

Chapter 6 Static Magnetic Fields

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6-1 Introduction

- Electric charges at rest: $\nabla \cdot \mathbf{D} = \rho$,
 $\nabla \times \mathbf{E} = 0$.

▪ Constitutive relation: $\mathbf{D} = \epsilon \mathbf{E}$,

▪ Electric force \mathbf{F}_e :
$$\mathbf{F}_e = q \mathbf{E} \quad (\text{N}).$$

- Electric charges in motion:

▪ Magnetic force \mathbf{F}_m :
$$\mathbf{F}_m = q \mathbf{u} \times \mathbf{B} \quad (\text{N}),$$

The force was found in experiments!
Defined as \mathbf{B} : magnetic flux density (Wb/m^2 = Tesla)

- Lorentz's force equation:
$$\mathbf{F} = q(\mathbf{E} + \mathbf{u} \times \mathbf{B}) \quad (\text{N}),$$

6-2 Fundamental Postulates of Magnetostatics in Free Space

- Two postulates for \mathbf{B} in free space:

$$\nabla \cdot \mathbf{B} = 0,$$
$$\nabla \times \mathbf{B} = \mu_0 \mathbf{J}.$$

$\mu_0 = 4\pi \times 10^{-7}$ (H/m), permeability of free space

\mathbf{J} : current density

Permeability is the measure of the ability of a material to support the formation of a magnetic field within itself. Hence, it is the degree of **magnetization** that a material obtains in response to an applied magnetic field.

Chap. 3

$$\nabla \cdot \mathbf{E} = \frac{\rho}{\epsilon_0}$$

$$\nabla \times \mathbf{E} = 0.$$

$$\nabla \cdot (\nabla \times \mathbf{B}) = 0$$



$$\nabla \cdot \mathbf{J} = 0,$$

$$-\frac{\partial \rho}{\partial t}$$

No Magnetic Charge

- Comparison of divergence \mathbf{E} and \mathbf{B} :

$$\nabla \cdot \mathbf{E} = \rho/\epsilon_0 \quad \nabla \cdot \mathbf{B} = 0,$$

→ No magnetic charge

The Law of Conservation of Magnetic Flux

- The integral form of \mathbf{E} :

$$\oint_S \mathbf{E} \cdot d\mathbf{s} = \frac{Q}{\epsilon_0},$$

Q is the source of the total outward electric flux through any closed surface.

$$\nabla \cdot \vec{D} = 0$$

- The integral form of \mathbf{B} :

$$\oint_S \mathbf{B} \cdot d\mathbf{s} = 0,$$

$$\oint_D \vec{B} \cdot d\vec{r} = 0$$

The total outward magnetic flux through any closed surface is zero.

$$\oint \vec{B} \cdot d\vec{S} = 0$$

- **No magnetic flow sources**
- The magnetic flux lines always close upon themselves

The Law of Conservation of Magnetic Flux

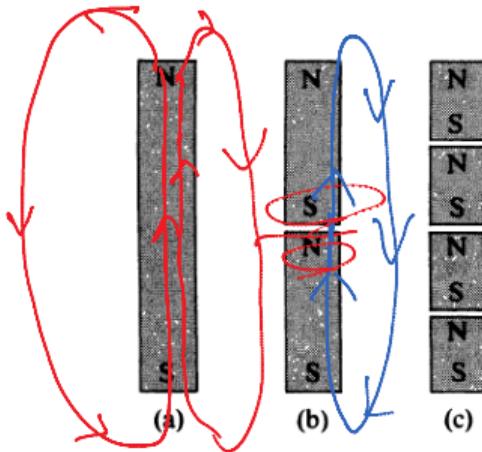
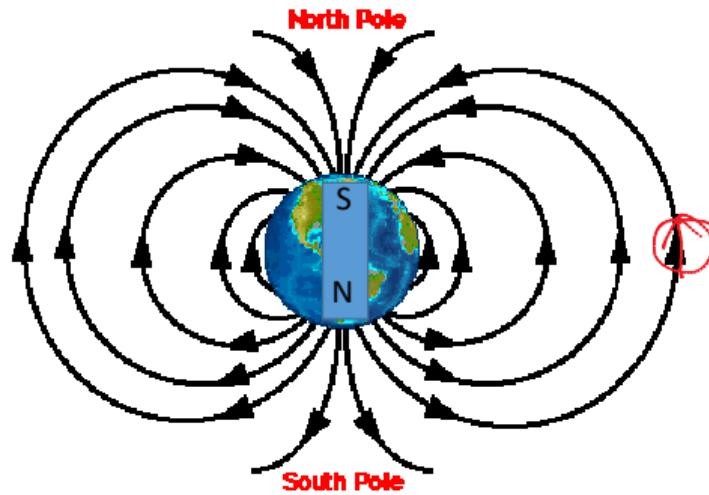


FIGURE 6–1
Successive division of a bar magnet.

The magnetic flux lines follow closed paths from one end of a magnet to the other end outside the magnet and then continue inside the magnet back to the first end.

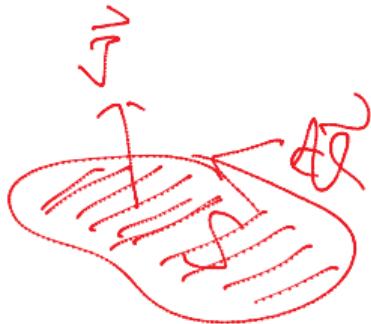
The Earth's Magnetic Field



Ampere's Circuital Law

Chap.3

$$\nabla \cdot \mathbf{E} = \frac{\rho}{\epsilon_0}$$



$$\begin{aligned}\nabla \times \mathbf{B} &= \mu_0 \mathbf{J}, \\ \downarrow & \\ \int_S (\nabla \times \mathbf{B}) \cdot d\mathbf{s} &= \mu_0 \int_S \mathbf{J} \cdot d\mathbf{s} \\ \downarrow & \\ \boxed{\oint_C \mathbf{B} \cdot d\ell} &= \mu_0 I,\end{aligned}$$

C : the contour bounding the surface S
 I : the total current through S

Gauss's law

Ampere's circuital law: the circulation of the magnetic flux density in free space around any closed path is equal to μ_0 times the total current flowing through the surface bounded by the path.

A Summary

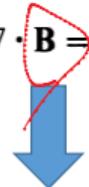
Postulates of Magnetostatics in Free Space	
Differential Form	Integral Form
$\nabla \cdot \mathbf{B} = 0$	$\oint_S \mathbf{B} \cdot d\mathbf{s} = 0$
$\nabla \times \mathbf{B} = \mu_0 \mathbf{J}$	$\oint_C \mathbf{B} \cdot d\ell = \mu_0 I$

$$\nabla \cdot \vec{B} = 0$$
$$\nabla \times \vec{E} = 0$$

6-3 Vector Magnetic Potential

Chap.3

$$\nabla \cdot \mathbf{B} = 0$$



\mathbf{B} is solenoidal
By null identity

$$\mathbf{B} = \nabla \times \mathbf{A} \quad (\text{T})$$

where \mathbf{A} : **vector** magnetic potential (Wb/m)

$$\nabla \times \mathbf{E} = 0$$

$$\mathbf{E} = -\nabla V$$

In magnetostatics: $J \rightarrow \mathbf{A} \rightarrow \mathbf{B}$

In electrostatics: $p \rightarrow V \rightarrow \mathbf{E}$

$$\nabla \cdot \mathbf{A} = ?$$

- To specify a vector, we should specify its curl and divergence.
We have $\boxed{\mathbf{B} = \nabla \times \mathbf{A}} \quad (\text{T})$ How to choose $\nabla \cdot \mathbf{A}$?

$$\nabla \times \mathbf{B} = \mu_0 \mathbf{J}$$



$$\mathbf{B} = \nabla \times \mathbf{A}$$

$$\nabla \times \nabla \times \mathbf{A} = \mu_0 \mathbf{J}.$$

Vector identity:

$$\nabla \times \nabla \times \mathbf{A} = \nabla(\nabla \cdot \mathbf{A}) - \nabla^2 \mathbf{A}$$

$$\nabla^2 \mathbf{A} = \nabla(\nabla \cdot \mathbf{A}) - \nabla \times \nabla \times \mathbf{A}.$$

$$\nabla^2 V = \dots$$

Definition of Laplacian of \mathbf{A}

$$\nabla^2(A_x \hat{\mathbf{a}}_x + A_y \hat{\mathbf{a}}_y + A_z \hat{\mathbf{a}}_z)$$

=

- In Cartesian: $\nabla^2 \mathbf{A} = \mathbf{a}_x \nabla^2 A_x + \mathbf{a}_y \nabla^2 A_y + \mathbf{a}_z \nabla^2 A_z.$
(Similar to Laplacian of V)

- In other coordinates: should use the definition of Laplacian of \mathbf{A}

$$\nabla(\nabla \cdot \mathbf{A}) - \nabla^2 \mathbf{A} = \mu_0 \mathbf{J}.$$

$$\nabla(\nabla \cdot \mathbf{A}) - \nabla^2 \mathbf{A} = \mu_0 \mathbf{J}.$$



To simplify the equation, we choose

$$\boxed{\nabla \cdot \mathbf{A} = 0},$$

Vector's Poisson's equation

$$\boxed{\nabla^2 \mathbf{A} = -\mu_0 \mathbf{J}}.$$

In Cartesian coordinate:

$$\nabla^2 A_x = -\mu_0 J_x,$$

$$\nabla^2 A_y = -\mu_0 J_y,$$

$$\nabla^2 A_z = -\mu_0 J_z.$$

By comparison

Solution:

$$A_x = \frac{\mu_0}{4\pi} \int_{V'} \frac{J_x}{R} dv'.$$



Combine 3 components
↓

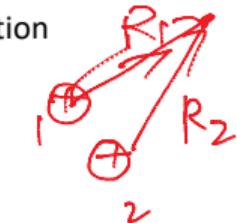
$$\boxed{\mathbf{A} = \frac{\mu_0}{4\pi} \int_{V'} \frac{\mathbf{J}}{R} dv'} \quad (\text{Wb/m}).$$

$$\partial A_x / \partial x + \partial A_y / \partial y + \partial A_z / \partial z$$

Analogy in electrostatics: ✓

Scalar's Poisson's equation

$$\nabla^2 V = -\frac{\rho}{\epsilon_0}$$



Solution:

$$V = \frac{1}{4\pi\epsilon_0} \int_{V'} \frac{\rho}{R} dv'.$$

V (spoke)

R (r')

Review the Analogy

$$\mathbf{A} = \frac{\mu_0}{4\pi} \int_{V'} \frac{\mathbf{J}}{R} dv' \quad (\text{Wb/m}).$$

In magnetostatics: $\mathbf{J} \rightarrow \mathbf{A} \rightarrow \mathbf{B}$
In electrostatics: $\rho \rightarrow V \rightarrow E$

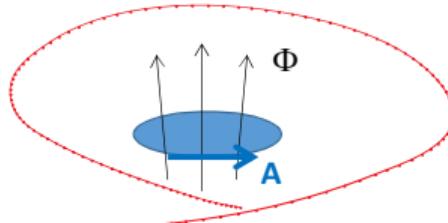
$$V = \frac{1}{4\pi\epsilon_0} \int_{V'} \frac{\rho}{R} dv'.$$

Relation of Magnetic Flux Φ and Magnetic Vector Potential A

The diagram illustrates the relationship between magnetic flux and magnetic vector potential. At the top left, a yellow-shaded area represents a surface S . A red curved arrow labeled "Magnetic flux" points to the equation $\Phi = \int_S \mathbf{B} \cdot d\mathbf{s}$, which is written above the surface. Above the equation, a red handwritten note indicates units of Wb/m^2 . To the right of the surface, another red curved arrow labeled "Magnetic flux density" points to the expression $\mathbf{B} = \nabla \times \mathbf{A}$, which is enclosed in a blue box. A large blue downward-pointing arrow connects the two parts. To the right of the arrow, there is a hand-drawn diagram of a closed loop with arrows indicating a clockwise direction, with a red handwritten label B next to it.

$$\Phi = \int_S (\nabla \times \mathbf{A}) \cdot d\mathbf{s} = \oint_C \mathbf{A} \cdot d\ell \quad (\text{Wb}).$$

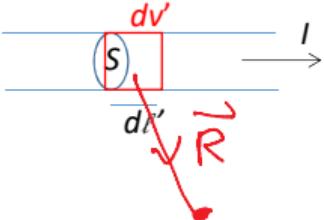
Physical significance of \mathbf{A} : line integral of \mathbf{A} around any closed path = the total Φ passing through the area enclosed by the path



6-4 The Biot-Savart Law and Applications

- The magnetic field due to a current-carrying circuit.
- For a thin wire with cross-sectional area S ($dv' = S d\ell' = \mathbf{S} \bullet d\ell'$), we have

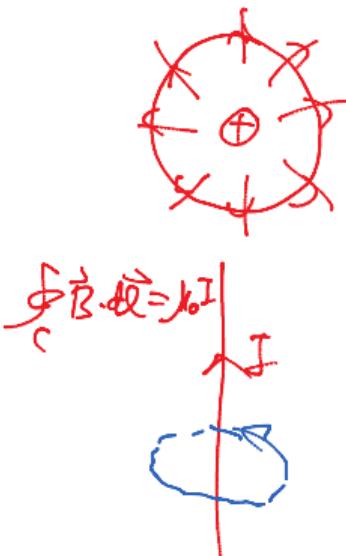
$$\mathbf{J} dv' = JS d\ell' = I d\ell', \quad J: (\text{A/m}^2)$$
$$JS = I$$



$$\mathbf{A} = \frac{\mu_0}{4\pi} \int_{v'} \frac{\mathbf{J}}{R} dv' \quad (\text{Wb/m}).$$

$$\mathbf{A} = \frac{\mu_0 I}{4\pi} \oint_C \frac{d\ell'}{R(d\ell')} \quad (\text{Wb/m}),$$

C is closed because current must flow in a closed path.



$$\mathbf{B} = \nabla \times \mathbf{A}$$



$$\mathbf{A} = \frac{\mu_0 I}{4\pi} \oint_{C'} \frac{d\ell'}{R} \quad (\text{Wb/m}),$$

source: \vec{J}, I
fields: \vec{B}, \vec{A}

$$\begin{aligned}\mathbf{B} = \nabla \times \mathbf{A} &= \nabla \times \left[\frac{\mu_0 I}{4\pi} \oint_{C'} \frac{d\ell'}{R} \right] \\ &= \frac{\mu_0 I}{4\pi} \oint_{C'} \nabla \times \left(\frac{d\ell'}{R} \right).\end{aligned}$$

$$\frac{\partial \mathcal{A}}{\partial x} = 0$$

unprimed curl: to the field coordinate
primed integration: to the source coordinate



$$\nabla \times (f\mathbf{G}) = f\nabla \times \mathbf{G} + (\nabla f) \times \mathbf{G}.$$

with $f = 1/R$ and $\mathbf{G} = d\ell'$,

$$\mathbf{B} = \frac{\mu_0 I}{4\pi} \oint_{C'} \left[\frac{1}{R} \nabla \times d\ell' + \left(\nabla \frac{1}{R} \right) \times d\ell' \right].$$

(1)

(2)

For term (1): primed and unprimed coordinates are independent $\rightarrow 0$

For term (2):

$$\frac{1}{R} = [x - x')^2 + (y - y')^2 + (z - z')^2]^{-1/2}; \quad R \text{ is from source to field}$$

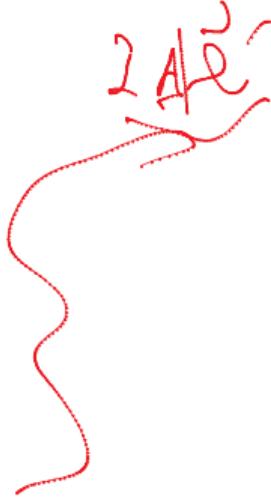
$$\nabla \left(\frac{1}{R} \right) = \mathbf{a}_x \frac{\partial}{\partial x} \left(\frac{1}{R} \right) + \mathbf{a}_y \frac{\partial}{\partial y} \left(\frac{1}{R} \right) + \mathbf{a}_z \frac{\partial}{\partial z} \left(\frac{1}{R} \right)$$

$$= - \frac{\mathbf{a}_x(x - x') + \mathbf{a}_y(y - y') + \mathbf{a}_z(z - z')}{[(x - x')^2 + (y - y')^2 + (z - z')^2]^{3/2}}$$

$$= - \frac{\mathbf{R}}{R^3} = - \mathbf{a}_R \frac{1}{R^2}$$

Quotient rule and chain rule

$$\nabla' \left(\frac{1}{R} \right) = \hat{a}_R \frac{1}{R^2}$$

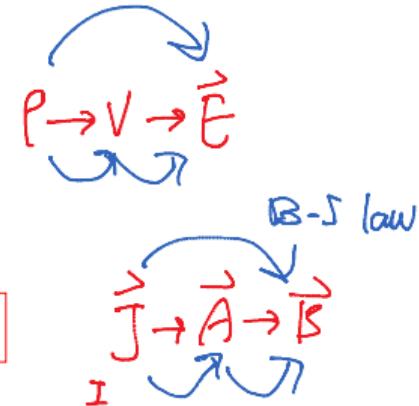


$$\mathbf{B} = \frac{\mu_0 I}{4\pi} \oint_C \left[\frac{1}{R} \nabla \times d\ell' + \left(\nabla \frac{1}{R} \right) \times d\ell' \right].$$



$$\nabla \left(\frac{1}{R} \right) = -\mathbf{a}_R \frac{1}{R^2},$$

$$\mathbf{B} = \frac{\mu_0 I}{4\pi} \oint_C \frac{d\ell' \times \mathbf{a}_R}{R^2} \quad (\text{T}).$$



Biot-Savart law: \mathbf{B} due to a current element $I d\ell'$

Comparison with Ampere's circuital law:

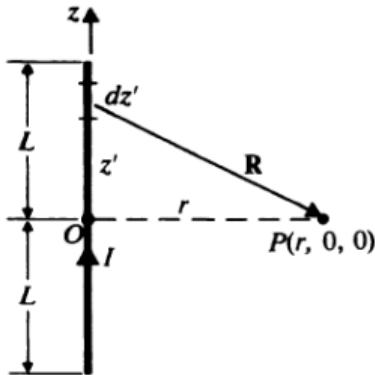
$$\oint_C \mathbf{B} \cdot d\ell = \mu_0 I,$$

Because \mathbf{B} does not have to be constant along C , **Biot-Savart law is more general** to determine \mathbf{B} than Ampere's circuital law (although the former is more difficult in calculation).

$$V = \frac{Q}{4\pi\epsilon_0 R} \rightarrow V = \frac{1}{4\pi\epsilon_0} \int \frac{P d\vec{l}'}{R} \rightarrow \vec{J} d\vec{l}' \rightarrow I d\vec{l}'$$

$$\vec{A} = \frac{\mu_0 I}{4\pi} \int \frac{d\vec{l}'}{R}$$

EXAMPLE 6–4 A direct current I flows in a straight wire of length $2L$. Find the magnetic flux density \mathbf{B} at a point located at a distance r from the wire in the bisecting plane: (a) by determining the vector magnetic potential \mathbf{A} first, and (b) by applying Biot-Savart law.

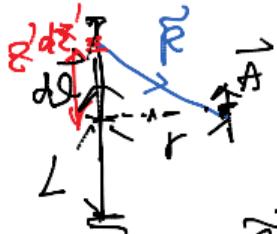


Method 1: $\vec{A} \rightarrow \vec{B}$

Method 2: $I d\vec{l}' \rightarrow \vec{B}$
BS law

FIGURE 6–5
A current-carrying straight wire (Example 6–4).

$$(a) \vec{A} = \frac{\mu_0 I}{4\pi} \int \frac{d\vec{l}'}{R}$$



$$dL' = \hat{a}_z dz'$$

$$R = \sqrt{z'^2 + r^2}$$

$$\vec{A} = \frac{\mu_0 I}{4\pi} \int \frac{\hat{a}_z dz'}{\sqrt{z'^2 + r^2}} = \dots = \hat{a}_z$$

$$\vec{B} = \nabla \times \vec{A} = \hat{a}_r \frac{\partial A_z}{\partial \phi} - r \hat{a}_\phi \frac{\partial A_z}{\partial r} = \dots = \hat{a}_\phi \frac{\mu_0 I L}{2\pi r \sqrt{L^2 + r^2}}$$

$$\nabla \times \vec{A} = \frac{1}{r} \begin{vmatrix} \hat{a}_r & \hat{a}_\phi & \hat{a}_z \\ \frac{\partial}{\partial r} & \frac{\partial}{\partial \phi} & \frac{\partial}{\partial z} \\ 0 & 0 & A_z \end{vmatrix}$$

$$A_z = \hat{a}_z \frac{\mu_0 I}{4\pi} \ln \left(\frac{\sqrt{L^2 + r^2} + L}{\sqrt{L^2 + r^2} - L} \right)$$

$$(b) \quad \vec{B} = \frac{\mu_0 I}{4\pi} \int_C' \frac{d\vec{r}' \times \hat{a}_R}{R^2}$$

$\Rightarrow \vec{B} \perp d\vec{r}', \vec{B} \perp \hat{a}_R$

$$E = \frac{1}{4\pi\epsilon_0} \int \frac{P}{R^2} dv' \hat{a}_R$$

$$\downarrow \\ \vec{J} dv' \times \hat{a}_R$$

$$\downarrow \\ I d\vec{r}' \times \hat{a}_R$$

$$\hat{a}_R = \vec{R}/R$$

$$\vec{R} = (\hat{a}_x r - \hat{a}_y z')$$

$$\frac{\hat{a}_R}{R^2} = \frac{\vec{R}}{R^3}$$

$$\vec{B} = \frac{\mu_0 I}{4\pi} \int_{-L}^L \frac{\hat{a}_z dz' \times (\hat{a}_x r - \hat{a}_y z')}{(z'^2 + r^2)^{3/2}}$$

6-5 The Magnetic Dipole

- Example 6-7:

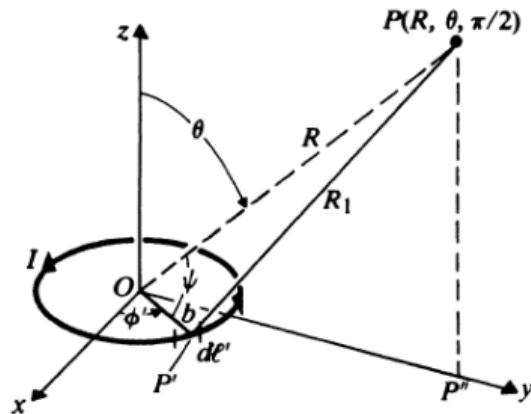


FIGURE 6-8
A small circular loop carrying current I (Example 6-7).

$$\textcircled{A} = \mathbf{a}_\phi \frac{\mu_0 I b^2}{4R^2} \sin \theta.$$

$$\mathbf{B} = \frac{\mu_0 I b^2}{4R^3} (\mathbf{a}_R 2 \cos \theta + \mathbf{a}_\theta \sin \theta),$$

$$V = \dots$$

$$\mathbf{E} = \dots$$

EXAMPLE 6–7 Find the magnetic flux density at a distant point of a small circular loop of radius b that carries current I (a *magnetic dipole*).

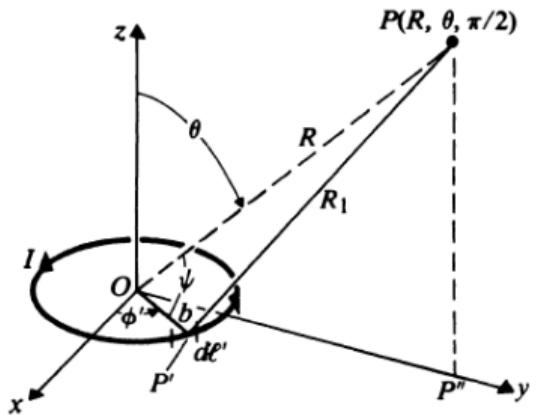
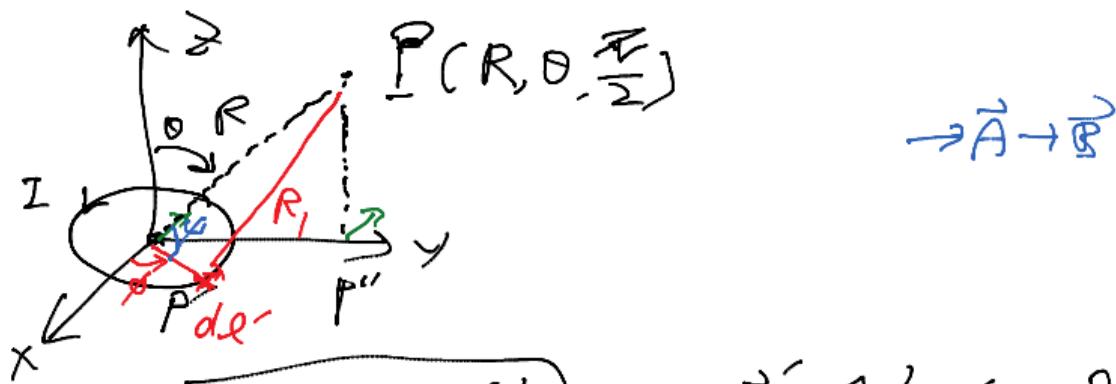


FIGURE 6–8
A small circular loop carrying current I (Example 6–7).



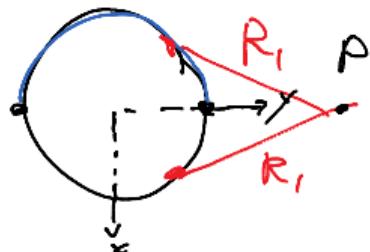
$$1^{\circ} \quad \boxed{\vec{A} = \frac{\mu_0 I}{4\pi} \int \frac{d\vec{l}'}{R}}$$

Integrand.

$$\frac{\cos \phi'}{R_1} : \begin{array}{c} - \\ + \end{array} \begin{array}{c} - \\ + \end{array}$$

top view

$$\frac{\sin \phi'}{R_1} : \begin{array}{c} - \\ + \end{array} \begin{array}{c} + \\ - \end{array}$$



$$d\vec{l}' = \hat{a}_{\phi}' d\ell' = (-\hat{a}_x' \sin \phi' + \hat{a}_y' \cos \phi') b d\phi'$$

$$\vec{A} = \frac{\mu_0 I}{4\pi} \cdot 2 \int_{-\pi/2}^{\pi/2} \frac{-\hat{a}_x' \sin \phi'}{R_1} b d\phi'$$

$$= \hat{a}_\phi \frac{\mu_0 I}{4\pi} 2 \int_{-\pi/2}^{\pi/2} \frac{b \sin \phi'}{R_1} d\phi' \quad \text{①}$$

$\hat{a}_x' \Rightarrow \hat{a}_\phi$
general

$$2^{\circ} \quad \frac{1}{R_1} : R_1^2 = R^2 + b^2 - 2Rb \cos \phi' \leftarrow$$

$R \cos \phi = \text{projection of } \overline{OP} \text{ on } \overline{OP}'$

$= (\text{projection of } \overline{OP} \text{ on } \overline{OP}'') \text{ and}$

$(\angle \text{ of } \overline{OP}'' \text{ on } \overline{OP})$

$$= R \sin \theta \cos(\frac{\pi}{2} - \phi') = R \sin \theta \sin \phi'$$

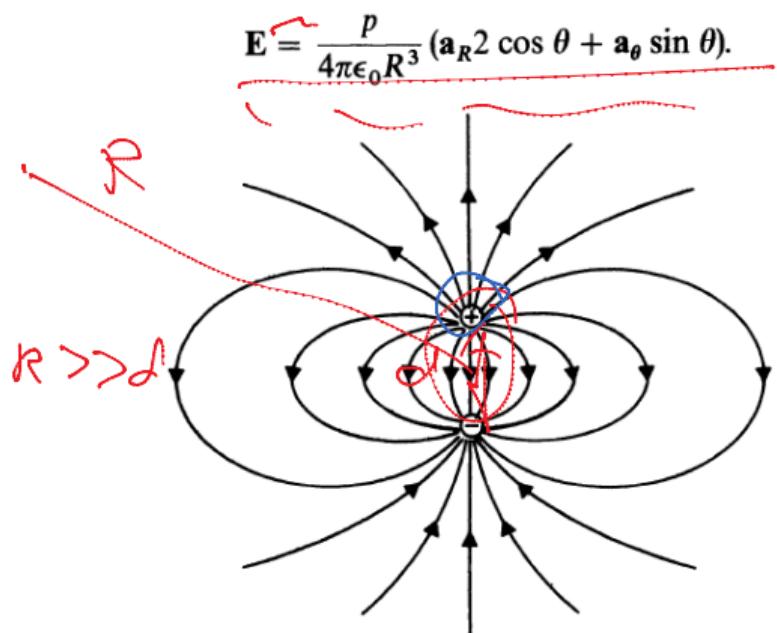
$$\Rightarrow \dots \Rightarrow \frac{1}{R_1} = \frac{1}{R} \left(1 + \frac{b^2}{R^2} - \frac{2b}{R} \sin \theta \sin \phi' \right)^{-\frac{1}{2}}$$

when $R \gg b$ $\frac{1}{R_1} \approx \frac{1}{R} \left(1 - \frac{2b}{R} \sin \theta \sin \phi' \right)^{-\frac{1}{2}}$

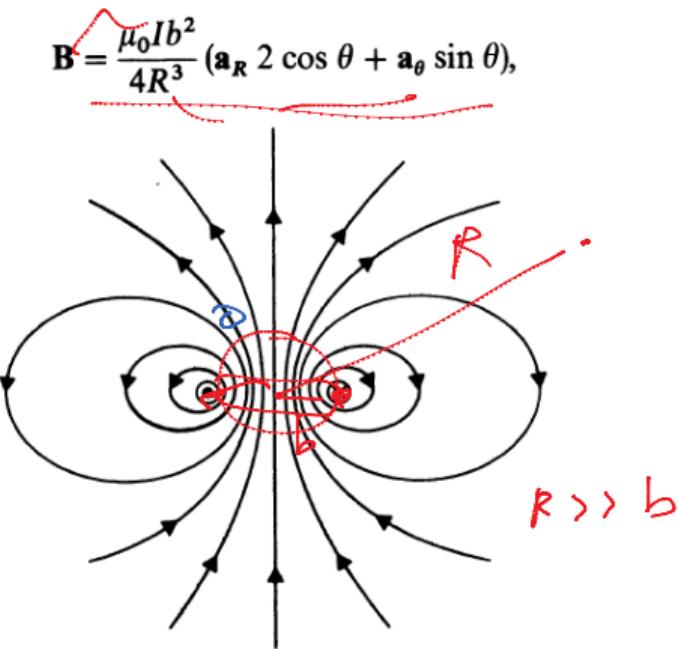
when $R \approx b$ $\frac{1}{R_1} \approx \frac{1}{R} \left(1 + \frac{b}{R} \sin \theta \sin \phi' \right) \xrightarrow{\text{---}} ②$

$$\textcircled{2} \quad m \quad \textcircled{1} \Rightarrow \vec{A} = \hat{\alpha}_\phi \frac{\mu_0 I b}{2\pi} \int_{-\pi/2}^{\pi/2} \left(1 + \frac{b}{R} \right) r \cos \theta \sin \phi' d\phi' =$$

$$3^\circ \quad \vec{B} = \nabla \times \vec{A} = \dots = \frac{\mu_0 I b^2}{4R^3} \left(\hat{\alpha}_R 2 \cos \theta + \hat{\alpha}_0 \sin \theta \right) = \hat{\alpha}_\phi \frac{\mu_0 I b^2}{4R^2} \sin \theta$$



(a) Electric dipole.



(b) Magnetic dipole.

FIGURE 6-9

Electric field lines of an electric dipole and magnetic flux lines of a magnetic dipole.

- Difference: \mathbf{E} terminated on the charges; \mathbf{B} continuous
- Fields (\mathbf{E} and \mathbf{B}) are similar at far fields

$$\mathbf{A} = \mathbf{a}_\phi \frac{\mu_0 I b^2}{4R^2} \sin \theta.$$

$\hat{\mathbf{a}}_z$ $\hat{\mathbf{a}}_R$

$$\mathbf{A} = \mathbf{a}_\phi \frac{\mu_0 I b^2}{4\pi R^2} \sin \theta$$

$$\mathbf{a}_z \times \mathbf{a}_R = \mathbf{a}_\phi \sin \theta$$

$$\mathbf{A} = \frac{\mu_0 m \times \mathbf{a}_R}{4\pi R^2} \quad (\text{Wb/m}),$$

where $m = \mathbf{a}_z I \pi b^2 = \mathbf{a}_z IS = \mathbf{a}_z m \quad (\text{A} \cdot \text{m}^2)$

Defined as **magnetic dipole moment**

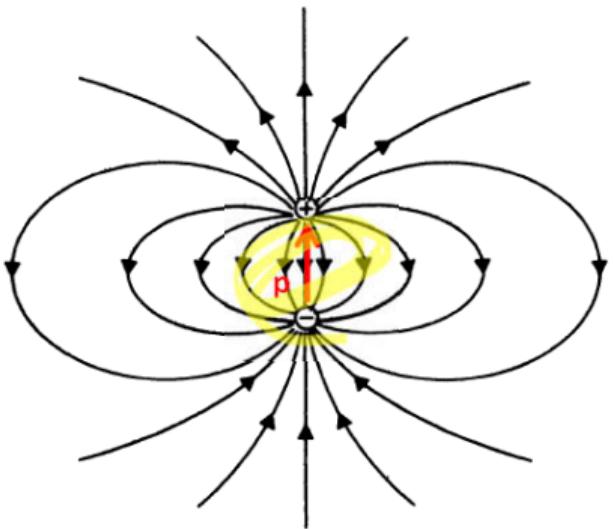
$$\mathbf{B} = \frac{\mu_0 I b^2}{4R^3} (\mathbf{a}_R 2 \cos \theta + \mathbf{a}_\theta \sin \theta),$$



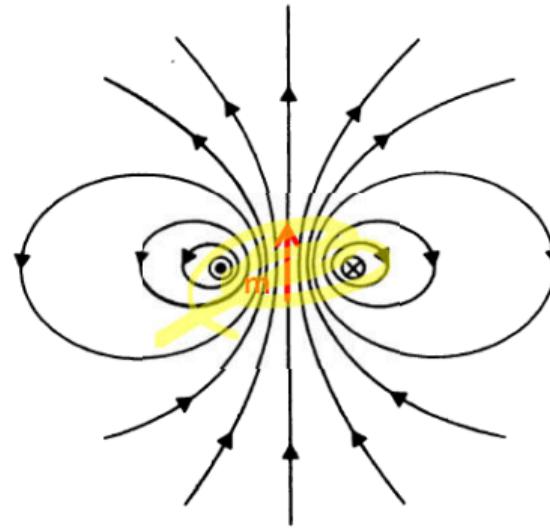
$$\mathbf{B} = \frac{\mu_0 m}{4R^3} (\mathbf{a}_R 2 \cos \theta + \mathbf{a}_\theta \sin \theta) \quad (\text{T}).$$

$$\mathbf{p} = q\mathbf{d}$$

Electric dipole moment



(a) Electric dipole.



(b) Magnetic dipole.

Electric dipole moment \mathbf{p}

Magnetic dipole moment \mathbf{m}

$$\mathbf{p} \rightarrow \mathbf{m}$$

$$1/\epsilon_0 \rightarrow \mu_0$$

$$\bullet \rightarrow \times$$

$$V = \frac{\mathbf{p} \cdot \mathbf{a}_R}{4\pi\epsilon_0 R^2} \quad (\text{V}),$$



Right-hand rule: \mathbf{m} along thumb and
direction of current along fingers

$$\mathbf{A} = \frac{\mu_0 \mathbf{m} \times \mathbf{a}_R}{4\pi R^2} \quad (\text{Wb/m}),$$

We call a small current-carrying loop a **magnetic dipole**

6-5.1 Scalar Magnetic Potential

$$\nabla \times \mathbf{B} = \mu_0 \mathbf{J}$$

For a region $\mathbf{J} = 0$

$$\nabla \times \mathbf{B} = 0$$

By null identity

$$\mathbf{B} = -\mu_0 \nabla V_m,$$

V_m : scalar magnetic potential

$$\nabla \times \mathbf{E} = 0$$

$$\mathbf{E} = -\nabla V$$

Analogy	
V_m	V
\mathbf{B}/μ_0	\mathbf{E}

Analogous to electric potential

$$\mathbf{E} = -\nabla V$$

$$V_2 - V_1 = - \int_{P_1}^{P_2} \mathbf{E} \cdot d\ell \quad (\text{V}).$$

\mathbf{E}

$$k = 1/(4\pi\epsilon_0)$$

$$V = \frac{1}{4\pi\epsilon_0} \int_{V'} \frac{\rho}{R} dv' \quad (\text{V}).$$



$$V_m = \frac{1}{4\pi} \int_{V'} \frac{\rho_m}{R} dv' \quad (\text{A}).$$

No μ_0 in V_m

$$\mathbf{B} = -\mu_0 \nabla V_m,$$

$$V_{m2} - V_{m1} = - \int_{P_1}^{P_2} \frac{1}{\mu_0} \mathbf{B} \cdot d\ell.$$

\mathbf{B}/μ_0

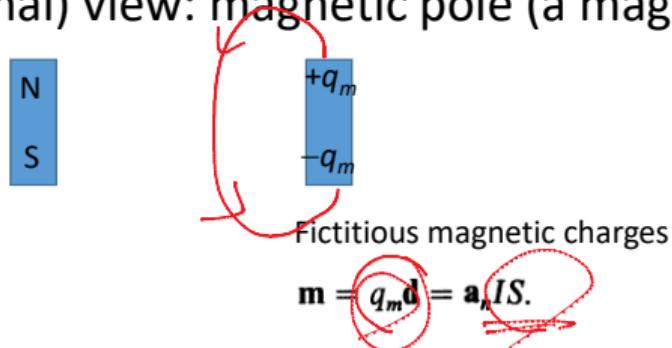
$$k = (\mu_0/(4\pi)) / \mu_0$$

Fictitious magnetic charges: μ_m

1. A mathematical (not physical) model
2. Helpful in discussion of magnetostatics from electrostatics

Magnetic Source

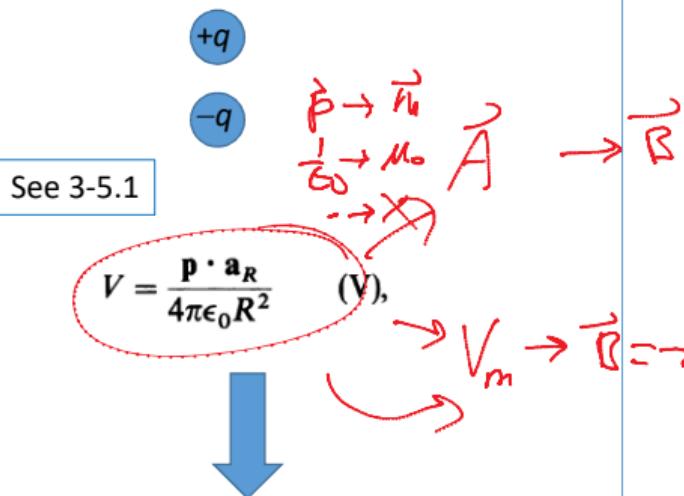
- Macroscopic (traditional) view: magnetic pole (a magnetic dipole)



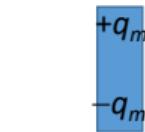
- Microscopic view: circulating atomic current

Potential due to a dipole

Electric dipole



Magnetic dipole



$$V_m = \frac{\mathbf{m} \cdot \mathbf{a}_R}{4\pi R^2} \quad (\text{A}). \quad \boxed{\text{No } \mu_0 \text{ in } V_m}$$

$$\boxed{\mathbf{B} = -\mu_0 \nabla V_m},$$

$$\boxed{\mathbf{B} = \frac{\mu_0 m}{4\pi R^3} (\mathbf{a}_R 2 \cos \theta + \mathbf{a}_\theta \sin \theta) \quad (\text{T})}.$$

Same as in Example 6-7

Electric potential

$$V = \frac{\mathbf{p} \cdot \mathbf{a}_R}{4\pi\epsilon_0 R^2} \quad (\text{V}),$$

$$\nabla \times \mathbf{E} = 0.$$

$\mathbf{J} = 0$

Fictitious magnetic charge and
magnetic scalar potential

$$V_m = \frac{\mathbf{m} \cdot \mathbf{a}_R}{4\pi R^2} \quad (\text{A}).$$

$$\nabla \times \mathbf{B} = 0.$$

V_m holds at any points
with no currents

\mathbf{B} is conservative

$\mathbf{J} \neq 0$

Circulating current and
magnetic vector potential

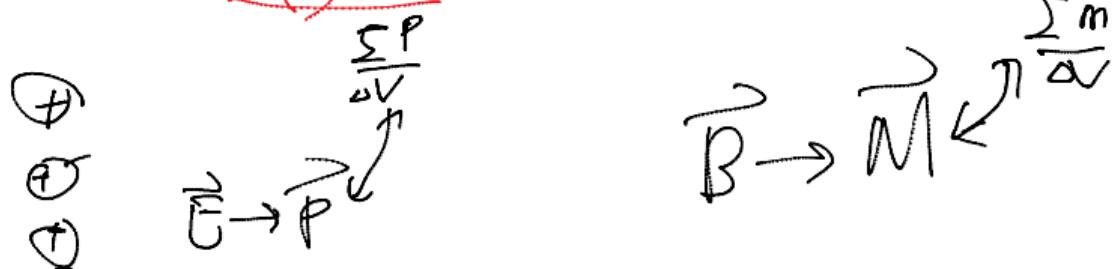
$$\mathbf{A} = \frac{\mu_0 \mathbf{m} \times \mathbf{a}_R}{4\pi R^2} \quad (\text{Wb/m}),$$

$$\nabla \times \mathbf{B} = \mu_0 \mathbf{J}.$$

\mathbf{B} is nonconservative

6-6 Magnetization and Equivalent Current Densities

- Microscopic viewpoint: orbiting electrons → atomic currents → magnetic dipoles \mathbf{m}
- Without external \mathbf{B} : random orientation of magnetic dipoles → no net magnetic dipole moment, $\sum \mathbf{m} = 0$
- With external \mathbf{B} : alignment of magnetic dipoles → induced magnetic dipole moment $\mathbf{m} \neq 0$



Let \mathbf{m}_k : magnetic dipole moment of an atom

Define magnetization vector \mathbf{M}

N , #

n : number density
 $n\Delta v = N$: total #

$$\mathbf{M} = \lim_{\Delta v \rightarrow 0} \frac{\sum_{k=1}^N \mathbf{m}_k}{\Delta v} \quad (\text{A/m}),$$

↓
 \mathbf{M} : density of total
magnetic dipoles

$$d\mathbf{m} = \mathbf{M} dv'$$

$$\mathbf{A} = \frac{\mu_0 \mathbf{m} \times \mathbf{a}_R}{4\pi R^2} \quad (\text{Wb/m}),$$

$$\downarrow \quad d\mathbf{m} = \mathbf{M} dv'$$

$$d\mathbf{A} = \frac{\mu_0 \mathbf{M} \times \mathbf{a}_R}{4\pi R^2} dv'.$$

Recall polarization vector \mathbf{P}

$$\vec{P} = \frac{\partial}{\partial}$$

$$d\vec{p} = \vec{P} dv'$$

$$V = \frac{\mathbf{p} \cdot \mathbf{a}_R}{4\pi\epsilon_0 R^2} \quad (\text{V}),$$

$$\nabla' \left(\frac{1}{R} \right) = \frac{\mathbf{a}_R}{R^2}. \quad \text{R: source to field}$$

$$d\mathbf{A} = \frac{\mu_0}{4\pi} \mathbf{M} \times \nabla' \left(\frac{1}{R} \right) dv'.$$



$$\mathbf{A} = \int_{V'} d\mathbf{A} = \frac{\mu_0}{4\pi} \int_{V'} \mathbf{M} \times \nabla' \left(\frac{1}{R} \right) dv',$$

By using the vector identity

$$\mathbf{M} \times \nabla' \left(\frac{1}{R} \right) = \frac{1}{R} \nabla' \times \mathbf{M} - \nabla' \times \left(\frac{\mathbf{M}}{R} \right)$$

$$\mathbf{A} = \frac{\mu_0}{4\pi} \int_{V'} \frac{\nabla' \times \mathbf{M}}{R} dv' - \underline{\frac{\mu_0}{4\pi} \int_{V'} \nabla' \times \left(\frac{\mathbf{M}}{R} \right) dv'}$$

By using the vector identity (Prob. 6-20)

$$\int_{V'} \nabla' \times \mathbf{F} dv' = - \oint_{S'} \mathbf{F} \times \underline{ds'},$$

$$\mathbf{A} = \frac{\mu_0}{4\pi} \int_{V'} \frac{\nabla' \times \mathbf{M}}{R} dv' + \underline{\frac{\mu_0}{4\pi} \oint_{S'} \frac{\mathbf{M} \times \mathbf{a}'}{R} ds'}$$

See section 3-7.1

$$V = \frac{1}{4\pi\epsilon_0} \int_{V'} \mathbf{P} \cdot \nabla' \left(\frac{1}{R} \right) dv'.$$

$$\mathbf{A} = \frac{\mu_0}{4\pi} \int_{V'} \frac{\mathbf{v}' \times \mathbf{M}}{R} dv' + \frac{\mu_0}{4\pi} \oint_{S'} \frac{\mathbf{M} \times \mathbf{a}_n}{R} ds',$$

Comparisons with

$$\boxed{\mathbf{A} = \frac{\mu_0}{4\pi} \int_{V'} \frac{\mathbf{J}}{R} dv'}$$

$\frac{A}{m} \approx m^2$

$A \cdot m$

$\boxed{\mathbf{J}_m = \nabla \times \mathbf{M} \quad (A/m^2)}$

$\boxed{\mathbf{J}_{ms} = \mathbf{M} \times \mathbf{a}_n \quad (A/m)}$

Prime is omitted for simplicity

See section 3-7.1

$$\rho_p = -\nabla \cdot \mathbf{P}$$

$$\rho_{ps} = \mathbf{P} \cdot \mathbf{a}_n$$

- For a given \mathbf{M}
- Find equivalent **magnetization current densities** \mathbf{J}_m and \mathbf{J}_{ms}
 - \mathbf{A}
 - $\mathbf{B} = \nabla \times \mathbf{A}$
- $\tilde{\mathbf{M}} \rightarrow \tilde{\mathbf{J}}_h, \tilde{\mathbf{J}}_{ms}, \rightarrow \tilde{\mathbf{A}} \rightarrow \tilde{\mathbf{B}}$



Magnetization \mathbf{M}

homogeneous

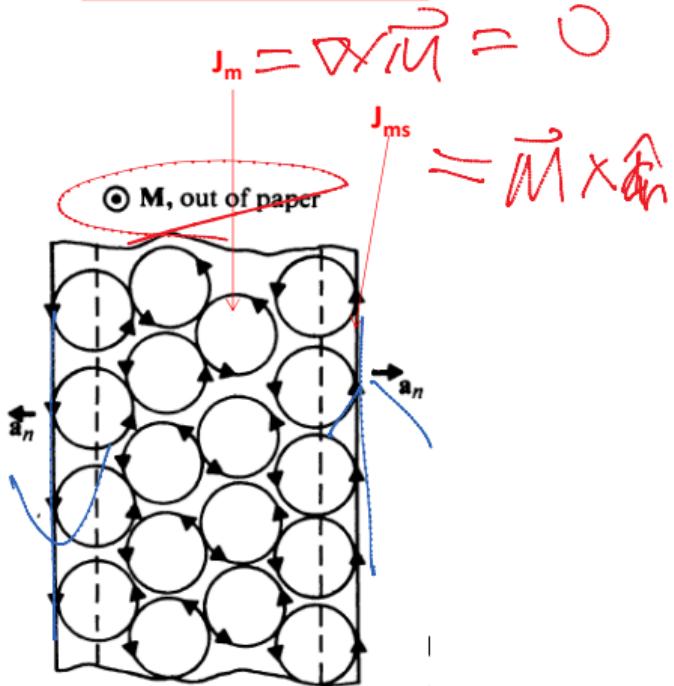


FIGURE 6-10
A cross section of a magnetized material.

Polarization \mathbf{P}

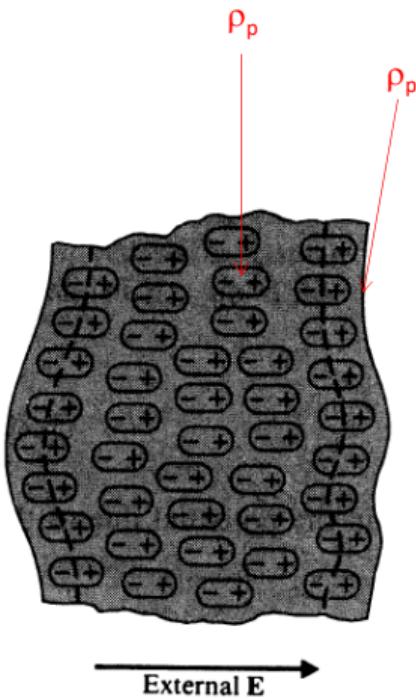
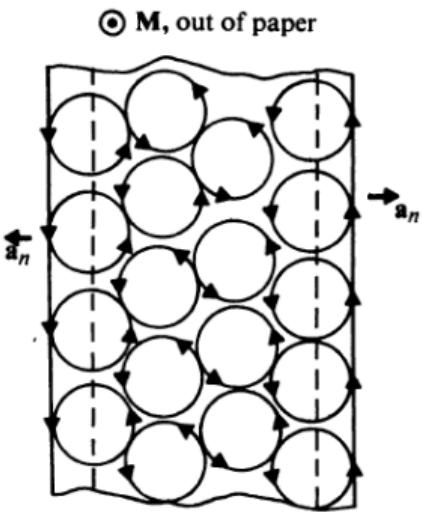


FIGURE 3-20
A cross section of a polarized dielectric medium.



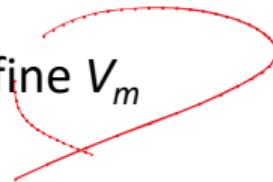
$$\mathbf{J}_m = \nabla \times \mathbf{M} \quad (\text{A/m}^2)$$

$$\mathbf{J}_{ms} = \mathbf{M} \times \mathbf{a}_n \quad (\text{A/m}).$$

- Check directions of \mathbf{J}_{ms}
- If \mathbf{M} is uniform inside \rightarrow currents inside cancel each other $\rightarrow \mathbf{J}_m = 0$
(i.e., $\nabla \times (\text{constant}) = 0$)

6-6.1 Equivalent Magnetization Charge Densities

- In a current-free region, we may define V_m
- \mathbf{B} can be found by $\mathbf{B} = -\mu_0 \nabla V_m$,



$$V_m = \frac{\mathbf{m} \cdot \mathbf{a}_R}{4\pi R^2} \quad (\text{A}).$$



$$d\mathbf{m} = \mathbf{M} dv'$$

$$dV_m = \frac{\mathbf{M} \cdot \mathbf{a}_R}{4\pi R^2} dv'$$



P_m
 ρ_{ms}

$$\vec{A} = \vec{m}$$

$$\downarrow \quad d\vec{m} =$$

$$\vec{J}_m = \nabla \times \vec{m}$$

$$\vec{J}_{ms} = \vec{m} \times \hat{a}_R$$



integration

$$V_m = \frac{1}{4\pi} \int_{V'} \frac{\mathbf{M} \cdot \mathbf{a}_R}{R^2} dv'.$$

$$V = \frac{1}{4\pi\epsilon_0} \int_{V'} \frac{\mathbf{P} \cdot \mathbf{a}_R}{R^2} dv',$$

Following similar steps
as in section 3-7.1

$$V_m = \frac{1}{4\pi} \oint_{S'} \frac{\mathbf{M} \cdot \mathbf{a}'_n}{R} ds' + \frac{1}{4\pi} \int_{V'} \frac{-(\nabla' \cdot \mathbf{M})}{R} dv',$$

A/m A/m^2

$$\rho_m \cdot A/m^2$$

$$\boxed{\rho_{ms} = \mathbf{M} \cdot \mathbf{a}_n \quad (\text{A/m})}$$

$$\boxed{\rho_m = -\nabla \cdot \mathbf{M} \quad (\text{A/m}^2).}$$

$$\overrightarrow{M} \leftarrow \overrightarrow{P}$$

$$V = \frac{1}{4\pi\epsilon_0} \oint_{S'} \frac{\mathbf{P} \cdot \mathbf{a}'_n}{R} ds' + \frac{1}{4\pi\epsilon_0} \int_{V'} \frac{(-\nabla' \cdot \mathbf{P})}{R} dv',$$

$$\boxed{\rho_{ps} = \mathbf{P} \cdot \mathbf{a}_n}$$

$$\boxed{\rho_p = -\nabla \cdot \mathbf{P}.}$$

- A **polarized dielectric** may be replaced by an equivalent ρ_p and ρ_{ps}

Polarization charge density

$$\rho_{ps} = \mathbf{P} \cdot \mathbf{a}_n$$

$$\rho_p = -\nabla \cdot \mathbf{P}.$$

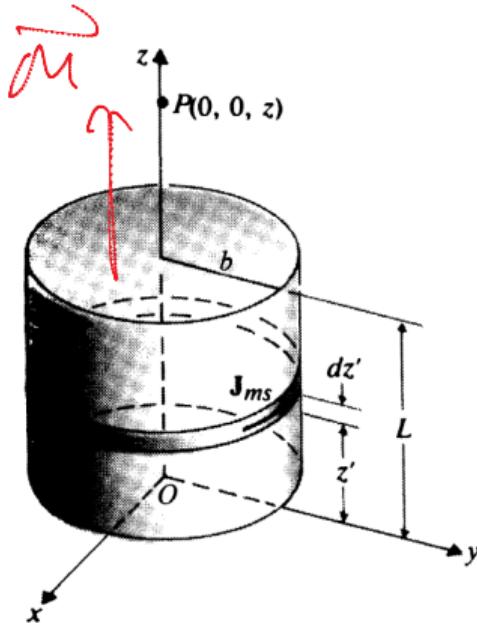
- A **magnetized body** may be replaced by an equivalent ρ_m and ρ_{ms}

Magnetization charge density

$$\rho_{ms} = \mathbf{M} \cdot \mathbf{a}_n \quad (\text{A/m})$$

$$\rho_m = -\nabla \cdot \mathbf{M} \quad (\text{A/m}^2).$$

EXAMPLE 6–8 Determine the magnetic flux density on the axis of a uniformly magnetized circular cylinder of a magnetic material. The cylinder has a radius b , length L , and axial magnetization $\mathbf{M} = \mathbf{a}_z M_0$.



Question: B on z axis?

Methods:

- (1) Calculate J_m and J_{ms}
- (2) \mathbf{B} due to \mathbf{J}

$$\text{M} \rightarrow \begin{matrix} \overrightarrow{J_m} \\ \overrightarrow{J_{ms}} \end{matrix} \rightarrow \vec{A} \rightarrow \vec{B}$$

FIGURE 6–11
A uniformly magnetized circular cylinder (Example 6–8).

$$1^{\circ} \quad \vec{J}_m = \vec{B} \times \vec{M} = 0$$

$$\underline{\vec{J}_{ms}} = \vec{B} \times \hat{a}_n = (\alpha_z M_0) \times (\hat{a}_r) \rightarrow = \hat{a}_\phi M_0$$

side surface

$$2^{\circ} \quad d\vec{B} = \hat{a}_z \frac{M_0 dI' b^2}{2(z^2 + b^2)^{3/2}} J_{ms} dz' = M_0 dz'$$

z : distance between source and field

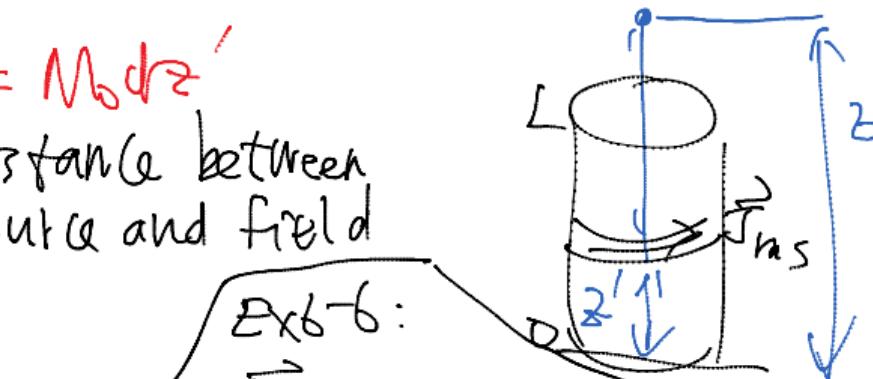
$$\vec{B} = \int d\vec{B} = \hat{a}_z \int_0^L \frac{\mu_0 M_0 b^2}{2((z-z')^2 + b^2)^{3/2}} dz'$$

$$= \dots = \dots$$

Ex-6:

\vec{B} on axis due to a litular loop current:

$$\vec{B} = \hat{a}_z \frac{\mu_0 I b^2}{2(z^2 + b^2)^{3/2}}$$



6-7 Magnetic Field Intensity and Relative Permeability

- Review: External \mathbf{E}_{ext} applied to a dielectric material → induced dipole moments inside the dielectric material (and thus, $\mathbf{E}_{\text{induced}}$)

→ \mathbf{E} inside the dielectric $\mathbf{E}_{\text{total}} = \mathbf{E}_{\text{ext}} + \mathbf{E}_{\text{induced}}$

$$\nabla \cdot \mathbf{E} = \frac{1}{\epsilon_0} (\rho + \rho_p).$$

ρ_p

$\nabla \cdot \vec{E} = \frac{\rho}{\epsilon_0}$ \Rightarrow $\nabla \cdot \vec{D} = \rho$

In dielectrics, we consider ρ_p

Magnetic Side

- External \mathbf{B}_{ext} applied to a **magnetic** material → induced dipole moments inside the **magnetic** material (and thus, $\mathbf{B}_{\text{induced}}$)

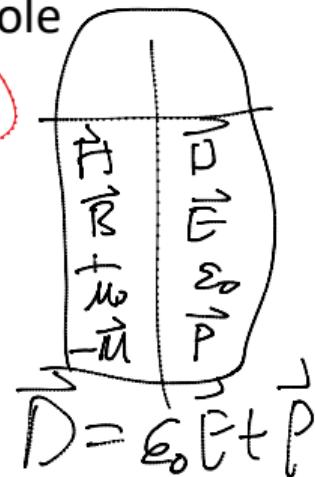
→ \mathbf{B} inside the magnetic $\mathbf{B}_{\text{total}} = \mathbf{B}_{\text{ext}} + \mathbf{B}_{\text{induced}}$

→ $\frac{1}{\mu_0} \nabla \times \mathbf{B} = \mathbf{J} + \mathbf{J}_m = \mathbf{J} + \nabla \times \mathbf{M}$

$$\nabla \times \left(\frac{\mathbf{B}}{\mu_0} - \mathbf{M} \right) = \mathbf{J}.$$

Defined as \mathbf{H} : magnetic field intensity

$$\mathbf{H} = \frac{\mathbf{B}}{\mu_0} - \mathbf{M} \quad (\text{A/m}).$$



$$\nabla \times \left(\frac{\mathbf{B}}{\mu_0} - \mathbf{M} \right) = \mathbf{J}.$$

$$\mathbf{H} = \frac{\mathbf{B}}{\mu_0} - \mathbf{M} \quad (\text{A/m}).$$



$$\nabla \times \mathbf{H} = \mathbf{J} \quad (\text{A/m}^2),$$

\mathbf{J} : volume density of **free** current

$$\nabla \cdot (\epsilon_0 \mathbf{E} + \mathbf{P}) = \rho.$$

$$\mathbf{D} = \epsilon_0 \mathbf{E} + \mathbf{P} \quad (\text{C/m}^2).$$



$$\nabla \cdot \mathbf{D} = \rho \quad (\text{C/m}^3),$$

ρ : volume density
of **free** charges

$$\nabla \times \mathbf{H} = \mathbf{J} \quad (\text{A/m}^2),$$

$$\nabla \cdot \mathbf{D} = \rho \quad (\text{C/m}^3),$$



integration

$$\int_S (\nabla \times \mathbf{H}) \cdot d\mathbf{s} = \int_S \mathbf{J} \cdot d\mathbf{s}$$



Stoke's theorem

$$\oint_C \mathbf{H} \cdot d\ell = I \quad (\text{A}),$$

C : the contour bounding the surface S

Another form of Ampere's circuital law: the circulation of the magnetic field intensity around any closed path is equal to the free current flowing through the surface bounded by the path.

$$\int_V \nabla \cdot \mathbf{D} dv = \int_V \rho dv$$

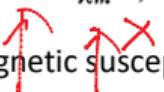
$$\oint_S \mathbf{D} \cdot d\mathbf{s} = Q \quad (\text{C}).$$

Another form of Gauss's law: ...

If the magnetic properties of the medium is *linear* and *isotropic*, then
 $\mathbf{M} \sim \mathbf{H}$

$$\mathbf{M} = \chi_m \mathbf{H},$$

χ_m : magnetic susceptibility



$$\mathbf{H} = \frac{\mathbf{B}}{\mu_0} - \mathbf{M} \quad (\text{A/m}).$$



$$\mathbf{M} = \chi_m \mathbf{H},$$

$$\begin{aligned}\mathbf{B} &= \mu_0(1 + \chi_m)\mathbf{H} \\ &= \mu_0\mu_r \mathbf{H} = \mu \mathbf{H} \quad (\text{Wb/m}^2)\end{aligned}$$

$$\mathbf{H} = \frac{\mathbf{B}}{\mu}$$

$$\mathbf{P} = \epsilon_0 \chi_e \mathbf{E},$$

τ \propto



$$\begin{array}{c} \mathbf{H} \\ \mathbf{B} \\ \perp \end{array} \quad \begin{array}{c} \mathbf{D} \\ \mathbf{E} \\ \perp \end{array}$$

μ

$$\begin{aligned}\mathbf{D} &= \epsilon_0(1 + \chi_e)\mathbf{E} \\ &= \epsilon_0\epsilon_r \mathbf{E} = \epsilon \mathbf{E} \quad (\text{C/m}^2),\end{aligned}$$

$$\vec{D} = \epsilon \vec{E}$$

$$\begin{aligned}\mathbf{B} &= \mu_0(1 + \chi_m)\mathbf{H} \\ &= \mu_0\mu_r\mathbf{H} = \mu\mathbf{H} \quad (\text{Wb/m}^2)\end{aligned}$$

$$\begin{aligned}\mathbf{D} &= \epsilon_0(1 + \chi_e)\mathbf{E} \\ &= \epsilon_0\epsilon_r\mathbf{E} = \epsilon\mathbf{E} \quad (\text{C/m}^2),\end{aligned}$$

Or

$$\mathbf{H} = \frac{1}{\mu} \mathbf{B} \quad (\text{A/m}),$$

where $\mu_r = 1 + \chi_m = \frac{\mu}{\mu_0}$

μ : permeability

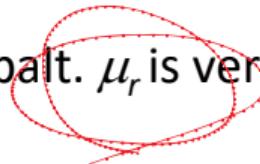
μ_r : relative permeability

$$\epsilon_r = 1 + \chi_e = \frac{\epsilon}{\epsilon_0}$$

For a simple medium (linear, isotropic, homogeneous), χ_m and μ_r are constants.

Relative permeability μ_r

- Ferromagnetic materials: iron, nickel, and cobalt. μ_r is very large (i.e., easy to be magnetized)



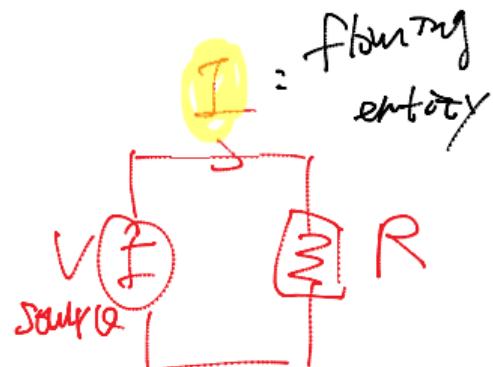
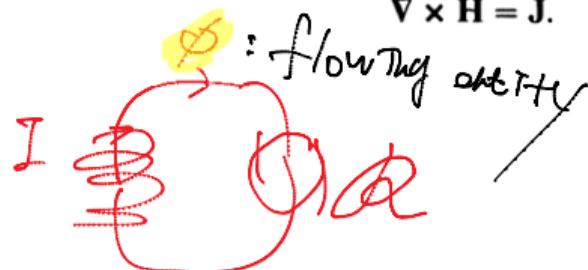
Analogy between electrostatics and magnetostatics

Electrostatics	Magnetostatics
\mathbf{E}	\mathbf{B}
\mathbf{D}	\mathbf{H}
ϵ	$\frac{1}{\mu}$
\mathbf{P}	$-\mathbf{M}$
ρ	\mathbf{J}
V	\mathbf{A}
\vec{x}	\vec{x}

6-8 Magnetic Circuits

z

- Magnetic circuits: transformers, generators, motors, relays, magnetic recording devices, and so on.
- Electric circuits: to find V (and E) and I
Magnetic circuits: to find I (and H) and Φ
- Analysis of magnetic circuits: $\nabla \cdot \mathbf{B} = 0$,
 $\nabla \times \mathbf{H} = \mathbf{J}$.



Magnetomotive Force (mmf)

- Analogous to electromotive force (emf)
- Not a force in Newtons, but in ampere (A)

$$\oint_c \mathbf{H} \cdot d\ell = \oint_c (A),$$



For N turns (see Example 6-10)

$$\oint_c \mathbf{H} \cdot d\ell = NI = \overbrace{mmf}^m$$

A toroidal core with N turns of wires wound

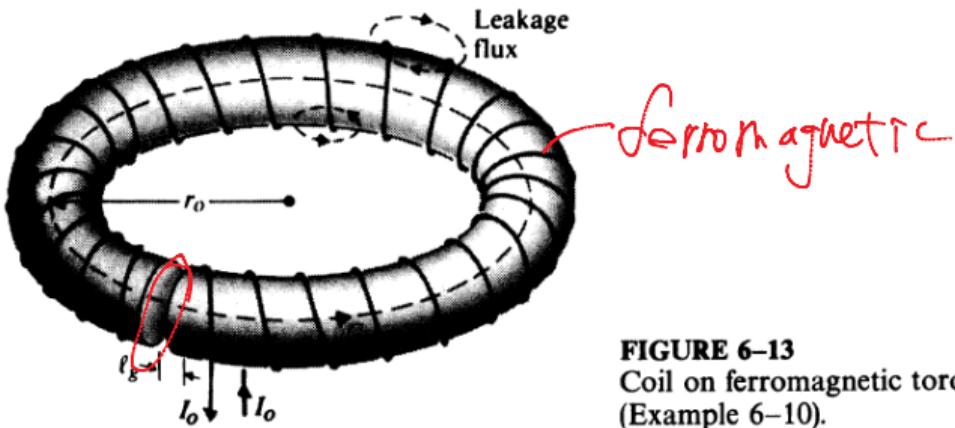


FIGURE 6–13
Coil on ferromagnetic toroid with air gap
(Example 6–10).

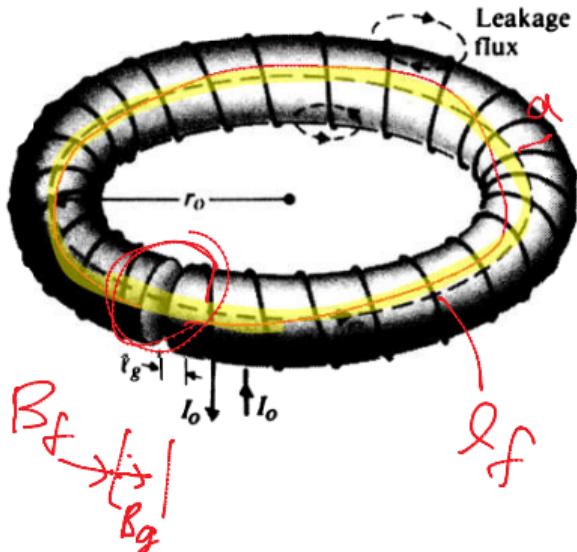
In the ferromagnetic core

$$\left. \begin{aligned} \mathbf{B}_f &= \mathbf{a}_\phi \frac{\mu_0 \mu N I_o}{\mu_0 (2\pi r_o - \ell_g) + \mu \ell_g}. \\ \mathbf{H}_f &= \mathbf{a}_\phi \frac{\mu_0 N I_o}{\mu_0 (2\pi r_o - \ell_g) + \mu \ell_g}. \end{aligned} \right\}$$

In the air gap

$$\mathbf{H}_g = \mathbf{a}_\phi \frac{\mu N I_o}{\mu_0 (2\pi r_o - \ell_g) + \mu \ell_g}.$$

EXAMPLE 6–10 Assume that N turns of wire are wound around a toroidal core of a ferromagnetic material with permeability μ . The core has a mean radius r_o , a circular cross section of radius a ($a \ll r_o$), and a narrow air gap of length ℓ_g , as shown in Fig. 6–13. A steady current I_o flows in the wire. Determine (a) the magnetic flux density, B_f , in the ferromagnetic core; (b) the magnetic field intensity, H_f , in the core; and (c) the magnetic field intensity, H_g , in the air gap.



B_f
 H_f, H_g

$$r_g + l_f = 2\pi r_o$$

FIGURE 6–13
Coil on ferromagnetic toroid with air gap
(Example 6–10).

Ampere's Circuital Law: $\oint \vec{H} \cdot d\vec{l} = NI_0$

$$H_g l_g + H_f l_f = NI_0 \rightarrow \textcircled{1}$$



normal B

should be continuous $\Rightarrow B_f = B_g = \mu_\phi B \rightarrow \textcircled{2}$

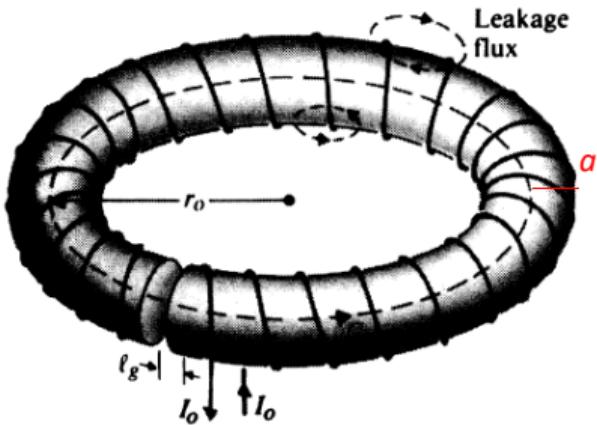
$\textcircled{1}$ and $\textcircled{2} \Rightarrow$

$$\vec{H}_f = \frac{\vec{B}}{\mu_f}$$

$$\vec{H}_g = \frac{\vec{B}}{\mu_0}$$

$$\frac{B}{\mu_0} l_g + \frac{B}{\mu_f} l_f = NI_0$$

$$\Rightarrow \vec{B} = \mu_\phi \frac{\mu_0 NI_0}{l_g + \mu_0 l_g} = \vec{B}_f = \vec{B}_g$$



a: radius of the coil
S: cross section of the toroid core

FIGURE 6-13
 Coil on ferromagnetic toroid with air gap
 (Example 6-10).

If $a \ll r_0$, $\mathbf{B} \sim \text{constant}$,

$$\Phi \cong \underline{\mathbf{B}S},$$



$$\mathbf{B}_f = \mathbf{a}_\phi \frac{\mu_0 \mu N I_o}{\mu_0 (2\pi r_o - \ell_g) + \mu \ell_g}.$$

$$\Phi = \frac{NI_o}{(2\pi r_o - \ell_g)/\mu S + \ell_g/\mu_0 S}.$$

$$\Phi = \frac{NI_o}{(2\pi r_o - \ell_g)/\mu S + \ell_g/\mu_0 S}$$

$$\Phi = \frac{\mathcal{V}_m}{R_f + R_g},$$

where $R_f = \frac{2\pi r_o - \ell_g}{\mu S} = \frac{\ell_f}{\mu S}$,

$$\ell_f = 2\pi r_o - \ell_g$$

ℓ_f : length of the ferromagnetic core

$$I = \frac{V}{R}$$

$$R_g = \frac{\ell_g}{\mu_0 S}.$$

R_f : reluctance of the ferromagnetic core (H^{-1})	\propto
R_g : reluctance of the air gap	\propto

electrical circuit	magnetic circuit
I	Φ
V	I
R	R
ℓ	ℓ
S	S
σ	μ

Ohm's law: $I = V/R$ Resistance $R = \ell/(OS)$

Analogous to Electric Circuit

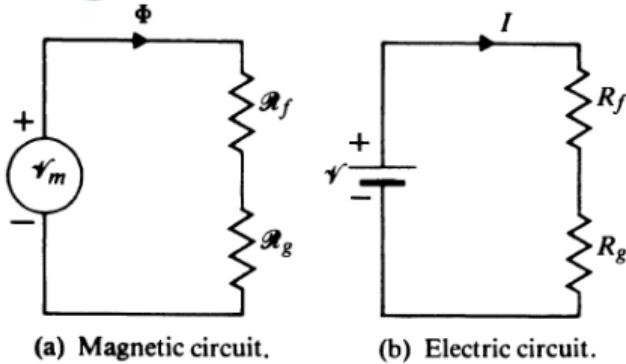


FIGURE 6–14

Equivalent magnetic circuit and analogous electric circuit for toroidal coil with air gap in Fig. 6–13.

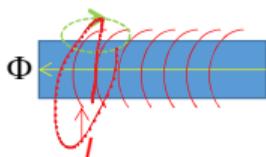
$$\Phi = \frac{\mathcal{V}_m}{\mathcal{R}_f + \mathcal{R}_g}, \quad I = \frac{\mathcal{V}}{R_f + R_g}.$$

Magnetic Circuits	Electric Circuits
mmf, \mathcal{V}_m ($= NI$)	emf, \mathcal{V}
magnetic flux, Φ	electric current, I
reluctance, \mathcal{R}	resistance, R
permeability, μ	conductivity, σ

Difficulty in Analysis of Magnetic Circuits

- 1. Very difficult to account for leakage fluxes

Magnetic circuits



Leakage fluxes Φ outside $\neq 0$
due to $\mu_0 \neq 0$ (in air)

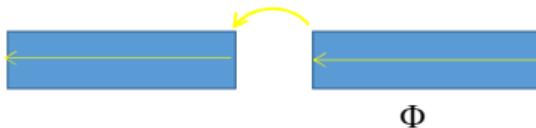
Electric circuits



Current I outside = 0
because of $\sigma = 0$ (in air)

- 2. Difficult to account for fringing effect (at the air gap)

Magnetic circuits



- 3. B and H have a nonlinear relationship
 - $B(H)$ or μ is not a constant

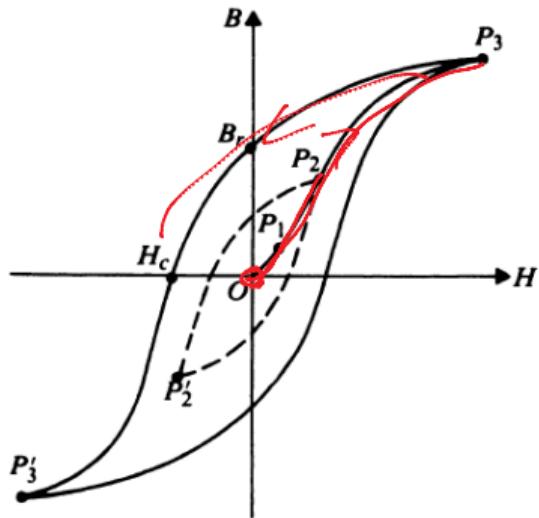


FIGURE 6–17
Hysteresis loops in the B - H plane for ferromagnetic material.

KVL and KCL in Magnetic Circuits

A hand-drawn diagram on the left shows a vertical magnetic core with a rectangular cross-section. A red arrow labeled $\nabla_m = (\Phi_f + \Phi_g) \vec{B}$ points upwards through the core. To the right, a blue box contains the equation $\Phi = \frac{\mathcal{V}_m}{R_f + R_g}$, with a red circle around the denominator. An arrow points from this box to another blue box containing the KVL equation $\sum_j N_j I_j = \sum_k R_k \Phi_k$, with a red circle around the left side of the equation.

KVL: around a closed path in a magnetic circuit the algebraic sum of ampere-terms is equal to the algebraic sum of the products of the reluctances and fluxes

See Chap. 5

$$I = \frac{\mathcal{V}}{R_f + R_g}.$$

A hand-drawn diagram on the left shows a vertical magnetic core with a rectangular cross-section. A red arrow labeled $\nabla \cdot \mathbf{B} = 0$ points upwards through the core. An arrow points from this to a blue box containing the KCL equation $\sum_j \Phi_j = 0$.

KCL: the algebraic sum of all the magnetic fluxes flowing out of a junction in a magnetic circuit is zero

$$\nabla \cdot \mathbf{J} = 0.$$