

Support Vector Machines

Mon Feb 22

$$y = \text{sign}(w^T x + w_0)$$

$$p(y=+1) = \frac{1}{1 + \exp(w^T x)}$$

$$\text{If } p(y=+1) \geq 0.5 \quad \textcircled{y = +1}$$

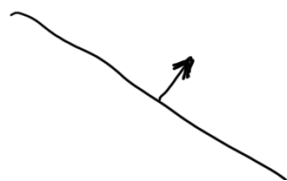
For a new data point:

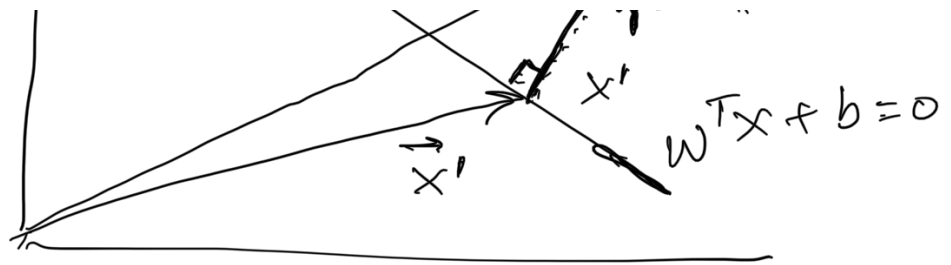
$$\underline{p(y=+1)} = \underline{0.95}$$

For another data point:

$$\underline{p(y=+1)} = \underline{0.55}$$

x_2





$$\boxed{\vec{x} = \vec{x}' + \vec{r}}$$

$$\vec{x}' = \vec{x} - \vec{r}$$

x_1

$$\hat{w} = \frac{\vec{w}}{\|\vec{w}\|} \rightarrow \text{unit vector orthogonal to the line}$$

$$\|\vec{w}\| = \sqrt{w_1^2 + w_2^2 + \dots}$$

$$\vec{r} = \gamma \hat{w} = \frac{\gamma \vec{w}}{\|\vec{w}\|} = \frac{\gamma \vec{w}}{\sqrt{\vec{w}^T \vec{w}}}$$

$$\vec{x}' = \vec{x} - \frac{\gamma \vec{w}}{\|\vec{w}\|}$$

Since \vec{x}' lies on the decision line
 $\vec{w}^T \vec{x}' + b = 0$

$$\vec{w}^T \left(\vec{x} - \frac{\gamma \vec{w}}{\|\vec{w}\|} \right) + b = 0$$

$$\vec{w}^T \vec{x} - \gamma \frac{\vec{w}^T \vec{w}}{\|\vec{w}\|} + b = 0$$

$$\gamma \cdot w^T w = w^T x + b$$

$$\gamma \cdot \|w\|$$

$$\gamma = \frac{w^T x + b}{\|w\|}$$

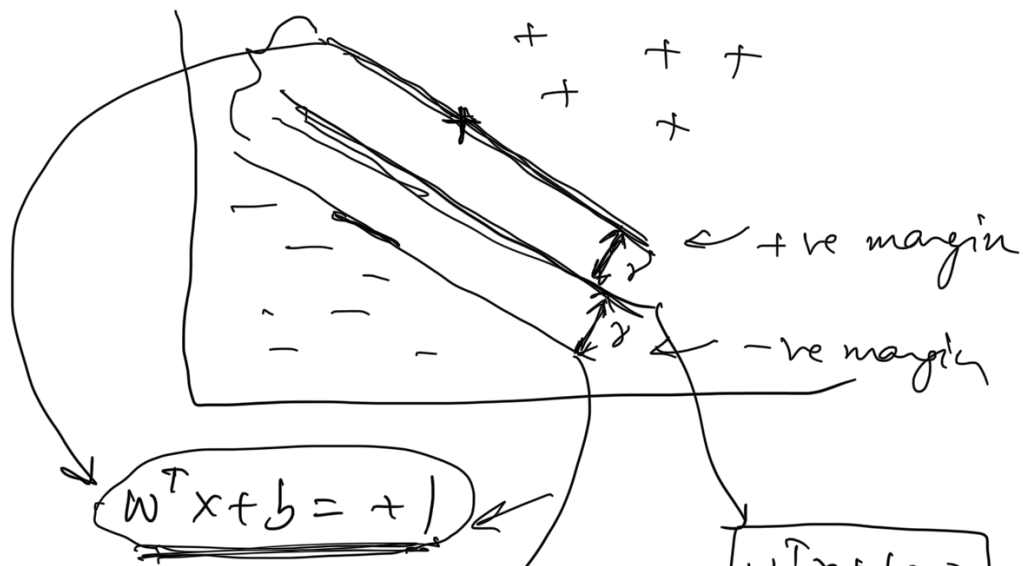
$$\left[\begin{array}{l} \text{Since} \\ w^T w = \|w\|^2 \end{array} \right]$$

for a -ve example

$$\gamma = - \frac{(w^T x + b)}{\|w\|}$$

$$\gamma = \left(y \frac{w^T x + b}{\|w\|} \right)$$

This is margin of an example.



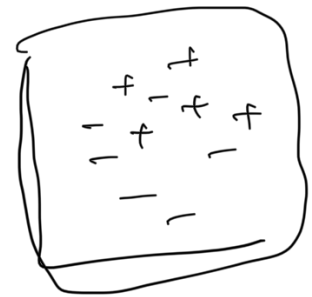
$$\underline{w^T x + b = -1} \quad \swarrow$$

$$\underline{w^T x + b = 0}$$

Distance between two margins:

will be

$$\frac{2}{\|w\|}$$



i^{th} training example: $\underline{x_i}, \underline{y_i}$

If w, b has to correctly classify this instance

$$\underline{y_i (w^T x_i + b) \geq 0}$$

If w, b have to be on the correct side of the margin:

$$\underline{y_i (w^T x_i + b) \geq 1}$$

Opt with equality constraints.

$$f(x, y) = x^2 + 2y^2 - 2$$

$$h(x, y) = \boxed{x + y - 1 = 0}$$

$$L(x, y, \beta) = x^2 + 2y^2 - 2 + \beta(x + y - 1) = 0$$

$$\frac{\partial L}{\partial x} = 2x + \beta = 0$$

$$\frac{\partial L}{\partial y} = 4y + \beta = 0$$

$$\frac{\partial L}{\partial \beta} = \underline{x + y - 1 = 0}$$

$$\begin{aligned} 4y - 2x &= 0 \\ x &= 2y \end{aligned}$$

$$x = 1 - y$$

$$1 - y = 2y$$

$$\boxed{y = \frac{1}{3} \quad x = \frac{2}{3}}$$

Wednesday Feb 24

$$\nabla f(w_1, w_2) = \lambda \nabla g(w_1, w_2)$$

$$g(w_1, w_2) = 0$$

$$L = f(w_1, w_2) + \lambda g(w_1, w_2)$$

$$\nabla_{(w_1, w_2)} L = \nabla f(w_1, w_2) + \lambda \nabla g(w_1, w_2) = 0$$

$$\nabla \perp g(w_1, w_2) = 0$$

$$f(x, y) = x^3 + y^2$$

$$g(x): x^2 - 1 \leq 0$$

$$L(x, y, \alpha) = f(x, y) + \alpha g(x, y)$$

$$= x^3 + y^2 + \alpha (x^2 - 1)$$

$$w = \begin{bmatrix} w_1 \\ w_2 \end{bmatrix}$$

$$\min_{w_1, w_2} \quad \frac{w_1^2 + w_2^2}{2}$$

$$\|w\|^2 = w_1^2 + w_2^2$$

$$\begin{aligned} \text{s.t.} \quad & 1 - (-1)(w_1 + w_2 + b) \leq 0 \quad y_1 = -1 \\ & \equiv 1 + w_1 + w_2 + b \leq 0 \quad x_1 = \begin{bmatrix} 1 \\ 1 \end{bmatrix} \\ & 1 - (+1)(2w_1 + 2w_2 + b) \leq 0 \quad y_2 = +1 \\ & \quad \quad \quad x_2 = \begin{bmatrix} 2 \\ 2 \end{bmatrix} \\ & 1 - 2w_1 - 2w_2 - b \leq 0 \end{aligned}$$

$$L = \frac{w_1^2 + w_2^2}{2} + \alpha_1 (1 + w_1 + w_2 + b) + \alpha_2 (1 - 2w_1 - 2w_2 - b)$$

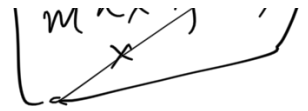
$$\alpha_1, \alpha_2 \geq 0$$

$$\frac{\partial L}{\partial w_1}, \quad \frac{\partial L}{\partial w_2}, \quad \frac{\partial L}{\partial \alpha_1}, \quad \frac{\partial L}{\partial \alpha_2}, \quad \frac{\partial L}{\partial b}$$

$$L(w, \alpha, \beta)$$

$$\min f(x)$$

Assume w is fixed



$$\Theta_p(w) \left[\max_{\alpha, \beta; \alpha_i \geq 0} L(w, \alpha, \beta) \right]$$

$$\min_w \Theta_p(w)$$

min-max is going to
give us the optimal solution

what if we solve:

$$\max_{\alpha, \beta; \alpha_i \geq 0} \left[\min_w L(w, \alpha, \beta) \right] \rightarrow \underline{\underline{\text{dual}}}$$

max-min

$$\text{max-min} \leq \text{min-max}$$

"duality-gap"

$$f(w_1, w_2)$$

$$L_p = \frac{\|w\|^2}{2} + \sum_{i=1}^N \alpha_i \{1 - y_i (\underline{w}^T x_i + b)\}$$

$$\frac{\partial L}{\partial w} = \frac{1}{2} * 2w + \sum_{i=1}^N \alpha_i (-y_i x_i)$$

$$= w - \sum_{i=1}^N \alpha_i y_i x_i$$

$$\begin{aligned} \|w\|^2 &= w^T w \\ \frac{d}{dw} w^T w &= 2w \end{aligned}$$

$$\begin{aligned} w &= \sum_{i=1}^N \alpha_i y_i x_i \\ \sum_{i=1}^N \alpha_i y_i &= 0 \end{aligned}$$

$$L_p = \frac{\|w\|^2}{2} + \sum \alpha_i \{1 - y_i (w^T x_i + b)\}$$

$$= \frac{1}{2} w^T w + \sum \alpha_i \{1 - y_i (w^T x_i + b)\}$$

Replace w with $\sum_{i=1}^N \alpha_i y_i x_i$

Solve the dual to get $\alpha_1, \alpha_2, \dots, \alpha_N$

↙
cross prod

Feed the α 's to get w