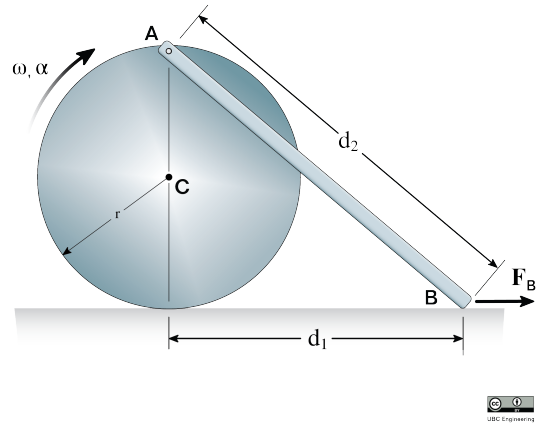


## 22-R-KIN-JL-50

A disc with a slender rod attached rolls without slipping. At the instant shown, it has an angular velocity of  $\vec{\omega}_C = -5 \text{ rad/s } \hat{k}$  and an angular acceleration of  $\vec{\alpha}_C = -4 \text{ rad/s}^2 \hat{k}$ . No friction occurs between the rod and the floor. The rod has a mass  $m_{rod} = 8 \text{ kg}$ ,  $d_1 = 3 \text{ m}$ , and  $r = 0.5 \text{ m}$ . A force pulls point  $B$  on the rod to the right with a magnitude of  $F_B = 6 \text{ N}$ .

Determine the reaction forces  $A_x$  and  $A_y$  acting on the rod and the angular acceleration  $\alpha_{AB}$  of the rod at the instant shown.



### Solution

The first step is to set up our equations of motion for the rod and take the moments about its center of mass.

$$\sum F_x = m a_{Gx} \implies m a_{Gx} = A_x + F_B$$

$$\sum F_y = m a_{Gy} \implies m a_{Gy} = A_y - mg + N_B$$

$$\begin{aligned} \sum M_G = I_G \alpha_{AB} &\implies I_G \alpha_{AB} = F_B(r) - A_x(r) + N_B\left(\frac{d_1}{2}\right) - A_y\left(\frac{d_1}{2}\right) \\ &= (F_B - A_x)(r) + (N_B - A_y)\left(\frac{d_1}{2}\right) \end{aligned}$$

Next we can find the motion of  $A$  using relative motion since we know the motion of  $C$ .

$$\vec{a}_A = \vec{a}_C + \vec{\alpha}_C \times \vec{r}_{A/C} - \omega_C^2 \vec{r}_{A/C}$$

$$\vec{a}_A = \alpha_C r \hat{i} + \alpha_C r \hat{i} - \omega_C^2 r \hat{j}$$

$$\vec{a}_A = 3.2 \hat{i} - 10 \hat{j}$$

Then we can find the motion of  $B$  using relative motion since we now know the motion of  $A$ . Notice that at this instant, both  $A$  and  $B$  are moving in the  $\hat{i}$  direction only, and so  $\vec{\omega}_{AB} = 0$ .

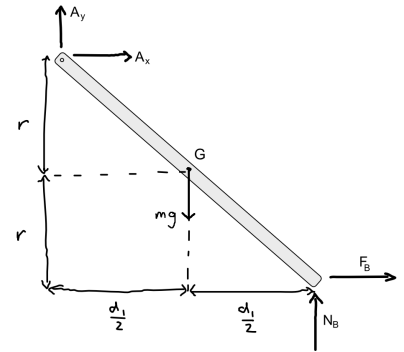
$$\vec{a}_B = \vec{a}_A + \vec{\alpha}_{AB} \times \vec{r}_{B/A} - \omega_{AB}^2 \vec{r}_{B/A}$$

$$\vec{a}_B = (3.2 \hat{i} - 10 \hat{j}) + [\alpha_{AB} \hat{k} \times (3 \hat{i} - 0.8 \hat{j})] - 0$$

$$\vec{a}_B = (3.2 + 0.8 \alpha_{AB}) \hat{i} + (3 \alpha_{AB} - 10) \hat{j}$$

We also know that  $B$  has no acceleration in the  $\hat{j}$  direction, and so we can set  $3 \alpha_{AB} - 10 = 0$  and solve for  $\alpha_{AB}$ .

$$\vec{\alpha}_{AB} = 10/3 = 3.333 \hat{k} \text{ [rad/s}^2\text{]}.$$



(continued on next page)

Then using relative motion again, we can find the motion of  $G$ , and substitute in our value for  $\vec{\alpha}_{AB}$  to find the components  $\vec{a}_{Gx}$  and  $\vec{a}_{Gy}$ .

$$\vec{a}_G = \vec{a}_A + \vec{\alpha}_{AB} \times \vec{r}_{G/A} - \omega_{AB}^2 \vec{r}_{G/A}$$

$$\vec{a}_G = (3.2 \hat{i} - 10 \hat{j}) + [\alpha_{AB} \hat{k} \times (1.5 \hat{i} - 0.4 \hat{j})] - 0$$

$$\vec{a}_G = (3.2 + 0.4 \alpha_{AB}) \hat{i} + (1.5 \alpha_{AB} - 10) \hat{j}$$

$$\vec{a}_G = 4.533 \hat{i} - 5 \hat{j}$$

Lastly, we can solve the three equations of motion, with the 3 unknowns  $A_x$ ,  $A_y$ , and  $N_B$ . Note that the moment of inertia of the rod about its center of mass is  $I_G = \frac{1}{12} m d_2^2 = \frac{1}{12} m (4r^2 + d_1^2) = \frac{8}{12} (0.64 + 9) = 6.427 \text{ [kg*m}^2\text{]}$  :

$$m a_{Gx} = A_x + F_B \implies A_x = m a_{Gx} - F_B = (8)(4.533) - 6 = 30.26 \text{ [N]}$$

$$m a_{Gy} = A_y - mg + N_B \implies A_y + N_B = (8)(-5) + (8)(9.81) = 38.48$$

$$I_G \alpha_{AB} = (F_B - A_x)(r) + (N_B - A_y)\left(\frac{d_1}{2}\right) \implies -A_y + N_B = [I_G \alpha_{AB} + (A_x - F_B)(r)]\left(\frac{2}{d_1}\right) = 20.75$$

Solving the system of equations for  $A_x$  by subtracting them, we have:

$$2 A_x = 17.73 \implies A_x = 8.865 \text{ [N]}$$