



Formula SAE
Electrical System Form Template for Electric
Vehicles

Electrical System Form

FSAE-E2015

The University of Akron

Akron Electric

Car E217

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Table of Contents

Table of Contents	iii
I List of Figures.....	vii
II List of Tables.....	viii
III List of Abbreviations	ix
1 System Overview	2
2 Electrical Systems	4
2.1 Shutdown Circuit.....	4
2.1.1 Description/concept.....	4
2.1.2 Wiring / additional circuitry	7
2.1.3 Position in car	9
2.2 IMD	11
2.2.1 Description (type, operation parameters)	11
2.2.2 Wiring/cables/connectors/	11
2.2.3 Position in car	12
2.3 Inertia Switch	13
2.3.1 Description (type, operation parameters)	13
2.3.2 Wiring/cables/connectors/	13
2.3.3 Position in car	14
2.4 Brake Plausibility Device	14
2.4.1 Description/additional circuitry	14
2.4.2 Wiring	15
2.4.3 Position in car/mechanical fastening/mechanical connection	15
2.5 Reset / Latching for IMD and BMS	16
2.5.1 Description/circuitry	16
2.5.2 Wiring/cables/connectors	16
2.5.3 Position in car	16
2.6 Shutdown System Interlocks	17
2.6.1 Description/circuitry	17
2.6.2 Wiring/cables/connectors	17
2.6.3 Position in car	18

2.7	Tractive system active light	18
2.7.1	Description/circuitry	18
2.7.2	Wiring/cables/connectors	19
2.7.3	Position in car	20
2.8	Measurement points.....	20
2.8.1	Description	20
2.8.2	Wiring, connectors, cables	21
2.8.3	Position in car	22
2.9	Pre-Charge circuitry	23
2.9.1	Description	23
2.9.2	Wiring, cables, current calculations, connectors	23
2.9.3	Position in car	26
2.10	Discharge circuitry.....	27
2.10.1	Description	27
2.10.2	Wiring, cables, current calculations, connectors	28
2.10.3	Position in car	31
2.11	HV Disconnect (HVD).....	32
2.11.1	Description	32
2.11.2	Wiring, cables, current calculations, connectors	32
2.11.3	Position in car	33
2.12	Ready-To-Drive-Sound (RTDS)	34
2.12.1	Description	34
2.12.2	Wiring, cables, current calculations, connectors	34
2.12.3	Position in car	35
3	Accumulator	36
3.1	Accumulator pack 1.....	36
3.1.1	Overview/description/parameters	36
3.1.2	Cell description	41
3.1.3	Cell configuration	41
3.1.4	Cell temperature monitoring	41
3.1.5	Battery management system.....	41
3.1.6	Accumulator indicator.....	45

3.1.7	Wiring, cables, current calculations, connectors	46
3.1.8	Accumulator insulation relays.....	46
3.1.9	Fusing	46
3.1.10	Charging	48
3.1.11	Mechanical Configuration/materials.....	49
3.1.12	Position in car	50
3.2	Accumulator pack 2.....	51
4	Energy meter mounting	52
4.1	Description	52
4.2	Wiring, cables, current calculations, connectors	52
4.3	Position in car	53
5	Motor controller	54
5.1	Motor controller 1	54
5.1.1	Description, type, operation parameters.....	54
5.1.2	Wiring, cables, current calculations, connectors	54
5.1.3	Position in car	56
5.2	Motor controller 2	56
6	Motors	57
6.1	Motor 1	57
6.1.1	Description, type, operating parameters.....	57
6.1.2	Wiring, cables, current calculations, connectors	58
6.1.3	Position in car	58
6.2	Motor 2.....	59
7	Torque encoder.....	60
7.1	Description/additional circuitry.....	60
7.2	Torque Encoder Plausibility Check.....	60
7.3	Wiring.....	61
7.4	Position in car/mechanical fastening/mechanical connection.....	62
8	Additional LV-parts interfering with the tractive system.....	63
8.1	LV part 1	63
8.1.1	Description	63
8.1.2	Wiring, cables,	63

8.1.3	Position in car	64
8.2	LV part 2	65
9	Overall Grounding Concept.....	66
9.1	Description of the Grounding Concept.....	66
9.2	Grounding Measurements	66
10	Firewall(s)	67
10.1	Firewall 1.....	67
10.1.1	Description/materials.....	67
10.1.2	Position in car	68
10.2	Firewall 2.....	68
11	Appendix	69

I List of Figures

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II List of Tables

Table 1.1 General parameters.....	2
Table 2.1 List of switches in the shutdown circuit	7
Table 2.2 Wiring – Shutdown circuit	9
Table 2.3 Parameters of the IMD.....	11
Table 2.4 Parameters of the Inertia Switch.....	13
Table 7.1 Torque encoder data	14
Table 2.6 Parameters of the TSAL	19
Table 2.7 General data of the pre-charge resistor	25
Table 2.8 General data of the pre-charge relay	26
Table 2.9 General data of the discharge circuit	30
Table 3.1 Main accumulator parameters	40
Table 3.2 Main cell specification.....	41
Table 3.5 Wire data of company A, 0.205 mm ²	46
Table 3.3 Basic AIR data.....	46
Table 3.4 Basic fuse data	47
Table 3.5 Fuse Protection Table.....	48
Table 3.6 General charger data.....	48
Table 5.1 General motor controller data	54
Table 5.2 Wire data of company A, 0.205 mm ²	55
Table 6.1 General motor data.....	57
Table 7.1 Torque encoder data	60

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III List of Abbreviations

- HV: High Voltage
- GLVS: Grounded Low Voltage System
- BMS: Battery Management System
- BMM: Battery Management System Master
- BMSS: Battery Management System Slave (S)
- SAS: Sensor Acquisition System
- MCS: Motor Controller System
- SS: Safety System
- DDS: Dashboard Display System

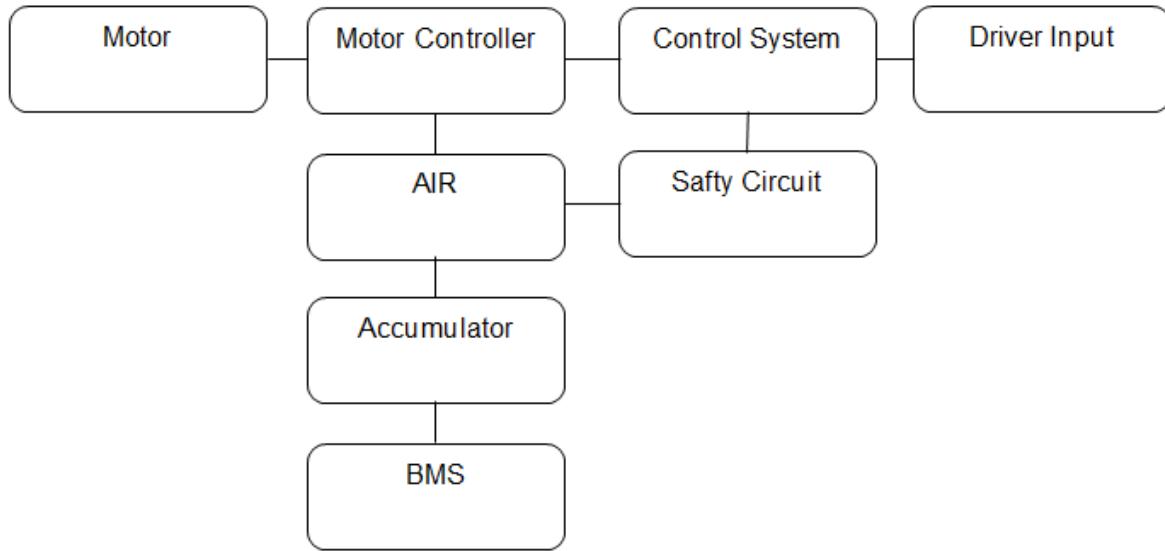
1 System Overview

The University of Akron's electrical system concept splits the electrical system into the Tractive HV system, and the GLV control system. The tractive system includes the motors, motor controllers, batteries, AIR's, main fuse, and part of the BMS. The GLV control system includes the control section of the BMS, sensors.

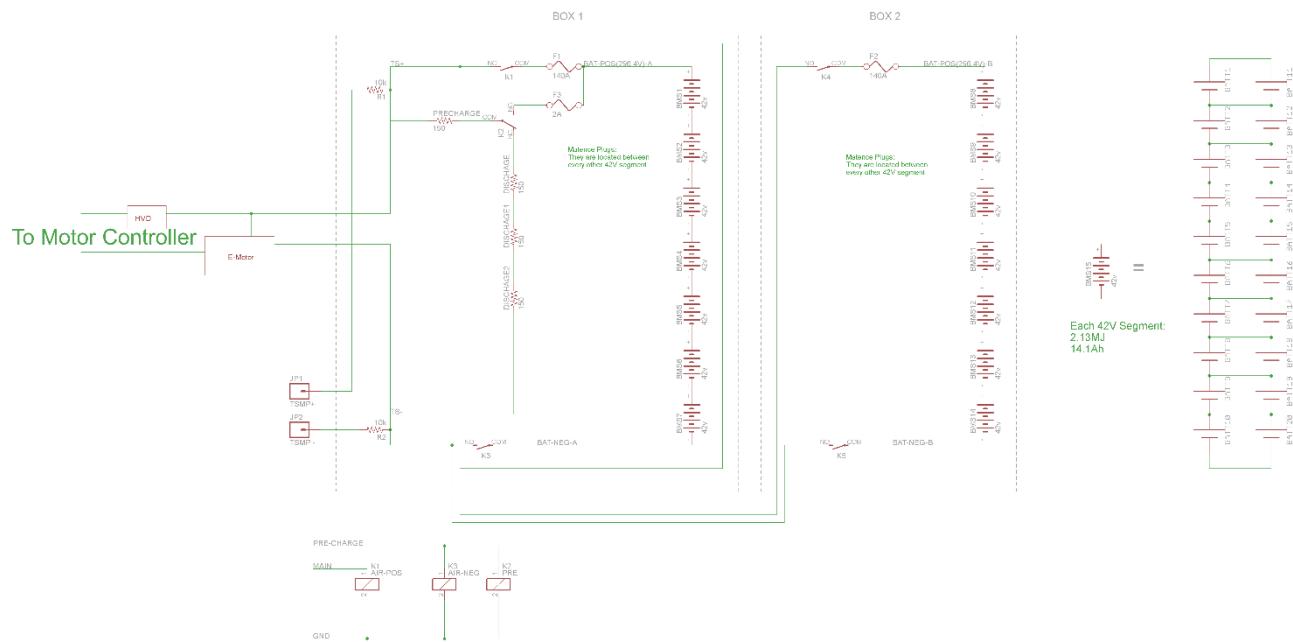
The vehicle is a single motor, rear wheel drive electric car. The motor is a 79kW peak output power with a 3.5:1 gear ratio and a mechanical differential. Traction control is required to keep wheel slip to a minimum. The accumulator system consists of 280LiPo battery cells. They are connected in two accumulators that hold two 70 series sets.

Maximum Tractive-system voltage:	294VDC
Nominal Tractive-system voltage:	231VDC
Control-system voltage:	24VDC
Accumulator configuration:	70s4p
Total Accumulator capacity:	28.2Ah 6.46 kWatt-hours; 29.68MJ
Motor type:	Permanent Magnet Brushless AC
Number of motors:	One
Maximum combined motor power in kW	79kW

Table 1.1 General parameters



University of Akron 2015 Battery Layout



2 Electrical Systems

2.1 Shutdown Circuit

2.1.1 Description/concept

The shutdown circuit carries the current to open or close the Accumulator Isolation Relays, providing several methods for shutting down the high voltage parts of the car in emergencies. All the emergency switches are connected in series so if one switch opens, the power is removed to the AIR's. The safety system gets its power from the GLVMS. The power supplied to the GLVMS is from our custom battery pack. The power after the GLVMS flows through the E-Stops and then to the safety circuits. These are controlled by digital hardware monitoring IMD, Brake pressure, current, and BMS issues. The ECU relay is to stop the car from precharging until the start button is hit and brake pedal is depressed. We do this to add hardware and software lockouts. The safety system faults that are AMS, IMD, or BSPD are only cleared with a car power down. That would require driver to have access to GLVMS and they do not. The shutdown system also examines where the fault is to alert the team what faulted. (10.14 E-Stop datasheet)

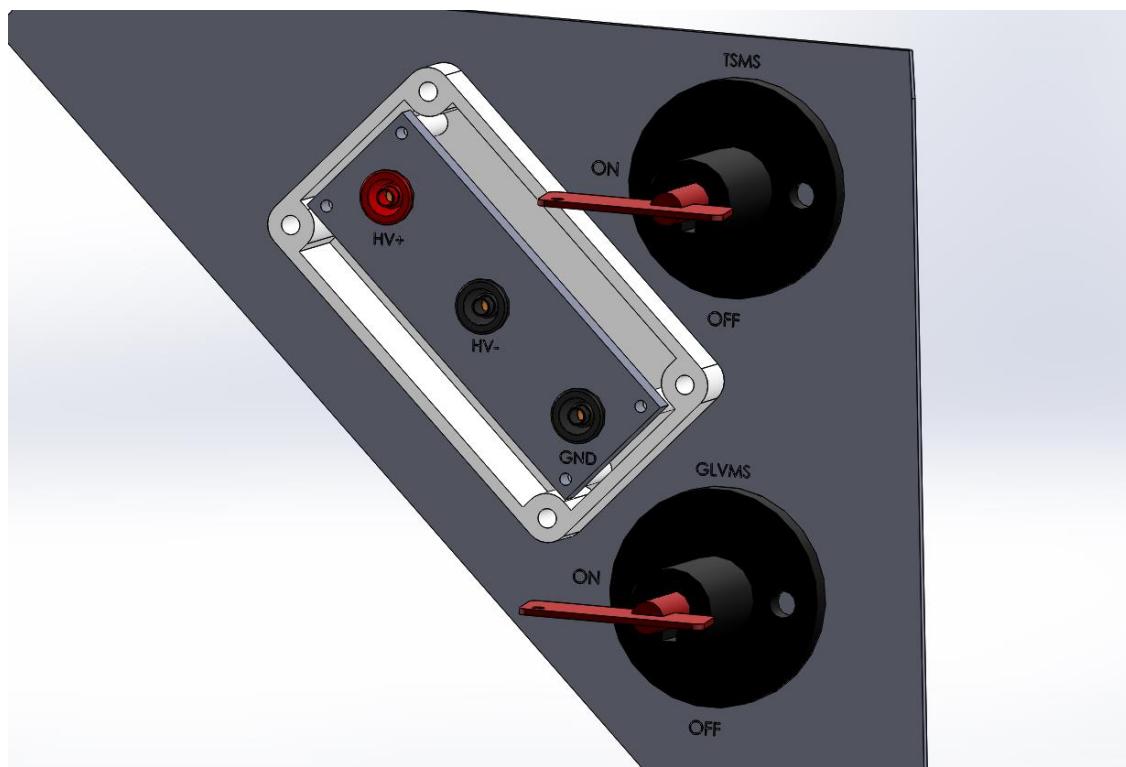
We are able to perform lockout at the TSMS by removing the red key. The safety officer keeps the one key on themselves. This prevents the car from being energized when in an unsafe condition. The key is unique enough that it would be hard to activate without it. This is demonstrated below:



TSMS and GLVMS in the OFF position:



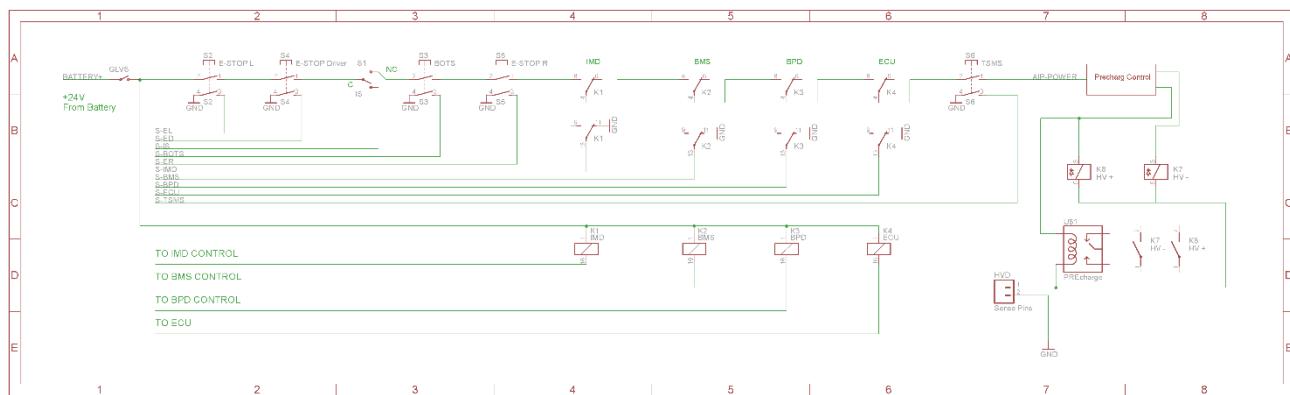
TSMS and GLVMS in the ON position:



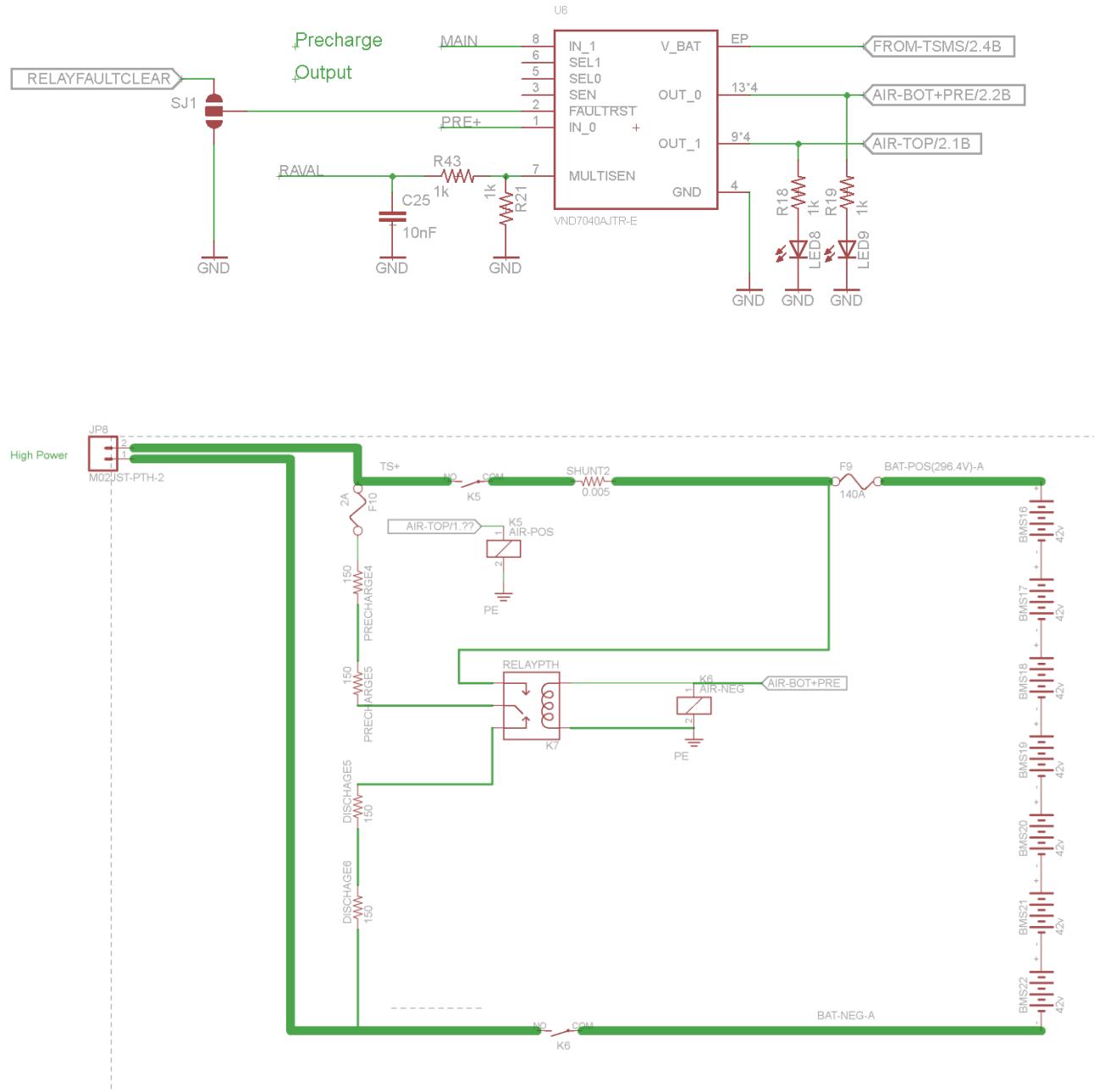
Part	Function
Main Switch (for control and tractive-system; CSMS, TSMS)	Normally open
Brake over travel switch (BOTS)	Normally closed
Shutdown buttons (SDB)	Normally closed
Insulation Monitoring Device (IMD)	Normally closed
Battery Management System (BMS)	Normally closed
Inertia Switch	Normally closed
Interlocks	Closed when circuits are connected
Brake System Plausibility Device	Normally Closed
Software system (ECU)	Normally Closed

Table 2.1 List of switches in the shutdown circuit

2.1.2 Wiring / additional circuitry



Relay Control

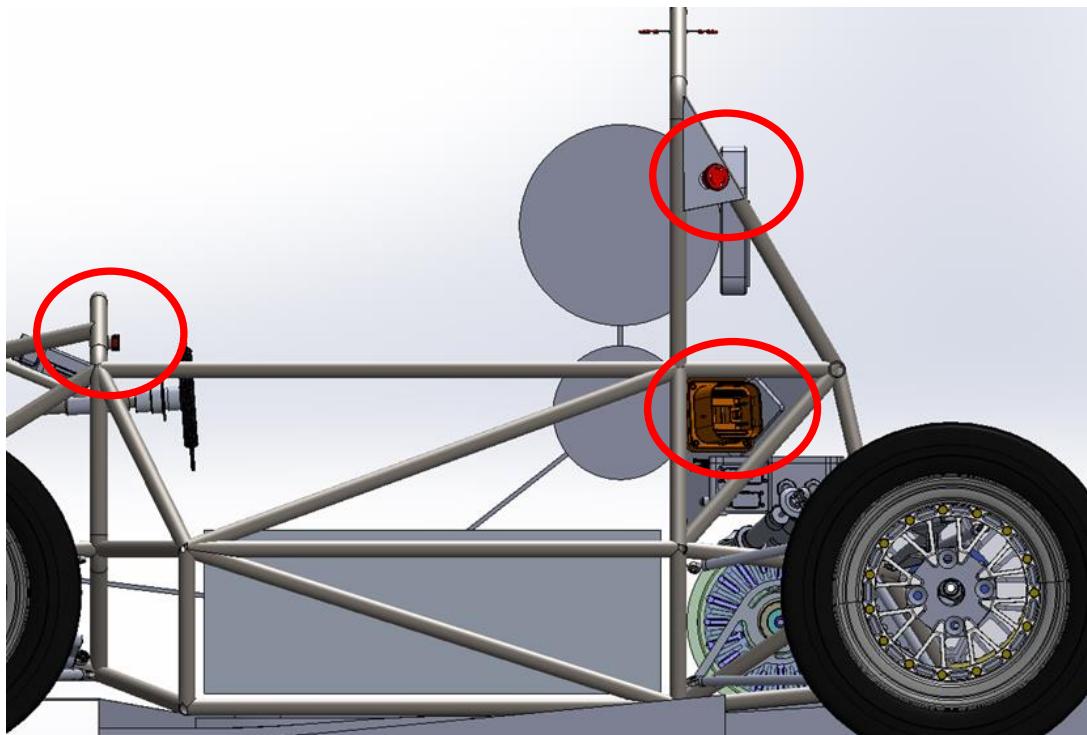


Total Number of AIRs:	4
Current per AIR:	0.25A
Additional parts consumption within the shutdown circuit:	1A
Total current:	2A
Cross sectional area of the wiring used:	2.1mm ²

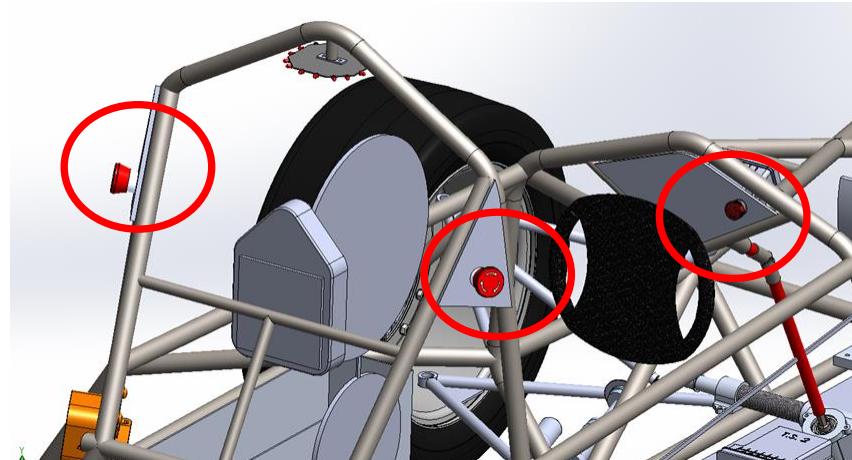
Table 2.2 Wiring – Shutdown circuit

2.1.3 Position in car

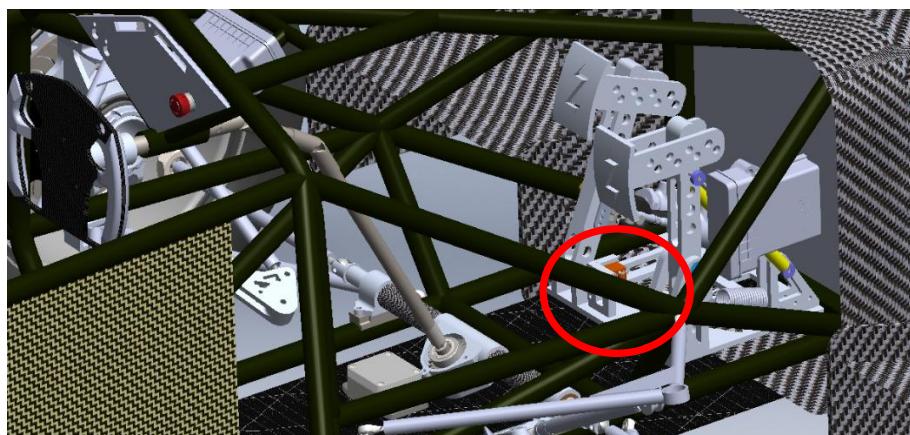
Disconnect, driver e-stop, and left e-stop:



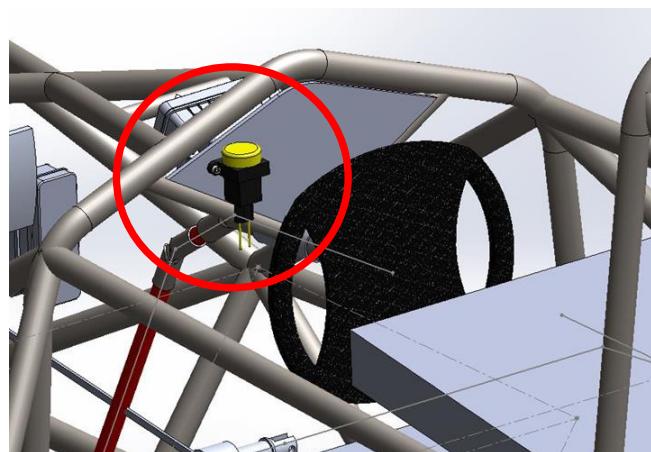
Driver e-stop, right e-stop and left e-stop:



BOTS:



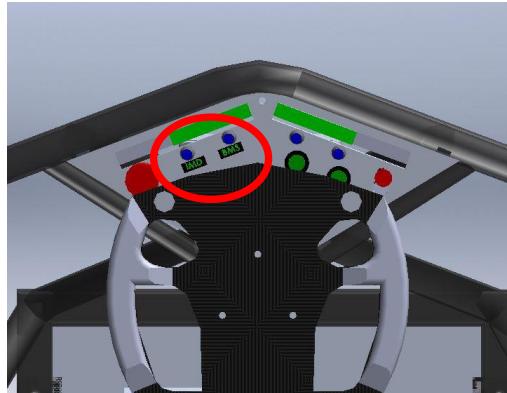
IS:



2.2 IMD

2.2.1 Description (type, operation parameters)

Bender A-Isometer IR-155-3203, Automatic Device Self-test and Continuous measurement of insulation resistance. The indicator is wired to the front dash. The LED is lit by software cue from the safety system (SS) to the Dashboard Display System DDS controller warning the driver. **The system is not able to be reset unless there is a GLVMS power cycle.**



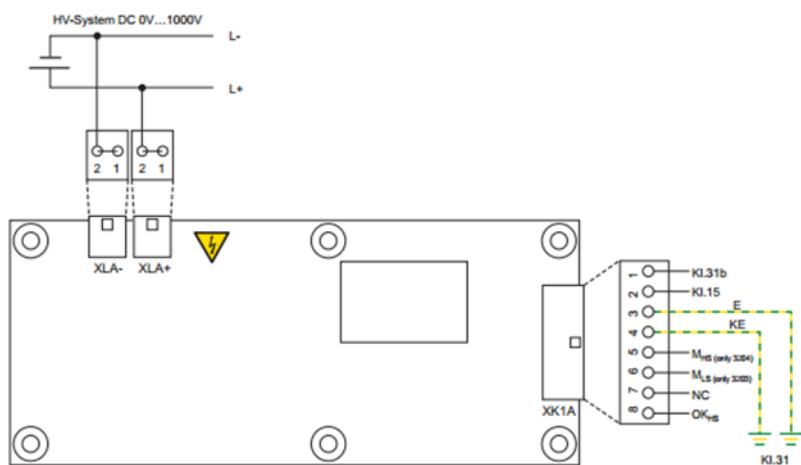
Supply voltage range:	10..36VDC
Supply voltage	24VDC
Environmental temperature range:	-40..105°C
Selftest interval:	Always at startup, then every 20 minutes
High voltage range:	DC 0..1000V
Set response value:	300kΩ (500Ω/Volt)
Max. operation current:	500mA
Approximate time to shut down at 50% of the response value:	27s

Table 2.3 Parameters of the IMD

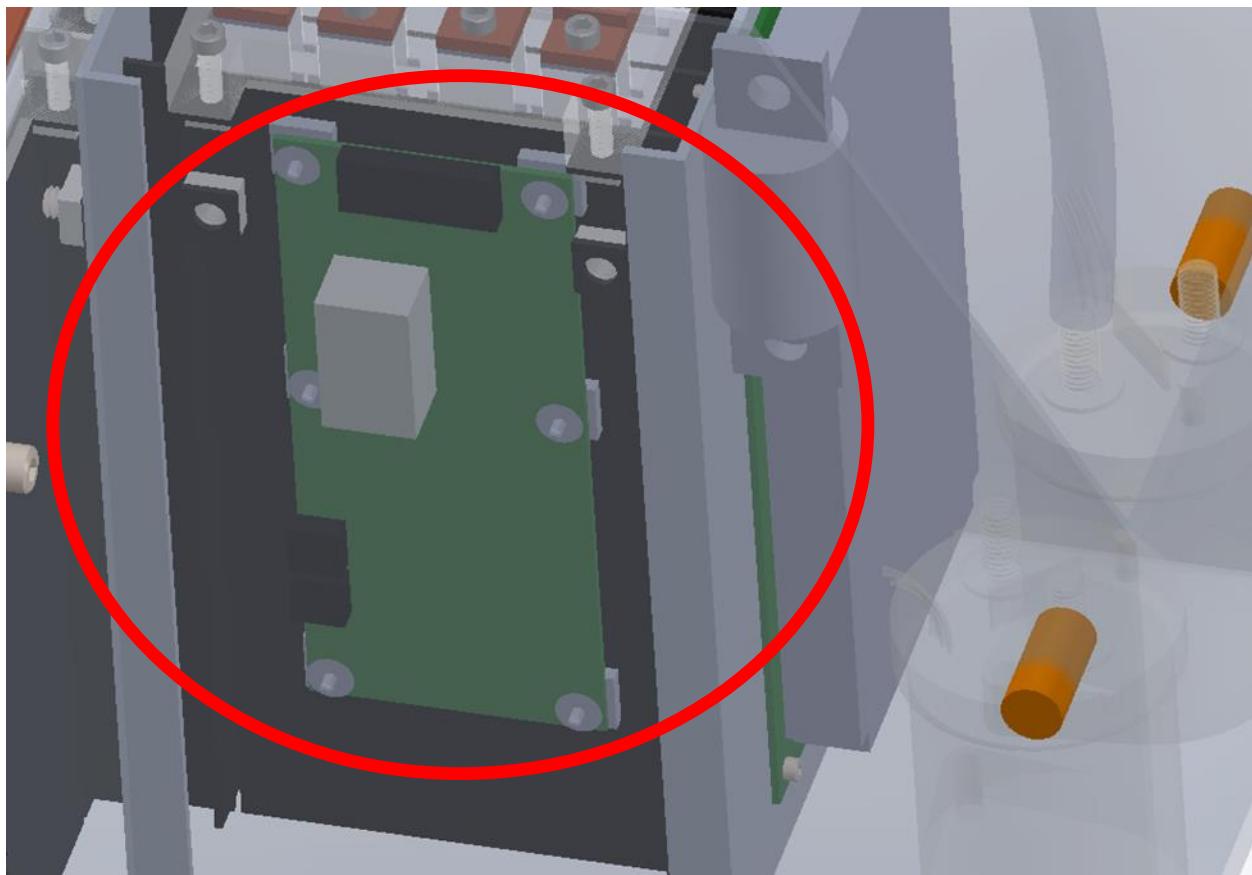
2.2.2 Wiring/cables/connectors

The IMD requires 24 Gauge PVC wire with a 300v and 105C rating.

Wiring diagrams



2.2.3 Position in car



2.3 Inertia Switch

2.3.1 Description (type, operation parameters)

The inertia switch will be normally closed and will open to shut down the tractive system in the event of a crash. This is hooked up in series with the other safety switches that control the AIR's so if it went off the tractive system would become unpowered. The driver will have the ability to depress the Sensata crash sensor to reset it. The crash sensor is removable off the dashboard with two screws and an electrical connector to test the device at competition. 10.5 Datasheet

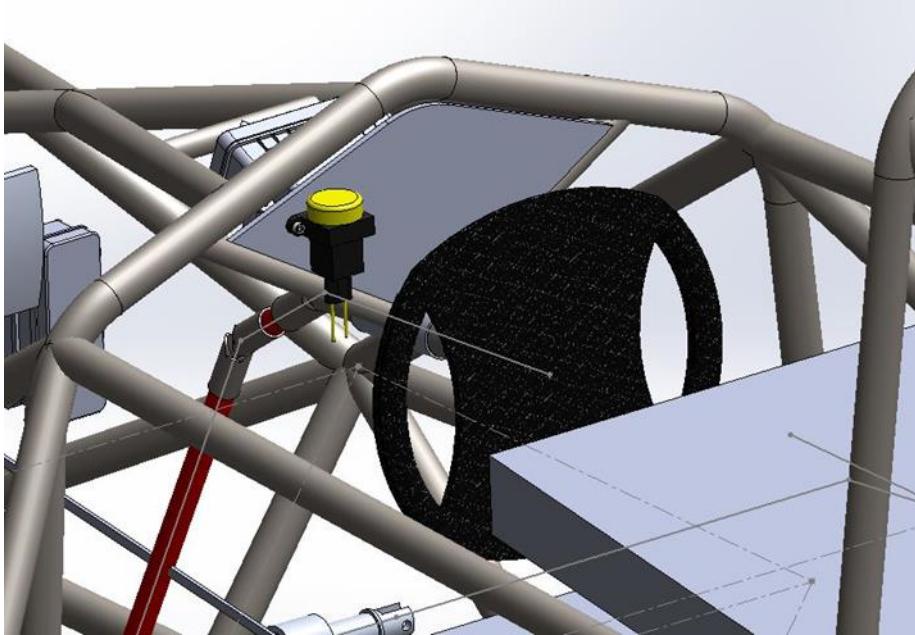
Inertia Switch type:	Sensata Resettable crash sensor
Supply voltage range:	10..36VDC
Supply voltage:	24VDC
Environmental temperature range:	-40..105°C
Max. operation current:	10A
Trigger characteristics:	6g for 50ms / 11g for 15ms

Table 2.4 Parameters of the Inertia Switch

2.3.2 Wiring/cables/connectors/

The crash sensor will be rigidly mounted to the frame of the car near the bottom to ensure that it receives the full force of any vibration or impact using a mating connector and 18 AWG, PVC, 105 C, 300v wire will be used for the electrical connections.

2.3.3 Position in car



2.4 Brake Plausibility Device

2.4.1 Description/additional circuitry

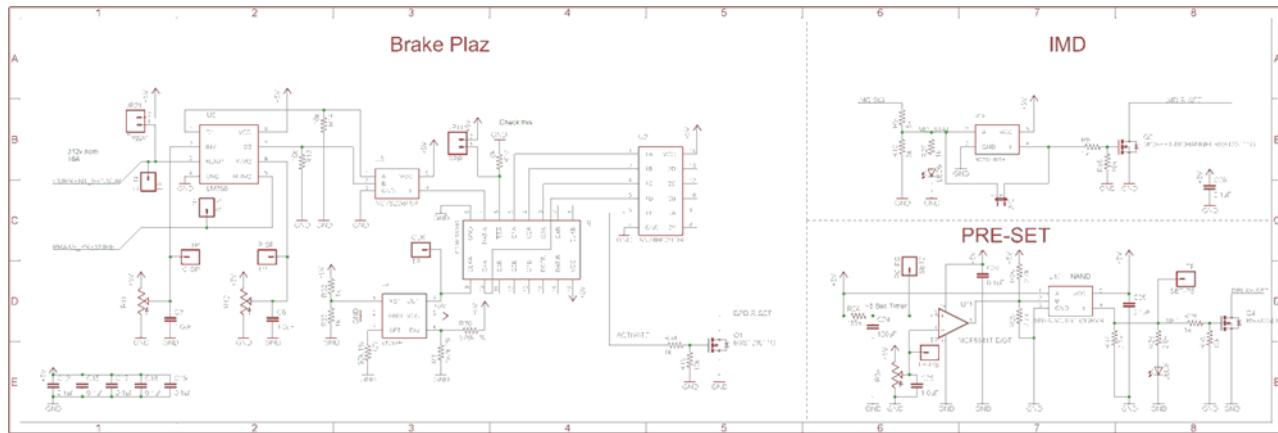
The purpose of the brake plausibility system is to ensure that the brake pedal does not pass a certain threshold if the motors are being driven. It will work by using **brake pressure** on the brake pedal to measure braking and a current sensor on the connection between the accumulator and motor controllers to measure the current. These measured values will be compared to pre-calculated constant threshold values. The current set point is at 16.6A. **To reset this system, it requires a GLVMS power cycle.**

Brake sensor used:	PX2AF1XX500PAAAX
Torque encoder (current sensor) used:	MLX91205
Supply voltages:	5V
Maximum supply currents:	20mA
Operating temperature:	-40..100 °C
Output used to control AIRs:	Open a relay

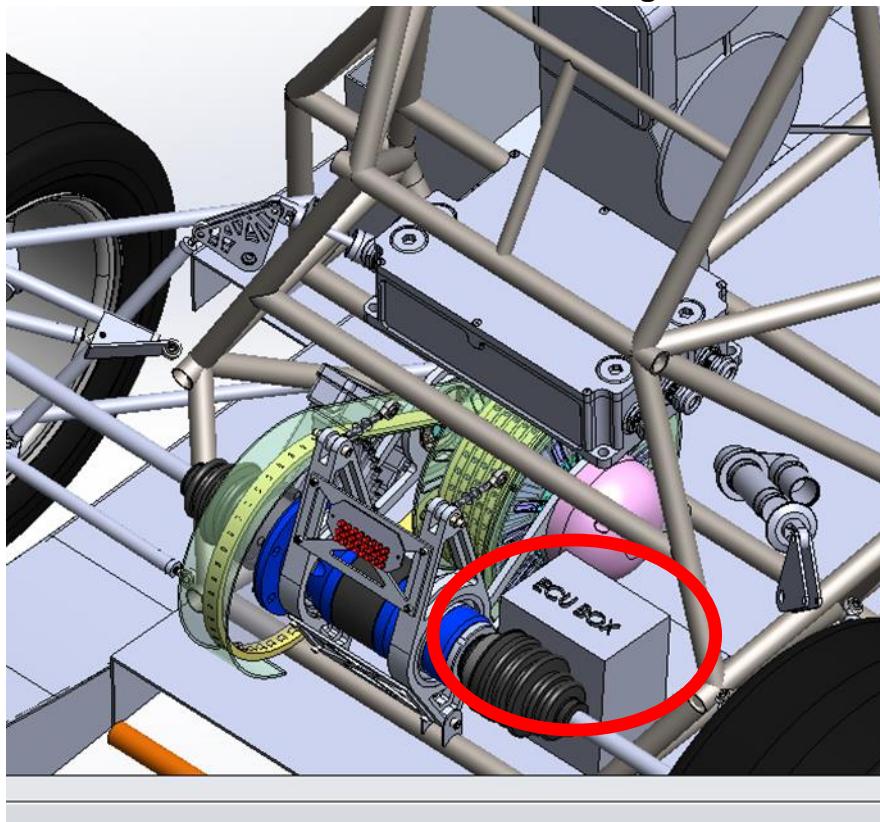
Table 2.5 Torque encoder data

2.4.2 Wiring

The brake plausibility system takes a 9V power input from the LV power system, along with 0-5V digital sensor input from the brake pedal sensor and the current sensor on the motor supply. The only output is the on or off 24v relay power that goes to the shutdown circuit. The reset of this system is done by power cycling the GLVS or hitting the reset button. **The TSAL uses 24 Gauge PVC wire with a 300v and 105C rating.** **10.16 datasheet**



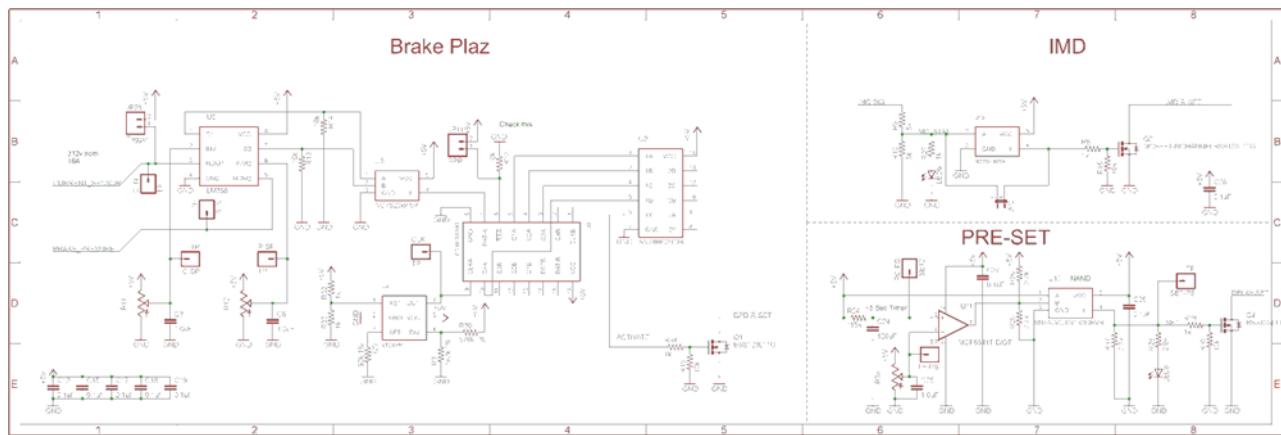
2.4.3 Position in car/mechanical fastening/mechanical connection



2.5 Reset / Latching for IMD and BMS

2.5.1 Description/circuitry

If the IMD or BMS becomes tripped, the latching relays will open. A GLVS power cycle will reset these systems or pushing the reset button. The latching relays are set by the PRE-SET circuit. Below is the IMD hardware Safety System. The BMS is done in software but is only reset (turned on) during startup.

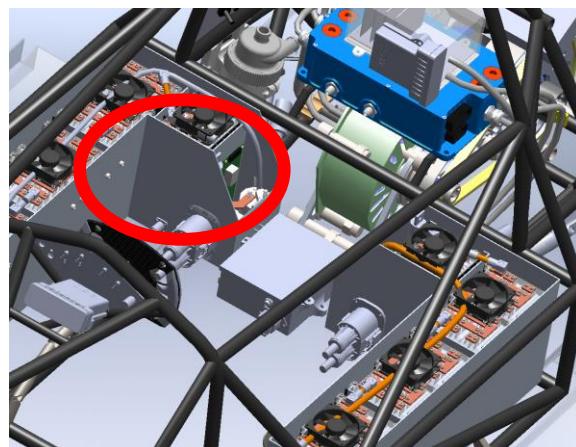


2.5.2 Wiring/cables/connectors

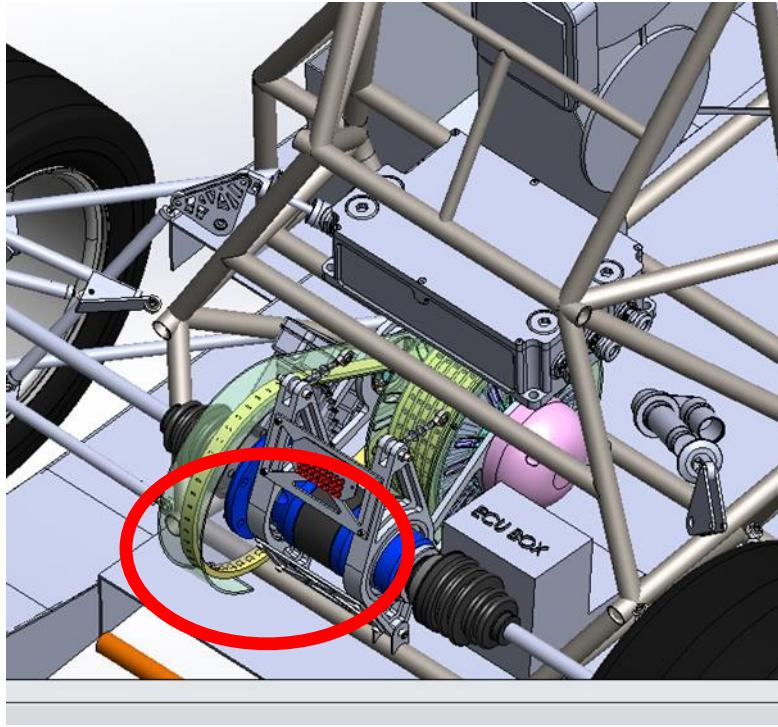
The BMS and IMD relay is wired into the shutdown system in series with other safety systems. This is wired with **The TSAL uses 24 Gauge PVC wire with a 300v and 105C rating**. The BMS has a relay on the PCB that it can trip to open the shutdown circuit. [10.16 wire datasheet](#)

2.5.3 Position in car

IMD:



Control circuitry:



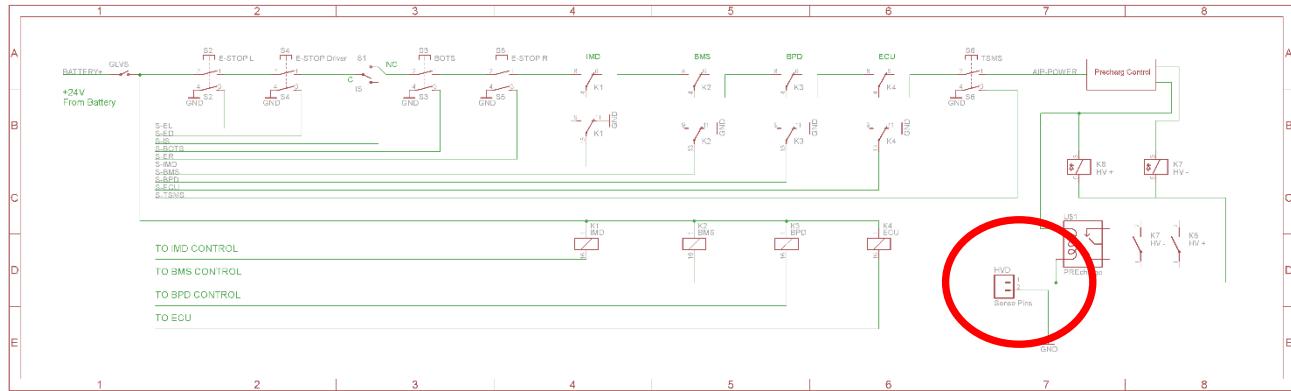
2.6 Shutdown System Interlocks

2.6.1 Description/circuitry

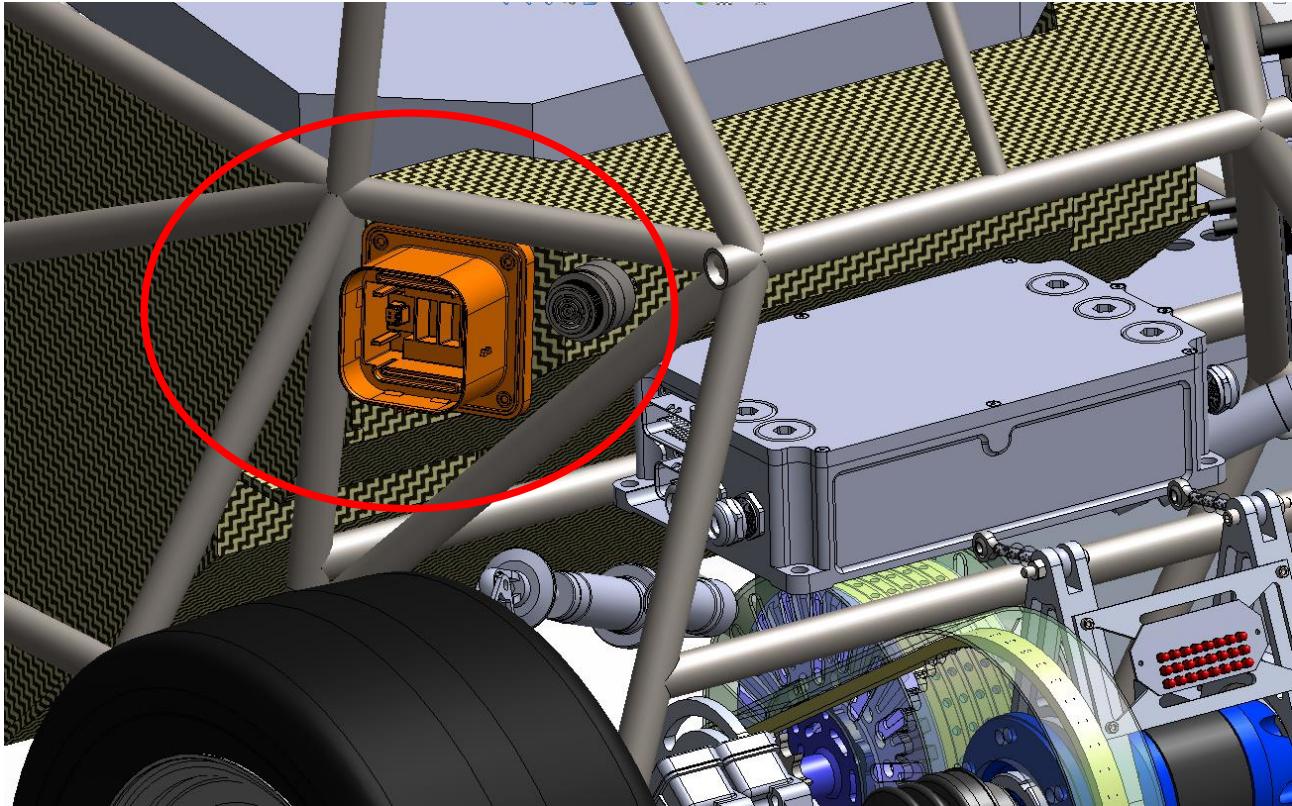
The interlocks are achieved by using sense low voltage isolated pins in the connectors to detect open or closed connections. The AIR's power travel threw them. We have interlocks between the HVD. **All other connectors will require tools to open.**

2.6.2 Wiring/cables/connectors

The HVD requires 18 Gauge PVC wire with a 300v and 105C rating.



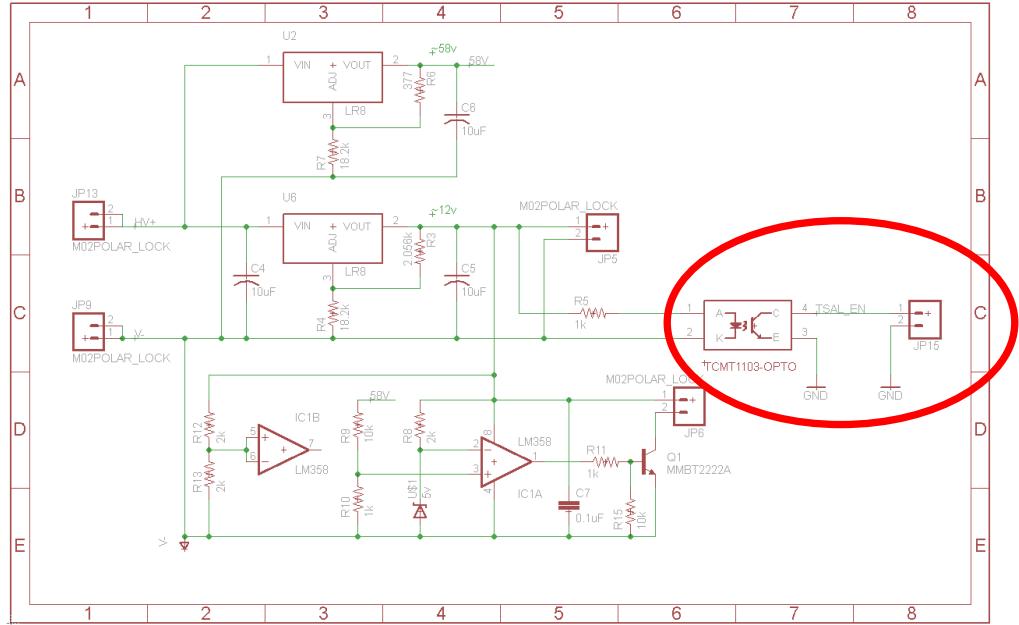
2.6.3 Position in car



2.7 Tractive system active light

2.7.1 Description/circuitry

The TSAL consists of 16 LED's mounted every 45 deg. to form an octagon with 2 LED's on each side. The 3 Hz flashing frequency is driven by a 555 timer. This is turned on by a high voltage sensor after the AIR's in the battery pack. (shown below)

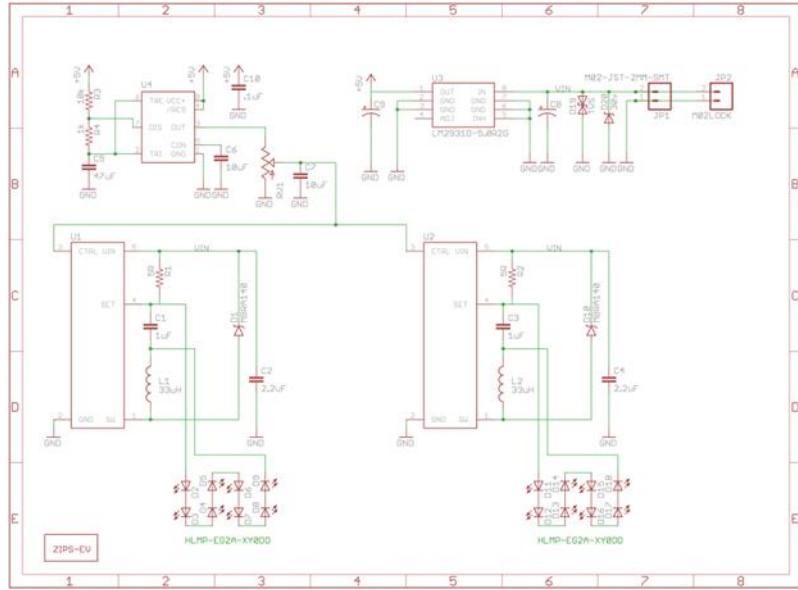


Supply voltage:	24VDC
Max. operational current:	40mA
Lamp type	LED
Power consumption:	1 W
Brightness	100 Lumen
Frequency:	1.5Hz
Size (length x height x width):	20mm x 10mm x 50mm

Table 2.6 Parameters of the TSAL

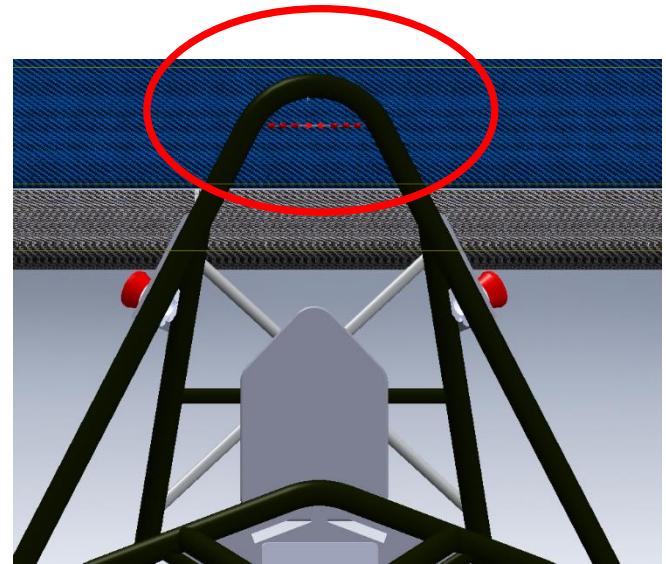
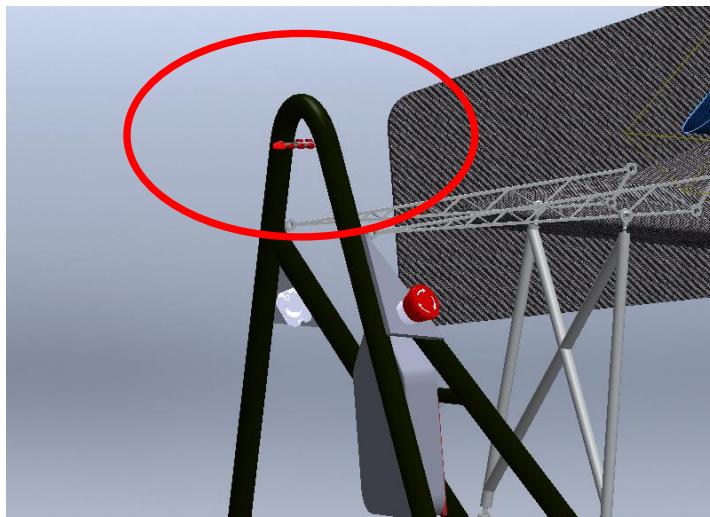
2.7.2 Wiring/cables/connectors

The TSAL uses 24 Gauge PVC wire with a 300v and 105C rating. 10.16 datasheet



2.7.3 Position in car

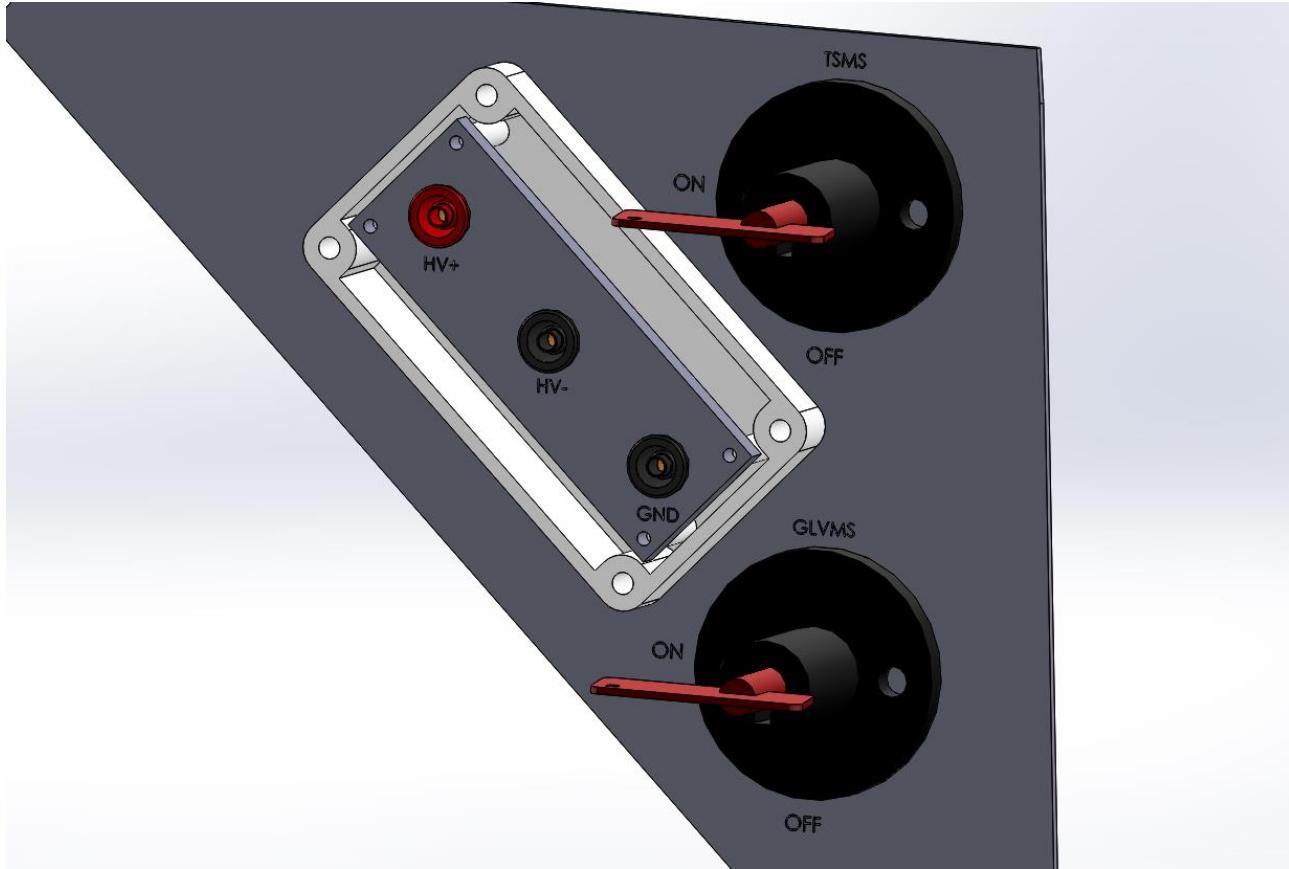
The TSAL is mounted to the bottom of the main roll hoop as required by the rules. It will be mounted with a metal bracket if necessary.



2.8 Measurement points

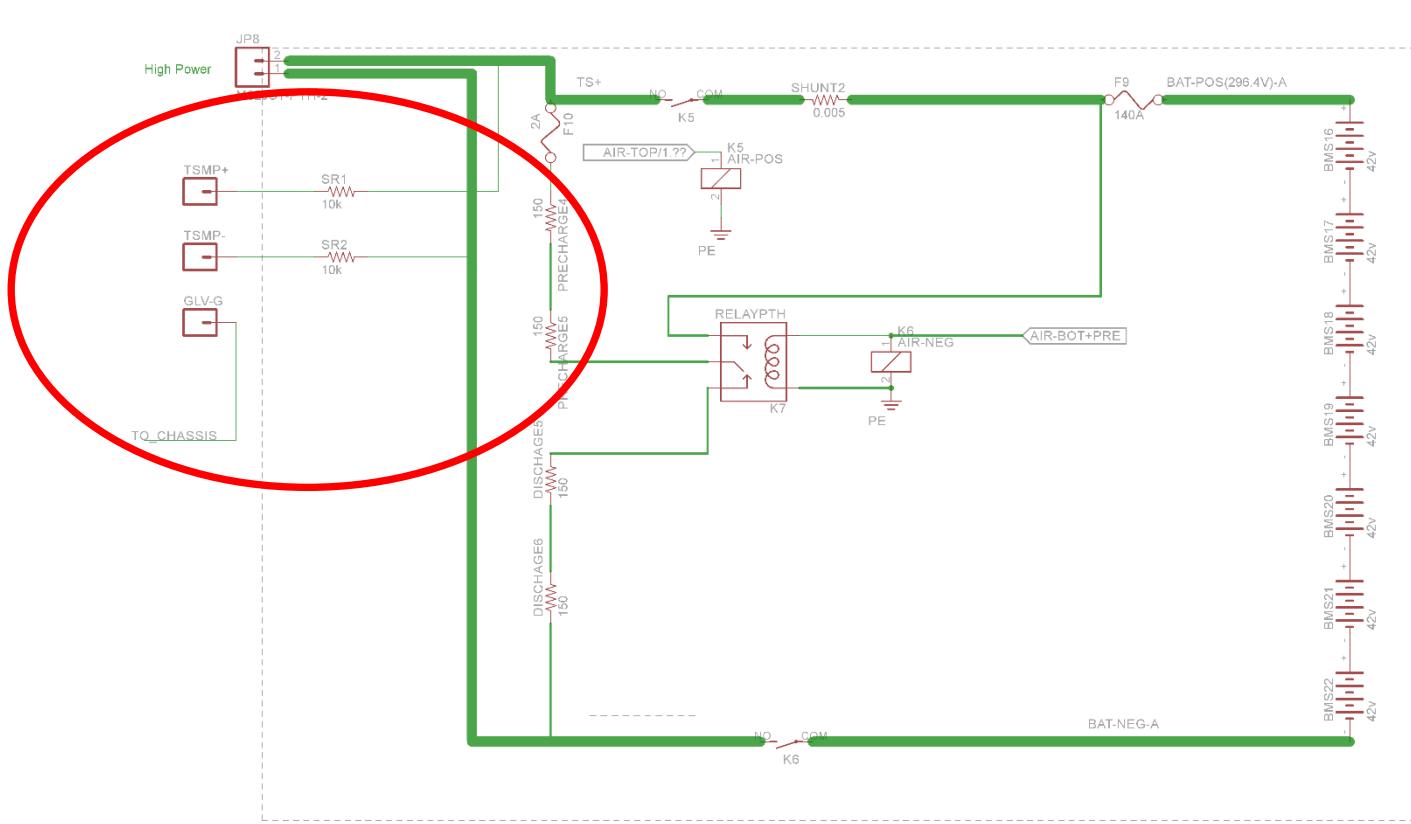
2.8.1 Description

4mm red and black banana jacks will be used to allow tractive system voltage measurement. They sit in an IP67 plastic box that has thumb screws holding on the cover. [The box is UL Listed to UL508-4x, 12, & 13 specifications.](#) [10.11 Jack Datasheet](#) [10.12 Resistor Datasheet](#) [10.15 Wire Info](#)

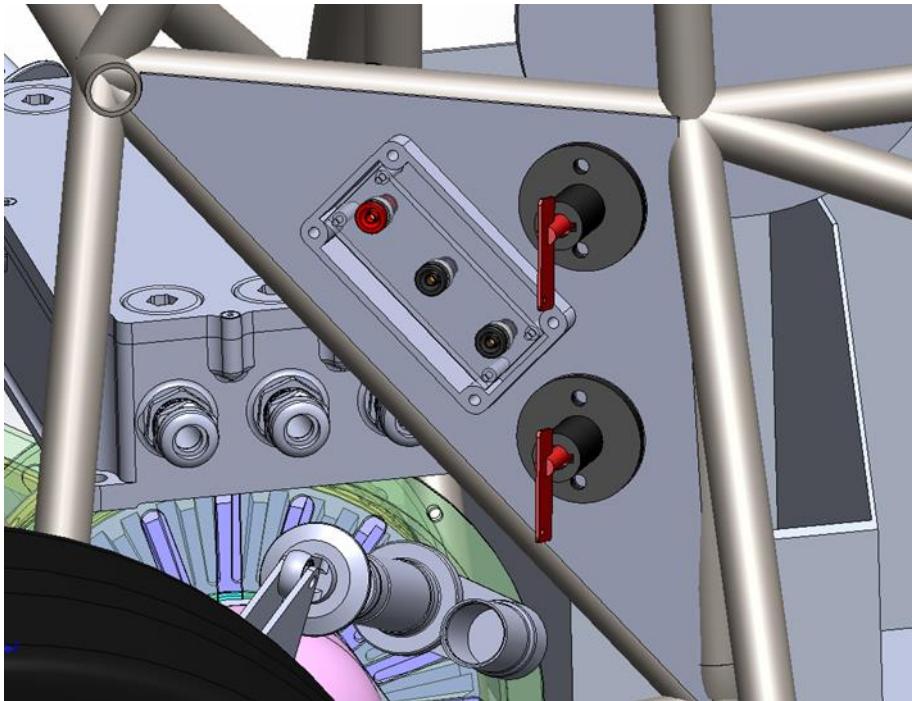


2.8.2 Wiring, connectors, cables

The TSMP 24 Gauge PVC wire with a 300v and 105C rating wire will connect the banana jacks in line with a 10kOhm resistor to the HV+ and HV- connections after the AIR's.



2.8.3 Position in car

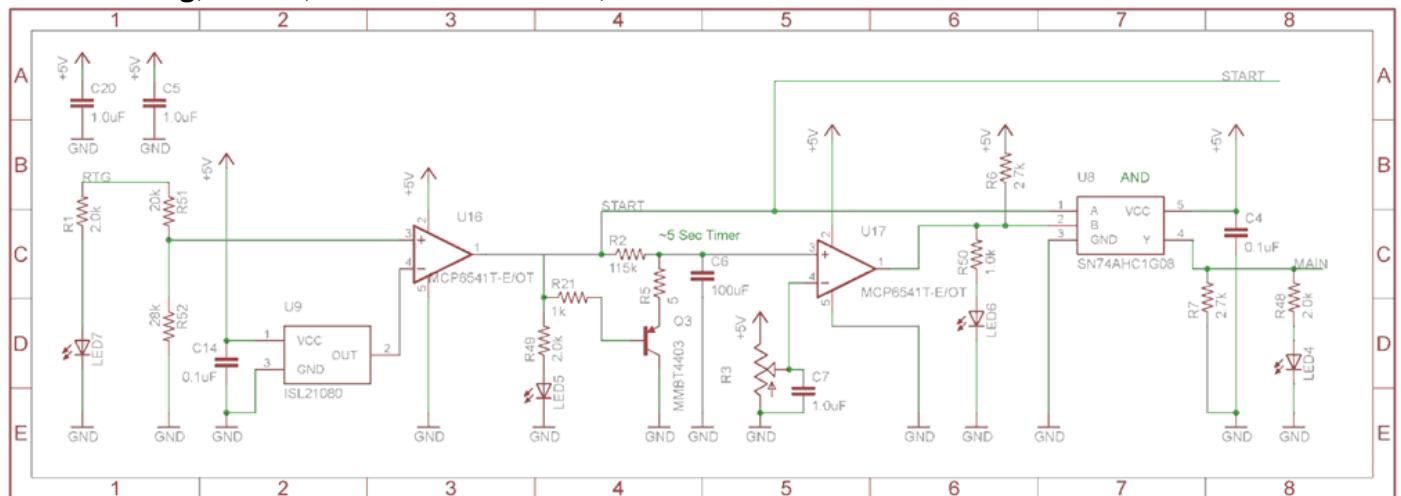


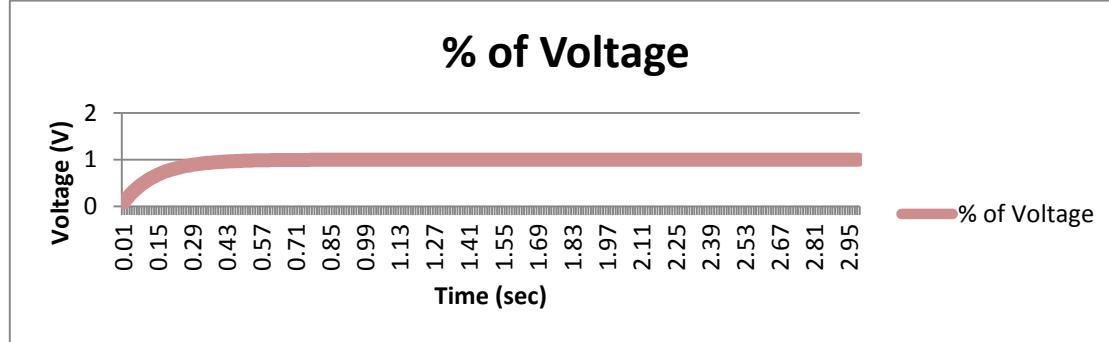
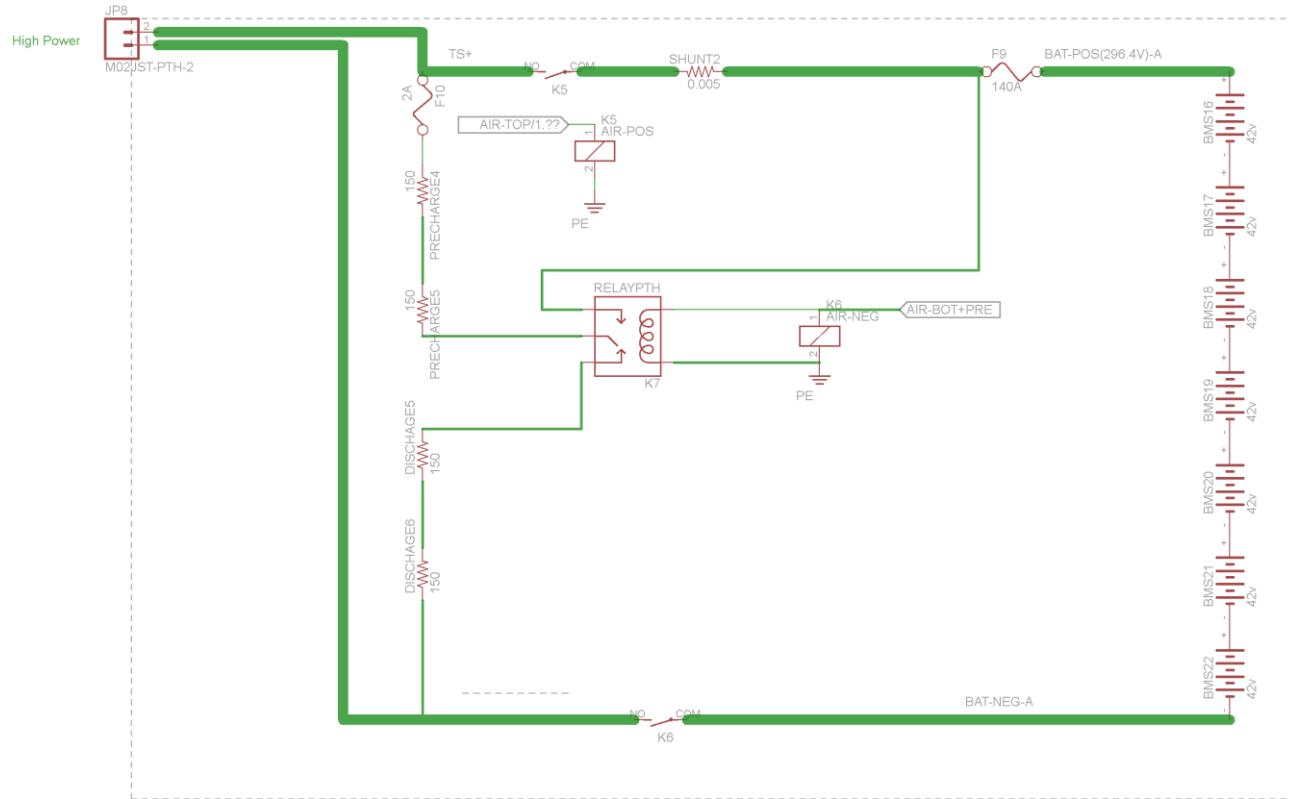
2.9 Pre-Charge circuitry

2.9.1 Description

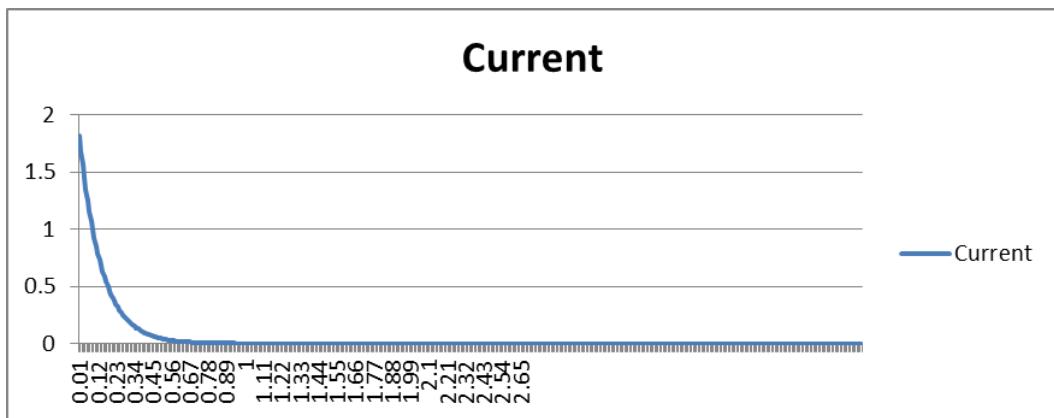
The Pre-Charge system of the car is used to equalize the potential of the across the AIR switch and both battery packs. Pre-Charge started when the safety system is all clear of faults. This includes the ECU clearing its fault and setting the ready to drive relay. Bottom or negative relay turns on with the Pre-Charge relay in series with two 150 ohm resistors. The hardware then waits 2.5 seconds. This 2.5 second delay originates from the safety system board. This is set by an RC timer. After the 2.5 seconds are up, the Pre-Charge relay stays on and the AIR's turn on shorting out the Pre-Charge resistor. During Pre-Charge, the car is acquiring data from the motor controller to verify voltage is present and increasing on the battery input to the device. If this doesn't happen, the car will trip ECU safety stop and report an error code. The Control circuitry is not near the high voltage.

2.9.2 Wiring, cables, current calculations, connectors





$$\text{Formula} = 1 - 294.2 \frac{-t}{150 * 0.00088}$$



$$\text{Formula} = 294.2 * 2.7182^{\frac{-t}{150*0.00088}}$$

Resistor Type:	WFH160L150JE - Wirewound
Resistance:	150Ω
Continuous power rating:	160W
Overload power rating:	160W
Voltage rating:	600V
Cross-sectional area of the wire used:	1.31mm ²

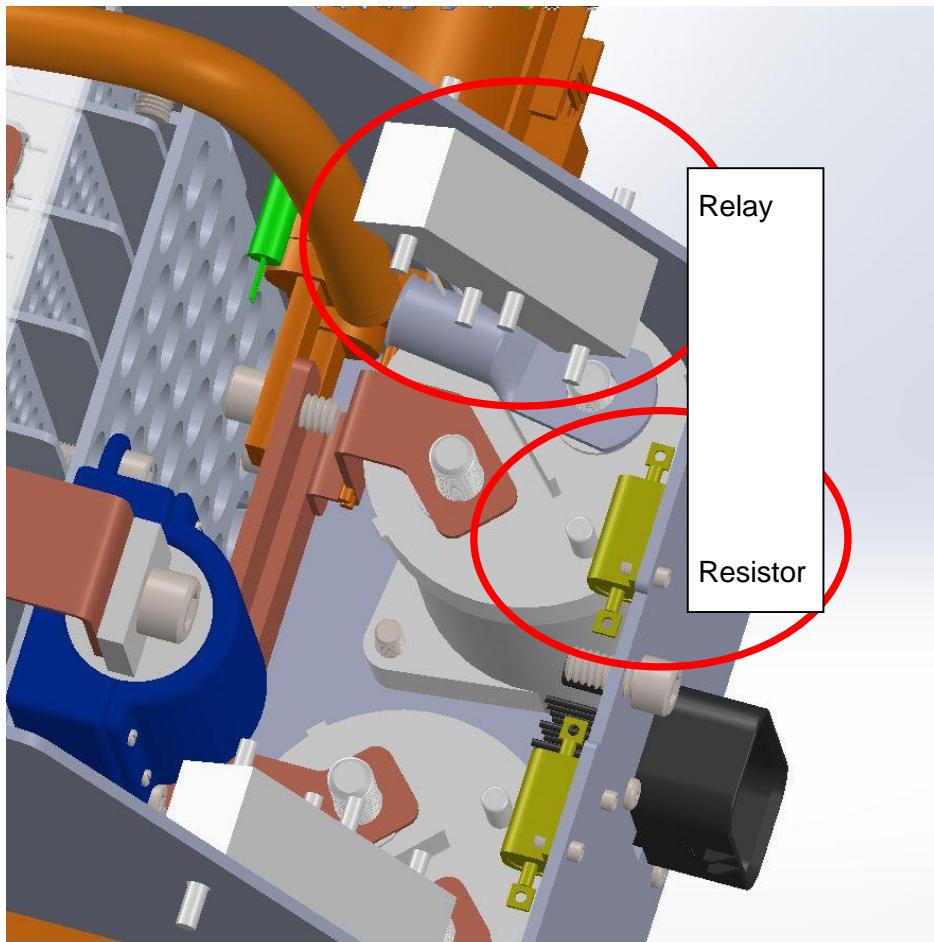
Table 2.7 General data of the pre-charge resistor

Relay Type:	5501-24-1
Contact arrangement:	SPST-NO
Continuous DC current:	3A
Voltage rating	7500VDC
Cross-sectional area of the wire used:	1.31mm ²

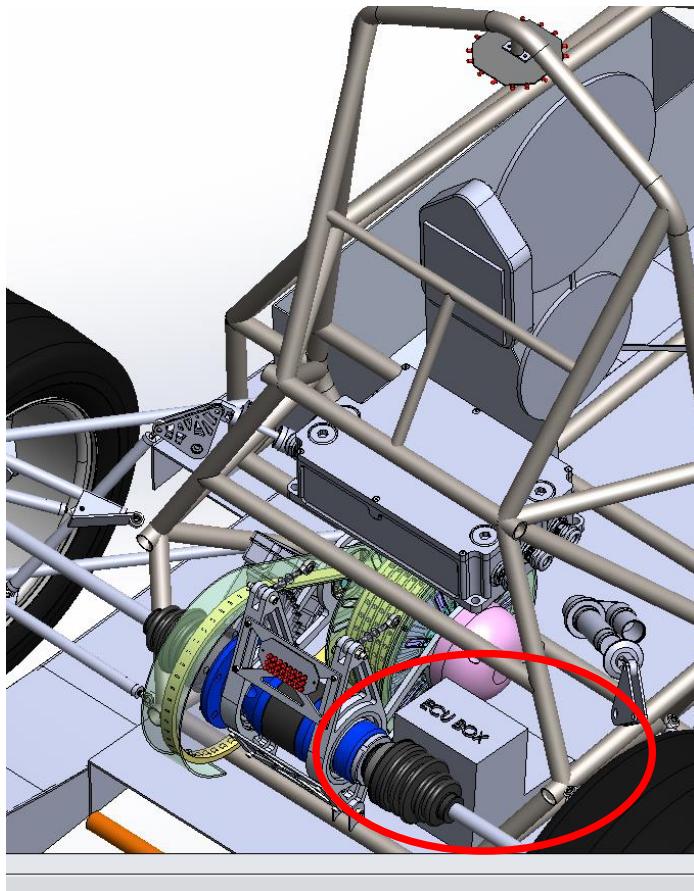
Table 2.8 General data of the pre-charge relay

2.9.3 Position in car

Relay and resistor (in accumulator)



Control system:

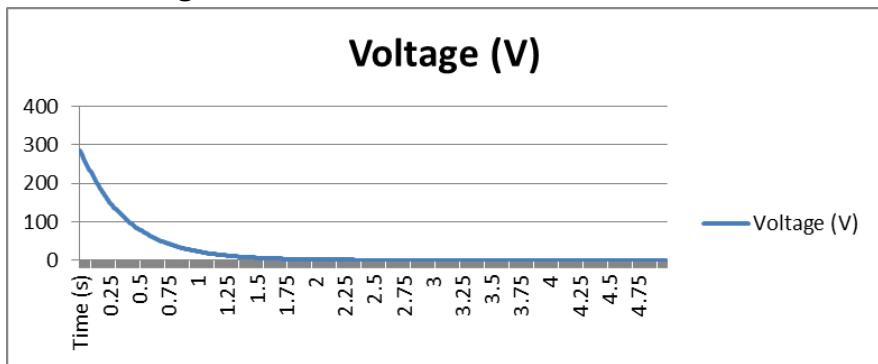


2.10 Discharge circuitry

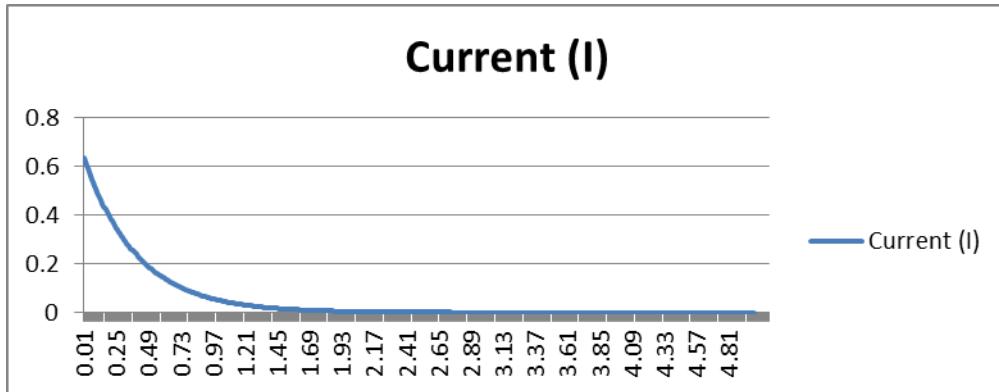
2.10.1 Description

Our system requires a discharge system to get the capacitive energy out of the motor controller. Our system uses a resistor to drop the energy. We are able to discharge the energy in about 1.8 seconds. **This circuit works off of the inverted precharge system relay output. It works by being a normally closed relay shorting the output of the accumulators and only opens when the precharge system activates and main AIRs open.**

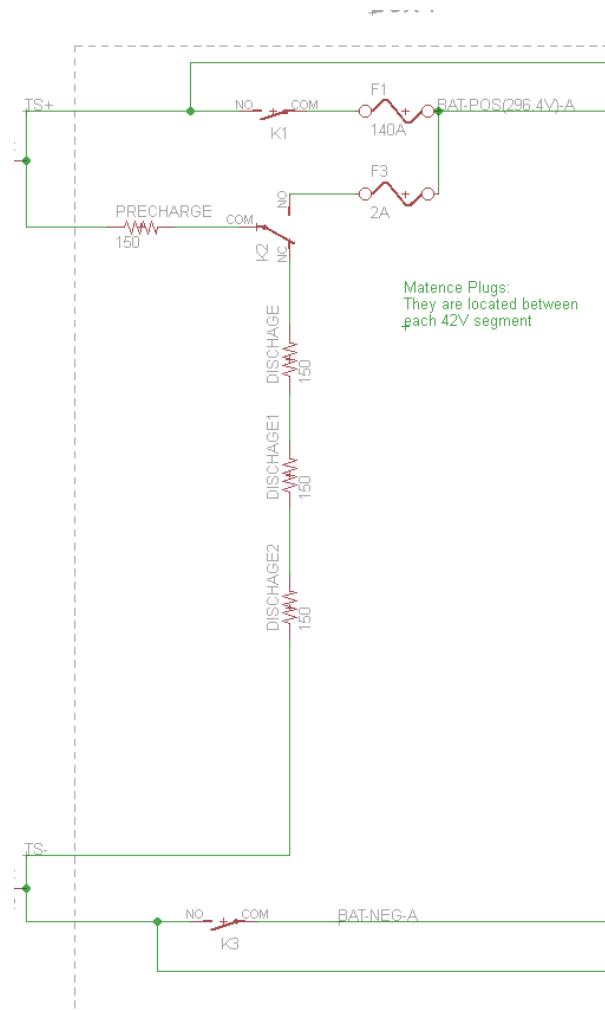
2.10.2 Wiring, cables, current calculations, connectors



$$\text{Formula} = \frac{294.2}{450} 2.7182^{\frac{-t}{150*0.00088}}$$



$$\text{Formula} = 294.2 * 2.7182^{\frac{-t}{150*0.00088}}$$



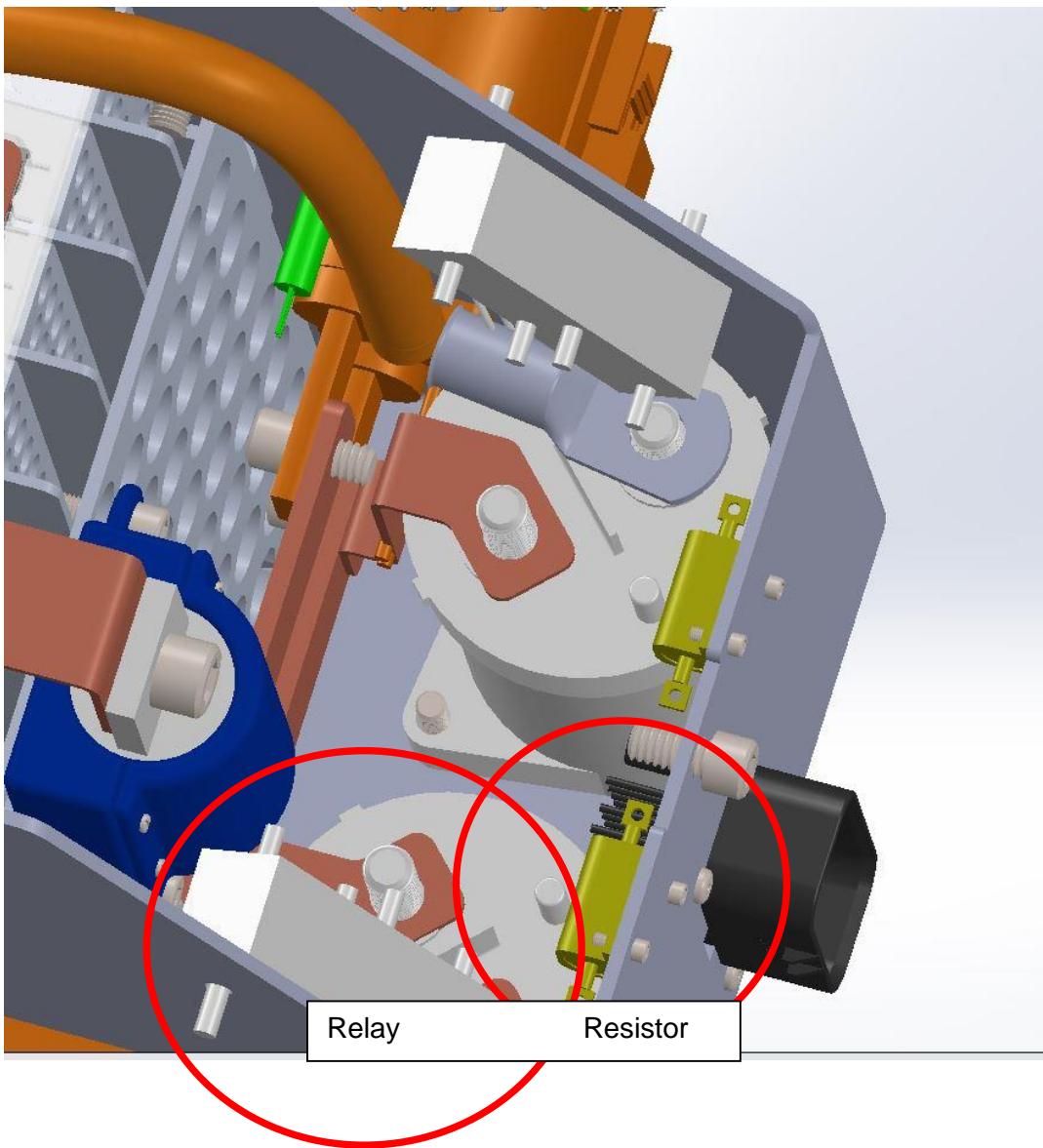
Resistor Type:	WFH160L150JE - Wirewound
Resistance:	450Ω
Continuous power rating:	160W
Overload power rating:	160W
Voltage rating:	600V
Maximum expected current:	0.7A
Average current:	0.4A
Cross-sectional area of the wire used:	1.31 mm ²

Table 2.9 General data of the discharge circuit

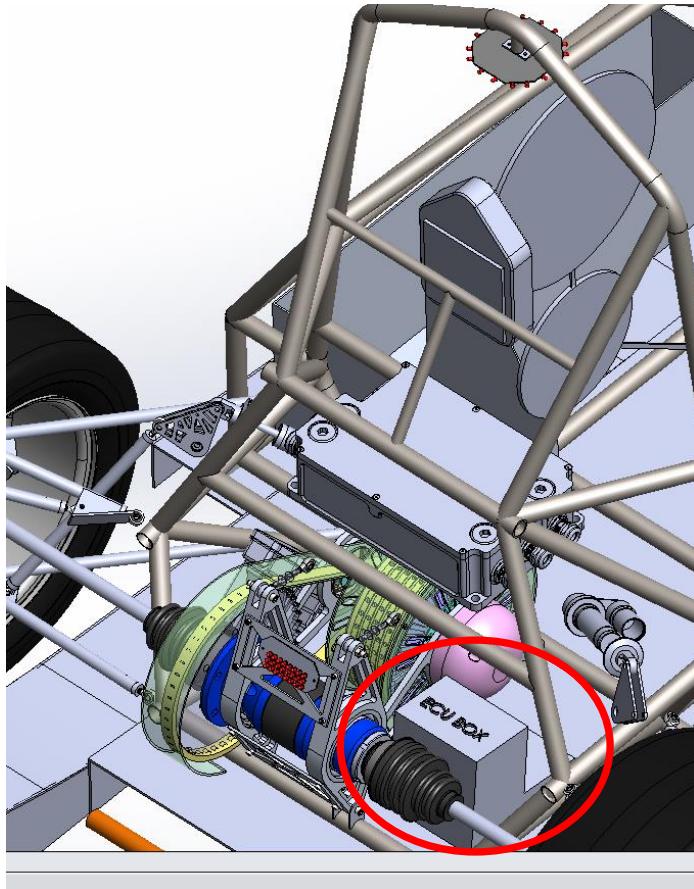
Relay Type:	5502-24-1
Contact arrangement:	SPST-NC
Continuous DC current:	3A
Voltage rating	7500VDC
Cross-sectional area of the wire used:	1.31 mm ²

Table 2.10 General data of the dis-charge relay

2.10.3 Position in car



Control system:



2.11 HV Disconnect (HVD)

2.11.1 Description

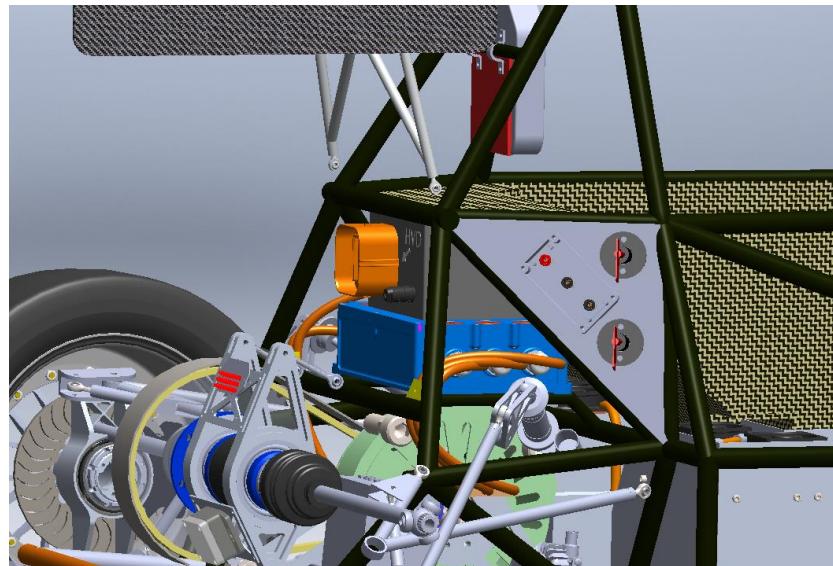
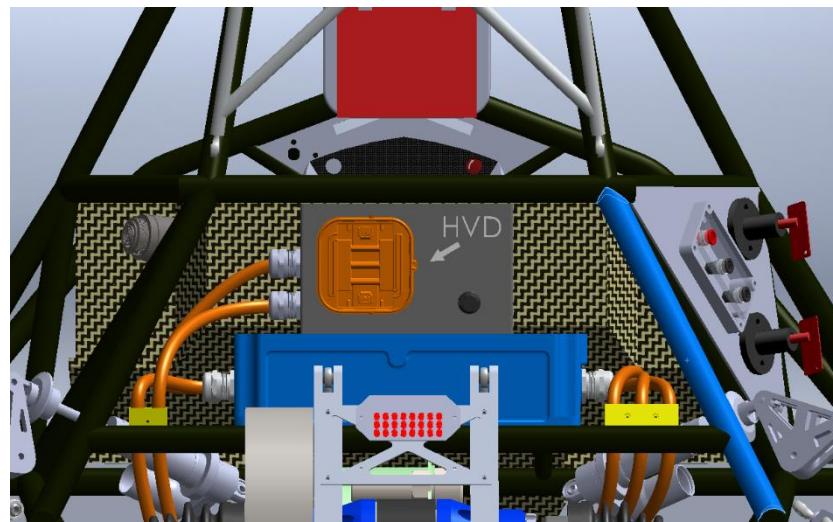
The HVD is a 1-1587987-7 (10.13 Datasheet for HVD) model from TE connectivity. It is a member of their Series B connector family and is capable of 630Amps and 450V. It is disconnected by a pull handle.

2.11.2 Wiring, cables, current calculations, connectors

Wire - EXRAD-FSX1X 1 couple.



2.11.3 Position in car

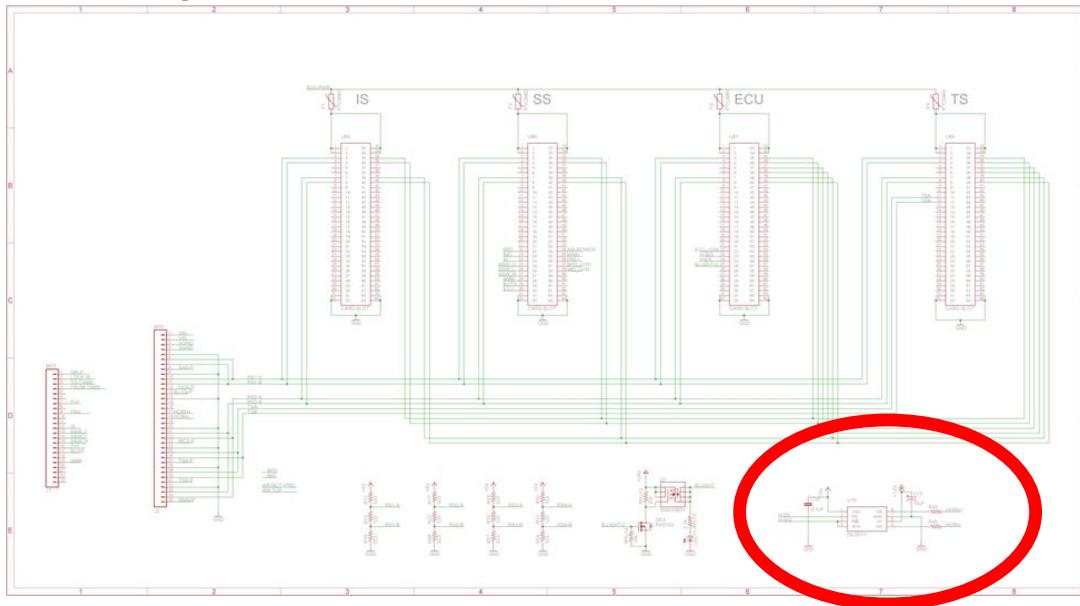


2.12 Ready-To-Drive-Sound (RTDS)

2.12.1 Description

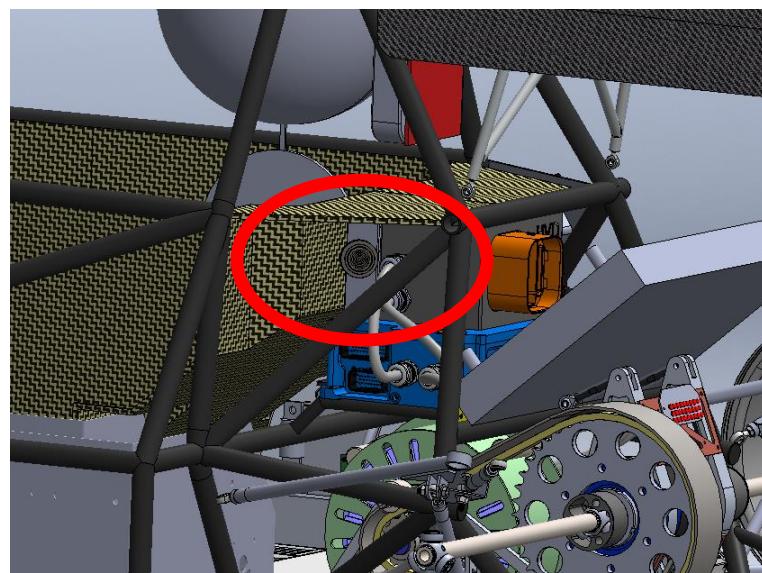
Upon the Accumulator Isolation Relays closing, and the motor controllers turning on, a 24V car horn will turn on **for more than one second and less than three** to notify all that the vehicle is ready to drive. The horn (Piezzo) is driven by a mosfet driver. The signal that drives the buzzer is from the ECU with software. We are using a Mallory PT-4532PLQ. The horn is capable of generating 83bBA at 2 meters.

2.12.2 Wiring, cables, current calculations, connectors



The Horn uses 24 Gauge PVC wire with a 300v and 105C rating. (10.16 Wire Datasheet) There are no connectors for the Horn. 10.16 datasheet

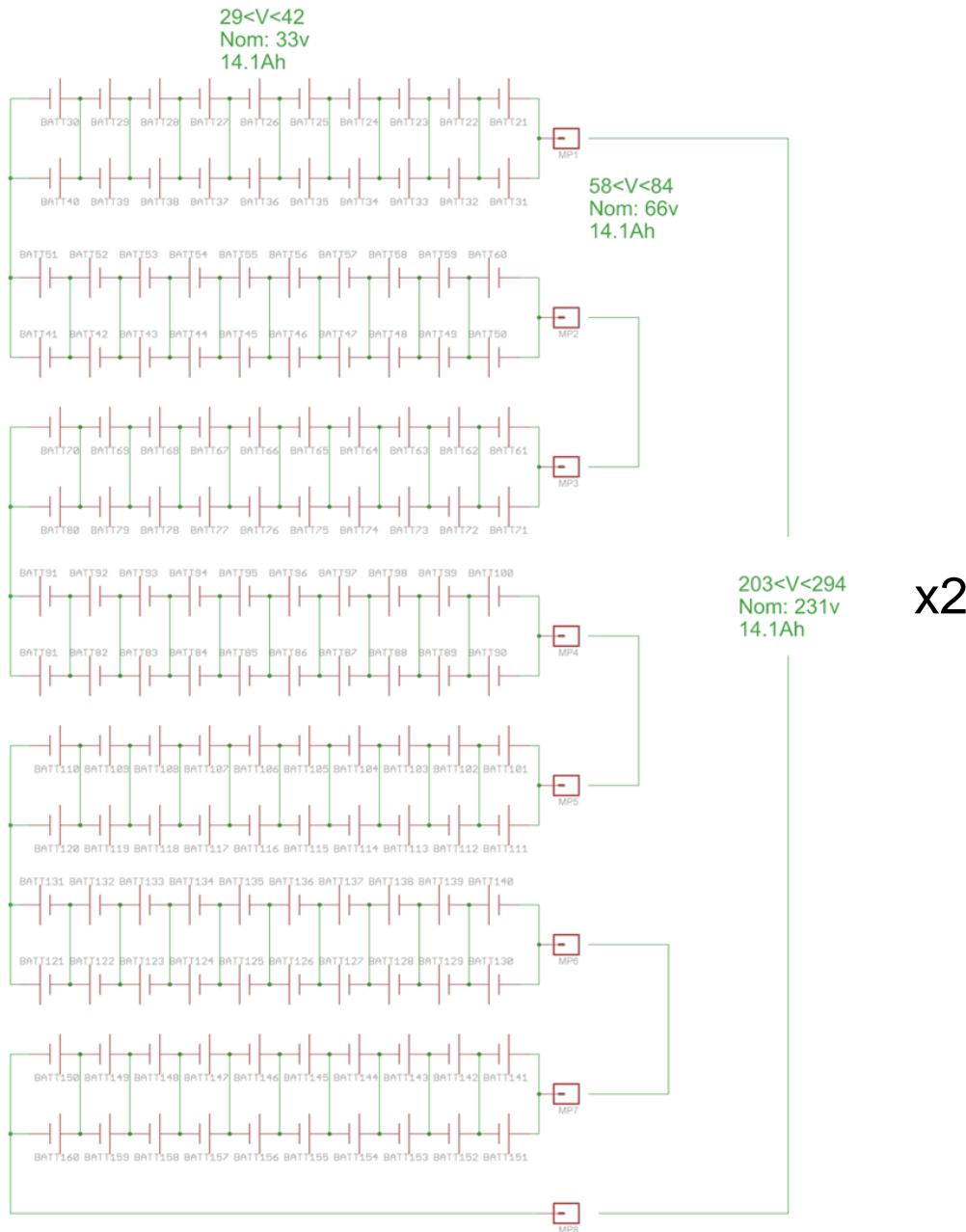
2.12.3 Position in car



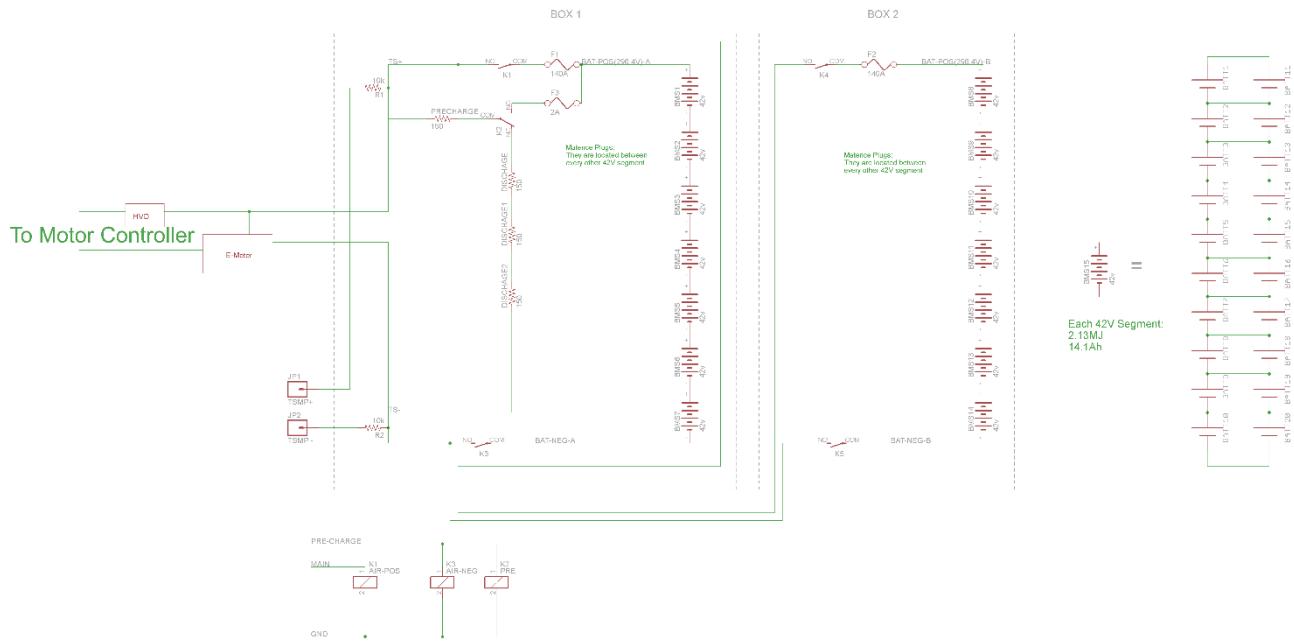
3 Accumulator

3.1 Accumulator pack 1

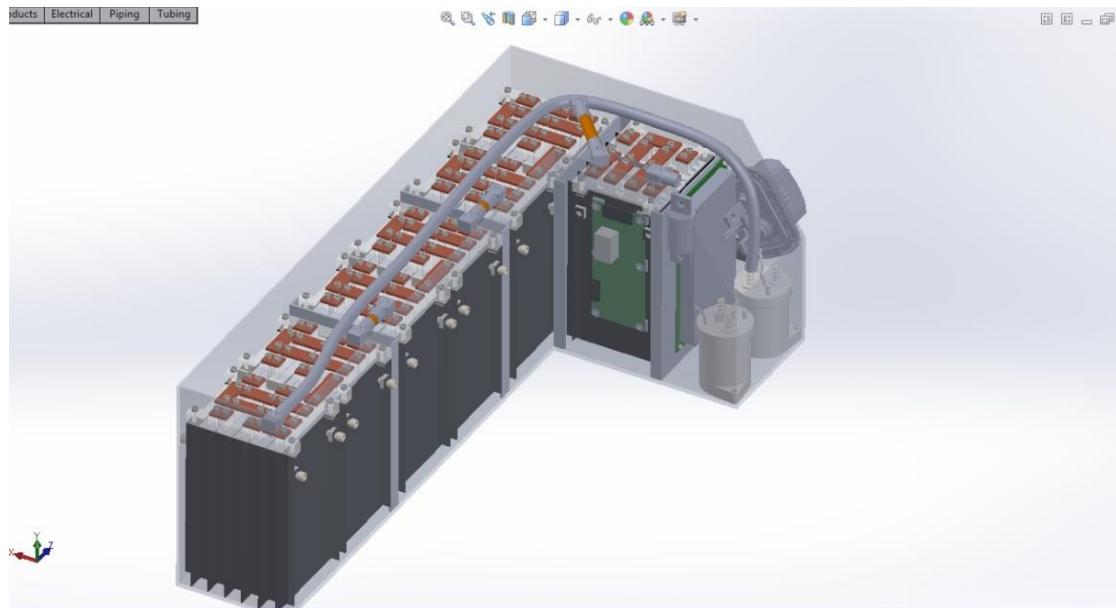
3.1.1 Overview/description/parameters



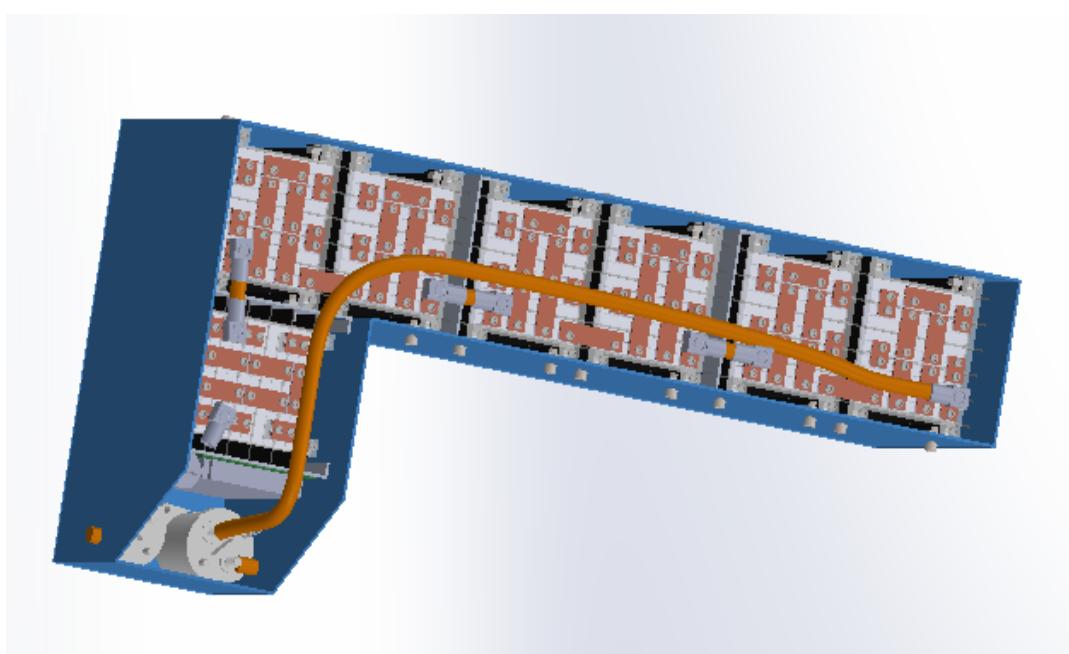
University of Akron 2015 Battery Layout



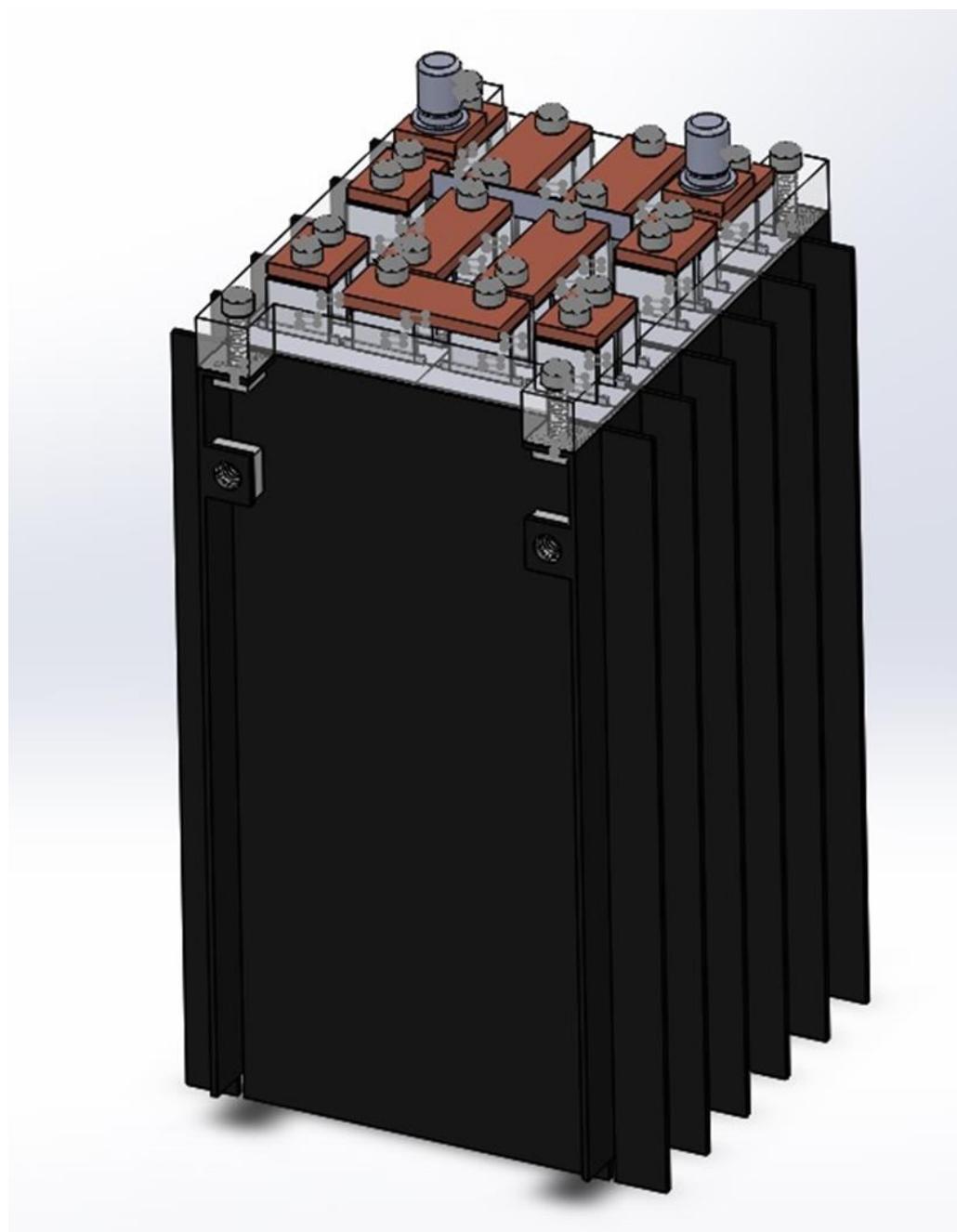
Right (Box1-70s2p)



Left (Box2-70s2p)



Modules (10s2p) x7 per container ~42v



Maximum Voltage:	294VDC
Nominal Voltage:	231VDC
Minimum Voltage:	203VDC
Maximum output current:	580A for 2s
Maximum nominal current:	280A
Maximum charging current:	28A
Total numbers of cells:	280
Cell configuration:	70s4p
Total Capacity:	(7.05Ah)(3.3V)(3600j/Wh)(280cells)x10^6=23.45MJ (7.05Ah)(3.3V)(280cells)=6,514.2 Watt-hours
Number of cell stacks < 120VDC	7

Table 3.1 Main accumulator parameters

3.1.2 Cell description

Cell Manufacturer and Type	Melasta SLPB9145180
Cell nominal capacity:	7.05 Ah
Maximum Voltage:	4.2 V
Nominal Voltage:	3.3V
Minimum Voltage:	3.0V
Maximum output current:	25C for 10s
Maximum nominal output current:	20C
Maximum charging current:	2C
Maximum Cell Temperature (discharging)	60°C
Maximum Cell Temperature (charging)	45°C
Cell chemistry:	LiPo

Table 3.2 Main cell specification

HV Battery Cell Datasheet

3.1.3 Cell configuration

Each accumulator contains 140 cells. The cells are separated in 7 segments containing 20 cells each. The segments are in a 10s2p arrangement. Each parallel cell in the segment is back to back. The cells are connected together by clamping custom copper bus bar on top of the tabs. This is shown in above figure.

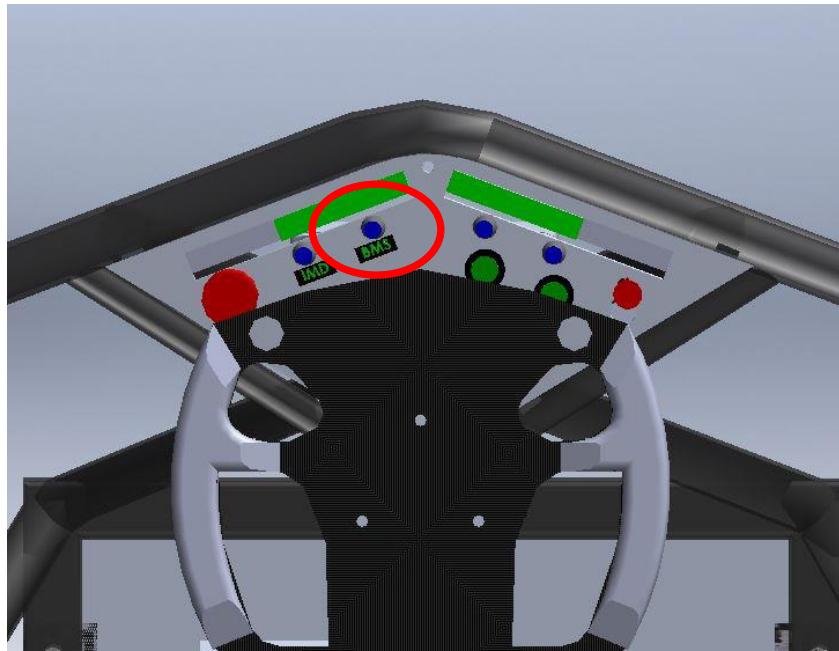
3.1.4 Cell temperature monitoring

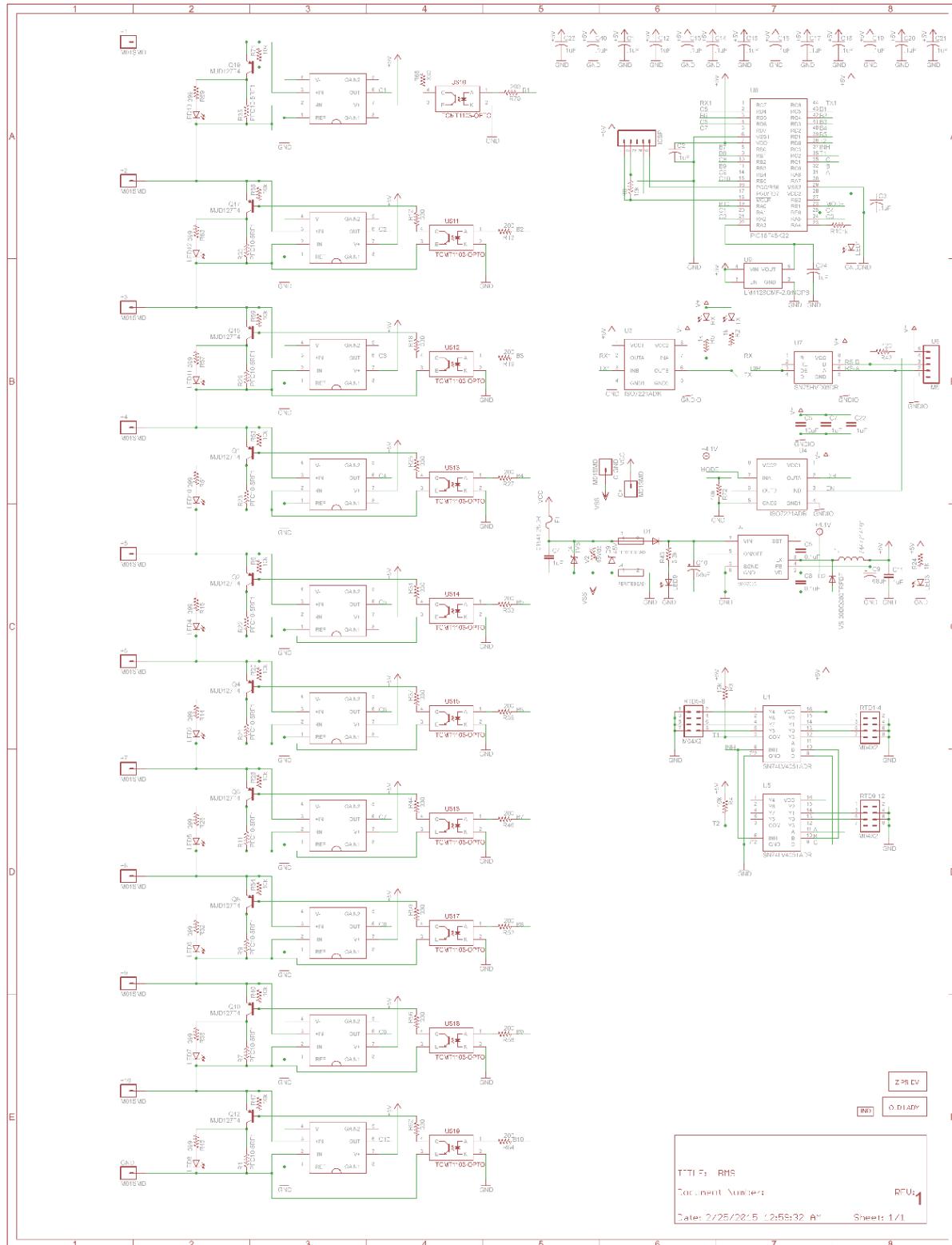
Every cell will be monitored for temperature. We do this by putting an NTC resistor between the cells. Each battery segment PIC will monitor the cell temperature.

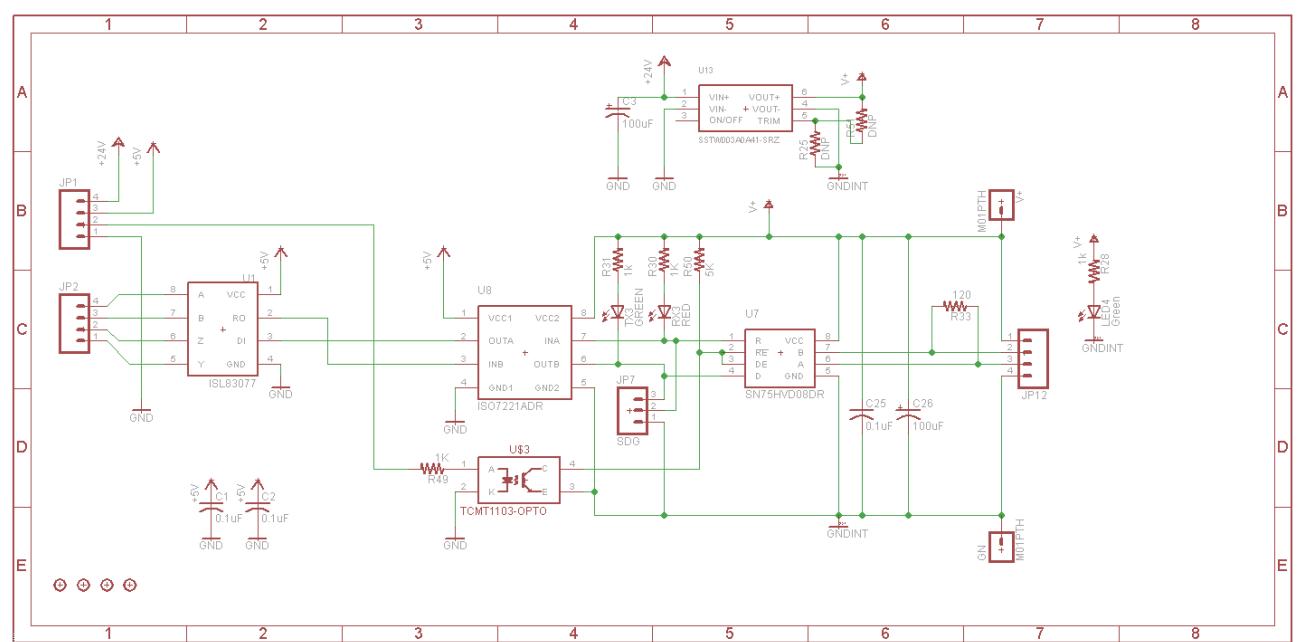
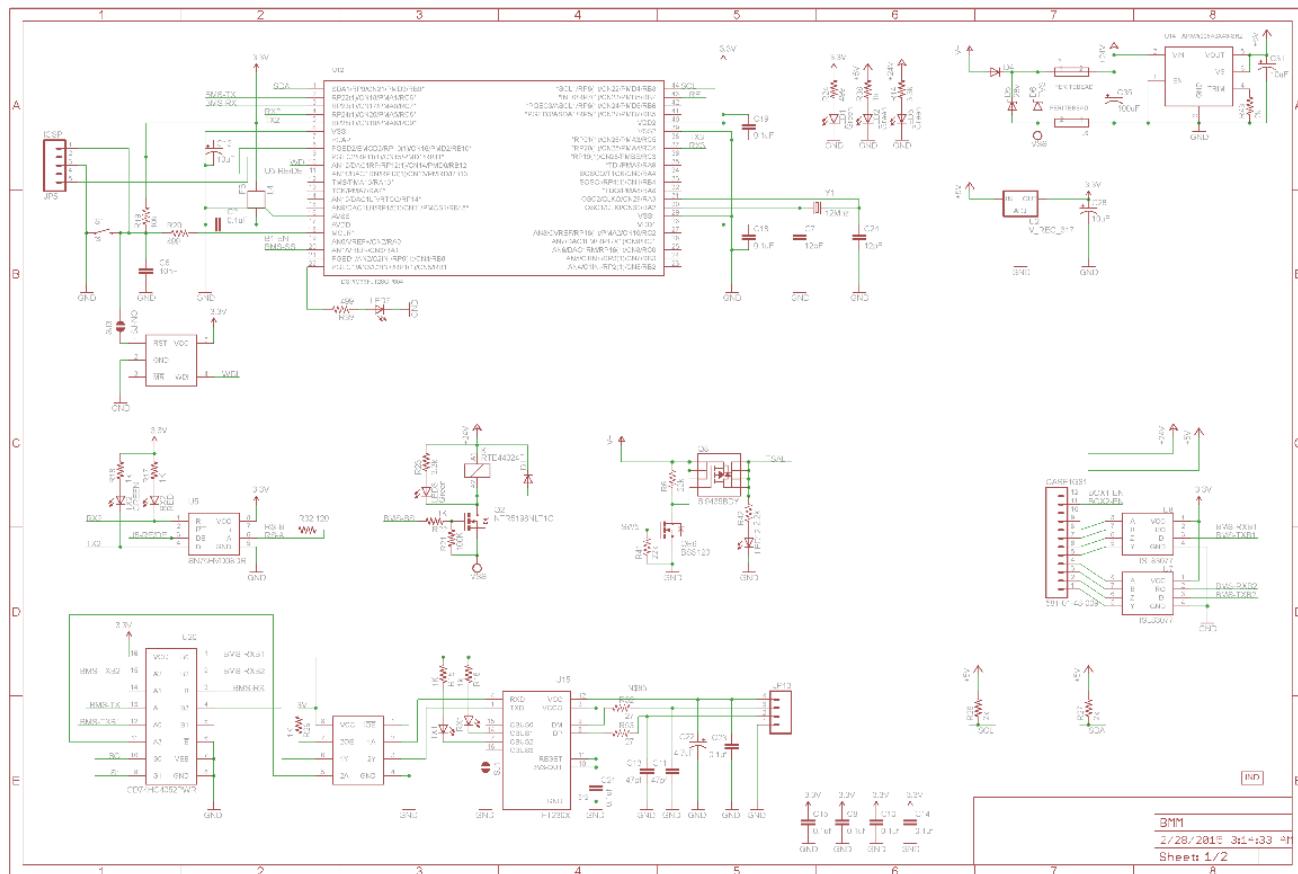
3.1.5 Battery management system

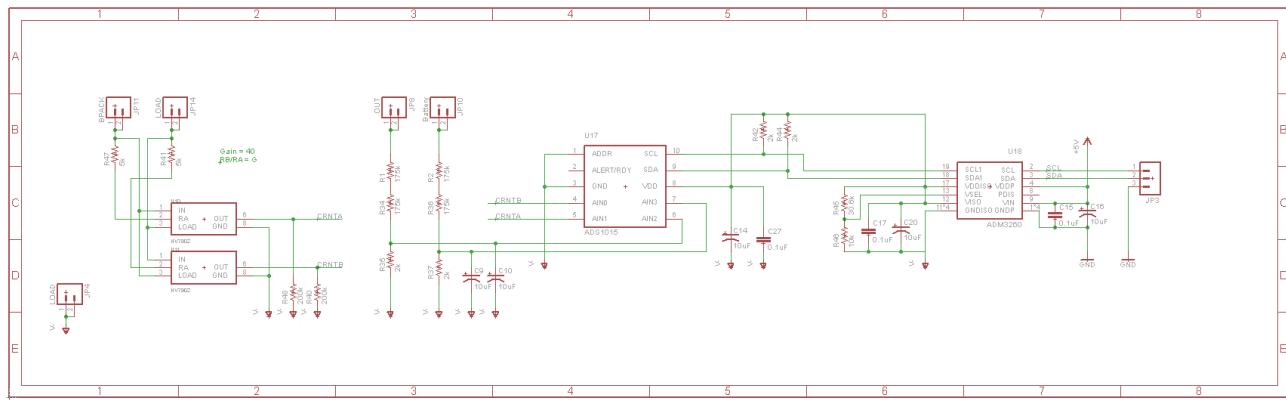
280 cells will be monitored by the BMS that we made ourselves. 14 Slave devices with microcontrollers will communicate with one Master. This communication is done over RS485 and is isolated at each cell and master. The BMS is capable of opening a relay in the shutdown circuit to open the AIRs in the case of an error. At a minimum cell voltage of 3.8 and a maximum of 4.2, the

BMS will take actions to bypass the affected cell(s) and shutdown the tractive system if necessary. The BMS also reacts to temperature problems at 60°C. The BMS can also measure current with a high side current shunt and trigger the safety system. The BMS shuts down the tractive system via a relay that is tied into the safety loop. If shut down, it would trip the safety system and the car would shut down. These boards are linked with **locking Molex connectors**. This allows for hot swapping boards. The slave boards are mounted to the sides of the modules. There is wire going between the BMS PCB and the Battery pack. We have PCB inline fuses to protect the wires.



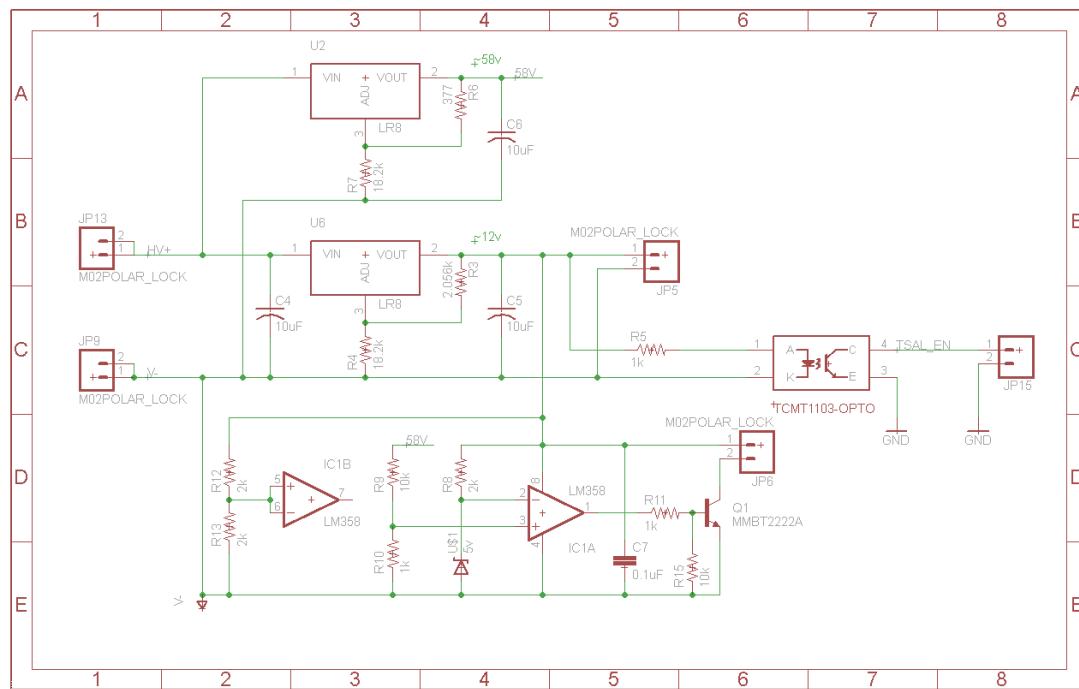






3.1.6 Accumulator indicator

The accumulator indicator is an LED that will be attached to the battery enclosure to indicate that the pack is active. This indicator will be wired across the first and last AIR's, so that it is powered when there is voltage on the vehicle side of the accumulator container. It therefore the circuit below is only powered from tractive system voltage. It does not run off of the GLVS and therefore work outside of the car. The wire used for this AWG 22.



3.1.7 Wiring, cables, current calculations, connectors

Wire type	Alpha Wire 1855
Continuous current rating:	7A
Cross-sectional area	0.030 in
Maximum operating voltage:	600V
Temperature rating:	105 °C
Wire connects the following components:	Cell and BMS

Table 3.3

3.1.8 Accumulator insulation relays

Relay Type:	EV200AAANA
Contact arrangement:	SPST
Continuous DC current rating:	500A
Overload DC current rating:	N/A
Maximum operation voltage:	900VDC
Nominal coil voltage:	24VDC
Normal Load switching:	Make and break up to 500A
Maximum Load switching	10 times at 1500A

Table 3.4 Basic AIR data

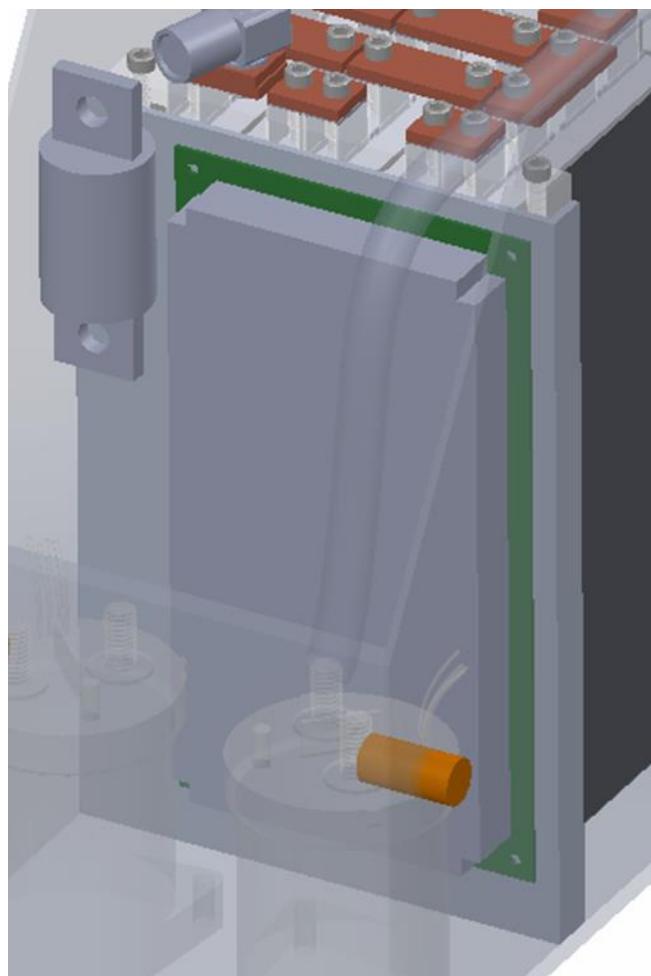
AIR Data sheet

3.1.9 Fusing

We use two main fuses in the car. One in each bank that fuses the outputs of each individual box. The fuse holders we are using are the LSCR001 from little fuse. They are 600v, 400A rated fuse holder.

Fuse manufacturer and type:	Littelfuse, Class T
Continuous current rating:	150A
Maximum operating voltage	300VDC
Type of fuse:	High speed
I _{2t} rating:	1500A2s at 450VDC
Interrupt Current (maximum current at which the fuse can interrupt the current)	20000A

Table 3.5 Basic fuse data



Location	Wire Size	Wire Ampacity	Fuse type	Fuse rating
Cells to AIRs	2 AWG	255	2xMNO Fuse	145
AIR to Motor controller	2 AWG	255	N/A	N/A
AIR to TSAL	24 AWG	3.5	EFG Fuse	XXX
Accumulator output connector	2 AWG	300		
Cells to BMS	22	7		

Table 3.6 Fuse Protection Table

3.1.10 Charging

The battery charging will use the battery management system to control the charger. The BMS-master by default is not able to talk to the charger directly and control the AIR's.. We designed a charging control adapter board that hosts the interfaces and isolation necessary to follow the rules of the competition. This board also hosts the safety system for the IMD, control relays, lights and LCD display.

Charger Type:	SmartCharge-12000
Maximum charging power:	12kW
Maximum charging voltage:	350V
Maximum charging current:	70A
Interface with accumulator	serial communication
Input voltage:	120-230 VAC
Input current:	Up to 50A

Table 3.7 General charger data

3.1.11 Mechanical Configuration/materials

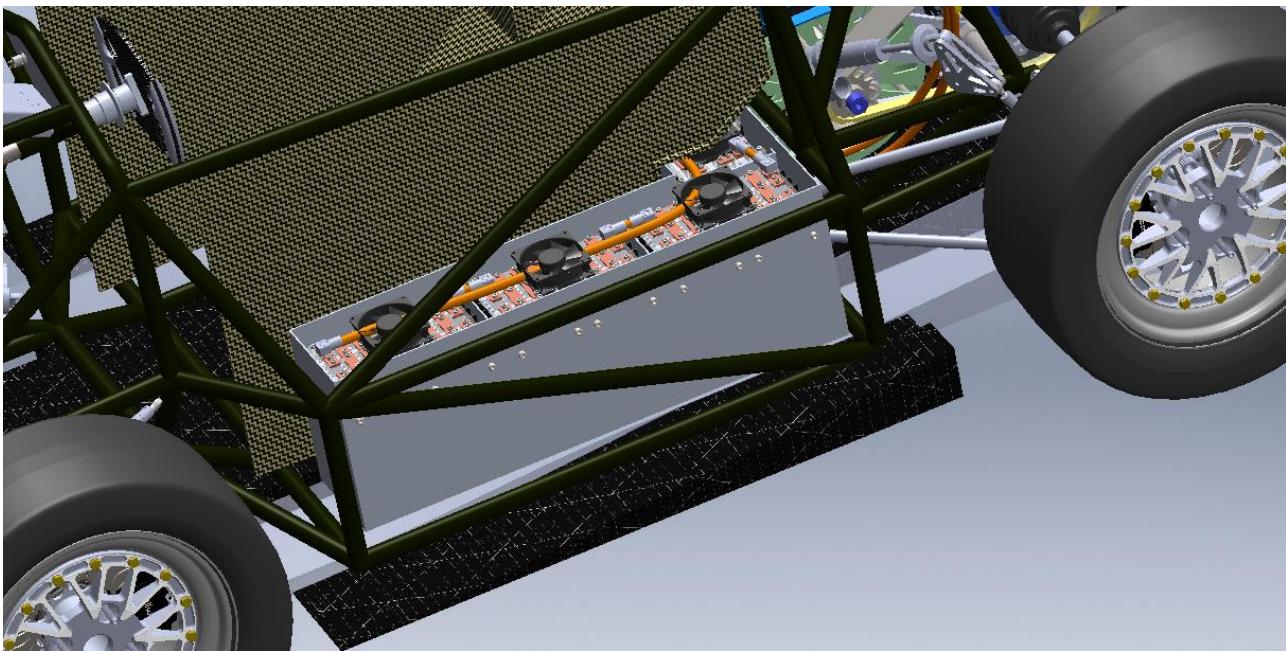
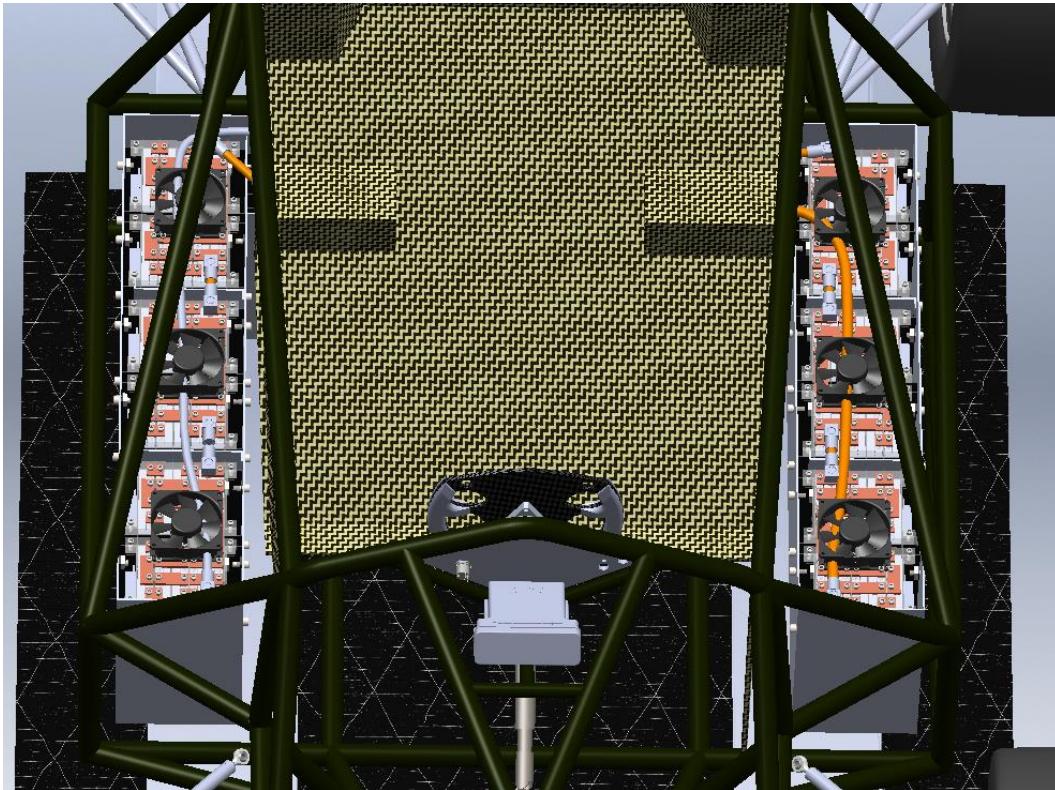
The accumulator design features two separate containers each housing 140 cells along with accompanying components and PCBs. These containers are designed to be easily removable for charging and servicing. The HV warning sticker for these accumulators will be positioned on the exterior walls near the HV connector. The connectors being used in the design incorporate an interlock, however additionally these connectors will be zip tied to ensure full connection with the port. The housing of the container is made up of 5 components; 3 side panels, 1 floor plate, and 1 lid. To minimize the number of fasteners used in the overall assembly, bending of the side walls was utilized. Where the 3 side walls mate are 3 bolted joints where 3 ¼" bolts are used to secure them. Flanges were also designed to mate with the floor plate and the corresponding jointed connection rules were followed. The lid of the housing is secured via 6 bolts to ensure the lid is secure to the rest of the housing. The accumulator will also have holes/ports for cooling aspects. Holes are included in both the lid and the bottom plate, these holes enable for an even flow of air through the cell segment walls. The holes on the lid mate with 24 volt PC fans that use filters and tubing to the front intake to ensure water is not leaked into the container. The holes on the bottom exit to an area that does not experience water and therefore not necessary to seal.

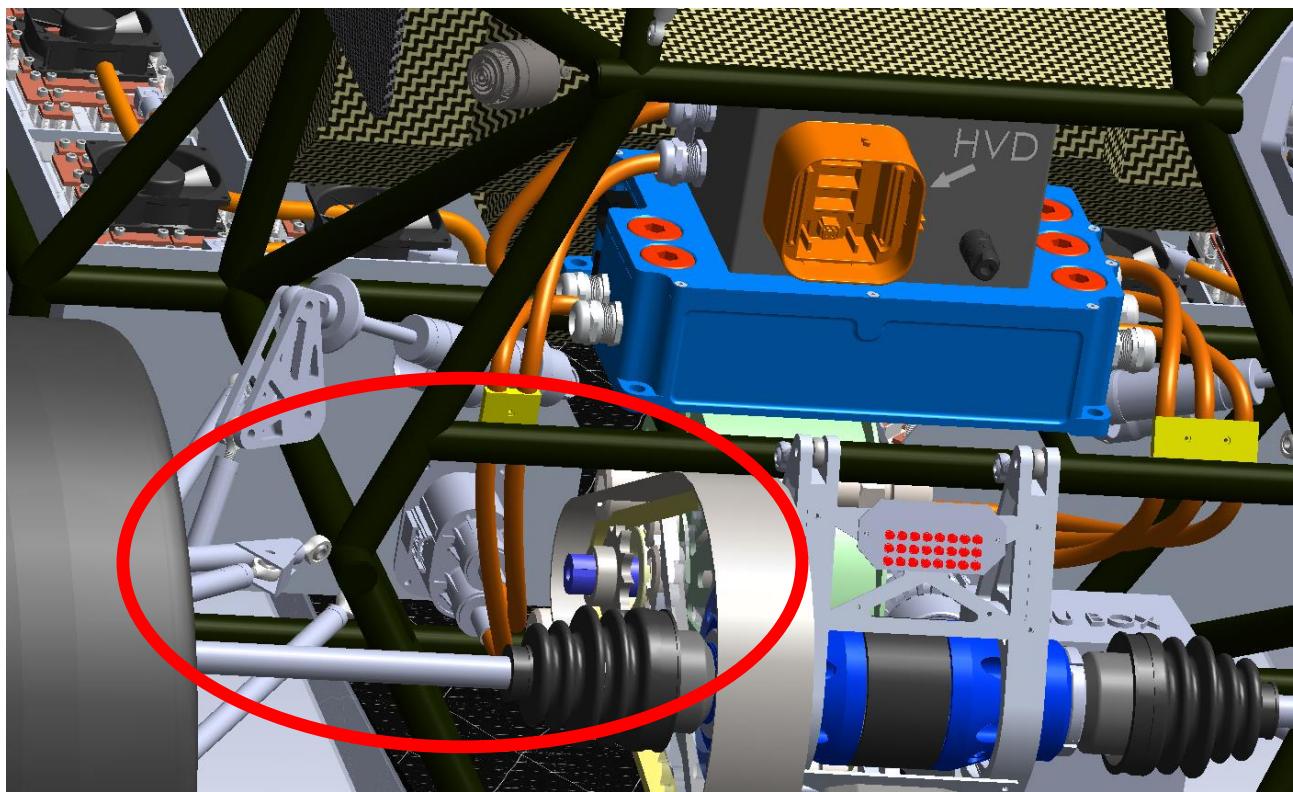
The design of the battery segments incorporates an array of aluminum partitions. These partitions interlock with each other and are fastened into the accumulator via bolts to the sidewalls. The partitions are designed and assembled in such a way so that cells are compressed to an allowable pressure and thus ensuring that they are securely in place inside the segment wall assembly. The electrical tabs of the cells are connected using a series of copper busbars. The busbar width (0.600") and thicknesses (0.0625" and 0.125") were determined using formulas from the current that will be witnessed in through the cells. The busbars themselves are secured via a bolted method that incorporates a steel mounting plate with a threaded hole to accept the bolt that runs through the busbar and the cell tabs. The bolts are locked to the busbar with a Belleville Washer to increase the distribution of pressure to the busbar and to ensure loosening doesn't occur over time. The busbars are oriented to the cell segments via an acrylic pattern that is mechanically attached to the top of the segment wall assembly. These acrylic patterns create electrical separation/insulation between the busbars and thus prevents arching. Terminal rings will be used to route the current sense from the cells to the BMS and these will be secured underneath the bolt used to secure the busbar. The BMS boards for each electrical segment are located along the vertical sides of the segment wall assembly. To connect the electrical segments together in accordance to the rules quick disconnects were designed in. This quick disconnects satisfy the need for maintenance plugs because the electrical segments are under the 6MJ and 120V limit. We are using the 6648223-1 from TE with a boot to cover up the connector. Maintenance Plugs

The accumulator features a separate compartment for components of the accumulator that need to be electrically isolated. Each compartment inside the accumulator is electrically isolated by aluminum dividers wrapped in Kapton tape. Inside this component compartment AIRs, fuses, connectors, relays, current sense, resistors among other are located. These components are arranged in a way to prevent low voltage wiring from violating the 1.2" electrical insulation requirement. Also included in this compartment is the Indicator Light, which is positioned directly

above connector. This indicator light is of the panel mounted variation, therefore it can simply secure against the side of the accumulator wall.

3.1.12 Position in car





3.2 Accumulator pack 2

We don't have two separate packs

Energy meter mounting

3.3 Description

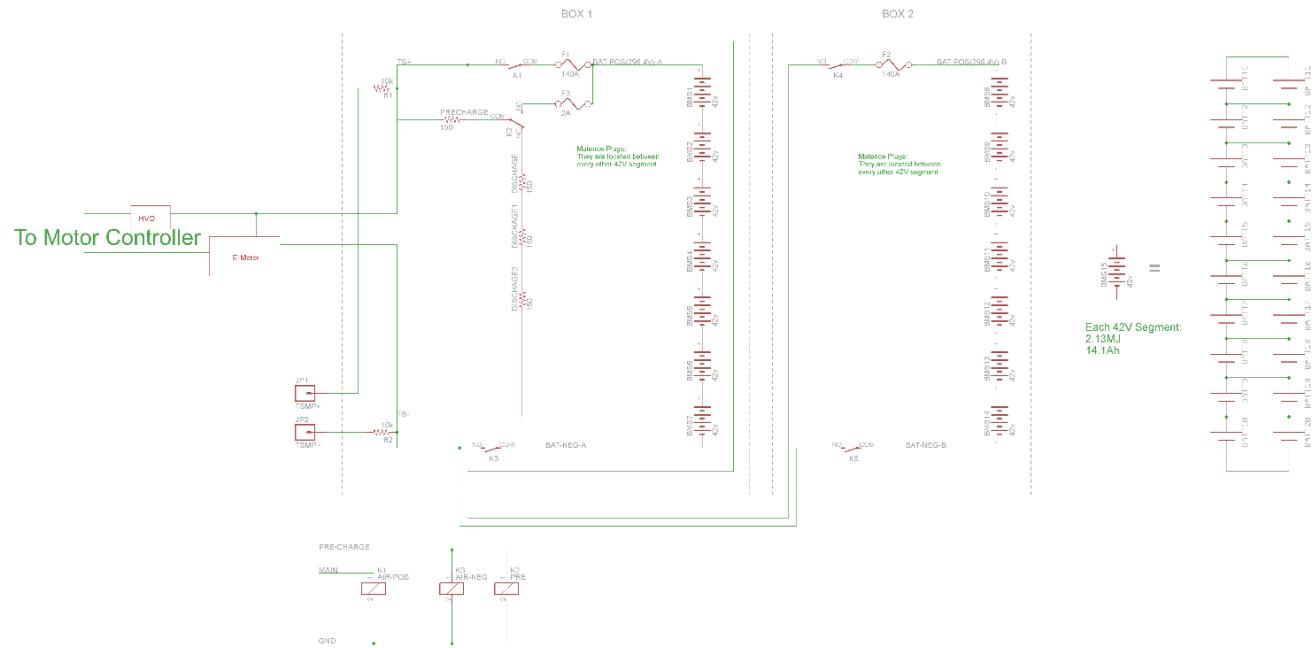
Energy Meter will be connected between the ground of the accumulator and motor controller. It will measure the total energy used and calculate the efficiency.

3.4 Wiring, cables, current calculations, connectors

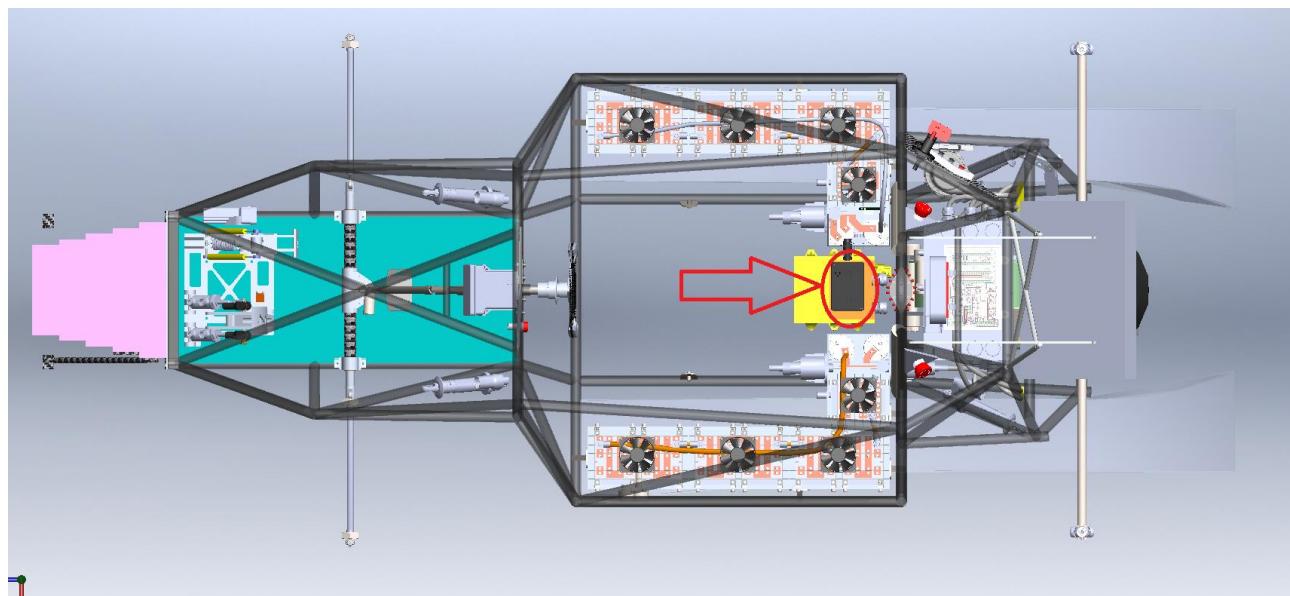
All connections to the accumulator, the motors, and the energy meter are all Exrad XLE 2 cable.

We have a 1A fuse between the TS+ and the HV sense input on the box.

University of Akron 2015 Battery Layout



3.5 Position in car



4 Motor controller

4.1 Motor controller 1

4.1.1 Description, type, operation parameters

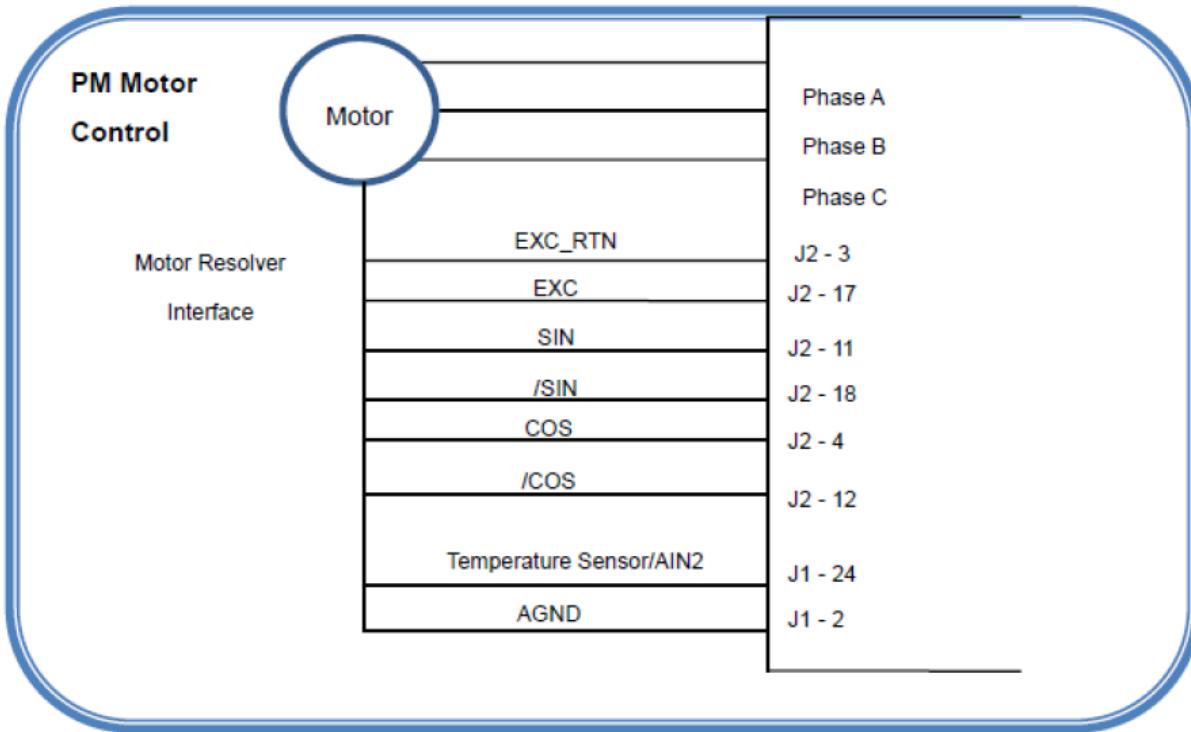
The PM100DX from Rinehart Motion Systems we are using are permanent magnet brushless AC motor controllers. They are capable of 0-360V and 300Arms. The motor controllers are commanded via analog signals sent by our self-designed motor controller PCB (MCS). It communicates over a RS485 communication bus from the ECU. The motor controllers also control the regenerative braking of the car. This is set from hardware controlled by our software. The controllers are isolated. Because of that, nothing connecting to them needs isolated from chassis ground.

Motor controller type:	RMS PM100DX brushless AC
Maximum continuous power:	108kW
Maximum peak power:	126kW for 30s
Maximum Input voltage:	360VDC
Output voltage:	250VAC
Maximum continuous output current:	300Arms
Maximum peak current:	350Arms for 30s
Control method:	analog signal
Cooling method:	water
Auxiliary supply voltage:	12VDC

Table 4.1 General motor controller data

4.1.2 Wiring, cables, current calculations, connectors

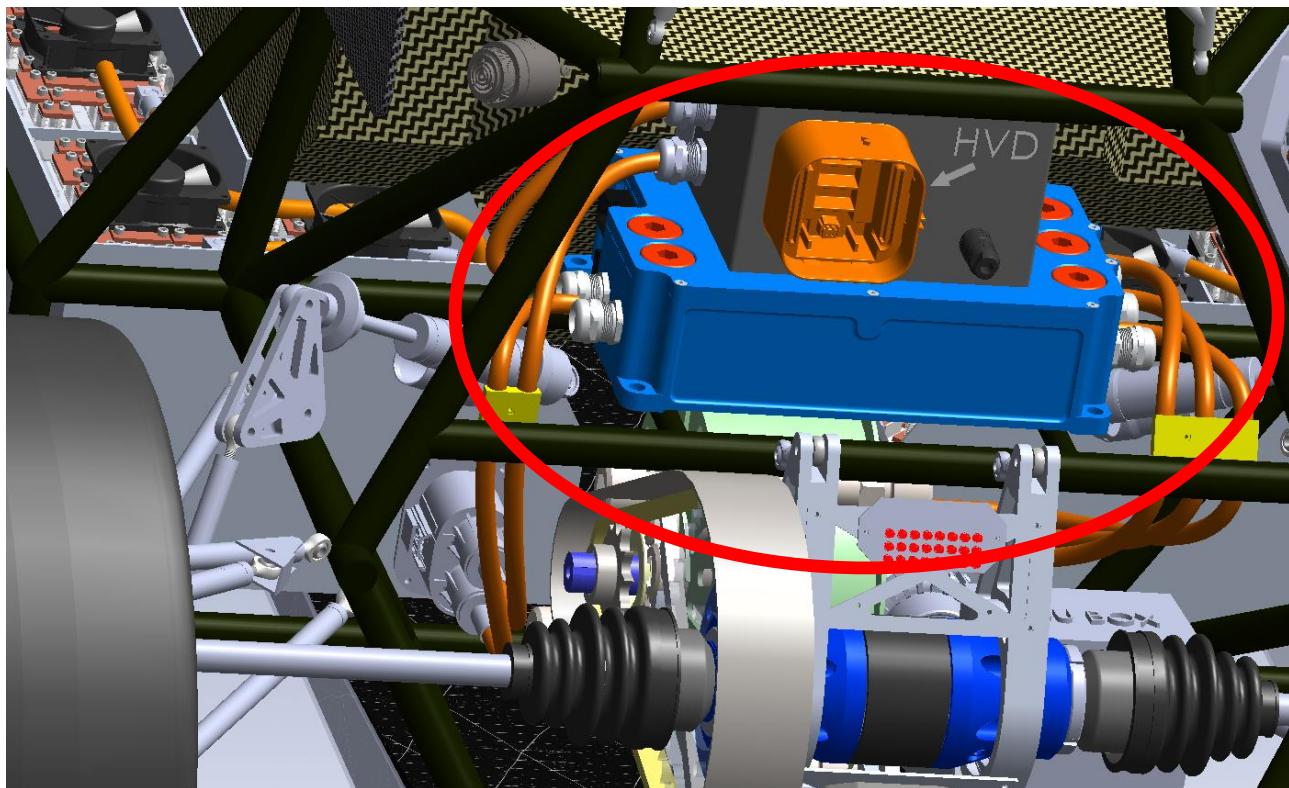
All connections to the accumulator, the motors, and the energy meter are all Exrad XLE 2 cable. The motor controller will do all of our shield grounding for us on the High power cable. They go through grounding cable glands. This makes a sealed connection. The conductor is clamped in a bus bar in the motor controller.



Wire type:	Champlain Exrad xlx2x
Current rating:	255A
Maximum operating voltage:	1000V
Temperature rating:	240 °C

Table 4.2 Wire data of company A, 0.205 mm²

4.1.3 Position in car



4.2 Motor controller 2

There is only one motor controller.

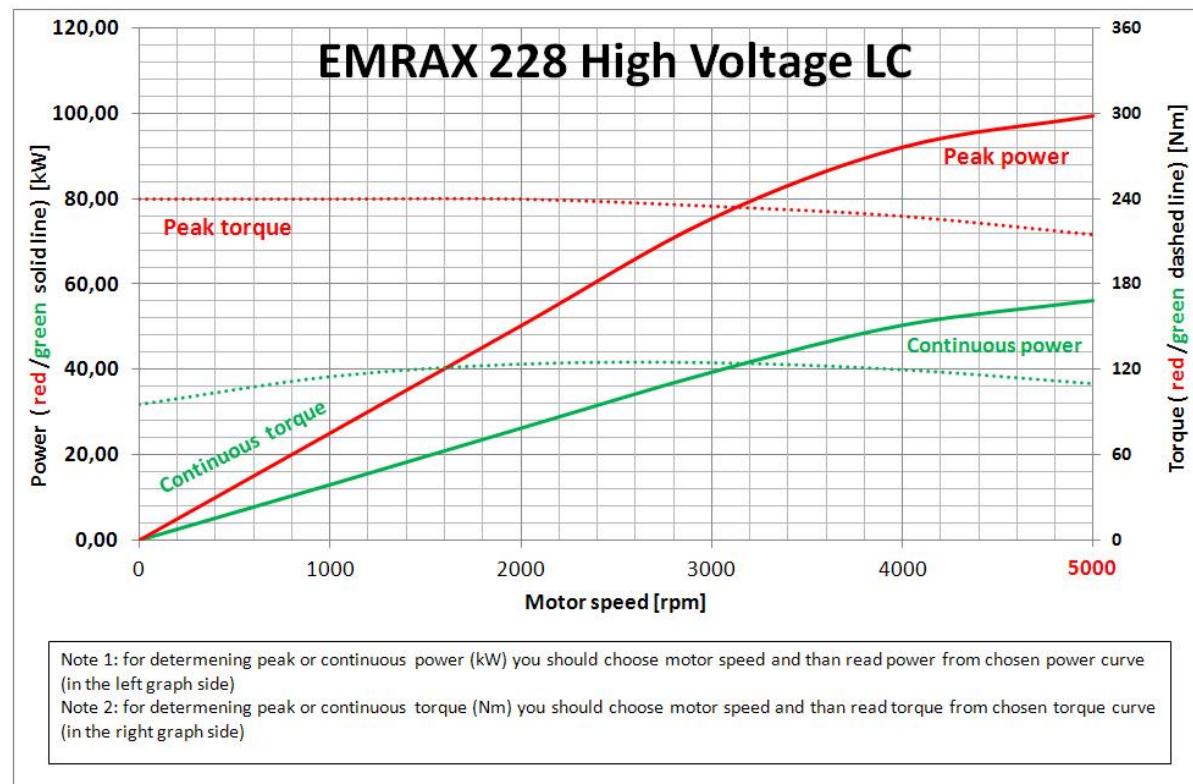
5 Motors

5.1 Motor 1

5.1.1 Description, type, operating parameters

Motor Manufacturer and Type:	Enstroj EMRAX228 HV
Motor principle	Brushless Synchronous Three Phase AC
Maximum continuous power:	45kW
Peak power:	100kW for 3s
Input voltage:	50-600Vdc
Nominal current:	115A
Peak current:	240A
Maximum torque:	240Nm
Nominal torque:	125Nm
Cooling method:	Water

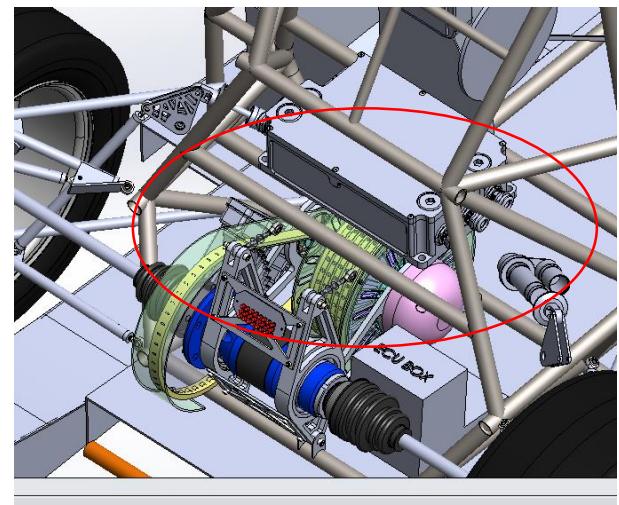
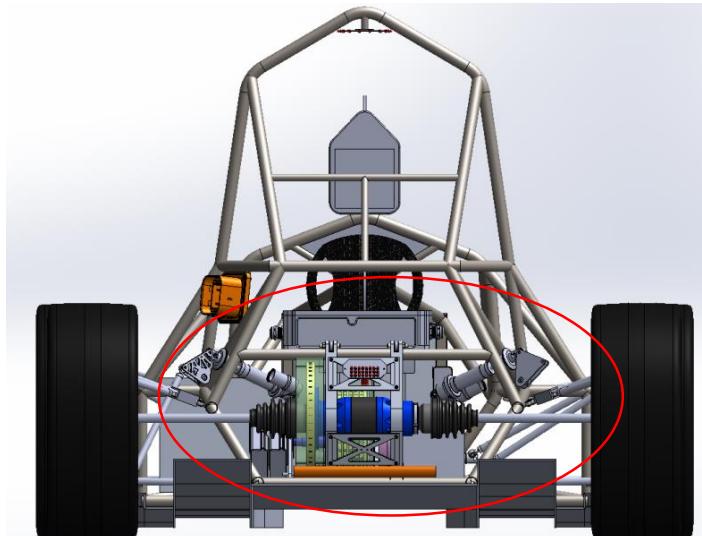
Table 5.1 General motor data



5.1.2 Wiring, cables, current calculations, connectors

The three shielded wires coming to the motor have 90 degree crimp terminals and then bolted on to the connections to the motor. We are adding locking nuts to prevent looseness of the connection. We are 3D printing a cover that goes over these terminals to provide isolation spacing and protect people.

5.1.3 Position in car



5.2 Motor 2

We only have one motor in the car.

6 Torque encoder

6.1 Description/additional circuitry

The two CLS1322-075 sensors are linear displacement sensor. They will be connected to the throttle pedals of the vehicle. As the pedal moves the sensor will slide with the pedal and provide an analog output to the system. That output will be sent as an input to a conditioning circuit. Once conditioned, the signal will be sent to the main controller.

Torque encoder manufacturer and type:	CLS1322-075
Torque encoder principle:	potentiometer
Supply voltage:	3.3V
Maximum supply current:	20mA
Operating temperature:	-20..180 °C
Used output:	150mV-3.2V

Table 6.1 Torque encoder data

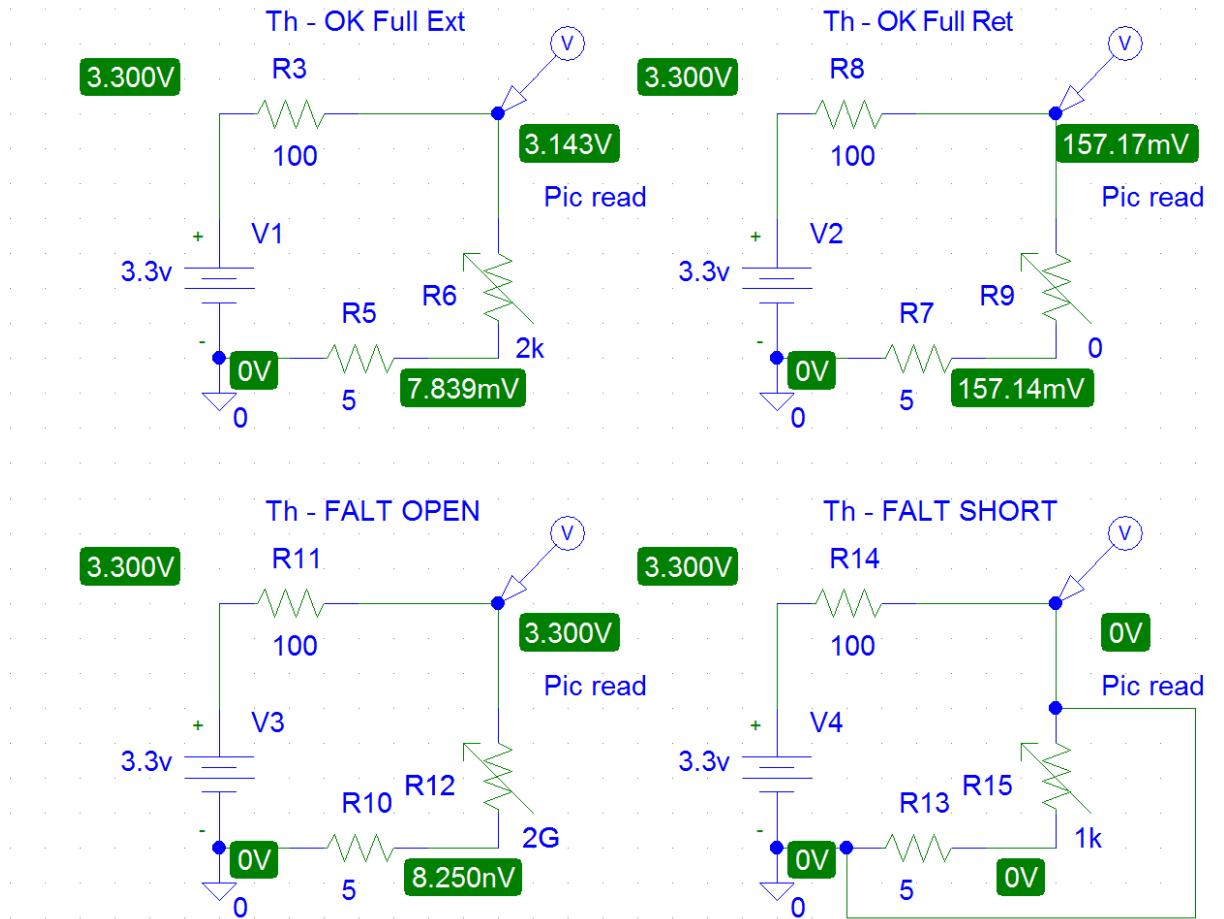
6.2 Torque Encoder Plausibility Check

If an error occurs in the measuring requested torque from the throttle pedal the main controller will shut the vehicle down. A number of errors could occur. If the communication is lost between the SAS (Where the analog signal is measured) and ECU the car will be shutdown (AIR's opened). If at any time the conditioning circuit is shorted or becomes open the controller will see the loss of signal and shut the car down. If the outputs of the two potentiometers differ by more than 10% the vehicle will be shut down as stated in the rules.

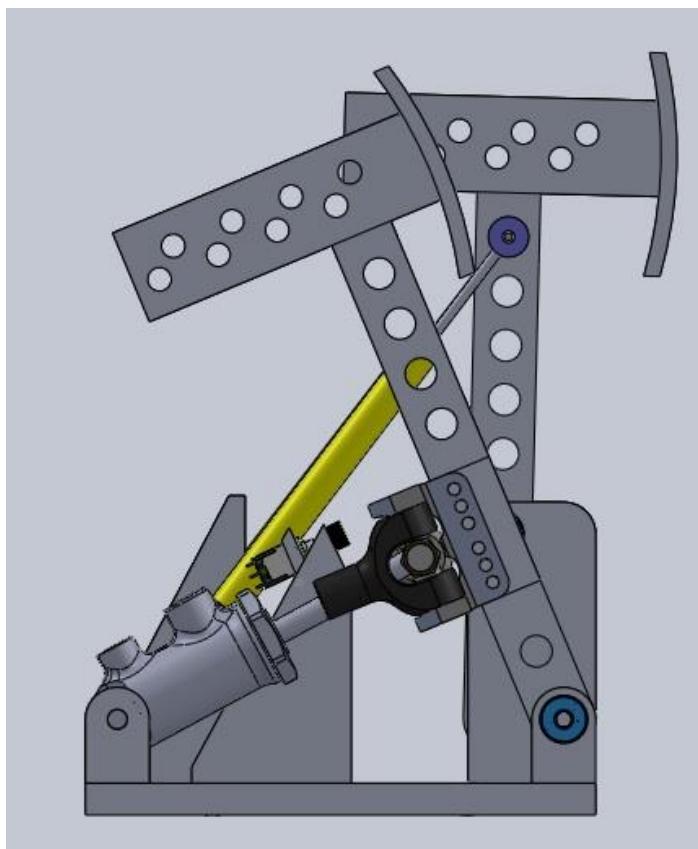
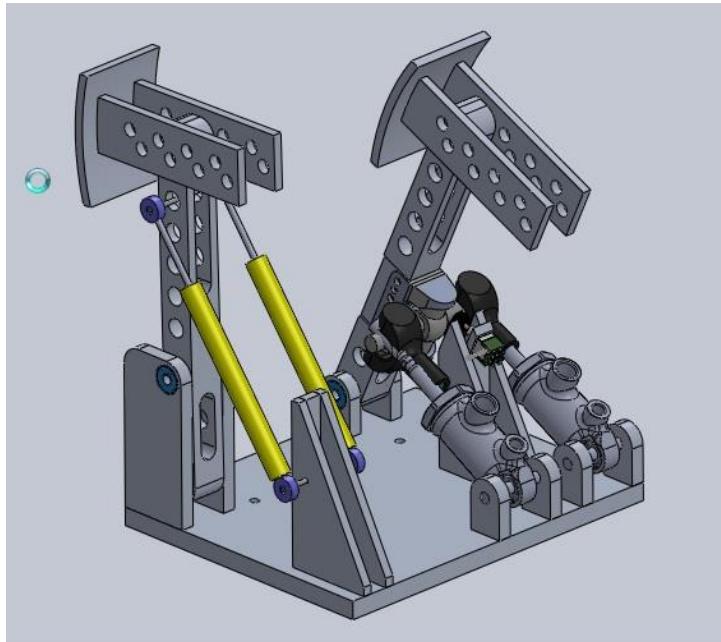
We check for above failures by first, monitoring data integrity by using check sums in serial data and in code. We monitor position sensors integrity by using the sensors as rheostats and adding a 5 ohm resistor in series with the sensor. We added a 100 ohm pull up on the ADC pin. With the sensor connected to the ADC pin to ground we can measure all fault modes.

The analog output to the motor controller is made created by an I2C DAC. It is buffered by an op-amp. That signal goes to a SPDT relay. The output to the motor controller is on the common pin. The DAC is connected to the NO pin. The NC pin is pulled to ground. The uC reads the DAC to verify output matched set point. If they match, the relay opens and stays open as long as the car is on and output matches set point.

6.3 Wiring



6.4 Position in car/mechanical fastening/mechanical connection



7 Additional LV-parts interfering with the tractive system

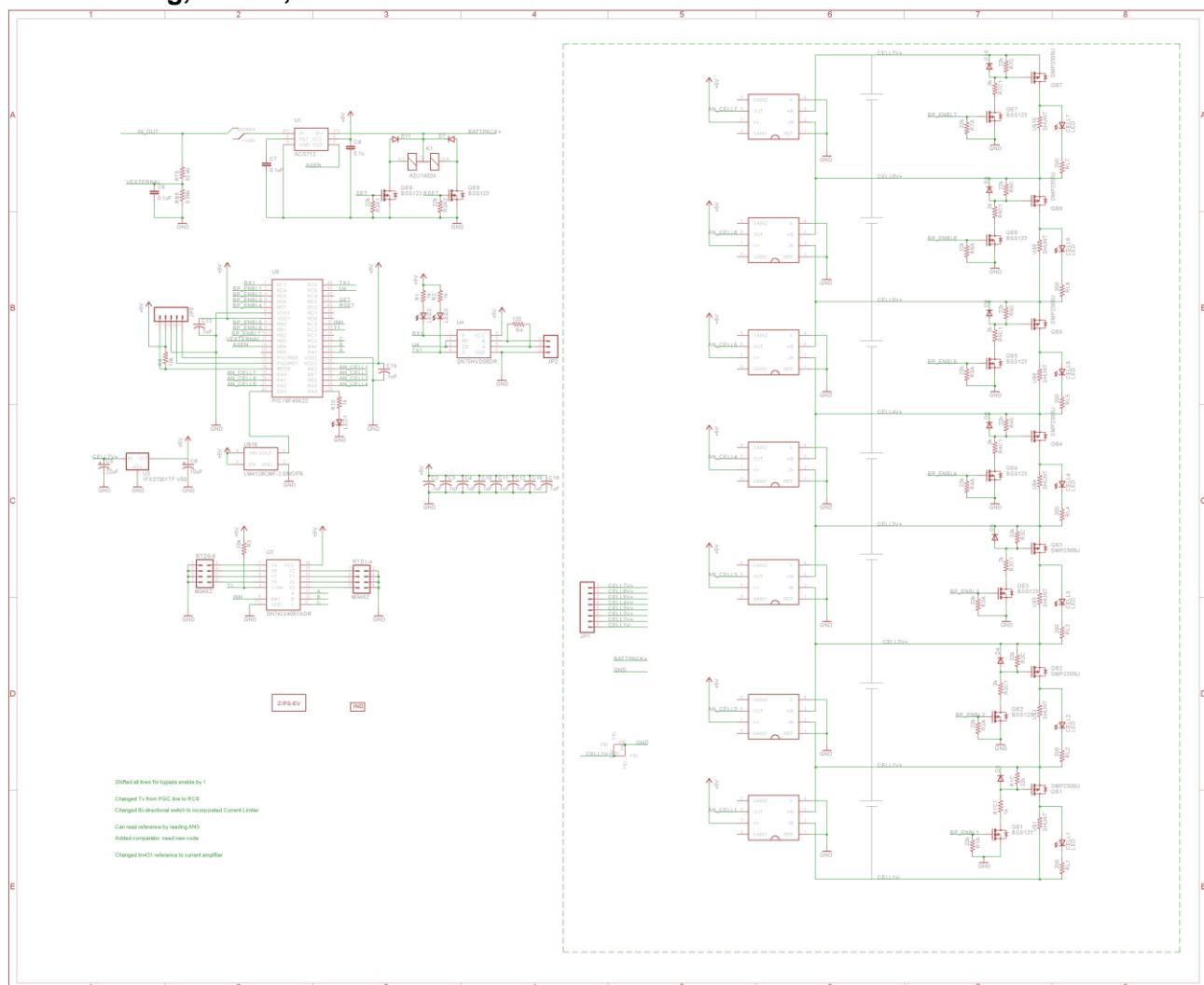
7.1 LV part 1 – GLVS

Our GLVS is powered by a custom battery pack. This pack is protected by a student designed battery management system that is from a reference design from Design Flux Technologies.

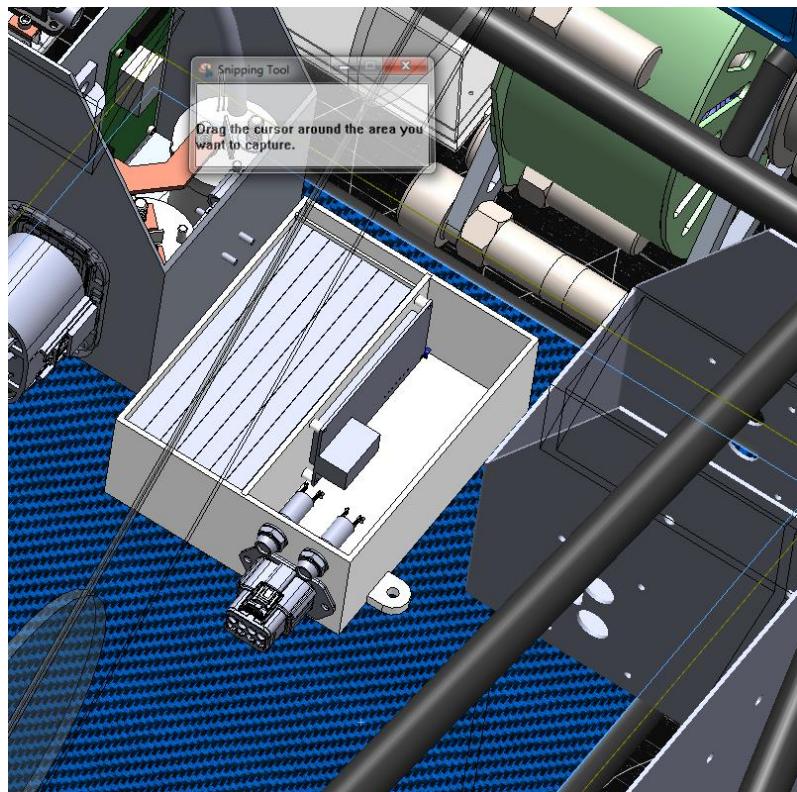
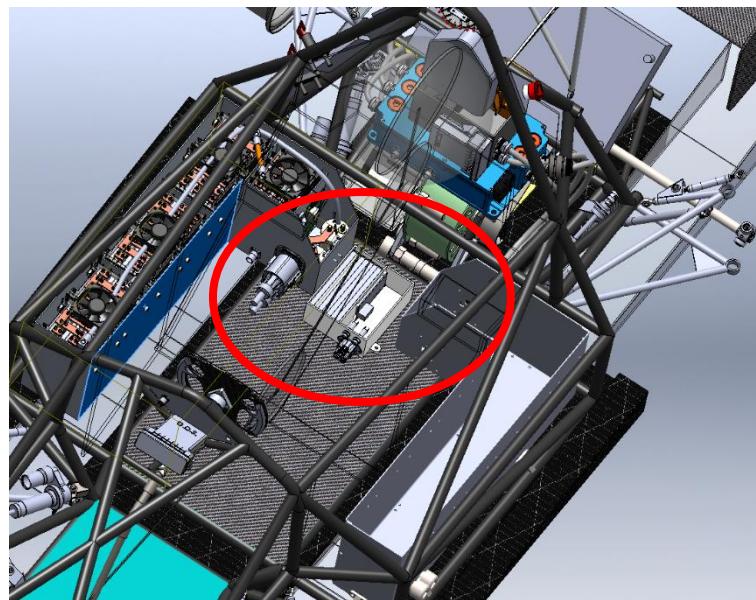
7.1.1 Description

7 cells will be monitored by the BMS that we made ourselves. The BMS is capable of opening a relay to disconnect the pack. The BMS will monitor cells for minimum voltage of 2.75v and a maximum of 4.2. Our BMS will take actions to bypass the affected cell(s) of higher voltage and shutdown the GLVS system if necessary. The BMS also reacts to temperature problems at 60°C. The BMS can also measure current and trigger the safety system. There is a wire going between the BMS PCB and the Battery pack.

7.1.2 Wiring, cables,



7.1.3 Position in car



7.2 LV part 2

N/A

8 Overall Grounding Concept

8.1 Description of the Grounding Concept

The chassis is made from conductive chrome-moly and will provide low resistance paths through the frame. The steering wheel will have a ground wire thru the disconnect to insure low resistance. Firewalls will be mounted to the car with tabs welded to the frame. The tabs will have paint removed to make a solid electrical connection to the firewall

8.2 Grounding Measurements

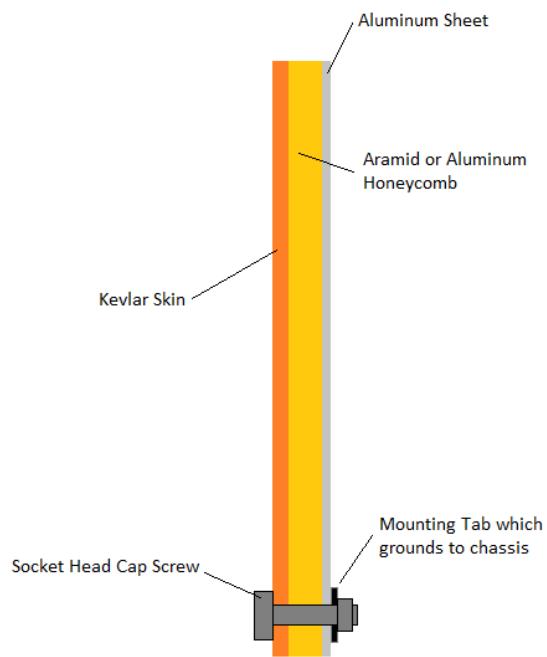
GLVMP location. GLV battery lead comes out and lands on a frame bolt.

9 Firewall(s)

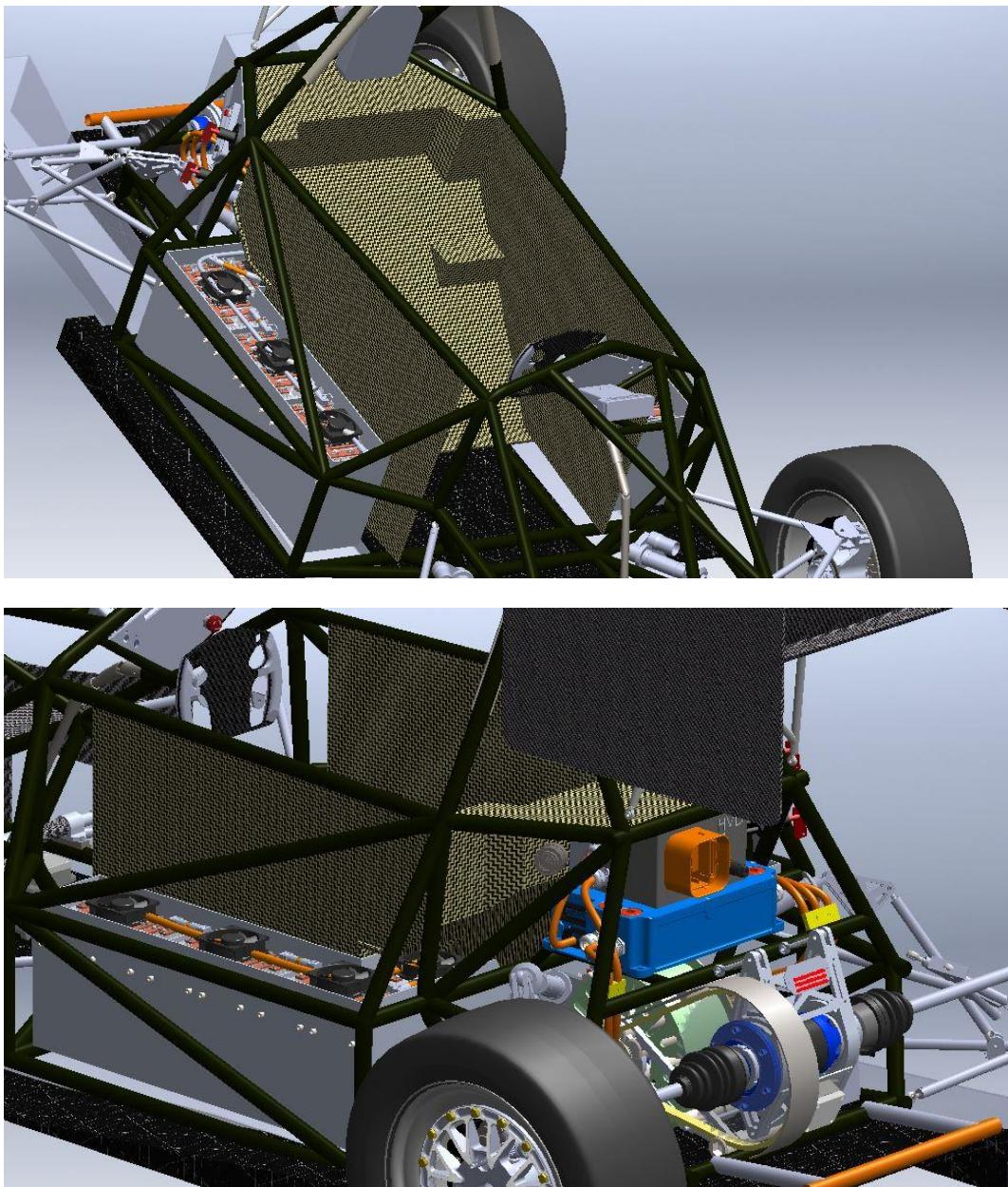
9.1 Firewall 1

9.1.1 Description/materials

The Tractive System Firewall serves purpose of not only protecting the driver from potential hazard, but also supporting the driver in the car. Because the seat is molded foam and not rigidly mounted to the chassis, the firewall must be capable of supporting the driver's torso and seat throughout the dynamic events. The proposed firewall is a composite structure consisting of fire retardant materials. This allows us to make a stiff panel that is also fire resistant. The concept, attached below, consists of an aluminum skin (**0.5 mm thick**) facing the HV components (per the required firewall rules) and fire resistant core materials, followed by a Kevlar skin. A thick kevlar skin will be sufficient in preventing piercing of the firewall, and the honeycomb structure will give the panel enough stiffness to support the loads required. The firewall is grounded to the chassis via the mounting system used to secure it to the chassis. This consists of Socket head cap screws through the firewall and tabs welded directly to the chassis. In the event that this grounding method is not sufficient, a properly sized grounding strap will be added to the aluminum skin to which travels to the chassis.



9.1.2 Position in car



9.2 Firewall 2

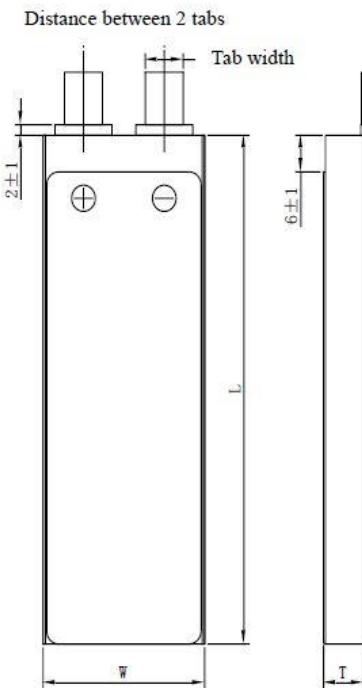
We only have one firewall in the car.

10 Appendix

10.1 HV Battery Cell Datasheet

3. 产品规格 SPECIFICATION

单颗电池规格 Specifications of single cell



◆ 标称容量 Typical Capacity①	7.05Ah
◆ 标称电压 Nominal Voltage	3.7V
◆ 充电条件 Charge Condition	最大持续电流充电 Max. Continuous charge Current
	峰值充电 Peak Charge current
	电压 Voltage
◆ 放电条件 Discharge Condition	Max Continuous Discharge Current
	Peak Discharge Current
	Cut-off Voltage
◆ 交流内阻 AC Impedance(mOHM)	<2.0
◆ 循环寿命【充电:1.0C,放电:20C】 Cycle Life 【CHA:1.0C,DCH:20C】	>100cycles
◆ 使用温度 Operating Temp.	充电 Charge
	放电 Discharge
◆ 电芯尺寸 Cell Dimensions	厚度 Thickness(T)
	宽度 Width(W)
	长度 Length(L)
◆ 极耳尺寸 Dimensions of Cell tabs	极耳间距 Distance between 2 tabs
	极耳宽度 Tab Width
	极耳厚度 Tab Thickness
◆ 重量 Weight(g)	
①标称容量: 0.5CmA,4.2V~3.0V@23°C±2°C Typical Capacity:0.5CmA,4.2V~3.0V@23°C±2°C	

<http://www.melasta.com/product.asp?lie=Lithium%20polymer%20battery>

10.2 AIR

Product Facts

- Designed to be the smallest, lightest weight, lowest cost sealed contactor in the industry with its current rating (500+A carry, 2000A interrupt at 320VDC).
- Built-in coil economizer – only 1.7W hold power @ 12VDC and it limits back EMF to 0V. Models requiring external economizer also available.
- Optional auxiliary contact for easy monitoring of power contact position.
- Hermetically sealed – intrinsically safe, operates in explosive/harsh environments with no oxidation or contamination of coils or contacts, including long periods of non-operation.
- Versatile coil/power connections.
- CE marked for EC applications.
- AIAG QS9000 designed, built and approved



EV200 Series Contactor
(CZONKA® Relay, Type III)

Typical EV200 applications include battery switching and back-up, DC voltage power control, circuit protection and safety.

For factory-direct application assistance, dial 800-253-4560, ext. 2055, or 805-220-2055.

Performance Data

Parameter	Units	Value for EV200 Series
Contact Arrangement, power contacts		1 Form X (SPST-NO-DM)
Rated Operating Voltage	VDC	12 - 900
Continuous (Carry) Current, Typical	A	500 @ 85°C, 400 mcm conductors <i>Consult Factory for required conductors for higher (500+A) currents</i>
Make/Break Current at Various Voltages ^b	A	See next page
Break Current at 320VDC ^b	A	2,000, 1 cycle ^a
Contact Resistance, Typ. (@200A)	mohms	0.2
Load Life	Cycles	See next page
Mechanical Life	Cycles	1 million
Contact Arrangement, auxiliary contacts		1 Form A (SPST-NO)
Aux. Contact Current, Max.	A	2A @ 30VDC / 3A @ 125VAC
Aux. Contact Current, Min.	mA	100mA @ 8V
Aux. Contact Resistance, Max.	ohms	0.417 @ 30VDC / .150 @ 125VAC
Operate Time @ 25°C		
Close (includes bounce), Typ.	ms	15
Bounce (after close only), Max.	ms	7
Release (includes arcing), Max @ 2000A	ms	12
Dielectric Withstanding Voltage	Vrms	2,200 @ sea level (leakage <1mA)
Insulation Resistance @ 500VDC	megohms	100 ^a
Shock, 11ms 1/2 sine, peak, operating	G	20
Vibration, sine, 80-2000Hz., peak	G	20
Operating Ambient Temperature	°C	-40 to +85
Weight, Nominal	lb.(kg)	.95 (.43)

Coil Operating Voltage (valid over temperature range)

Voltage (will operate)	9-36VDC	32-95VDC	48-95VDC
Voltage (Max.)	36VDC	95VDC	95VDC
Pickup (close) Voltage Max.	9VDC	32VDC	48VDC
Hold Voltage (Min.)	7.5VDC	22VDC	34VDC
Dropout (open) Voltage (Min.)	6VDC	18VDC	27VDC
Inrush Current (Max.)	3.8A	1.3A	0.7A
Holding Current (Avg.)	0.13A@12V, 0.07A@24V	0.03A@48V	0.02A@72V
Inrush Time (Max.)	130ms	130ms	130ms

Part Numbering System

Typical Part Number	EV200	A	A	A	N	A
Series:						
EV200 = 500+ Amp, 12-900VDC Contactor						
Contact Form:						
A = Normally Open						
H = Normally Open with Aux. Contacts						
Coil Voltage:						
A = 9-36VDC (1 = requires external coil economizer)						
D = 32-95VDC (2 = requires external coil economizer)						
J = 48-95VDC (3 = requires external coil economizer)						
R = 28VDC with Mechanical Economizer						
Coil Wire Length:						
A = 15.3 in (390 mm)						
B = 6.0 in (152 mm)						
Coil Terminal Connector:						
N = None						

<http://www.te.com/catalog/pn/en/1618002-7>

10.3 Maintenance Plugs

RAPID LOCK Quick Connect/Disconnect Bus Bar Connectors

- Replacement for threaded studs
- No loose nuts = no fretting/heat rise
- Quick connect/disconnect
- Safety locking feature
- Currents from 50A to 250A
- Wire sizes from 2.5 to 95mm²
- Color coding available
- Straight and right angle versions

Pin Connectors Swage

Type	Type	Size	Current Rating	Part No
Pin Contact	Swage	#8	50A	6648221-1
Pin Contact	Swage	#4	120A	6648222-1*
Pin Contact	Swage	#2	150A	6648223-1
Pin Contact	Swage	12mm	250A	1857523-3

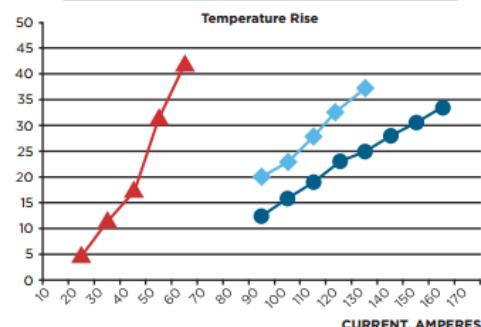
Pin Connectors Screw and Washer

Type	Type	Size	Current Rating	Part No
Pin Contact	Screw & Washer	2085957-1*	#4	120A
Pin Contact	Screw & Washer	6648226-1	#2	150A

Insulation Boots

Part No	Size	Color
1651003-1	#4 #8	Black
1651003-2	#4 #8	Red
1651003-3	#4 #8	Grey
1651003-4	#4 #8	Blue
1766600-1	#2	Black
1766600-2	#2	Red
1766600-3	#2	Grey
1766600-4	#2	Blue

● 2 - #2 wire ● 4 - #4 wire ● 8 - #12 wire



Socket Connectors - Straight

Type	Size	Wire Size	Current Rating	Color	Part No
Straight housing	#8			Black	1643279-1
Straight housing	#8			Red	1643279-2
Straight housing	#8			Blue	1643279-3
Straight receptacle contact	#8	#8	50A		6648317-1
Straight housing	#4			Black	1651766-1
Straight receptacle contact	#4	#4	120A		6648434-1

Socket Connectors - Right Angle

Type	Part No	Size	Wire Size	Current Rating	Color
Right Angle Socket	6648228-1	#8	#8	50A	Black
Right Angle Socket	6648228-2	#8	#8	50A	Red
Right Angle Socket	6648237-1	#8	#12		Black
Right Angle Socket	6648235-1	#4	#4	120A	Black
Right Angle Socket	6648235-2	#4	#4	120A	Red
Right Angle Socket	6648239-1	#4	#6		Black
Right Angle Socket	6648239-2	#4	#6		Red
Right Angle Socket	6648236-1	#4	#8		Black
Right Angle Socket	6648236-2	#4	#8		Red

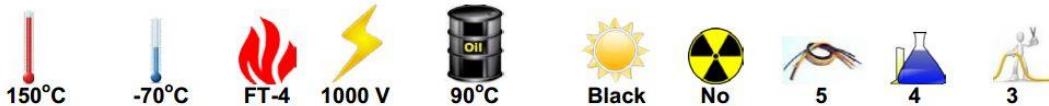
*Part numbers listed are examples of some available samples, please visit website for additional and mating part numbers



More info at :

<http://www.te.com/catalog/bin/TE.Connect?C=24079&M=PPROP&P=&BML=10576,17560,17685,17694&LG=1&PG=1&IDS=471845,471847,471618,471851,471619,471623,434075,434076,471634,434073,471631,434071,471620,471621,471622,471624,434074,434059,434061,434072&N=5>

10.4 HV cable



Ampacity 150°C rated single-insulated conductor in free air at 40°C ambient air temperature.

Product Number	Standard Conductor Bare Copper	Nom. Dia Cond. in. mm.	Nom. Dia. Primary insulation in. mm.	Nom. Dia. Shield in. mm.	Nom. Dia. Outside in. mm.	Shield Coverage	Min. Static Bend Radius	Finished Weight (lbs/mft)	Ampa -city
EXRAD-XLX10X	10 (105/30)	.112 2.84	.162 4.11	.184 4.67	.234 5.94	95%	30mm	59.0	80
EXRAD-XLX8X	8 (133/29)	.166 4.22	.236 5.99	.254 6.45	.304 7.72	95%	39mm	92.0	106
EXRAD-XLX6X	6 (133/27)	.195 4.95	.265 6.73	.283 7.19	.333 8.46	95%	42mm	126.0	155
EXRAD-XLX4X	4 (133/25)	.242 6.15	.312 7.92	.330 8.37	.390 9.91	95%	50mm	187.0	190
EXRAD-XLX2X	2 (665/30)	.318 8.08	.388 9.86	.410 10.41	.490 12.45	95%	60mm	295.0	255
EXRAD-XLX1X	1 (779/30)	.346 8.79	.446 11.33	.469 11.91	.529 13.44	95%	95mm	335.0	293
EXRAD-XLX1/0X	1/0 (1007/30)	.390 9.91	.500 12.70	.528 13.41	.588 14.91	95%	105mm	412.0	339
EXRAD-XLX2/0X	2/0 (1254/30)	.438 11.13	.558 14.17	.586 14.83	.666 16.92	95%	115mm	534.0	390
EXRAD-XLX3/0X	3/0 (1615/30)	.475 12.07	.595 15.11	.623 15.82	.703 17.86	95%	125mm	620.0	451
EXRAD-XLX4/0X	4/0 (2107/30)	.602 15.29	.722 18.34	.750 19.05	.830 21.08	95%	150mm	876.0	529



Manufacturing Locations:
Colchester, Vermont
El Paso, TX
Leeds, Massachusetts

More information at

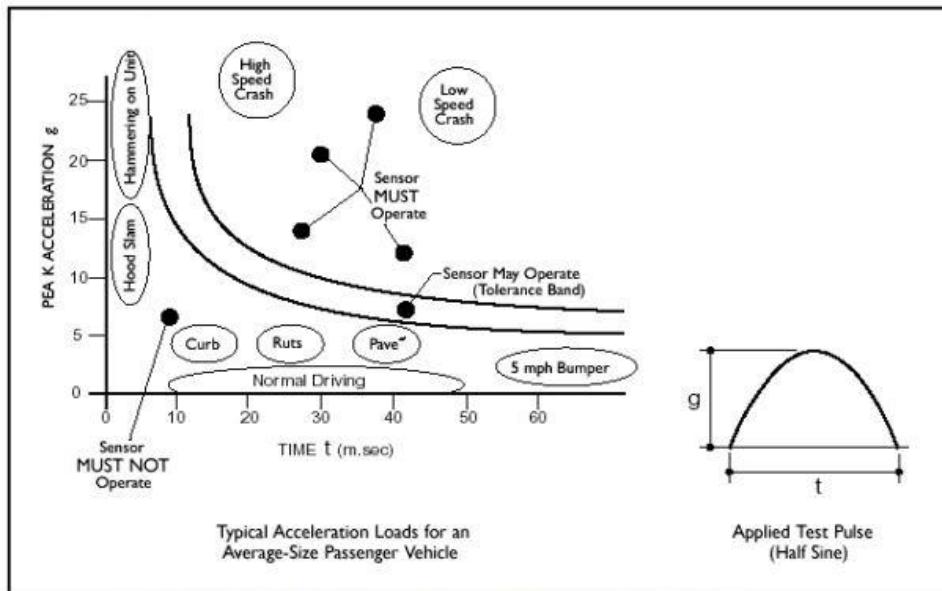
http://www.champcable.com/product_pdfs/14_SAE_XLE_Shielded_High_Voltage.pdf

10.5 Crash Sensor

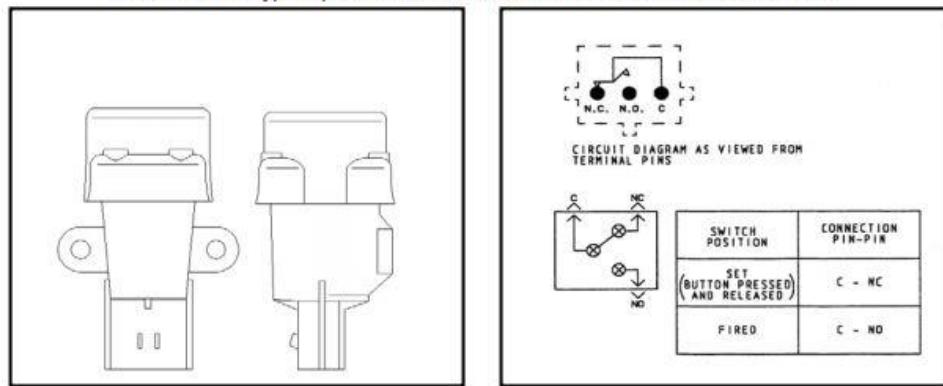
Features:

- Unique magnet restrained mass inertia mechanism
- Rated at 10 Amps electrical load
- Manually resettable

www.sensata.com Printed in U.S.A., December 2010



Above are the typical performance characteristics of resettable crash sensors



<http://www.sensata.com/download/resettable-crash.pdf>

10.6 IMD

Referred from 2.1.1.

Technical data

Insulation coordination acc. to IEC 60664-1

Protective separation (reinforced insulation)	between (L+/L-) – (Kl. 31, Kl. 15, E, KE, M _{Hs} , M _{Ls} , OK _{Hs})
Voltage test	AC 3500 V/1 min

Supply/IT system being monitored

Supply voltage U_S	DC 10...36 V
Max. operating current I_S	150 mA
Max. current I_k	2 A
	6 A/2 ms inrush current
HV voltage range (L+/L-) U_n	AC 0...1000 V (peak value) 0...660 V rms (10 Hz...1 kHz) DC 0...1000 V
Power consumption	< 2 W

Response values

Response value hysteresis (DCP)	25 %
Response value R_{an}	100 kΩ...1 MΩ
Undervoltage detection	0...500 V

Measuring range

Measuring range	0...10 MΩ
Undervoltage detection	0...500 V default setting: 0 V (inactive)
Relative uncertainty	
SST (≤ 2 s)	good > 2* R_{an} ; bad < 0.5* R_{an}
Relative uncertainty DCP (default setting 100 kΩ)	0...85 kΩ ▶ ± 20 kΩ 100 kΩ...10 MΩ ▶ ± 15%
Relative uncertainty output M (fundamental frequency)	±5 % at each frequency (10 Hz; 20 Hz; 30 Hz; 40 Hz; 50 Hz)
Relative uncertainty undervoltage detection	$U_n \geq 100$ V ▶ ±10 %; at $U_n \geq 300$ V ▶ ±5 %
Relative uncertainty (SST)	"Good condition" $\geq 2^* R_{an}$ "Bad condition" $\leq 0.5^* R_{an}$

Complete data sheet located at: http://www.bender-de.com/fileadmin/products/doc/IR155-32xx-V004_DB_en.pdf

10.7 HV Fuse

POWR-GARD® Fuse Datasheet



Expertise Applied | Answers Delivered

CLASS T – JLLN / JLLS SERIES FUSES

300/600 VAC • Fast-Acting • 1-1200 A





Description

JLLN / JLLS fuses are less than 1/3 the size of comparable Class R fuses and are typically used for short circuit protection of drives and surge sensitive components. When rated in accordance with the NEC®, JLLN / JLLS fuses provide fast-acting overload and short circuit protection for non-inductive circuits and equipment.

Features/Benefits

- Extremely current-limiting
- Compact design
- 200 kA Interrupting Rating

Applications

- Variable speed drive protection
- Compact mains switches

Specifications

Voltage Ratings

AC:	300 V (JLLN)
600 V (JLLS)	
DC:	160 V (JLLN 1 – 60 A)
125 V (JLLN 70 – 1200 A)	
300 V (JLLS)	

Interrupting Ratings

AC:	200 kA rms symmetrical
DC:	20 kA (JLLN 35-1200 A only)

Ampere Range

1 – 1200 A

Approvals

- AC: Standard 248-15, Class T
- UL Listed (File: E81895);
- JLLN (1 – 1200 A)
- JLLS (1 – 800 A)
- UL Recognized (File: E71611)
- JLLN PCB Mount (35 – 60 A)
- JLLS (900 – 1200 A)
- CSA Certified (File: LR29862)
- JLLN/JLLS (1 – 600 A)
- DC: UL Listed (File: E81895);
- JLLN (35 – 1200 A)
- Littelfuse self-certified
- JLLN (1 – 30 A)
- JLLS (1 – 1200 A)

Environmental

RoHS Compliant

(Note: Not all amperages are RoHS compliant.
Contact the factory for additional details.)

Ordering Information

AMPERE RATINGS					
1	25	70	175	450	1100
2	30	80	200	500	1200
3	35	90	225	600	
6	40	100	250	700	
10	45	110	300	800	
15	50	125	350	900*	
20	60	150	400	1000	
*JLLS only					

Part Numbering System

JLLN xxxx V –
 Series –
 Amperage –
 Package Quantity –
 T = 10 (1-60 A)
 V = 5 (70-100 A)
 X = 1 (110-1200 A)

Options

- Blank = Standard Non-Plated
- XP = Premium Plated
- XL = Leaded*
- XV = Vertical Mount*
- XLS = Solder Lead*

*Option is available for JLLN 35-60 A only. Premium plating is standard

Web Resources

Download TC Curves, CAD drawings and other technical information: littelfuse.com/jlln
littelfuse.com/jlls

Recommended Fuse Holders

LFT30 Series
LFT60 Series
LSCR Series for 700-800 A

Dimensions

Please refer to the Class T dimensions on page 4

10.8 Motor Controller



RINEHART MOTION SYSTEMS LLC

TM 7929 SW Burns Way, Suite B, Wilsonville, OR 97070 503.344.5085

AC Motor Controller for Electric and Hybrid Vehicles

Product Summary

The Rinehart Motion Systems LLC (RMS) PM Family of AC Motor Controllers are designed for on- and off-road Electric (EV) or Hybrid Electric (HEV) applications. The motor controller converts the DC power from the vehicle ESS (Energy Storage System / Battery) to the 3-phase AC required by the motor. These Traction drives are fabricated using a patented high heat flux thermal design approach that dramatically reduces the size and weight of the finished drive, and improves its life in the automotive environment. With extensive experience in automotive and military vehicle traction and power electronics applications, RMS has achieved a major breakthrough in integrating Motor Control into a vehicle.



RMS offers several different models within the PM Family of motor controllers to suit the DC bus voltage and motor current requirements of your specific vehicle. The PM Family has been designed to operate with many types of motors, including Induction Motors (IM) and Permanent Magnet motors (PMSM or IPM). Contact RMS for the latest list of motors supported by our controllers. The Drive can also be tuned to your new motor - contact the factory for more information.

The primary difference between models in the PM Family is the rated voltage and current (ultimate power output):

Controller Model	PM100DX	PM100DZ	PM100DXR *	PM150DX	PM150DZ
Maximum DC Voltage – operating	360 V	720 V	400 V	360 V	720 V
Maximum DC Voltage – non-operating	500 V	900 V	500 V	500 V	900 V
Motor Current Continuous	300 Arms	150 Arms	300 Arms	450 Arms	225 Arms
Motor Current Peak **	350 Arms	200 Arms	450 Arms	450 Arms	300 Arms
DC Bus Capacitance	440 µF	280 µF	440 µF	880 µF	560 µF
Size	See drawing				
Weight	7.5 kg	7.5 kg	7.5 kg	10.7 kg	10.7 kg
Minimum Conductor Size		4 AWG		2 AWG	4 AWG***
Maximum Conductor Size		1 AWG		3/0 AWG	1 AWG
Minimum Cable O.D.		9.0 mm		11.0 mm	
Maximum Cable O.D.		16.5 mm		21.0 mm	

* The PM100DXR is only available for special applications (i.e. racing), use must be approved by RMS.

** Peak current is defined as a maximum of 30 seconds.

*** Depending on cable, it may be necessary to add additional sleeve to cable to meet the minimum Cable O.D. of the cable gland.

http://www.rinehartmotion.com/files/Download/PM_Datasheet_01052012.pdf

10.9 Motor

EMRAX 228 Technical Data Table

Technical data	Type			EMRAX 228 High Voltage			EMRAX 228 Medium Voltage			EMRAX 228 Low Voltage								
	AC	LC	CC	AC	LC	CC	AC	LC	CC	AC	LC	CC						
Air cooling = AC																		
Liquid cooling = LC																		
Combined cooling = Air + Liquid cooling = CC																		
Ingress protection	IP21	IP65	IP21	IP21	IP65	IP21	IP21	IP65	IP21	IP21	IP65	IP21						
Cooling medium specification (Air Flow = AF; Water Flow = WF - if inlet water temperature and/or ambient temperature are lower, then continuous power is higher)	AF speed 25 m/s; 25°C	inlet WF 8 l/min - 40°C; ambient air 25°C	inlet WF 8 l/min - 40°C; ambient air 25°C	AF speed 25 m/s; 25°C	inlet WF 8 l/min - 40°C; ambient air 25°C	inlet WF 8 l/min - 40°C; ambient air 25°C	AF speed 25 m/s; 25°C	inlet WF 8 l/min - 40°C; ambient air 25°C	inlet WF 8 l/min - 40°C; ambient air 25°C	AF speed 25 m/s; 25°C	inlet WF 8 l/min - 40°C; ambient air 25°C	inlet WF 8 l/min - 40°C; ambient air 25°C						
Weight [kg]	12,0	12,3	12,3	12,0	12,3	12,3	12,0	12,3	12,3	12,0	12,3	12,3						
Diameter ø / width [mm]							228 / 86											
Battery voltage range [Vdc]	50 – 600 (*700 – to get 6500 RPMp)			50 – 450 (*540 – to get 6500 RPMp)			24 – 150 (*180 – to get 6500 RPMp)											
Peak motor power (few min at cold start / few seconds at hot start) [kW]	100																	
Continuous motor power (depends on the motor RPM 3000 - 5000) [kW]	28 - 42	28 - 42	35 - 55	28 - 42	28 - 42	35 - 55	28 - 42	28 - 42	35 - 55									
Maximal rotation speed [RPM]	5500 (*6500 RPM peak)																	
Maximal motor current (for 2 min if cooled as described in Manual for EMRAX) [Arms]	240			340			900											
Continuous motor current [Arms]	115			160			450											
Maximal motor torque (for a few seconds) [Nm]	240																	
Continuous motor torque [Nm]	125																	
Torque / motor current [Nm/1Aph rms]	1,1			0,75			0,27											
Maximal temperature of the copper windings in the stator and also max. temp. of the magnets [°C]	120																	
Motor efficiency [%]	93 – 98																	
Internal phase resistance at 25 °C [mΩ]	18			8,0			1,12											
Input phase wire cross-section [mm²]	10,2			15,2			38											
Induction in Ld/Lq [µH]	175/180			75/80			10,6/11,2											
Controller / motor signal	sine wave																	
Specific idle speed (no load RPM) [RPM/1Vdc]	9,8			14			40											
Specific load speed (depends on the controller settings) [RPM/1Vdc]	8 – 9,8			11 – 14			34 – 40											
Magnetic field weakening (for higher RPM at low torque) [%]	up to 100																	
Magnetic flux – axial [Vs]	0,0542			0,0355			0,0131											
Temperature sensor in the motor	kty 81/210																	
Number of pole pairs	10																	
Rotor inertia (mass dia=175mm, m=5,5kg) [kg*cm²]	421																	
Bearings SKF – FAG	R/R 6206/6206 or R/AR 6206/7206 or AR/AR 7206/7206 (»O« orientation)																	

*For a few seconds.

Maximal battery voltage is 700 Vdc (EMRAX 228 High Voltage). Maximal RPM must not be exceeded.

It is possible to weaken the magnetic field (up to 100%) to get higher RPM at existing battery voltage. Maximal RPM must not be exceeded.

These data are valid for the motors, which were sold after January 2014.

EMRAX motors that had been made before May 2012 have 30% lower power/torque and RPM than new generation of EMRAX motors.

10.10 Low Voltage Battery

Polymer Lithium-ion battery Product Specification	Doc. No.	Q/WMDCJ06011-2007
	Edition No.	1.0
	Sheet	1/6

1、Scope:

This product specification describes Wanma polymer lithium-ion battery. Please use the test methods that recommend in this specification. If you have any opinions or advices about the test items and methods, please contact us. Please read the cautions recommended in the specifications first, take the credibility measure of the cell's usage.

If the cells should be used at the environment that not preferred in this document, please connect with our first and get our authorization.

It is claimed that we should have no responsibility with the contingency and loss due to the cells' wrong usage (not preferred in the product specification).

2、Product Type, Model and Dimension:

2.1 Type: Polymer lithium-ion battery

2.2 Model: PL-9759156-5C(Cell or adding Cu tabs)

2.3 Cell Dimension with Tolerance +/- 0.5mm (Thickness×Width×Length, mm³): 9.8×59.5×157.0

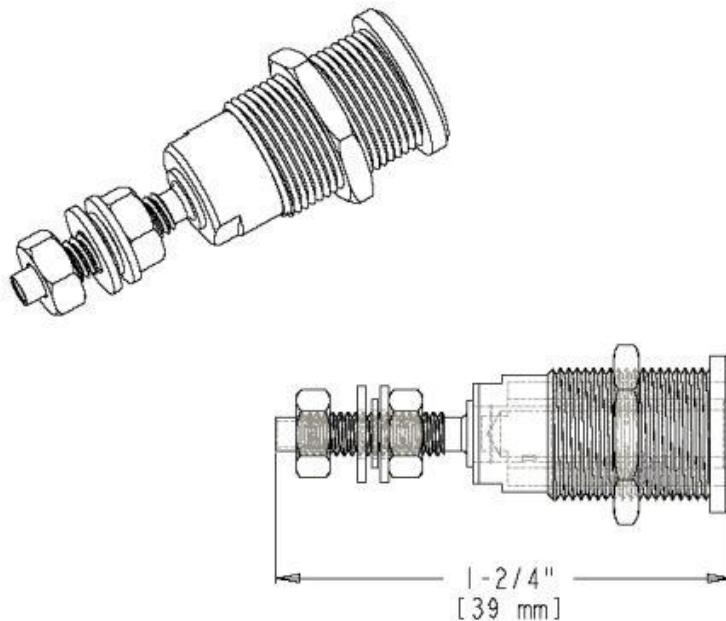
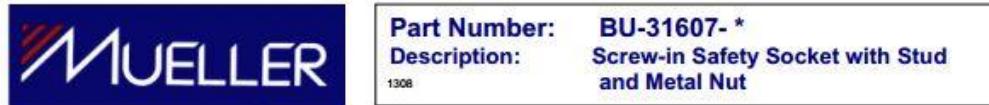
Pack Dimension(Max, Thickness×Width×Length, mm³): _____

3、Specification:

Item	Specifications		Remark
Nominal Capacity	10100_mAh		0.2C ₅ A discharge
Typical Capacity	10000_mAh		0.2C ₅ A discharge
Nominal Voltage	3.7V		Average Voltage at 0.2C ₅ A discharge
Charge Current	Standard: 0.2 C ₅ A; Max: 1C ₅ A		Working temperature: 0~45°C
Charge cut-off Voltage	4.200±0.05V		
Discharge Current	Continuously:5C ₅ A; Max: 10C ₅ A		Working temperature: 0~60°C
Discharge cut-off Voltage	2.75V		
Cell Voltage	3.7~3.9V		When leave factory
Impedance	≤15mΩ		AC 1KHz after 50% charge
Weight	Approx210g		
Storage temperature	≤1month	-20~45°C	Best 20±5°C for long-time storage
	≤3month	0~30°C	
	≤6month	20±5°C	
Storage humidity	65±20% RH		

<http://www.batteryspace.com/prod-specs/3.7V10Ah.pdf>

10.11 TSMP



- Screw-in Safety Socket with Stud and Metal Nut
- Material: Hardware: nickel-plated brass; Insulator: ABS-nylon composite
- Length: 1.53" (39 mm)
- *Std. Colors: -0 Black, -2 Red
- Rating: 600Volts, category III, 1000Volts, category II, 45 Amps, IEC 1010 Compliant
- RoHS Compliant

Mueller Electric Company
1625 E. 31st Street
Cleveland, Ohio 44114

ISO 9001:2000
Over 95 Years Of Innovation
www.muellerelectric.com

TEL 800-955-2629
TEL 216-771-5225
FAX 216-771-3068

Full datasheet: <http://muellerelectric.com/wp-content/uploads/DS-BU-31607-0.pdf>

10.12 TSMP-Resistors



High Power Resistor

Type SBC (Square Ceramic) Series

Key Features

- Up to 17 Watts
- Fusible Styles
- Vertical or Axial
- Non Flammable
- Special Solvent Resistance
- Customer Specials Invited
- Widely Available from Distribution



This range of Power Wirewound Resistors are wound on continuous glass fibre elements or have a ceramic core depending on resistance value. The element is housed in a ceramic case and sealed with an inorganic silica filler. Their construction gives a resistor with high insulation resistance and low surface temperature, capable of withstanding high overload currents. These resistors are ideally suited to a variety of applications within industrial and commercial environments, where performance and reliability are of prime importance. Applications include fan force ovens, cooker hoods, power supplies and triac based speed controls. Custom Design Variants in value and style are welcomed.

Characteristics - Electrical

Resistance Values:	Series E24 5% E12 10% (see tables for value limits per style)
Resistance Tolerance:	$\pm 5\%$ $\pm 10\%$
Maximum Continuous Voltage:	$\sqrt{P} \times R$
Load Life:	$\Delta R <= 3\%$ 1000 hours at 70°C
Power Rating:	See Surface Temperature Curve (below)

Characteristics - Environmental and Mechanical

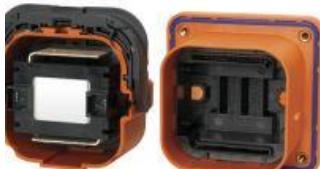
Temperature Coefficient of Resistance:	200ppm/°C (400ppm/°C below 18R)
Resistance to Solder Heat:	$\Delta R < 0.2\%$ (350°C for 2.5 seconds)
Voltage Coefficient of Resistance:	Negligible
Operating Temperature Range:	-55°C to +350°C
Load Stability:	$\Delta R < 5\%$ (full load at 70°C for 1000 hours)
Long Term Damp Heat:	$\Delta R < 0.2\%$ (21 days at 40°C for 93% humidity)
Shelf Life:	$\Delta R < 1.0\%$ (per 12 months)
Insulation Resistance:	> 10000M
Dielectric Strength:	2000V RMS
Lead Material:	Steel - Solder coat
Marking:	Legend mark, Manufacturer name, type, ohmic value and tolerance.

Full datasheet:

<http://www.te.com/commerce/DocumentDelivery/DDEController?Action=srchrv&DocNm=1773278&DocType=DS&DocLang=English>

10.13 HVD

AMP+ Manual Service Disconnect Fused Version



KEY FEATURES

- Finger proof, touch safe
- Finger actuated - 2 stage lever assist latching
- No tool required to unmate
- 2x integrated internal HVIL
- Scalable design
- Current rating determined by fuse rating or shunt
- Available with integrated fuse up to 630A or with shunt
- USCAR-2, USCAR-37, IEC 60529, RoHS compliant
- Tested to 50 mating cycles
- Sealed

TE Technical Support Center

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te.com

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APPLICATIONS

- HV battery pack or remote location
- Energy storage systems (ESS)

MECHANICAL

- Latching style: Finger actuated - 2 stage lever assist
- Mating cycles: Tested to 50
- Stud: M6
- IP rating: Mated: IPx7, IP6K9k
- HVIL: 2x integrated, internal
- Unmated: IP2xb

ELECTRICAL

- Fuse rating: Up to 630A
- Voltage rating for fused version: 450 VDC
- Shunted version for higher voltages
- Operating temperature: -40 °C to 65 °C
- Storage temperature: -40 °C to 85 °C
- Current rating: Based on fuse selection

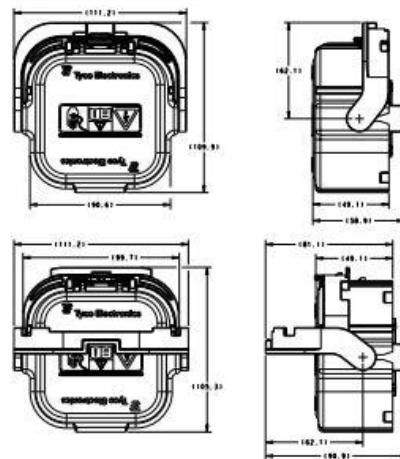
STANDARDS AND SPECIFICATIONS

- USCAR-2
- USCAR-37
- IEC 60529
- RoHS

PRODUCT OFFERING

1587987-8	Receptacle Assembly, 200A, MSD
2103172-8	Plug Assembly, 200A, MSD, Market label
1587987-9	Receptacle Assembly, 250A, MSD
2103172-9	Plug Assembly, 250A, MSD, Market label
1-1587987-1	Receptacle Assembly, 350A, MSD
1-2103172-1	Plug Assembly, 350A, MSD, Market label
1-1587987-7	Receptacle Assembly, Shunt (No fuse), MSD
1-2103172-7	Plug Assembly, Shunt (No fuse), MSD, Market label

PRODUCT DIMENSIONS



Full Datasheet: <http://www.te.com/content/dam/te/global/english/industries/hybrid-electric-mobility-solutions/amp-msd-tech-sheet.pdf>

10.14 E-Stop

SSA-EB Series Emergency Stop Buttons



Datasheet



Figure 1. SSA-EBM-xxE Series with Enclosure



Figure 2. SSA-EBP-xxE Series with Enclosure

- Push-to-stop, twist-to-release operation
- Rugged, modular design; easy assembly and installation
- Kits available for easy selection
- Choice of metal or plastic button base with or without enclosure; all kits include disc label with "Emergency Stop" legend
- Choice of normally closed (safety) or combination normally closed/normally open (non safety) contacts
- Latching design complies with ISO 13850; direct (positive) opening operation per IEC 60947-5-1

Models		Button Base Material	Contacts	Enclosure Included
SSA-EBM-02L		Metal	2 normally closed	No
SSA-EBM-11L			1 normally closed and 1 normally open	
SSA-EBM-12L			2 normally closed and 1 normally open	
SSA-EBP-02L		Plastic	2 normally closed	
SSA-EBP-11L			1 normally closed and 1 normally open	
SSA-EBP-12L			2 normally closed and 1 normally open	
SSA-EBM-02E			2 normally closed	Yes
SSA-EBM-11E			1 normally closed and 1 normally open	
SSA-EBM-12E			2 normally closed and 1 normally open	
SSA-EBP-02E			2 normally closed	
SSA-EBP-11E			1 normally closed and 1 normally open	
SSA-EBP-12E			2 normally closed and 1 normally open	

Dimensions

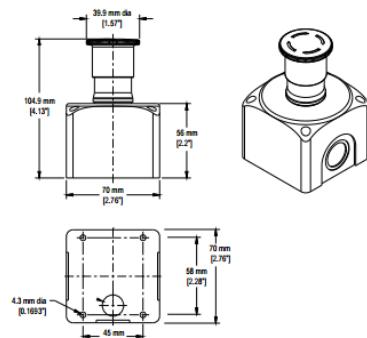


Figure 4. SSA-EBM-xxE and EBP-xxE Series E-Stop Buttons

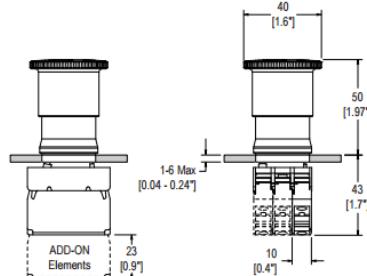


Figure 5. SSA-EBM-xxL and EBP-xxL Series E-Stop Buttons

Full Datasheet: <http://info.bannersalesforce.com/cs/groups/public/documents/literature/111880.pdf>

10.15 TSMS / HV sense wire


[Enlarge](#)

Mouser Part #: 602-6460-100-04
Manufacturer Part #: 6460 OR005
Manufacturer: Alpha Wire
Description: Multi-Paired Cables 22AWG 2C SHIELD
100ft SPOOL ORANGE

Images are for reference only
See Product Specifications

[Add to Compare List](#)
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[Specifications](#)
[My Notes](#)

Manufacturer:	Alpha Wire	<input checked="" type="checkbox"/>
Product Category:	Multi-Paired Cables	<input checked="" type="checkbox"/>
RoHS:	Details	<input checked="" type="checkbox"/>
Number of Pairs:	1	<input type="checkbox"/>
Wire Gauge - AWG:	22 AWG	<input type="checkbox"/>
Stranding:	7 x 0.0096	<input type="checkbox"/>
Shielding:	Shielded	<input type="checkbox"/>
Length:	100 ft	<input type="checkbox"/>
Voltage Rating:	300 V	<input type="checkbox"/>
Jacket Material:	Polyvinyl Chloride (PVC)	<input type="checkbox"/>
Insulation Material:	Polypropylene (PP)	<input type="checkbox"/>
Type:	Industrial Automation	<input type="checkbox"/>
Jacket Color:	Orange	<input type="checkbox"/>
Brand:	Alpha Wire	<input type="checkbox"/>
Conductor Material:	Tinned Copper	<input type="checkbox"/>

Full datasheet: <http://www.mouser.com/ProductDetail/Alpha-Wire/6460-OR005/?qs=sGAEpiMZZMv1%2f%252b2kKkGMBdDOvp5WNq%252bt9emRXpKWYqs%3d>

10.16 Hookup wire

Alpha Wire | 711 Lidgerwood Avenue, Elizabeth, NJ 07207
Tel: 1-800-52 ALPHA (25742), Web: www.alphawire.com

[Request a Sample](#)

Customer Specification**PART NO. 3050****Construction**

		Diameters (In)
1) Component 1	1 X 1 HOOKUP	
a) Conductor	24 (7/32) AWG Tinned Copper	0.024
b) Insulation	0.016" Wall, Nom. PVC	0.056+/- 0.002
(1) Print	ALPHA WIRE E163869-* RU AWM STYLES 1569 105C OR 1007 80C VW-1 300V 24 AWG --- LXXXX CSA TR-64 90C FT1 ROHS {0} * = Factory Code <i>[Note: Product may have c(UL) or CSA markings depending upon plant of manufacture.]</i>	
(2) Color(s)	WHITE, BLACK, RED, GREEN, YELLOW, BLUE, BROWN ORANGE, SLATE, VIOLET, WHITE/BLACK, WHITE/RED WHITE/GREEN, WHITE/YELLOW, WHITE/BLUE WHITE/BROWN, WHITE/ORANGE, WHITE/SLATE WHITE/VIOLET, GREEN/YELLOW, PINK	

Applicable Specifications

1) UL	AWM/STYLE 1007	80°C / 300 V _{RMS}
	AWM/STYLE 1569	105°C / 300 V _{RMS}
	VW-1	
2) CSA International	TR-64	90°C
	FT1	

Environmental

Full Datasheet: <http://www.alphawire.com/Home/Products/Wire/Hook-Up-Wire/Premium/3050?device=pdf>