant () Bool
(<= (+ x2 (+ x3 (+ x4 (* (- 1) x5)))) (- 7))
)

(push)
(assert (not (iff z3_interpolant implementation_interpolant)))
(check-sat) ;; This check returns unsat, i.e. z3_interpolant is equivalent to implementation_interpolant
(pop)

(push)
(assert (not (implies  mathsat_interpolant implementation_interpolant)))
(check-sat) ;; This check returns sat, i.e. mathsat_interpolant does not imply implementation_interpolant
(pop)

(push)
```

```
(assert (not (implies implementation_interpolant mathsat_interpolant)))
(check-sat) ;; This check returns unsat, i.e. implementation_interpolant implies mathsat_interpolant
(pop)
```

4.3.2 Performance comparison with iZ3 and MathSat

This section discusses a benchmark of interpolation generation for the UTVPI theory. Similarly to the previous chapter, we compare the performance of our tool with respect to the iZ3 and Mathsat.

Benchmark description

The benchmark contains the following parameters:

- l stands for a random number of the max value of the bounds
- m stands for the number of variables allowed in the random signature
- n stands for the number of inequalities of the form: $a_1 x_{k_1} + a_2 x_{k_2} \leq c$ or $a_1 x_{k_1} - a_2 x_{k_2} \leq c$ where a_1, a_2 are chosen uniformly at random from the set of elements $\{-1, 0, 1\}$, k_1, k_2 are chosen uniformly at random from the set of elements $\{1, \ldots, n\}$, and c is chosen uniformly at random from the set $\{-l, \ldots, l\}$

We constructed a pair of inconsistent formulas $(A - part, B - part)$ using an identical construction to the benchmark proposed in the previous chapter, using two $z3 :: solver$ in order to maintain each $A - part$ and $B - part$ consistent but inconsistent with each other.

Experimental results

We designed the problem because the randomness makes it difficult to come up with trivial solutions. This problem was executed 100 and 10000 times using the parameters $(l = 1000, m = 10, n = 5)$ and $(l = 10, m = 10, n = 20)$ respectively.

The following graph reports the time needed by our implementation, iZ3, and the interpolation generation algorithm from Mathsat. It is well known that both iZ3 and Mathsat does not compute uniform interpolants for UTVPI. Regardless, the benchmark was used with the purpose to compare their execution time on normal interpolants.

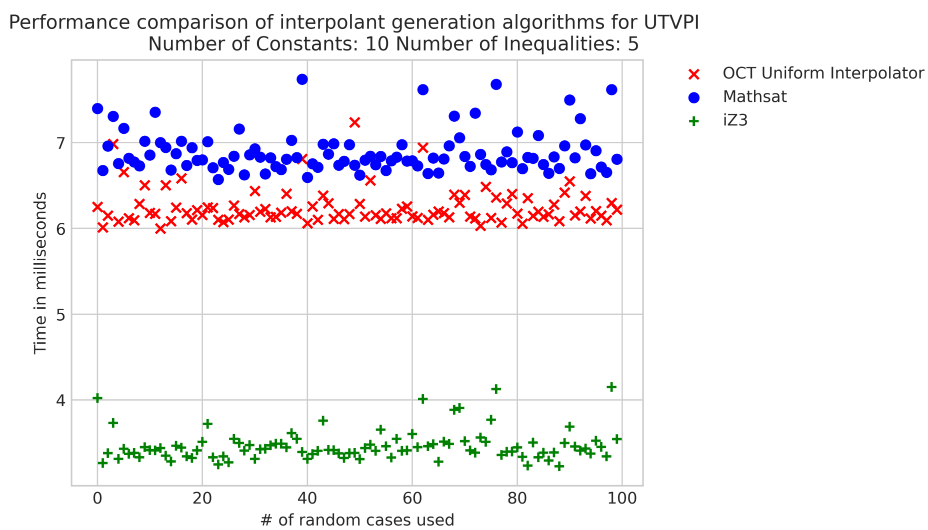

Figure 4.1: Performance comparison graph of UTVPI interpolant generation algorithms for the benchmark (l = 1000, m = 10, n = 5)

The following graph compares an upper bound of the number of addition operations required by iZ3 and our implementation. The upper bound in iZ3 denotes the number of row operations since the internal implementation in Z3 uses a matrix representation of the linear terms where the upper bound for our implementation counts the number of additions used to compute the interpolants. The former is ob-

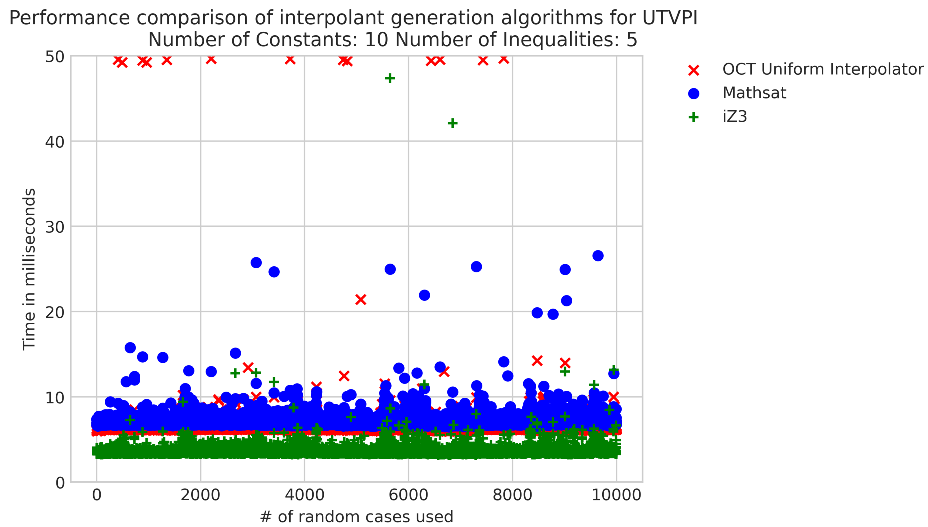

Figure 4.2: Performance comparison graph of UTVPI interpolant generation algorithms for the benchmark (l = 1000, m = 10, n = 5)

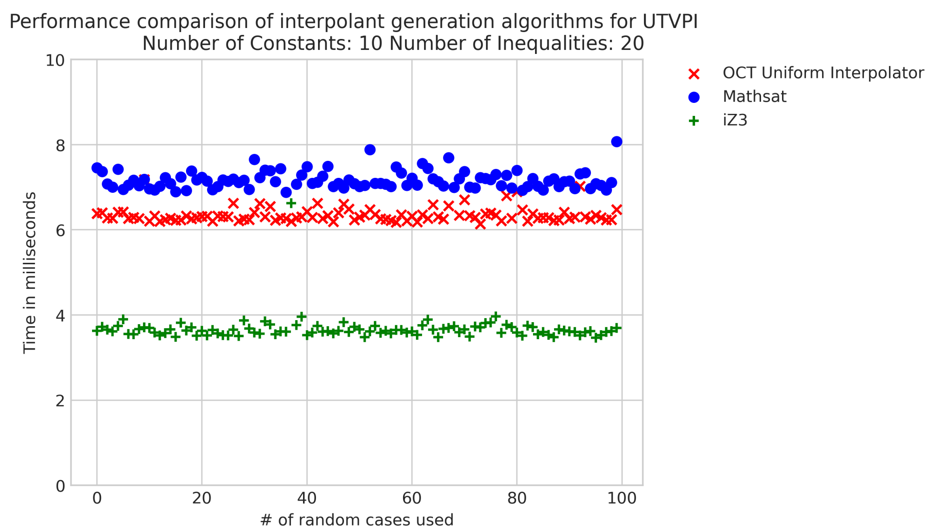

Figure 4.3: Performance comparison graph of UTVPI interpolant generation algorithms for the benchmark (l = 1000, m = 10, n = 20)

tained using the z3-statistics feature from Z3; the latter is computed by introducing appropriate logging variables in our implementation.

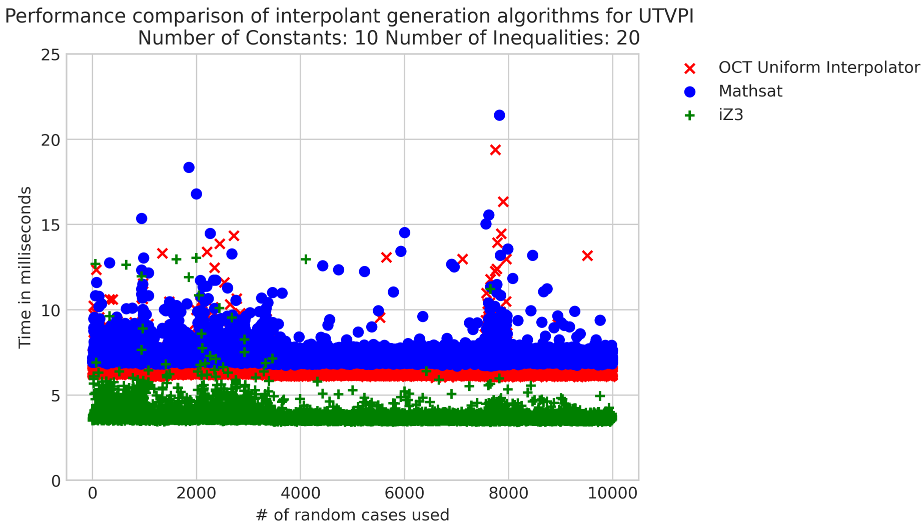

Figure 4.4: Performance comparison graph of UTVPI interpolant generation algorithms for the benchmark (l = 1000, m = 10, n = 20)

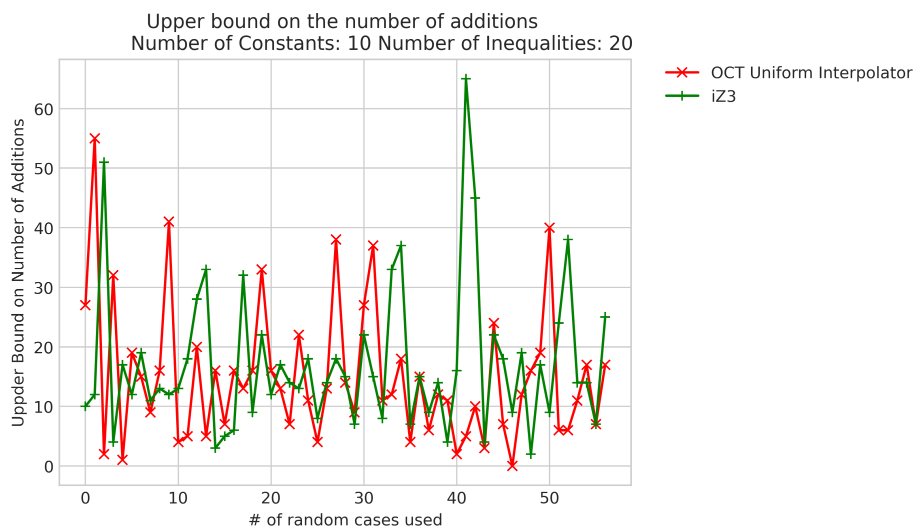

Figure 4.5: Performance comparison graph of UTVPI interpolant generation algorithms for the benchmark (l = 1000, m = 10, n = 20)

4.4 Conclusions

This chapter presented the approach by Prof. Kapur for computing the uniform interpolant of a satisfiable formula in the UTVPI theory. Several examples and testing of the implementation indicated that the output produced by Kapur's algorithm produces a stronger interpolant than the other ones produced by iZ3 and Mathsat. The performance comparison showed a closer difference in times compared to the performance comparison obtained for the EUF theory.

In order to improve the current implementation it will be interesting to explore the use of heuristics to determine the order in which the uncommon variable should be eliminated. The current implementation uses a lexicographic approach based on the occurrence of the symbols in the input formula. Different heuristic can consider the number of occurrences of the uncommon symbols in different inequalities, a topological order based on the dependency of the linear combinations of the inequalities, etc.

Chapter 5

Interpolation algorithm for the theory combination of EUF and UTVPI

In previous chapters, we discussed uniform interpolanting algorithms for the EUF and UTVPI theories respectively. This was possible since each theory satisfies the Uniform Interpolant Property (UIP). Nonetheless, as shown in [9], the UIP does not hold for combined theory of EUF and integer difference logic (IDL). The same counter-example applies for the theory combination of EUF and UTPVI. Hence, there cannot be an algorithm for computing the uniform interpolant for this combined theory. Thus, this chapter discusses interpolation algorithm for the combined theory of EUF and UTVPI and conditions in which the output obtained is a uniform interpolant.

Theory combination techniques involve reusing the algorithms for verification problems of the theories involved by either purifying terms over the theories, or reducing the original problem into a base theory, or a combination of these two.

Usually the approaches following the first approach aforementioned rely on a Nelson-Oppen framework [50, 3, 5]

Despite possibly more efficient approaches using model-based theory combination techniques [1] [3], the latter requires operations which many SMT solvers do not provide proper API to implement these. Hence, the approach used in the thesis work follows [50] since it does not require extensive modification to the decision procedures used. Many of the necessary modifications were implemented on top of Z3 and PicoSAT/TraceCheck.

The propagation of new equalities and disjunction of equalities requires the additional step to split these formulas into the correct part of the interpolant pair. Among the major contributions of [50] was the introduction of the class of equality interpolanting theories.

Definition 5.0.1. *A theory $\mathcal{T}$ is* equality interpolating *if for every A, B in $\mathcal{T}$ and every AB-mixed equality $a = b$ such that $A \wedge B \models_{\mathcal{T}} a = b$, there exists a term t in $\mathcal{T}$ (called interpolanting term) such that $A \wedge B \models_{\mathcal{T}} a = t$ and $A \wedge B \models_{\mathcal{T}} b = t$.*

The relevance of the existance of the interpolating term for a deduced AB-mixed equality becomes relevant in the context of splitting a formula into a suitable A-part and B-part respectively. Deciding where to include AB-common terms to either the A-part or the B-part of the interpolantion pair affects the final result since the interpolant will be *closer* to the A-part or to the B-part respectively. The authors in [50] include AB-common terms to the B-part. However, this implementation work includes AB-common terms to the A-part due to the interest in uniform interpolants.

[1]An interesting property of model-based theory combination is that it is not needed to propagate disjunctions, even if the theories are not convex. The reason is due to the *disjunctiviness* of the problem is handled *lazily* by the SAT solver.

5.1 A partially sound uniform interpolant generation algorithm for the combined theory of EUF and UTVPI

This section introduces a partially sound uniform interpolant generation algorithm for the aforementioned theories in the sense that it produces a uniform interpolant if for all variables x to eliminate in the UTVPI components of the input formula ψ, either:

- $\psi \models_{EUF+UTVPI} x \leq n_1$ and $\psi \models_{EUF+UTVPI} -x \leq n_2$ where $n_1, n_2 \in \mathbb{Z}$, or
- There exists $a_1x + a_2y$ with y a common variable such that $\psi \models_{EUF+UTVPI} a_1x + a_2y \leq n_1$ and $\psi \models_{EUF+UTVPI} -a_1x - a_2y \leq n_2$, where $a_1, a_2 \in \{-1, 0, 1\}$ and $n_1, n_2 \in \mathbb{Z}$

The algorithm is a tableux-like algorithm which specifies formula state and reduction rules. It extends the approach in [25] by incorporating additional structure to handle UTVPI formulas and more reduction rules to handle the Normalize and Elim rules introduced in the uniform interpolant generation algorithm for UTVPI theory in Chapter 4.

5.1.1 A tableux-like uniform interpolant generation algorithm for EUF

In this section, we review the uniform interpolant generation algorithm for EUF from [25]. The algorithm follows a similar preprocessing step as the uniform interpolation algorithm for EUF discussed in Chapter 3. The 'formula state' encodes a triplet $\langle\delta(\underline{y},\underline{z}),\phi(\underline{y},\underline{z}),\psi(\underline{e},\underline{y},\underline{z})\rangle$ of the resulting formula after preprocessing with the following meaning:

- $\underline{e}$ encodes information about the variables to be eliminated.
- $\underline{y}$ encodes information about the variables to be eliminated than became common variables since the algorithm detected an equality of a variable in this category with a common term.
- $\underline{z}$ encodes information about the common variables. It is worth mentioning that each $\underline{\mathrm{e}}$, $\underline{\mathrm{y}}$, and $\underline{\mathrm{z}}$ are indexed terms which encode an ordering relation between them.
- $\delta(\underline{y},\underline{z})$ stands for the formulas that provide an explicit definition for variables in $\underline{y}$ using a DAG-representation.
- $\phi(\underline{y},\underline{z})$ stands for the formulas that do not contain variables to eliminate.
- $\psi(\underline{e},\underline{y},\underline{z})$ stands for the formulas that contain variables to eliminate.

Some definitions are needed before discussing the tableux rules in [25].

Definition 5.1.1. *A term t (resp. literal L) is $\underline{e}$-free when there is no occurrence of variables to eliminate in t (resp. L).*

Two flat terms t, u of the form

$$t := f(a_1,\ldots,a_n), u := f(b_1,\ldots,b_n)$$

are said to be compatible *if and only if every $i = 1,\ldots,n$, either a_i is identical to b_i or both a_i and b_i are $\underline{e}$-free.*

The difference set of two compatible terms *like above is the set of dis-equalities $a_i \neq b_i$ such that a_i is not identical to b_i.*

The algorithm in [25] provides the following tableux rules:

1. Simplification rules:
   - 1.0) If an atom like $t = t$ belong to ψ, just remove it; if a literal like $t \neq t$ occurs somewhere, delete ψ, replace ϕ with $\perp$ and stop.
   - 1.i) If t is not a variable to eliminate and ψ contains both $t = a$ and $t = b$, remove the latter and replace it with $b = a$.
   - 1.ii) If ψ contains $e_i = e_j$ with $i > j$, remove it and replace every e_i in δ, ϕ, ψ by e_j.
2. DAG update rule: if ψ contains $e_i = t(\underline{y}, \underline{z})$, remove it, rename every e_i in δ, ϕ, ψ as y_j (for fresh y_j) and add $y_j = t(\underline{y}, \underline{z})$ to $\delta(\underline{y}, \underline{z})$.
3. e-Free Literal rule: if ψ contains a literal $L(\underline{y}, \underline{z})$ move it to $\phi(\underline{y}, \underline{z})$.
4. If ψ contains a pair of atoms $t = a$ and $u = b$, where t and u are compatible flat terms, and not dis-equality from the difference set of t, u belongs to ϕ, then non-deterministically apply one of the following alternatives:
   - 4.0) Remove from ψ the atom $f(b_1, \ldots, b_n) = b$, add to ψ the atom $b = a$ and add to ϕ all the equalities $a_i = b_i$ such that $a_i \neq b_i$ is in the difference set of t, u;
   - 4.1) Add to ϕ one of the dis-equalities form the difference set of t, u.

5.1.2 Our proposed partially sound uniform interpolant generation algorithm for EUF + UTVPI

Our algorithm first purifies a given satisfiable input formula in the combined theory of EUF and UTVPI and uses an extended tableux-like algorithm using additional rules to deal with UTVPI formulas. If the input formula is not satisfiable, then return $\perp$ as result. We use the data structures discussed in Chapter 4 to deal with UTVPI formulas, hence we keep a normal form representation of the UTVPI inequalities in the formula state inside the proposed tableux-like algorithm. The previous rules of the uniform interpolant generation algorithm for EUF involving propagation of equations suits the UTVPI component as well. The additional rules are the following:

5. Eliminate uncommon UTVPI terms: if there are UTVPI inequalities of the form $a_i x + a_j e_j \leq k_1$ and $a_k y - a_j e_j \leq k_2$ in ψ, then introduce to ϕ the UTVPI inequality $a_i x + a_k y \leq k_1 + k_2$.

6. Normalize UTVPI inequalities: if there is a UTVPI inequality of the form $a_i x + a_i x \leq k$ in the formula state, then remove it and insert to ψ the UTVPI inequality $a_i x \leq \lfloor k/2 \rfloor$

7. Normalize bounds: if there are two UTVPI inequalities of the form $a_i x + a_j y \leq k_1$, $a_i x + a_j y \leq k_2$ in the formula state with $\{k_1, k_2\} \in \mathbb{N}$, then remove them both and insert to ψ the UTVPI inequality $a_i x + a_j y \leq min(k_1, k_2)$

8. Propagate fully bounded uncommon UTVPI inequalities: if there are two UTVPI inequalities in ψ of the form $a_i e_i + a_j e_j \leq k_1$ and $-a_i e_i - a_j e_j \leq k_2$, where $a_i \in \{1, -1\}, a_j \in \{1, 0, -1\}$ and $i > j$ or e_i is uncommon and e_j is common then non-deterministically apply the following rule:

   – Remove both $a_i e_i + a_j e_j \leq k_1$ and $-a_i e_i - a_j e_j \leq k_2$ from ψ and replace every e_i by $l - a_i a_j e_j$ where $l \in \{-a_j k_2, -a_j k_2 + 1, \ldots, a_j k_1 - 1, a_j k_1\}$.

Remark : Notice that if no transformation applies to the formula state, we obtain the same the following types of formulas for the EUF component according to [25]

- ψ only contains dis-equalities of the kind $e_i \neq a$ and equalities of the kind $f(a_1, \ldots, a_n) = a$. If ψ contains equalities of the kind $f(a_1, \ldots, a_n) = a$ it means that at least one a_i must belong to $\underline{e}$. If ψ contains two equalities of the form $f(a_1, \ldots, a_n) = a$ and $f(b_1, \ldots, b_n) = b$ then it means $f(a_1, \ldots, a_n)$ and $f(b_1, \ldots, b_n)$ are incompatible or $a_i \neq b_i$ belongs to ϕ.

Similarly, the following types of formulas for the UTVPI component exists in the formula state if no transformation apply: bounded only by an upper bound, bounded only by a lower bound, and fully Bounded with $\pm$ infinity. The latter follows directly from the normal form representation of UTVPI inequalities induced by the data structures introduced in Chapter 4. Otherwise, rules 8 and 9 should have applied.

5.1.3 Termination, and partial soundness of the proposed algorithm

Lemma 5.1.1. *The non-deterministic procedure presented above always terminates.*

Proof. Following a similar proof as in [25] it is enough to show every branch of the algorithm terminates. The rules involving the EUF component are cover in [25]. For the rest of the rules involving UTVPI expressions, we first notice that there is a $\mathcal{O}(n^2)$ bound over all the UTVPI expressions for UTVPI signature S where n is the number of distinct variables in S. The rules relax the bounds of all the bounds in the inequalities, which does not induce a negative cycle, otherwise the input formula could not be satisfiable. $\square$

Before proving the partial soundness of the tableux algorithm for the theory combination of EUF and UTVPI, we first state important results relating the existence of uniform interpolant.

Lemma 5.1.2. *[25] Let R be a canonical ground rewrite system over a signature Σ. There is a Σ-structure $\mathcal{M}$ such that for every pair of ground terms t, u we have that $\mathcal{M} \models t = u$ if and only if R-normal formal of t is the same as the R-normal form of u. Consequently, R is consistent with a set of negative literals S if and only if for every $t \neq u \in S$ the R-normal forms of t and u are different.*

Lemma 5.1.3. *[8] Let T be a theory. A formula $\psi(\underline{y})$ is a uniform interpolant in T of $\exists \underline{e}.\phi(\underline{e}, \underline{y})$ if and only if it satisfies the following two conditions:*

i) $T \models \forall \underline{y}.((\exists \underline{e}.\phi(\underline{e}, \underline{y})) \rightarrow \psi(\underline{y}))$

ii) for every model $\mathcal{M}$ of T, for every tuple of elements $\underline{a}$ from the support of $\mathcal{M}$ such that $\mathcal{M} \models \psi(\underline{a})$ it is possible to find another model $\mathcal{N}$ of T such that M embeds into $\mathcal{N}$ and $\mathcal{N} \models \exists \underline{e}.\psi(\underline{e}, \underline{a})$

Theorem 5.1.4. *Given an input formula $\psi := \exists \underline{e}.\phi(\underline{e}, \underline{z})$, if ψ satisfies the weakening conditions in 5.1 and the proposed algorithm terminates with its branches in the formula states*

$$\langle \delta_1(\underline{y_1}, \underline{z}), \phi_1(\underline{y_1}, \underline{z}), \psi_1(\underline{e_1}, \underline{y_1}, \underline{z})\rangle, \ldots, \langle \delta_k(\underline{y_k}, \underline{z}), \phi_k(\underline{y_k}, \underline{z}), \psi_k(\underline{e_k}, \underline{y_k}, \underline{z})\rangle$$

Then the uniform interpolant of $\exists \underline{e}.\phi(\underline{e}, \underline{z})$ in $EUF + UTVPI$ is the DAG-unravelling [2] of the formula

$$\bigvee_{i=1}^{k} \exists \underline{y_i}.(\delta_i(\underline{y_i}, \underline{z}) \wedge \phi_i(\underline{y_i}, \underline{z}))$$

Proof. The proof follows the similar style of the proof of Theorem 5.1 in [25]. Let α be $\bigvee_{i=1}^{k} \exists \underline{y_i}.(\delta_i(\underline{y_i}, \underline{z}) \wedge \phi_i(\underline{y_i}, \underline{z}))$. First, we notice that it is enough to prove the two items 5.1.3 to show our assertion. The first item follows since α was obtained from the rules in the proposed algorithm.

[2]Unravelling means that the explicit recursive substitution of the each of the y_i variables are substituted in $\phi_i(\underline{y_i}, \underline{z})$ using the equations in $\delta_i(\underline{y_i}, \underline{z})$.

To address the second item of the lemma, given a model $\mathcal{M}$ such that $\mathcal{M} \models \alpha$, finding an isomorphic embedding $\mathcal{N}$ such that $\mathcal{N} \models \exists \underline{e}.\phi(\underline{e}, \underline{z})$ is equivalent , using Robinson Lemma [10], to prove that there is a model for $\Delta(\mathcal{M}) \cup \phi \cup \{a = \mathcal{I}(a)\}_{a \in \underline{y} \cup \underline{z}}$.

Following [25], we can obtain a model for the EUF component using the model induced by the canonical form obtained by orienting the equations in ψ. In other to obtain a model for the UTVPI component, we noticed that if the input formula satisfies the weakening conditions in 5.1 then either:

- If the uncommon variable is bounded from below and bounded from above, then we can find a model for these variables by picking an integer in the respective range of the bounds.
- If the above condition does not hold, then there exists an UTVPI expression $a_1 x + a_2 y$ such that $\psi \models_{EUF+UTVPI} n_2 \leq a_1 x + a_2 y \leq n_1$, where y is common. Thus, we can generate a canonical rewrite system for each of the branches that the rule 9. in the proposed algorithm by adding rules of the form $x \to a_1(a_2 y + i)$ where $i \in \{n_2, \ldots, n_1\}$. A model from this induced canonical rewrite system can be obtained by Lemma 5.1.2.

With the latter, we can find a model $\mathcal{N}$ satisfying $\exists \underline{e}.\psi(\underline{e}, \underline{y}, \underline{z})$ with the desired conditions. Therefore, α is an uniform interpolant for $\exists \underline{e}.\phi(\underline{e}, \underline{z})$.

□

5.1.4 Illustrating Example

Let us consider the following input formula in the combined theory satisfying the weakening conditions in 5.1: $\{y - x \leq 0, -y + x \leq 10 y + x \leq 20, -y - x \leq -10, -e + x \leq 0, e - y \leq 0, f(e) = x\}$ with symbols to eliminate to be $\{e\}$.

The normal form produced for the UTVPI component of the proposed algorithm is the following conjunction of inequalities:

$\{x \leq 15, -x \leq -5, y \leq 10, y + x \leq 20, y - x \leq 0, -y \leq 0, -y + x \leq 10, -y - x \leq -10, e \leq 10, e + x \leq 25, e - x \leq 5, e + y \leq 20, e - y \leq 10, -e \leq -5, -e + x \leq 10, -e - x \leq -10, -e + y \leq 5, -e- \leq -5\}$

Since the above contains $e \leq 10$ and $-e \leq -5$ then by rule 8. of the proposed algorithm we make 5 branches propagating the equation $e = i$ where $i \in \{5, \ldots, 10\}$.

The final output produced by the algorith is hence $(f(5) = x \wedge \delta) \vee (f(6) = x \wedge \delta) \vee (f(7) = x \wedge \delta) \vee (f(8) = x \wedge \delta) \vee (f(9) = x \wedge \delta) \vee (f(10) = x \wedge \delta)$ where δ is $x \leq 15 \wedge -x \leq 5 \wedge y \leq 10 \wedge y + x \leq 20 \wedge y - x \leq 0 \wedge -y \leq 0 \wedge -y + x \leq 10 \wedge -y - x \leq -10$.

5.2 Yorsh-Musuvathi Interpolation Combination Framework

The algorithm extends a Nelson-Oppen framework which allows the Yorsh-Musuvathi framework to produce an Interpolant for combined theories using Interpolant generation algorithm for each of the theories involved. In order to integrate interpolants to the latter, the algorithm includes a *partial interpolant* every time a disjunction of equalities (conflict clause) is propagated. These *partial interpolants* are computed from an unsatisfiability proof obtained by including the negation of the disjunction to the formula using the following definition:

Definition 5.2.1. *[50] Let $\langle A, B \rangle$ be a pair of clause sets such that $A \wedge B \vdash \bot$. Let $\mathcal{T}$ be a proof of unsatisfiability of $A \wedge B$. The propositional formula $p(c)$ for a clause c in $\mathcal{T}$ is defined by induction on the proof structure:*

- *if c is one of the input clauses then*

  - *if* $c \in A$, *then* $p(c) := \bot$
  - *if* $c \in B$, *then* $p(c) := \top$

- *otherwise, c is a result of resolution, i.e. let* c_1, c_2 *be two clauses of the form* $x \vee c_1^{'}$, $\neg x \vee c_2^{'}$ *respectively. The partial interpolant for c is defined as follows:*
  - *if* $x \in A$ *and* $x \notin B$ *(x is A-local), then* $p(c) := p(c_1) \vee p(c_2)$
  - *if* $x \notin A$ *and* $x \in B$ *(x is B-local), then* $p(c) := p(c_1) \wedge p(c_2)$
  - *otherwise (x is AB-common), then* $p(c) := (x \vee p(c_1)) \wedge (\neg x \vee p(c_2))$

5.3 Implementation

The thesis implementation uses the Yorsh-Musuvathi framework to reuse the uniform interpolant generation algorithms for the EUF and UTVPI theory. The implementation maintains a map data structure that keeps track of the *partial interpolants*. This ensures that the base case for the above formula $p(c)$ is replaced by previous clauses as required in [50].

Since introducing negations is necessary to compute partial interpolants, we noticed the following interaction with the theories involved in the thesis work:

- EUF case: negations of literals in this theory are just dis-equalities, which the interpolation algorithm implemented handles as Horn clauses with a false head term.
- UTVPI case: negations of literals in this theory are either dis-equalities or strict inequalities. The dis-equalities are purified an appended to the EUF component; strict inequalities of the form $x > y$ are replaced by non-strict inequalities of the form $x \geq y + 1$.

The main loop of the procedure is shown below:

Algorithm 11 Nelson-Oppen Propagation

```
procedure NELSON-OPPEN PROPAGATION ( z3::expr_vector const & part_A, z3::expr_vector const & part_B )
    T1, T2 = Purify(part_A, part_B)
    DisjunctionEqualitiesIterator ψ()
    ψ.init()
    while true do
        if T1 ⊨_EUF ⊥ then
            return T1
        end if
        if T2 ⊨_UTVPI ⊥ then
            return T2
        end if
        if T1 ⊨_EUF ψ.current() then
            if T2 ⊨_UTVPI ψ.current() then
                continue
            else
                append ψ.current() to T2
                ψ.init()
            end if
        else
            if T2 ⊨_UTVPI ψ.current() then
                continue
            else
                append ψ.current() to T2
                ψ.init()
            end if
        end if
        UpdatePartialInterpolant(ψ.current())
        ψ.next()
    end while
end procedure
```

5.4 Evaluation

5.4.1 Detailed evaluation of a complete example

A simple example

Let us consider the following example: $\alpha = \{f(x_1) = 0, x_1 = a, y_1 \leq a\}; \beta = \{x_1 \leq b, y_1 = b, f(y_1) \neq 0\}$. The implementation produces the following interpolant [3]:

$$((x_1 \neq y_1 \vee f(y_1) = 0 \vee (f(x_1) = 0 \wedge ((x_1 = y_1 \vee (-x_1 + y_1 \leq 0 \wedge x_1 - y_1 \leq -1) \vee y_1 - x_1 \leq -1) \wedge (x_1 \neq y_1)))) \wedge (x_1 = y_1 \vee (((x_1 = y_1) \vee (-x_1 + y_1 \leq 0 \wedge x_1 - y_1 \leq -1) \vee y_1 - x_1 \leq -1) \wedge x_1 \neq y_1)))$$

The following SMT query verifies that the previous result obtained is an interpolant of the input formula:

```
(declare-fun x1 () Int)
(declare-fun x2 () Int)
(declare-fun x3 () Int)
(declare-fun y1 () Int)
(declare-fun y2 () Int)
(declare-fun y3 () Int)
(declare-fun a () Int)
(declare-fun b () Int)
(declare-fun f (Int) Int)
(declare-fun g (Int) Int)

(define-fun part_a () Bool
(and
(= (f x1) 0)
(= x1 a)
(<= y1 a)
))

(define-fun part_b () Bool
(and
(<= x1 b)
(= y1 b)
(distinct (f y1) 0)
))
```

[3]A trace of the execution can be found at the Appendix section since it is considerably large to include it in this section

```
(define-fun my_interpolant () Bool

(let ((a!1 (and (<= (+ (* (- 1) x1) y1) 0) (<= (+ x1 (* (- 1) y1)) (- 1)))))
(let ((a!2 (or (= x1 y1) a!1 (<= (+ (* (- 1) x1) y1) (- 1)))))
(let ((a!3 (or (not (= (f x1) 0)) (= 0 (f x1)) (and a!2 (not (= x1 y1)))))
      (a!5 (or (= x1 y1) (and a!2 (not (= x1 y1))))))
(let ((a!4 (or (not (= x1 y1)) (= (f y1) 0) (and (= (f x1) 0) a!3))))
  (and a!4 a!5)))))
)

(push)
;; This returns unsat, which verifies that the input
;; is an inconsistent pair of formulas
(assert (and part_a part_b))
(check-sat)
(pop)
(push)
;; This returns unsat, which verifies that the ouput
;; is implied by the A-part
(assert (not (implies part_a my_interpolant)))
(check-sat)
(pop)
(push)
;; This returns unsat, which verifies that the ouput
;; is inconsistent with the B-part
(assert (and my_interpolant part_b))
(check-sat)
(pop)
```

For this example these are the interpolants reported by Z3 and Mathsat respectively:

- Z3 interpolant: (and ($\geq$ (+ x1 (* (- 1) y1)) 0) (= (f x1) 0))
- Mathsat interpolant: (or (= (f y1) 0) ($\leq$ 1 (+ x1 (* (- 1) y1))))

The following SMT query verifies the strength relation between the interpolants produced:

```
(declare-fun x1 () Int)
(declare-fun x2 () Int)
(declare-fun x3 () Int)
(declare-fun y1 () Int)
(declare-fun y2 () Int)
(declare-fun y3 () Int)
(declare-fun a () Int)
(declare-fun b () Int)
```

```
(declare-fun f (Int) Int)
(declare-fun g (Int) Int)

(define-fun my_interpolant () Bool

(let ((a!1 (and (<= (+ (* (- 1) x1) y1) 0) (<= (+ x1 (* (- 1) y1)) (- 1)))))
(let ((a!2 (or (= x1 y1) a!1 (<= (+ (* (- 1) x1) y1) (- 1)))))
(let ((a!3 (or (not (= (f x1) 0)) (= 0 (f x1)) (and a!2 (not (= x1 y1)))))
      (a!5 (or (= x1 y1) (and a!2 (not (= x1 y1))))))
(let ((a!4 (or (not (= x1 y1)) (= (f y1) 0) (and (= (f x1) 0) a!3))))
  (and a!4 a!5)))))
)

(define-fun z3_interpolant () Bool
(and (>= (+ x1 (* (- 1) y1)) 0) (= (f x1) 0))
)

(define-fun mathsat_interpolant () Bool
(or (= (f y1) 0) (<= 1 (+ x1 (* (- 1) y1))))
)

(push)
;; The following returns sat, which means
;; that my_interpolant does not imply z3_interpolant
(assert (not (implies my_interpolant z3_interpolant)))
(check-sat)
(pop)
(push)
;; The following returns unsat, which means
;; that z3_interpolant implies my_interpolant
(assert (not (implies z3_interpolant my_interpolant)))
(check-sat)
(pop)
(push)
;; The following returns unsat, which means
;; that my_interpolant implies math_interpolant
(assert (not (implies my_interpolant mathsat_interpolant)))
(check-sat)
(pop)
(push)
;; The following returns sat, which means
;; that mathsat_interpolant does not imply my_interpolant
(assert (not (implies mathsat_interpolant my_interpolant )))
(check-sat)
(pop)
(push)
;; The following returns unsat, which means
;; that z3_interpolant implies math_interpolant
(assert (not (implies z3_interpolant mathsat_interpolant)))
(check-sat)
(pop)
(push)
;; The following returns sat, which means
;; that mathsat_interpolant does not imply z3_interpolant
(assert (not (implies mathsat_interpolant z3_interpolant )))
(check-sat)
(pop)
```

5.5 Conclusions

This chapter showed the implementation of the interpolation combination algorithm in [50] and the necessary changes for the EUF and UTVPI algorithms presented in previous chapters.

In addition, a new partially sound algorithm for the uniform interpolant generation for the combined theory of EUF + UTVPI was introduced in the sense that the algorithm is sound if the input formula satisfies particular requirements. The implementation of this algorithm will be considered in the future if the rules 8 and 9 can be replaced for propagation rules that avoid splitting.

If the input formula in the combined theory satisfies the weakening conditions mentioned in 5.1, the proposed algorithm produces uniform interpolants. On the other hand, the implemented algorithm requires a $B - part$ formula to compute a conventional interpolant. The former algorithm outputs a disjunction of conjunctions of equalities and inequalities of UTVPI terms, where the latter algorithm outputs a conjunction of Horn clauses with inequalities of UTVPI terms.

Chapter 6

Future Work

Regarding implementation work, there are several improvements that were not explored in the thesis work since many of them do not change the overall time complexity of the implementation, but these consume additional memory resources. These improvements are the following:

Major improvements:

- Improve hash function for terms: during testing the congruence closure algorithm, it was evident that dealing with numerous terms, collisions happened to the point that some terms were merged since the signature function indicated to do so, but this merges should not happen. Intrinsically, the current implementation relies on the hash function provided by Z3, which might not be optimized for many terms or it might be that their decision procedures encode internal information differently. Nonetheless, for a typical verification problem the implementation will not find any problems since these issues were noticed while dealing with instance problems involving graph terms of more than 1000000 nodes.

- Regarding the theory combination of EUF and UTPVI, it will be interesting to explore a more specific interpolation combination approach. The thesis culminated with a uniform interpolant algorithm for the combine theory, but the author agrees a better job can be done to avoid propagating disjunctions of the equalities by extending the signature, consequently the interpolation procedures, for both of the theories involved or propagate these disjunctions as using a compact representation.

- Currently the implementation for combined EUF and UTVPI theory does not incrementally check the consistency of the current formula in the main loop of the implementation 5.3. Changing the latter to an incremental approach will maintain lemmas so the computation of intermediate results will not be performed repetitively.

Minor improvements:

- The space needed to encode curry nodes *can be significantly reduced* up to an order of $\mathcal{O}(n)$. The reason for this current allocation schema is that it exists a double bonding effect while performing curryfication of all the terms in the arguments of function applications.

Appendix A: additional proofs

6.1 Theorems about Interpolants

6.1.1 Interpolants are closed under conjunction and disjunction

Theorem 6.1.1. *If I_1, I_2 are interpolants of $\langle A, B\rangle$, then $I_1 \wedge I_2, I_1 \vee I_2$ are also interpolants of $\langle A, B\rangle$.*

Proof. We notice that $vars(I_1 \wedge I_2) \subseteq vars(A) \cap vars(B)$ and $vars(I_1 \vee I_2) \subseteq vars(A) \cap vars(B)$, otherwise I_1, I_2 couldn't be interpolants.

Since I_1, I_2 are interpolants, we have that $A \vdash I_1$, $B \wedge I_1 \vdash \perp$ and $A \vdash I_2$, $B \wedge I_2 \vdash \perp$

Here are formal proofs for $A \vdash I_1 \wedge I_2$ and $B \wedge I_1 \wedge I_2 \vdash \perp$:

$$\dfrac{\begin{matrix} A \\ \vdots \\ I_1 \end{matrix} \quad \begin{matrix} A \\ \vdots \\ I_2 \end{matrix}}{I_1 \wedge I_2} \qquad \begin{matrix} \dfrac{B \wedge I_1 \wedge I_2}{B \wedge I_1} \\ \vdots \\ \perp \end{matrix}$$

Here are formal proofs for $A \vdash I_1 \vee I_2$ and $B \wedge (I_1 \vee I_2) \vdash \perp$:

$$
\dfrac{\begin{array}{c} A \\ \vdots \\ I_1 \end{array}}{I_1 \vee I_2}
\qquad
\dfrac{\begin{array}{c} B \wedge (I_1 \vee I_2) \\ \vdots\, * \\ (B \wedge I_1) \vee (B \wedge I_2) \end{array} \quad \begin{array}{c} \overline{B \wedge I_1} \\ \vdots \\ \bot \end{array} \quad \begin{array}{c} \overline{B \wedge I_2} \\ \vdots \\ \bot \end{array}}{\bot}
$$

where $*$ is any proof applying the distributivity property of the conjunction symbol over the disjunction symbol.

$\square$

6.1.2 Interpolants distribute conjunctions over disjunctions in the A-part

Theorem 6.1.2. *Let $\mathcal{F}_i$ be a set of formulas and I_i an interpolant for each $\langle A \wedge \mathcal{F}_i, B\rangle$ respectively. Then $\bigvee_i I_i$ is an interpolant for $\langle A \wedge (\bigvee_i \mathcal{F}_i), B\rangle$*

Proof. Let $A_i = A \wedge \mathcal{F}_i$ and $\hat{A} = A \wedge (\bigvee_i \mathcal{F}_i)$.

We see that $vars(I_i) \subseteq vars(A_i) \subseteq vars(\hat{A})$, hence $vars(\bigvee_i I_i) = \bigcup_i vars(I_i) \subseteq \bigcup_i vars(A_i) \subseteq vars(\hat{A})$. Similarly we can prove that $vars(\bigvee_i I_i) \subseteq vars(B)$. Thus, $vars(\bigvee_i I_i) \subseteq vars(A \wedge (\bigvee_i \mathcal{F}_i)) \cap vars(B)$.

To prove $\hat{A} \vdash \bigvee_i I_i$: We notice that $\hat{A} = \bigvee_i A_i$. From the latter and using the generalized version of the disjunction elimination rule in logic, i.e.

$$
\dfrac{\alpha_1 \vee \cdots \vee \alpha_n \quad \dfrac{\begin{array}{c} \overline{\alpha_1} \\ \vdots \\ I_1 \end{array}}{I_1 \vee \cdots \vee I_n} \quad \ldots \quad \dfrac{\begin{array}{c} \overline{\alpha_n} \\ \vdots \\ I_n \end{array}}{I_1 \vee \cdots \vee I_n}}{I_1 \vee \cdots \vee I_n}
$$

and distributing disjunctions over conjunctions in $\bigvee_i A_i$ the statement holds.

To prove $B \wedge \bigvee_i I_i \vdash \bot$: Since each $B \wedge I_i \vdash \bot$, by using the generalized version of the disjunction elimination rule from above, the result holds.

Therefore, $\bigvee_i I_i$ is an interpolant for $\langle A \wedge (\bigvee_i \mathcal{F}_i), B\rangle$.

$\square$

Appendix B: additional traces

6.2 Trace for example in theory combination chapter

```
Part a
EUF-component
(= (c_f c_x1) c_oct_1)
(= c_x1 a_a)
Octagon-component
(= 0 c_oct_1)
(<= c_y1 a_a)
Part b
EUF-component
(= c_y1 b_b)
(distinct (c_f c_y1) c_oct_2)
Octagon-component
(<= c_x1 b_b)
(= 0 c_oct_2)
Shared variables
(ast-vector
  c_x1
  a_a
  c_y1
  b_b
  c_oct_1
  c_oct_2)
(= 0 c_oct_1)
(<= c_y1 a_a)
(<= c_x1 b_b)
(= 0 c_oct_2)
(= (c_f c_x1) c_oct_1)
(= c_x1 a_a)
(= c_y1 b_b)
(not (= (c_f c_y1) c_oct_2))

Disjunction implied in EUF: (= c_x1 a_a)
Partial interpolant already computed
```

```
Disjunction implied in EUF: (= c_y1 b_b)
Partial interpolant already computed

Disjunction implied in OCT: (= c_x1 c_y1)
Clause Id: 2 (Fact) Predicate: (<= c_y1 a_a) Interpolant(old): false
Clause Id: 3 (Fact) Predicate: (<= c_x1 b_b) Interpolant(old): true
Clause Id: 5 (Fact) Predicate: (= c_x1 a_a) Interpolant(old): false
Clause Id: 6 (Fact) Predicate: (= c_y1 b_b) Interpolant(old): true
Clause Id: 7 (Fact) Predicate: (not (= c_x1 c_y1)) Interpolant(new): false
Clause Id: 8 (Conflict Clause) Predicate: (or (not (<= c_y1 a_a))
    (not (<= c_x1 b_b))
    (not (= c_x1 a_a))
    (not (= c_y1 b_b))
    (= c_x1 c_y1))
Inside partialInterpolantConflict
Case OCT
(ast-vector
  (<= c_y1 a_a)
  (= c_x1 a_a)
  (not (= c_x1 c_y1)))
(ast-vector
  (<= c_x1 b_b)
  (= c_y1 b_b))
DNF: (let ((a!1 (and (<= (- c_y1 a_a) 0)
                (<= (- c_x1 a_a) 0)
                (<= (+ (- c_x1) a_a) 0)
                (<= (- c_x1 c_y1) (- 1))))
      (a!2 (and (<= (- c_y1 a_a) 0)
                (<= (- c_x1 a_a) 0)
                (<= (+ (- c_x1) a_a) 0)
                (<= (+ (- c_x1) c_y1) (- 1)))))
  (or a!1 a!2))
Input for OctagonInterpolant (ast-vector
  (<= (- c_y1 a_a) 0)
  (<= (- c_x1 a_a) 0)
  (<= (+ (- c_x1) a_a) 0)
  (<= (- c_x1 c_y1) (- 1)))
Input for OctagonInterpolant (ast-vector
  (<= (- c_y1 a_a) 0)
  (<= (- c_x1 a_a) 0)
  (<= (+ (- c_x1) a_a) 0)
  (<= (+ (- c_x1) c_y1) (- 1)))
Theory-specific interpolant: (let ((a!1 (and (<= (+ (- c_x1) c_y1) 0) (<= (- c_x1 c_y1) (- 1))))
      (a!2 (and (<= (+ (- c_x1) c_y1) (- 1)))))
  (or a!1 a!2))
Interpolant for OCT: (let ((a!1 (and (<= (+ (- c_x1) c_y1) 0) (<= (- c_x1 c_y1) (- 1))))
      (a!2 (and (<= (+ (- c_x1) c_y1) (- 1)))))
  (and (or a!1 a!2 false false false) true true))
Interpolant((from conflict)new): (let ((a!1 (and (<= (+ (* (- 1) c_x1) c_y1) 0)
                (<= (+ c_x1 (* (- 1) c_y1)) (- 1)))))
  (or a!1 (<= (+ (* (- 1) c_x1) c_y1) (- 1))))
Clause Id: 9 (Derived(2,8)) Predicate: (or (not (<= c_x1 b_b)) (not (= c_x1 a_a)) (not (= c_y1 b_b)) (= c_x1 c_y1)) Pivot: (<= c_y1 a_a)
Pivot is A-local
Partial interpolant (let ((a!1 (and (<= (+ (* (- 1) c_x1) c_y1) 0)
                (<= (+ c_x1 (* (- 1) c_y1)) (- 1)))))
  (or false a!1 (<= (+ (* (- 1) c_x1) c_y1) (- 1))))
Interpolant((from derived)new): (let ((a!1 (and (<= (+ (* (- 1) c_x1) c_y1) 0)
```

```
               (<= (+ c_x1 (* (- 1) c_y1)) (- 1)))))
  (or a!1 (<= (+ (* (- 1) c_x1) c_y1) (- 1))))
Clause Id: 10 (Derived(9,3)) Predicate: (or (= c_x1 c_y1) (not (= c_x1 a_a)) (not (= c_y1 b_b))) Pivot: (<= c_x1 b_b)
Pivot is B-local
Partial interpolant (let ((a!1 (and (<= (+ (* (- 1) c_x1) c_y1) 0)
               (<= (+ c_x1 (* (- 1) c_y1)) (- 1)))))
(let ((a!2 (or a!1 (<= (+ (* (- 1) c_x1) c_y1) (- 1)))))
  (and a!2 true)))
Interpolant((from derived)new): (let ((a!1 (and (<= (+ (* (- 1) c_x1) c_y1) 0)
               (<= (+ c_x1 (* (- 1) c_y1)) (- 1)))))
  (or a!1 (<= (+ (* (- 1) c_x1) c_y1) (- 1))))
Clause Id: 11 (Derived(10,5)) Predicate: (or (= c_x1 c_y1) (not (= c_y1 b_b))) Pivot: (= c_x1 a_a)
Pivot is A-local
Partial interpolant (let ((a!1 (and (<= (+ (* (- 1) c_x1) c_y1) 0)
               (<= (+ c_x1 (* (- 1) c_y1)) (- 1)))))
  (or a!1 (<= (+ (* (- 1) c_x1) c_y1) (- 1)) false))
Interpolant((from derived)new): (let ((a!1 (and (<= (+ (* (- 1) c_x1) c_y1) 0)
               (<= (+ c_x1 (* (- 1) c_y1)) (- 1)))))
  (or a!1 (<= (+ (* (- 1) c_x1) c_y1) (- 1))))
Clause Id: 12 (Derived(11,6)) Predicate: (= c_x1 c_y1) Pivot: (= c_y1 b_b)
Pivot is B-local
Partial interpolant (let ((a!1 (and (<= (+ (* (- 1) c_x1) c_y1) 0)
               (<= (+ c_x1 (* (- 1) c_y1)) (- 1)))))
(let ((a!2 (or a!1 (<= (+ (* (- 1) c_x1) c_y1) (- 1)))))
  (and a!2 true)))
Interpolant((from derived)new): (let ((a!1 (and (<= (+ (* (- 1) c_x1) c_y1) 0)
               (<= (+ c_x1 (* (- 1) c_y1)) (- 1)))))
  (or a!1 (<= (+ (* (- 1) c_x1) c_y1) (- 1))))
Clause Id: 13 (Derived(12,7)) Predicate: false Pivot: (= c_x1 c_y1)
Pivot is AB-common
Partial interpolant: (let ((a!1 (and (<= (+ (* (- 1) c_x1) c_y1) 0)
               (<= (+ c_x1 (* (- 1) c_y1)) (- 1)))))
(let ((a!2 (or (= c_x1 c_y1) a!1 (<= (+ (* (- 1) c_x1) c_y1) (- 1)))))
  (and a!2 (or (not (= c_x1 c_y1)) false))))
Interpolant((from derived)new): (let ((a!1 (and (<= (+ (* (- 1) c_x1) c_y1) 0)
               (<= (+ c_x1 (* (- 1) c_y1)) (- 1)))))
(let ((a!2 (or (= c_x1 c_y1) a!1 (<= (+ (* (- 1) c_x1) c_y1) (- 1)))))
  (and a!2 (not (= c_x1 c_y1)))))
Final interpolant for conflict clause: (let ((a!1 (and (<= (+ (* (- 1) c_x1) c_y1) 0)
               (<= (+ c_x1 (* (- 1) c_y1)) (- 1)))))
(let ((a!2 (or (= c_x1 c_y1) a!1 (<= (+ (* (- 1) c_x1) c_y1) (- 1)))))
  (and a!2 (not (= c_x1 c_y1)))))

Disjunction implied in OCT: (= c_oct_1 c_oct_2)
Clause Id: 1 (Fact) Predicate: (= 0 c_oct_1) Interpolant(old): false
Clause Id: 4 (Fact) Predicate: (= 0 c_oct_2) Interpolant(old): true
Clause Id: 7 (Fact) Predicate: (not (= c_oct_1 c_oct_2)) Interpolant(new): false
Clause Id: 8 (Conflict Clause) Predicate: (or (not (= 0 c_oct_1)) (not (= 0 c_oct_2)) (= c_oct_1 c_oct_2))
Inside partialInterpolantConflict
Case OCT
-------It was sat!
(ast-vector
  (= 0 c_oct_1)
  (not (= c_oct_1 c_oct_2)))
(ast-vector
  (= 0 c_oct_2))
DNF: (let ((a!1 (and (<= c_oct_1 0)
               (<= (- c_oct_1) 0)
```

```
                (<= (+ (- c_oct_1) c_oct_2) (- 1)))))
  (or (and (<= c_oct_1 0) (<= (- c_oct_1) 0) (<= (- c_oct_1 c_oct_2) (- 1)))
      a!1))
Input for OctagonInterpolant (ast-vector
  (<= c_oct_1 0)
  (<= (- c_oct_1) 0)
  (<= (- c_oct_1 c_oct_2) (- 1)))
Input for OctagonInterpolant (ast-vector
  (<= c_oct_1 0)
  (<= (- c_oct_1) 0)
  (<= (+ (- c_oct_1) c_oct_2) (- 1)))
Theory-specific interpolant: (let ((a!1 (and (<= (- c_oct_1) 0)
                (<= c_oct_1 0)
                (<= (+ (- c_oct_2) c_oct_1) (- 1)))))
  (or a!1
      (and (<= (- c_oct_1) 0) (<= c_oct_1 0) (<= (- c_oct_2 c_oct_1) (- 1)))))
Interpolant for OCT: (let ((a!1 (and (<= (- c_oct_1) 0)
                (<= c_oct_1 0)
                (<= (+ (- c_oct_2) c_oct_1) (- 1)))))
(let ((a!2 (or a!1
               (and (<= (- c_oct_1) 0)
                    (<= c_oct_1 0)
                    (<= (- c_oct_2 c_oct_1) (- 1)))
               false
               false)))
  (and a!2 true)))
Interpolant((from conflict)new): (let ((a!1 (and (>= c_oct_1 0)
                (<= c_oct_1 0)
                (<= (+ (* (- 1) c_oct_2) c_oct_1) (- 1))))
      (a!2 (and (>= c_oct_1 0)
                (<= c_oct_1 0)
                (<= (+ c_oct_2 (* (- 1) c_oct_1)) (- 1)))))
  (or a!1 a!2))
Clause Id: 9 (Derived(1,8)) Predicate: (or (not (= 0 c_oct_2)) (= c_oct_1 c_oct_2)) Pivot: (= 0 c_oct_1)
Pivot is AB-common
Partial interpolant: (let ((a!1 (and (>= c_oct_1 0)
                (<= c_oct_1 0)
                (<= (+ (* (- 1) c_oct_2) c_oct_1) (- 1))))
      (a!2 (and (>= c_oct_1 0)
                (<= c_oct_1 0)
                (<= (+ c_oct_2 (* (- 1) c_oct_1)) (- 1)))))
  (and (or (= 0 c_oct_1) false) (or (not (= 0 c_oct_1)) a!1 a!2)))
Interpolant((from derived)new): (let ((a!1 (and (>= c_oct_1 0)
                (<= c_oct_1 0)
                (<= (+ (* (- 1) c_oct_2) c_oct_1) (- 1))))
      (a!2 (and (>= c_oct_1 0)
                (<= c_oct_1 0)
                (<= (+ c_oct_2 (* (- 1) c_oct_1)) (- 1)))))
  (and (= 0 c_oct_1) (or (not (= 0 c_oct_1)) a!1 a!2)))
Clause Id: 10 (Derived(9,4)) Predicate: (= c_oct_1 c_oct_2) Pivot: (= 0 c_oct_2)
Pivot is AB-common
Partial interpolant: (let ((a!1 (and (>= c_oct_1 0)
                (<= c_oct_1 0)
                (<= (+ (* (- 1) c_oct_2) c_oct_1) (- 1))))
      (a!2 (and (>= c_oct_1 0)
                (<= c_oct_1 0)
                (<= (+ c_oct_2 (* (- 1) c_oct_1)) (- 1))))
      (a!4 (or (not (not (= 0 c_oct_2))) true)))
```

```
(let ((a!3 (and (= 0 c_oct_1) (or (not (= 0 c_oct_1)) a!1 a!2))))
  (and (or (not (= 0 c_oct_2)) a!3) a!4)))
Interpolant((from derived)new): (let ((a!1 (and (>= c_oct_1 0)
                (<= c_oct_1 0)
                (<= (+ (* (- 1) c_oct_2) c_oct_1) (- 1))))
      (a!2 (and (>= c_oct_1 0)
                (<= c_oct_1 0)
                (<= (+ c_oct_2 (* (- 1) c_oct_1)) (- 1)))))
(let ((a!3 (and (= 0 c_oct_1) (or (not (= 0 c_oct_1)) a!1 a!2))))
  (or (not (= 0 c_oct_2)) a!3)))
Clause Id: 11 (Derived(10,7)) Predicate: false Pivot: (= c_oct_1 c_oct_2)
Pivot is AB-common
Partial interpolant: (let ((a!1 (and (>= c_oct_1 0)
                (<= c_oct_1 0)
                (<= (+ (* (- 1) c_oct_2) c_oct_1) (- 1))))
      (a!2 (and (>= c_oct_1 0)
                (<= c_oct_1 0)
                (<= (+ c_oct_2 (* (- 1) c_oct_1)) (- 1)))))
(let ((a!3 (and (= 0 c_oct_1) (or (not (= 0 c_oct_1)) a!1 a!2))))
  (and (or (= c_oct_1 c_oct_2) (not (= 0 c_oct_2)) a!3)
       (or (not (= c_oct_1 c_oct_2)) false))))
Interpolant((from derived)new): (let ((a!1 (and (>= c_oct_1 0)
                (<= c_oct_1 0)
                (<= (+ (* (- 1) c_oct_2) c_oct_1) (- 1))))
      (a!2 (and (>= c_oct_1 0)
                (<= c_oct_1 0)
                (<= (+ c_oct_2 (* (- 1) c_oct_1)) (- 1)))))
(let ((a!3 (and (= 0 c_oct_1) (or (not (= 0 c_oct_1)) a!1 a!2))))
  (and (or (= c_oct_1 c_oct_2) (not (= 0 c_oct_2)) a!3)
       (not (= c_oct_1 c_oct_2)))))
Final interpolant for conflict clause: (let ((a!1 (and (>= c_oct_1 0)
                (<= c_oct_1 0)
                (<= (+ (* (- 1) c_oct_2) c_oct_1) (- 1))))
      (a!2 (and (>= c_oct_1 0)
                (<= c_oct_1 0)
                (<= (+ c_oct_2 (* (- 1) c_oct_1)) (- 1)))))
(let ((a!3 (and (= 0 c_oct_1) (or (not (= 0 c_oct_1)) a!1 a!2))))
  (and (or (= c_oct_1 c_oct_2) (not (= 0 c_oct_2)) a!3)
       (not (= c_oct_1 c_oct_2)))))
EUF solver found a contradiction
(ast-vector
  (= (c_f c_x1) c_oct_1)
  (= c_x1 a_a)
  (= c_y1 b_b)
  (not (= (c_f c_y1) c_oct_2))
  (= c_x1 c_y1)
  (= c_oct_1 c_oct_2))
Clause Id: 1 (Fact) Predicate: (= (c_f c_x1) c_oct_1) Interpolant(old): false
Clause Id: 4 (Fact) Predicate: (not (= (c_f c_y1) c_oct_2)) Interpolant(old): true
Clause Id: 5 (Fact) Predicate: (= c_x1 c_y1) Interpolant(old): (let ((a!1 (and (<= (+ (* (- 1) c_x1) c_y1) 0)
                (<= (+ c_x1 (* (- 1) c_y1)) (- 1)))))
(let ((a!2 (or (= c_x1 c_y1) a!1 (<= (+ (* (- 1) c_x1) c_y1) (- 1)))))
  (and a!2 (not (= c_x1 c_y1)))))
Clause Id: 6 (Fact) Predicate: (= c_oct_1 c_oct_2) Interpolant(old): (let ((a!1 (and (>= c_oct_1 0)
                (<= c_oct_1 0)
                (<= (+ (* (- 1) c_oct_2) c_oct_1) (- 1))))
      (a!2 (and (>= c_oct_1 0)
                (<= c_oct_1 0)
```

```
                (<= (+ c_oct_2 (* (- 1) c_oct_1)) (- 1)))))
(let ((a!3 (and (= 0 c_oct_1) (or (not (= 0 c_oct_1)) a!1 a!2))))
  (and (or (= c_oct_1 c_oct_2) (not (= 0 c_oct_2)) a!3)
       (not (= c_oct_1 c_oct_2)))))
Clause Id: 7 (Conflict Clause) Predicate: (or (not (= (c_f c_x1) c_oct_1))
    (= (c_f c_y1) c_oct_2)
    (not (= c_x1 c_y1))
    (not (= c_oct_1 c_oct_2)))
Inside partialInterpolantConflict
Case EUF
Part a: (ast-vector
  (= (c_f c_x1) c_oct_1)
  (= c_x1 c_y1)
  (= c_oct_1 c_oct_2))
Part b: (ast-vector
  (not (= (c_f c_y1) c_oct_2)))
Theory-specific Interpolant for EUF: (and (= c_oct_1 (c_f c_x1)))
Interpolant for EUF: (let ((a!1 (and (<= (+ (* (- 1) c_x1) c_y1) 0)
                (<= (+ c_x1 (* (- 1) c_y1)) (- 1))))
      (a!3 (and (>= c_oct_1 0)
                (<= c_oct_1 0)
                (<= (+ (* (- 1) c_oct_2) c_oct_1) (- 1))))
      (a!4 (and (>= c_oct_1 0)
                (<= c_oct_1 0)
                (<= (+ c_oct_2 (* (- 1) c_oct_1)) (- 1)))))
(let ((a!2 (or (= c_x1 c_y1) a!1 (<= (+ (* (- 1) c_x1) c_y1) (- 1))))
      (a!5 (and (= 0 c_oct_1) (or (not (= 0 c_oct_1)) a!3 a!4))))
(let ((a!6 (and (or (= c_oct_1 c_oct_2) (not (= 0 c_oct_2)) a!5)
                (not (= c_oct_1 c_oct_2)))))
(let ((a!7 (or (and (= c_oct_1 (c_f c_x1)))
               false
               (and a!2 (not (= c_x1 c_y1)))
               a!6)))
  (and a!7 true)))))
Interpolant((from conflict)new): (let ((a!1 (and (>= c_oct_1 0)
                (<= c_oct_1 0)
                (<= (+ (* (- 1) c_oct_2) c_oct_1) (- 1))))
      (a!2 (and (>= c_oct_1 0)
                (<= c_oct_1 0)
                (<= (+ c_oct_2 (* (- 1) c_oct_1)) (- 1))))
      (a!5 (and (<= (+ (* (- 1) c_x1) c_y1) 0)
                (<= (+ c_x1 (* (- 1) c_y1)) (- 1)))))
(let ((a!3 (and (= 0 c_oct_1) (or (not (= 0 c_oct_1)) a!1 a!2)))
      (a!6 (or (= c_x1 c_y1) a!5 (<= (+ (* (- 1) c_x1) c_y1) (- 1)))))
(let ((a!4 (and (or (= c_oct_1 c_oct_2) (not (= 0 c_oct_2)) a!3)
                (not (= c_oct_1 c_oct_2)))))
  (or a!4 (= c_oct_1 (c_f c_x1)) (and a!6 (not (= c_x1 c_y1)))))))
Clause Id: 8 (Derived(1,7)) Predicate: (or (= (c_f c_y1) c_oct_2) (not (= c_x1 c_y1)) (not (= c_oct_1 c_oct_2))) Pivot: (= (c_f c_x1) c_oct_1)
Pivot is AB-common
Partial interpolant: (let ((a!1 (and (>= c_oct_1 0)
                (<= c_oct_1 0)
                (<= (+ (* (- 1) c_oct_2) c_oct_1) (- 1))))
      (a!2 (and (>= c_oct_1 0)
                (<= c_oct_1 0)
                (<= (+ c_oct_2 (* (- 1) c_oct_1)) (- 1))))
      (a!5 (and (<= (+ (* (- 1) c_x1) c_y1) 0)
                (<= (+ c_x1 (* (- 1) c_y1)) (- 1)))))
(let ((a!3 (and (= 0 c_oct_1) (or (not (= 0 c_oct_1)) a!1 a!2)))
```

```
      (a!6 (or (= c_x1 c_y1) a!5 (<= (+ (* (- 1) c_x1) c_y1) (- 1)))))
(let ((a!4 (and (or (= c_oct_1 c_oct_2) (not (= 0 c_oct_2)) a!3)
                (not (= c_oct_1 c_oct_2)))))
(let ((a!7 (or (not (= (c_f c_x1) c_oct_1))
               a!4
               (= c_oct_1 (c_f c_x1))
               (and a!6 (not (= c_x1 c_y1))))))
  (and (or (= (c_f c_x1) c_oct_1) false) a!7)))))
Interpolant((from derived)new): (let ((a!1 (and (>= c_oct_1 0)
                (<= c_oct_1 0)
                (<= (+ (* (- 1) c_oct_2) c_oct_1) (- 1))))
      (a!2 (and (>= c_oct_1 0)
                (<= c_oct_1 0)
                (<= (+ c_oct_2 (* (- 1) c_oct_1)) (- 1))))
      (a!5 (and (<= (+ (* (- 1) c_x1) c_y1) 0)
                (<= (+ c_x1 (* (- 1) c_y1)) (- 1)))))
(let ((a!3 (and (= 0 c_oct_1) (or (not (= 0 c_oct_1)) a!1 a!2)))
      (a!6 (or (= c_x1 c_y1) a!5 (<= (+ (* (- 1) c_x1) c_y1) (- 1)))))
(let ((a!4 (and (or (= c_oct_1 c_oct_2) (not (= 0 c_oct_2)) a!3)
                (not (= c_oct_1 c_oct_2)))))
(let ((a!7 (or a!4
               (not (= (c_f c_x1) c_oct_1))
               (= c_oct_1 (c_f c_x1))
               (and a!6 (not (= c_x1 c_y1))))))
  (and (= (c_f c_x1) c_oct_1) a!7)))))
Clause Id: 9 (Derived(8,4)) Predicate: (or (not (= c_oct_1 c_oct_2)) (not (= c_x1 c_y1))) Pivot: (= (c_f c_y1) c_oct_2)
Pivot is AB-common
Partial interpolant: (let ((a!1 (and (>= c_oct_1 0)
                (<= c_oct_1 0)
                (<= (+ (* (- 1) c_oct_2) c_oct_1) (- 1))))
      (a!2 (and (>= c_oct_1 0)
                (<= c_oct_1 0)
                (<= (+ c_oct_2 (* (- 1) c_oct_1)) (- 1))))
      (a!5 (and (<= (+ (* (- 1) c_x1) c_y1) 0)
                (<= (+ c_x1 (* (- 1) c_y1)) (- 1))))
      (a!9 (or (not (= (c_f c_y1) c_oct_2)) true)))
(let ((a!3 (and (= 0 c_oct_1) (or (not (= 0 c_oct_1)) a!1 a!2)))
      (a!6 (or (= c_x1 c_y1) a!5 (<= (+ (* (- 1) c_x1) c_y1) (- 1)))))
(let ((a!4 (and (or (= c_oct_1 c_oct_2) (not (= 0 c_oct_2)) a!3)
                (not (= c_oct_1 c_oct_2)))))
(let ((a!7 (or a!4
               (not (= (c_f c_x1) c_oct_1))
               (= c_oct_1 (c_f c_x1))
               (and a!6 (not (= c_x1 c_y1))))))
(let ((a!8 (or (= (c_f c_y1) c_oct_2) (and (= (c_f c_x1) c_oct_1) a!7))))
  (and a!8 a!9))))))
Interpolant((from derived)new): (let ((a!1 (and (>= c_oct_1 0)
                (<= c_oct_1 0)
                (<= (+ (* (- 1) c_oct_2) c_oct_1) (- 1))))
      (a!2 (and (>= c_oct_1 0)
                (<= c_oct_1 0)
                (<= (+ c_oct_2 (* (- 1) c_oct_1)) (- 1))))
      (a!5 (and (<= (+ (* (- 1) c_x1) c_y1) 0)
                (<= (+ c_x1 (* (- 1) c_y1)) (- 1)))))
(let ((a!3 (and (= 0 c_oct_1) (or (not (= 0 c_oct_1)) a!1 a!2)))
      (a!6 (or (= c_x1 c_y1) a!5 (<= (+ (* (- 1) c_x1) c_y1) (- 1)))))
(let ((a!4 (and (or (= c_oct_1 c_oct_2) (not (= 0 c_oct_2)) a!3)
                (not (= c_oct_1 c_oct_2)))))
```

```
(let ((a!7 (or a!4
               (not (= (c_f c_x1) c_oct_1))
               (= c_oct_1 (c_f c_x1))
               (and a!6 (not (= c_x1 c_y1))))))
  (or (= (c_f c_y1) c_oct_2) (and (= (c_f c_x1) c_oct_1) a!7))))))
Clause Id: 10 (Derived(9,5)) Predicate: (not (= c_oct_1 c_oct_2)) Pivot: (= c_x1 c_y1)
Pivot is AB-common
Partial interpolant: (let ((a!1 (and (>= c_oct_1 0)
                (<= c_oct_1 0)
                (<= (+ (* (- 1) c_oct_2) c_oct_1) (- 1))))
      (a!2 (and (>= c_oct_1 0)
                (<= c_oct_1 0)
                (<= (+ c_oct_2 (* (- 1) c_oct_1)) (- 1))))
      (a!5 (and (<= (+ (* (- 1) c_x1) c_y1) 0)
                (<= (+ c_x1 (* (- 1) c_y1)) (- 1)))))
(let ((a!3 (and (= 0 c_oct_1) (or (not (= 0 c_oct_1)) a!1 a!2)))
      (a!6 (or (= c_x1 c_y1) a!5 (<= (+ (* (- 1) c_x1) c_y1) (- 1)))))
(let ((a!4 (and (or (= c_oct_1 c_oct_2) (not (= 0 c_oct_2)) a!3)
                (not (= c_oct_1 c_oct_2))))
      (a!9 (or (not (not (= c_x1 c_y1))) (and a!6 (not (= c_x1 c_y1))))))
(let ((a!7 (or a!4
               (not (= (c_f c_x1) c_oct_1))
               (= c_oct_1 (c_f c_x1))
               (and a!6 (not (= c_x1 c_y1))))))
(let ((a!8 (or (not (= c_x1 c_y1))
               (= (c_f c_y1) c_oct_2)
               (and (= (c_f c_x1) c_oct_1) a!7))))
  (and a!8 a!9))))))
Interpolant((from derived)new): (let ((a!1 (and (>= c_oct_1 0)
                (<= c_oct_1 0)
                (<= (+ (* (- 1) c_oct_2) c_oct_1) (- 1))))
      (a!2 (and (>= c_oct_1 0)
                (<= c_oct_1 0)
                (<= (+ c_oct_2 (* (- 1) c_oct_1)) (- 1))))
      (a!5 (and (<= (+ (* (- 1) c_x1) c_y1) 0)
                (<= (+ c_x1 (* (- 1) c_y1)) (- 1)))))
(let ((a!3 (and (= 0 c_oct_1) (or (not (= 0 c_oct_1)) a!1 a!2)))
      (a!6 (or (= c_x1 c_y1) a!5 (<= (+ (* (- 1) c_x1) c_y1) (- 1)))))
(let ((a!4 (and (or (= c_oct_1 c_oct_2) (not (= 0 c_oct_2)) a!3)
                (not (= c_oct_1 c_oct_2))))
      (a!9 (or (= c_x1 c_y1) (and a!6 (not (= c_x1 c_y1))))))
(let ((a!7 (or a!4
               (not (= (c_f c_x1) c_oct_1))
               (= c_oct_1 (c_f c_x1))
               (and a!6 (not (= c_x1 c_y1))))))
(let ((a!8 (or (= (c_f c_y1) c_oct_2)
               (not (= c_x1 c_y1))
               (and (= (c_f c_x1) c_oct_1) a!7))))
  (and a!8 a!9))))))
Clause Id: 11 (Derived(10,6)) Predicate: false Pivot: (= c_oct_1 c_oct_2)
Pivot is AB-common
Partial interpolant: (let ((a!1 (and (>= c_oct_1 0)
                (<= c_oct_1 0)
                (<= (+ (* (- 1) c_oct_2) c_oct_1) (- 1))))
      (a!2 (and (>= c_oct_1 0)
                (<= c_oct_1 0)
                (<= (+ c_oct_2 (* (- 1) c_oct_1)) (- 1))))
      (a!5 (and (<= (+ (* (- 1) c_x1) c_y1) 0)
```

```
                (<= (+ c_x1 (* (- 1) c_y1)) (- 1)))))
(let ((a!3 (and (= 0 c_oct_1) (or (not (= 0 c_oct_1)) a!1 a!2)))
      (a!6 (or (= c_x1 c_y1) a!5 (<= (+ (* (- 1) c_x1) c_y1) (- 1)))))
(let ((a!4 (and (or (= c_oct_1 c_oct_2) (not (= 0 c_oct_2)) a!3)
                (not (= c_oct_1 c_oct_2))))
      (a!9 (or (= c_x1 c_y1) (and a!6 (not (= c_x1 c_y1))))))
(let ((a!7 (or a!4
               (not (= (c_f c_x1) c_oct_1))
               (= c_oct_1 (c_f c_x1))
               (and a!6 (not (= c_x1 c_y1)))))
      (a!10 (or (not (not (= c_oct_1 c_oct_2))) a!4)))
(let ((a!8 (or (= (c_f c_y1) c_oct_2)
               (not (= c_x1 c_y1))
               (and (= (c_f c_x1) c_oct_1) a!7))))
  (and (or (not (= c_oct_1 c_oct_2)) (and a!8 a!9)) a!10))))))
Interpolant((from derived)new): (let ((a!1 (and (>= c_oct_1 0)
                (<= c_oct_1 0)
                (<= (+ (* (- 1) c_oct_2) c_oct_1) (- 1))))
      (a!2 (and (>= c_oct_1 0)
                (<= c_oct_1 0)
                (<= (+ c_oct_2 (* (- 1) c_oct_1)) (- 1))))
      (a!5 (and (<= (+ (* (- 1) c_x1) c_y1) 0)
                (<= (+ c_x1 (* (- 1) c_y1)) (- 1)))))
(let ((a!3 (and (= 0 c_oct_1) (or (not (= 0 c_oct_1)) a!1 a!2)))
      (a!6 (or (= c_x1 c_y1) a!5 (<= (+ (* (- 1) c_x1) c_y1) (- 1)))))
(let ((a!4 (and (or (= c_oct_1 c_oct_2) (not (= 0 c_oct_2)) a!3)
                (not (= c_oct_1 c_oct_2))))
      (a!9 (or (= c_x1 c_y1) (and a!6 (not (= c_x1 c_y1))))))
(let ((a!7 (or a!4
               (not (= (c_f c_x1) c_oct_1))
               (= c_oct_1 (c_f c_x1))
               (and a!6 (not (= c_x1 c_y1))))))
(let ((a!8 (or (= (c_f c_y1) c_oct_2)
               (not (= c_x1 c_y1))
               (and (= (c_f c_x1) c_oct_1) a!7))))
  (and (or (not (= c_oct_1 c_oct_2)) (and a!8 a!9))
       (or (= c_oct_1 c_oct_2) a!4)))))))
Final interpolant for conflict clause: (let ((a!1 (and (>= c_oct_1 0)
                (<= c_oct_1 0)
                (<= (+ (* (- 1) c_oct_2) c_oct_1) (- 1))))
      (a!2 (and (>= c_oct_1 0)
                (<= c_oct_1 0)
                (<= (+ c_oct_2 (* (- 1) c_oct_1)) (- 1))))
      (a!5 (and (<= (+ (* (- 1) c_x1) c_y1) 0)
                (<= (+ c_x1 (* (- 1) c_y1)) (- 1)))))
(let ((a!3 (and (= 0 c_oct_1) (or (not (= 0 c_oct_1)) a!1 a!2)))
      (a!6 (or (= c_x1 c_y1) a!5 (<= (+ (* (- 1) c_x1) c_y1) (- 1)))))
(let ((a!4 (and (or (= c_oct_1 c_oct_2) (not (= 0 c_oct_2)) a!3)
                (not (= c_oct_1 c_oct_2))))
      (a!9 (or (= c_x1 c_y1) (and a!6 (not (= c_x1 c_y1))))))
(let ((a!7 (or a!4
               (not (= (c_f c_x1) c_oct_1))
               (= c_oct_1 (c_f c_x1))
               (and a!6 (not (= c_x1 c_y1))))))
(let ((a!8 (or (= (c_f c_y1) c_oct_2)
               (not (= c_x1 c_y1))
               (and (= (c_f c_x1) c_oct_1) a!7))))
  (and (or (not (= c_oct_1 c_oct_2)) (and a!8 a!9))
```

```
      (or (= c_oct_1 c_oct_2) a!4)))))))
-> Final Interpolant: (let ((a!1 (and (<= (+ (* (- 1) c_x1) c_y1) 0)
               (<= (+ c_x1 (* (- 1) c_y1)) (- 1)))))
(let ((a!2 (or (= c_x1 c_y1) a!1 (<= (+ (* (- 1) c_x1) c_y1) (- 1)))))
(let ((a!3 (or (not (= (c_f c_x1) 0))
              (= 0 (c_f c_x1))
              (and a!2 (not (= c_x1 c_y1)))))
      (a!5 (or (= c_x1 c_y1) (and a!2 (not (= c_x1 c_y1))))))
(let ((a!4 (or (not (= c_x1 c_y1)) (= (c_f c_y1) 0) (and (= (c_f c_x1) 0) a!3))))
  (and a!4 a!5)))))
Interpolant:
(let ((a!1 (and (<= (+ (* (- 1) x1) y1) 0) (<= (+ x1 (* (- 1) y1)) (- 1)))))
(let ((a!2 (or (= x1 y1) a!1 (<= (+ (* (- 1) x1) y1) (- 1)))))
(let ((a!3 (or (not (= (f x1) 0)) (= 0 (f x1)) (and a!2 (not (= x1 y1)))))
      (a!5 (or (= x1 y1) (and a!2 (not (= x1 y1))))))
(let ((a!4 (or (not (= x1 y1)) (= (f y1) 0) (and (= (f x1) 0) a!3))))
  (and a!4 a!5)))))
rm -rf tests/*.o tests/basic_test
```

Appendix C: additional implementation code of relevant data structures

6.3 Congruence Closure with Explanation operation header

```
class Hornsat;

class CongruenceClosureExplain : public CongruenceClosure {

  Hornsat * hsat;

  PendingElements pending_elements;
  PendingPointers equations_to_merge;
  PendingPointers pending_to_propagate;

  FactoryCurryNodes const & factory_curry_nodes;

  LookupTable lookup_table;
```

```
UseList     use_list;

void pushPending(PendingPointers &, const PendingElement &);
void merge();
void merge(EquationCurryNodes const &);
void propagate();
void propagateAux(CurryNode const &, CurryNode const &,
   EqClass, EqClass, PendingElement const &);

EqClass         highestNode(EqClass, UnionFind &);
EqClass         nearestCommonAncestor(EqClass, EqClass,
   UnionFind &);
PendingPointers explain(EqClass, EqClass);
void            explainAlongPath(EqClass, EqClass, UnionFind
    &, ExplainEquations &, PendingPointers &);
std::ostream &  giveExplanation(std::ostream &, EqClass,
   EqClass);

public:
CongruenceClosureExplain(Hornsat *, CongruenceClosureExplain
    const &, UnionFindExplain &);
CongruenceClosureExplain(Z3Subterms const &,
   UnionFindExplain &, FactoryCurryNodes &, IdsToMerge const
    &);
~CongruenceClosureExplain();

bool areSameClass(EqClass, EqClass);
bool areSameClass(z3::expr const &, z3::expr const &);

EqClass  constantId(EqClass);
```

```
  EqClass  find(EqClass);
  z3::expr z3Repr(z3::expr const &);

  void merge(EqClass, EqClass);
  void merge(z3::expr const &, z3::expr const &);

  PendingPointers explain(z3::expr const &, z3::expr const &);
  std::ostream &  giveExplanation(std::ostream &, z3::expr const &, z3::expr const &);

  z3::expr_vector z3Explain(z3::expr const &, z3::expr const &);
  std::ostream &  z3Explanation(std::ostream &, const z3::expr &, const z3::expr &);

  friend std::ostream & operator << (std::ostream &, const CongruenceClosureExplain &);
};
```

6.4 Hornsat (Gallier's data structure) header

```
class Hornsat {

  friend class EUFInterpolant;

  unsigned num_hcs, num_literals;
  // This structure is only used in our approach
  // for conditional-elimination
  std::unordered_map<unsigned, HornClause *> head_term_indexer;
```

```

  UnionFindExplain          ufe;
  CongruenceClosureExplain  equiv_classes;

  std::vector<Literal>    list_of_literals;
  ClassList               class_list;
  std::vector<unsigned>   num_args;
  std::vector<LiteralId>  pos_lit_list;
  // 'facts' is a queue of all the (temporary)
  // literals that have value true
  std::queue<LiteralId>   facts;
  std::queue<TermIdPair>  to_combine;

  bool consistent;

  void satisfiable();
  void closure();

 public:
  Hornsat(CongruenceClosureExplain &, HornClauses const &);
  ~Hornsat();

  void build(CongruenceClosureExplain &, HornClauses const &);
  bool isConsistent() const ;
  void unionupdate(LiteralId, LiteralId);
  friend std::ostream & operator << (std::ostream &, Hornsat
     const &);
};
```

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