ECE 5780 / 6780 Real-Time Systems

Ada Basics



Lab 1: To Do in Ada

Cyclic scheduler

Cyclic scheduler with watchdog

Communication among tasks

Real-Time Programming

- It is mostly about concurrent programming
- We also need to handle timing constraints on concurrent executions of tasks
 - And other important performance metrics such as energy consumption

Real-Time Programming

- Without OS support (bare metal)
 - Static schedule and cyclic execution
- With RTOS support
 - Program in general-purpose language like C and use scheduling policy to assign priorities
- With RTOS and language support
 - Program in RT Java or Ada
 - RTOS is "hidden"

Why Ada?

- Developed by DoD for embedded and real-time systems
 - Back when hundreds of languages were used
 - Goal was to have a standardized language for DoD's embedded real-time systems
 - \$201M
- But Ada mandate ended in 1997
 - Could not be enforced
 - But did reduce the number of languages used in DoD computer systems by 2 orders of magnitude
- Many versions
 - Ada 83, Ada 95, Ada 2005, Ada 2012

Features

- Strong typing
- Modularity mechanisms (packages)
- Run-time checking
- Exception handling
- Generics
- Object-oriented
- Concurrent programming
- Real-time support

Application Area

- Safety-critical systems
 - Avionics
 - Military systems
 - Space applications

```
-- File: hello world.adb
with Ada.Text_IO; -- Basic I/O
use Ada.Text_IO; -- Integrate namespace
procedure hello_world is
   Message: constant String:= "Hello World";
begin
   Put_Line(Message);
end hello world;
```

```
-- File: hello world.adb
with Ada.Text IO; -- Basic I/O
use Ada.Text_IO; -- Integrate namespace
procedure hello_world is
   Message: constant String:= "Hello World";
begin
   Put_Line(Message);
end hello world;
```

```
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```

```
-- File: hello world.adb
with Ada.Text_IO; -- Basic I/O
use Ada.Text_IO; -- Integrate namespace
procedure hello_world is
   Message: constant String:= "Hello World";
begin
   Put_Line(Message); -- Case insensitive
end hello world;
```

Typical Program Structure

Declaration 1 -- to introduce identities/variables and define data structures

Declaration2 – to define operations: procedures, functions, and/or tasks (concurrent operations) to manipulate the data structures

Main program

(Program body) -- a sequence of statements or operations to compute the result (output)

Basic Structures

- Basic data types: Boolean, Integer, Float, Character, String
 - X: Integer; -- Declare X as an integer
 - X : Integer := 0; -- Declare and initialize X
- New type via subtype, array, etc...
 - subtype Die is Integer range 1 .. 6; -- One die
 - type Dice is array (0 .. 22) of Die; -- 23 dice
 - To use
 - D : Dice;
 - Value := D(index);

Control Statements (1)

```
x := y; -- Assign y to x
if x = y then
z := 1;
else
z := 0;
x := 42; -- Several statements!
end if;
```

Control Statements (2)

```
loop
   z := z + 1;
   exit when z > 100;
end loop; -- Loops may be nested
for i in 1...100 loop
   Put Line("Inside loop");
end loop;
```

Procedures

```
procedure F1(var: in Integer; var: out String) is
```

- -- Local variables
- -- Definitions of local procedures/functions/tasks/..

begin

-- Code

end F1;

- In/out parameters are read/write only
- Main program: procedure without argument

Example

```
procedure example1 is
    i: Integer := 0;
    procedure printVal(a: Integer) is
    begin
         if a > 0 then
              put_line(Integer'Image(a));
         end if;
    end printVal;
begin
    loop
         printVal(a => i);
         i := i + 1;
         exit when i > 10;
    end loop;
end example1;
```

Functions

```
function fname(x1, x2: Float) return Float is
```

- -- local variables
- -- definitions of local procedures/functions/tasks/..

```
begin
return x1 * x2;
end fname;
```

Time

- Package: Ada.Calendar
 - Type for relative time: Duration
 - Type for absolute time: Time
 - For getting present time: Clock (of type Time)
- To get current time

```
t: Time;
```

t := Ada.Calendar.Clock;

To get time as a Duration

```
t: Duration;
```

t := Ada.Calendar.Seconds(Ada.Calendar.Clock);

Delaying a Statement

- To wait x seconds, we could have delay x;
- But the above would cause drifts, especially in loop
- The correct way to do this is delay until y;

Generating a Random Number

A float between [0, 1]

G: Generator;

```
Reset(G)
   Val := Random(G);

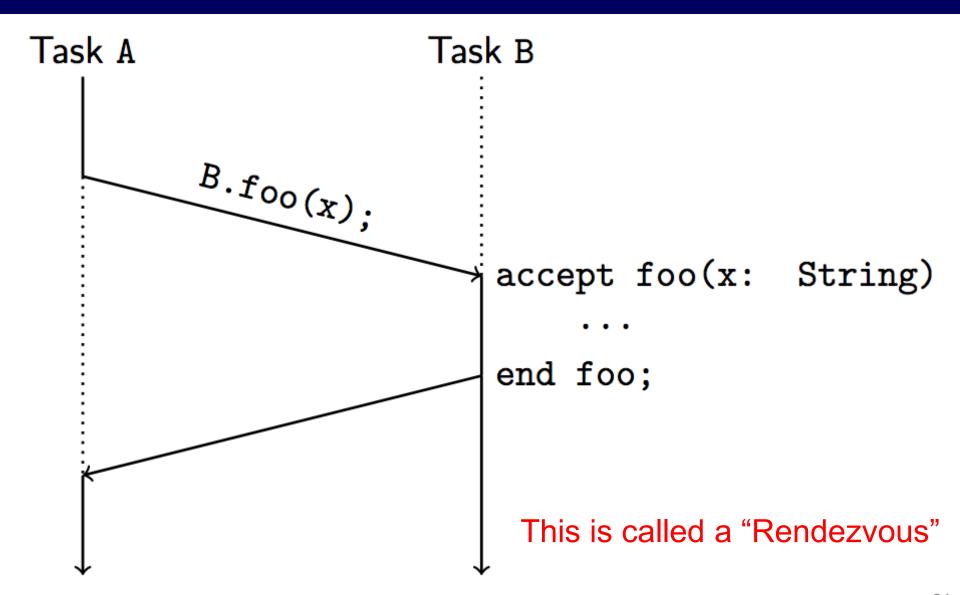
    An integer between [0, 10]

   subtype Num_Gen is Integer range 0 .. 10;
   package Random_Gen is new
      Ada.Numerics.Discrete_Random(Num_Gen);
   use Random_Gen;
   G: Random_Gen.Generator;
   Reset(G)
   Val: Num_Gen := random(G);
```

Creating a Task in Ada

```
task My_Task is
   entry Init;
   entry Get(Item: out Integer);
   entry Put(Item: in Integer);
end My_Task;
task body My_Task is
   -- Declarations needed by task code
begin
   -- Task code goes here
end My_Task;
```

Concurrent Exec. with Synch.



Rendezvous

```
procedure foo
                                        task user;
                                        task body user is begin
   task T is
       entry E(...in/out parameter...);
                                            T.E(....)
   end;
   task body T is begin
                                        end
                                     begin
       accept E(... ...) do
           -- sequence of statements
                                        taskT: T;
       end E;
                                        taskU: user;
                                     end
                                     end foo;
```

taskT and taskU will be started concurrently

Rendezvous

task body A is begin

...

B.Call;
accept Call do
...

end A

end Call
...

end B

Select Statement

```
task body A is
    empty: Boolean := false;
begin
    loop
        select
            accept Init do
            end Init;
        or
            accept Put(Item: Integer) do
            end Put;
    end loop;
end A;
```

```
Procedure x is
  task type A is
    entry Init;
    entry Put(Item: Integer);
  end A;
  task body A is
  end A
TaskA: A;
begin
  TaskA.init;
  TaskA.put(y);
end x;
```

Guarded Entries: When Statement

```
select
    when not Is_Empty(Container) =>
        accept get(Item: out Integer) do
        end get;
or
    when not Is_Full(Container) =>
        accept put(Item: in Integer);
        end put;
end select;
```

Choice: More on Select Statement

```
select
task Server is
                                            when <boolean expression> =>
   entry S1(...);
                                                accept S1(...) do
   entry S2(...);
                                                  -- Code for this service
                                                end S1;
end Server;
                                        or
task body Server is
                                            accept S2(...) do
                                                -- Code for this service
                                            end S2;
begin
                                        or
    Loop
                                            terminate;
                                        end select;
       -- Prepare for service
                                    end loop;
                                end server;
```

Rendezvous Implementation

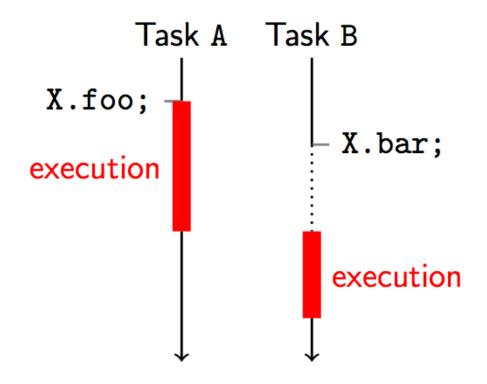
- This is implemented with entry queues
 - The compiler takes care of this!
- Each entry has a queue for tasks waiting to be accepted
 - A call to the entry is inserted in the queue
 - The first task in the queue will be "accepted" first (like the queue for a semaphore)
- By default, the queuing policy is FIFO
 - Different queuing policies can be specified

More on Task

- A task starts executing as soon as it's created
 - For example: T: rtTask;
- Use explicit synchronization if necessary (like an "Init" entry)

Protected Types

- Provide mutual exclusion
 - For concurrent execution
 - Only one procedure/entry of instance can run at any time



Implementation

```
protected Integer_Buffer is
    entry Insert (i : in Integer);
                                              To use:
    entry Remove (i : out Integer);
private
                                              Integer_Buffer.insert(x);
    buffer : Integer;
                                              Integer_Buffer.remove(y)
    empty: Boolean := True;
end Integer_Buffer;
protected body Integer_Buffer is
    entry Insert (i: in Integer) when empty is
    begin
    end insert
end integer_buffer;
```

Options

Procedures

Unconditionally changes the state of the protected object

Entries

Can only be executed when the boundary condition is true

Functions

 Used to report the state of a protected object and do not change the state of the protected object

GNAT

- Free compiler and software development toolset for the full Ada programming language
 - Linux, Windows, and Mac compatible
- Integrated into the GCC compiler system
- To compile
 - \$ gnatmake myprogram
- To run
 - \$./myprogram