CSC390 (Computer Org. & Arch.) Final Exam- Spring 2016

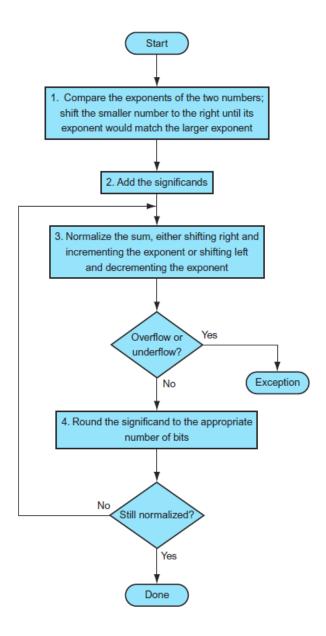


Name:

Student ID:

Q1. What decimal number is represented by the following IEEE754 single precision floating point number? (10 pts)

Q2. The following flow chart shows the binary floating-point addition algorithm for adding two floating point numbers in MIPS architecture. (10 pts)



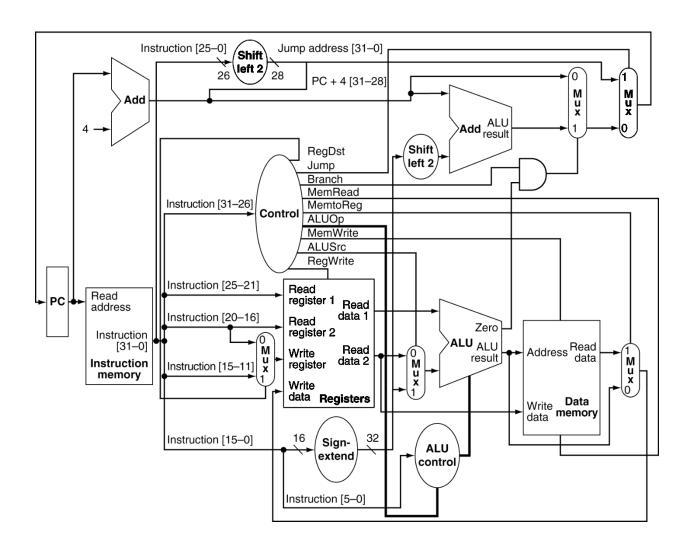
Use the above algorithm to perform addition of two binary floating-point numbers, 1001.000 and 0.0101. Clearly show the results produced in every step of the operation

Q3. Consider the following load-type instruction, Iw \$s0, 32(\$t2), and its corresponding machine code:

100011010101000000000000000100000

This machine code consists of Opcode, Source registers (rs), destination registers (rt), and 16 bits offset.

Now suppose the instruction is executed in the MIPS processor as shown in the following figure. Highlight the different control signals and multiplexer inputs that will be activated during the execution process of the above **Iw** instruction. Also indicate the buses where different portions of the machine code and the content of **32(\$t2)** can be found. (10 pts)



Q4. Show what happens when the branch is taken in the following instruction sequence, assuming the pipeline is optimized for branches that are not taken and the branch execution is moved to the ID stage:

10 add \$14, \$4, \$2 14 sub \$10, \$4, \$6 18 beq \$5, \$2, 4 22 or \$13, \$2, \$6 24 and \$12, \$2, \$6 38 lw \$8, 32(\$7)

Use figure 3 (a & b) to show what happen when a branch is taken. Specifically, **indicate the input/output values of the PC**, adders, pipeline register data and control signals.

Explain how the **beq** instruction is tested in the ID stage and what is advantage of moving the branch execution in the ID section?

(20 pts)

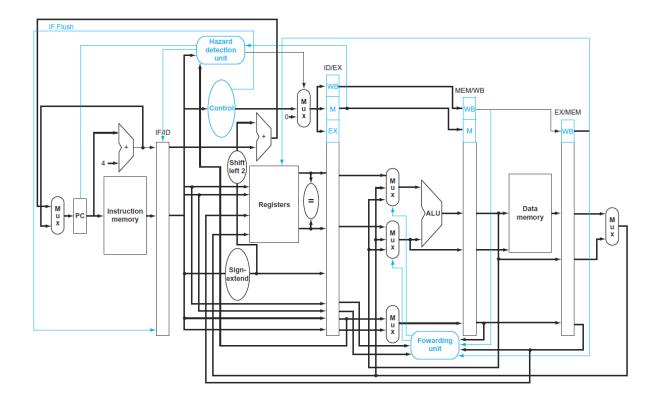


Figure 3(a)

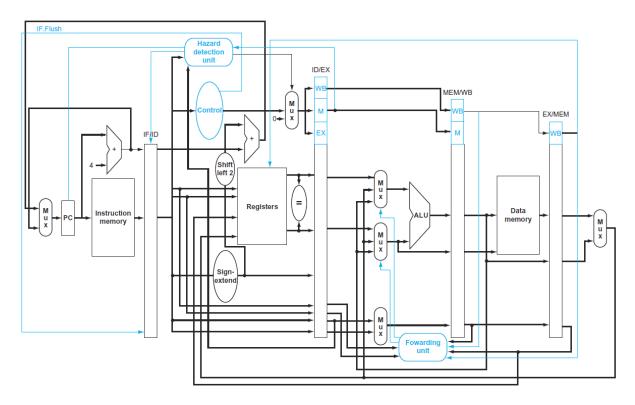


Figure 3(b)

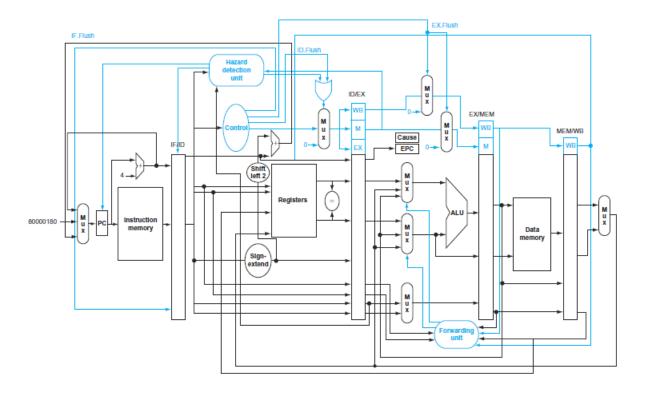
Q5. Control is the most challenging aspect of processor design: it is both the hardest part to get right and the hardest part to make fast. One of the hardest part of control is implementing exceptions and interrupts- event other than branches and jumps that change the normal flow of instruction execution. A pipeline implementation treats exceptions as another form of control hazard. For example, suppose there is an arithmetic overflow in an **add** instruction. We must flush the instructions that follow the **add** instruction from the pipeline and began fetching instruction from new address.

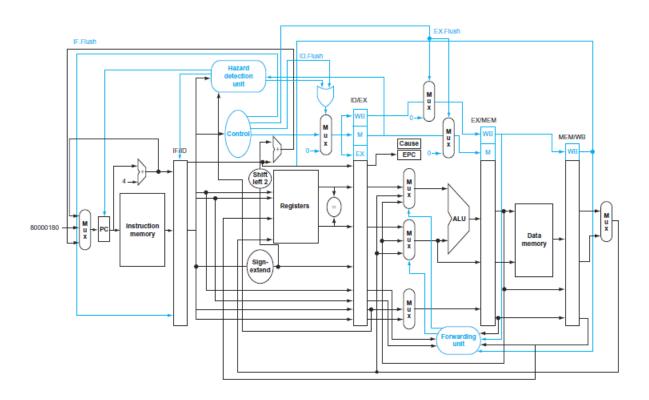
Given the following sequence of instruction,

Assume the instruction to be invoked on an exception begin like this:

80000180_{hex} lw \$20, 1000(\$0) 80000184_{hex} sw \$21, 1004(\$0)

Show what happens in the pipeline if an overflow exception occurs in the **add** instruction. Specifically, **indicate the input/output values of the PC, adders, pipeline register data, bubble (no operation) and control signals.** On Figure 4 (a & b) clearly indicate your answer. (15 pts)





Q6. Given, a magnetic hard disk has 512B sector, 75,00rpm, 2ms average seek time, 200MB/s transfer rate, 0.2ms controller overhead, idle disk. Calculate the average data read time of that disk drive. (7 pts)				

Q7. Consider a direct-mapped cache with 16 KiB of data and a block size of 16 bytes. Assume the 32-bit physical address is used to map the cache memory. Identify the memory bits that are used as index bits, tag bits and the offset bits of this direct-mapped cache memory. Also, draw a block diagram of the above cache memory clearly showing the data field, tag field, valid bit and how the hit/miss is detected using the valid bit and the tag bits. How many total bits are required for this direct-mapped cache memory?

(18 pts)

Now, consider a memory address of 20500_{dec} . To what block number does this byte address (20500_{dec}) map? (10 pts)