

21-R-KM-ZA-11 Solution

Question: Slotted member AC rotates with an angular velocity of $\omega_{AC} = 5 \text{ rad/s}$, and an angular acceleration of $\alpha_{AC} = 1 \text{ rad/s}^2$, and has a length of $d_1 = 1.22 \text{ m}$. Another rod attaches point C to point B on disc O , and has a length of $d_2 = 1.83 \text{ m}$. If disc O rotates with an angular velocity of $\omega_O = 4 \text{ rad/s}$, and an angular acceleration of $\alpha_O = 1 \text{ rad/s}^2$, find the relative velocity and acceleration of point C with respect to point B . Use the coordinate system shown to express your answers.

The following dimensions are known: $\phi = 55 \text{ degrees}$, $\theta = 20 \text{ degrees}$, $r = 0.5 \text{ m}$

Solution: Figure 1 shows the system being considered, and shows where the rotating frame is placed. Since velocity and acceleration of C with respect to B is needed, the x -axis of the rotating frame is placed along the bar that connects C to B .

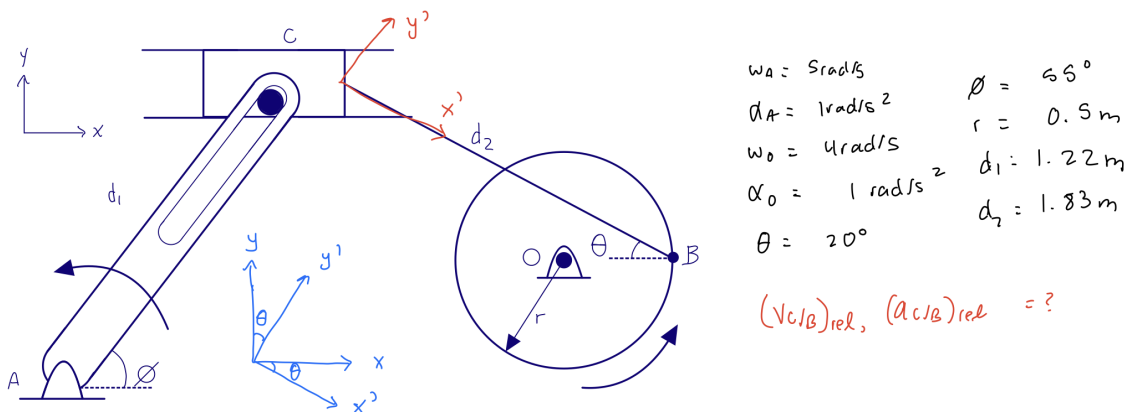


Figure 1

We know the velocity of B as we know the radius and angular velocity of O . Furthermore, we know the direction of $(v_{C/B})_{rel}$ as it is on the x axis of the rotating frame. We can rewrite it relative to the fixed frame. Finally, we know the distance between C and A , and the direction of the angular velocity of the rotating frame. The velocity equations for point C with respect to A and B are written, and then equated in Figure 2. The y component is cancelled, as C is constrained to move in the x direction only.

$$\begin{aligned}
 \vec{v}_C &= \vec{v}_A + \vec{\omega}_A \times \vec{r}_{C/A} = 5\hat{k} \times d_1(\cos\phi\hat{i} + \sin\phi\hat{j}) \\
 &= 5d_1\cos\phi\hat{j} - 5d_1\sin\phi\hat{i} \quad \text{constrained to } x\text{-direction only} \\
 \vec{v}_C &= -4.997 \text{ m/s } \hat{i} \\
 \vec{v}_C &= \vec{v}_B + \vec{\omega}_{CB} \times \vec{r}_{C/B} + (\vec{v}_{C/B})_{rel} \\
 \left\{ \begin{aligned} \vec{v}_B &= \frac{\omega_O}{r} \hat{j} = 8 \text{ m/s } \hat{j} \\ \vec{\omega}_{CB} &= \omega_{CB} \hat{k} \\ \vec{r}_{C/B} &= d_2(-\cos\theta\hat{i} + \sin\theta\hat{j}) \\ (\vec{v}_{C/B})_{rel} &= v_{C/B} \hat{i} = v_{C/B}(\cos\theta\hat{i} - \sin\theta\hat{j}) \end{aligned} \right. \\
 -4.997\hat{i} &= 8\hat{j} + \omega_{CB}\hat{k} \times [-1.72\hat{i} + 0.626\hat{j}] + v_{C/B}(\cos 20^\circ\hat{i} - \sin 20^\circ\hat{j})
 \end{aligned}$$

Figure 2

Rewriting the velocity equations into its x and y components in Figure 3, we are left with two equations and two unknowns: $(v_{C/B})_{rel}$ and Ω_{CB} . Solving the system of equations gives the magnitude of each.

$$\begin{aligned}
 \textcircled{1} \uparrow : \quad -4.997 &= -\Omega_{CB} 0.626 + v_{C/B} \cos 20 \\
 \textcircled{2} \uparrow : \quad 0 &= 8 - \Omega_{CB} 1.72 - v_{C/B} \sin 20 \\
 \text{solve } \textcircled{1} + \textcircled{2} : \quad \Omega_{CB} &= \frac{v_{C/B} \cos 20 + 4.997}{0.626} \\
 v_{C/B} \sin 20 &= 8 - \frac{1.72}{0.626} (v_{C/B} \cos 20 + 4.997) \\
 v_{C/B} &= \frac{\left(8 - \frac{1.72 (4.997)}{0.626} \right)}{\left(\sin 20 + \frac{1.72 \cos 20}{0.626} \right)} = -1.960 \text{ m/s} \\
 \therefore \vec{v}_{C/B} &= -1.960 (\cos 20 \hat{i} - \sin 20 \hat{j}) \quad \vec{\Omega}_{CB} = 5.04 \text{ rad/s } \hat{k}
 \end{aligned}$$

Figure 3

Figure 4 shows the acceleration equations written for C with respect to points A and B. Once again the y component is cancelled as the motion of C is constrained. We know the acceleration of B as it can be broken down into its normal and tangential components. Furthermore, we can assume the direction of the angular acceleration of the rotating frame to be \hat{k} , and we know the direction of $(a_{C/B})_{rel}$ as B and C are connected along the x axis of the rotating frame.

$$\begin{aligned}
 \vec{a}_C &= \vec{a}_A + \vec{\alpha}_A \times \vec{r}_{C/A} - \omega_A^2 \vec{r}_{C/A} \\
 &= 0 + 1\hat{k} \times d_1 [\cos \theta \hat{i} + \sin \theta \hat{j}] - (5^2) d_1 [\cos \theta \hat{i} + \sin \theta \hat{j}] \\
 &= 0.6998 \hat{j} - 0.999 \hat{i} - 17.49 \hat{i} - 24.98 \hat{j} \quad \text{constrained to x-direction only} \\
 \vec{a}_C &= -18.489 \hat{i} \text{ m/s}^2 \\
 \vec{a}_C &= \vec{a}_B + \vec{\dot{\Omega}}_{CB} \times \vec{r}_{C/B} - \Omega_{CB}^2 \vec{r}_{C/B} + 2\vec{\Omega}_{CB} \times (\vec{v}_{C/B})_{rel} + (\vec{a}_{C/B})_{rel} \\
 \vec{a}_B &= \vec{a}_{Bn} + \vec{a}_{Bt} = -\left(\frac{v_B^2}{r}\right) \hat{i} + \alpha_B r \hat{j} \\
 &= (-128 \hat{i} + 1 \hat{j}) \text{ m/s}^2 \\
 \vec{\dot{\Omega}}_{CB} &= \dot{\Omega}_{CB} \hat{k} \\
 \vec{r}_{C/B} &= d_2 (-\cos \theta \hat{i} + \sin \theta \hat{j}) \\
 \vec{\Omega}_{CB} &= 5.04 \hat{k} \text{ rad/s} \\
 (\vec{v}_{C/B})_{rel} &= -1.960 (\cos 20 \hat{i} - \sin 20 \hat{j}) \quad \text{same dir as velocity} \\
 (\vec{a}_{C/B})_{rel} &= a_{C/B} (\cos 20 \hat{i} - \sin 20 \hat{j}) \quad \leftarrow \text{bc on x' axis} \\
 -18.489 \hat{i} &= -128 \hat{i} + 1 \hat{j} + \vec{\Omega}_{CB} \hat{k} \times d_2 (-\cos \theta \hat{i} + \sin \theta \hat{j}) - 5.04^2 d_2 (-\cos \theta \hat{i} + \sin \theta \hat{j}) \\
 &\quad + 2(5.04 \hat{k}) \times -1.960 (\cos 20 \hat{i} - \sin 20 \hat{j}) + (a_{C/B})_{rel} (\cos 20 \hat{i} - \sin 20 \hat{j})
 \end{aligned}$$

Figure 4

Plugging all the values into the acceleration equation, and rewriting it into its x and y components yields the two equations shown in Figure 5. Collecting like terms gives a system of equations with two equations and two unknowns: $(a_{C/B})_{rel}$ and $\ddot{\Omega}_{CB}$. Solving reveals the magnitude of the relative acceleration.

$$\begin{aligned}
 \hat{i}: -18.489 &= -128 - \ddot{\Omega}_{CB} d_2 \sin \theta + 5.04^2 d_2 \cos \theta - 2(5.04)(1.960 \sin 20^\circ) + (a_{C/B})_{rel} \cos 20^\circ \\
 &\quad \underbrace{\hspace{1cm}} \underbrace{\hspace{1cm}} \text{"i constants"} \underbrace{\hspace{1cm}} \\
 \hat{j}: 0 &= 1 - \ddot{\Omega}_{CB} d_2 \cos \theta - 5.04^2 d_2 \sin \theta - 2(5.04)(1.960 \cos 20^\circ) - (a_{C/B})_{rel} \sin 20^\circ \\
 &\quad \underbrace{\hspace{1cm}} \underbrace{\hspace{1cm}} \text{"j constants"} \underbrace{\hspace{1cm}}
 \end{aligned}$$

$$\begin{aligned}
 (1) \hat{i}: 72.587 &= -\ddot{\Omega}_{CB} d_2 \sin 20^\circ + (a_{C/B})_{rel} \cos 20^\circ && \text{2 eqns, 2 unknowns, solve} \\
 (2) \hat{j}: 33.832 &= -\ddot{\Omega}_{CB} d_2 \cos 20^\circ - (a_{C/B})_{rel} \sin 20^\circ
 \end{aligned}$$

$$33.832 = -\cancel{d_2 \cos 20^\circ} \left(\frac{a_{C/B} \cos 20^\circ - 72.587}{\cancel{d_2 \sin 20^\circ}} \right) - a_{C/B} \sin 20^\circ$$

$$a_{C/B} = \frac{33.832 - 72.587 \frac{\cos 20^\circ}{\sin 20^\circ}}{\left(-\frac{\cos^2 20^\circ}{\sin 20^\circ} - \sin 20^\circ \right)} = 56.6 \text{ m/s}^2$$

$$\therefore (\vec{a}_{C/B})_{rel} = 56.6 (\cos 20^\circ \hat{i} - \sin 20^\circ \hat{j})$$

Figure 5