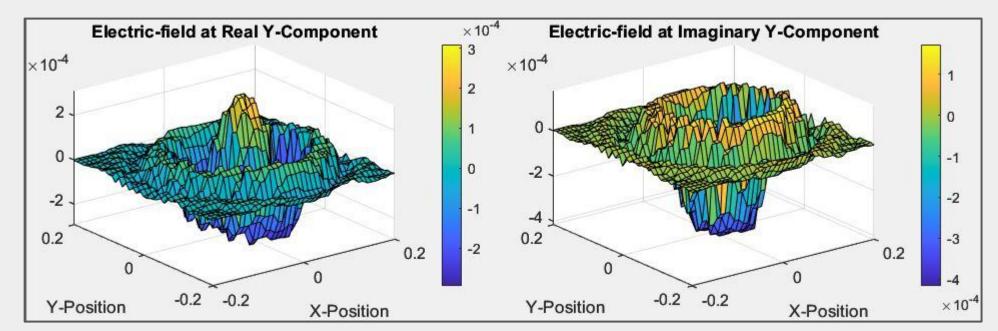
What is the ATR

An ATR consists of a room with metal sheeting to operate as a faraday cage with electromagnetic absorbent foam spikes to absorb any internal reflection.



Functional Evaluation

Improve reliability of mechanical systems and increase

Conduct static and dynamic tests on the structural

components and motor system for accuracy and

Determine range of motion and degree of freedom of

Conducting a functional analysis allowed the ATR team to

achieve the stated objective and develop documentation

Technologies used:

• C#/C++

• WIPL-D

• SQL

PNA

MATLAB

PowerShell

Raspberry Pi

Arduino Uno

ANSYS Workbench

Motors/Controllers

During this semester, significant changes made to the ATR include:

- Anechoic chamber
- New antenna mount
- Creation of phased array antenna
- PNA/Motor controller
- Relay installation and motor controller replacement
- Software

Objective:

Results:

including:

Near-to-far field transform

Scanning Evaluation:

polarization scans

Mechanical Evaluation:

• Support structures:

Improve documentation of ATR

quality of life purposes

• Traversal system for antennas:

No redundant data storage

Replaced motor controllers

95 -90 -85 -80 -75 -70 -65 -60 -55 -50 -45

No ability for remote scanning

Redesign antenna mounting system

Understand the mechanical function of ATR

accuracy of elevation, azimuth, vertical, and

Storage/Equipment Protection Evaluation:

Protection from static shock and power surges

of the ATR for future teams. Additionally, the team

identified areas of concern and addressed the areas

Implemented SQL server express for data searching

Azimuth scan of horn antenna (Left: before modifications of

ATR; Right: after modifications of ATR)

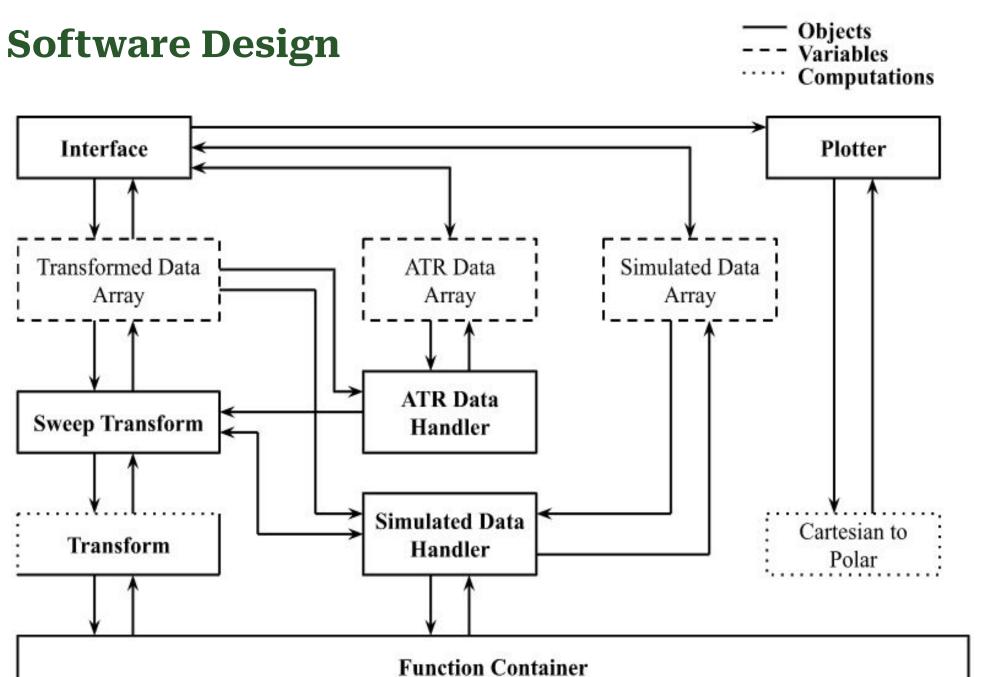
Quality of life

• Used google drive for 15GB of redundant data storage

Identify possible errors and inaccuracies

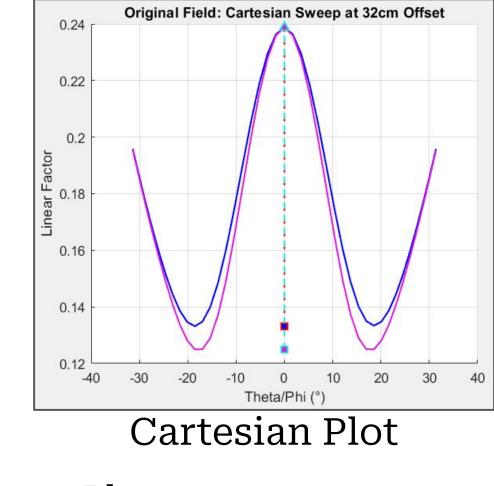
Objectives

- Convert a near-field radiation pattern into a far-field radiation pattern using a discrete computational algorithm
- Provide an easy-to-use software for future CSU ATR teams to transform, measure, and plot various simulated and measured electromagnetic fields



Software Capabilities

 The Software was designed to provide an easy-to-use multi-tool for ATR data interpretation and manipulation

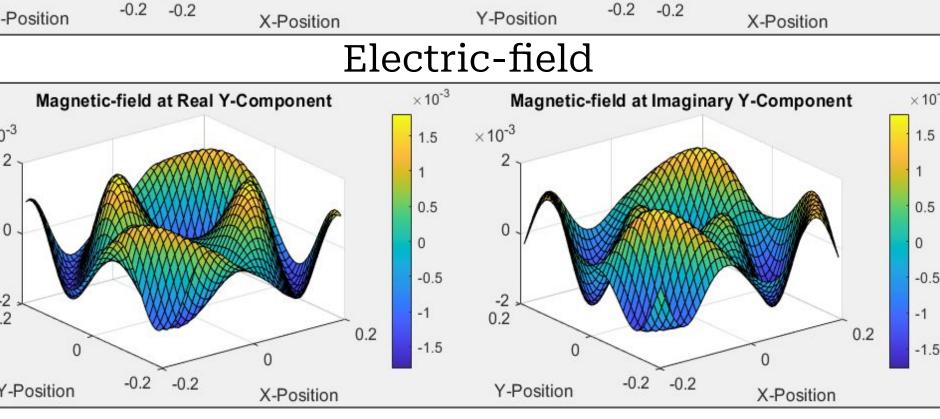


- <u>Visual</u>
 - 2D & 3D Heatmaps
 - Polar Radiation Pattern Plots
 - Cartesian Radiation Pattern Plots

Computational

- Theta and & Phi Axis Transformations
- Polynomial Regression Line Fitting
- Simulated and Measured Data Interpretation

Electric-field at Imaginary Y-Component Electric-field at Real Y-Component Y-Position Electric-field



Magnetic-field

Increase the number of redundancy systems for the

Increase the quality and power output of current motor

measured antenna and motor system

controller boards

Future

Project team members:

Parker Segelhorst (CE),

Adam Hulse (EE),

Josh Barber (CE)

Donovan Wells (ME),

Owen Dietrich (ME),

- Raspberry Pi for remote viewing Outreach and education
- Added a relay to the motor controller Increased stability of the vertical wall motor
- Installed an SQL server instance
- Created a redundant storage system
- Designed new motor controller case

Transform

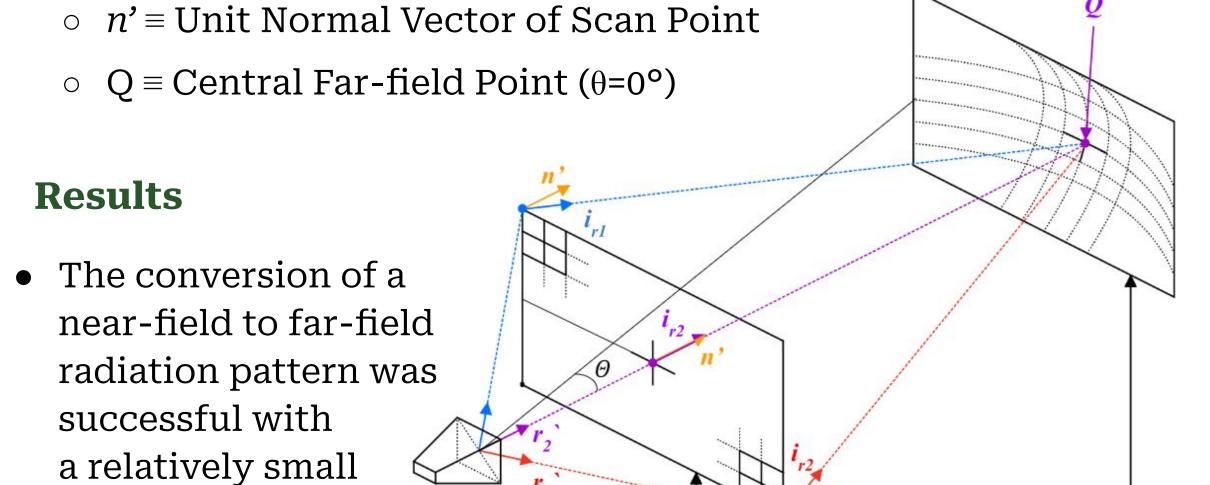
Near-field to Far-field Transformation

Colorado State University

Antenna Test Range

$$\boldsymbol{E}^{\text{sc}}(\boldsymbol{r}) = \frac{e^{-jk_0r}}{4\pi r} \oint_{S_1} \{\boldsymbol{n}' \times [\nabla' \times \boldsymbol{E}(\boldsymbol{r}')] + jk_0[\boldsymbol{n}' \times \boldsymbol{E}(\boldsymbol{r}')] \times \boldsymbol{i}_r\} e^{jk_0\boldsymbol{i}_r \cdot \boldsymbol{r}'} dS'$$

- Important Visual Components
 - o $r' \equiv \text{Unit Direction Vector to Near-field from Antenna}$
 - o $i_r = \text{Unit Direction Vector to Far-field from Scan Point}$
 - $\theta =$ Angle Between Normal Vector and Far-field Point



• Observations

margin of error

 Each transformed point needs to be multiplied by 5 because the rectangular mesh occupies only \% of the total surface

Near-field Mesh

• The field curl can be approximated, but the transform becomes less accurate the closer the far-field point gets

Future Work

- The transform can be implemented with spherical and cylindrical scans, not just cartesian
- More scans from the ATR can be transformed, including not just the Y-component, but the X and Z components

Error	10m Far-field	10Mm Far-field	-15° 15° 15° 30°.
Range Error	18.9%	~0%	-45° -60° -75° -75°
Max Error	1.17%	43.8%	-90°
Min Error	11.0%	~0%	Maximum Range: 40.49x▲ Maximum Value: -5.651x■ Minimum Value: -46.14x
			Original Field
Original vs. Transformed at 10m Offset Original Near-field Offset: 0m			Original vs. Transformed at 10Mm Offset Original Near-field Offset: 0m
-75° -90° -22.30 -19.23 -16.15 -13.08 -10.00 Original Sweep			-75° -60° -75° -75° -75° -75° -75° -75° -75° -75
10r	n Transfor	m	10Mm Transform

Contributors

Advisor: Dr. Branislav Notaros **EIR:** Bob Thelen VIP: Dr. Milan Ilic

Logarithmic Factor: Theta Sweep at 15.6cm Offse

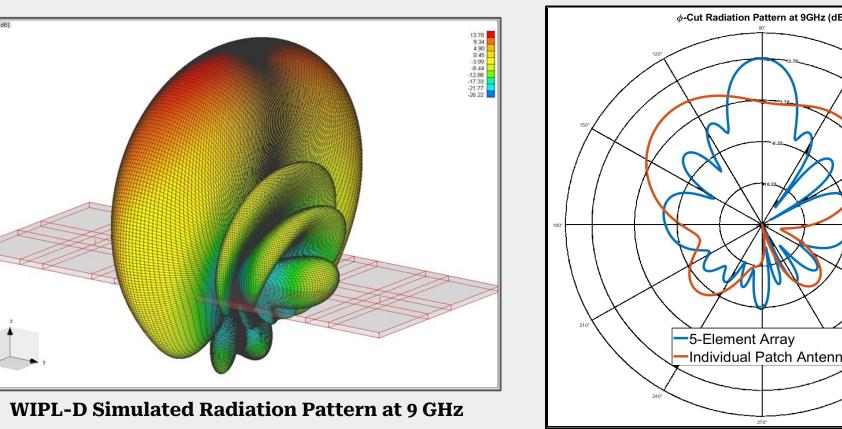
5-Element Patch Antenna Array

Background

- Radiation pattern is a key characteristic of an antenna Can be altered by power or phase fed to antenna
- Arraying antennas will create a more directed main beam
- Found in satellite communications, wireless networks, and radar systems

Objective

- Design antenna array consisting of 5 patch antennas
- Operate in phase within the X-band (8 GHz 12 GHz)
- Manufacture broadside array and test using the CSU ATR



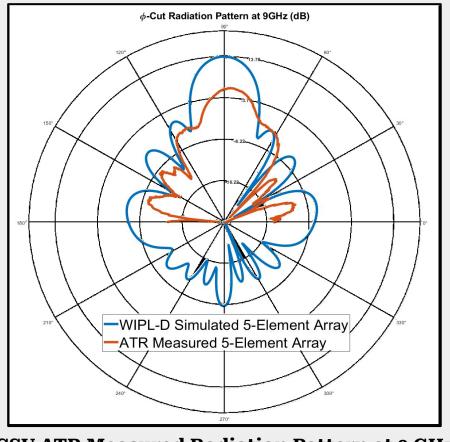
Procedure

- Design an individual patch to operate in X-Band Simulate in WIPL-D to visualize radiation pattern
- Add the individual patch into a 5-element array setup
- Manufacture PCB with Advanced Circuits
- Measure antenna array in ATR

Results

Far-field Mesh

Objective was met as the two plots appear very similar, indicating that the measured radiation pattern matches the theoretical radiation pattern at a frequency of 9 GHz which is the X-band.



CSU ATR Measured Radiation Pattern at 9 GHz

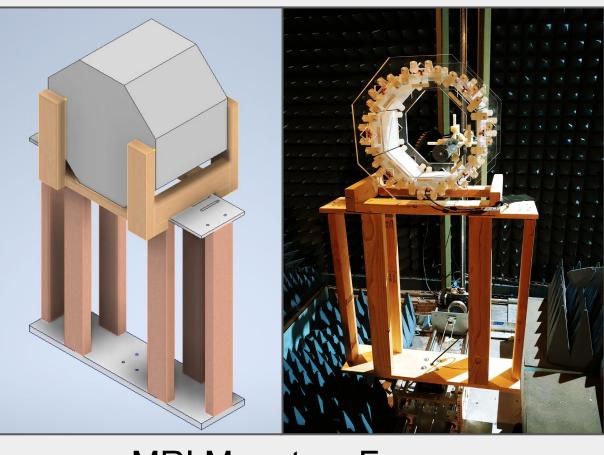
Antenna Mount

Objectives

- Antenna aperture wasn't at center of rotation, affected scan quality
- Integrate MRI coil mounting system for MRI team

Designing the New Mount

- Reduced costs by reusing parts (motor, bearings, hardware)
- New mounting system designed in three components, MRI specific, frame, antenna mount

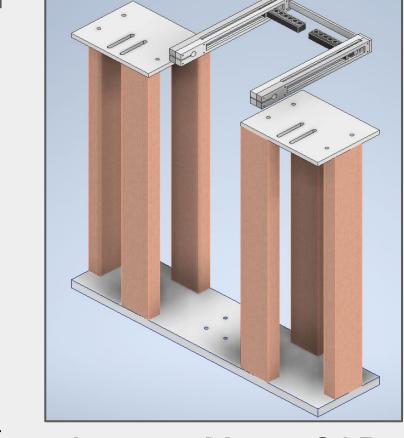


MRI Mount on Frame

- Antenna mount designed to be used with several antenna types and sizes
- Mount 3d printed, weight was optimized

Result

- Verified scan accuracy improved
- Data obtained for MRI team and patch array
- Mount too heavy for motor config., weaker than motor rating



MRI specific mount

performed, frame

can hold significant

and frame were

made of wood

Stress analysis

weight

Antenna Mount CAD Model