

Rohm,bd71847 driver Porting on imx8mm
platform of Linux 5.10.72 (NXP release)

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Linux Support Version compare

<https://www.nxp.com/design/software/embedded-software/i-mx-software/embedded-linux-for-i-mx-applications-processors:IMXLINUX>

Release	Build Sources and Documentation	Supported Platforms/Demo Images	Incremental Releases
Linux 5.10.72_2.2.2	<ul style="list-style-type: none">• Release Notes• See README on instructions for each release.• SCFW Porting Kit 1.11.2• Verisilicon IDE	<ul style="list-style-type: none">• i.MX 8DXL EVK• i.MX 8M Plus EVK• i.MX 8M Nano DDR3L EVK• i.MX 8M Nano EVK• i.MX 8M Mini EVK• i.MX 8M Quad EVK• i.MX 8QuadXPlus(C0) MEK• i.MX 8QuadMax MEK• i.MX 7ULP EVK• i.MX 6UltraLite, i.MX 6ULL, i.MX 6ULZ, i.MX 7Dual• i.MX 6SLL EVK• i.MX 6QuadPlus, i.MX 6Quad, i.MX 6DualPlus, i.MX 6Dual, i.MX 6DualLite, i.MX 6Solo, i.MX 6SoloX• i.MX 8M EVKs boot image(SystemReady-IR certified)	
Linux 5.4.47_2.2.0	<ul style="list-style-type: none">• Documentation• See README on instructions for each release.• SCFW Porting Kit• AACPlus Codec• Verisilicon IDE	<ul style="list-style-type: none">• i.MX 8M Nano EVK• i.MX 8M Mini EVK• i.MX 8M Quad EVK• i.MX 8QuadXPlus(C0) MEK, i.MX 8DualX MEK• i.MX 8QuadMax MEK• i.MX 7ULP EVK• i.MX 7Dual SABRESD• i.MX 6UltraLite, i.MX 6ULL, i.MX 6ULZ, i.MX 7Dual• i.MX 6SLL EVK• i.MX 6QuadPlus, i.MX 6Quad, i.MX 6DualPlus, i.MX 6Dual, i.MX 6DualLite, i.MX 6Solo, i.MX 6SoloX	

Default is not “bd71847”

Default is “bd71847”

Porting Step of u-boot (Linux version 5.10.72)

```
sources/u-boot-imx$ git status
```

```
On branch A100_develop
```

```
Your branch is up to date with 'origin/A100_develop'.
```

```
Changes not staged for commit:
```

```
(use "git add <file>..." to update what will be committed)
```

```
(use "git checkout -- <file>..." to discard changes in working directory)
```

```
modified: arch/arm/dts/imx8mm-ab2-u-boot.dtsi
modified: arch/arm/dts/imx8mm-evk-u-boot.dtsi
modified: arch/arm/dts/imx8mm-evk.dtsi
modified: board/freescale/imx8mm-evk/spl.c
modified: configs/imx8mm-evk_defconfig
modified: include/configs/imx8mm-evk.h
```

```
/u-boot-imx$ git diff arch/arm/dts/imx8mm-ab2-u-boot.dtsi
```

```
diff --git a/arch/arm/dts/imx8mm-ab2-u-boot.dtsi b/arch/arm/dts/imx8mm-ab2-u-boot.dtsi
index 7180e9691c..013226394d 100644
--- a/arch/arm/dts/imx8mm-ab2-u-boot.dtsi
+++ b/arch/arm/dts/imx8mm-ab2-u-boot.dtsi
@@ -143,11 +143,11 @@
        u-boot,dm-spl;
    };

-&{/soc@0/bus@308000000/i2c@30a20000/pca9450@25} {
+&{/soc@0/bus@308000000/i2c@30a20000/pmic@4b} {
        u-boot,dm-spl;
    };

-&{/soc@0/bus@308000000/i2c@30a20000/pca9450@25/regulators} {
+&{/soc@0/bus@308000000/i2c@30a20000/pmic@4b} {
        u-boot,dm-spl;
    };
};
```

Modify Compiler error

```
/u-boot-imx$ git diff arch/arm/dts/imx8mm-evk-u-boot.dtsi
```

```
diff --git a/arch/arm/dts/imx8mm-evk-u-boot.dtsi b/arch/arm/dts/imx8mm-evk-u-boot.dtsi
index 6f7b37cba2..c3b75892f4 100644
--- a/arch/arm/dts/imx8mm-evk-u-boot.dtsi
+++ b/arch/arm/dts/imx8mm-evk-u-boot.dtsi
@@ -151,11 +151,11 @@
        u-boot,dm-spl;
    };

-&{/soc@0/bus@308000000/i2c@30a20000/pca9450@25} {
+&{/soc@0/bus@308000000/i2c@30a20000/pmic@4b} {
        u-boot,dm-spl;
    };

-&{/soc@0/bus@308000000/i2c@30a20000/pca9450@25/regulators} {
+&{/soc@0/bus@308000000/i2c@30a20000/pmic@4b/regulators} {
        u-boot,dm-spl;
    };
};
```

Modify Compiler error

```
diff --git a/arch/arm/dts/imx8mm-evk.dtsi b/arch/arm/dts/imx8mm-evk.dtsi
index 9d8f07cfa9..e6a92083d5 100644
--- a/arch/arm/dts/imx8mm-evk.dtsi
+++ b/arch/arm/dts/imx8mm-evk.dtsi
@@ -165,127 +165,120 @@
```

```
&i2c1 {
    clock-frequency = <400000>;
    pinctrl-names = "default", "gpio";
+   pinctrl-names = "default";
    pinctrl-0 = <&pinctrl_i2c1>;
    pinctrl-1 = <&pinctrl_i2c1_gpio>;
    scl-gpios = <&gpio5 14 GPIO_ACTIVE_HIGH>;
    sda-gpios = <&gpio5 15 GPIO_ACTIVE_HIGH>;
    status = "okay";

    pmic: pca9450@25 {
        reg = <0x25>;
        compatible = "nxp,pca9450a";
        /* PMIC PCA9450 PMIC_nINT GPIO1_IO3 */
+   pmic: pmic@4b {
+       compatible = "rohm,bd71847";
+       reg = <0x4b>;
+       pinctrl-names = "default";
+       pinctrl-0 = <&pinctrl_pmic>;
+       gpio_intr = <&gpio1 3 GPIO_ACTIVE_LOW>;
+       interrupt-parent = <&gpio1>;
+       interrupts = <3 IRQ_TYPE_LEVEL_LOW>;
+       rohm,reset-snvs-powered;

+       #clock-cells = <0>;
+       #clocks = <&osc_32k 0>;
+       #clock-output-names = "clk-32k-out";
```

Check the last item → **Note 1**

It has mask .

```
regulators {
    #address-cells = <1>;
    #size-cells = <0>;

    pca9450,pmic-buck2-uses-i2c-dvs;
    /* Run/Standby voltage */
    pca9450,pmic-buck2-dvs-voltage = <950000>, <850000>;

    buck1_reg: regulator@0 {
        reg = <0>;
        regulator-compatible = "buck1";
        regulator-min-microvolt = <600000>;
        regulator-max-microvolt = <2100000>;
```

```

regulators {
    #address-cells = <1>;
    #size-cells = <0>;

    pca9450,pmic-buck2-uses-i2c-dvs;
    /* Run/Standby voltage */
    pca9450,pmic-buck2-dvs-voltage = <950000>, <850000>;

    buck1_reg: regulator@0 {
        reg = <0>;
        regulator-compatible = "buck1";
        regulator-min-microvolt = <600000>;
        regulator-max-microvolt = <2187500>;
    buck1_reg: BUCK1 {
        regulator-name = "BUCK1";
        regulator-min-microvolt = <700000>;
        regulator-max-microvolt = <1300000>;
        regulator-boot-on;
        regulator-always-on;
        regulator-ramp-delay = <3125>;
        regulator-ramp-delay = <1250>;
    };

    buck2_reg: regulator@1 {
        reg = <1>;
        regulator-compatible = "buck2";
        regulator-min-microvolt = <600000>;
        regulator-max-microvolt = <2187500>;
    buck2_reg: BUCK2 {
        regulator-name = "BUCK2";
        regulator-min-microvolt = <700000>;
        regulator-max-microvolt = <1300000>;
        regulator-boot-on;
        regulator-always-on;
        regulator-ramp-delay = <3125>;
        regulator-ramp-delay = <1250>;
        rohm,dvs-run-voltage = <1000000>;
        rohm,dvs-idle-voltage = <900000>;
    };

    buck3_reg: regulator@2 {
        reg = <2>;
        regulator-compatible = "buck3";
        regulator-min-microvolt = <600000>;
        regulator-max-microvolt = <2187500>;
    buck3_reg: BUCK3 {
        // BUCK5 in datasheet
        regulator-name = "BUCK3";
        regulator-min-microvolt = <700000>;

```

```

    buck3_reg: BUCK3 {
        // BUCK5 in datasheet
        regulator-name = "BUCK3";
        regulator-min-microvolt = <700000>;
        regulator-max-microvolt = <1350000>;
        regulator-boot-on;
        regulator-always-on;
    };

    buck4_reg: regulator@3 {
        reg = <3>;
        regulator-compatible = "buck4";
        regulator-min-microvolt = <600000>;
        regulator-max-microvolt = <3400000>;
    buck4_reg: BUCK4 {
        // BUCK6 in datasheet
        regulator-name = "BUCK4";
        regulator-min-microvolt = <3000000>;
        regulator-max-microvolt = <3300000>;
        regulator-boot-on;
        regulator-always-on;
    };

    buck5_reg: regulator@4 {
        reg = <4>;
        regulator-compatible = "buck5";
        regulator-min-microvolt = <600000>;
        regulator-max-microvolt = <3400000>;
    buck5_reg: BUCK5 {
        // BUCK7 in datasheet
        regulator-name = "BUCK5";
        regulator-min-microvolt = <1605000>;
        regulator-max-microvolt = <1995000>;
        regulator-boot-on;
        regulator-always-on;
    };

    buck6_reg: regulator@5 {
        reg = <5>;
        regulator-compatible = "buck6";
        regulator-min-microvolt = <600000>;
        regulator-max-microvolt = <3400000>;
    buck6_reg: BUCK6 {
        // BUCK8 in datasheet
        regulator-name = "BUCK6";
        regulator-min-microvolt = <800000>;
        regulator-max-microvolt = <1400000>;
        regulator-boot-on;
        regulator-always-on;
    };

```



```

};

ldo1_reg: regulator@6 {
    reg = <6>;
    regulator-compatible = "ldo1";
    regulator-min-microvolt = <1600000>;
ldo1_reg: LD01 {
    regulator-name = "LD01";
    regulator-min-microvolt = <3000000>;
    regulator-max-microvolt = <3300000>;
    regulator-boot-on;
    regulator-always-on;
};

ldo2_reg: regulator@7 {
    reg = <7>;
    regulator-compatible = "ldo2";
    regulator-min-microvolt = <800000>;
    regulator-max-microvolt = <1150000>;
ldo2_reg: LD02 {
    regulator-name = "LD02";
    regulator-min-microvolt = <900000>;
    regulator-max-microvolt = <900000>;
    regulator-boot-on;
    regulator-always-on;
};

ldo3_reg: regulator@8 {
    reg = <8>;
    regulator-compatible = "ldo3";
    regulator-min-microvolt = <800000>;
ldo3_reg: LD03 {
    regulator-name = "LD03";
    regulator-min-microvolt = <1800000>;
    regulator-max-microvolt = <3300000>;
    regulator-boot-on;
    regulator-always-on;
};

ldo4_reg: regulator@9 {
    reg = <9>;
    regulator-compatible = "ldo4";
    regulator-min-microvolt = <800000>;
    regulator-max-microvolt = <3300000>;
ldo4_reg: LD04 {
    regulator-name = "LD04";
    regulator-min-microvolt = <900000>;
    regulator-max-microvolt = <1800000>;

```

```

};

ldo5_reg: regulator@10 {
    reg = <10>;
    regulator-compatible = "ldo5";
    regulator-min-microvolt = <1800000>;
    regulator-max-microvolt = <3300000>;
ldo6_reg: LD06 {
    regulator-name = "LD06";
    regulator-min-microvolt = <900000>;
    regulator-max-microvolt = <1800000>;
    regulator-boot-on;
    regulator-always-on;
};
};

```



```
&i2c1 {
    clock-frequency = <400000>;
    pinctrl-names = "default";
    pinctrl-0 = <&pinctrl_i2c1>;
    status = "okay";

    pmic@4b {
        compatible = "rohm,bd71847";
        reg = <0x4b>;
        pinctrl-0 = <&pinctrl_pmic>;
        interrupt-parent = <&gpio1>;
        interrupts = <3 GPIO_ACTIVE_LOW>;
        rohm,reset-snvs-powered;

        regulators {
            buck1_reg: BUCK1 {
                regulator-name = "BUCK1";
                regulator-min-microvolt = <700000>;
                regulator-max-microvolt = <1300000>;
                regulator-boot-on;
                regulator-always-on;
                regulator-ramp-delay = <1250>;
            };

            buck2_reg: BUCK2 {
                regulator-name = "BUCK2";
                regulator-min-microvolt = <700000>;
                regulator-max-microvolt = <1300000>;
                regulator-boot-on;
                regulator-always-on;
                regulator-ramp-delay = <1250>;
                rohm,dvs-run-voltage = <1000000>;
                rohm,dvs-idle-voltage = <900000>;
            };

            buck3_reg: BUCK3 {
                // BUCK5 in datasheet
                regulator-name = "BUCK3";
                regulator-min-microvolt = <700000>;
                regulator-max-microvolt = <1350000>;
                regulator-boot-on;
                regulator-always-on;
            };

            buck4_reg: BUCK4 {
                // BUCK6 in datasheet
                regulator-name = "BUCK4";
                regulator-min-microvolt = <3000000>;
                regulator-max-microvolt = <3300000>;
                regulator-boot-on;
```

Check the last item → **Note 1**

```

u-boot-imx$ git diff board/freescale/imx8mm_evk/spl.c
diff --git a/board/freescale/imx8mm_evk/spl.c b/board/freescale/imx8mm_evk/spl.c
index 4ca63ff1ba..0bb81dd8cb 100644
--- a/board/freescale/imx8mm_evk/spl.c
+++ b/board/freescale/imx8mm_evk/spl.c
@@ -21,9 +21,10 @@
#include <asm/arch/ddr.h>

#include <power/pmic.h>
-#ifdef CONFIG_POWER_PCA9450
-#include <power/pca9450.h>
-#else
+//#ifdef CONFIG_POWER_PCA9450
+//#include <power/pca9450.h>
+//#else
+#ifdef CONFIG_POWER_BD71837
#include <power/bd71837.h>
#endif
#include <asm/mach-imx/gpio.h>
@@ -192,8 +193,10 @@ int board_mmc_getcd(struct mmc *mmc)

#ifdef CONFIG_POWER
#define I2C_PMIC 0
-#ifdef CONFIG_POWER_PCA9450
-int power_init_board(void)
+//#ifdef CONFIG_POWER_PCA9450
+#ifdef CONFIG_POWER_BD71837
+#if 0
+/*int power_init_board(void)
{
    struct pmic *p;
    int ret;
@@ -226,13 +229,14 @@ int power_init_board(void)
    pmic_reg_write(p, PCA9450_RESET_CTRL, 0xA1);

    return 0;

```

```

-}
-#else
-int power_init_board(void)
+}*/
+#endif
+//#else
+int power_init_board(void)
{
    struct pmic *p;
    int ret;

-
+    printf("power_init_board in coming\r\n");
    ret = power_bd71837_init(I2C_PMIC);
    if (ret)
        printf("power init failed");
}

```

(END)

```
/u-boot-imx$ git diff configs/imx8mm_evk_defconfig
diff --git a/configs/imx8mm_evk_defconfig b/configs/imx8mm_evk_defconfig
index 531bb1ba35659..cbc45bd8bb 100644
--- a/configs/imx8mm_evk_defconfig
+++ b/configs/imx8mm_evk_defconfig
@@ -128,6 +128,7 @@ CONFIG_FEC_MXC=y
 CONFIG_MII=y
 CONFIG_PINCTRL=y
 CONFIG_PINCTRL_IMX8M=y
+CONFIG_SPL_DM_PMIC_BD71837=y
 CONFIG_DM_REGULATOR=y
 CONFIG_DM_REGULATOR_FIXED=y
 CONFIG_DM_REGULATOR_GPIO=y

/u-boot-imx$ git diff include/configs/imx8mm_evk.h
diff --git a/include/configs/imx8mm_evk.h b/include/configs/imx8mm_evk.h
index 34c37e942e..652f3f4539 100644
--- a/include/configs/imx8mm_evk.h
+++ b/include/configs/imx8mm_evk.h
@@ -34,7 +34,8 @@
 #define CONFIG_POWER
 #define CONFIG_POWER_I2C
 #if defined(CONFIG_IMX8M_LPDDR4) && defined(CONFIG_TARGET_IMX8MM_EVK)
-#define CONFIG_POWER_PCA9450
+// #define CONFIG_POWER_PCA9450
+#define CONFIG_POWER_BD71837
 #else
 #define CONFIG_POWER_BD71837
 #endif
```

Porting Step of Linux (Linux version 5.10.72)

```
sources/linux-imx$ git status
```

```
On branch A100_develop
```

```
Your branch is up to date with 'origin/A100_develop'.
```

```
Changes not staged for commit:
```

```
(use "git add <file>..." to update what will be committed)
```

```
(use "git checkout -- <file>..." to discard changes in working directory)
```

```
modified: arch/arm64/boot/dts/freescale/imx8mm-evk.dtsi
modified: arch/arm64/configs/imx_v8_defconfig
modified: drivers/clock/Makefile
modified: drivers/mfd/rohm-bd718x7.c
```

```
no changes added to commit (use "git add" and/or "git commit -a")
```

```
/sources/linux-imx$
```

```
sources/linux-imx$ git diff arch/arm64/boot/dts/freescale/imx8mm-evk.dtsi
diff --git a/arch/arm64/boot/dts/freescale/imx8mm-evk.dtsi b/arch/arm64/boot/dts/freescale/imx8mm-evk.dtsi
index 7bb3541a1b41..9668388a3b7e 100755
--- a/arch/arm64/boot/dts/freescale/imx8mm-evk.dtsi
+++ b/arch/arm64/boot/dts/freescale/imx8mm-evk.dtsi
@@ -234,70 +234,82 @@
     status = "okay";
```

```
pmic_nxp: pca9450@25 {
    compatible = "nxp,pca9450a";
    compatible = "nxp,pca9450a0819";
    reg = <0x25>;
    pinctrl-0 = <&pinctrl_pmic>;
    pinctrl-names = "default";
    interrupt-parent = <&gpio1>;
    interrupts = <3 IRQ_TYPE_LEVEL_LOW>;
```

```
};
pmic@4b {
    compatible = "rohm,bd71847";
    reg = <0x4b>;
    pinctrl-0 = <&pinctrl_pmic>;
    interrupt-parent = <&gpio1>;
    interrupts = <3 GPIO_ACTIVE_LOW>;
    rohm,reset-snvs-powered;
```

```
regulators {
    buck1_reg: BUCK1 {
    buck1_reg: BUCK1 {
        regulator-name = "BUCK1";
        regulator-min-microvolt = <600000>;
        regulator-max-microvolt = <2187500>;
        regulator-min-microvolt = <700000>;
        regulator-max-microvolt = <1300000>;
        regulator-boot-on;
        regulator-always-on;
        regulator-ramp-delay = <3125>;
        nxp,dvs-run-voltage = <850000>;
        nxp,dvs-standby-voltage = <800000>;
        regulator-ramp-delay = <1250>;
    };
    buck2_reg: BUCK2 {
        regulator-name = "BUCK2";
        regulator-min-microvolt = <600000>;
        regulator-max-microvolt = <2187500>;
        regulator-min-microvolt = <700000>;
        regulator-max-microvolt = <1300000>;
        regulator-boot-on;
        regulator-always-on;
```

Check the last item → **Note 2**

Check the last item → **Note 3**

```

        regulator-ramp-delay = <3125>;
        regulator-ramp-delay = <1250>;
        rohm,dvs-run-voltage = <1000000>;
        rohm,dvs-idle-voltage = <900000>;
};

buck3_reg: BUCK3 {
buck3_reg: BUCK3 {
    // BUCK5 in datasheet
    regulator-name = "BUCK3";
    regulator-min-microvolt = <600000>;
    regulator-max-microvolt = <2187500>;
    regulator-min-microvolt = <700000>;
    regulator-max-microvolt = <1350000>;
    regulator-boot-on;
    regulator-always-on;
};

buck4_reg: BUCK4 {
    // BUCK6 in datasheet
    regulator-name = "BUCK4";
    regulator-min-microvolt = <600000>;
    regulator-max-microvolt = <3400000>;
    regulator-min-microvolt = <3000000>;
    regulator-max-microvolt = <3300000>;
    regulator-boot-on;
    regulator-always-on;
};

buck5_reg: BUCK5 {
    // BUCK7 in datasheet
    regulator-name = "BUCK5";
    regulator-min-microvolt = <600000>;
    regulator-max-microvolt = <3400000>;
    regulator-min-microvolt = <1605000>;
    regulator-max-microvolt = <1995000>;
    regulator-boot-on;
    regulator-always-on;
};

buck6_reg: BUCK6 {
    // BUCK8 in datasheet
    regulator-name = "BUCK6";
    regulator-min-microvolt = <600000>;
    regulator-max-microvolt = <3400000>;
    regulator-min-microvolt = <800000>;
    regulator-max-microvolt = <1400000>;
    regulator-boot-on;
    regulator-always-on;
};

```

```

};

ldo1_reg: LD01 {
ldo1_reg: LD01 {
    regulator-name = "LD01";
    regulator-min-microvolt = <1600000>;
    regulator-max-microvolt = <3300000>;
    regulator-max-microvolt = <1900000>;
    regulator-boot-on;
    regulator-always-on;
};

ldo2_reg: LD02 {
    regulator-name = "LD02";
    regulator-min-microvolt = <800000>;
    regulator-max-microvolt = <1150000>;
    regulator-max-microvolt = <900000>;
    regulator-boot-on;
    regulator-always-on;
};

ldo3_reg: LD03 {
    regulator-name = "LD03";
    regulator-min-microvolt = <800000>;
    regulator-min-microvolt = <1800000>;
    regulator-max-microvolt = <3300000>;
    regulator-boot-on;
    regulator-always-on;
};

ldo4_reg: LD04 {
    regulator-name = "LD04";
    regulator-min-microvolt = <800000>;
    regulator-max-microvolt = <3300000>;
    regulator-min-microvolt = <900000>;
    regulator-max-microvolt = <1800000>;
    regulator-boot-on;
    regulator-always-on;
};

ldo5_reg: LD05 {
    regulator-name = "LD05";
    regulator-min-microvolt = <1800000>;
    regulator-max-microvolt = <3300000>;
ldo6_reg: LD06 {
    regulator-name = "LD06";
    regulator-min-microvolt = <900000>;
    regulator-max-microvolt = <1800000>;
    regulator-boot-on;
};

```



```
sources/linux-imx$ git diff drivers/clock/Makefile
```

```
diff --git a/drivers/clock/Makefile b/drivers/clock/Makefile
old mode 100644
new mode 100755
index 8a52da49c99a..4a1f22c0ce21
--- a/drivers/clock/Makefile
+++ b/drivers/clock/Makefile
@@ -21,7 +21,7 @@ endif
obj-$(CONFIG_MACH_ASM9260) += clock-asm9260.o
obj-$(CONFIG_COMMON_CLK_AXI_CLKGEN) += clock-axi-clkgen.o
obj-$(CONFIG_ARCH_AXM5516) += clock-axm5516.o
-obj-$(CONFIG_COMMON_CLK_BD718XX) += clock-bd718x7.o
+# obj-$(CONFIG_COMMON_CLK_BD718XX) += clock-bd718x7.o
obj-$(CONFIG_COMMON_CLK_BM1880) += clock-bm1880.o
obj-$(CONFIG_COMMON_CLK_CDCE706) += clock-cdce706.o
obj-$(CONFIG_COMMON_CLK_CDCE925) += clock-cdce925.o
```

```
sources/linux-imx$
```

```
sources/linux-imx$ git diff drivers/mfd/rohm-bd718x7.c
```

```
diff --git a/drivers/mfd/rohm-bd718x7.c b/drivers/mfd/rohm-bd718x7.c
old mode 100644
new mode 100755
index c32c1b6c98fa..d0e581427024
--- a/drivers/mfd/rohm-bd718x7.c
+++ b/drivers/mfd/rohm-bd718x7.c
@@ -136,8 +136,8 @@ static int bd718xx_i2c_probe(struct i2c_client *i2c,
    int ret;
    unsigned int chip_type;
    struct mfd_cell *mfd;
-   int cells;
+   int cells;
+   printk("bd718xx_i2c_probe plugin finish xxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxx 0830 -22222222222222222222 xxxxxxxxxxxxxxxx\r\n");
    if (!i2c->irq) {
        dev_err(&i2c->dev, "No IRQ configured\n");
        return -EINVAL;
```

This is check by myself

```
sources/linux-imx$
```

Booting Log

```
[ 2.089823] lib80211_crypt: registered algorithm 'WEP'
[ 2.089826] lib80211_crypt: registered algorithm 'CCMP'
[ 2.089830] lib80211_crypt: registered algorithm 'TKIP'
[ 2.089918] 9pnet: Installing 9P2000 support
[ 2.094226] tsn generic netlink module v1 init...
[ 2.099009] Key type dns_resolver registered
[ 2.104201] registered taskstats version 1
[ 2.108312] Loading compiled-in X.509 certificates
[ 2.134991] usb_phy_generic usbphynop1: supply vcc not found, using dummy regulator
[ 2.142943] usb_phy_generic usbphynop2: supply vcc not found, using dummy regulator
[ 2.152838] bd718xx_i2c_probe plugin finish xxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxx 0830 -22222222222222222222 xxxxxxxxxxxxxxxxxxxx
[ 2.231255] LDO6: supplied by regulator-dummy
[ 2.238559] i2c i2c-0: IMX I2C adapter registered
[ 2.245135] adv7511 1-003d: supply avdd not found, using dummy regulator
[ 2.251982] adv7511 1-003d: supply dvdd not found, using dummy regulator
[ 2.258739] adv7511 1-003d: supply pvdd not found, using dummy regulator
[ 2.265503] adv7511 1-003d: supply a2vdd not found, using dummy regulator
[ 2.272330] adv7511 1-003d: supply v3p3 not found, using dummy regulator
[ 2.279075] adv7511 1-003d: supply vlp2 not found, using dummy regulator
[ 2.287485] adv7511 1-003d: Probe failed. Remote port 'mipi_dsi@32e10000' disabled
[ 2.299913] i2c i2c-1: IMX I2C adapter registered
[ 2.306162] pca953x 2-0020: using no AI
[ 2.316374] ak4458 2-0010: Failed to request supplies: -517
[ 2.322392] ak4458 2-0012: Failed to request supplies: -517
[ 2.332750] ak5558 2-0013: Failed to request supplies: -517
[ 2.341587] ak4458 2-0011: Failed to request supplies: -517
[ 2.347753] ov5640_mipi 2-003c: No sensor reset pin available
[ 2.353553] ov5640_mipi 2-003c: supply DOVDD not found, using dummy regulator
[ 2.360802] ov5640_mipi 2-003c: supply DVDD not found, using dummy regulator
[ 2.367893] ov5640_mipi 2-003c: supply AVDD not found, using dummy regulator
[ 2.383919] ov5640_mipi 2-003c: Read reg error: reg=300a
[ 2.389239] ov5640_mipi 2-003c: Camera is not found
[ 2.394343] i2c i2c-2: IMX I2C adapter registered
[ 2.400778] SoC: i.MX8MM revision 1.0
```

Verify and testing

```
# dmesg
[ 0.000000] Booting Linux on physical CPU 0x0000000000 [0x410fd034]
[ 0.000000] Linux version 5.10.72-lts-5.10.y+ga68e31b63f86 (oe-user@oe-host) (aarch64-poky-linux-gcc (GCC) 10.2.0, GNU ld (GNU Binutils) 2.36.1
.20210209) #1 SMP PREEMPT Tue Apr 5 23:00:00 UTC 2011
[ 0.000000] Machine model: FSL i.MX8MM EVK board
[ 0.000000] efi: UEFI not found.
[ 0.000000] Reserved memory: created CMA memory pool at 0x0000000096000000, size 640 MiB
[ 0.000000] OF: reserved mem: initialized node linux,cma, compatible id shared-dma-pool
[ 0.000000] NUMA: No NUMA configuration found
[ 0.000000] NUMA: Faking a node at [mem 0x0000000040000000-0x00000000bfffffff]
[ 0.000000] NUMA: NODE_DATA [mem 0x95bda700-0x95bdcfff]
[ 0.000000] Zone ranges:
[ 0.000000]   DMA      [mem 0x0000000040000000-0x00000000bfffffff]
[ 0.000000]   DMA32    empty
[ 0.000000]   Normal    empty
[ 0.000000] Movable zone start for each node
[ 0.000000] Early memory node ranges
[ 0.000000]   node    0: [mem 0x0000000040000000-0x00000000bfffffff]
[ 0.000000] Initmem setup node 0 [mem 0x0000000040000000-0x00000000bfffffff]
```

```
00: /# i2cdetect -r -y 0
10:  0  1  2  3  4  5  6  7  8  9  a  b  c  d  e  f
20:  --  --  --  --  --  --  --  --  --  --  --  --  --  --  --  --
30:  --  --  --  --  --  --  --  --  --  --  --  --  --  --  --  --
40:  --  --  --  --  --  --  --  --  --  --  UU  --  --  --  --
50:  --  --  --  --  --  --  --  --  --  --  --  --  --  --  --  --
60:  --  --  --  --  --  --  --  --  --  --  --  --  --  --  --  --
70:  --  --  --  --  --  --  --  --  --  --  --  --  --  --  --  --
```

```
/sys/bus/i2c/devices# ls -al
```

```
total 0
drwxr-xr-x 2 root root 0 Mar 24 10:25 .
drwxr-xr-x 4 root root 0 Mar 24 10:25 ..
lrwxrwxrwx 1 root root 0 Mar 24 10:25 0-0025 -> ../../../../devices/platform/soc@0/30800000.bus/30a20000.i2c/i2c-0/0-0025
lrwxrwxrwx 1 root root 0 Mar 24 10:25 0-004b -> ../../../../devices/platform/soc@0/30800000.bus/30a20000.i2c/i2c-0/0-004b
lrwxrwxrwx 1 root root 0 Mar 24 10:25 1-003d -> ../../../../devices/platform/soc@0/30800000.bus/30a30000.i2c/i2c-1/1-003d
lrwxrwxrwx 1 root root 0 Mar 24 10:25 1-0050 -> ../../../../devices/platform/soc@0/30800000.bus/30a30000.i2c/i2c-1/1-0050
lrwxrwxrwx 1 root root 0 Mar 24 10:25 2-0010 -> ../../../../devices/platform/soc@0/30800000.bus/30a40000.i2c/i2c-2/2-0010
lrwxrwxrwx 1 root root 0 Mar 24 10:25 2-0011 -> ../../../../devices/platform/soc@0/30800000.bus/30a40000.i2c/i2c-2/2-0011
lrwxrwxrwx 1 root root 0 Mar 24 10:25 2-0012 -> ../../../../devices/platform/soc@0/30800000.bus/30a40000.i2c/i2c-2/2-0012
lrwxrwxrwx 1 root root 0 Mar 24 10:25 2-0013 -> ../../../../devices/platform/soc@0/30800000.bus/30a40000.i2c/i2c-2/2-0013
lrwxrwxrwx 1 root root 0 Mar 24 10:25 2-0020 -> ../../../../devices/platform/soc@0/30800000.bus/30a40000.i2c/i2c-2/2-0020
lrwxrwxrwx 1 root root 0 Mar 24 10:25 2-003c -> ../../../../devices/platform/soc@0/30800000.bus/30a40000.i2c/i2c-2/2-003c
lrwxrwxrwx 1 root root 0 Mar 24 10:25 i2c-0 -> ../../../../devices/platform/soc@0/30800000.bus/30a20000.i2c/i2c-0
lrwxrwxrwx 1 root root 0 Mar 24 10:25 i2c-1 -> ../../../../devices/platform/soc@0/30800000.bus/30a30000.i2c/i2c-1
lrwxrwxrwx 1 root root 0 Mar 24 10:25 i2c-2 -> ../../../../devices/platform/soc@0/30800000.bus/30a40000.i2c/i2c-2
```

```
/sys/bus/i2c/devices# cd 0-004b
```

```
/sys/bus/i2c/devices/0-004b# ls -al
```

```
total 0
drwxr-xr-x 7 root root 0 Mar 24 10:25 .
drwxr-xr-x 6 root root 0 Mar 24 10:25 ..
drwxr-xr-x 3 root root 0 Mar 24 10:25 bd71847-clk.2.auto
drwxr-xr-x 3 root root 0 Mar 24 10:25 bd71847-pmic.3.auto
-r--r--r-- 1 root root 4096 Mar 24 10:27 consumers
lrwxrwxrwx 1 root root 0 Mar 24 10:27 driver -> ../../../../bus/i2c/drivers/rohm-bd718x7
drwxr-xr-x 3 root root 0 Mar 24 10:25 gpio-keys.1.auto
-r--r--r-- 1 root root 4096 Mar 24 10:27 modalias
-r--r--r-- 1 root root 4096 Mar 24 10:25 name
lrwxrwxrwx 1 root root 0 Mar 24 10:27 of_node -> ../../../../firmware/devicetree/base/soc@0/bus@30800000/
drwxr-xr-x 2 root root 0 Mar 24 10:27 power
drwxr-xr-x 14 root root 0 Mar 24 10:25 regulator
lrwxrwxrwx 1 root root 0 Mar 24 10:25 subsystem -> ../../../../bus/i2c
-r--r--r-- 1 root root 4096 Mar 24 10:27 suppliers
-rw-r--r-- 1 root root 4096 Mar 24 10:25 uevent
```

```
/sys/bus/i2c/devices/0-004b#
```

```
:/sys/bus/i2c/devices/0-004b# cat name
bd71847
:/sys/bus/i2c/devices/0-004b# cd regulator/
:/sys/bus/i2c/devices/0-004b/regulator# ls -al
total 0
drwxr-xr-x 14 root root 0 Mar 24 10:25 .
drwxr-xr-x  7 root root 0 Mar 24 10:25 ..
drwxr-xr-x  3 root root 0 Mar 24 10:25 regulator.10
drwxr-xr-x  3 root root 0 Mar 24 10:25 regulator.11
drwxr-xr-x  3 root root 0 Mar 24 10:25 regulator.12
drwxr-xr-x  3 root root 0 Mar 24 10:25 regulator.13
drwxr-xr-x  3 root root 0 Mar 24 10:25 regulator.14
drwxr-xr-x  3 root root 0 Mar 24 10:25 regulator.15
drwxr-xr-x  3 root root 0 Mar 24 10:25 regulator.4
drwxr-xr-x  3 root root 0 Mar 24 10:25 regulator.5
drwxr-xr-x  3 root root 0 Mar 24 10:25 regulator.6
drwxr-xr-x  3 root root 0 Mar 24 10:25 regulator.7
drwxr-xr-x  3 root root 0 Mar 24 10:25 regulator.8
drwxr-xr-x  3 root root 0 Mar 24 10:25 regulator.9
:/sys/bus/i2c/devices/0-004b/regulator#
```


Note

Note 1

```
pmic: pmic@4b {  
    compatible = "rohm,bd71847";  
    reg = <0x4b>;  
    pinctrl-names = "default";  
    pinctrl-0 = <&pinctrl_pmic>;  
    gpio_intr = <&gpio1 3 GPIO_ACTIVE_LOW>;  
    interrupt-parent = <&gpio1>;  
    interrupts = <3 IRQ_TYPE_LEVEL_LOW>;  
    rohm,reset-snvs-powered;
```

Check the last item → **Note 1**

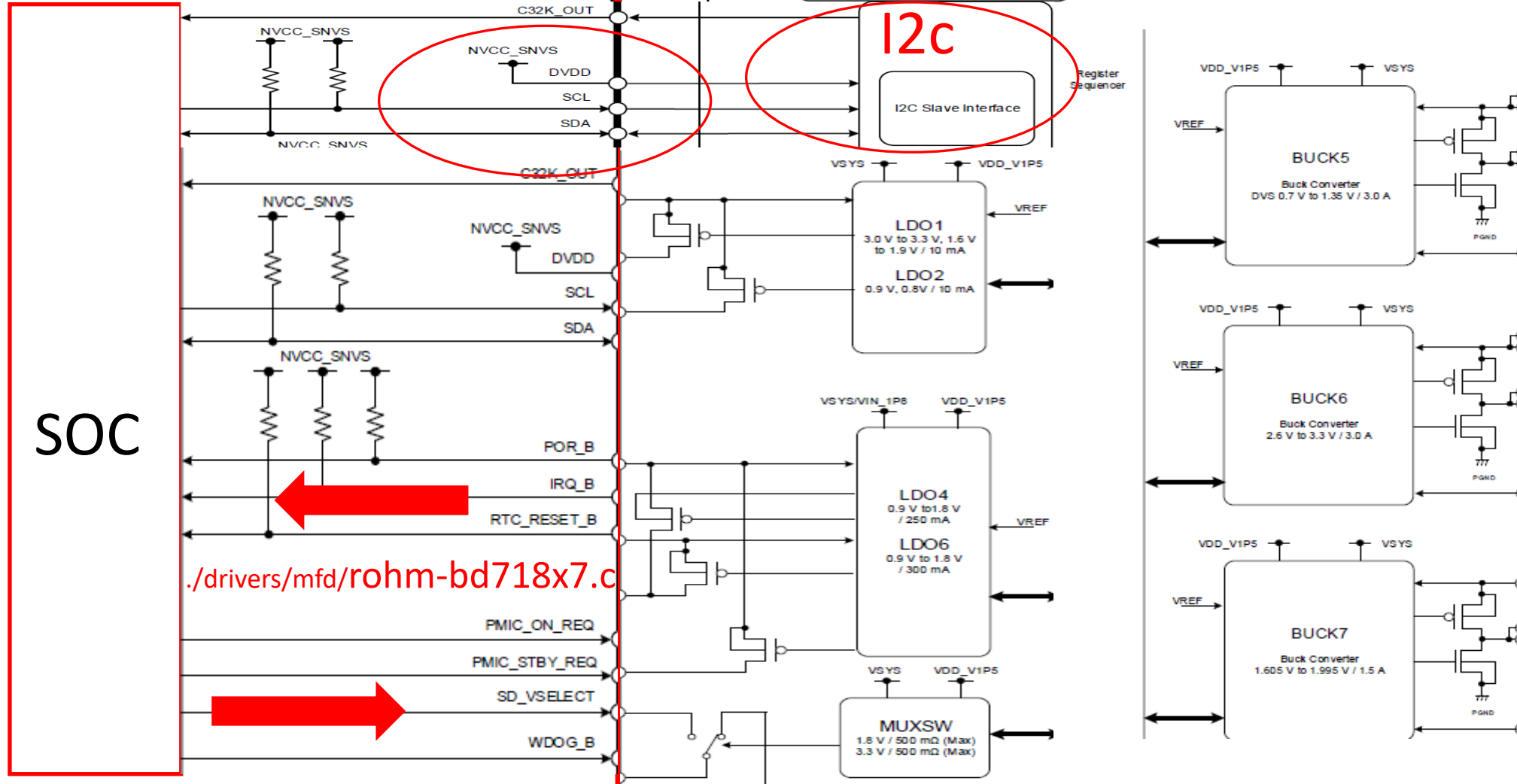
Interrupt 3 of GPIO1 . This is PMIC_n_INT . It shall configured according your board

BD71847AMWV

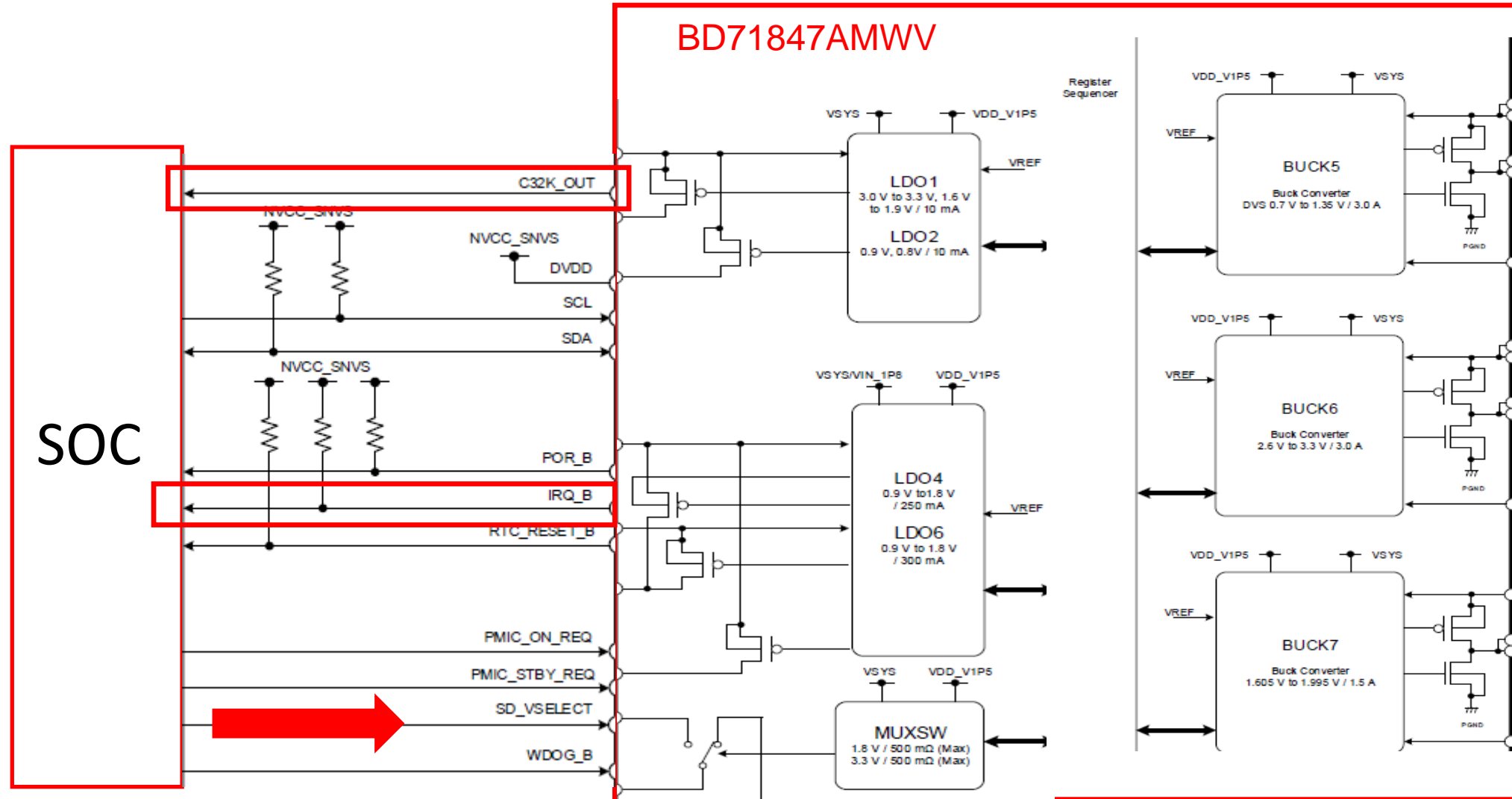
`/drivers/input/keyboard/gpio_keys.c`

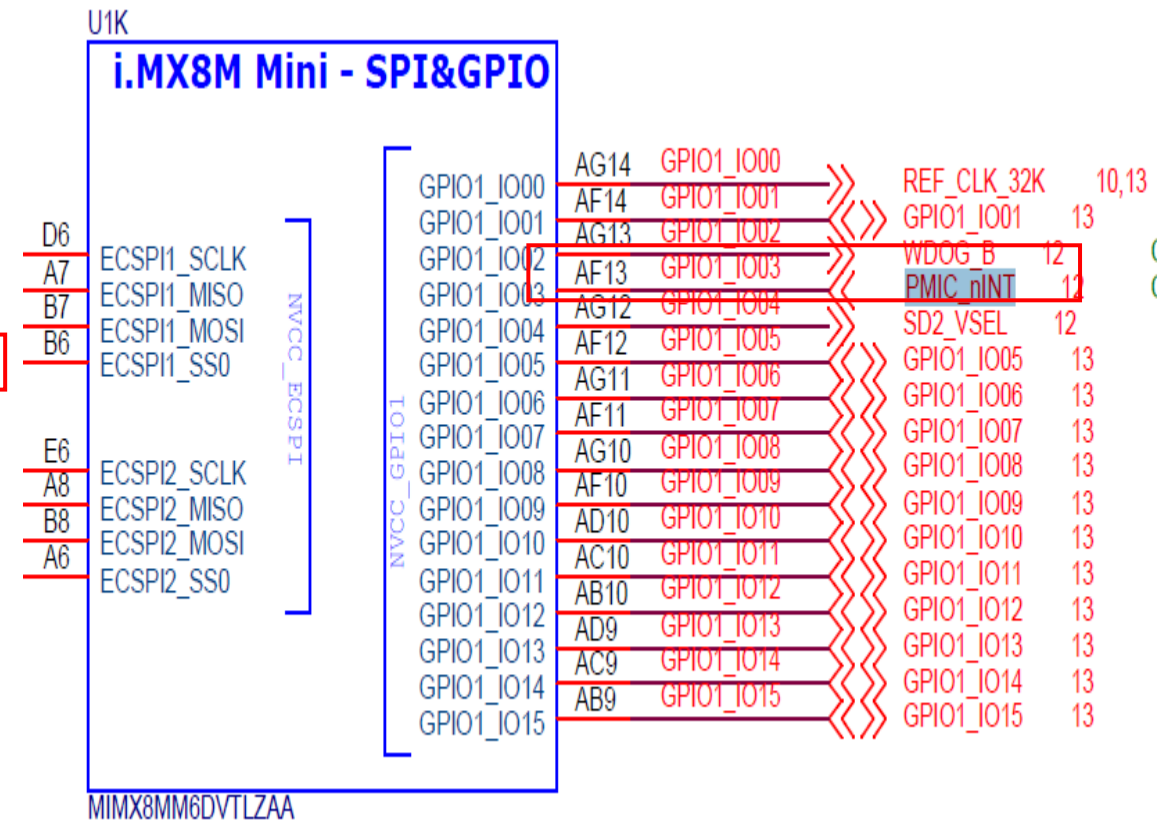
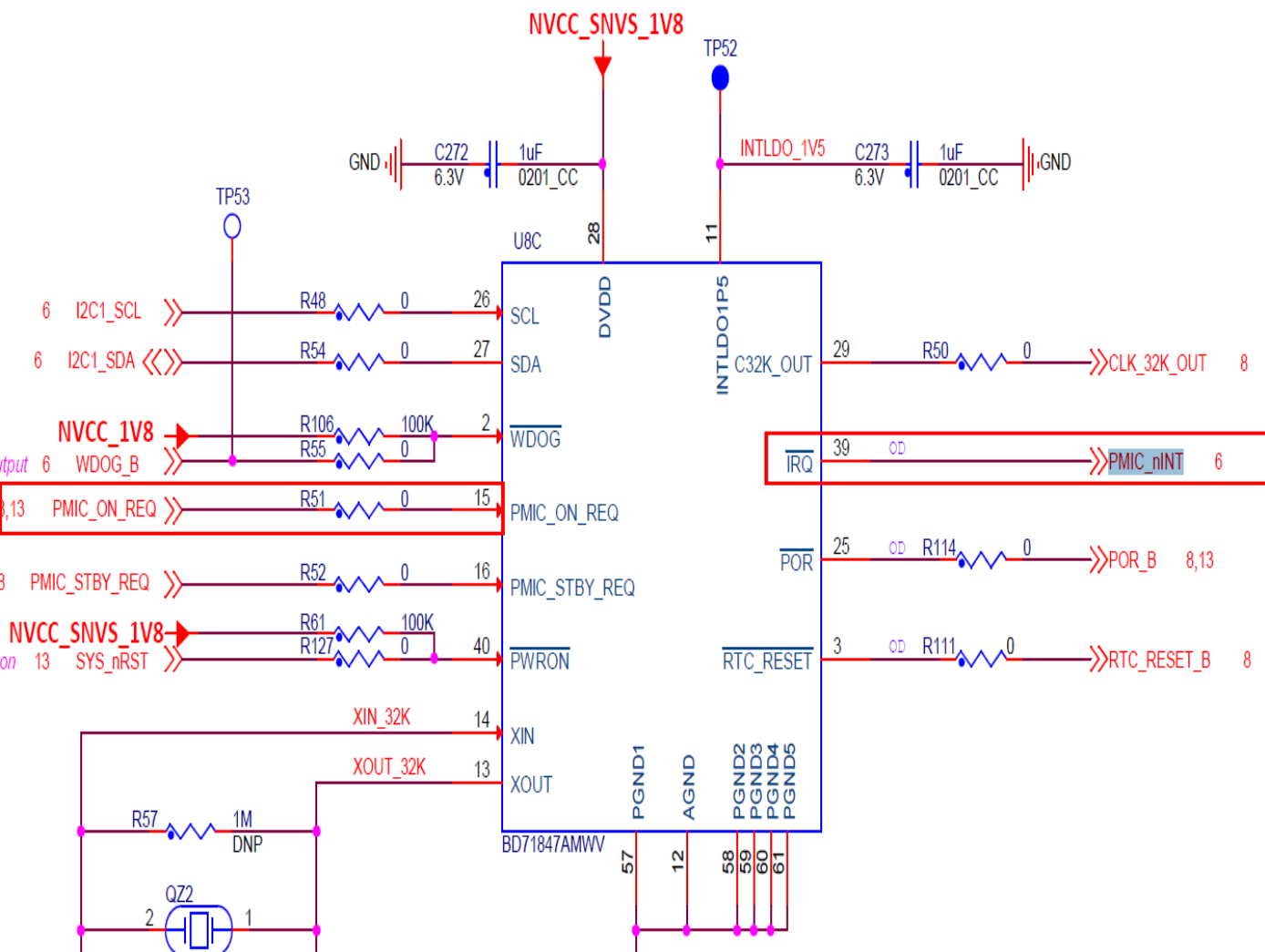
`./drivers/regulator/bd718x7-regulator.c`

`/drivers/clk/clk-bd718x7.c`



`./drivers/mfd/rohm-bd718x7.c`





Note 2

```
@@ -234,70 +234,82 @@
    status = "okay";

    pmic_nxp: pca9450@25 {
        compatible = "nxp,pca9450a";
        compatible = "nxp,pca9450a0819";
        reg = <0x25>;
        pinctrl-0 = <&pinctrl_pmic>;
        pinctrl-names = "default";
        interrupt-parent = <&gpio1>;
        interrupts = <3 IRQ_TYPE_LEVEL_LOW>;
    };
```

Check the last item → **Note 2**

It shall keep it because of compiler error. Other files will delete-note so let we keep there.

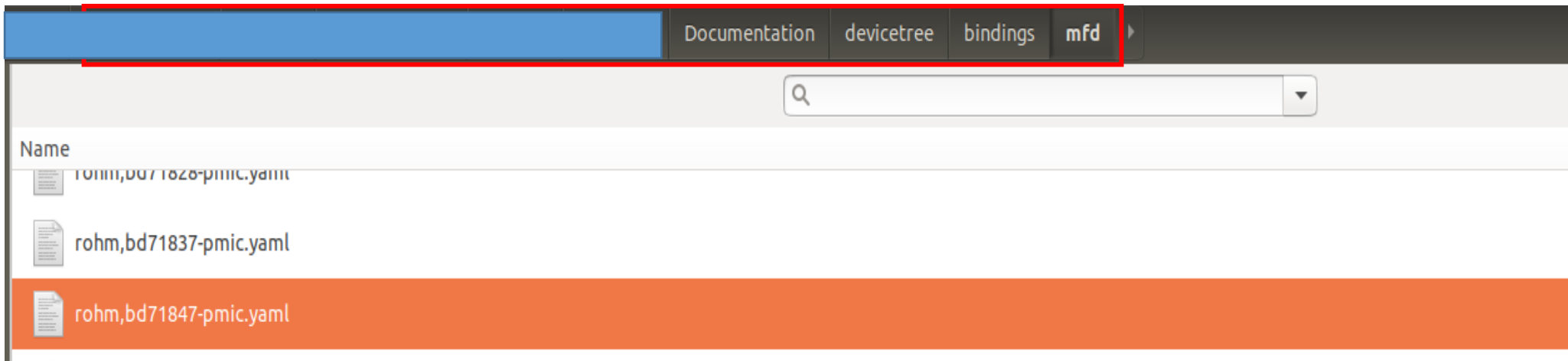
```
/sources/linux-imx$ grep -r -n -P "pmic_nxp" ./
/arch/arm64/boot/dts/freescale/imx8mm-evk.dts:236:    pmic_nxp: pca9450@25 {
/arch/arm64/boot/dts/freescale/imx8mm-ddr4-evk.dts:30:/delete-node/&pmic_nxp;
/arch/arm64/boot/dts/freescale/imx8mm-evk-qca-wifi.dts:14:/delete-node/&pmic_nxp;
/sources/linux-imx$
```

Note 3

```
pmic@4b {  
    compatible = "rohm,bd71847";  
    reg = <0x4b>;  
    pinctrl-0 = <&pinctrl_pmic>;  
    interrupt-parent = <&gpio1>;  
    interrupts = <3 GPIO_ACTIVE_LOW>;  
    rohm,reset-snvs-powered;
```

Check the last item → **Note 3**

Reference the Document inside yocto project



This one is OK

```
pmic@4b {
    compatible = "rohm,bd71847";
    reg = <0x4b>;
    pinctrl-0 = <&pinctrl_pmic>;
    interrupt-parent = <&gpio1>;
    interrupts = <3 GPIO_ACTIVE_LOW>;
    rohm,reset-snvs-powered;
}
```

(1)

```
i2c {
    #address-cells = <1>;
    #size-cells = <0>;
    pmic: pmic@4b {
        compatible = "rohm,bd71847";
        reg = <0x4b>;
        interrupt-parent = <&gpio1>;
        interrupts = <29 IRQ_TYPE_LEVEL_LOW>;
        #clock-cells = <0>;
        clocks = <&osc 0>;
        rohm,reset-snvs-powered;
        rohm,short-press-ms = <10>;
        rohm,long-press-ms = <2000>;
    }
}
```

(1)

(2)

- (1) It shall configured according you board map to which interrupt
- (2) Clocks configured shall mask it and no use or it will hang during booting.
- (3) According the Linux 5.4.47, it only use these two items at imx_v8_defconfig

CONFIG_MFD_ROHM_BD718XX	➔ for BD71837/BD71847 core
CONFIG_REGULATOR_BD718XX	➔ for regulator control
CONFIG_COMMON_CLK_BD718XX	➔ for clock gate control
CONFIG_KEYBOARD_GPIO	➔ for reset induced by short press of power button.

Note 4

When you put these codes to build in you project you have to clean build kernel / u-boot . Then you can build your image smooth.

```
$ bitbake virtual/kernel -c cleansstate -f
Loading cache: 100% |#####|
#####| Time: 0:00:00
Loaded 4948 entries from dependency cache.
Parsing recipes: 100% |#####|
#####| Time: 0:00:01
Parsing of 3342 .bb files complete (3338 cached, 4 parsed). 4952 targets, 283 skipped, 3 masked, 0 errors.
NOTE: Resolving any missing task queue dependencies
```

```
$ bitbake virtual/kernel
Loading cache: 100% |#####|
#####| Time: 0:00:00
Loaded 4948 entries from dependency cache.
Parsing recipes: 100% |#####|
#####| Time: 0:00:01
Parsing of 3342 .bb files complete (3338 cached, 4 parsed). 4952 targets, 283 skipped, 3 masked, 0 errors.
NOTE: Resolving any missing task queue dependencies

Build Configuration:
```

```
$ bitbake imx-image-a100 -c cleansstate -f
```

```
Loading cache: 100% |#####| Time: 0:00:00
Loaded 4948 entries from dependency cache.
Parsing recipes: 100% |#####| Time: 0:00:01
Parsing of 3342 .bb files complete (3338 cached, 4 parsed). 4952 targets, 283 skipped, 3 masked, 0 errors.
NOTE: Resolving any missing task queue dependencies
```

```
$ bitbake imx-image-a100
```

```
Loading cache: 100% |#####| Time: 0:00:00
Loaded 4948 entries from dependency cache.
Parsing recipes: 100% |#####| Time: 0:00:01
Parsing of 3342 .bb files complete (3338 cached, 4 parsed). 4952 targets, 283 skipped, 3 masked, 0 errors.
NOTE: Resolving any missing task queue dependencies
NOTE: Multiple providers are available for runtime linux-firmware-bcm4359-pcie (firmware-nxp-wifi, linux-firmware)
Consider defining a PREFERRED_PROVIDER entry to match linux-firmware-bcm4359-pcie
```