**Description** - Called when a new trip is uploaded to the service to process the trip. Once the trip is successfully uploaded the app waits to receive a push notification which notifies the app to make a request to pull the processed trip details

**Request Url** :- <https://uapi.drivedq.com/mob/post>

**Method** : **POST**

**Headers :**

**Mobkey**: yKJB5Cn5T99XZptJma6H

**Appversion**: 93

**Request body** :

{"I":[{"A":"SetDataPointCollection","B":"","Z":"\u003d\u003d"}],"KV":{"TripSeconds":"141","TripClientGUID":"e680c602-7bf2-4235-a954-b9f0aec29789","StartReason":"ab","ClientDriverToken":"JVZ3UCubJby6GdUGKCrV","TotalPoints":"151","StopReason":"il"}}

**Decoded Value of Z :**

{

"Accuracys": [],

"DPAMeta": {

"AutoStarted": false,

"ELogs": [

"12-08 :: 11.47.21.415 [TripRecordingService] gone into foreground",

"12-08 :: 11.47.21.522 [UAAppClass] requestActivityRecognitionUpdates onSuccess",

"12-08 :: 11.47.21.699 [TripRecordingService] first real location detected",

"12-08 :: 11.47.21.929 [ReverseGeocodeJobService] onStartJob",

"12-08 :: 11.47.23.509 [ReverseGeocodeJobService] r-geo-coded start | Flinders Walk, Melbourne",

"12-08 :: 11.50.50.894 [TripRecordingService] stopping TripRecordingService IDLE\_THEN\_LOST\_GPS\_SIGNAL | 21223",

"12-08 :: 11.50.52.594 [TripRecordingService] onDestroy StopReason: IDLE\_THEN\_LOST\_GPS\_SIGNAL",

"12-08 :: 11.50.52.662 [TripRecordingService] BAT\_START:18% BAT\_STOP:18% | LIFETIME:3 min, 31 sec",

"12-08 :: 11.50.52.717 [UAAppClass] stopBeaconRangeScanning unbind",

"12-08 :: 11.51.38.204 [TripRecordingService] trip OK so far, but trimmed end | SIZE:185 INDEX1:179 INDEX2:172 INDEX3:185",

"12-08 :: 11.51.46.630 [TripRecordingService] au bounded",

"12-08 :: 11.51.46.678 [TripRecordingService] trip ok, will queue for delivery",

"12-08 :: 11.51.46.774 [TripRecordingService] ClientDriverToken: JVZ3UCubJby6GdUGKCrV"

],

"KV": {

"BuildVersion": "1",

"LastLonLat": "",

"StartReason": "ab",

"StopReason": "il"

},

"LastLonLat": "",

"RecNotes": [],

"SLogs": [

"12-08 :: 11.43.34.913 [ActivityDetectionService] (STILL 100%) ( | POINTS:-150 TP:-150 TH:285",

"12-08 :: 11.43.34.916 [TripRecordingService] first real location detected",

"12-08 :: 11.43.35.100 [ReverseGeocodeJobService] onStartJob",

"12-08 :: 11.43.36.624 [ReverseGeocodeJobService] r-geo-coded start | Flinders Walk, Melbourne",

"12-08 :: 11.43.43.509 [ActivityDetectionService] (STILL 100%) (m,m,m,m,m) | POINTS:-150 TP:-450 TH:285",

"12-08 :: 11.44.02.789 [ActivityDetectionService] (STILL 100%) (m,m,m,m,m) | POINTS:-150 TP:-750 TH:285",

"12-08 :: 11.44.03.697 [ActivityDetectionService] (STILL 100%) (m,m,m,m,m) | POINTS:-150 TP:-802 TH:285",

"12-08 :: 11.44.13.727 [ActivityDetectionService] (STILL 100%) (m,m,m,m,m) | POINTS:-150 TP:-1102 TH:285",

"12-08 :: 11.44.30.219 [ActivityDetectionService] (STILL 100%) (m,m,m,m,m) | POINTS:-150 TP:-1402 TH:285",

"12-08 :: 11.44.30.261 [ActivityDetectionService] last IV < 240s & total points < -1200",

"12-08 :: 11.44.30.331 [TripRecordingService] onStartCommand action: LOW\_POINTS\_AND\_OLD\_IN\_VEHICLE",

"12-08 :: 11.44.30.390 [TripRecordingService] onDestroy StopReason: LOW\_POINTS\_AND\_OLD\_IN\_VEHICLE",

"12-08 :: 11.44.30.465 [TripRecordingService] BAT\_START:18% BAT\_STOP:18% | LIFETIME:0 min, 56 sec",

"12-08 :: 11.44.30.543 [UAAppClass] stopBeaconRangeScanning unbind",

"12-08 :: 11.44.30.775 [TripRecordingService] onDestroy FP extremely short trip, ignored. SR: LOW\_POINTS\_AND\_OLD\_IN\_VEHICLE",

"12-08 :: 11.44.30.975 [TripRecordingService] first real location detected",

"12-08 :: 11.44.31.120 [RestartOptimizeTripDetectionJobService] onStartJob",

"12-08 :: 11.44.31.195 [OptimizeTripDetectionService] startService",

"12-08 :: 11.44.31.273 [ReverseGeocodeJobService] onStartJob",

"12-08 :: 11.44.31.528 [ReverseGeocodeJobService] r-geo-coded start | Grant Street - Stop 17, Melbourne VIC 3004, Australia",

"12-08 :: 11.44.39.259 [ActivityDetectionService] (STILL 100%) | POINTS:-150 TP:-150 TH:345",

"12-08 :: 11.44.49.106 [ActivityDetectionService] (STILL 100%) | POINTS:-150 TP:-450 TH:345",

"12-08 :: 11.45.00.068 [ActivityDetectionService] (STILL 100%) | POINTS:-150 TP:-750 TH:345",

"12-08 :: 11.45.11.223 [ActivityDetectionService] (STILL 100%) | POINTS:-150 TP:-1050 TH:285",

"12-08 :: 11.45.20.151 [ActivityDetectionService] (STILL 100%) | POINTS:-150 TP:-1350 TH:285",

"12-08 :: 11.47.07.822 [BluetoothTransitionBroadcastReceiver] onReceive",

"12-08 :: 11.47.17.999 [BluetoothTransitionBroadcastReceiver] onReceive",

"12-08 :: 11.47.20.066 [BluetoothTransitionBroadcastReceiver] ACTION\_ACL\_CONNECTED",

"12-08 :: 11.47.21.062 [TripRecordingService] onCreate",

"12-08 :: 11.47.21.318 [TripRecordingService] onStartCommand action: AUTO\_START\_VIA\_BT"

],

"TLogs": [

"IS OPTIMIZED IN FOREGROUND"

]

},

"Lats": [],

"Longs": [],

"Utcs": [],

"Velos": [],

"Weather": [],

"ZAccuracys": [

3,

0,

2,

-1,

1,

**:**

**:**

**:**

1

],

"ZLats": [

-37819226,

-94,

-96,

-96,

-94,

-97,

-95,

-97,

-96,

-97,

**:**

**:**

**:**

0

],

"ZLongs": [

144969516,

35,

35,

35,

35,

35,

**:**

**:**

**:**

0

],

"ZUtcs": [

1597213041850,

1885,

115,

998,

**:**

**:**

**:**

589

],

"ZVelos": [

114,

0,

0,

0,

0,

**:**

**:**

**:**

25,

0,

0,

0,

0,

0,

0,

0,

0

]

}

**Response** :

{

"I": [

{

"A": 22,

"B": "eyJPdGhlckluZm8iOltdLCJUcmlwVG9rZW4iOiJzZUtMYldpNTRwTFlKaVhSeTdCSiIsIkNsaWVudERyaXZlclRva2VuIjoiSlZaM1VDdWJKYnk2R2RVR0tDclYiLCJWYWxpZGF0ZWQiOnRydWV9",

"E": "",

"K": "",

"Z": ""

}

],

"KV": {}

}

**Decoded value of B :**

{

"OtherInfo": [],

"TripToken": "EtzfAmDE6DzpcowHCAx8",

"ClientDriverToken": "JVZ3UCubJby6GdUGKCrV",

"Validated": true

}