Introduction to Machine Learning

Kernel Support Vector Machines

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1 Support Vector Machines

1.1 SVM Learning

SVM Optimization

Optimization Formulation

minimize
$$\frac{\|\mathbf{w}\|^2}{2}$$

subject to $y_n(\mathbf{w}^{\top}\mathbf{x}_n + b) \ge 1, \ n = 1, \dots, N.$

• Introducing Lagrange Multipliers, α_n , n = 1, ..., N

Rewriting as a (primal) Lagrangian

minimize
$$L_P(\mathbf{w}, b, \alpha) = \frac{\|\mathbf{w}\|^2}{2} + \sum_{n=1}^N \alpha_n \{1 - y_n(\mathbf{w}^\top \mathbf{x}_n + b)\}$$

subject to $\alpha_n \ge 0$ $n = 1, ..., N$.

Solving the Lagrangian

• Set gradient of L_P to 0

$$\frac{\partial L_P}{\partial \mathbf{w}} = 0 \Rightarrow \mathbf{w} = \sum_{n=1}^N \alpha_n y_n \mathbf{x}_n$$

$$\frac{\partial L_P}{\partial b} = 0 \Rightarrow \sum_{n=1}^{N} \alpha_n y_n = 0$$

• Substituting in L_P to get the dual L_D

Dual Lagrangian Formulation

maximize
$$L_D(\mathbf{w}, b, \alpha) = \sum_{n=1}^{N} \alpha_n - \frac{1}{2} \sum_{m,n=1}^{N} \alpha_m \alpha_n y_m y_n(\mathbf{x}_m^{\top} \mathbf{x}_n)$$

subject to $\sum_{n=1}^{N} \alpha_n y_n = 0, \alpha_n \ge 0 \ n = 1, \dots, N.$

1.2 Kernel SVM

Dot Product Formulation

- All training examples (\mathbf{x}_n) occur in $dot/inner\ products$
- Also recall the prediction using SVMs

$$\begin{aligned} \boldsymbol{y}^* &= sign(\mathbf{w}^{\top}\mathbf{x}^* + b) \\ &= sign((\sum_{n=1}^{N} \alpha_n y_n \mathbf{x}_n)^{\top}\mathbf{x}^* + b) \\ &= sign(\sum_{n=1}^{N} \alpha_n y_n \frac{(\mathbf{x}_n^{\top}\mathbf{x}^*)}{} + b) \end{aligned}$$

• Replace the dot products with kernel functions

- Kernel or non-linear SVM
- Kernel SVM with radial basis function kernel (RBF)

$$k(\mathbf{x}_i, \mathbf{x}_j) = exp\left(-\frac{1}{2\gamma^2}||\mathbf{x}_i - \mathbf{x}_j||^2\right)$$

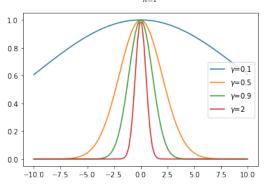
Setting γ and C

 \bullet C is the regularization parameter

$$L(\mathbf{w}, b) = \|\mathbf{w}\|^2 + C \sum_{i=1}^{N} \xi_i$$
 subject to constraints

• For the role of γ , consider the following two aspects:

$$y^* = sign(\sum_{n=1}^{N} \alpha_n y_n (\mathbf{x}_n^{\mathsf{T}} \mathbf{x}^*) + b)$$



- γ determines the influence of a training example inverse of the radius of influence of support vectors
- \bullet C determines the trade-off between the total slack (errors on training data) and the size of the margin (regularization)

- \bullet Setting γ too large makes the decision boundary too complex, C will not prevent overfitting
- Setting γ very small makes the decision boundary simple (linear)
- \bullet Usually a grid search is performed to identify optimal C and γ

References