

```

1 def Jvec(self, m, v, u=None):
2     # Set current model; clear dependent property A(m)
3     self.curModel = m
4     sigma = self.curModel.transform #  $\sigma = \mathcal{M}(m)$ 
5     if u is None:
6         # Run forward simulation if u not provided
7         u = self.fields(self.curModel)
8     else:
9         shp = (self.mesh.nC, self.survey.nTx)
10        u = u.reshape(shp, order='F')
11
12    D = self.mesh.faceDiv
13    G = self.mesh.cellGrad
14    # Derivative of model transform,  $\frac{\partial \sigma}{\partial m}$ 
15    dsigdm_x_v = self.curModel.transformDeriv * v
16
17    # Take derivative of C(m,u) w.r.t. m
18    dCdm_x_v = np.empty_like(u)
19    # loop over fields for each transmitter
20    for i in range(self.survey.nTx):
21        # Derivative of inner product,  $\left(M_{1/\sigma}^f\right)^{-1}$ 
22        dAdsig = D * self.dMdsig( G * u[:,i] )
23        dCdm_x_v[:, i] = dAdsig * dsigdm_x_v
24
25    # Take derivative of C(m,u) w.r.t. u
26    dCdu = self.A
27    # Solve for  $\frac{\partial u}{\partial m}$ 
28    dCdu_inv = self.Solver(dCdu, **self.solverOpts)
29    P = self.survey.getP(self.mesh)
30    J_x_v = - P * mkvc( dCdu_inv * dCdm_x_v )
31    return J_x_v

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