**Conditions that trigger data point collection for a trip.**

**1)** The initial and default **distance\_filter** is **1000 meters** when the app starts.

**2)** The app constantly keeps detecting motion change or GPS/location change. If the distance\_filter is exactly **1000 meters**, no ongoing trip is found, and when we receive one GPS location or activity(in\_vehicle, bicycle), we deduct **300m** from the distance\_filter.

**3)** If there is a motion detection or GPS change, the app then checks if accuracy < **50 m** , speed >= **10m/h** and action\_type is **in\_vehicle**.

**4)** If the above is true, then the app checks if the vehicle is in cooldown mode, if yes then **distance\_filter = distance\_filter + 1500**.

**5)** If not in cooldown mode, the minimum distance calculated based on various conditions as follows :-

|  |  |
| --- | --- |
| **Condition** | **Distance\_filter Value** |
| **5.1)** action \_type is **in\_vehicle** | Distance\_filter = distance\_filter - 100m |
| **5.2)** Action\_type is **in\_vehicle**, accuracy < **50m** and speed>=**0m/h** | Distance\_filter = distance\_filter - 250m |
| **5.3)** Action\_type is **in\_vehicle**, accuracy **100m** and speed>=**8m/h** | Distance\_filter = distance\_filter - 350m |
| **5.4)** Action\_type is **in\_vehicle**, accuracy < **50m** and speed>=**10m/h** | Distance\_filter = distance\_filter- 400m |

**6)** The app then starts scanning for a beacon only when the below conditions are satisfied :

|  |
| --- |
| **Condition** |
| **6.1)** action \_type is **in\_vehicle** |
| **6.2)** Accuracy < 50 |
| **6.3)** Speed >= 10 m/h |
| **6.4)** Device is not in cool down mode |
| **6.5)** No trip is ongoing |

**7)** Once the correct beacon is found with the current vehicle/driver profile and **distance\_filter <100m eg. 90m**, the app starts to record the trip.

**8)** The first set of data points is collected when location is detected after first becon discovery and connection.

**9)** Thereafter, every **90m** (our calculated distance\_filter), the app requests for location and other data points to be collected.

**10)** Once the car halts or slows down, if the activity type is "**in\_vehicle**" or "**bicycle**" and the accuracy and speed change is detected to be lower than the above values, here after, the app starts adding to the distance\_filter in the below conditions

* Distance\_filter calculation based on activty\_type changes (**in\_vehicle**, **bicycle**, **running** or **walking**)

|  |  |
| --- | --- |
| **Condition** | **Distance\_filter Value** |
| **10.1)** action \_type is “**bicycle”** | Distance\_filter = distance\_filter +100m |
| **10.2)** Confidence **100%** & motion type is not “**in\_vehicle**” | Distance\_filter = distance\_filter +150m |
| **10.3)**action\_type is not **“in\_vehicle”** | Distance\_filter = distance\_filter +50m |

* Distance\_filter calculation based on GPS location changes.

|  |  |
| --- | --- |
| **Condition** | **Distance\_filter Value** |
| **10.4)** action\_type is “**in\_vehicle”,** location accuracy **< 50m,** speed **>= 10m/h** andCoolDown mode is **active** | Distance\_filter = distance\_filter +1000m |
| **10.5)** action\_type is not “**in\_vehicle”** | Distance\_filter = distance\_filter +100m |

**11)** Once the distance\_filter reaches upto **1000m/1km**, the trip is stopped, and post processing is done to create a request body for trip upload.

**12)** The trip might also be stopped if there is low battery signal or GPS is disabled.

**Conclusion: - The data point collection depends on the below conditions :-**

|  |  |
| --- | --- |
| **Condition** | **Result** |
| 1. If the trip is **NOT** on-going, we still receive the location even if the distance\_filter is anywhere between 100m-1000m | Data points are **NOT** saved or recorded |
| 1. If the trip is **NOT** on-going and calculated distance\_filter is between **0-100m** along with the above mentioned parameter requirements points from section **6.1** - **6.5** | Start a new trip and collect data points based on calculated distance\_filter eg. If the distance\_filter is **90m**, then collect a new set of data points every **90m**. |
| 1. If trip **is** on-going | Collect data points depending on the distance filter value between **0-1000m**. Once the distance\_filter value reaches 1000m, stop the trip. |