

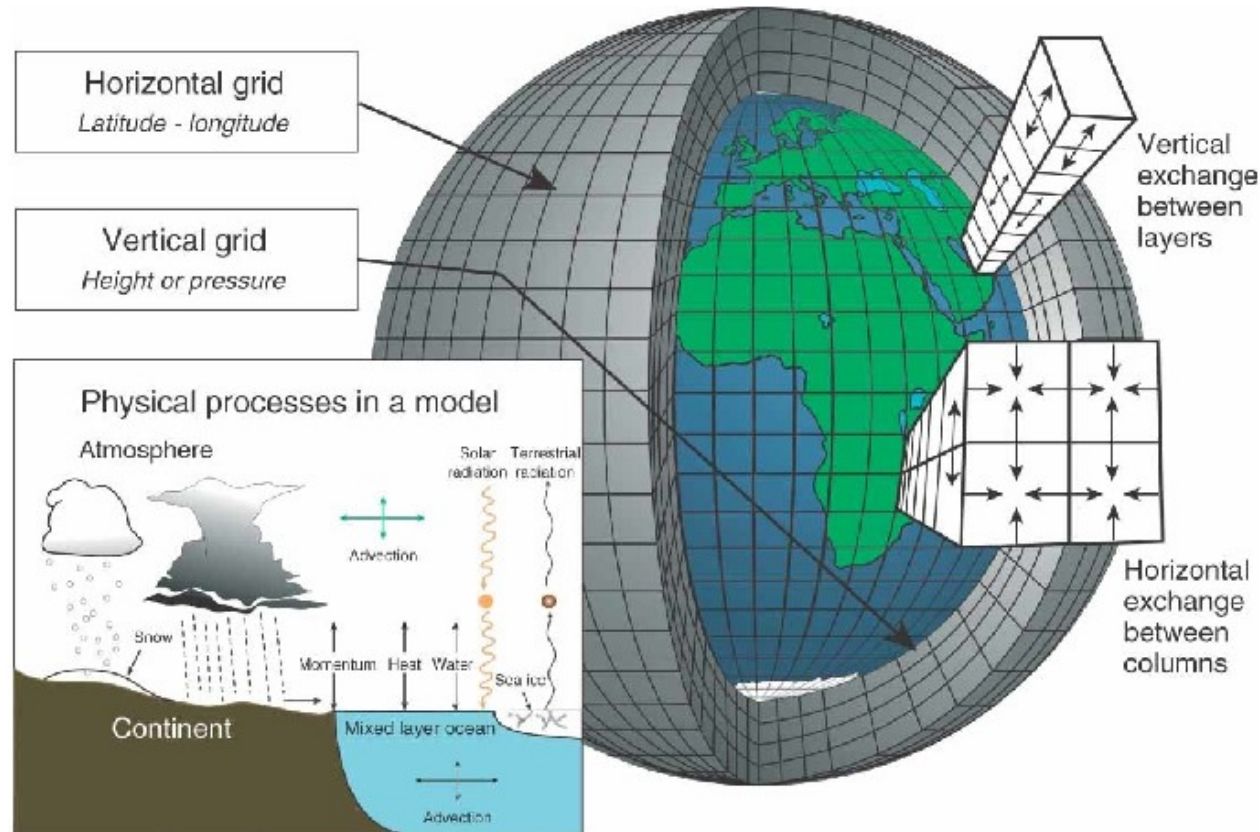


Combining **Neural Networks** and **Physics** for Weather and Climate Predictions

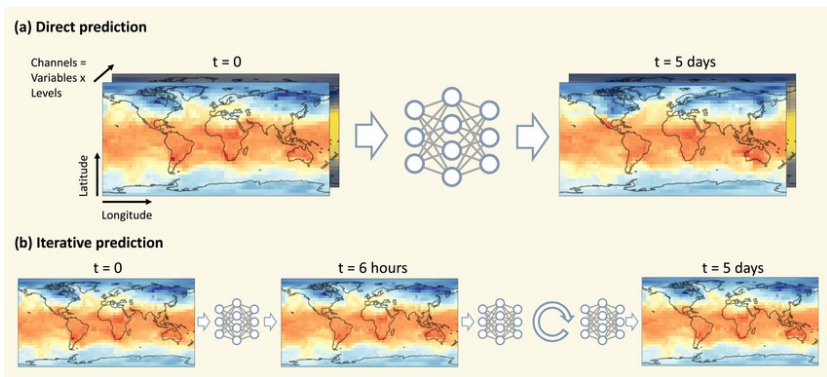
STK-IN9300
Anna Lina Sjur

General Circulation Models (GCM) basics

- Built on well-understood **physical principles**
- Defined on a **grid**
- Sub-grid scale processes are **parameterized**
- Run in **ensembles**
- Computational heavy
 - One run would take centuries on a laptop



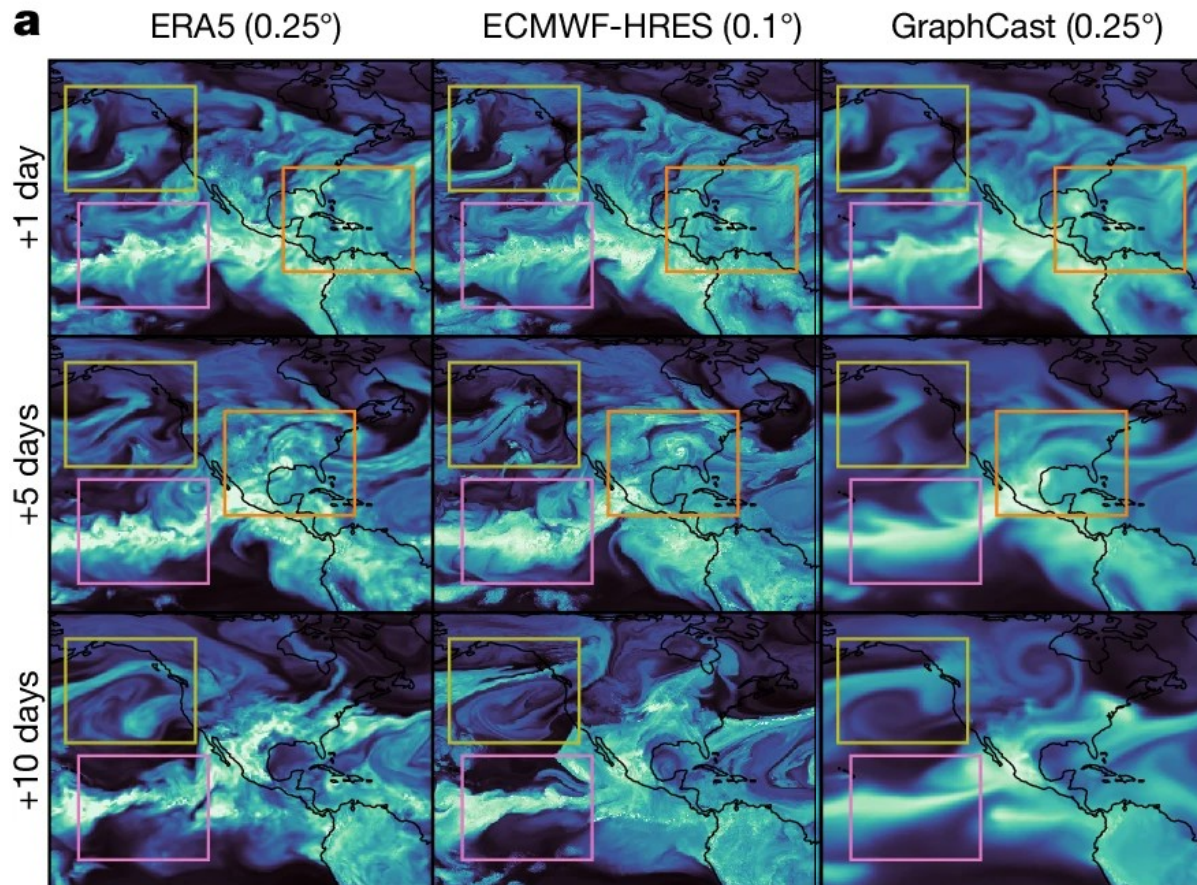
Neural Networks for weather prediction



Rasp et al. (2020)

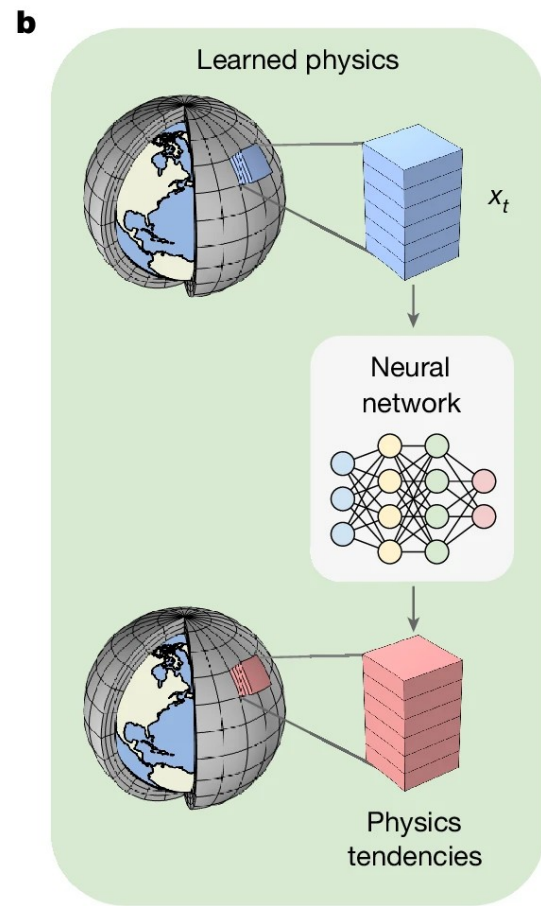
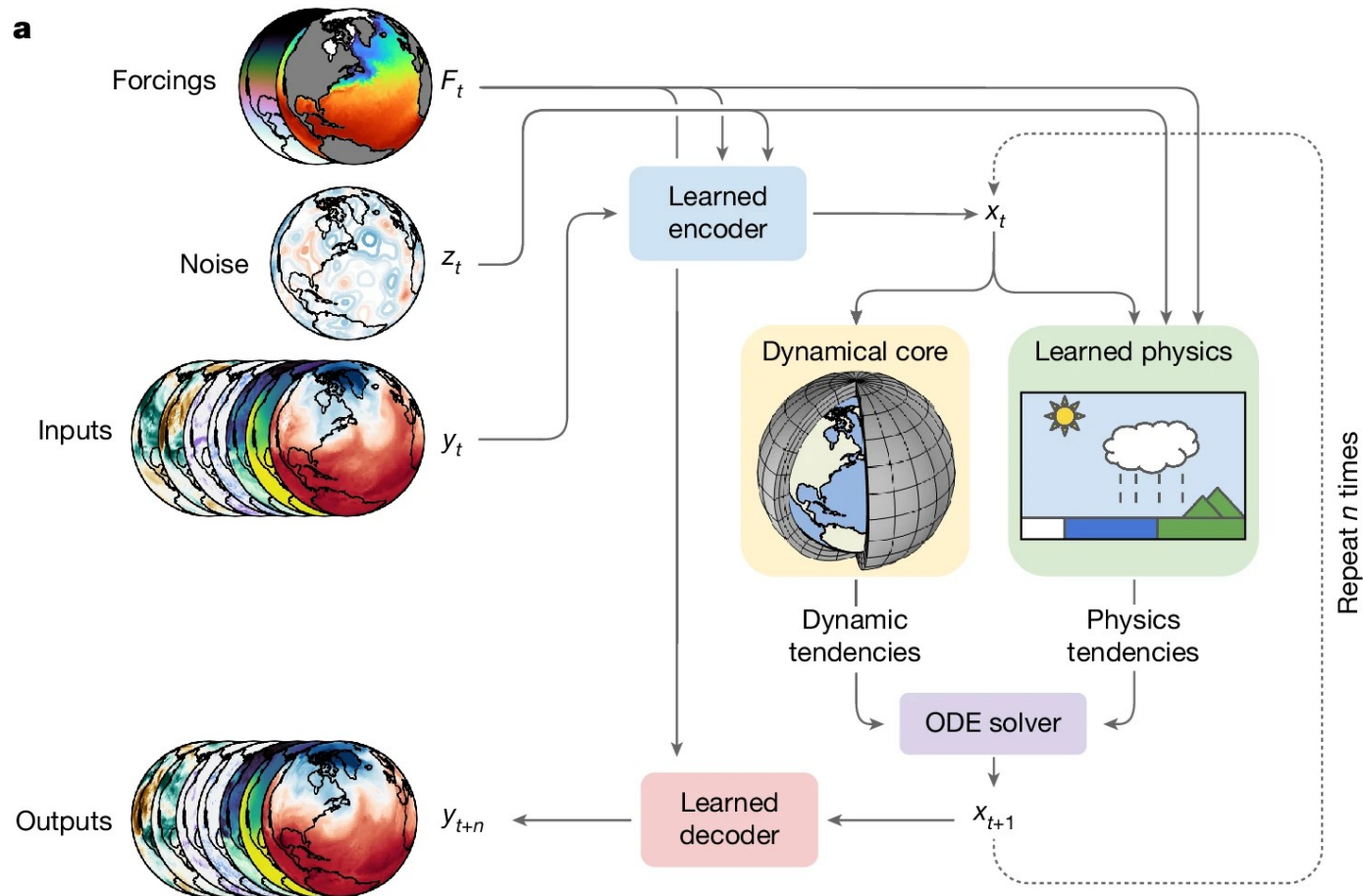
- Train on reanalysis data
- Computationally cheaper than GCMs
- Good short-time deterministic forecast
- Blurry on longer time scales

Watt-Meyer et al. (2024)



Combining the two → NeuralGCM

Watt-Meyer et al. (2024)



Dynamical core

Watt-Meyer et al. (2024)

Solve physical equations, which are a combination of

- momentum equations
- the second law of thermodynamics,
- thermodynamic equation of state (ideal gas)
- continuity equation
- hydrostatic approximation

$$\frac{\partial \zeta}{\partial t} = -\nabla \times \left((\zeta + f) \mathbf{k} \times \mathbf{u} + \dot{\sigma} \frac{\partial \mathbf{u}}{\partial \sigma} + RT' \nabla \log p_s \right)$$

$$\frac{\partial \delta}{\partial t} = -\nabla \cdot \left((\zeta + f) \mathbf{k} \times \mathbf{u} + \dot{\sigma} \frac{\partial \mathbf{u}}{\partial \sigma} + RT' \nabla \log p_s \right) - \nabla^2 \left(\frac{\|\mathbf{u}\|^2}{2} + \Phi + R\bar{T} \log p_s \right)$$

$$\frac{\partial T}{\partial t} = -\mathbf{u} \cdot \nabla T - \dot{\sigma} \frac{\partial T}{\partial \sigma} + \frac{\kappa T \omega}{p} = -\nabla \cdot \mathbf{u} T' + T' \delta - \dot{\sigma} \frac{\partial T}{\partial \sigma} + \frac{\kappa T \omega}{p}$$

$$\frac{\partial q_i}{\partial t} = -\nabla \cdot \mathbf{u} q_i + q_i \delta - \dot{\sigma} \frac{\partial q_i}{\partial \sigma}$$

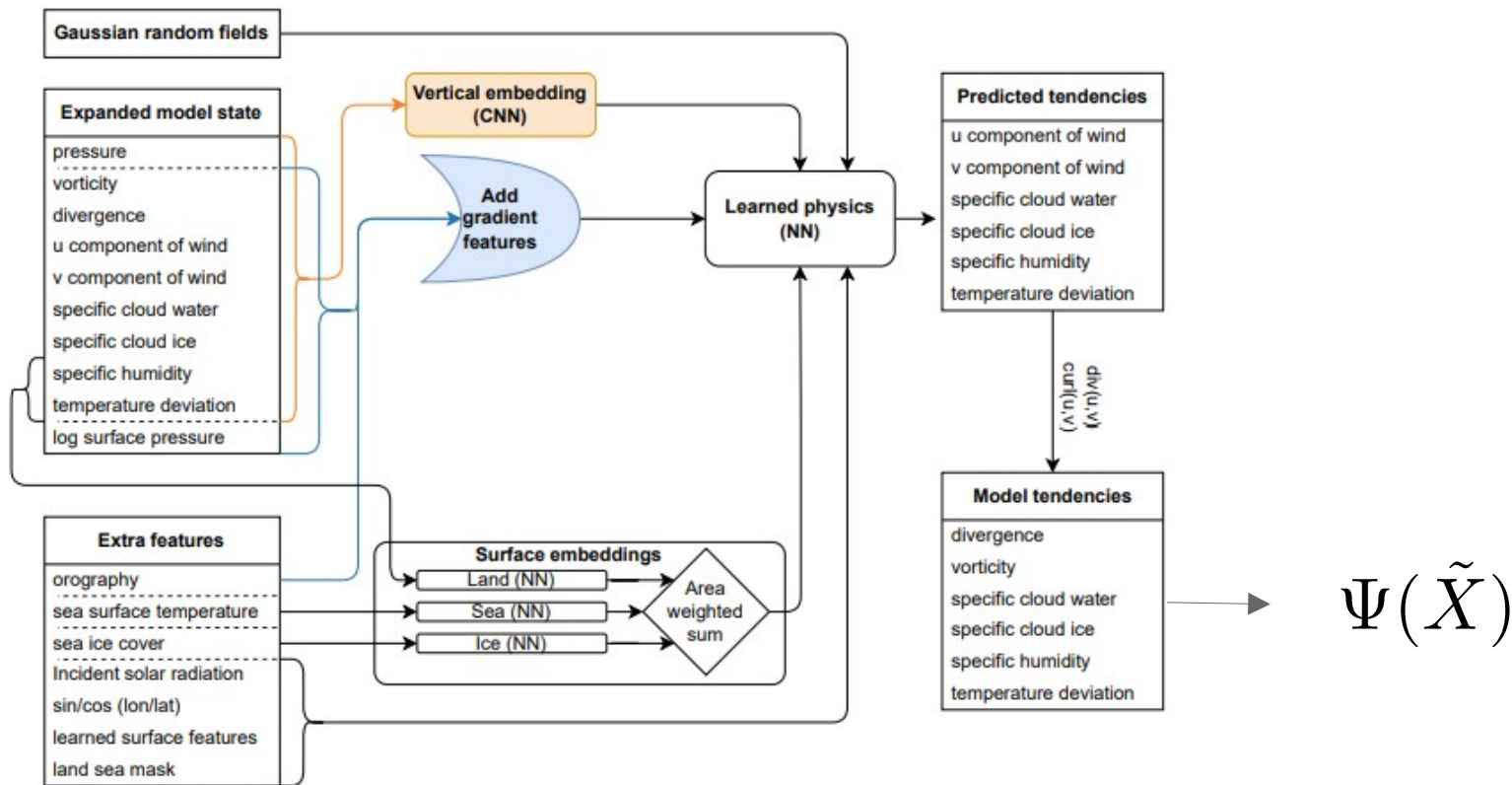
$$\frac{\partial \log p_s}{\partial t} = -\frac{1}{p_s} \int_0^1 \nabla \cdot (\mathbf{u} p_s) d\sigma = -\int_0^1 (\delta + \mathbf{u} \cdot \nabla \log p_s) d\sigma$$

(1)

$$\longrightarrow \Phi(\tilde{X})$$

Learned physics

Watt-Meyer et al. (2024)



Supplementary Figure 1: Visualization of the data flow in the learned physics module of NeuralGCM.

Combining tendencies and training

Watt-Meyer et al. (2024)

NeuralGCM implements

$$\begin{aligned}\frac{\partial \tilde{X}}{\partial t} &= \Phi(\tilde{X}) + \Psi(\tilde{X}), \quad t_0 < t < t_0 + \tau, \\ \tilde{X}(t_0) &= \text{Encode}(Y(t_0)).\end{aligned}$$

Then finally, $X = \text{Decode}(\tilde{X})$ is evaluated against Y .

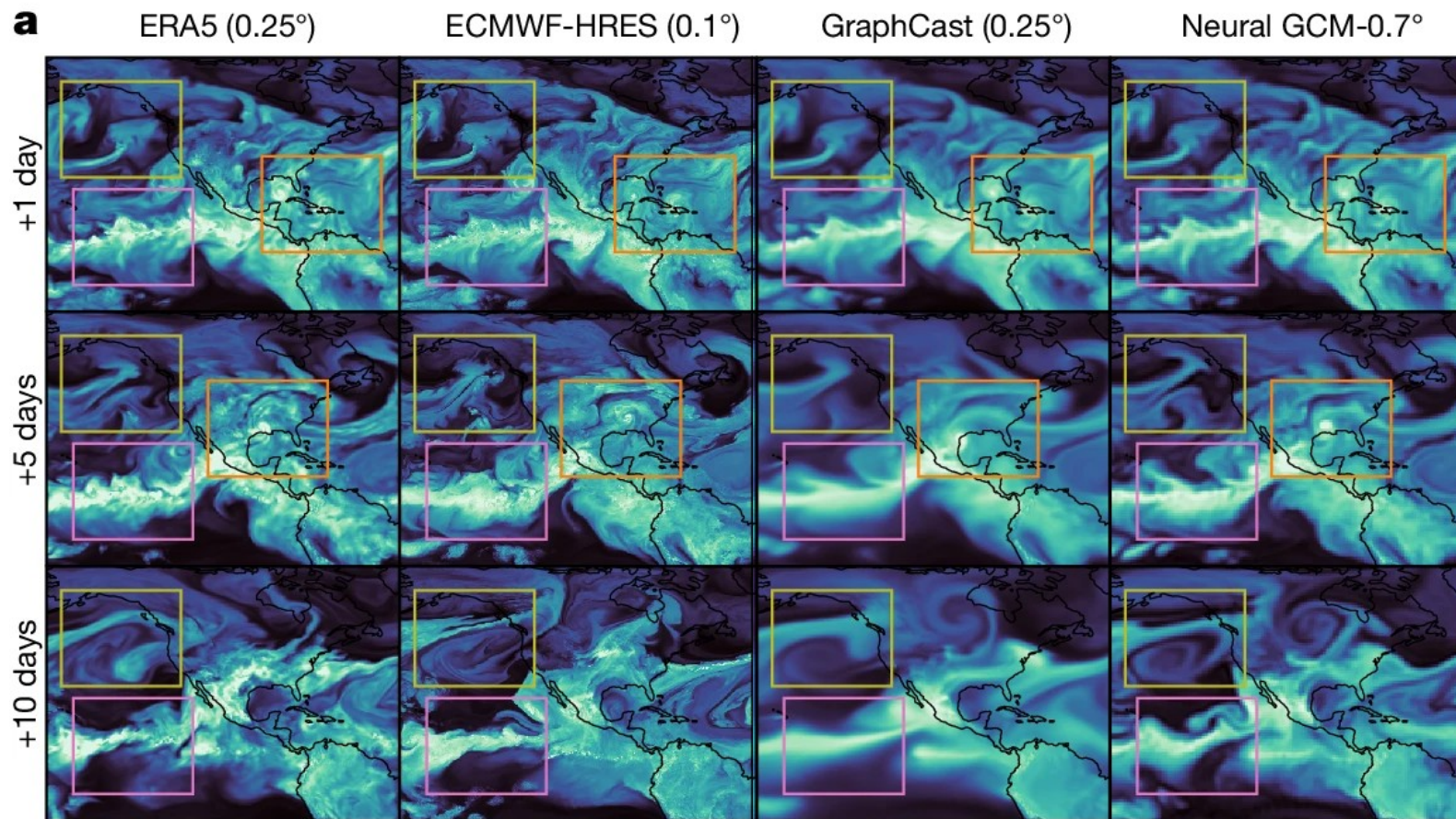
Deterministic forecast \rightarrow Mean Squared Error (MSE)

Ensemble forecast \rightarrow Continuous Ranked Probability Score (CRPS)

Finally, use Adam to minimize the loss.

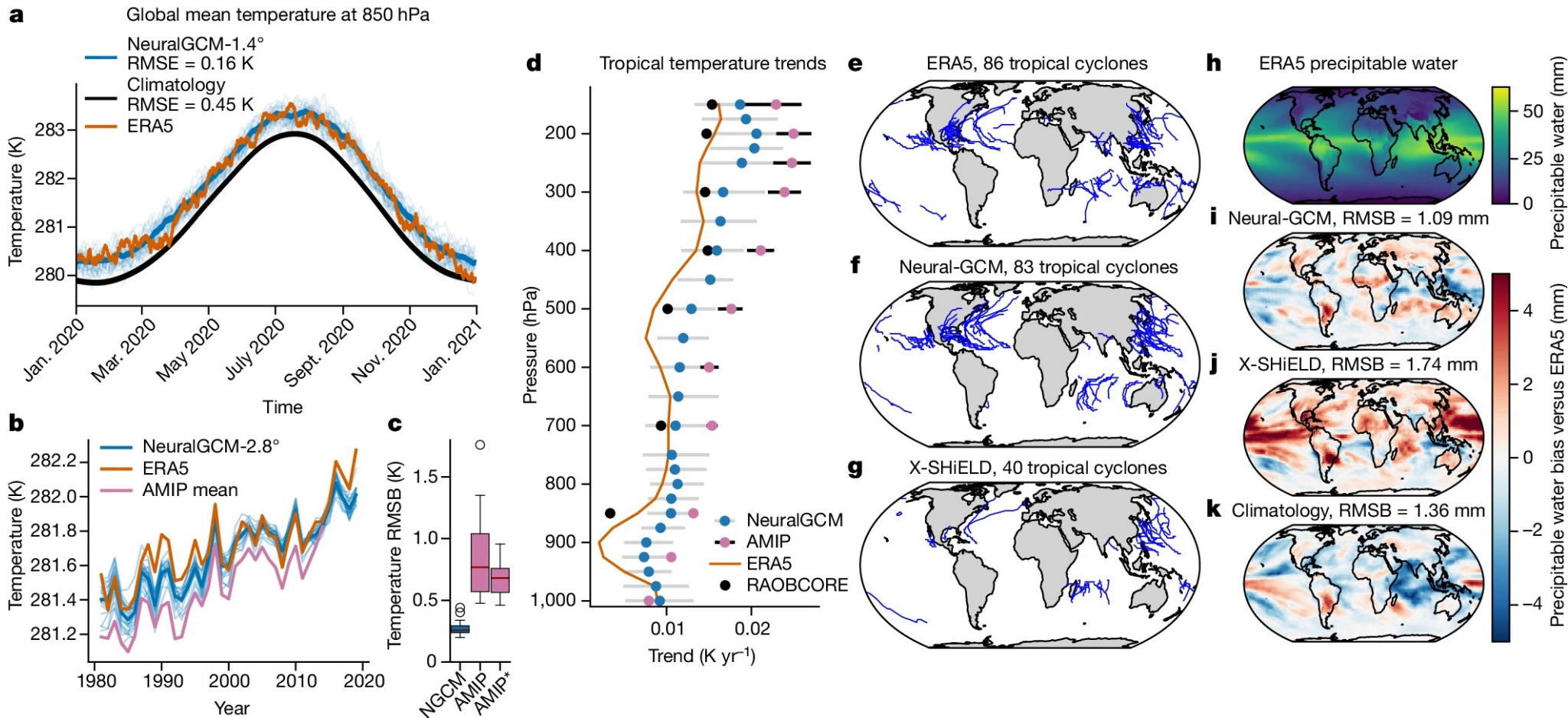
Medium-range weather forecast

Watt-Meyer et al. (2024)

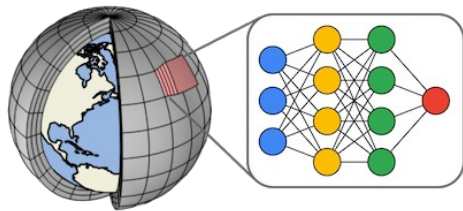


Simulations of climate

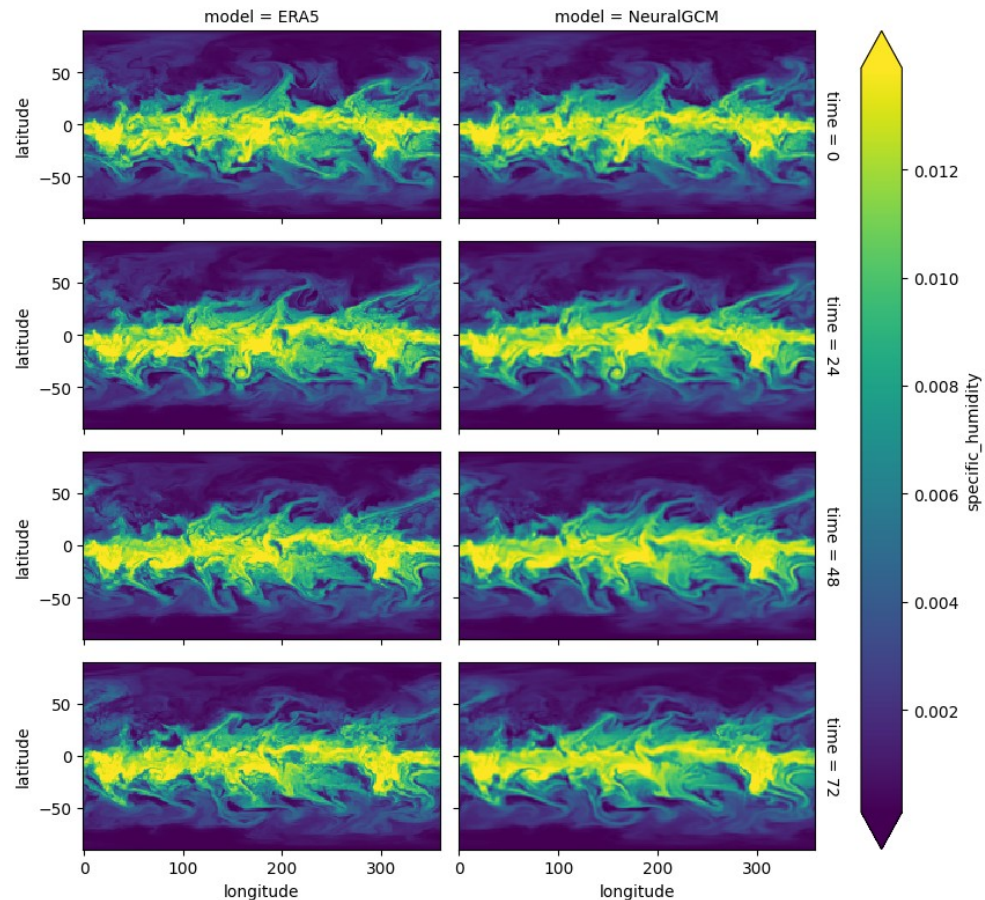
Watt-Meyer et al. (2024)



...and you can run it on your own computer*!



NeuralGCM



Loss functions

Watt-Meyer et al. (2024)

$$\begin{aligned}\mathcal{L}_{\text{Deterministic}} = & \lambda_{\text{data}} \mathcal{M}_{\text{Data}} + \lambda_{\text{spec}} \mathcal{M}_{\text{DataSpec}} + \lambda_{\text{model}} \mathcal{M}_{\text{Model}} \\ & + \lambda_{\text{spec}} \mathcal{M}_{\text{ModelSpec}} + \lambda_{\text{bias}} \mathcal{M}_{\text{MSBias}},\end{aligned}$$

$$\mathcal{M}_*(\tau) := \frac{1}{|\mathcal{T}|} \sum_{t \in \mathcal{T}} \sum_{\sigma, v} \sum_{\substack{\tau' \in \mathcal{D} \\ \tau' \leq \tau}} \rho_*(X(t \rightarrow t + \tau', v, \sigma), Y(t + \tau', v, \sigma))^2,$$

$$\mathcal{L}_{\text{CRPS}}(\tau) := \sum_{t \in \mathcal{T}} \sum_{p, v} \sum_{\substack{\tau' \in \mathcal{D} \\ \tau' \leq \tau}} [\mathcal{C}_{\text{spectral}}(t, \tau', v) + \mathcal{C}_{\text{nodal}}(t, \tau', v)].$$

$$\begin{aligned}\mathcal{C}_{\text{spectral}}(t, p, v, \tau) = & \frac{1}{2} \sum_{l, m} \left[|X(t \rightarrow t + \tau, \dots, l, m) - Y(t + \tau, \dots, l, m)| \right. \\ & + |X'(t \rightarrow t + \tau, \dots, l, m) - Y(t + \tau, \dots, l, m)| \\ & \left. - |X(t \rightarrow t + \tau, \dots, l, m) - X'(t \rightarrow t + \tau, \dots, l, m)| \right],\end{aligned}$$