

# Gavial, Programming the web with multi-tier FRP: Semantics

This document contains the denotational semantics of ‘Gavial: Programming the web with multi-tier FRP’.

First, we define our semantic domain, secondly we list all core operations regarding clients, events and behaviors. Our project has three kinds of behaviors (plus events) on three tiers, in order to cut down on the size and make this document as legible as possible, our core operations section does not contain the written semantics for all tiers. Instead we limit ourselves to the client tier, the basic operations have no tier-specific abnormalities and the definitions for the session and application tier are nearly identical. For examples of written semantics on core operations on a different tier we have used application tier core operations in the paper.

Thirdly we introduce the conversion primitives. All operations that do not have an impact on time (i.e., no delays) but convert from one tier to another or from one FRP abstraction to another are given.

Next, we define the boundary operations which give precise semantics to server-to-client and client-to-server primitives.

Finally we finish up by proving some useful properties.

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## 1 Domain

$$Client \subset \mathbb{N} \quad \mathbf{finite}(Client) \quad \llbracket Client \rrbracket = Client$$

$$ClientStatus = \{Connected, Disconnected\}$$

$$ClientChange = ClientStatus \times Client$$

$$Time = \mathbb{R}_{\geq 0}$$

$$\exists Time_0, Time_\infty \in Time$$

$$\forall c \in Client. \exists Time_{0,c}, Time_{\infty,c} \in Time$$

$$ServerSlot = Client \uplus \top$$

$$Time^s = Time \times ServerSlot$$

$$\forall s_1, s_2 \in ServerSlot. s_1 < s_2 \Leftrightarrow (s_1 = \top \wedge s_2 \neq \top) \vee (s_1 \neq s_2 \neq \top \wedge s_1 < s_2)$$

$$\forall t_1, t_2 \in Time. \forall s_1, s_2 \in ServerSlot.$$

$$(t_1, s_1) < (t_2, s_2) \Leftrightarrow t_1 < t_2 \vee (t_1 = t_2 \wedge s_1 < s_2)$$

$$delay_{C \rightarrow S} : Time \times Client \rightarrow Time^s$$

$$\forall c \in Client. \forall t, t' \in Time. (t < t') \implies delay_{C \rightarrow S}(t, c) < delay_{C \rightarrow S}(t', c)$$

$$\forall c, c' \in Client. \forall t, t' \in Time. delay_{C \rightarrow S}(t, c) = (t', c') \implies t \leq t' \wedge c = c'$$

$$delay_{S \rightarrow C} : Time^s \times Client \rightarrow Time$$

$$\forall c \in Client. \forall s, s' \in Time^s. (s < s') \implies delay_{S \rightarrow C}(s, c) < delay_{S \rightarrow C}(s', c)$$

$$\forall c \in Client. \forall (t, slot) \in Time^s. delay_{S \rightarrow C}((t, slot), c) > t$$

$$Time_{0,c}^s = delay_{C \rightarrow S}(Time_{0,c}, c)$$

$$Time_{\infty,c}^s = delay_{C \rightarrow S}(Time_{\infty,c}, c)$$

$$\forall c \in Client. (Time_0 < Time_{0,c} < Time_{\infty,c} < Time_\infty)$$

$$\forall c \in Client. (Time_0^s < Time_{0,c}^s < Time_{\infty,c}^s < Time_\infty^s)$$

$$\llbracket Event_\tau^C \rrbracket = \left\{ e \in Client \rightarrow \mathcal{P}(Time \times \llbracket \tau \rrbracket) \mid \forall c \in Client. \begin{pmatrix} \mathbf{finite}(e(c)) \\ \wedge \forall (t, v), (t', v') \in e(c). t = t' \Rightarrow v = v' \\ \wedge \forall (t, -) \in e(c). Time_{0,c} < t < Time_{\infty,c} \end{pmatrix} \right\}$$

$$\llbracket Event_\tau^S \rrbracket = \left\{ e \in Client \rightarrow \mathcal{P}(Time^s \times \llbracket \tau \rrbracket) \mid \forall c \in Client. \begin{pmatrix} \mathbf{finite}(e(c)) \\ \wedge \forall (s, v), (s', v') \in e(c). s = s' \Rightarrow v = v' \\ \wedge \forall (s, -) \in e(c). Time_{0,c}^s < s < Time_{\infty,c}^s \end{pmatrix} \right\}$$

$$\llbracket Event_{\tau}^A \rrbracket = \left\{ e \in \mathcal{P}(Time^s \times \llbracket \tau \rrbracket) \mid \begin{array}{l} \mathbf{finite}(e) \\ \wedge \forall (s, v), (s', v') \in e. s = s' \Rightarrow v = v' \\ \wedge \forall (s, -) \in e. Time_0^s < s < Time_{\infty}^s \end{array} \right\}$$

$$\llbracket Behavior_{\tau}^C \rrbracket = \left\{ b \in Client \rightarrow Time \rightarrow \llbracket \tau \rrbracket \mid \begin{array}{l} \forall c \in Client. \mathbf{dom}(b(c)) = \\ \{ t \in Time \mid Time_{0,c} \leq t < Time_{\infty,c} \} \end{array} \right\}$$

$$\llbracket Behavior_{\tau}^S \rrbracket = \{ b \in Client \rightarrow Time^s \rightarrow \llbracket \tau \rrbracket \mid \forall c \in Client. \mathbf{dom}(b(c)) = \{ s \in Time^s \mid Time_{0,c}^s \leq s < Time_{\infty,c}^s \} \}$$

$$\llbracket Behavior_{\tau}^A \rrbracket = \left\{ b \in Time^s \rightarrow \llbracket \tau \rrbracket \mid \mathbf{dom}(b) = \left\{ s \in Time^s \mid Time_0^s \leq s < Time_{\infty}^s \right\} \right\}$$

$$\llbracket IncBehavior_{\tau,\delta}^C \rrbracket = \{ (e, v, f) \in \llbracket Event_{\delta}^C \rrbracket \times (Client \rightarrow \llbracket \tau \rrbracket) \times Client \rightarrow (\llbracket \tau \rrbracket \times \llbracket \delta \rrbracket \rightarrow \llbracket \tau \rrbracket) \}$$

$$\llbracket IncBehavior_{\tau,\delta}^S \rrbracket = \{ (e, v, f) \in \llbracket Event_{\delta}^S \rrbracket \times (Client \rightarrow \llbracket \tau \rrbracket) \times (Client \rightarrow (\llbracket \tau \rrbracket \times \llbracket \delta \rrbracket \rightarrow \llbracket \tau \rrbracket)) \}$$

$$\llbracket IncBehavior_{\tau,\delta}^A \rrbracket = \left\{ (e, v_0, f) \in \llbracket Event_{\delta}^A \rrbracket \times \llbracket \tau \rrbracket \times (\llbracket \tau \rrbracket \times \llbracket \delta \rrbracket \rightarrow \llbracket \tau \rrbracket) \right\}$$

$$\llbracket DiscBehavior_{\tau}^C \rrbracket = \left\{ (e, v, f) \in \llbracket IncBehavior_{\tau,\tau}^C \rrbracket \mid f = \lambda c. \lambda v. \lambda v'. v' \right\}$$

$$\llbracket DiscBehavior_{\tau}^S \rrbracket = \left\{ (e, v, f) \in \llbracket IncBehavior_{\tau,\tau}^S \rrbracket \mid f = \lambda c. \lambda v. \lambda v'. v' \right\}$$

$$\llbracket DiscBehavior_{\tau}^A \rrbracket = \left\{ (e, v_0, f) \in \llbracket IncBehavior_{\tau,\tau}^A \rrbracket \mid f = \lambda v. \lambda v'. v' \right\}$$

## 2 Core Operations

### 2.1 Client Information

**Definition 1.**

$$\begin{aligned} & client : Behavior_{Client}^S \\ \llbracket client \rrbracket &= \lambda c. \lambda s. \begin{cases} c & \text{if } Time_{0,c}^s \leq s < Time_{\infty,c}^s \\ \perp & \text{otherwise} \end{cases} \end{aligned}$$

**Theorem 1.** *client returns a valid result.*

*Proof.* There is one property that the resulting value must comply with in order to be valid.

1. The domain is correct by definition.

□

**Definition 2.**

$$\begin{aligned} & \text{clientChanges} : \text{Event}_{\text{ClientChange}}^A \\ \llbracket \text{clientChanges} \rrbracket &= \cup_{c \in \text{Client}} \{ (\text{Time}_{0,c}^s, (\text{Connected}, c)), (\text{Time}_{\infty,c}^s, (\text{Disconnected}, c)) \} \end{aligned}$$

**Theorem 2.**  $\llbracket \text{clientChanges} \rrbracket$  returns a valid result.

*Proof.* There are 3 properties that the resulting value must comply with in order to be valid.

1. The result is finite since there is a finite number of clients.
2. All values are unique in (server)time since both  $\text{Time}_{0,c}^s$  and  $\text{Time}_{\infty,c}^s$  are indexed by  $c$  while  $\text{Time}_{0,c}^s < \text{Time}_{\infty,c}^s$  and are thus client-specific.
3. All values are within the required bounds since  $\text{Time}_{0,c}^s$  and  $\text{Time}_{\infty,c}^s$  is always between  $\text{Time}_0^s$  and  $\text{Time}_{\infty}^s$

□

## 2.2 Events

**Definition 3.**

$$\begin{aligned} & \text{map} : \text{Event}_{\alpha}^C \rightarrow (\alpha \rightarrow \beta) \rightarrow \text{Event}_{\beta}^C \\ \llbracket \text{map} \rrbracket(e, f) &= \lambda c. \{ (t, f(v)) \mid (t, v) \in e(c) \} \end{aligned}$$

**Theorem 3.** If the arguments are valid,  $\llbracket \text{map} \rrbracket(e, f)$  returns a valid result.

*Proof.* There are 3 properties that the resulting value must comply with in order to be valid.

1. No additional values are added so the result remains finite.
2. No changes are made to the time component of the event values, all relevant properties of  $e$  hold.
3. See above.

□

**Definition 4.**

$$\begin{aligned} & \text{map} : \text{Event}_{\alpha}^S \rightarrow (\alpha \rightarrow \beta) \rightarrow \text{Event}_{\beta}^S \\ \llbracket \text{map} \rrbracket(e, f) &= \lambda c. \{ (s, f(v)) \mid (s, v) \in e(c) \} \end{aligned}$$

**Theorem 4.** If the arguments are valid,  $\llbracket \text{map} \rrbracket(e, f)$  returns a valid result.

*Proof.* Similar to  $\text{Event}^C$

□

**Definition 5.**

$$\begin{aligned} & \text{map} : \text{Event}_{\alpha}^A \rightarrow (\alpha \rightarrow \beta) \rightarrow \text{Event}_{\beta}^A \\ \llbracket \text{map} \rrbracket(e, f) &= \{ (s, f(v)) \mid (s, v) \in e \} \end{aligned}$$

**Theorem 5.** If the arguments are valid,  $\llbracket \text{map} \rrbracket(e, f)$  returns a valid result.

*Proof.* Similar to  $\text{Event}^C$

□

**Definition 6.**

$$\begin{aligned} & \text{filter} : \text{Event}_{\tau}^C \rightarrow (\tau \rightarrow \text{Bool}) \rightarrow \text{Event}_{\tau}^C \\ \llbracket \text{filter} \rrbracket(e, f) &= \lambda c. \{ (t, v) \mid (t, v) \in e(c) \wedge f(v) \} \end{aligned}$$

**Theorem 6.** If the arguments are valid,  $\llbracket \text{filter} \rrbracket(e, f)$  returns a valid result.

*Proof.* There are 3 properties that the resulting value must comply with in order to be valid.

1. Event values are only being removed and not added so it remains finite.
2. No changes are made to the time component of the event values, all relevant properties of  $e$  hold.

3. See above. □

**Definition 7.**

$$\begin{aligned} \text{filter} : \text{Event}_\tau^S &\rightarrow (\tau \rightarrow \text{Bool}) \rightarrow \text{Event}_\tau^S \\ \llbracket \text{filter} \rrbracket(e, f) &= \lambda c. \{(s, v) \mid (s, v) \in e(c) \wedge f(v)\} \end{aligned}$$

**Theorem 7.** *If the arguments are valid,  $\llbracket \text{filter} \rrbracket(e, f)$  returns a valid result.*

*Proof.* Similar to  $\text{Event}^C$  □

**Definition 8.**

$$\begin{aligned} \text{filter} : \text{Event}_\tau^A &\rightarrow (\tau \rightarrow \text{Bool}) \rightarrow \text{Event}_\tau^A \\ \llbracket \text{filter} \rrbracket(e, f) &= \{(s, v) \mid (s, v) \in e \wedge f(v)\} \end{aligned}$$

**Theorem 8.** *If the arguments are valid,  $\llbracket \text{filter} \rrbracket(e, f)$  returns a valid result.*

*Proof.* Similar to  $\text{Event}^C$  □

**Definition 9.**

$$\begin{aligned} \text{union} : \text{Event}_\tau^C &\rightarrow \text{Event}_\tau^C \rightarrow (\tau \rightarrow \tau \rightarrow \tau) \rightarrow \text{Event}_\tau^C \\ \llbracket \text{union} \rrbracket(e, e', f) &= \lambda c. \text{let } \begin{aligned} \text{left} &= \{(t, v) \mid (t, v) \in e(c) \wedge \forall (t', -) \in e'(c). t \neq t'\} \\ \text{both} &= \{(t, f(v, v')) \mid (t, v) \in e(c) \wedge (t', v') \in e'(c) \wedge t = t'\} \\ \text{right} &= \{(t, v) \mid (t, v) \in e'(c) \wedge \forall (t', -) \in e(c). t \neq t'\} \end{aligned} \\ &\quad \text{in } \text{left} \cup \text{both} \cup \text{right} \end{aligned}$$

**Theorem 9.** *If the arguments are valid,  $\llbracket \text{union} \rrbracket(e, e', f)$  returns a valid result.*

*Proof.* There are 3 properties that the resulting value must comply with in order to be valid.

1. The union of three finite sets remains finite.
2. The event values are unique in time by construction, *both* handles exactly this case, merging two values into one with  $f$  whenever the event values have the same time component.
3. The event values are within the correct bounds since both  $e$  and  $e'$  are too.

□

**Definition 10.**

$$\begin{aligned} \text{union} : \text{Event}_\tau^S &\rightarrow \text{Event}_\tau^S \rightarrow (\tau \rightarrow \tau \rightarrow \tau) \rightarrow \text{Event}_\tau^S \\ \llbracket \text{union} \rrbracket(e, e', f) &= \lambda c. \text{let } \begin{aligned} \text{left} &= \{(s, v) \mid (s, v) \in e(c) \wedge \forall (s', -) \in e'(c). s \neq s'\} \\ \text{both} &= \{(s, f(v, v')) \mid (s, v) \in e(c) \wedge (s', v') \in e'(c) \wedge s = s'\} \\ \text{right} &= \{(s, v) \mid (s, v) \in e'(c) \wedge \forall (s', -) \in e(c). s \neq s'\} \end{aligned} \\ &\quad \text{in } \text{left} \cup \text{both} \cup \text{right} \end{aligned}$$

**Theorem 10.** *If the arguments are valid,  $\llbracket \text{union} \rrbracket(e, e', f)$  returns a valid result.*

*Proof.* Similar to  $\text{Event}^C$  □

**Definition 11.**

$$\begin{aligned} \text{union} : \text{Event}_\tau^A &\rightarrow \text{Event}_\tau^A \rightarrow (\tau \rightarrow \tau \rightarrow \tau) \rightarrow \text{Event}_\tau^A \\ \llbracket \text{union} \rrbracket(e, e', f) &= \\ \text{let } \begin{aligned} \text{left} &= \{(s, v) \mid (s, v) \in e \wedge \forall (s', -) \in e'. s \neq s'\} \\ \text{both} &= \{(s, f(v, v')) \mid (s, v) \in e \wedge (s', v') \in e' \wedge s = s'\} \\ \text{right} &= \{(s, v) \mid (s, v) \in e' \wedge \forall (s', -) \in e. s \neq s'\} \end{aligned} \\ &\quad \text{in } \text{left} \cup \text{both} \cup \text{right} \end{aligned}$$

**Theorem 11.** *If the arguments are valid,  $\llbracket \text{union} \rrbracket(e, e', f)$  returns a valid result.*

*Proof.* Similar to  $\text{Event}^C$  □

## 2.3 Behavior

**Definition 12.**

$$\begin{aligned} constant &: \alpha \rightarrow Behavior_{\alpha}^C \\ \llbracket constant \rrbracket(a) &= \lambda c. \lambda t. \begin{cases} a & \text{if } Time_{0,c} \leq t < Time_{\infty,c} \\ \perp & \text{otherwise} \end{cases} \end{aligned}$$

**Theorem 12.** *If the arguments are valid,  $\llbracket constant \rrbracket(a)$  returns a valid result.*

*Proof.* There is one property that the resulting value must comply with in order to be valid.

1. The domain is correct by definition. □

**Definition 13.**

$$\begin{aligned} constant &: \alpha \rightarrow Behavior_{\alpha}^S \\ \llbracket constant \rrbracket(a) &= \lambda c. \lambda s. \begin{cases} a & \text{if } Time_{0,c}^s \leq s < Time_{\infty,c}^s \\ \perp & \text{otherwise} \end{cases} \end{aligned}$$

**Theorem 13.** *If the arguments are valid,  $\llbracket constant \rrbracket(a)$  returns a valid result.*

*Proof.* Similar to  $Event^C$  □

**Definition 14.**

$$\begin{aligned} constant &: \alpha \rightarrow Behavior_{\alpha}^A \\ \llbracket constant \rrbracket(a) &= \lambda s. \begin{cases} a & \text{if } Time_0^s \leq s < Time_{\infty}^s \\ \perp & \text{otherwise} \end{cases} \end{aligned}$$

**Theorem 14.** *If the arguments are valid,  $\llbracket constant \rrbracket(a)$  returns a valid result.*

*Proof.* Similar to  $Event^C$  □

**Definition 15.**

$$\begin{aligned} map2 &: Behavior_{\alpha}^C \rightarrow Behavior_{\beta}^C \rightarrow (\alpha \rightarrow \beta \rightarrow \gamma) \rightarrow Behavior_{\gamma}^C \\ \llbracket map2 \rrbracket(b, b', f) &= \lambda c. \lambda t. \begin{cases} f(b(c)(t), b'(c)(t)) & \text{if } Time_{0,c} \leq t < Time_{\infty,c} \\ \perp & \text{otherwise} \end{cases} \end{aligned}$$

**Theorem 15.** *If the arguments are valid,  $\llbracket map2 \rrbracket(b, b', f)$  returns a valid result.*

*Proof.* There is one property that the resulting value must comply with in order to be valid.

1. The domain is valid by construction. □

**Definition 16.**

$$\begin{aligned} map2 &: Behavior_{\alpha}^S \rightarrow Behavior_{\beta}^S \rightarrow (\alpha \rightarrow \beta \rightarrow \gamma) \rightarrow Behavior_{\gamma}^S \\ \llbracket map2 \rrbracket(b, b', f) &= \lambda c. \lambda s. \begin{cases} f(b(c)(s), b'(c)(s)) & \text{if } Time_{0,c}^s \leq s < Time_{\infty,c}^s \\ \perp & \text{otherwise} \end{cases} \end{aligned}$$

**Theorem 16.** *If the arguments are valid,  $\llbracket map2 \rrbracket(b, b', f)$  returns a valid result.*

*Proof.* Similar to  $Event^C$  □

**Definition 17.**

$$\begin{aligned} map2 &: Behavior_{\alpha}^A \rightarrow Behavior_{\beta}^A \rightarrow (\alpha \rightarrow \beta \rightarrow \gamma) \rightarrow Behavior_{\gamma}^A \\ \llbracket map2 \rrbracket(b, b', f) &= \lambda s. \begin{cases} f(b(s), b'(s)) & \text{if } Time_0^s \leq s < Time_{\infty}^s \\ \perp & \text{otherwise} \end{cases} \end{aligned}$$

**Theorem 17.** *If the arguments are valid,  $\llbracket map2 \rrbracket(b, b', f)$  returns a valid result.*

*Proof.* Similar to  $Event^C$  □

## 2.4 Incremental Behavior

**Definition 18.**

$$\begin{aligned} constant &: \alpha \rightarrow IncBehavior_{\alpha, \delta}^C \\ \llbracket constant \rrbracket(a) &= (\lambda c. \emptyset, \lambda c. a, \lambda c. \lambda v. \lambda d. v) \end{aligned}$$

**Theorem 18.** *If the arguments are valid,  $\llbracket constant \rrbracket(a)$  returns a valid result.*

*Proof.* There is one property that the resulting value must comply with in order to be valid.

1. The 3 constructed elements of the tuple are of the correct type.

□

**Definition 19.**

$$\begin{aligned} constant &: \alpha \rightarrow IncBehavior_{\alpha, \delta}^S \\ \llbracket constant \rrbracket(a) &= (\lambda c. \emptyset, \lambda c. a, \lambda c. \lambda v. \lambda d. v) \end{aligned}$$

**Theorem 19.** *If the arguments are valid,  $\llbracket constant \rrbracket(a)$  returns a valid result.*

*Proof.* Similar to  $Event^C$

□

**Definition 20.**

$$\begin{aligned} constant &: \alpha \rightarrow IncBehavior_{\alpha, \delta}^A \\ \llbracket constant \rrbracket(a) &= (\emptyset, a, \lambda v. \lambda d. v) \end{aligned}$$

**Theorem 20.** *If the arguments are valid,  $\llbracket constant \rrbracket(a)$  returns a valid result.*

*Proof.* Similar to  $Event^C$

□

**Definition 21.**

$$\begin{aligned} \llbracket Inc_{\delta, \delta'} \rrbracket &= \{Left(x) \mid x \in \llbracket \delta \rrbracket\} \cup \{Right(y) \mid y \in \llbracket \delta' \rrbracket\} \cup \{All(x, y) \mid x \in \llbracket \delta \rrbracket, y \in \llbracket \delta' \rrbracket\} \\ incMap2 &: IncBehavior_{\tau, \delta}^C \rightarrow IncBehavior_{\tau', \delta'}^C \rightarrow (\tau \rightarrow \tau' \rightarrow \tau'') \\ &\rightarrow (\tau \rightarrow \tau' \rightarrow Inc_{\delta, \delta'} \rightarrow \delta'') \rightarrow (\tau'' \rightarrow \delta'' \rightarrow \tau'') \rightarrow IncBehavior_{\tau'', \delta''}^C \end{aligned}$$

$$\begin{aligned} \llbracket incMap2 \rrbracket((e, v, f), (e', v', f'), fi, fd, ff) &= \\ \text{let } b &= \llbracket convert \rrbracket((e, v, f)) \\ b' &= \llbracket convert \rrbracket((e', v', f')) \\ bb &= \llbracket map2 \rrbracket(b, b', \lambda x. \lambda y. (x, y)) \\ de &= \llbracket map \rrbracket(e, \lambda x. Left(x)) \\ de' &= \llbracket map \rrbracket(e', \lambda x. Right(x)) \\ de'' &= \llbracket union \rrbracket(de, de', \lambda (Left(x)). \lambda (Right(y)). All(x, y)) \\ e'' &= \llbracket snapshot \rrbracket(bb, \llbracket map \rrbracket(de'', \lambda dev. \lambda (bv, bv'). fd(bv)(bv')(dev))) \\ \text{in } &\llbracket filter \rrbracket(e'', \lambda x. x \neq \perp), \lambda c. fi(v(c), v'(c)), ff) \end{aligned}$$

**Theorem 21.** *If the arguments are valid,  $\llbracket incMap2 \rrbracket((e, v, f), (e', v', f'), fi, fd, ff)$  returns a valid result.*

*Proof.* There is one property that the resulting value must comply with in order to be valid.

1. The 3 constructed elements of the tuple are of the correct type.

□

**Definition 22.**

$$\begin{aligned} incMap2 : IncBehavior_{\tau, \delta}^S &\rightarrow IncBehavior_{\tau', \delta'}^S \rightarrow (\tau \rightarrow \tau' \rightarrow \tau'') \\ &\rightarrow (\tau \rightarrow \tau' \rightarrow Inc_{\delta, \delta'} \rightarrow \delta'') \rightarrow (\tau'' \rightarrow \delta'' \rightarrow \tau'') \rightarrow IncBehavior_{\tau'', \delta''}^S \end{aligned}$$

$$\begin{aligned} \llbracket incMap2 \rrbracket((e, v, f), (e', v', f'), fi, fd, ff) = \\ \text{let } b = \llbracket convert \rrbracket((e, v, f)) \\ b' = \llbracket convert \rrbracket((e', v', f')) \\ bb = \llbracket map2 \rrbracket(b, b', \lambda x. \lambda y. (x, y)) \\ de = \llbracket map \rrbracket(e, \lambda x. Left(x)) \\ de' = \llbracket map \rrbracket(e', \lambda x. Right(x)) \\ de'' = \llbracket union \rrbracket(de, de', \lambda(Left(x)). \lambda(Right(y)). All(x, y)) \\ e'' = \llbracket snapshot \rrbracket(bb, \llbracket map \rrbracket(de'', \lambda dev. \lambda(bv, bv'). fd(bv)(bv')(dev))) \\ \text{in}(\llbracket filter \rrbracket(e'', \lambda x. x \neq \perp), \lambda c. fi(v(c), v'(c)), ff) \end{aligned}$$

**Theorem 22.** *If the arguments are valid,  $\llbracket incMap2 \rrbracket((e, v, f), (e', v', f'), fi, fd, ff)$  returns a valid result.*

*Proof.* Similar to  $Event^C$  □

**Definition 23.**

$$\begin{aligned} incMap2 : IncBehavior_{\tau, \delta}^A &\rightarrow IncBehavior_{\tau', \delta'}^A \rightarrow (\tau \rightarrow \tau' \rightarrow \tau'') \\ &\rightarrow (\tau \rightarrow \tau' \rightarrow Inc_{\delta, \delta'} \rightarrow \delta'') \rightarrow (\tau'' \rightarrow \delta'' \rightarrow \tau'') \rightarrow IncBehavior_{\tau'', \delta''}^A \end{aligned}$$

$$\begin{aligned} \llbracket incMap2 \rrbracket((e, v, f), (e', v', f'), fi, fd, ff) = \\ \text{let } b = \llbracket convert \rrbracket((e, v, f)) \\ b' = \llbracket convert \rrbracket((e', v', f')) \\ bb = \llbracket map2 \rrbracket(b, b', \lambda x. \lambda y. (x, y)) \\ de = \llbracket map \rrbracket(e, \lambda x. Left(x)) \\ de' = \llbracket map \rrbracket(e', \lambda x. Right(x)) \\ de'' = \llbracket union \rrbracket(de, de', \lambda(Left(x)). \lambda(Right(y)). All(x, y)) \\ e'' = \llbracket snapshot \rrbracket(bb, \llbracket map \rrbracket(de'', \lambda dev. \lambda(bv, bv'). fd(bv)(bv')(dev))) \\ \text{in}(\llbracket filter \rrbracket(e'', \lambda x. x \neq \perp), fi(v, v'), ff) \end{aligned}$$

**Theorem 23.** *If the arguments are valid,  $\llbracket incMap2 \rrbracket((e, v, f), (e', v', f'), fi, fd, ff)$  returns a valid result.*

*Proof.* Similar to  $Event^C$  □

## 2.5 Discrete Behavior

$$\begin{aligned} discMap2 : DiscBehavior_{\alpha}^C &\rightarrow DiscBehavior_{\beta}^C \rightarrow (\alpha \rightarrow \beta \rightarrow \tau) \rightarrow DiscBehavior_{\tau}^C \\ \llbracket discMap2 \rrbracket(b, b', f) = \llbracket incMap2 \rrbracket \left( b, b', f, \lambda x. \lambda y. \lambda d. \begin{cases} f(x', y) & \text{if } d = Left(x') \\ f(x, y') & \text{if } d = Right(y') \\ f(x', y') & \text{if } d = All(x', y') \end{cases}, \lambda c. \lambda v. \lambda v'. v' \right) \\ \\ discMap2 : DiscBehavior_{\alpha}^S &\rightarrow DiscBehavior_{\beta}^S \rightarrow (\alpha \rightarrow \beta \rightarrow \tau) \rightarrow DiscBehavior_{\tau}^S \\ \llbracket discMap2 \rrbracket(b, b', f) = \llbracket incMap2 \rrbracket \left( b, b', f, \lambda x. \lambda y. \lambda d. \begin{cases} f(x', y) & \text{if } d = Left(x') \\ f(x, y') & \text{if } d = Right(y') \\ f(x', y') & \text{if } d = All(x', y') \end{cases}, \lambda c. \lambda v. \lambda v'. v' \right) \end{aligned}$$



$$discMap2 : DiscBehavior_{\alpha}^A \rightarrow DiscBehavior_{\beta}^A \rightarrow (\alpha \rightarrow \beta \rightarrow \tau) \rightarrow DiscBehavior_{\tau}^A$$

$$\llbracket discMap2 \rrbracket(b, b', f) = \llbracket incMap2 \rrbracket \left( b, b', f, \lambda x. \lambda y. \lambda d. \begin{cases} f(x', y) & \text{if } d = Left(x') \\ f(x, y') & \text{if } d = Right(y') \\ f(x', y') & \text{if } d = All(x', y') \end{cases}, \lambda v. \lambda v'. v' \right)$$

We can define discrete map two in terms of the incremental version since we defined earlier that semantically discrete behaviors are a subset of incremental behaviors.

### 3 Conversions

#### 3.1 Events

**Definition 24.**

$$toApplication : Event_{\tau}^S \rightarrow Event_{Client \rightarrow \tau}^A$$

$$\llbracket toApplication \rrbracket(e) = \mathbf{let} \ allOccurrences = \cup_{c \in Client} \{(s, (c, v)) \mid (s, v) \in e(c)\}$$

$$\mathbf{in} \cup_{s \in Time^s. Time_0^s < s < Time_{\infty}^s} \left\{ (s, set) \mid set' = \{(c, v) \mid (s', (c, v)) \in allOccurrences \wedge s = s'\} \wedge set' \neq \emptyset \wedge set = \mathbf{fromSet}(set') \right\}$$

$$\mathbf{fromSet} : \mathcal{P}(Client \times \tau) \rightarrow Client \rightarrow \tau$$

$$\mathbf{fromSet}(s) = \lambda c. \begin{cases} v & \text{if } (v, c) \in s \\ \perp & \text{otherwise} \end{cases}$$

**Theorem 24.** *If the arguments are valid,  $\llbracket toApplication \rrbracket(e)$  returns a valid result.*

*Proof.* There are 3 properties that the resulting value must comply with in order to be valid.

1. There is a finite number of clients which implies that a union of all values for all connected clients is finite (a union of finite amount of finite sets).
2. We group all occurrences per time slot in a partial function using **fromSet**, as such the resulting set is unique in time since the original occurrences were unique in time per client.
3.  $Event^S$ s have time bounds that are always within the bounds of  $Event^A$ s and we only take sets that contain values from  $Event^S$ s.

□

**Definition 25.**

$$toSession : Event_{\tau}^A \rightarrow Event_{\tau}^S$$

$$\llbracket toSession \rrbracket(e) = \lambda c. \{(s, v) \mid (s, v) \in e \wedge Time_{0,c}^s < s < Time_{\infty,c}^s\}$$

**Theorem 25.** *If the arguments are valid,  $\llbracket toSession \rrbracket(e)$  returns a valid result.*

*Proof.* There are 3 properties that the resulting value must comply with in order to be valid.

1. The set of all events for a client is at most the same size and distribution as the set of all events for all clients. The latter is already required to be finite by  $Event^A$ s.
2. All event values are unique in time for  $Event^A$ s and per event value only one value is calculated per client so this is obvious.
3. We only select occurrences that fit the required time bounds.

□

### 3.2 Behavior

**Definition 26.**

$$\begin{aligned} toApplication &: Behavior_{\tau}^S \rightarrow Behavior_{Client \rightarrow \tau}^A \\ \llbracket toApplication \rrbracket(b) &= \lambda s. \begin{cases} \lambda c \rightarrow b(c)(s) & \text{if } Time_0^s \leq s < Time_{\infty}^s \\ \perp & \text{otherwise} \end{cases} \end{aligned}$$

**Theorem 26.** *If the arguments are valid,  $\llbracket toApplication \rrbracket(b)$  returns a valid result.*

*Proof.* There is one property that the resulting value must comply with in order to be valid.

1. The domain of the resulting function is within the required bounds by construction. □

**Definition 27.**

$$\begin{aligned} toSession &: Behavior_{\tau}^A \rightarrow Behavior_{\tau}^S \\ \llbracket toSession \rrbracket(b) &= \lambda c. \lambda s. \begin{cases} b(s) & \text{if } Time_{0,c}^s \leq s < Time_{\infty,c}^s \\ \perp & \text{otherwise} \end{cases} \end{aligned}$$

**Theorem 27.** *If the arguments are valid,  $\llbracket toSession \rrbracket(b)$  returns a valid result.*

*Proof.* There is one property that the resulting value must comply with in order to be valid.

1. The domain of the resulting function is within the required bounds by construction. □

### 3.3 Incremental Behavior

**Definition 28.**

$$\begin{aligned} toApplication &: IncBehavior_{\tau,\delta}^S \rightarrow IncBehavior_{Client \rightarrow \tau, Client \rightarrow \delta \times (ClientChange \uplus \top)}^A \\ \llbracket toApplication \rrbracket((e, v_0, f)) &= \text{let} \quad \begin{aligned} e' &= \llbracket map \rrbracket(\llbracket toApplication \rrbracket(e), \lambda map. (map, \top)) \\ clientChanges' &= \llbracket map \rrbracket(\llbracket clientChanges \rrbracket, \lambda c. (\lambda \_ . \perp, c)) \\ u &= \llbracket union \rrbracket(e', clientChanges', \lambda map. \lambda c. (map_1, c_2)) \end{aligned} \\ f' &= \lambda v. \lambda d. \lambda c. \begin{cases} v_0(c) & \text{if } d.2 = (Connected, c) \\ \perp & \text{if } d.2 = (Disconnected, c) \\ v(c) & \text{if } d.1(c) = \perp \\ f(c)(v(c))(d.1(c)) & \text{otherwise} \end{cases} \\ &\text{in}(u, \lambda c \rightarrow \perp, f') \end{aligned}$$

**Theorem 28.** *If the arguments are valid,  $\llbracket toApplication \rrbracket(b)$  returns a valid result.*

*Proof.* There is one property that the resulting value must comply with in order to be valid.

1. The 3 constructed elements of the resulting tuple are of the correct type. □

**Definition 29.**

$$\begin{aligned} toSession &: IncBehavior_{\tau,\delta}^A \rightarrow IncBehavior_{\tau,\delta}^S \\ \llbracket toSession \rrbracket((e, v, f)) &= (\llbracket toSession \rrbracket(e), \lambda c. \llbracket convert \rrbracket((e, v, f))(Time_{0,c}^s, \lambda c. f)) \end{aligned}$$

**Theorem 29.** *If the arguments are valid,  $\llbracket toSession \rrbracket((e, v, f))$  returns a valid result.*

*Proof.* There is one property that the resulting value must comply with in order to be valid.

1. The 3 constructed elements of the resulting tuple are of the correct type. □

### 3.4 Events $\leftrightarrow$ Behaviors

**Definition 30.**

$$\begin{aligned} \text{snapshot} &: \text{Event}_{\alpha \rightarrow \beta}^C \rightarrow \text{Behavior}_{\alpha}^C \rightarrow \text{Event}_{\beta}^C \\ \llbracket \text{snapshot} \rrbracket(e, b) &= \lambda c. \{(t, v(b(c)(t))) \mid (t, v) \in e(c)\} \end{aligned}$$

**Theorem 30.** *If the arguments are valid,  $\llbracket \text{snapshot} \rrbracket(e, b)$  returns a valid result.*

*Proof.* There are 3 properties that the resulting value must comply with in order to be valid.

1. A value is created for each value in  $e$  which is a finite amount.
2. Only one value is created for every value in  $e$  so the result remains unique in time. Note that the time bounds on  $e$  ensure that  $b(c)(t)$  is well defined.
3. The bounds do not change compared to  $e$ .

□

**Definition 31.**

$$\begin{aligned} \text{snapshot} &: \text{Event}_{\alpha \rightarrow \beta}^S \rightarrow \text{Behavior}_{\alpha}^S \rightarrow \text{Event}_{\beta}^S \\ \llbracket \text{snapshot} \rrbracket(e, b) &= \lambda c. \{(s, v(b(c)(s))) \mid (s, v) \in e(c)\} \end{aligned}$$

**Theorem 31.** *If the arguments are valid,  $\llbracket \text{snapshot} \rrbracket(e, b)$  returns a valid result.*

*Proof.* Similar to  $\text{Event}^C$

□

**Definition 32.**

$$\begin{aligned} \text{snapshot} &: \text{Event}_{\alpha \rightarrow \beta}^A \rightarrow \text{Behavior}_{\alpha}^A \rightarrow \text{Event}_{\beta}^A \\ \llbracket \text{snapshot} \rrbracket(e, b) &= \{(s, v(b(s))) \mid (s, v) \in e\} \end{aligned}$$

**Theorem 32.** *If the arguments are valid,  $\llbracket \text{snapshot} \rrbracket(e, b)$  returns a valid result.*

*Proof.* Similar to  $\text{Event}^C$

□

**Definition 33.**

$$\begin{aligned} \text{foldP} &: \text{Event}_{\delta}^C \rightarrow \tau \rightarrow (\tau \rightarrow \delta \rightarrow \tau) \rightarrow \text{IncBehavior}_{\tau, \delta}^C \\ \llbracket \text{foldP} \rrbracket(e, v, f) &= (e, \lambda c. v, \lambda c. f) \end{aligned}$$

**Theorem 33.** *If the arguments are valid,  $\llbracket \text{foldP} \rrbracket(e, v, f)$  returns a valid result.*

*Proof.* There is one property that the resulting value must comply with in order to be valid.

1. The 3 constructed elements of the resulting tuple are of the correct type.

□

**Definition 34.**

$$\begin{aligned} \text{foldP} &: \text{Event}_{\delta}^S \rightarrow \tau \rightarrow (\tau \rightarrow \delta \rightarrow \tau) \rightarrow \text{IncBehavior}_{\tau, \delta}^C \\ \llbracket \text{foldP} \rrbracket(e, v, f) &= (e, \lambda c. v, \lambda c. f) \end{aligned}$$

**Theorem 34.** *If the arguments are valid,  $\llbracket \text{foldP} \rrbracket(e, v, f)$  returns a valid result.*

*Proof.* Similar to  $\text{Event}^C$

□

**Definition 35.**

$$\begin{aligned} \text{foldP} &: \text{Event}_{\delta}^A \rightarrow \tau \rightarrow (\tau \rightarrow \delta \rightarrow \tau) \rightarrow \text{IncBehavior}_{\tau, \delta}^A \\ \llbracket \text{foldP} \rrbracket(e, v, f) &= (e, v, f) \end{aligned}$$

**Theorem 35.** *If the arguments are valid,  $\llbracket \text{foldP} \rrbracket(e, v, f)$  returns a valid result.*

*Proof.* Similar to  $\text{Event}^C$

□

### 3.5 Incremental Behavior $\rightarrow$ Behavior

**Definition 36.**

$$\begin{aligned} & \text{convert} : \text{IncBehavior}_{\tau, \delta}^C \rightarrow \text{Behavior}_{\tau}^C \\ & \llbracket \text{convert} \rrbracket ( (e, v, f) ) = \\ & \lambda c. \lambda s. \begin{cases} f(c)(f(c)(\dots(f(c)(v(c), d_1), \dots), d_{n-1})d_n) \\ \quad \text{if } \text{Time}_{0,c} \leq t < \text{Time}_{\infty,c} \wedge \\ \quad e(c) = \{(t_1, d_1), \dots, (t_n, d_n), (t_{n+1}, d_{n+1}), \dots\} \wedge \\ \quad t_1 < \dots < t_n \leq t < t_{n+1} < \dots \\ \perp \quad \text{otherwise} \end{cases} \end{aligned}$$

**Theorem 36.** *If the arguments are valid,  $\llbracket \text{convert} \rrbracket ( (e, v, f) )$  returns a valid result.*

*Proof.* There is one property that the resulting value must comply with in order to be valid.

1. The domain of the resulting function is within the required bounds by construction and it is well defined since an order can be given to the timestamps of  $e(c)$  due to time being ordered and the amount of event values being finite.

□

**Definition 37.**

$$\begin{aligned} & \text{convert} : \text{IncBehavior}_{\tau, \delta}^S \rightarrow \text{Behavior}_{\tau}^S \\ & \llbracket \text{convert} \rrbracket ( (e, v, f) ) = \\ & \lambda c. \lambda s. \begin{cases} f(c)(f(c)(\dots(f(c)(v(c), d_1), \dots), d_{n-1})d_n) \\ \quad \text{if } \text{Time}_{0,c}^s \leq s < \text{Time}_{\infty,c}^s \wedge \\ \quad e(c) = \{(s_1, d_1), \dots, (s_n, d_n), (s_{n+1}, d_{n+1}), \dots\} \wedge \\ \quad s_1 < \dots < s_n \leq s < s_{n+1} < \dots \\ \perp \quad \text{otherwise} \end{cases} \end{aligned}$$

**Theorem 37.** *If the arguments are valid,  $\llbracket \text{convert} \rrbracket ( (e, v, f) )$  returns a valid result.*

*Proof.* Similar to  $\text{Event}^C$

□

**Definition 38.**

$$\begin{aligned} & \text{convert} : \text{IncBehavior}_{\tau, \delta}^A \rightarrow \text{Behavior}_{\tau}^A \\ & \llbracket \text{convert} \rrbracket ( (e, v, f) ) = \\ & \lambda s. \begin{cases} f(f(\dots(f(v, d_1), \dots), d_{n-1})d_n) \\ \quad \text{if } \text{Time}_0^s \leq s < \text{Time}_{\infty}^s \wedge \\ \quad e = \{(s_1, d_1), \dots, (s_n, d_n), (s_{n+1}, d_{n+1}), \dots\} \wedge \\ \quad s_1 < \dots < s_n \leq s < s_{n+1} < \dots \\ \perp \quad \text{otherwise} \end{cases} \end{aligned}$$

**Theorem 38.** *If the arguments are valid,  $\llbracket \text{convert} \rrbracket ( (e, v, f) )$  returns a valid result.*

*Proof.* Similar to  $\text{Event}^C$

□

## 4 Boundary Operations

### 4.1 Events

**Definition 39.**

$$\begin{aligned} & \text{toServer} : \text{Event}_{\tau}^C \rightarrow \text{Event}_{\tau}^S \\ & \llbracket \text{toServer} \rrbracket (e) = \lambda c. \{(\text{delay}_{C \rightarrow S}(t, c), v) \mid (t, v) \in e(c)\} \end{aligned}$$

**Theorem 39.** *If the arguments are valid,  $\text{toServer}(e)$  returns a valid result.*

*Proof.* There are 3 properties that the resulting value must comply with in order to be valid.

1.  $Event^C$  is already finite, we do not add any elements.
2. The  $delay_{C \rightarrow S}$  function is injective since it is a strictly monotone function. Since  $Event^C$ s are unique in time, the resulting  $Event^S$  will remain unique in time after applying  $delay_{C \rightarrow S}$ .
3. Client events are bound for each client by  $Time_{0,c}$  and  $Time_{\infty,c}$ , since all events are delayed equally per client with  $delay_{C \rightarrow S}$  they are bounded by  $Time_{0,c}^s$  and  $Time_{\infty,c}^s$ .

□

**Definition 40.**

$$toClient : Event_{\tau}^S \rightarrow Event_{\tau}^C$$

$$\llbracket toClient \rrbracket(e) = \lambda c. \left\{ (t, v) \left| \begin{array}{l} (s, v) \in e(c) \\ \wedge t = delay_{S \rightarrow C}(s, c) \\ \wedge t < Time_{\infty,c} \end{array} \right. \right\}$$

**Theorem 40.** *If the arguments are valid,  $\llbracket toClient \rrbracket(e)$  returns a valid result.*

*Proof.* There are 3 properties that the resulting value must comply with in order to be valid.

1.  $Event^S$  is already finite, we do not add any elements.
2. The  $delay_{S \rightarrow C}$  function is injective since it is a strictly monotone function. Since  $Event^C$ s are unique in time, the resulting  $Event^S$  will remain unique in time after applying  $delay_{S \rightarrow C}$ .
3. Events in  $Event^S$ s are bounded by  $Time_{0,c}^s$  and  $Time_{\infty,c}^s$ .  $delay_{S \rightarrow C}(Time_{0,c}^s, c)$  is by definition larger than  $Time_{0,c}$  (the required lower bound) because delays are increasing.

The upper bound holds by definition of  $toClient$ .

□

## 4.2 Incremental Behavior

**Definition 41.**

$$toServer : IncBehavior_{\tau,\delta}^C \rightarrow IncBehavior_{\tau,\delta}^S$$

$$\llbracket toServer \rrbracket(b) = \mathbf{let}(e, v, f) = b$$

$$\mathbf{in}(\llbracket toServer \rrbracket(e), v, f)$$

**Theorem 41.** *If the arguments are valid,  $\llbracket toServer \rrbracket(b)$  returns a valid result.*

*Proof.* There is one property that the resulting value must comply with in order to be valid.

1. The 3 constructed elements of the resulting tuple are of the correct type.

□

**Definition 42.**

$$toClient : IncBehavior_{\tau,\delta}^S \rightarrow IncBehavior_{\tau,\delta}^C$$

$$\llbracket toClient \rrbracket(i) = \mathbf{let}(e, v, f) = i$$

$$\mathbf{in}(\llbracket toClient \rrbracket(e), v, f)$$

**Theorem 42.** *If the arguments are valid,  $\llbracket toClient \rrbracket(i)$  returns a valid result.*

*Proof.* There is one property that the resulting value must comply with in order to be valid.

1. The 3 constructed elements of the resulting tuple are of the correct type.

□

## 5 Commutative Replication

**Definition 43.**

$$\llbracket toServer \rrbracket(\llbracket map \rrbracket(e, f)) = \llbracket map \rrbracket(\llbracket toServer \rrbracket(e), f)$$

*Proof.*

$$\begin{aligned}
& \llbracket toServer \rrbracket(\lambda c. \{(t, f(v) \mid (t, v) \in e(c))\}) = & \llbracket map \rrbracket \\
& \lambda c. \{(delay_{C \rightarrow S}(t, c), v) \mid (t, v) \in (\lambda c. \{(t, f(v) \mid (t, v) \in e(c))\})(c)\} = & \llbracket toServer \rrbracket \\
& \lambda c. \{(t, f(v), v) \mid (t, v) \in (\lambda c. \{(delay_{C \rightarrow S}(t, c) \mid (t, v) \in e(c))\})(c)\} = & \text{rewrite} \\
& \lambda c. \{(t, f(v), v) \mid (t, v) \in (\llbracket toServer \rrbracket(e))(c)\} = & \llbracket toServer \rrbracket^{-1} \\
& \llbracket map \rrbracket(\llbracket toServer \rrbracket(e), f) = & \llbracket map \rrbracket^{-1}
\end{aligned}$$

□

**Definition 44.**

$$\llbracket toServer \rrbracket(\llbracket union \rrbracket(e, e', f)) = \llbracket union \rrbracket(\llbracket toServer \rrbracket(e), \llbracket toServer \rrbracket(e'), f)$$

*Proof.*

$$\begin{aligned}
\lambda c. \mathbf{let} \quad left &= \left\{ \begin{array}{l} (t, v) \mid \\ (t, v) \in e(c) \\ \wedge \forall (t', -) \in e'(c). t \neq t' \end{array} \right\} = & \llbracket union \rrbracket \\
both &= \left\{ \begin{array}{l} (t, f(v, v')) \mid \\ (t, v) \in e(c) \\ \wedge (t', v') \in e'(c) \\ \wedge t = t' \end{array} \right\} \\
right &= \left\{ \begin{array}{l} (t, v) \mid \\ (t, v) \in e'(c) \\ \wedge \forall (t', -) \in e(c). t \neq t' \end{array} \right\} \\
&\mathbf{in} \llbracket toServer \rrbracket(left \cup both \cup right) \\
\lambda c. \mathbf{let} \quad left &= \left\{ \begin{array}{l} (delay_{C \rightarrow S}(t, c), v) \mid \\ (t, v) \in e(c) \\ \wedge \forall (t', -) \in e'(c). t \neq t' \end{array} \right\} = & \llbracket toServer \rrbracket \\
both &= \left\{ \begin{array}{l} (delay_{C \rightarrow S}(t, c), f(v, v')) \mid \\ (t, v) \in e(c) \\ \wedge (t', v') \in e'(c) \\ \wedge t = t' \end{array} \right\} \\
right &= \left\{ \begin{array}{l} (delay_{C \rightarrow S}(t, c), v) \mid \\ (t, v) \in e'(c) \\ \wedge \forall (t', -) \in e(c). t \neq t' \end{array} \right\} \\
&\mathbf{in} left \cup both \cup right \\
\lambda c. \mathbf{let} \quad eS &= \lambda c. \{(delay_{C \rightarrow S}(t, c), v) \mid (t, v) \in e(c)\} = & \text{rewrite} \\
eS' &= \lambda c. \{(delay_{C \rightarrow S}(t, c), v) \mid (t, v) \in e'(c)\} \\
left &= \left\{ \begin{array}{l} (t, v) \mid \\ (t, v) \in eS(c) \\ \wedge \forall (t', -) \in eS'(c). t \neq t' \end{array} \right\} \\
both &= \left\{ \begin{array}{l} (t, f(v, v')) \mid \\ (t, v) \in eS(c) \\ \wedge (t', v') \in eS'(c) \\ \wedge t = t' \end{array} \right\} \\
right &= \left\{ \begin{array}{l} (t, v) \mid \\ (t, v) \in eS'(c) \\ \wedge \forall (t', -) \in eS(c). t \neq t' \end{array} \right\} \\
&\mathbf{in} left \cup both \cup right \\
\llbracket union \rrbracket \left( \begin{array}{l} \lambda c. \{(delay_{C \rightarrow S}(t, c), v) \mid (t, v) \in e(c)\}, \\ \lambda c. \{(delay_{C \rightarrow S}(t, c), v) \mid (t, v) \in e'(c)\}, \\ f \end{array} \right) &= & \llbracket union \rrbracket^{-1} \\
&\llbracket union \rrbracket(\llbracket toServer \rrbracket(e), \llbracket toServer \rrbracket(e'), f) = & \llbracket toServer \rrbracket
\end{aligned}$$

□