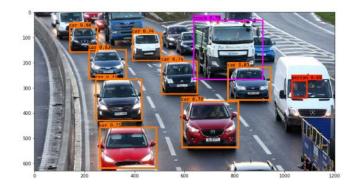


Convolution is the process involving **combination of two functions that produces the other function** as a result. In CNN's, the input image is subjected to convolution with use of filters that produces a **Feature map**.

Filters / Kernels

Filters /kernels are randomly generated vectors in the network consisting of weights and biases.

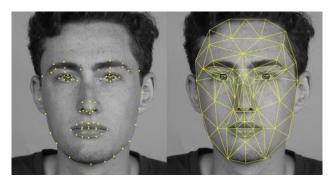
Applications of CNN



OBJECT DETECTION



SELF DRIVING CARS



FACIAL RECOGNISTION



Automatic Colorization of Black and White Images

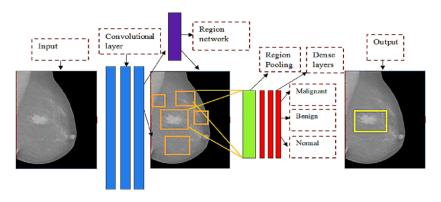




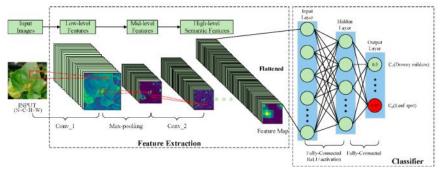




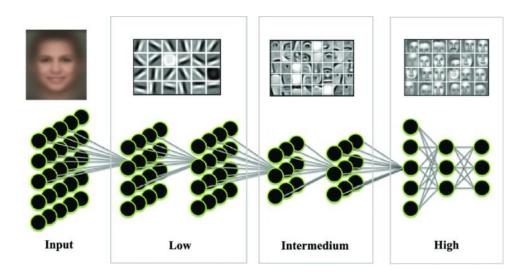
Up-scaling low-resolution images



BREAST CANCER DETECTION



LEAF DISEASE DETCTION



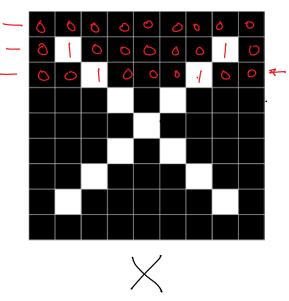
Limitations of ANN

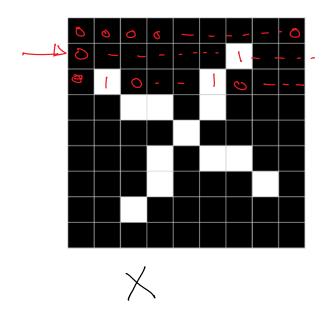
Thursday, October 26, 2023 10:24 PM

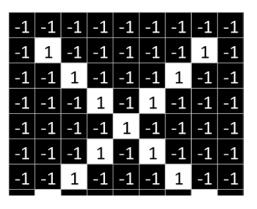
- 1. High Computation Cost
- 2. Overfitting
- 3. Loss of important info like spatial features



| Input | hidden | out | |
|-------|---|-------|--------------------|
| Layor | Layov | layer | |
| 841 | 0 0 0 0 0 0 0 4 3 3 3 4 =3 3 3 0 0 X | G | 8450 <u>3</u> - |





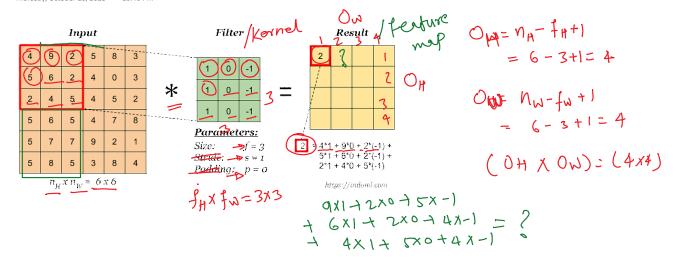


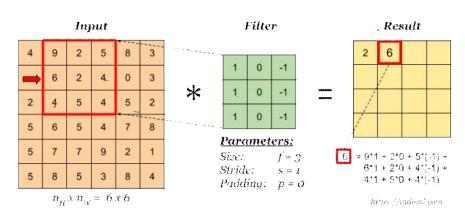
| -1 | -1 | -1 | -1 | -1 | -1 | -1 | -1 | -1 |
|----|----|----|----|----|----|----|----|----|
| -1 | -1 | -1 | -1 | -1 | -1 | 1 | -1 | -1 |
| -1 | 1 | -1 | -1 | -1 | 1 | -1 | -1 | -1 |
| -1 | -1 | 1 | 1 | -1 | 1 | -1 | -1 | -1 |
| -1 | -1 | -1 | -1 | 1 | -1 | -1 | -1 | -1 |
| -1 | -1 | -1 | 1 | -1 | 1 | 1 | -1 | -1 |
| -1 | -1 | -1 | 1 | -1 | -1 | -1 | 1 | -1 |

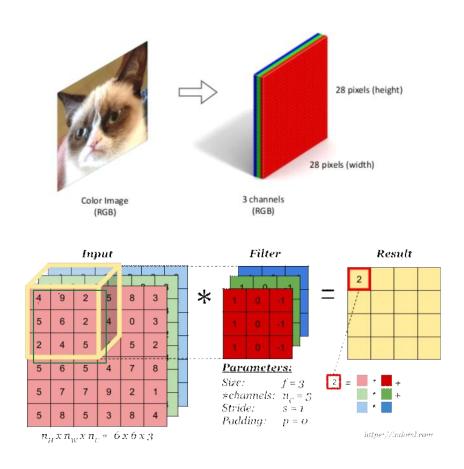
| -1 | -1 | -1 | 1 | -1 | 1 | -1 | -1 | -1 |
|----|----|----|----|----|----|----|----|----|
| -1 | -1 | 1 | -1 | -1 | -1 | 1 | -1 | -1 |
| -1 | 1 | -1 | -1 | -1 | -1 | -1 | 1 | -1 |
| -1 | -1 | -1 | -1 | -1 | -1 | -1 | -1 | -1 |

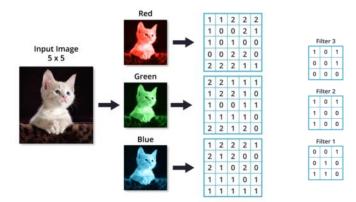
| -1 | -1 | -1 | 1 | -1 | 1 | 1 | -1 | -1 |
|----|----|----|----|----|----|----|----|----|
| -1 | -1 | -1 | 1 | -1 | -1 | -1 | 1 | -1 |
| -1 | -1 | 1 | -1 | -1 | -1 | -1 | -1 | -1 |
| -1 | -1 | -1 | -1 | -1 | -1 | -1 | -1 | -1 |

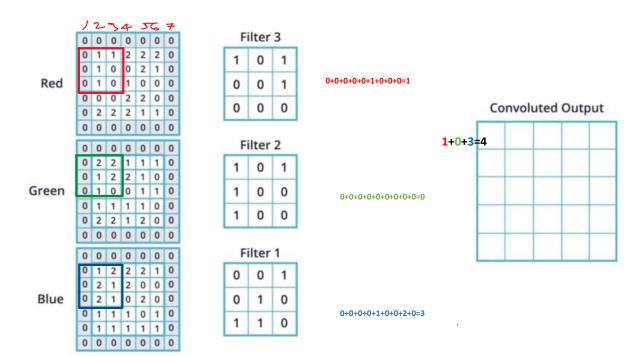


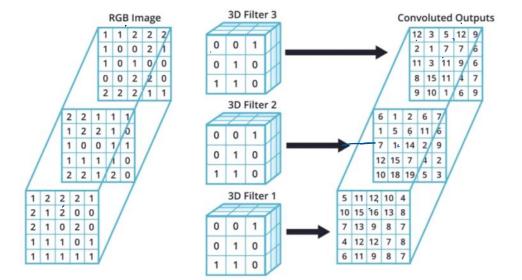








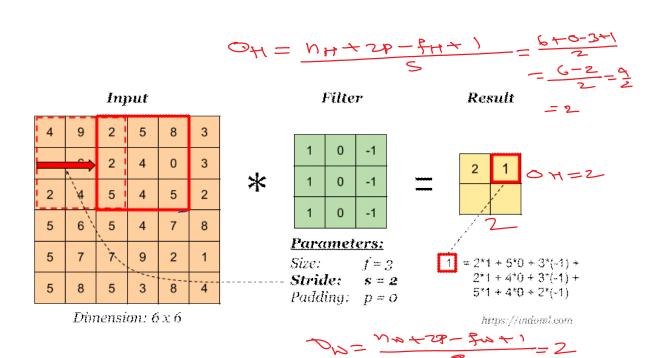


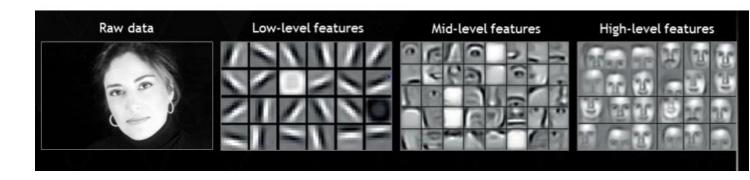


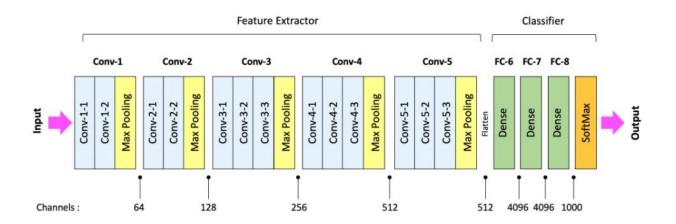
PADDING and STRIDES

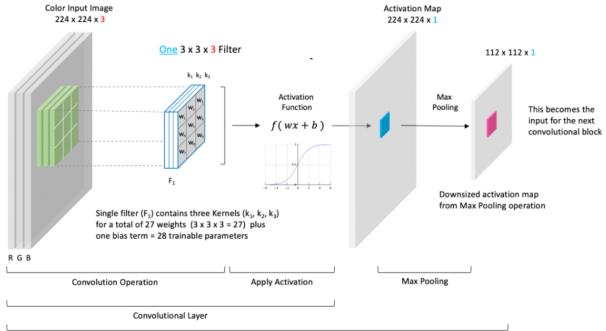
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OH=NH+2P-9+1 =6+(2×D-3+1= 4+16+ OXI+OX2+OXI+ 2 A+OX2+OXI+OX2+IX4+OX2+OX1+ Convoluted Image Pixel Values Kernel 3 x 3 Pixels 27 22 27 36 313 722 576 110 120 522 257 198 755 1360 798 507 567 687 1312 1689 955 1061 1288 1496 1911 1659 702 5 1400 1480 1269 1249 870 279 🥌 りゅーら OW=N#+ 2P-fy +1 - 6+2x1-3+1=6

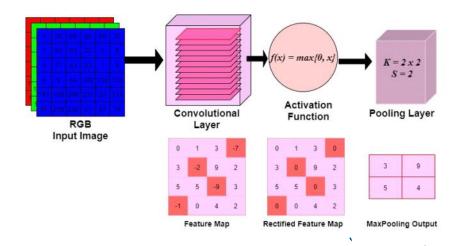


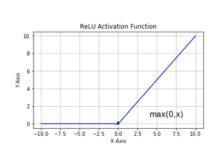


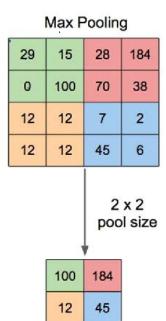


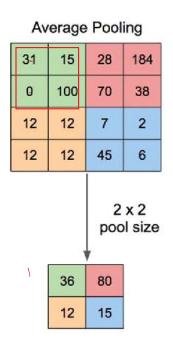


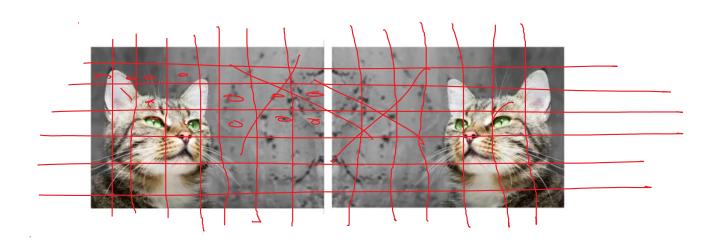
Convolutional Block











Before Flattening

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11.38 PM