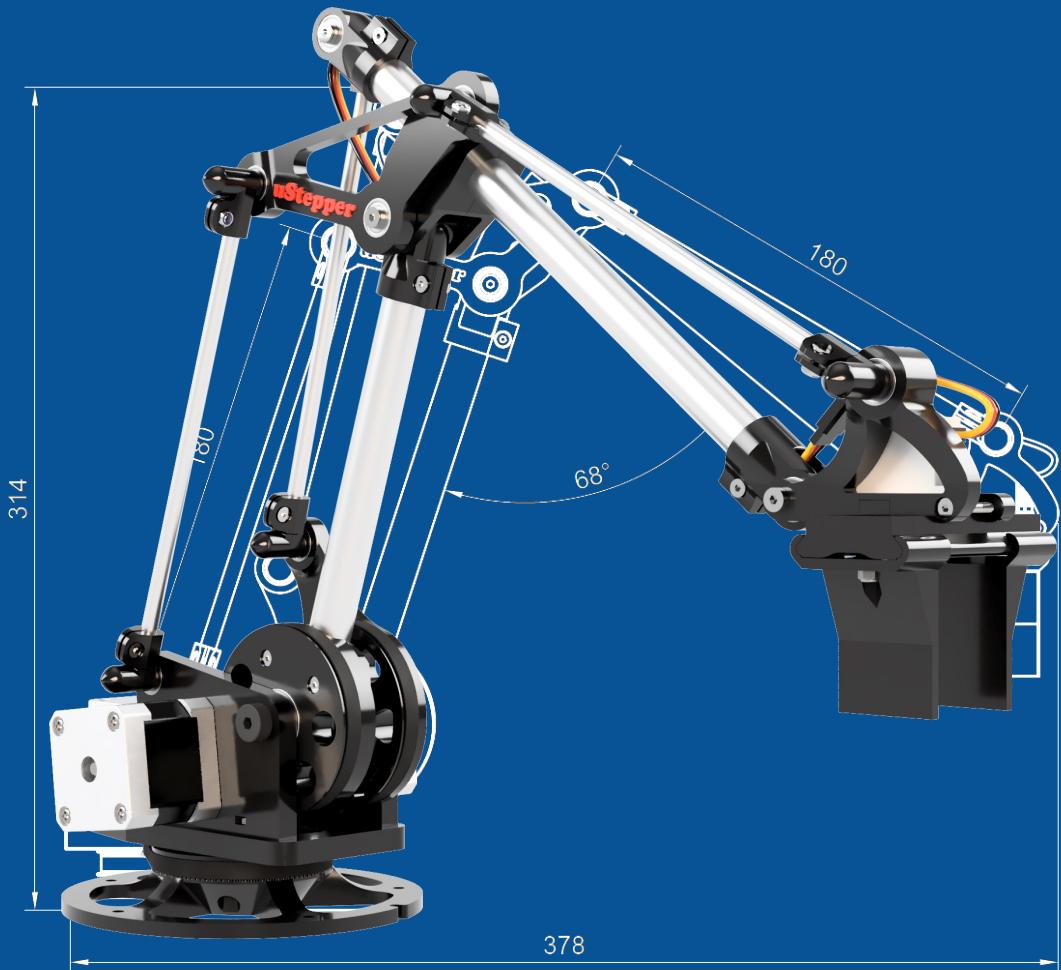
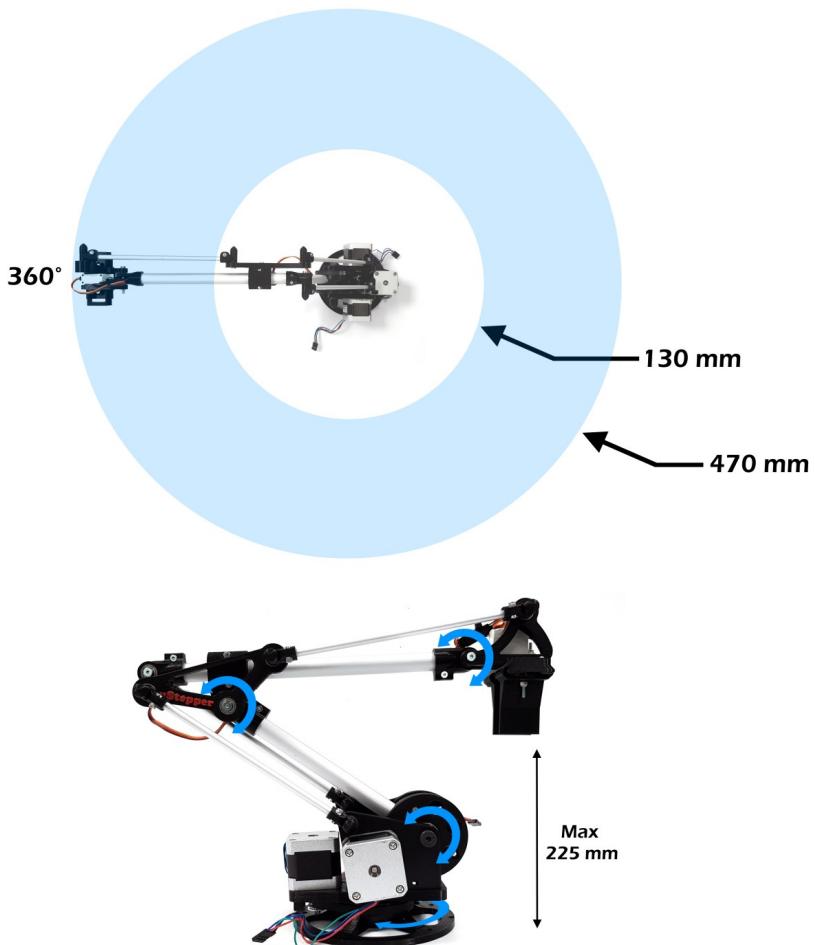


uStepper Robot Arm 4.0



Specifications

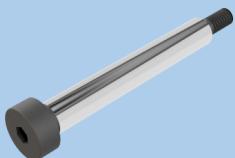


Weight (including stepper motors)	1460 g
Material	PLA plastic and Aluminum (tubes)
No. of axes	3
Maximum lift (close to base / furthest from base)	700 g / 350 g
Gear ratios (all axes)	5.1:1
Stepper motor torque	0.42 Nm
Mini servo torque	0.25 Nm @ 5 V

Bill Of Materials



Bill Of Materials



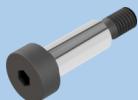
1 x shoulder bolt 7379-8-M6-55



1 x Tube 15 mm x 225 mm



3 x M4 x 35 mm



1 x shoulder bolt 7379-8-M6-20



1 x Tube 15 mm x 155 mm



7 x M3 nut



5 x 608ZZ Bearing



12 x 624ZZ Bearing



1 x 51105 Bearing



1 x F8-16M Bearing



3 x GT2 20T motor gear



3 x Belt GT2 228



2 x Tube 6 mm x 170 mm
1 x Tube 6 mm x 180 mm



8 x M4 SL nut



2 x M3 x 6 mm



26 x M3 x 10 mm



7 x M3 x 20 mm



3 x M3 x 25 mm



5 x M4 x 20 mm



5 x M4 washer



1 x M6 washer



1 x M8 washer

Bill Of Materials



1 x HK15148B Digital MG Servo



1 x 60 cm Servo Cable



1 x 25T x 20 mm Servo Horn Set

1:1 Nuts & Bolts

M3 x 6 mm



M3 x 10 mm



M3 x 20 mm



M3 x 25 mm



M4 x 20 mm



M4 x 35 mm



M6 x 20 mm



M6 x 55 mm



M3 nut



M4 nut



M6 nut

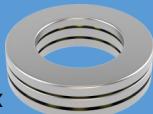


Robot Arm Assembly

1



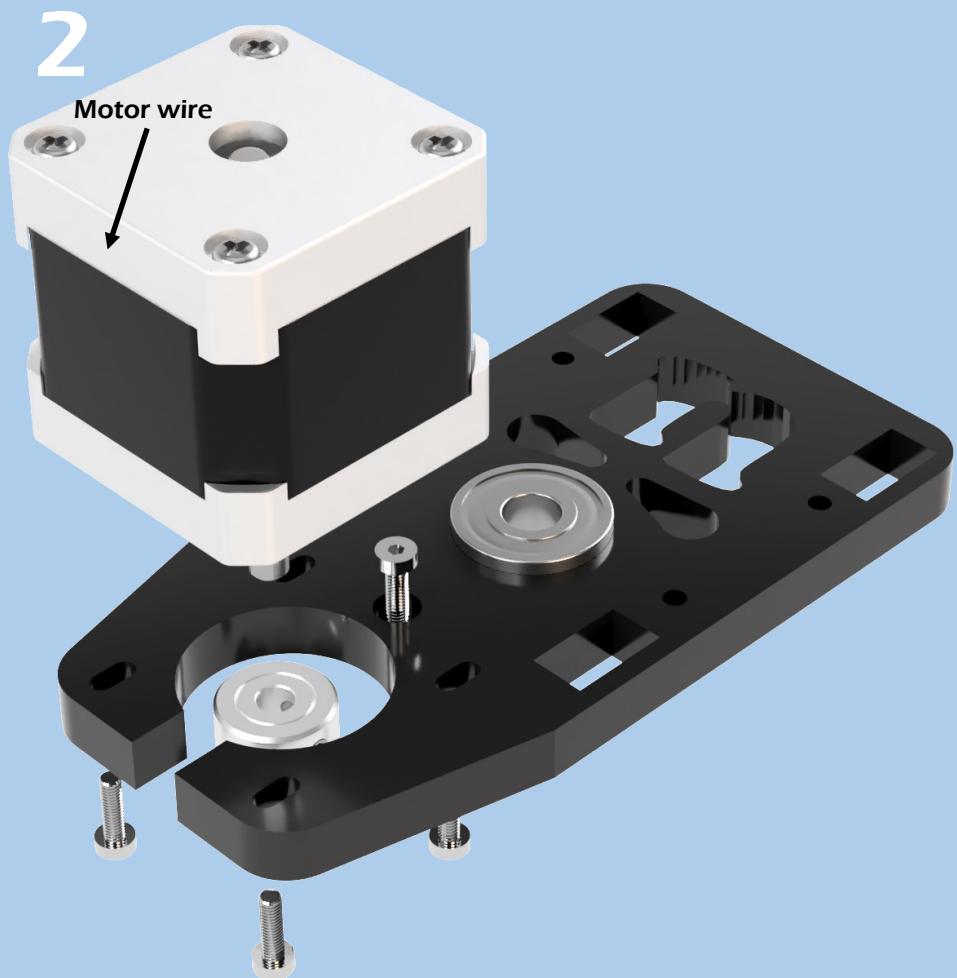
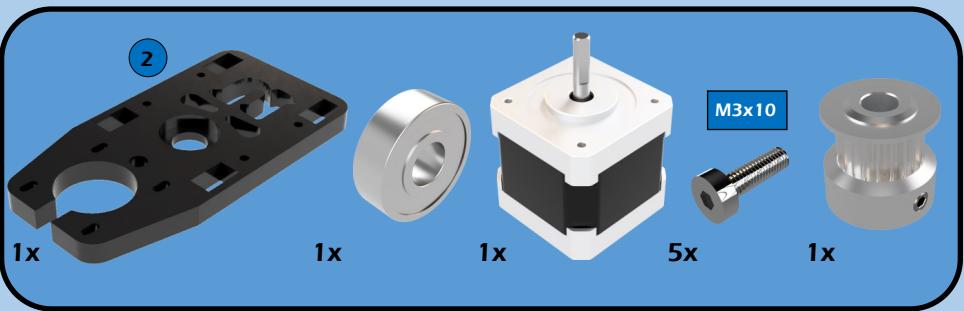
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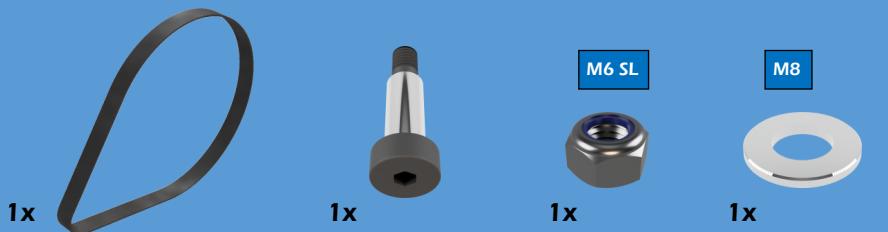


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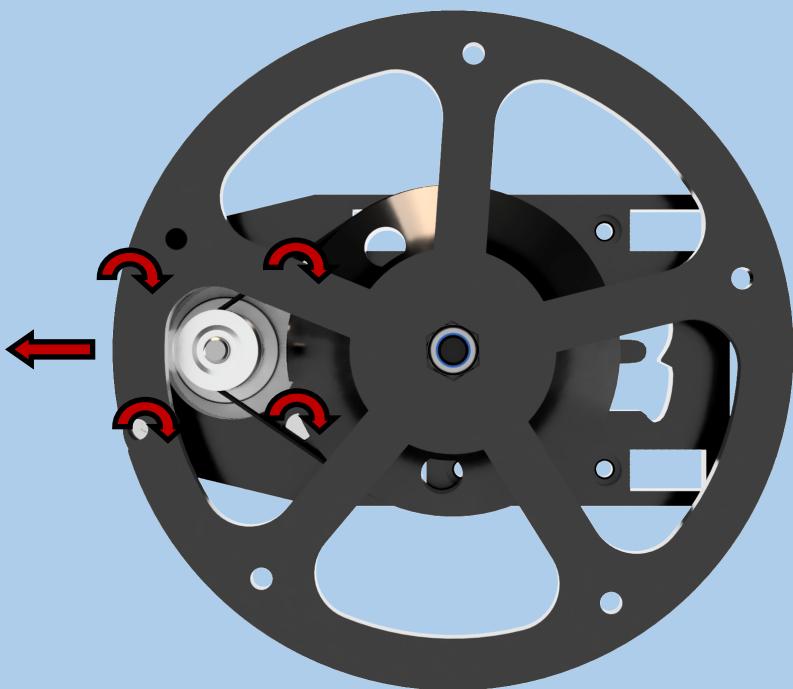
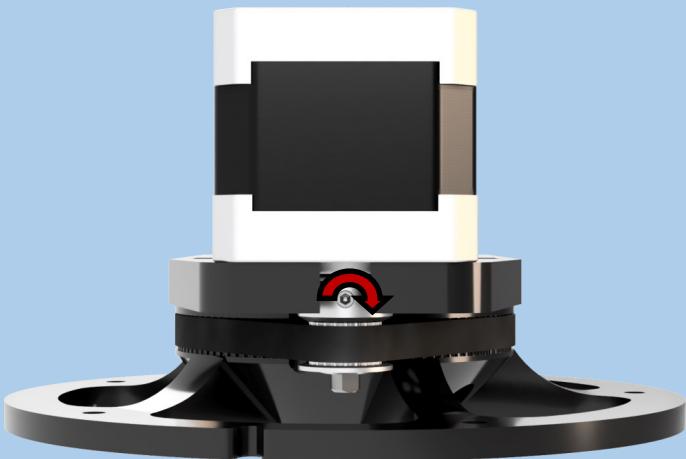




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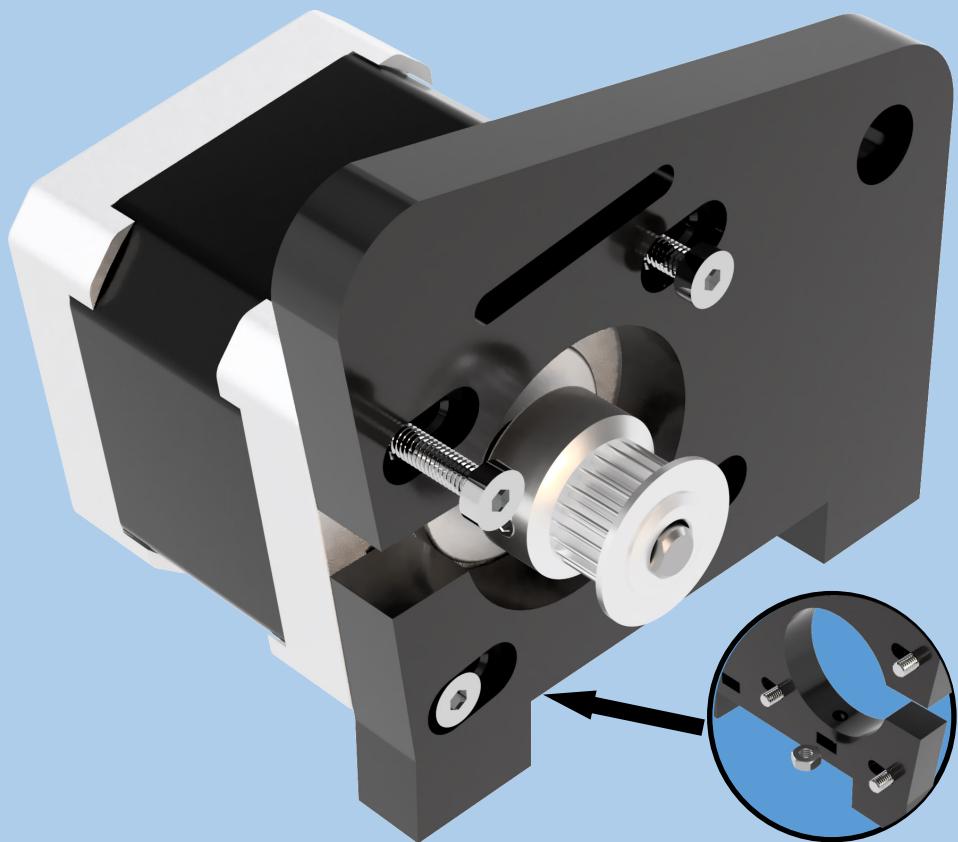
4



3



5



5



1x

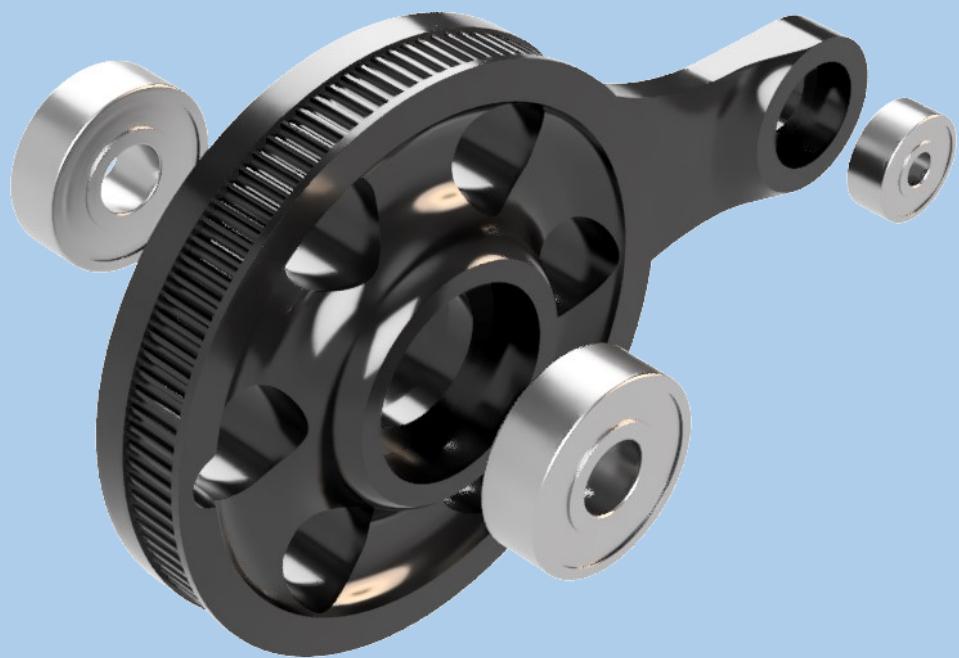


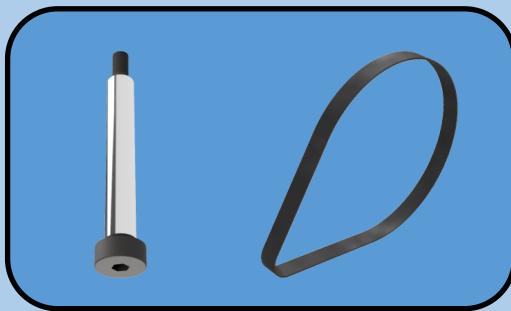
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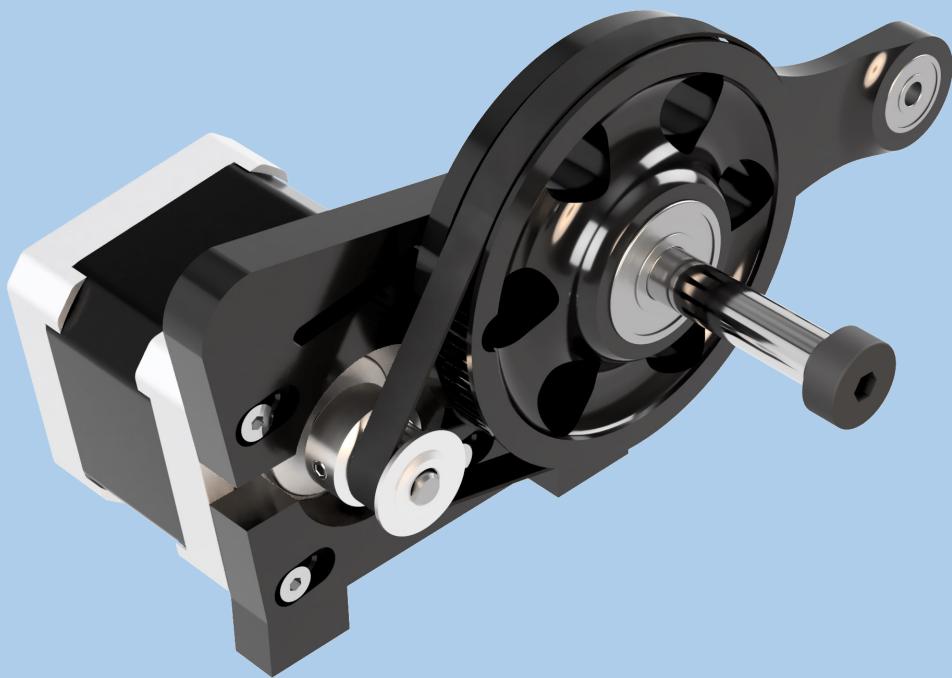
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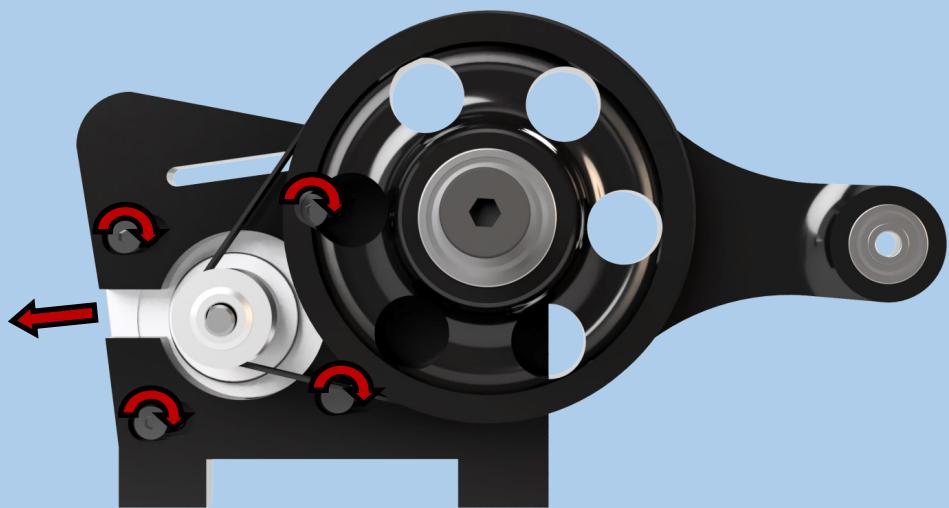
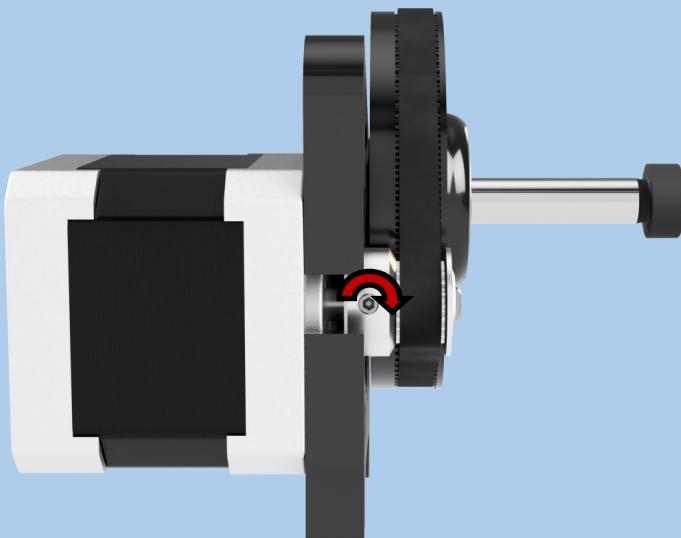


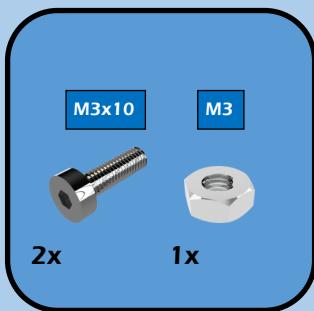


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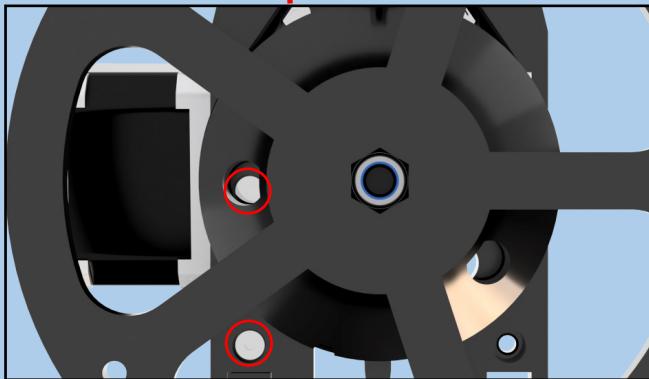


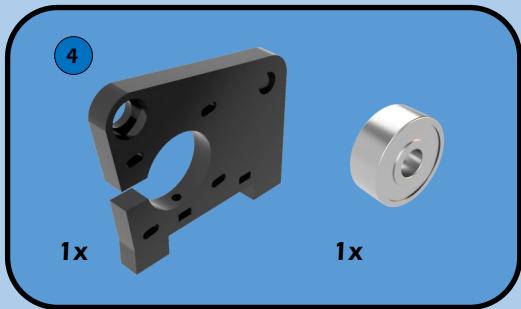
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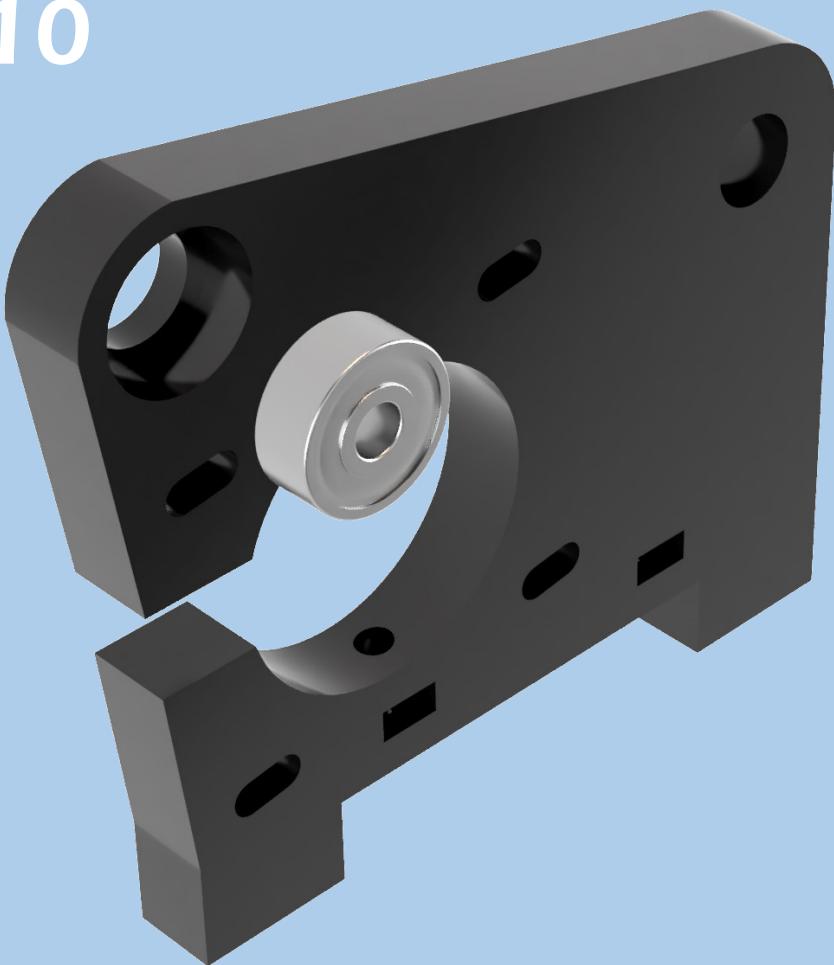


9





10





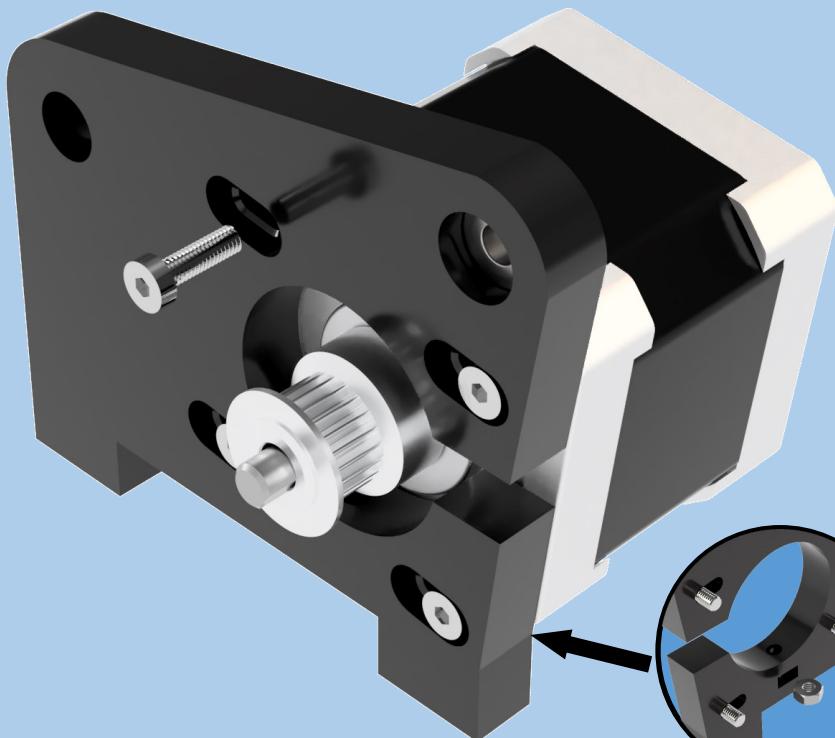
M3x10

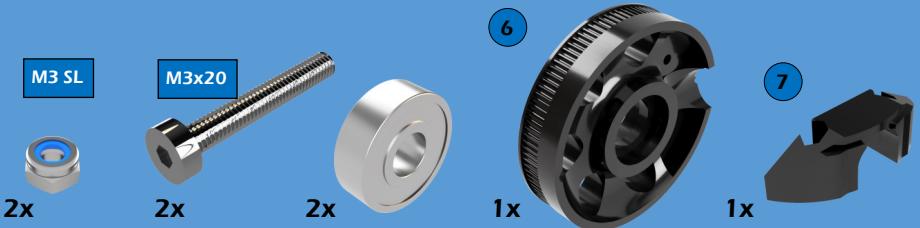


M3

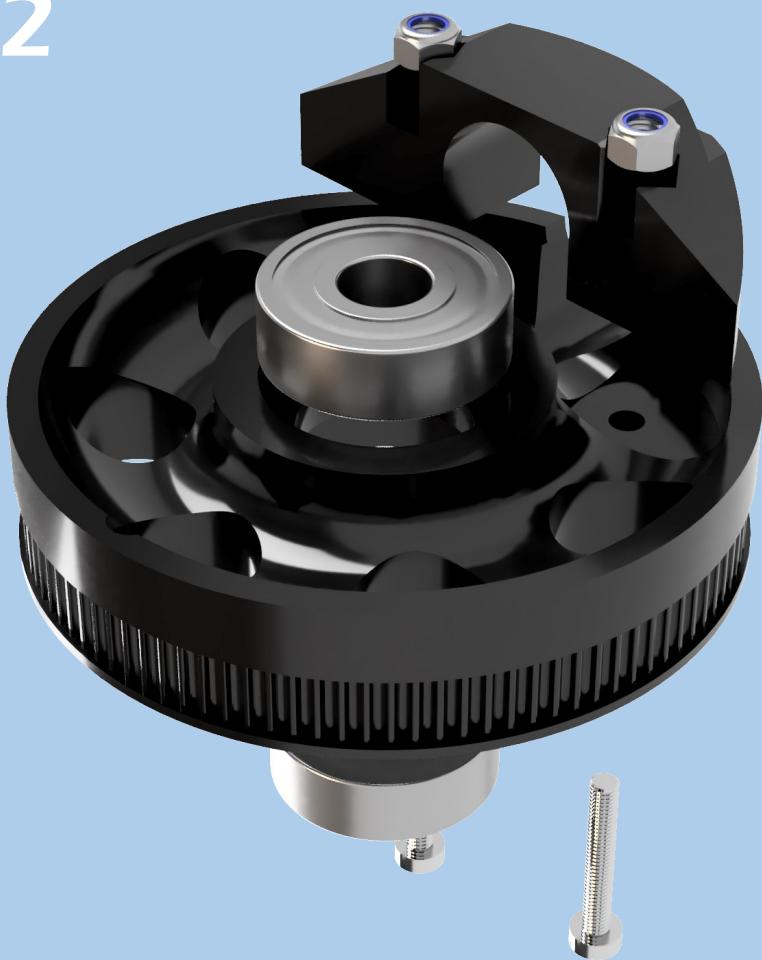


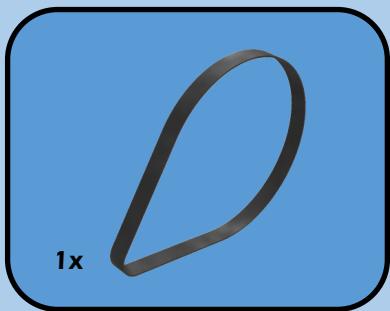
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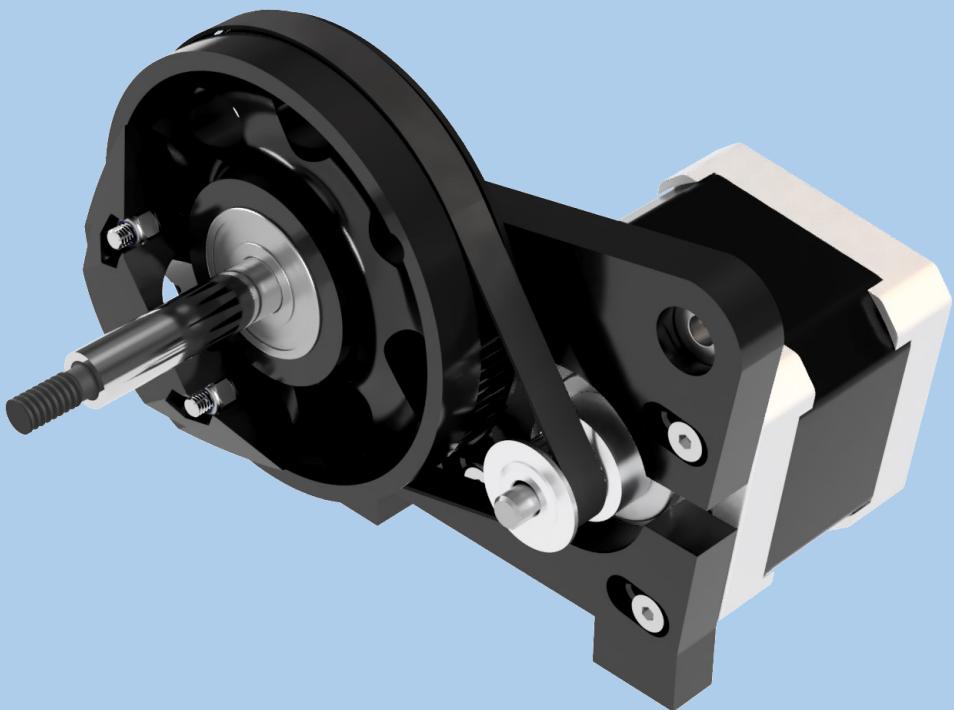
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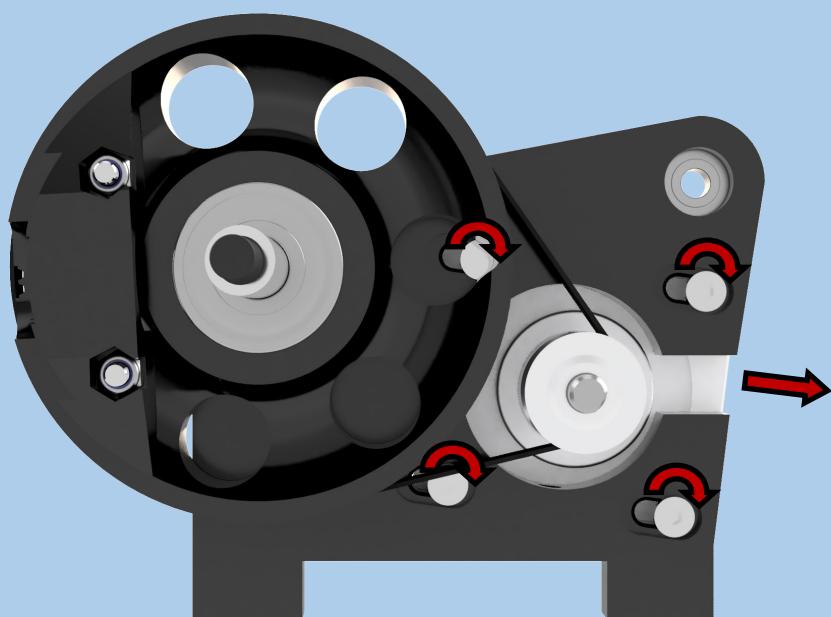
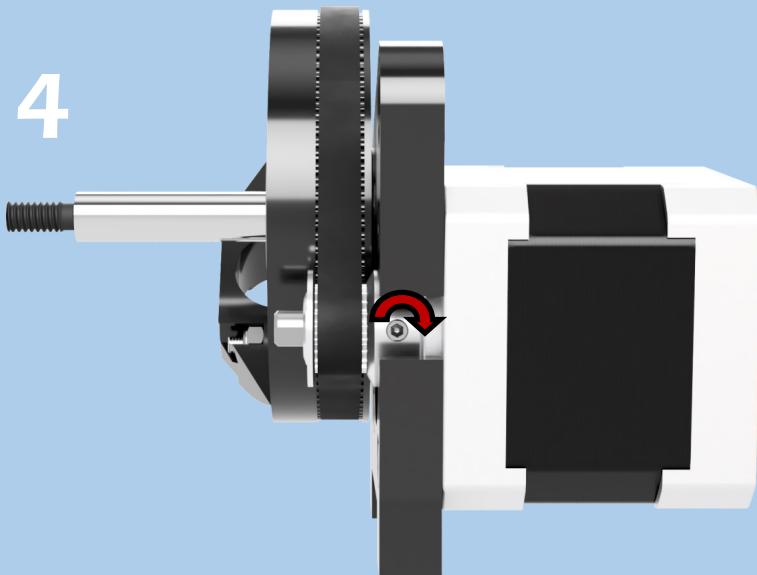


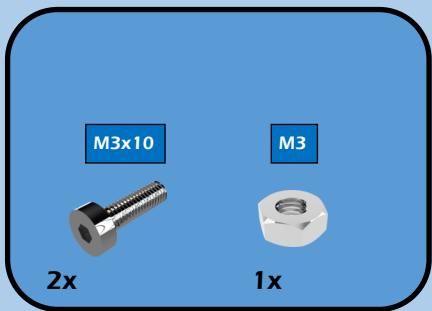
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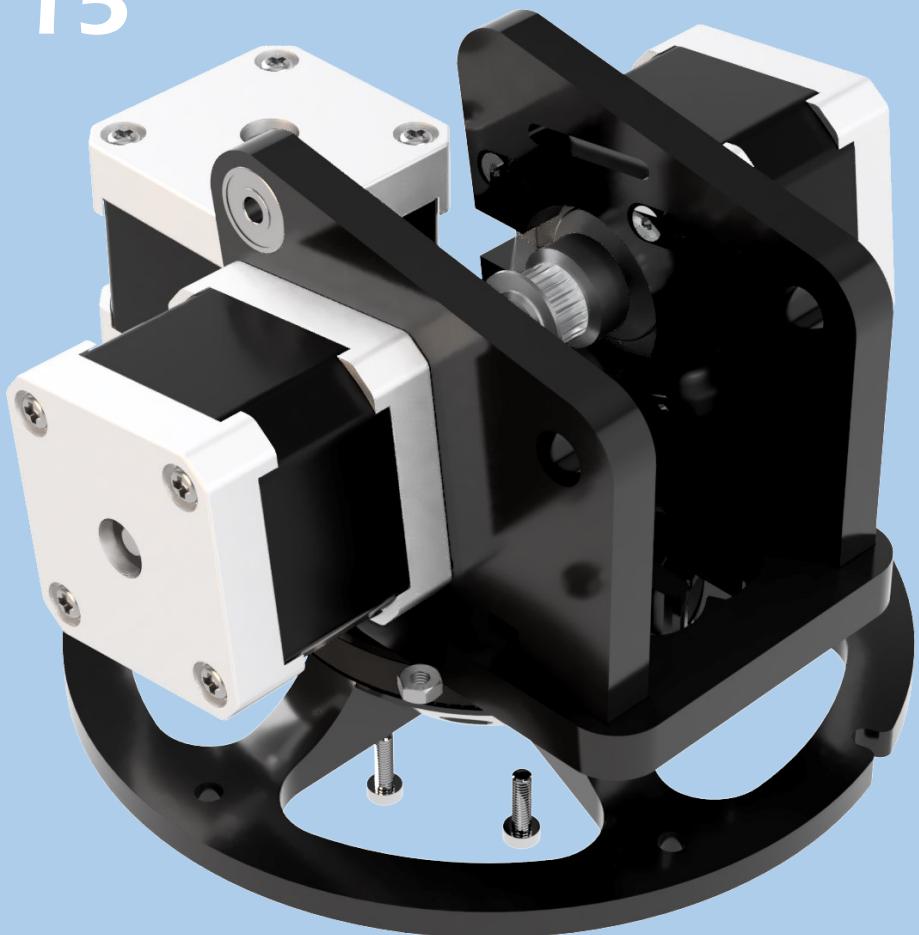


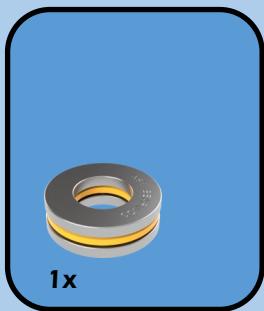
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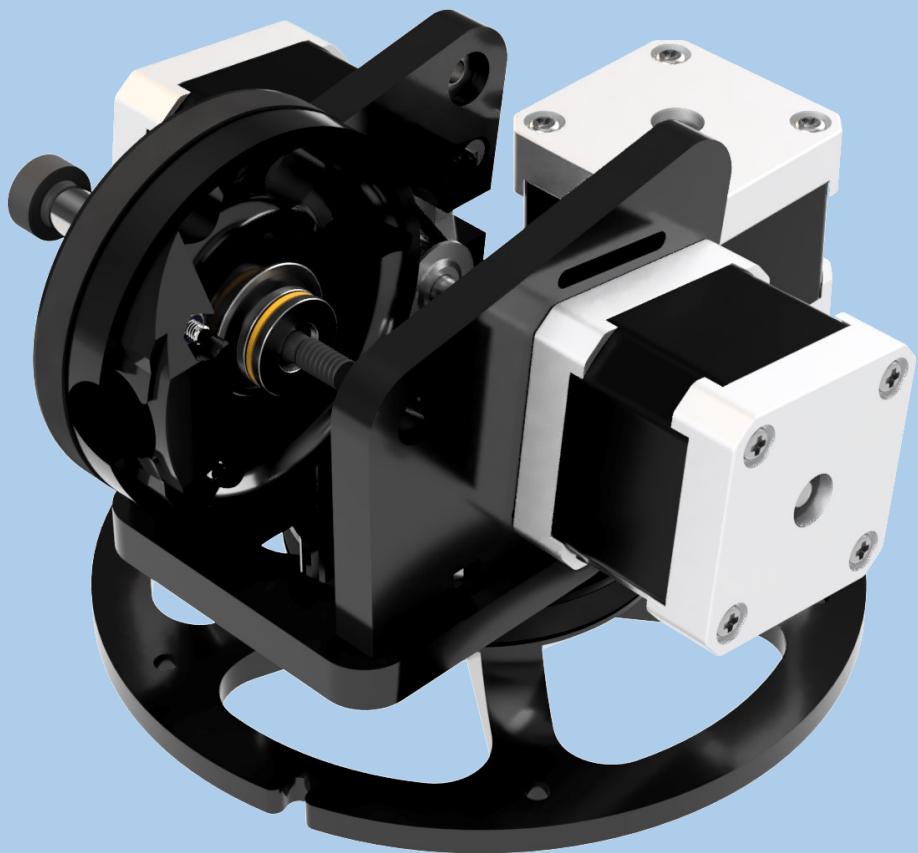


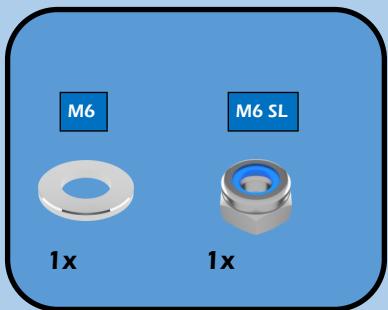
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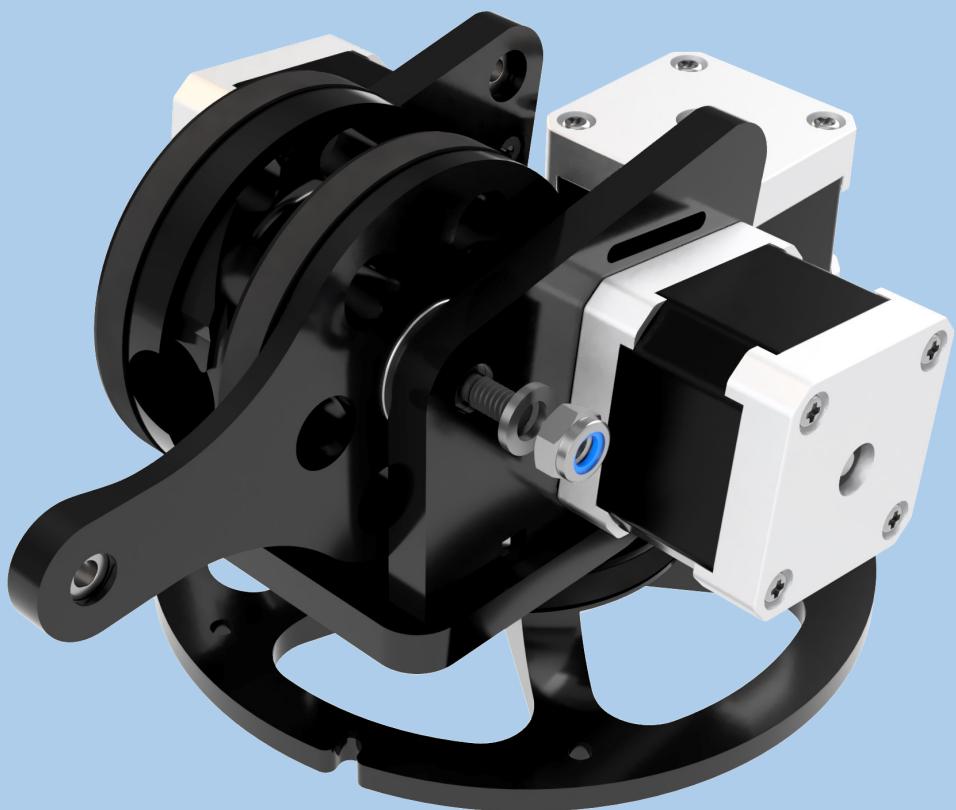


16





17



10



3x



3x



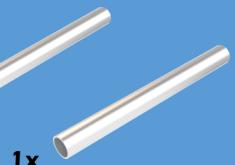
3x



6x



1x

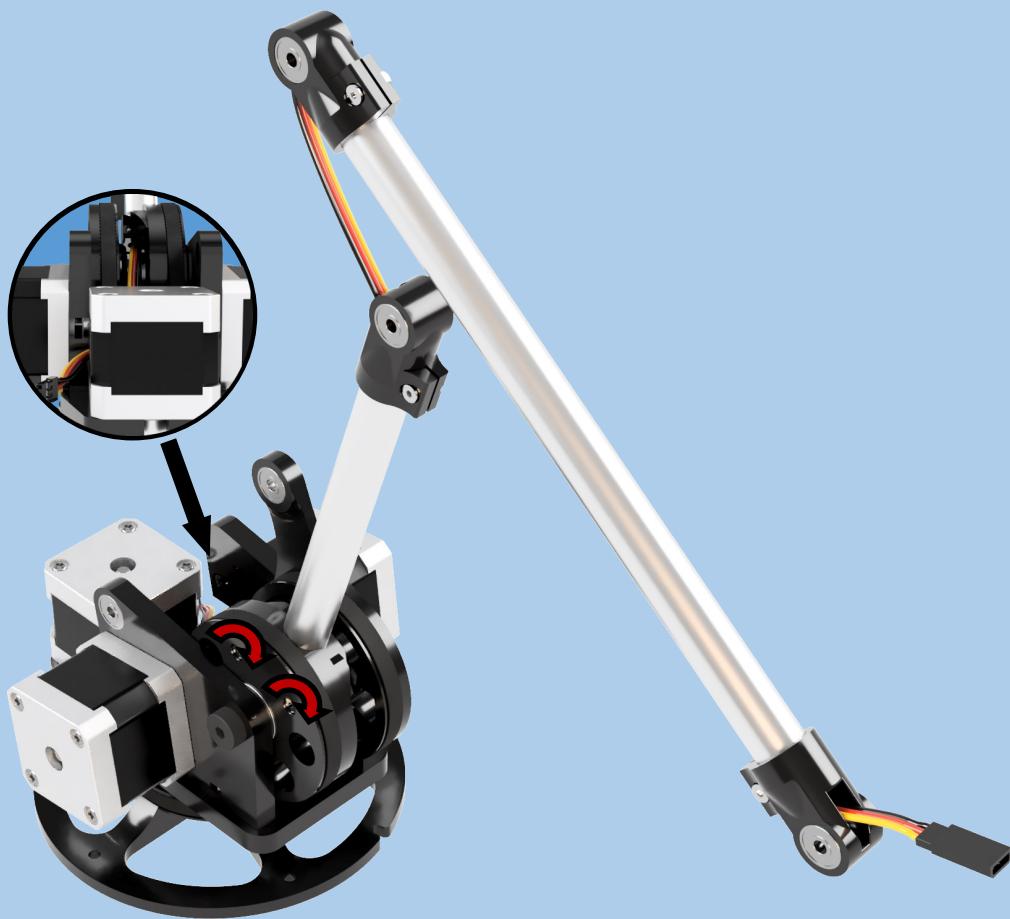


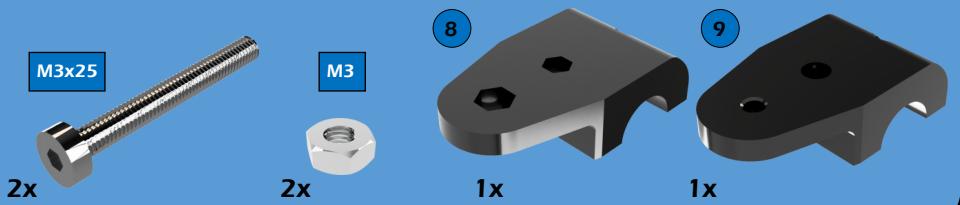
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18



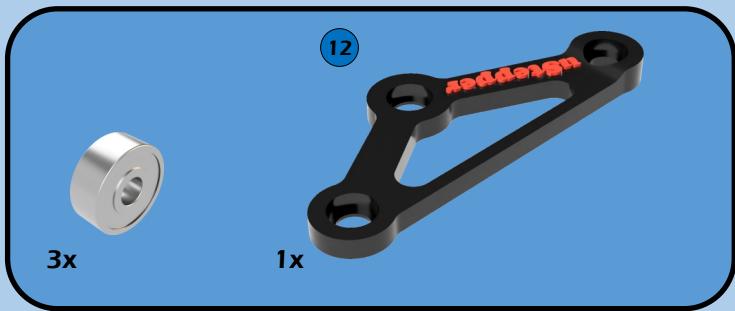
19





20





21



M4x35



1x

M4 SL



1x

M4



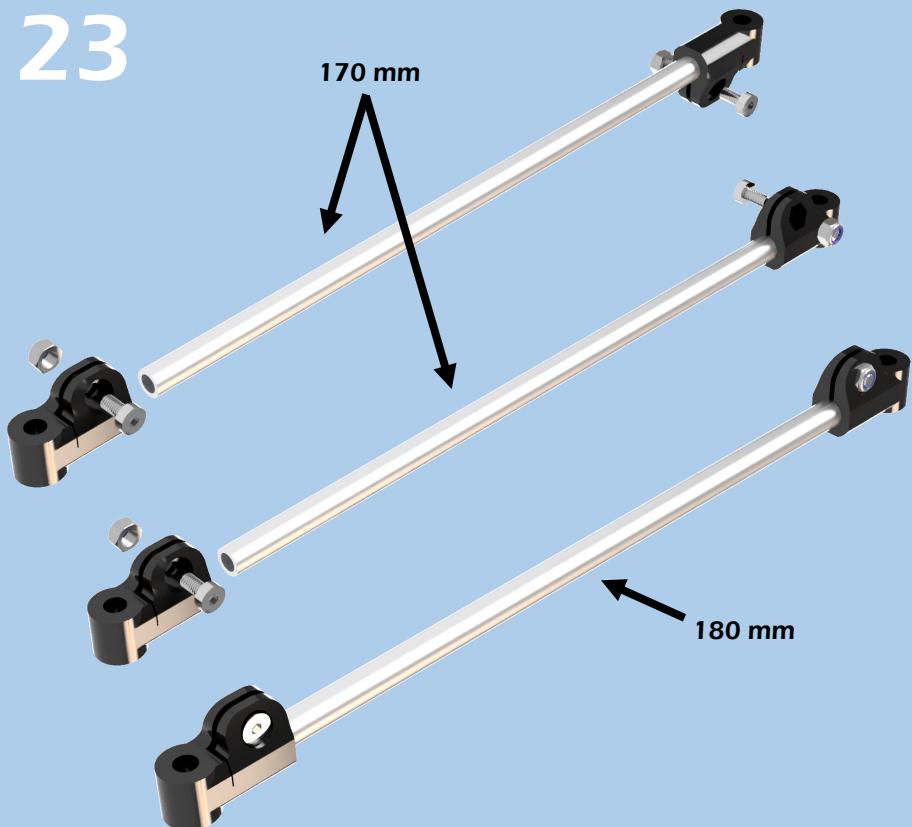
3x

22





23



M4x35

1x

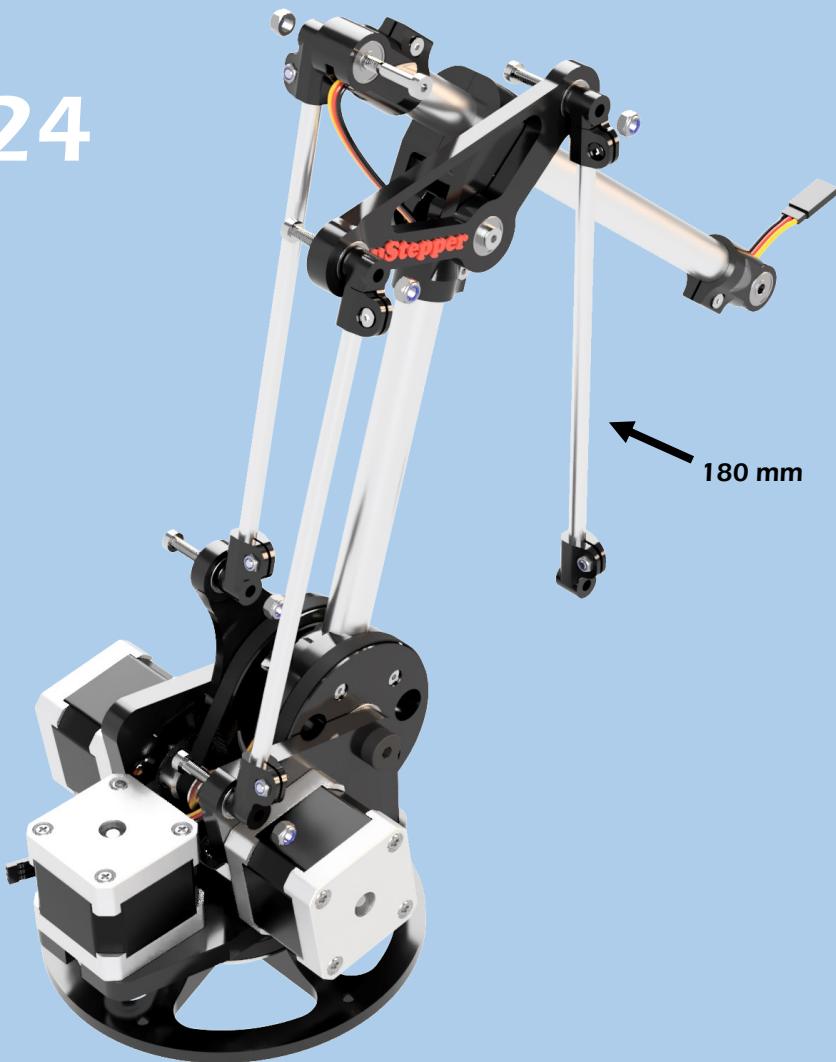
M4x20

4x

M4 SL

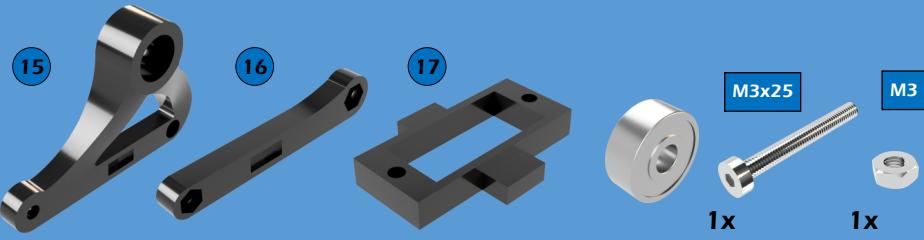
5x

24

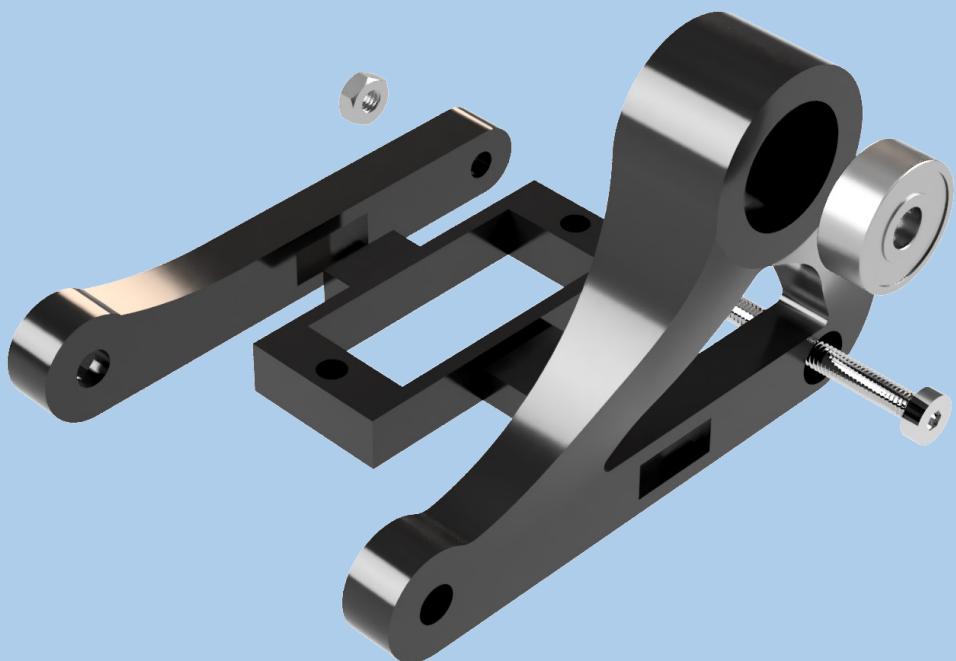




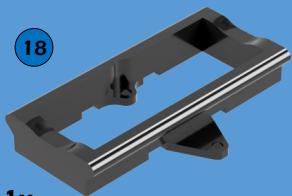
Robot Arm Gripper Assembly



25



18



1x

M3x20



2x

M3 SL

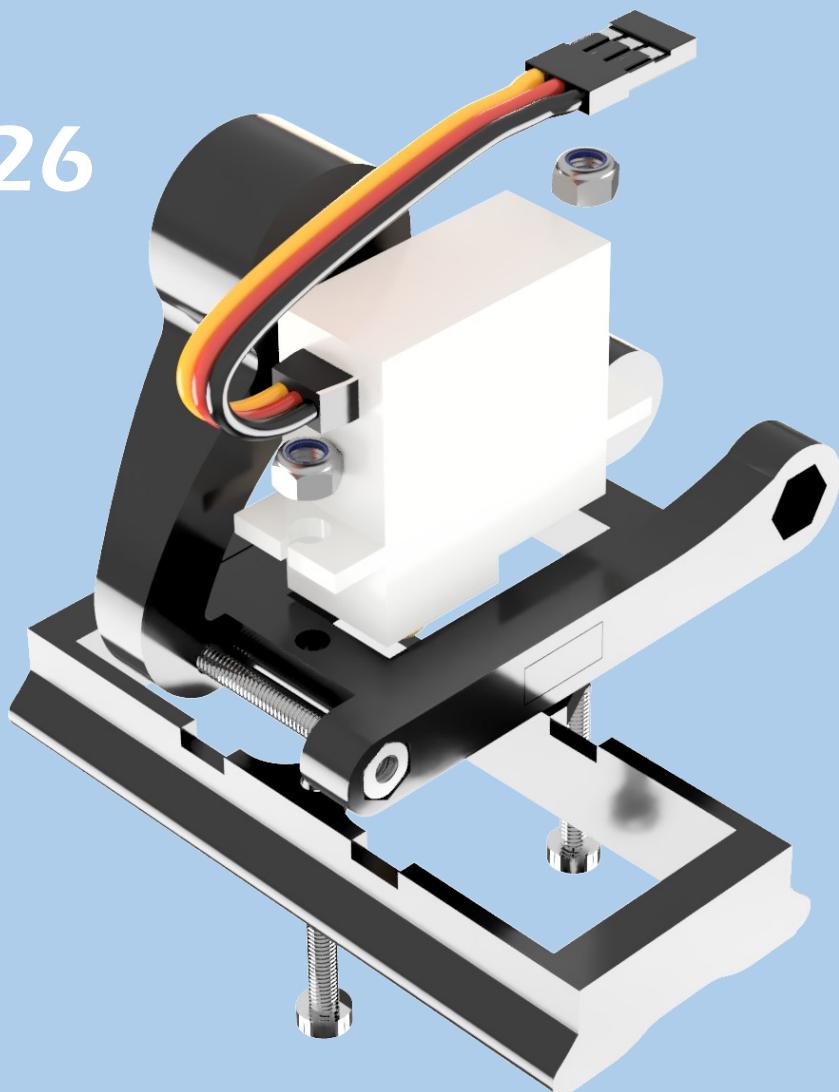


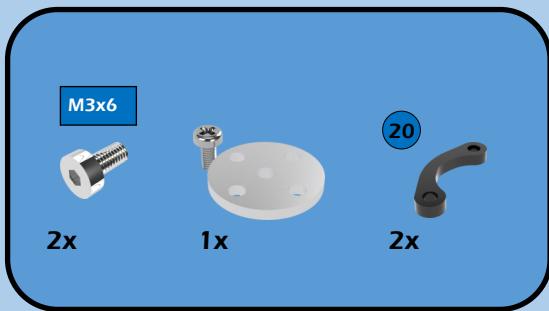
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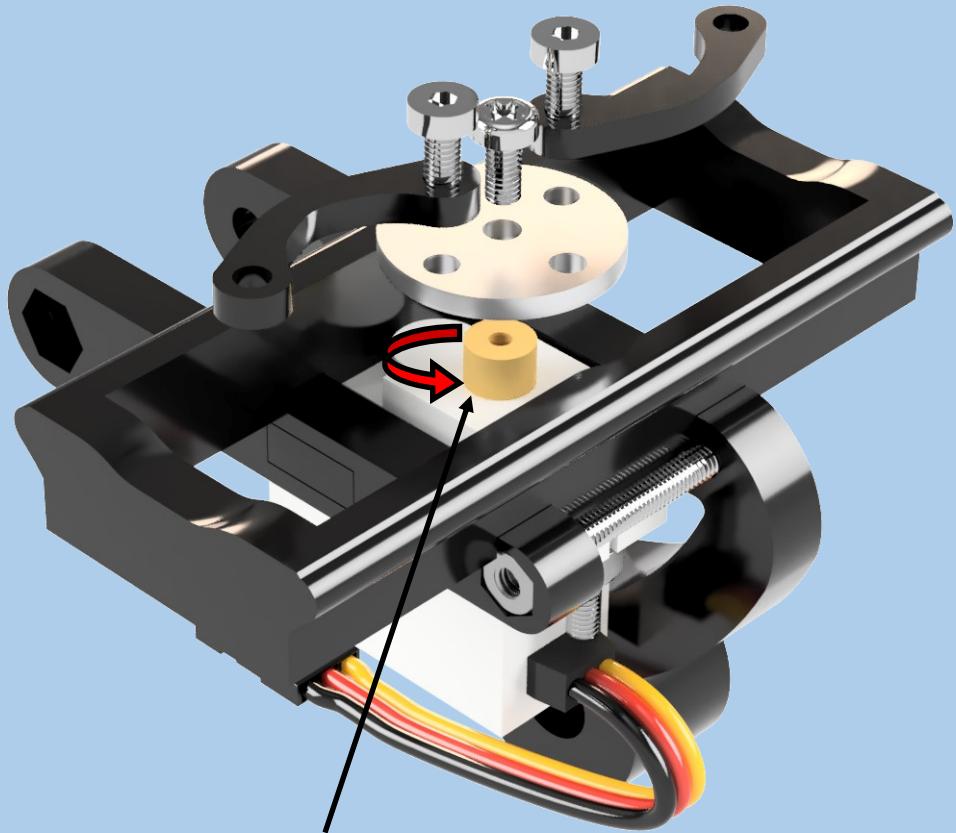
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26

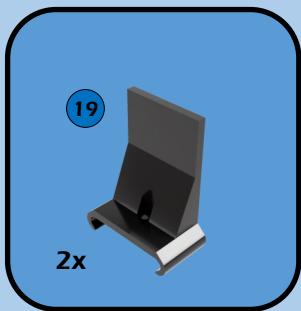




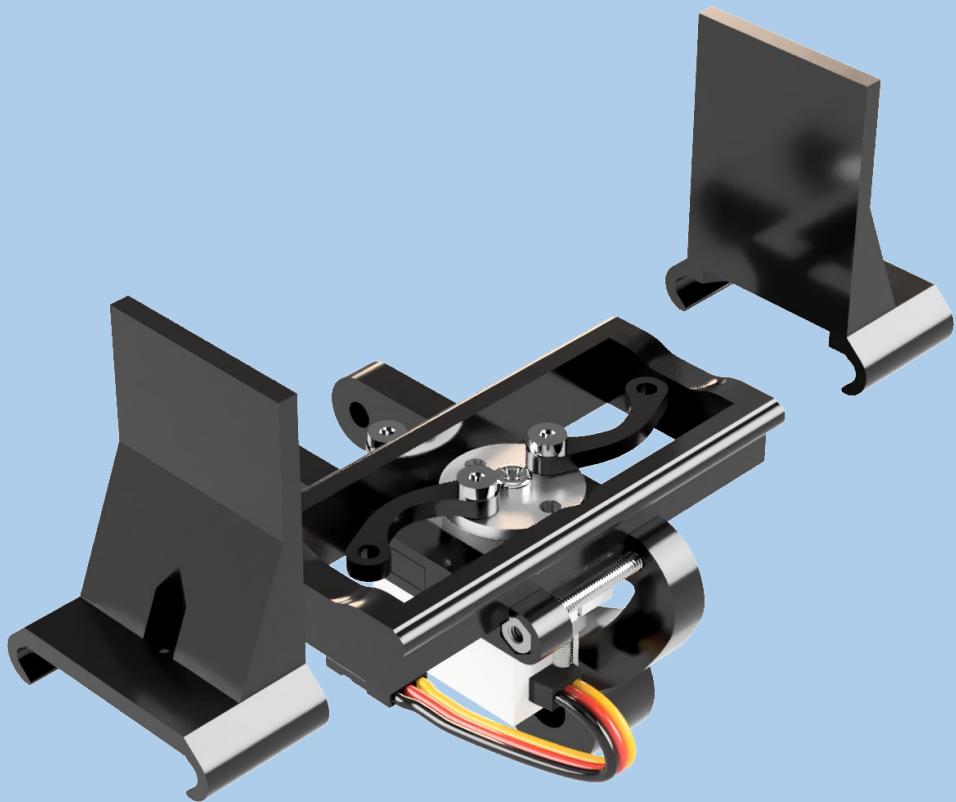
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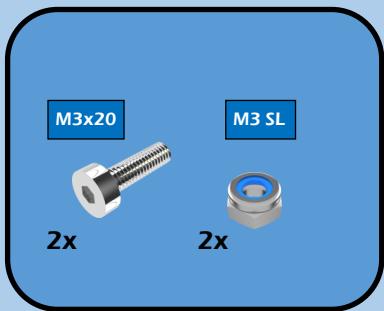


Make sure that the servo is at the furthest counter clockwise position

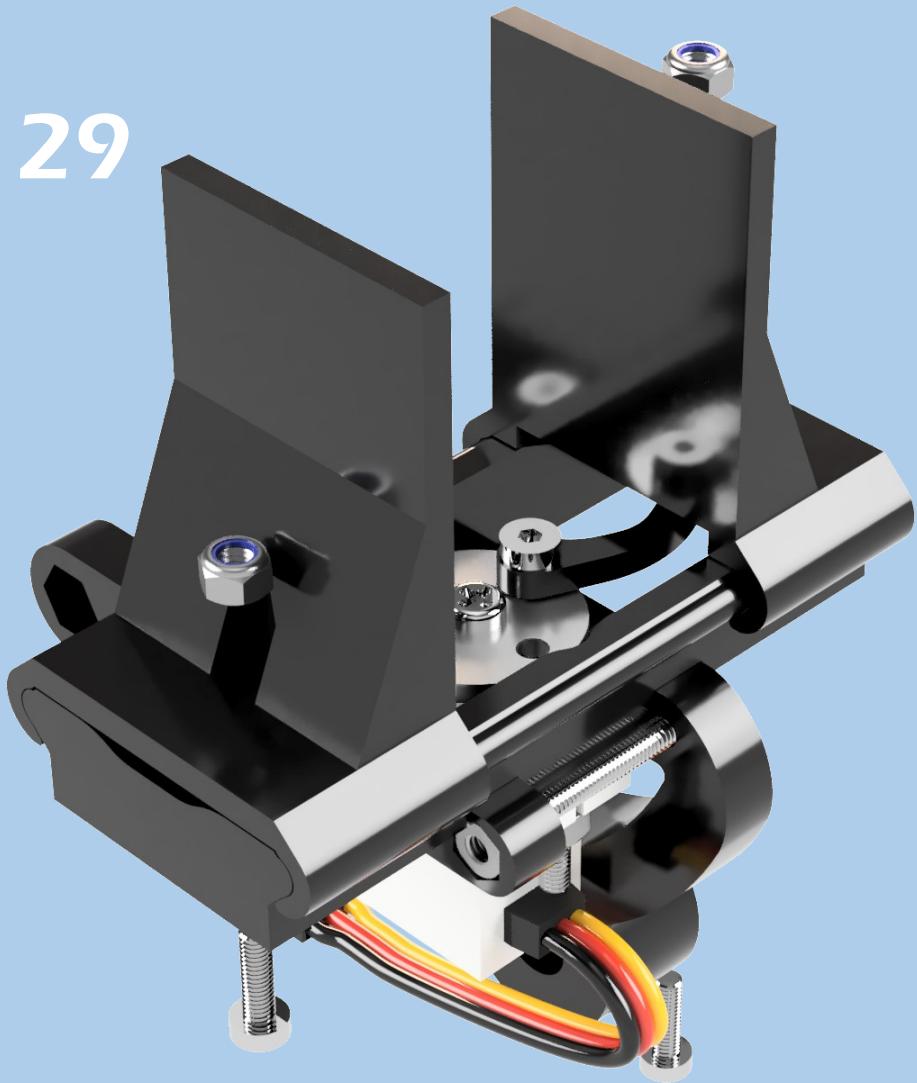


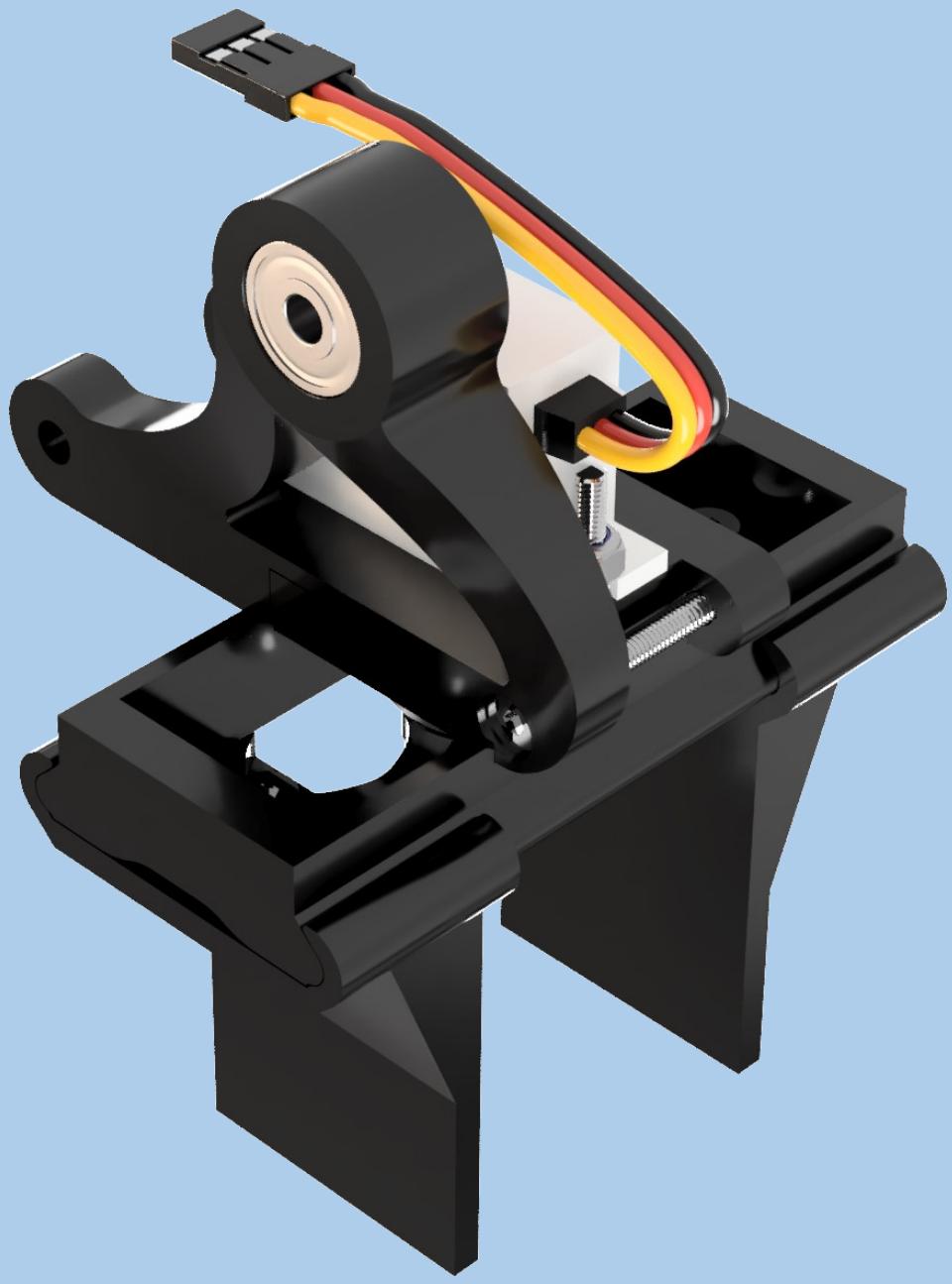
28





29





Robot Arm Gripper Mounting

M4x35



1x

M4x20



1x

M4 SL



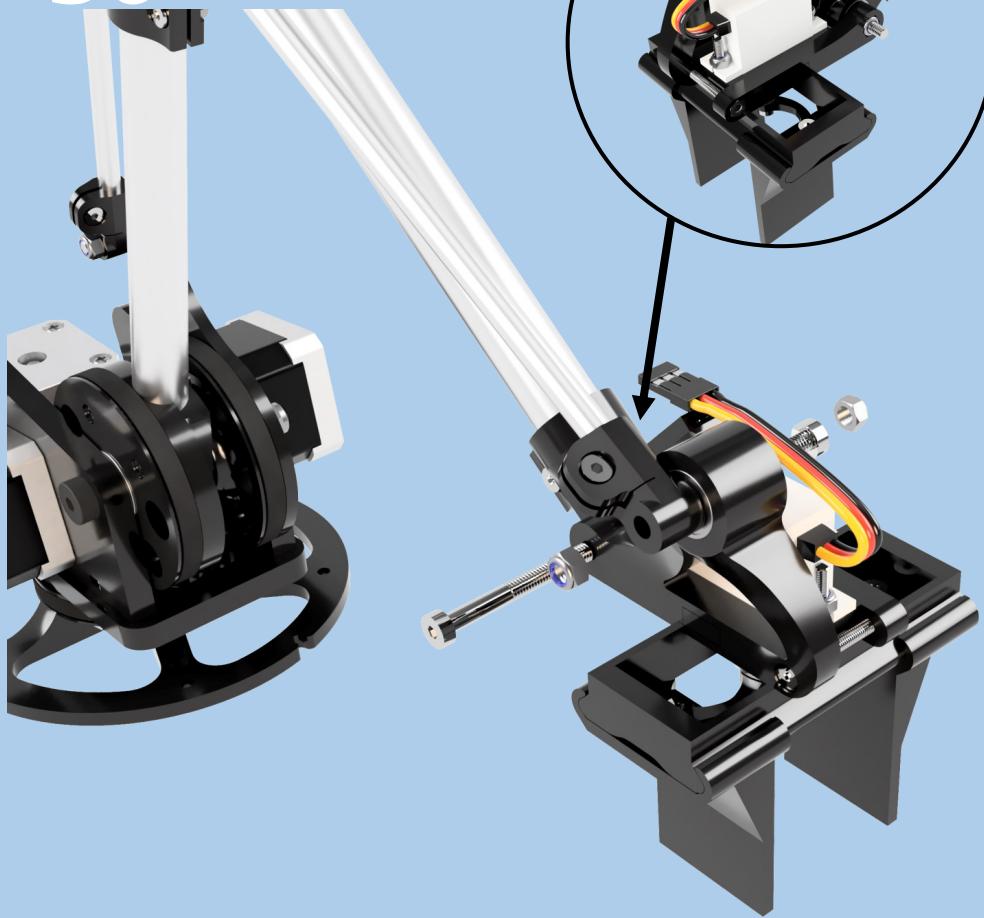
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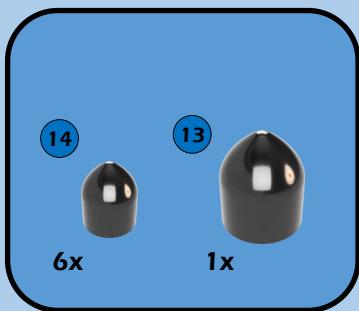
M4



2x

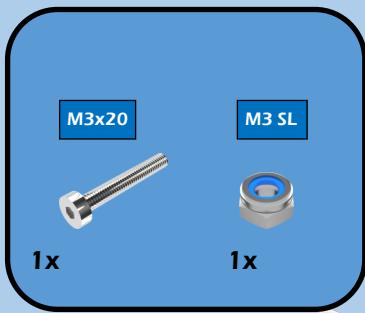
30





31





32



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1.2 uStepper ApS and/or ON Development IVS (or any individuals affiliated with either of the two companies) can not be held responsible for any damage inflicted upon assembly of the uStepper Robot Arm. This includes damage to 3D printed parts, which must be considered to be of prototyping quality compared to injection moulded parts. Care must be taken while assembling 3D printed parts, and use of excessive force may lead to damage of the parts.

1.3 By using the uStepper products (including, but not limited to, hardware and software) you acknowledge that uStepper ApS and/or ON Development IVS (or any individuals affiliated with either of the two companies) can not be held responsible for any personal injuries and/or damage to any 3rd party hardware that may occur when using the uStepper products.

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1.5 Nothing in these Terms and Conditions shall be construed so as to hold uStepper ApS and/or ON Development IVS liable for death or personal injury as a result of the negligence of uStepper ApS and/or ON Development IVS or that of its employees or agents.

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If any of these Terms and Conditions should be determined to be invalid, illegal or unenforceable for any reason by any court of competent jurisdiction then such Term or Condition shall be severed and the remaining Terms and Conditions shall survive and remain in full force and effect and continue to be binding and enforceable.

