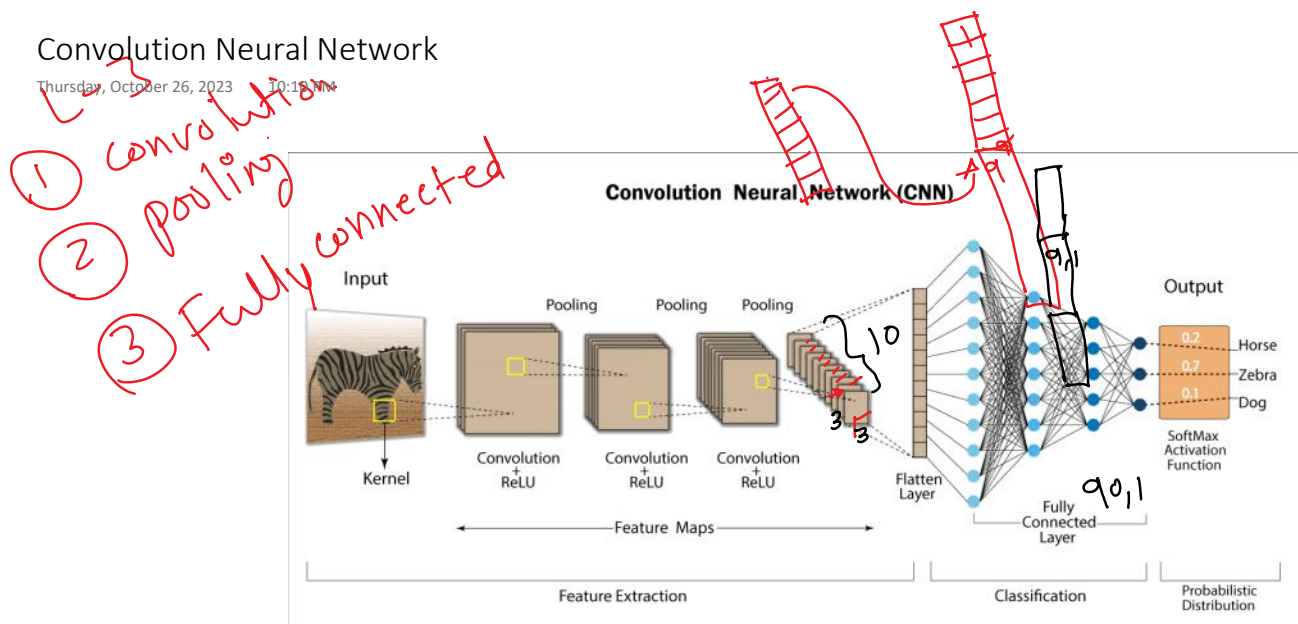


Convolution Neural Network

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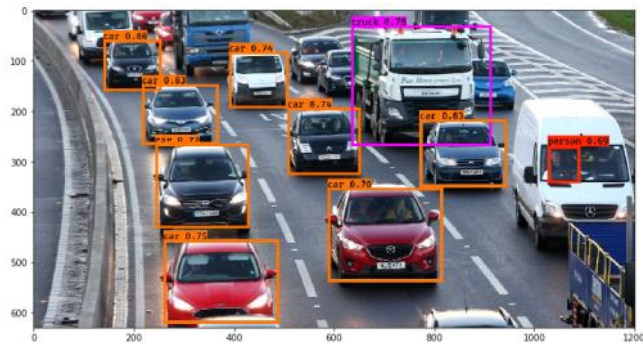


Convolution is the process involving **combination of two functions that produces the other function** as a result. In CNN's, the input image is subjected to convolution with use of filters that produces a **Feature map**.

Filters / Kernels

Filters /kernels are randomly generated vectors in the network consisting of weights and biases.

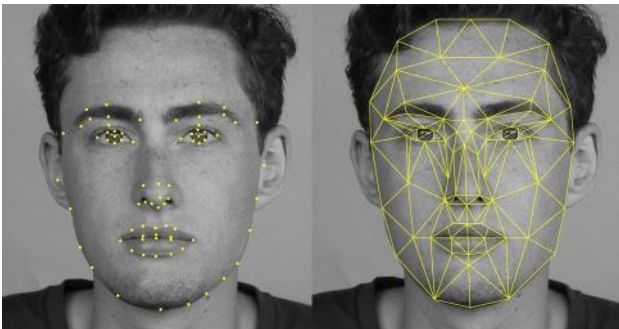
Applications of CNN



OBJECT DETECTION



SELF DRIVING CARS



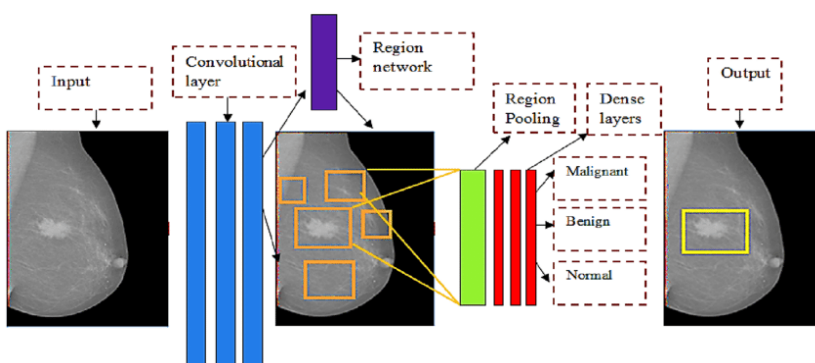
FACIAL RECOGNITION



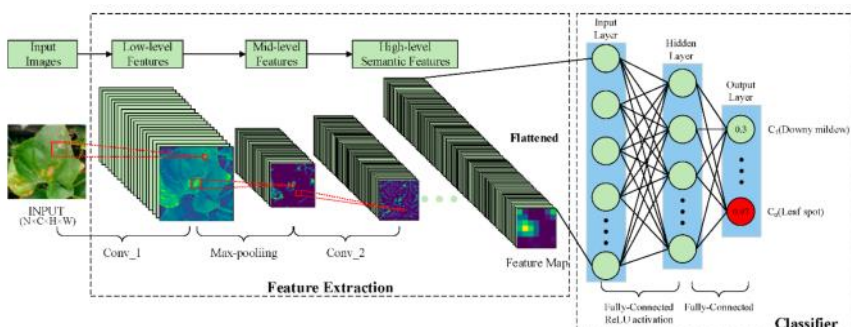
Automatic Colorization of Black and White Images



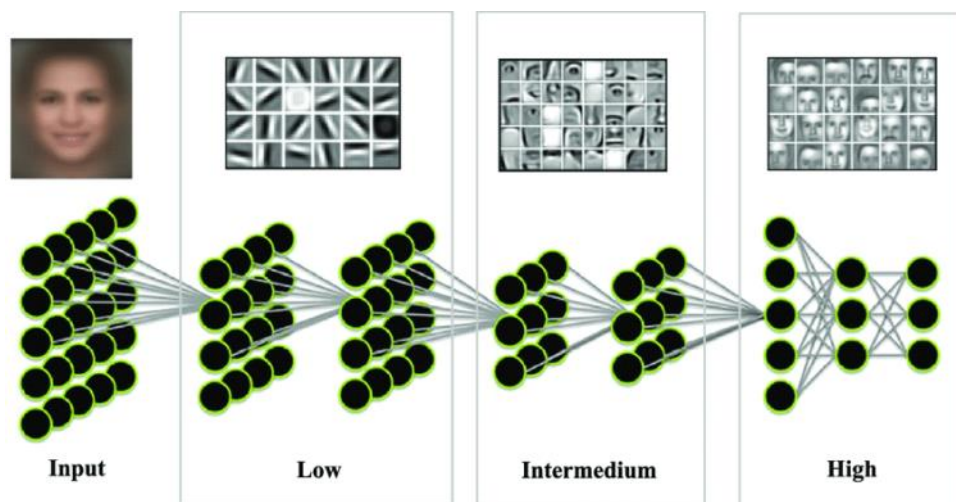
Up-scaling low-resolution images



BREAST CANCER DETECTION



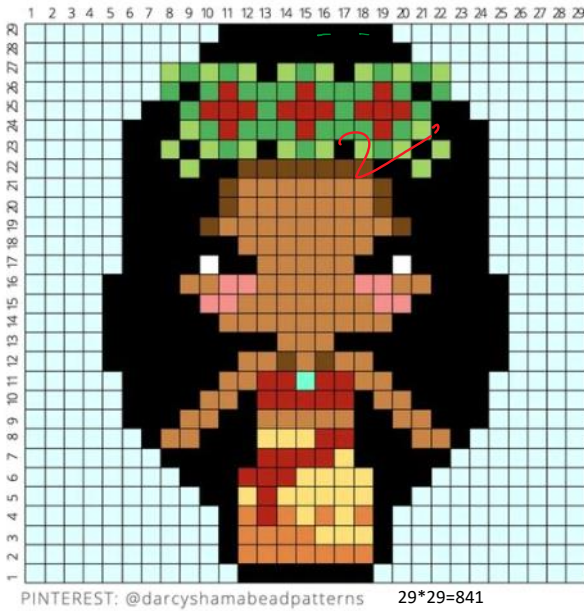
LEAF DISEASE DETCTION



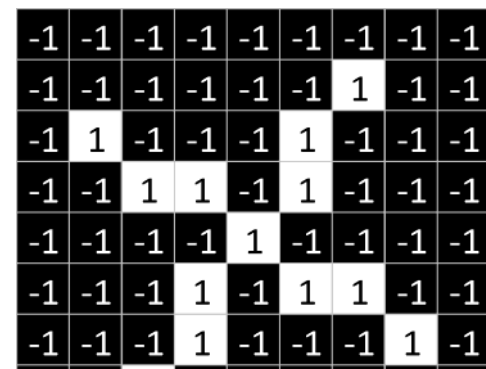
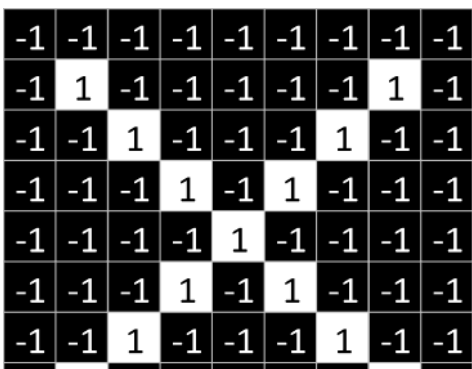
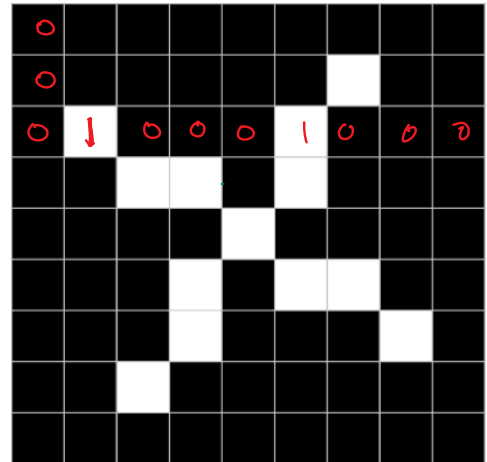
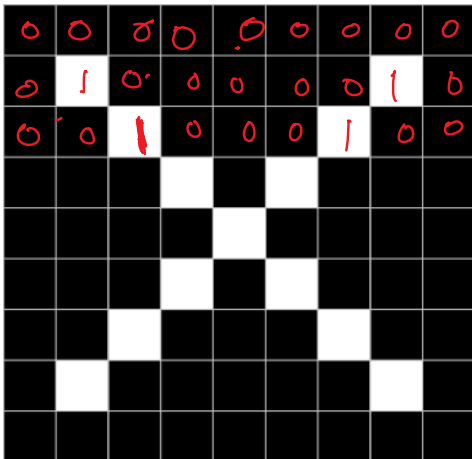
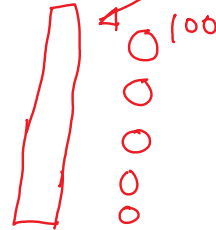
Limitations of ANN

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1. High Computation Cost
2. Overfitting
3. Loss of important info like spatial features



$$1920 \times 1080 = 20,736,000$$



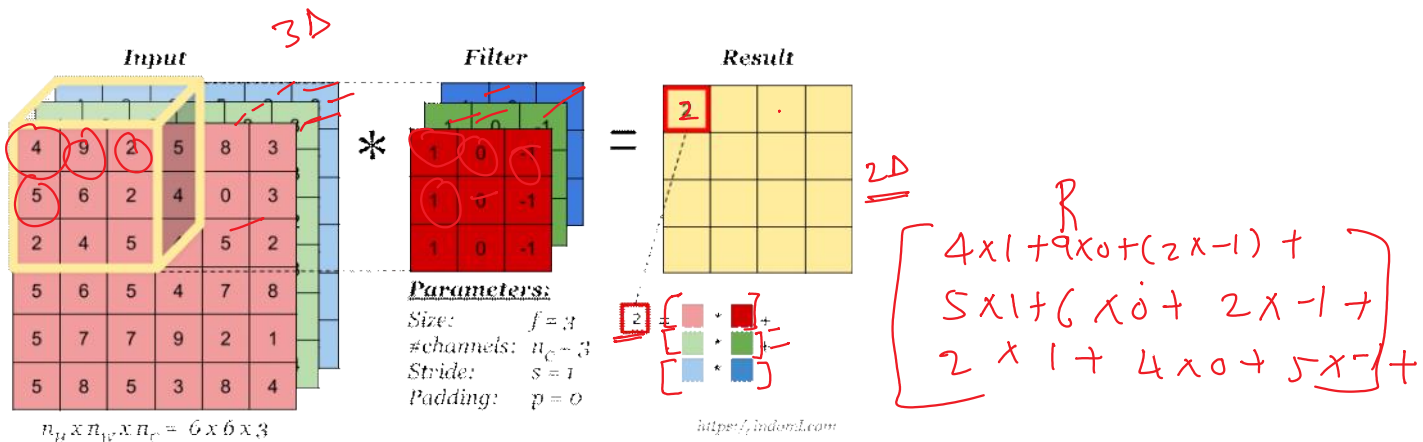
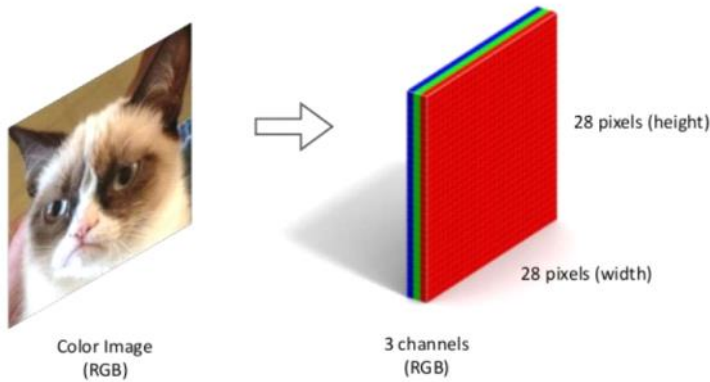
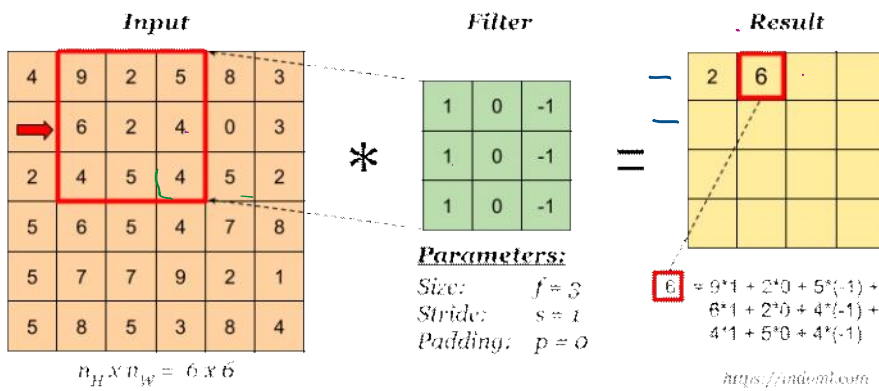
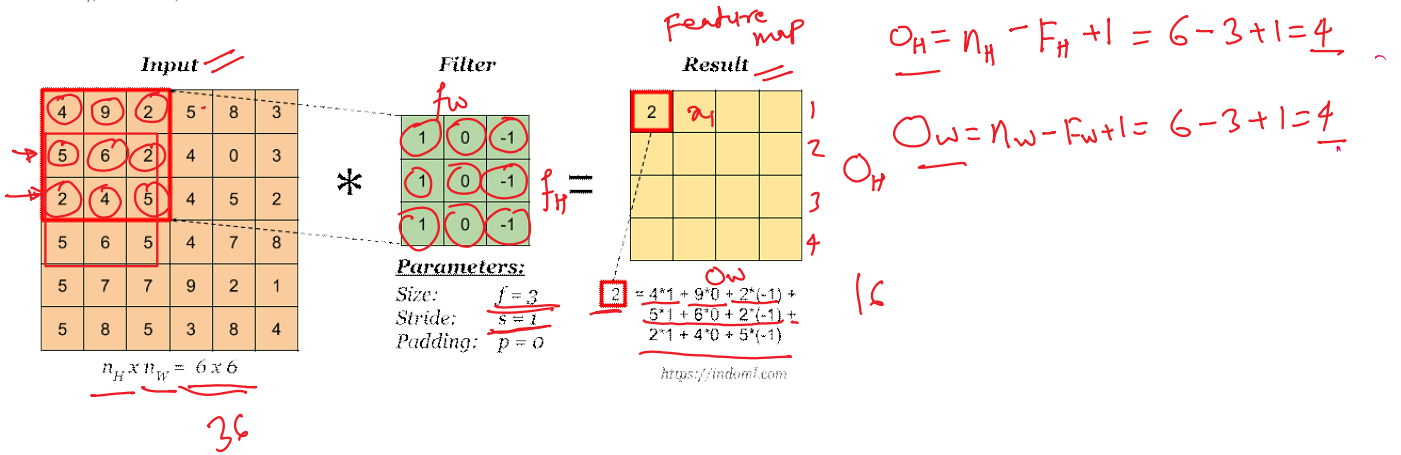
-1	-1	-1	1	-1	1	-1	-1	-1
-1	-1	1	-1	-1	-1	1	-1	-1
-1	1	-1	-1	-1	-1	-1	1	-1
-1	-1	-1	-1	-1	-1	-1	-1	-1

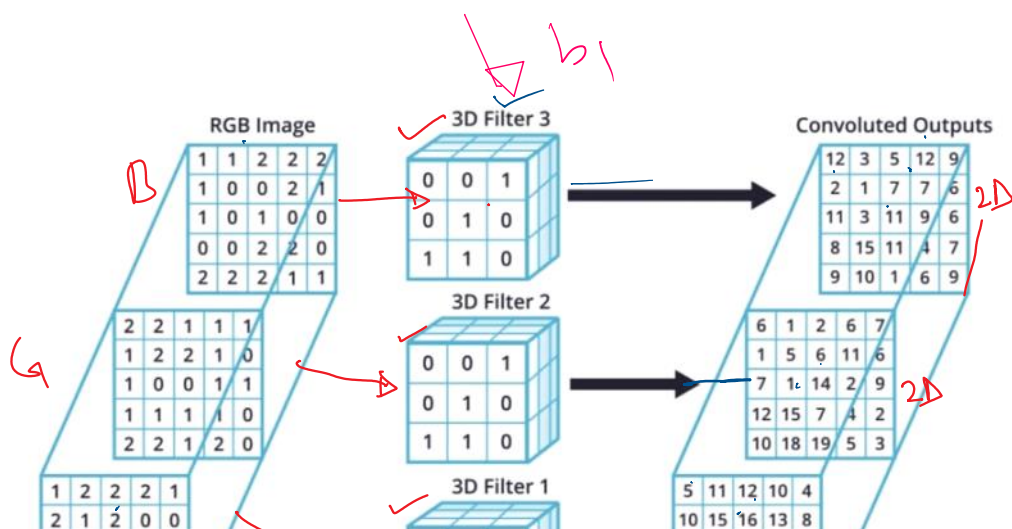
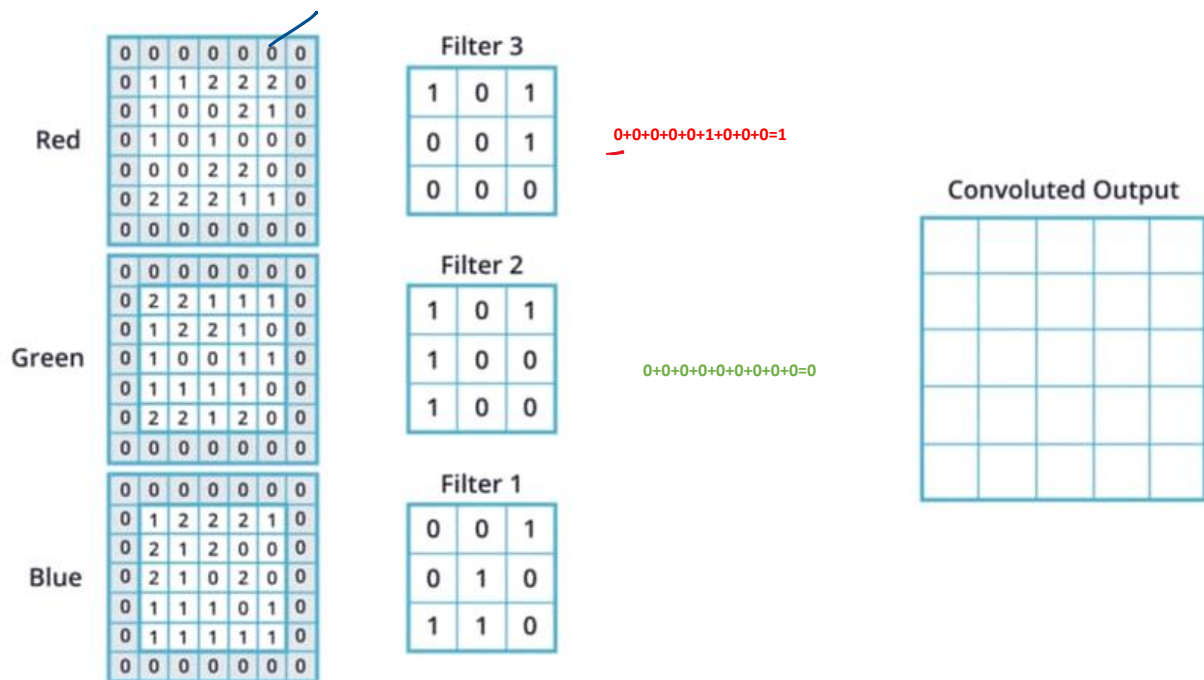
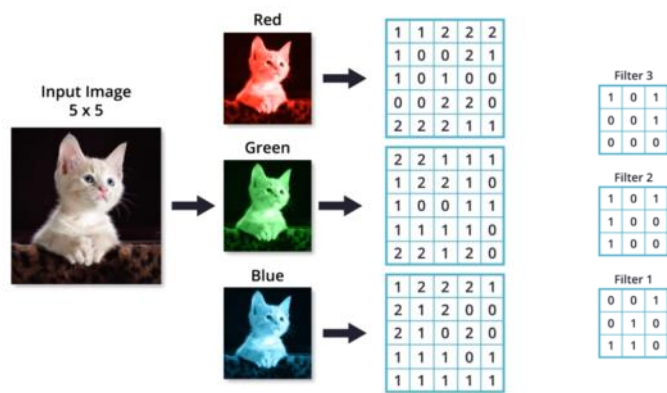
-1	-1	-1	1	-1	1	1	-1	-1
-1	-1	-1	1	-1	-1	-1	1	-1
-1	-1	1	-1	-1	-1	-1	-1	-1
-1	-1	-1	-1	-1	-1	-1	-1	-1

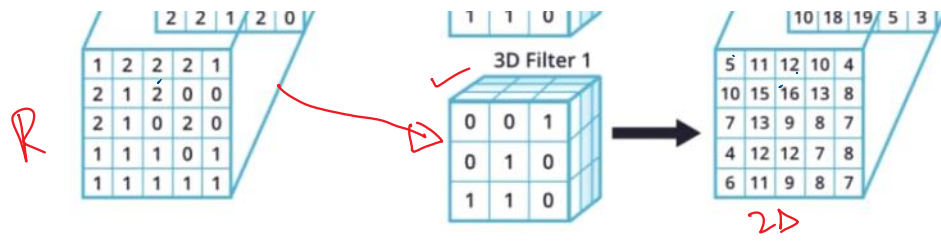
Convolution Operations

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<https://indoml.com/2018/03/07/student-notes-convolutional-neural-networks-cnn-introduction/>







PADDING and STRIDES

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$$O_W = \frac{n_w + 2p - f_w + 1}{s} = 6$$

$$O_H = \frac{n_h + 2p - f_h + 1}{s} = \frac{6 + 2 \cdot 1 - 3 + 1}{1} = 6$$

Pixel Values

0	0	0	0	0	0	0	0
0	1	0	4	2	1	5	0
0	8	2	5	4	34	12	0
0	20	13	25	15	240	2	0
0	76	8	6	6	100	76	0
0	34	66	134	223	201	3	0
0	255	123	89	55	32	2	0
0	0	0	0	0	0	0	0

$$0 + 0 + 0 + 0 + 4 + 0 + 0 + 16 + 2$$

Kernel 3 x 3 Pixels

1	2	1
2	4	2
1	2	1

Convolved Image

22	27	36	313	722	576
91	110	120	522	984	576
284	257	198	755	1360	798
507	567	687	1312	1689	955
1061	1288	1496	1911	1659	702
1400	1480	1269	1249	870	279

Input

4	9	2	5	8	3
2	4	5	4	5	2
5	6	5	4	7	8
5	7	7	9	2	1
5	8	5	3	8	4

Dimension: 6 x 6

$$O_W = \frac{n_w - f_w + 1}{s} = \frac{6 - 3 + 1}{2} = 2$$

$$O_H = \frac{n_h - f_h + 1}{s} = \frac{6 - 3 + 1}{2} = 2$$

Filter

1	0	-1
1	0	-1
1	0	-1

Result

2	1
---	---

Parameters:

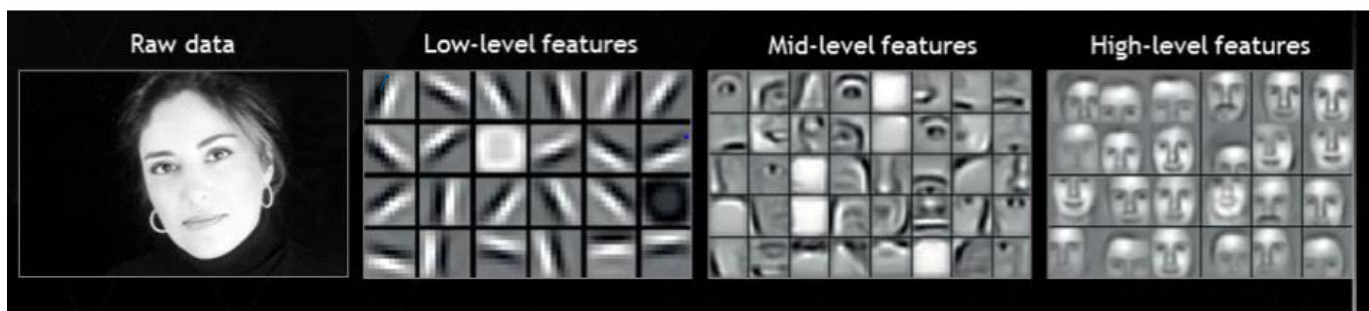
Size: $f = 3$

Stride: $s = 2$

Padding: $p = 0$

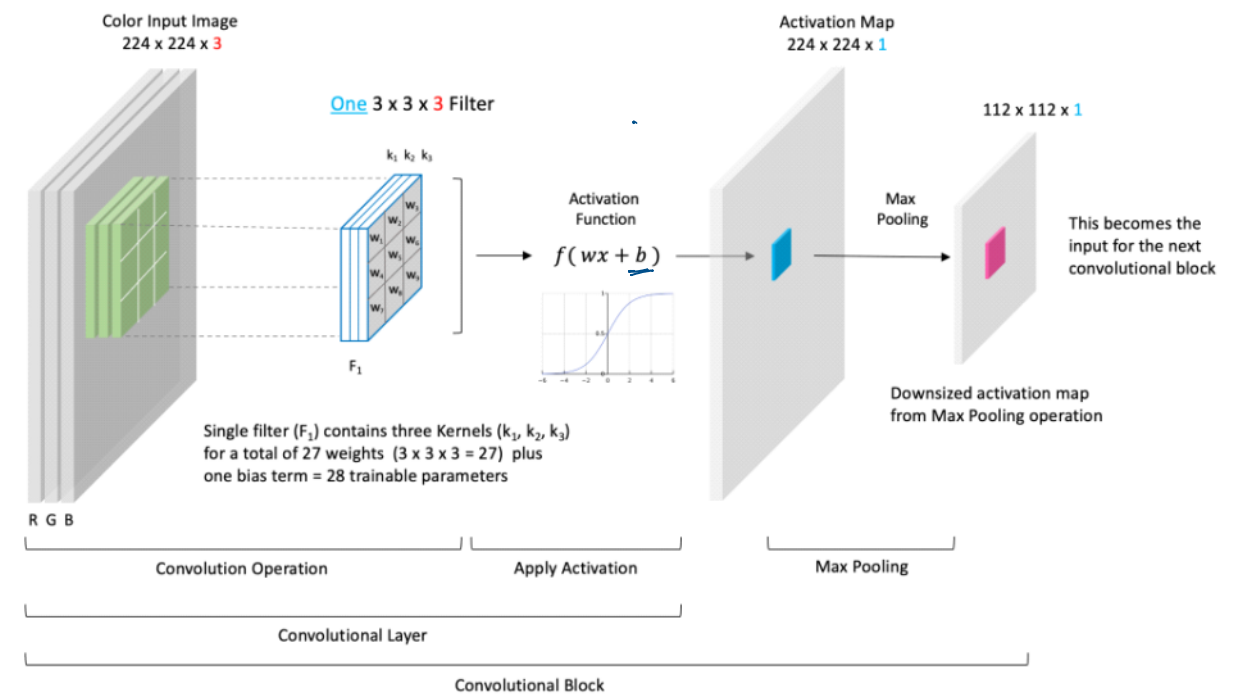
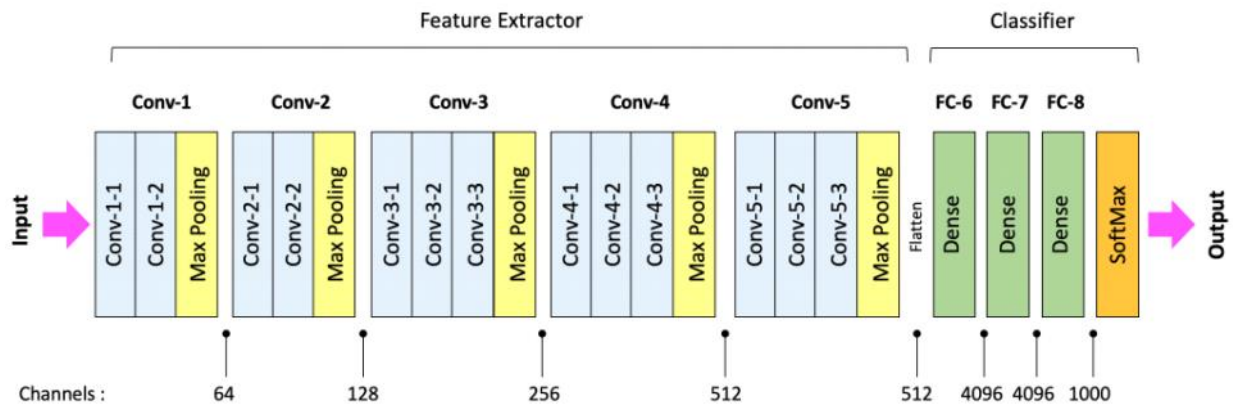
$$1 = 2 \cdot 1 + 5 \cdot 0 + 3 \cdot (-1) + 2 \cdot 1 + 4 \cdot 0 + 3 \cdot (-1) + 5 \cdot 1 + 4 \cdot 0 + 2 \cdot (-1)$$

<https://indoml.com>

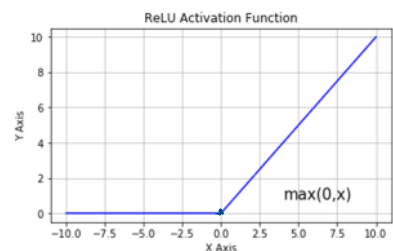
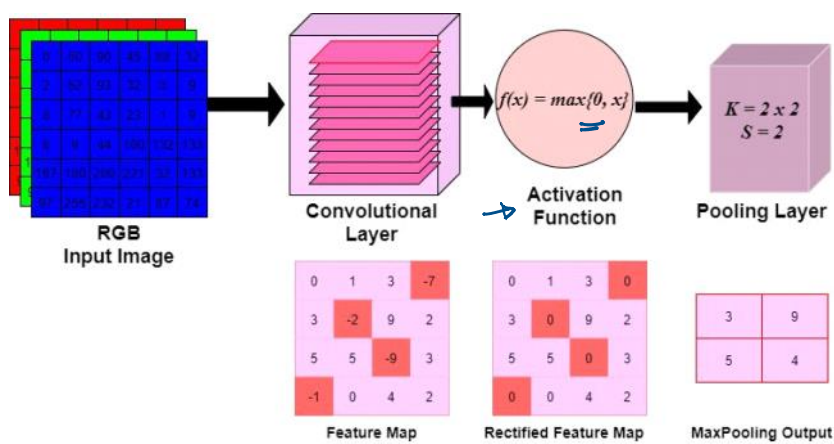


Max or Average Pooling

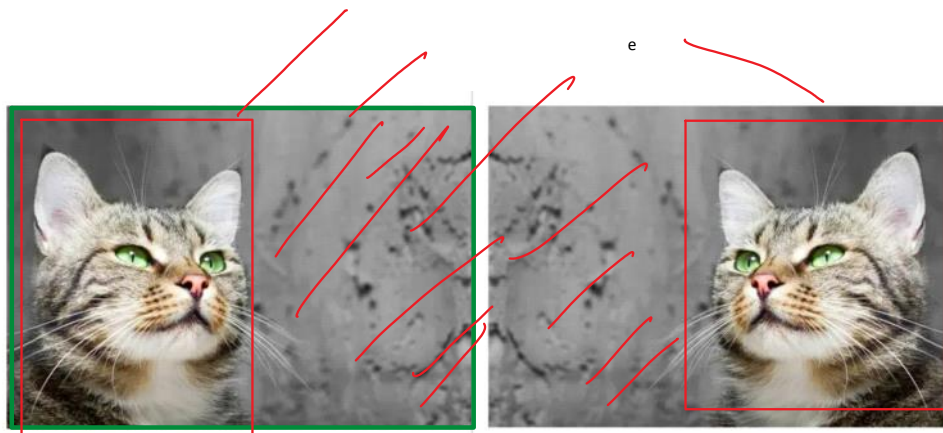
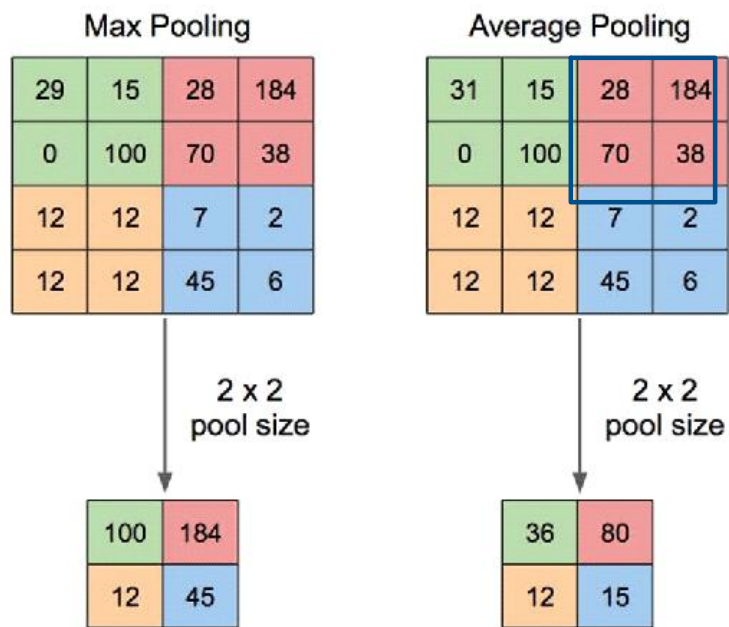
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2



Activation map



Before Flattening

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