Linear Dispersive Waves in Optical Fibers

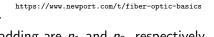
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Physical Properties of an Optical Fiber

- Silica glass core surrounded by cladding.
- Glass naturally charge neutral at rest and assumed to remain neutrally charged as light passes through it.
- Core is isotropic, homogeneous and non-birefringent.
- Core-cladding boundary at radius a.



CLADDING

COATING

- Refractive index of the core and cladding are n_1 and n_0 , respectively.
- Cladding of arbitrary radius.

CORE

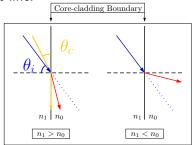
Properties of Light: Snell's Law

Boundary conditions necessary for light confinement in the core are required. We investigate the properties of light at the core-cladding boundary.

- Snell's Law is derived from Descarte's Law.
- **Descarte's Law:** Sufficiently small variations in the path of light implies light travels in a straight line.
- Reflection occurs only if

$$n_1 > n_0$$

$$\frac{\pi}{2} - \theta_i > \theta_c = \sin^{-1}\left(\frac{n_0}{n_1}\right).$$

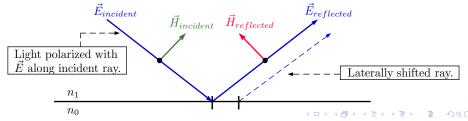


Properties of Light: Snell's Law and Goos-Hanchen Shift

Conclusion from Snell's law: Cylindrical symmetry and trigonometric identities give the maximum acceptance angle,

$$\theta_{\max} \leq \sin^{-1} \sqrt{\mathit{n}_1^2 + \mathit{n}_0^2}.$$

- Goos-Hanchen shift is a lateral shift of reflected rays.
- Electromagnetic waves have complex phase.
- Reflected ray no longer has same complex phase.
- Phase difference implies a lateral shift occurs.



Electromagnetic Theory

Maxwell's equations:

$$\vec{\nabla} \circ \vec{D} = \rho$$
 (1) $\vec{\nabla} \times \vec{E} = -\mu_0 \frac{\partial \vec{H}}{\partial t}$ (3)

$$\nabla \circ \vec{B} = 0$$
 (2) $\vec{\nabla} \times \vec{H} = \vec{J} + \frac{\partial \vec{D}}{\partial t}$ (4)

Combine to obtain Maxwell's wave equations;

$$\nabla^2 \vec{E} = \mu_0 n^2(r) \varepsilon_0 \frac{\partial^2 \vec{E}}{\partial t^2} \quad \text{and} \quad \nabla^2 \vec{H} = \mu_0 n^2(r) \varepsilon_0 \frac{\partial^2 \vec{H}}{\partial t^2}.$$

Solutions are monochromatic phasors w.r.t. time;

$$\vec{E}(\vec{r},t) = \vec{E}(r,\theta,z)e^{i\omega t}$$
 and $\vec{H}(\vec{r},t) = \vec{H}(r,\theta,z)e^{i\omega t}$. (5)

Hyperbolic PDEs: The Cauchy Problem

- Cauchy Problem: n^{th} order partial differential equation (PDE) with m independent variables and specified boundary conditions (BCs).
- Conditions specified on solution and derivatives of order < (n-1).
- Maxwell's wave equations: 2^{nd} order linear PDEs; independent variables (r, θ, z, t) .
- Boundary conditions:

$$E_T^{(core)} = E_T^{(cladding)}$$
 and $H_T^{(core)} = H_T^{(cladding)}$,

 $\forall T \in \{r, \theta, z, t\}$ satisfying r = a.

Hyperbolic PDEs: Method of Characteristics

Definition: Hyperbolic PDE

A PDE is hyperbolic for sets of points where the Cauchy problem has a unique solution in the neighbourhood of the points on any non-characteristic hyper-plane passing though them. Unique solutions are hyper-surfaces such that the hyper-planes have at least one less independent variable.

- Method of characteristics used to find unique solution along light rays.
- Known parametrization of solution used to determine unique solutions or hyperbolic regions for solutions are determined by unique parametrized hyper-planes satisfying solution uniquely.

Applying the Method of Characteristics: Example

• 1-dimensional wave equation:

$$u_{tt}(x,t) - c^2 u_{xx}(x,t) = 0,$$
 $u(x,0) = f(x)$ $u_t(x,0) = g(x)$ $u_t(x,0) = 0$ $u(t,t) = 0$ $u(t,t) = 0$ $u(t,t) = 0$

• Equivalent to 2nd order PDE;

$$\mathcal{L}[u] = a(x,t)u_{xx} + b(x,t)u_{tt} + d(x,t)u_{xt} = 0,$$

with a=1, $b=c^2$ and d=0.

Apply parametrization

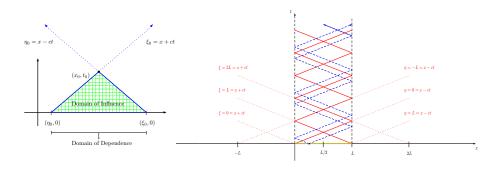
$$(x,t)\mapsto (\xi,\eta); \quad \xi(x,t)=x+ct, \quad \eta(x,t)=x-ct.$$

• Solutions necessarily hyperbolic since $b^2 - 4ac = c^4 > 0$.

Applying the Method of Characteristics: Example

 Solution obtain by inputting parametrization into PDE is called d'Alembert's solution;

$$u(x,t) = p(x+ct) - q(x-ct) = \frac{1}{2} \Big(f(\xi) + f(\eta) \Big) + \frac{1}{2c} \int_{\eta}^{\xi} g(s) ds.$$



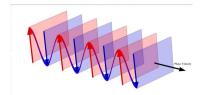
Dispersion: Definition

- Consider a homogeneous PDE with 4 independent variables (x_r, x_θ, x_z, t) .
- **Dispersion** defined by solutions $u(\vec{x},t) = Ae^{i\vec{\kappa}\circ\vec{x}-i\omega t}$, $\vec{\kappa}$, ω constants.
- Input into PDE to obtain dispersion relation $G(\omega, \kappa_r, \kappa_\theta, \kappa_z) = 0$.
- Solutions, ω , are called dispersion modes.
- Real solutions are $Re(u) = |A| \cos(\vec{\kappa} \circ \vec{x} \omega t + ArgA)$.

Dispersion: Phase Velocity

- For each dispersion mode ω , consider phase surfaces $\vartheta = \vec{\kappa} \circ \vec{x} \omega t$.
- Phase velocity is determined by the average number of wavelengths per period in the direction normal to phase surfaces with respect to space.
- For fixed phase surface $\vartheta = \text{constant}$, this direction is $\vec{\kappa}$.
- Average wavelength is $\lambda = 2\pi/|\vec{\kappa}|$ and the average period is $2\pi/\omega$.
- Phase velocity is given by

$$c(\vec{\kappa}) = \frac{W(\vec{\kappa})}{|\vec{\kappa}|} \hat{\kappa} = \frac{\omega}{|\vec{\kappa}|} \hat{\kappa}.$$



https://courses.lumenlearning.com/boundless-physics/chapter/waves/

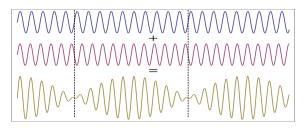
Dispersion: Group Velocity

 Group velocity is defined by considering local wavenumber and frequency given by

$$\kappa_i = \frac{\partial u}{\partial x_i}$$
 and $\omega = -\frac{\partial u}{\partial t}$, respectively.

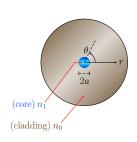
• Solving for $\kappa_i(x_i, t)$ defines the group velocity component-wise as

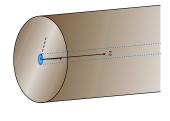
$$C_i(\vec{\kappa}) = \frac{\partial W(\vec{\kappa}, \vec{x}, t)}{\partial \kappa_i}.$$



 $\verb|http://www.phikwadraat.nl/images/article/duck/beatadd.png|$

Deriving a Solution: Plane Wave Solution





$$\nabla^{2}\vec{E} = \mu_{0}n^{2}(r)\varepsilon_{0}\frac{\partial^{2}\vec{E}}{\partial t^{2}}$$

$$\nabla^{2}\vec{H} = \mu_{0}n^{2}(r)\varepsilon_{0}\frac{\partial^{2}\vec{H}}{\partial t^{2}}$$

$$E_{T}^{(core)} = E_{T}^{(cladding)}$$
 $H_{T}^{(core)} = H_{T}^{(cladding)},$ $orall T \in \{r, heta, z, t\}, \quad r = a$

Plane wave solution for dispersive light rays propagating in the *z*-direction:

$$\vec{E}(r,\theta,z,t) = \vec{E}(r,\theta)e^{i(\omega t - \beta z)}$$
 and $\vec{H}(r,\theta,z,t) = \vec{H}(r,\theta)e^{i(\omega t - \beta z)}$.

Deriving a Solution: Necessary Equations

- In vacuum, $c = \omega/k$ =speed of light, $k = \omega \sqrt{\mu_0 \varepsilon_0}$ =wavenumber.
- Input \vec{E} and \vec{H} into Maxwell's wave equations to obtain:

$$\frac{\partial^2 E_z}{\partial r^2} + \frac{1}{r} \frac{\partial E_z}{\partial r} + \frac{1}{r^2} \frac{\partial^2 E_z}{\partial \theta^2} + \left(k^2 n^2(r) - \beta^2 \right) E_z = 0 \tag{6}$$

$$\frac{\partial^2 H_z}{\partial r^2} + \frac{1}{r} \frac{\partial H_z}{\partial r} + \frac{1}{r^2} \frac{\partial^2 H_z}{\partial \theta^2} + \left(k^2 n^2(r) - \beta^2 \right) H_z = 0.$$
 (7)

• Equations for $\vec{\nabla} \times \vec{E}$ and $\vec{\nabla} \times \vec{H}$ in cylindrical components used in Maxwell's equations (3) and (4), respectively, gives

$$\frac{1}{r}\frac{\partial E_{z}}{\partial \theta} + i\beta E_{\theta} = -\mu_{0}i\omega H_{r} \qquad \qquad \frac{1}{r}\frac{\partial H_{z}}{\partial \theta} + i\beta H_{\theta} = i\varepsilon_{0}\omega n^{2}E_{r}$$

$$-i\beta E_{r} - \frac{\partial E_{z}}{\partial r} = -\mu_{0}i\omega H_{\theta} \qquad \text{and} \qquad \qquad -i\beta H_{r} - \frac{\partial H_{z}}{\partial r} = i\varepsilon_{0}\omega n^{2}E_{\theta}$$

$$\frac{1}{r}\left(\frac{\partial (rE_{\theta})}{\partial r} - \frac{\partial E_{r}}{\partial \theta}\right) = -\mu_{0}i\omega H_{z} \qquad \qquad \frac{1}{r}\left(\frac{\partial (rH_{\theta})}{\partial r} - \frac{\partial H_{r}}{\partial \theta}\right) = i\varepsilon_{0}\omega n^{2}E_{z}$$

Deriving a Solution: Bessel's Equation

• Boundary value problems (6) and (7) are well-posed only if

$$E_z = R_E(r)\Theta_E(\theta)$$
, and $H_z = R_H(r)\Theta_H(\theta)$.

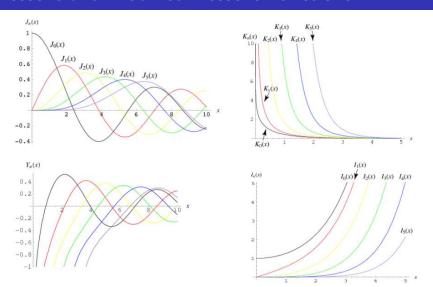
• W.I.o.g., R and Θ inputted into wave equation to obtain

$$\frac{d^2\Theta}{d\theta^2} = -m^2\Theta \quad \text{and} \quad \frac{d^2R}{dr^2} + \frac{1}{r}\frac{dR}{dr} + \left(\gamma^2 - \frac{m}{r^2}\right)R = 0.$$

- ODE w.r.t. R(r) is **Bessel's or modified Bessel's** equation of order m, such that $\gamma^2 = n^2k^2 \beta^2$.
- $J_m(ur)$ and $K_m(wr)$ are the Bessel functions satisfying light confinement BCs whenever $r \to 0$ and $r \to \infty$, respectively.

$$E_z = AJ_m(ur)\cos(m\theta + \alpha), \qquad E_z = CK_m(wr)\cos(m\theta + \alpha), H_z = BJ_m(ur)\sin(m\theta + \alpha), \qquad H_z = DK_m(wr)\sin(m\theta + \alpha), u^2 = n_1^2k^2 - \beta^2. \qquad w^2 = \beta^2 - n_0^2k^2.$$

Bessel's and Modified Bessel's Functions



http://mathworld.wolfram.com

Deriving a Solution: Bessel's Equation

Equations obtained from curls $\vec{\nabla} \times \vec{E}$ and $\vec{\nabla} \times \vec{H}$ are combined:

$$\begin{split} E_{\theta}^{(core)} &= \frac{-i}{u^2} \left((Am \frac{\beta}{r} J_m(ur) + B\omega \mu_0 \frac{\partial J_m(ur)}{\partial r} \right) \sin \left(m\theta + \alpha \right), \\ E_{\theta}^{(cladding)} &= \frac{-i}{w^2} \left(Cm\beta \frac{\partial K_m(wr)}{\partial r} + D \frac{\omega \mu_0}{r} \frac{\partial K_m(wr)}{\partial \theta} \right) \sin \left(m\theta + \alpha \right), \\ H_{\theta}^{(core)} &= \frac{-i}{u^2} \left(Am \frac{\beta}{r} J_m(wr) + B\omega \varepsilon_0 n_1^2 \frac{\partial K_m(wr)}{\partial r} \right) \cos \left(m\theta + \alpha \right), \\ H_{\theta}^{(cladding)} &= \frac{-i}{w^2} \left(Cm\beta J_m(wr) + D \frac{\omega \varepsilon_0 n_0^2}{r} \frac{\partial K_m(wr)}{\partial \theta} \right) \cos \left(m\theta + \alpha \right). \end{split}$$

Applying BCs for Maxwell's wave equations obtains:

$$\begin{pmatrix} \frac{m\beta}{u^2a^2}J_m(ua) & \frac{k\omega\mu_0}{ua}J'_m(ua) & \frac{m\beta}{w^2a}K_m(wa) & -\frac{k\omega\mu_0}{w^2a}K'_m(wa) \\ \frac{kn_1^2}{ua}J'_m(ua) & \frac{\omega\mu_0m}{u^2a^2}J_m(ua) & \frac{k^2n_0^2}{wa}K'_m(wa) & \frac{\omega\mu_0m\beta}{w^2a^2}K_m(wa) \\ J_m(ua) & 0 & -K_m(wa) & 0 \\ 0 & J_m(ua) & 0 & K_m(wa) \end{pmatrix} \begin{pmatrix} A \\ B \\ C \\ D \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \end{pmatrix}$$

Deriving a Solution: Characteristic Equation

 Characteristic equations give solutions along light rays; given by determinant

$$\begin{vmatrix} \frac{m\beta}{u^2a^2}J_m(ua) & \frac{k\omega\mu_0}{ua}J_m'(ua) & \frac{m\beta}{w^2a}K_m(wa) & -\frac{k\omega\mu_0}{w^2a}K_m'(wa) \\ \frac{kn_1^2}{ua}J_m'(ua) & \frac{\omega\mu_0m}{u^2a^2}J_m(ua) & \frac{k^2n_0^2}{wa}K_m'(wa) & \frac{\omega\mu_0m\beta}{w^2a^2}K_m(wa) \\ J_m(ua) & 0 & -K_m(wa) & 0 \\ 0 & J_m(ua) & 0 & K_m(wa) \end{vmatrix}.$$

- Families of solutions correspond to values of m w.r.t. **one** of the fields \vec{E} or \vec{H} .
- Seek solution for modes satisfying m = 0, called the TE and TM modes.

Conclusion: TE and TM Modes

• When m = 0, the characteristic equation becomes

$$\left(\frac{J_0'(ua)}{uaJ_0(ua)} + \frac{K_0'(wa)}{waK_0(wa)}\right) \left(\frac{J_0'(ua)}{uaJ_0(ua)} + \frac{n_0^2}{n_1^2} \frac{K_0'(wa)}{waK_0(wa)}\right) = 0.$$
with $H_z = BJ_0(ur)\sin(\alpha)$, $H_z = DK_0(wr)\sin(\alpha)$

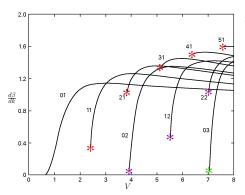
• Normalized frequency is

$$V = \sqrt{(wa)^2 + (ua)^2} = \left[a\sqrt{n_1^2 - n_0^2}\right]k = \left[a\sqrt{\mu_0\varepsilon_0(n_1^2 - n_0^2)}\right]\omega$$

• Since n_1 and n_0 are independent of frequency, the **normalized group velocity** is given by the product rule;

$$\frac{d\beta}{dk} = \frac{a\sqrt{n_1^2 - n_0^2}}{a\sqrt{n_1^2 - n_0^2}} \frac{d(\frac{V\beta}{k})}{dV} = V \frac{d(\frac{\beta}{k})}{dV} + \frac{\beta}{k}.$$

Conclusion: TE and TM modes

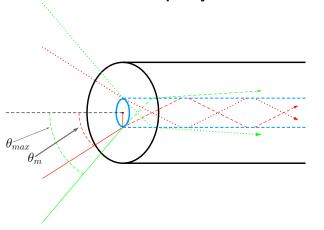


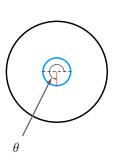
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- If V > 2.4 then group velocity is non-zero for other modes with $m \neq 0$.
- For sufficiently small ω , only TE mode present.
- Non-zero group velocity implies the corresponding mode propagates with a particular group velocity determined by its normalized frequency.
- \bullet A dispersion mode with some value of ω in the solution propagates HE and EH modes with corresponding group velocities.

Conclusion: Hybrid Modes

Can interpret dispersive properties with group velocity behaviour of modes w.r.t. source frequency.





The End