Topic 5

Single Cycle Processor

Introduction

- Starting from this topic, we will examine two RISC-V implementations
 - A simplified version
 - A more realistic pipelined version
- Supporting a simple subset, showing most aspects of RISC-V design
 - Memory reference: 1w, sw
 - Arithmetic/logical: add, sub, and, or
 - Conditional branch: beq
- You are expected to be able to change the hardware to support more instructions

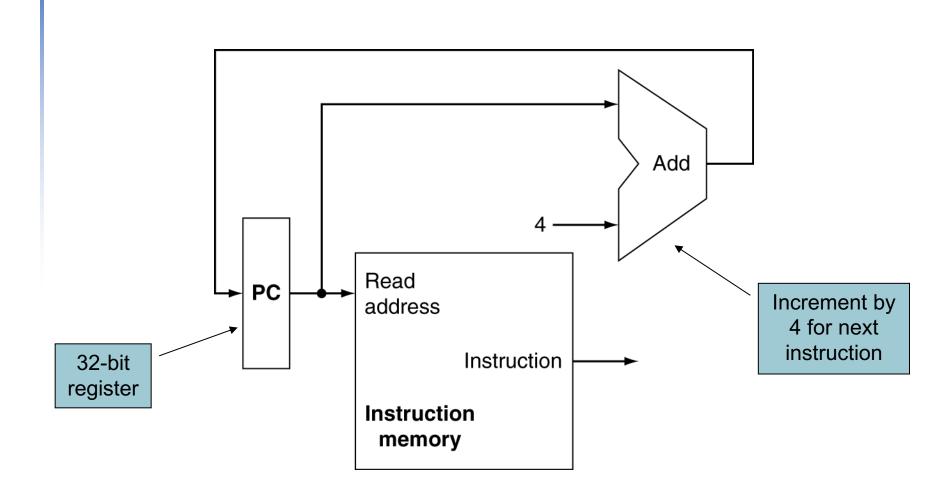
Instruction Execution

- PC → program memory, fetch instruction
- ② Use register addresses to access register file, read registers
- 3 Depending on instructions
 - Use ALU/Adder to calculate
 - Arithmetic/logic result
 - Memory address for load/store
 - Branch target address
- 4 Access register file or data memory for load or store or save calculation results
- ⑤ Update PC ← target address or PC + 4

Building a Datapath

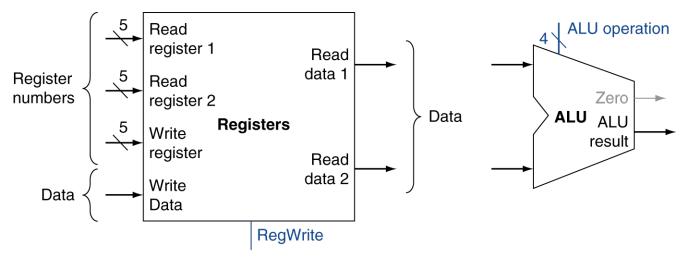
- Datapath
 - Elements that process, store, or route data in the CPU
 - E.g. registers, ALUs, mux's, memories, ...
- We will build a RISC-V datapath incrementally
- We will add a control unit to provide control signals to the datapath

Instruction Fetch



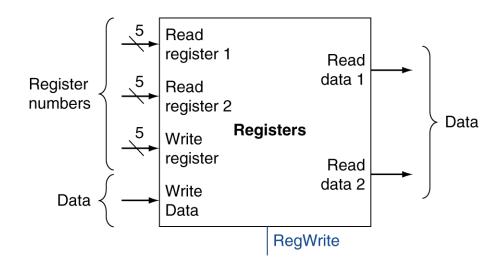
R-Format Instructions

- Operations: add rd, rs1, rs2
 - Read two register operands
 - Perform arithmetic/logical operation
 - Write register result
- We need:



a. Registers b. ALU

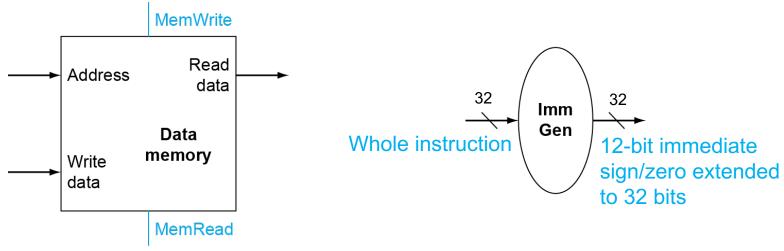
Register Files



- Data is read out whenever register numbers are provided
- Writes
 - Edge-triggered
 - All the write inputs (Write Data, Write Register, RegWrite) must be valid before the clock edge – setup time
- Can read and write the same register within a clock cycle: write first, followed by read.

Load/Store Instructions

- Operations: lw rd, imm12(rs1) sw rs2, imm12(rs1)
 - Read register operands
 - Calculate address using 12-bit immediate
 - Load: Read memory and update register
 - Store: Write register value to memory
- Additionally, we need:



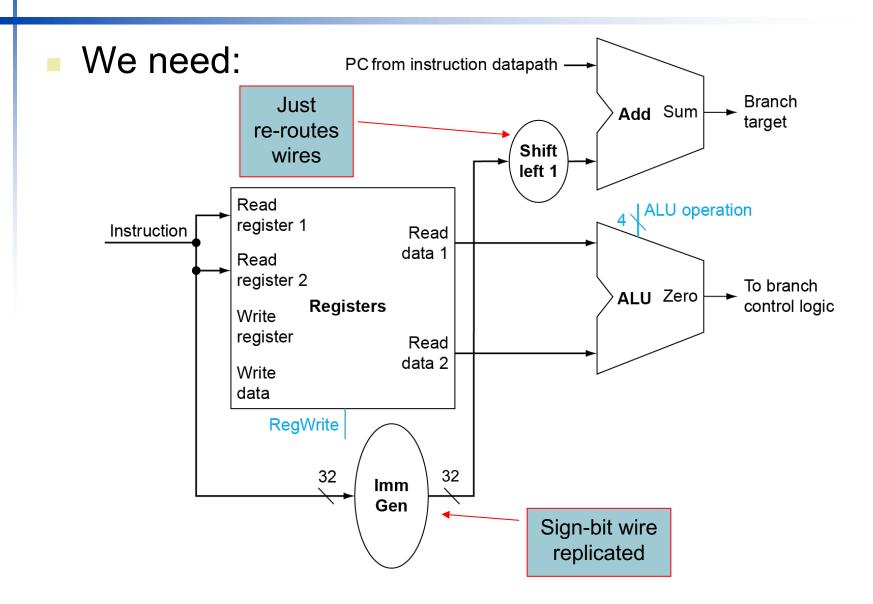
Beq Instructions

- Operations: beq rs1, rs2, target
 - Read register operands
 - Compare operands
 - $rs1==rs2? \Rightarrow rs1-rs2==0?$
 - Use ALU, subtract then check the Zero output of the ALU
 - Calculate target address

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Target PC = Current PC + immediate \times 2
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- Sign-extend the immediate
- Shift left 1 place (multiply by 2)
- Add to PC value

Branch Instructions



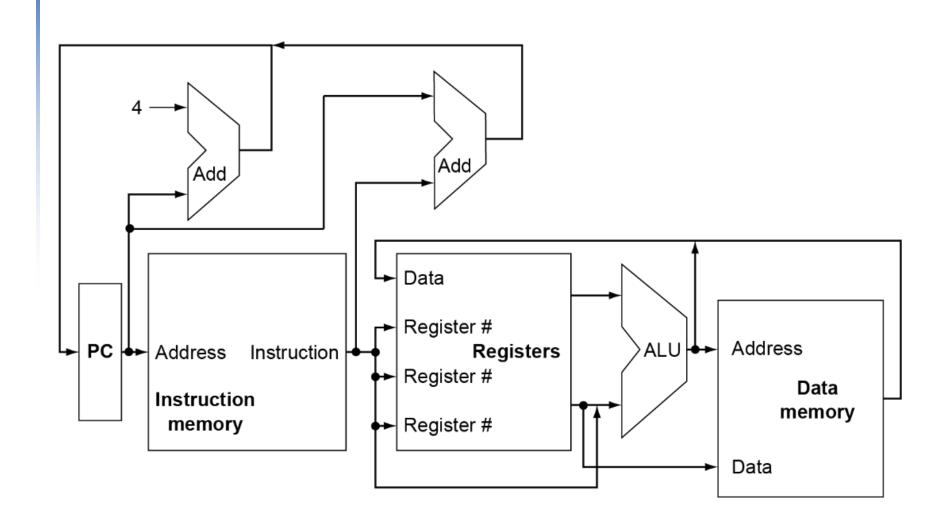
Туре	Field									
	7 bits	5 bits	5 bits	3 bits	5 bits	7 bits				
I-type	immediate[11:0	rs1	funct3	rd	opcode					
S-type	immed[11:5]	rs2	rs1	funct3	immed[4:0]	opcode				
B-type	immed[11,9:4]	rs1	funct3	immed[3:0,10]	opcode					
U-type	immed	rd	opcode							
J-type	immediate[rd	opcode							

- In B-type (SB-type) and J-type (UJ-type), immediate bits are swirled around
 - It saves hardware (muxes) in "Imm Gen" component which picks different fields in an instruction to assemble the immediate number according to different type of the instruction

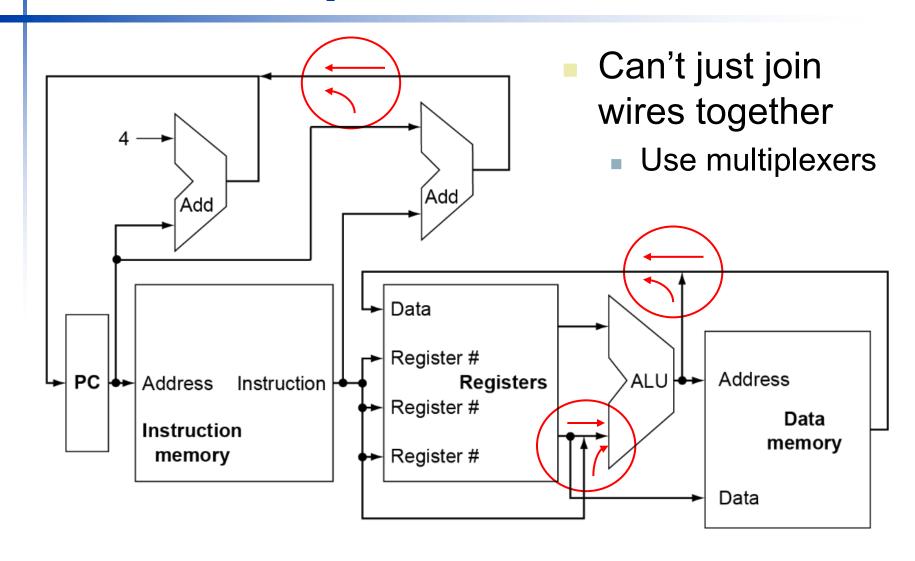
Composing the Elements

- First version of datapath executes an instruction in one single clock cycle
 - Each datapath element can only do one function at a time
 - Hence, we need separate instruction memory and data memory
- Use multiplexers where alternate data sources are used for different instructions

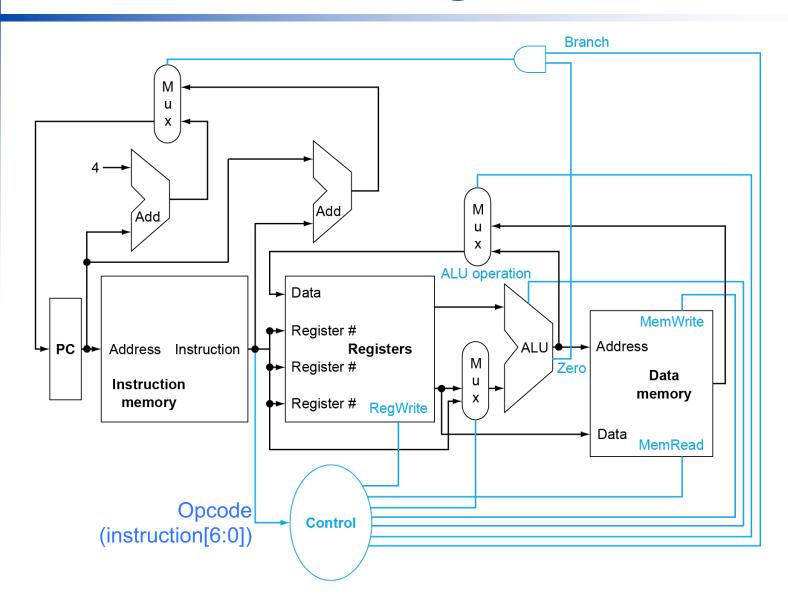
Combine The Operations



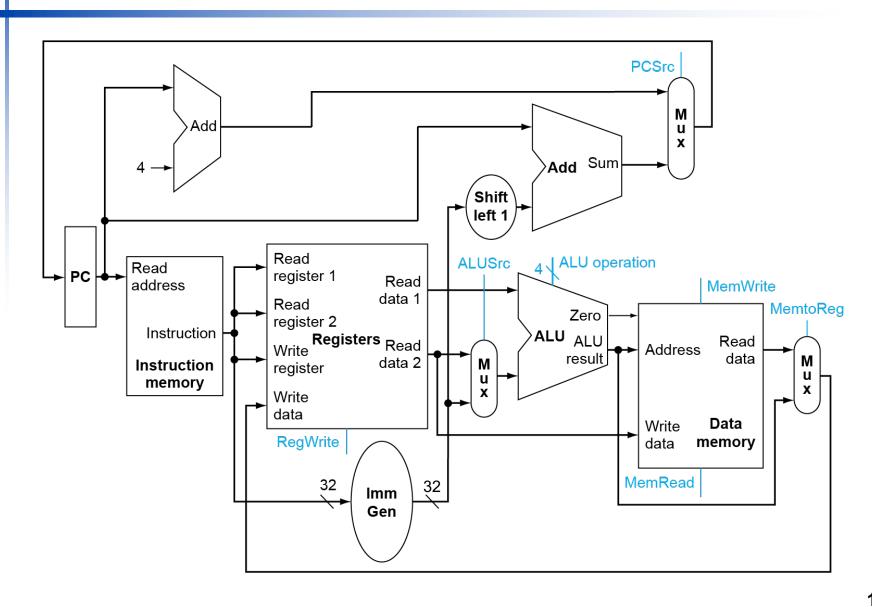
Add Multiplexers



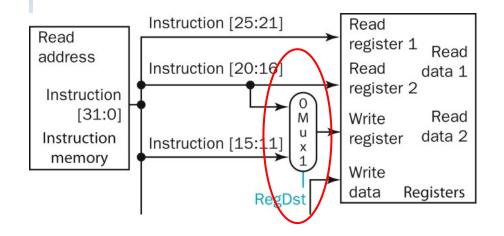
Add Control Signals

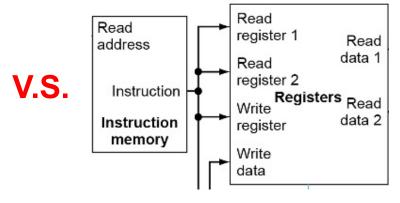


Putting Everything Together



- RISC-V has more types (6) then MIPS (4)
 - But it saves hardware on the critical path





MIPS Architecture: simpler instruction format, but more complicated hardware, longer delay

RISC-V Architecture: more complicated instruction format, but simpler hardware, thus better performance

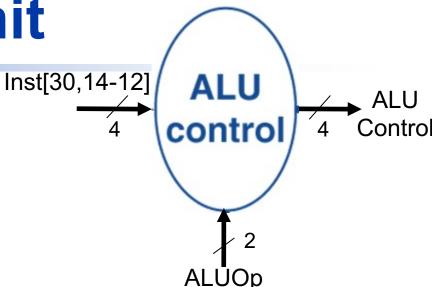
Add ALU Control

- ALU used for
 - Load/Store: Function = add
 - Branch: Function = subtract
 - R-type: Function depends on opcode

ALU control Signal	Function		
0000	AND		
0001	OR		
0010	add		
0110	subtract		

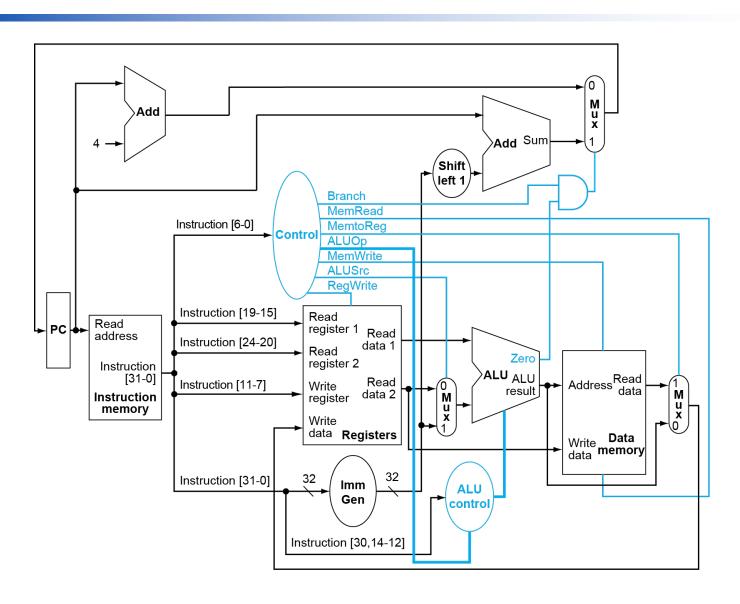
ALU Control Unit

- ALU Control is a combinational logic
 - Assume 2-bit ALUOp derived from opcode

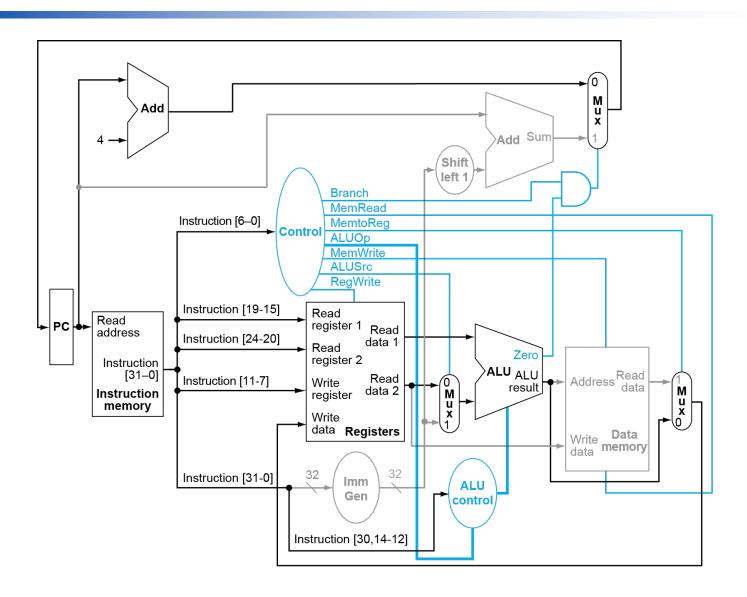


Instr.	Operation	ALU function	Opcode field	ALUOp (input)	i[30] (input)	funct3 (input)	ALU control (output)
lw	load register	add	XXXXXX	00	X	010	0010
sw	store register	add	XXXXXX	00	X	010	0010
beq	branch on equal	subtract	XXXXXX	01	X	000	0110
R-	add	add	100000	10	0	000	0010
type	subtract	subtract	100010		1	000	0110
	AND	AND	100100		0	111	0000
	OR	OR	100101		0	110	0001

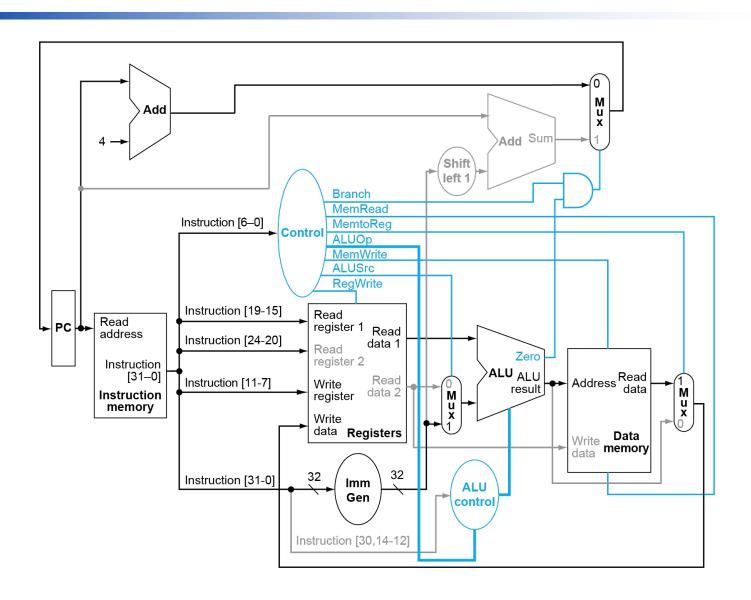
Datapath With Control Unit



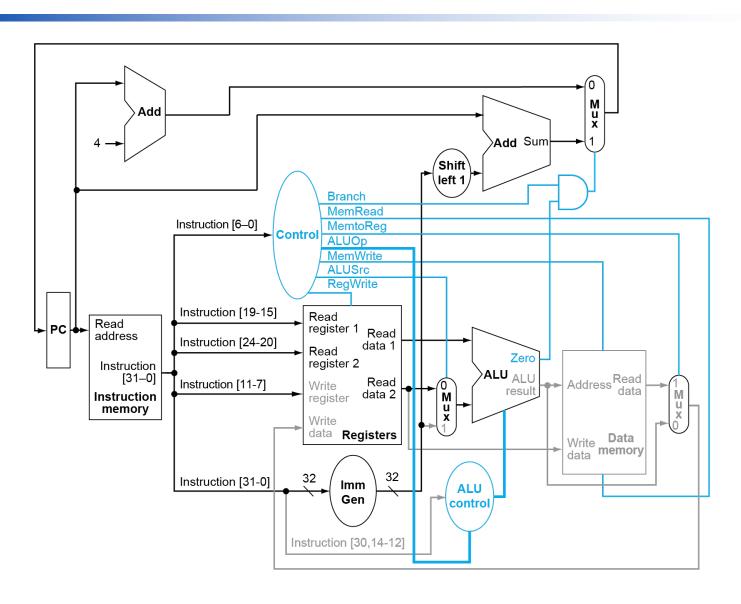
R-Type Instruction



Load Instruction



Branch-on-Equal Instruction



Control Signals

Control signals derived from instruction

Inst.	ALU Src	Mem Write	Mem Read	Branch	Memto Reg	Reg Write
add						
addi						
lw						
SW						
beq						

Performance Related Factors

- Algorithm
 - Determines number of operations executed
- Programming language, compiler, architecture
 - Determine number of machine instructions (lines of source code) executed per operation
- Processor and memory system
 - Determine how fast instructions are executed
- I/O system (including OS)
 - Determines how fast I/O operations are executed

How to Measure Computer Performance?

- Execution (response) time
 - How long it takes to do a task
 - Measure for PCs and embedded computers
- Throughput
 - Total work done per unit time
 - Servers

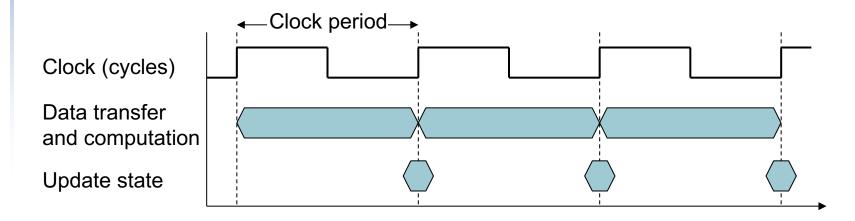
We'll focus on execution time for now

Execution Time

- Elapsed time for System Performance
 - Total execution time to complete a task, including
 - Processing, I/O, OS overhead, idle time, everything
 - But doesn't completely reflect computer's performance if it focuses on better throughput
- CPU time for CPU Performance
 - CPU execution time processing a task
 - Exclude I/O time, time spent for other tasks
 - Comprises user CPU time and system CPU time
 - Hard to differentiate
 - Different programs run with different CPU performance and system performance

CPU Clocking

 Operation of digital hardware governed by a constant-rate clock



- Clock period: duration of a clock cycle
 - e.g., $250ps = 0.25ns = 250 \times 10^{-12}s$
- Clock frequency (rate): cycles per second
 - e.g., $4.0GHz = 4000MHz = 4.0 \times 10^9Hz$

CPU Time

CPU Time = CPU Clock Cycles × Clock Cycle Time

= CPU Clock Cycles

Clock Rate

- Performance improved by
 - Reducing number of clock cycles
 - Increasing clock rate
 - Hardware designer must often trade off clock rate against cycle count

CPU Time Example

- Computer A: 2GHz clock, 10s CPU time
- Designing Computer B
 - Aim for 6s CPU time
 - Can do faster clock, but causes 1.2 × clock cycles
- How fast must Computer B clock be?

$$\begin{aligned} \text{Clock Rate}_{\text{B}} &= \frac{\text{Clock Cycles}_{\text{B}}}{\text{CPU Time}_{\text{B}}} = \frac{1.2 \times \text{Clock Cycles}_{\text{A}}}{6\text{s}} \\ \text{Clock Cycles}_{\text{A}} &= \text{CPU Time}_{\text{A}} \times \text{Clock Rate}_{\text{A}} \\ &= 10\text{s} \times 2\text{GHz} = 20 \times 10^9 \\ \text{Clock Rate}_{\text{B}} &= \frac{1.2 \times 20 \times 10^9}{6\text{s}} = \frac{24 \times 10^9}{6\text{s}} = 4\text{GHz} \end{aligned}$$

Instruction Count and CPI

Clock Cycles = Instruction Count \times Cycles per Instruction

CPU Time = Instruction Count \times CPI \times Clock Cycle Time $= \frac{Instruction Count \times CPI}{Clock Rate}$

- Instruction Count (IC) for a program
 - Determined by program, ISA and compiler
- Average cycles per instruction (CPI)
 - Determined by CPU hardware
 - If different instructions have different CPI
 - Average CPI affected by instruction mix

CPI Example

- Computer A: Cycle Time = 250ps, CPI = 2.0
- Computer B: Cycle Time = 500ps, CPI = 1.2
- Same ISA
- Which is faster, and by how much?

$$\begin{aligned} \text{CPU Time}_{A} &= \text{Instruction Count} \times \text{CPI}_{A} \times \text{Cycle Time}_{A} \\ &= I \times 2.0 \times 250 \text{ps} = I \times 500 \text{ps} & \quad \text{A is faster...} \end{aligned}$$

$$\begin{aligned} \text{CPU Time}_{B} &= \text{Instruction Count} \times \text{CPI}_{B} \times \text{Cycle Time}_{B} \\ &= I \times 1.2 \times 500 \text{ps} = I \times 600 \text{ps} \end{aligned}$$

$$\begin{aligned} &\frac{\text{CPU Time}_{B}}{\text{CPU Time}_{A}} &= \frac{I \times 600 \text{ps}}{I \times 500 \text{ps}} = 1.2 & \quad \text{...by this much} \end{aligned}$$

Performance Summary

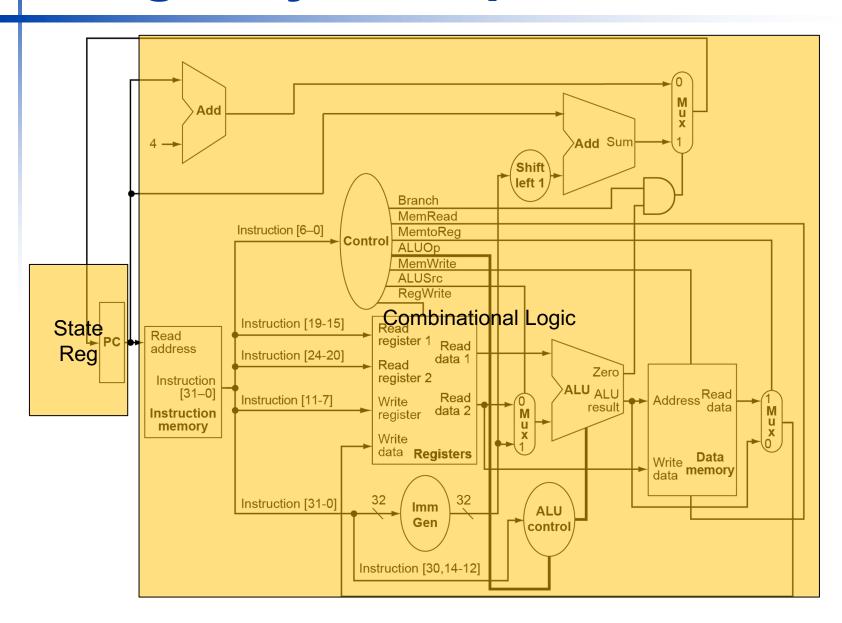
The BIG Picture

$$CPU Time = \frac{Instructions}{Program} \times \frac{Clock \ cycles}{Instruction} \times \frac{Seconds}{Clock \ cycle}$$

Performance depends on

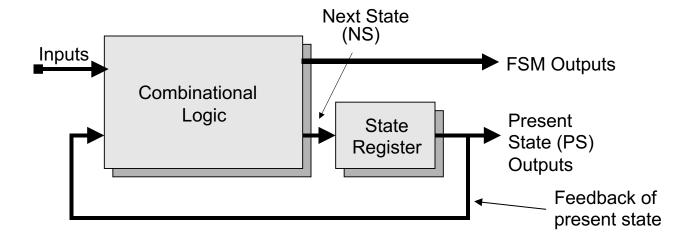
- **Clock Period**
- Algorithm: affects IC, possibly CPI
- Programming language: affects IC, CPI
- Compiler: affects IC, CPI
- Instruction set architecture: affects IC, CPI, Tc

Single Cycle Implementation



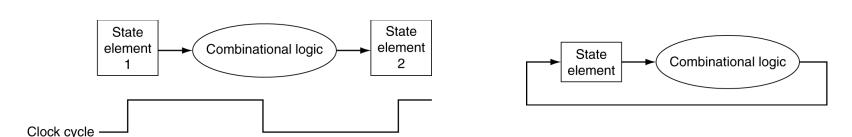
State Machine

Finite State Machine



Clocking Methodology

- Combinational logic does the computation during clock cycles
 - Between clock edges
 - Input (present state) from state elements, output (next state) to state element
 - Among all kinds of computations, longest delay determines clock period



- Longest instruction determines the clock cycle time
 - Critical path: the path having longest delay
 - load instruction
 Instruction memory → register file → ALU → data memory → register file (plus MUXes)
- Not feasible to vary period for different instructions
 - Waste time on other instructions
- How to improve the performance (faster speed)?

- Assume times for major components are
 - 100ps for register read or write
 - 200ps for accessing memory
 - 200ps for ALU operations

Instruction	Instr fetch	Register read	ALU op	Data Memory	Register write	Total time
lw	200ps	100 ps	200ps	200ps	100 ps	800ps
SW	200ps	100 ps	200ps	200ps		700ps
R-format	200ps	100 ps	200ps		100 ps	600ps
beq	200ps	100 ps	200ps			500ps

- Assume 100 instructions are executed
 - 15% are loads
 - 15% are stores
 - 40% are R format instructions
 - 30% are branches
- What's the clock cycle time for single-cycle processor?
- Execution time using single-cycle processor?