

# Vuong V. Trinh

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<http://trinhvv.github.io>

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EXPERIENCE	<b>Doctoral Candidate</b> , Commissariat à l'énergie atomique et aux énergies alternatives 2014–2017 Supervised by <b>Mazen Alamir</b> and <b>Patrick Bonnay</b> on cryogenics, funded by <b>CRYOGREEN</b> <ul style="list-style-type: none"><li>• Develop constrained explicit nonlinear control schemes using robust regression and kernel methods</li><li>• Develop constrained hierarchical distributed control schemes based on numerical optimization (derivative free and bundle methods) leveraging fixed-point iterations</li></ul> <b>Research Intern</b> , Grenoble Images Parole Signal Automatique laboratoire Jan–Jun 2014 Supervised by <b>Ioan D. Landau</b> and <b>Luc Dugard</b> on active vibration control <ul style="list-style-type: none"><li>• Develop reduced-order feedforward and feedback active vibration control schemes leveraging system identification, Youla-Kucera parametrization and <math>\mathcal{H}_\infty</math> control synthesis with experimental validation</li><li>• Laboratory instructor and poster presentator for the adaptive control course at <b>EECI IGSC 2016</b></li></ul>
EDUCATION	<b>Ph.D. Control &amp; Optimization</b> , Communauté Université Grenoble Alpes (exp.) 2018 <b>M.S. Automation &amp; Control</b> , Université Joseph Fourier & Institut Polytechnique de Grenoble 2014 <b>B.S. Automation &amp; Control (ELITECH)</b> , Hanoi University of Science and Technology 2012
SERVICES	<b>Adjunct Researcher</b> , Dong A University Research Institute since 2017 <ul style="list-style-type: none"><li>• Collaborate with <b>Phuc K. Tran</b>, <b>Tuan A. Mai</b> and <b>Huong T. Truong</b> on anomaly detection</li><li>• Collaborate with <b>Hyeong Joon Ahn</b> and <b>Canh D. Nguyen</b> on motion control of linear motors</li></ul> <b>Organization Team</b> , Junior Scientist and Industry annual meeting Mar 2016
AWARDS	<b>Excellence master fellowship</b> , PERSYVAL-Lab 2013 <b>Vallet scholarship</b> , Rencontres du Vietnam 2008 <b>Double prize in physics (1st) and maths (cons)</b> , Vietnam Mathematics & Youth Magazine 2005
VALORISATION	<b>MOOC HarvardX CS50</b> , edX (verified cert.) Feb 2018 <b>Project-based Research Week</b> , SEMIE Oct 2016
COMPETENCES	<b>Languages</b> Vietnamese ( <i>native</i> ), English ( <i>limited working proficiency</i> , IELTS 6.5), French ( <i>basic</i> ) <b>Techniques</b> Matlab, C/C++, Python, CPLEX, git, heroku, $\LaTeX$ , Inkscape, Siemens S7, STM32
PUBLICATIONS	[1] M. Alamir, P. Bonnay, F. Bonne and V. V. Trinh. Fixed-point based hierarchical MPC control design for a cryogenic refrigerator. <i>Journal of Process Control</i> , 58:117–130, 2017. doi: <a href="https://doi.org/10.1016/j.jprocont.2017.09.006">10.1016/j.jprocont.2017.09.006</a> [2] V. V. Trinh, M. Alamir, P. Bonnay and F. Bonne. Explicit model predictive control via nonlinear piecewise approximations. In: <i>Proc. 10th IFAC Symposium on Nonlinear Control Systems</i> , Monterey, CA, USA, 2016. doi: <a href="https://doi.org/10.1016/j.ifacol.2016.10.173">10.1016/j.ifacol.2016.10.173</a> [3] M. Alamir, V. V. Trinh and P. Bonnay. On the stabilization of fixed-point iterations arising in hierarchical control design. In: <i>Proc. 20th IFAC World Congress</i> , Toulouse, France, 2017. doi: <a href="https://doi.org/10.1016/j.ifacol.2017.08.1363">10.1016/j.ifacol.2017.08.1363</a>