

University of Illinois at Urbana-Champaign
Dept. of Electrical and Computer Engineering

ECE 220: Computer Systems & Programming

Interrupts and exceptions

Memory-mapped I/O

In **memory-mapped I/O**, interaction with the I/O devices is controlled by our program

- Our program polls ready bits of I/O registers to see if the I/O devices are ready for interaction
- This leads to inefficiencies since our program effectively stalls until an I/O operation is complete

Interrupt-driven I/O

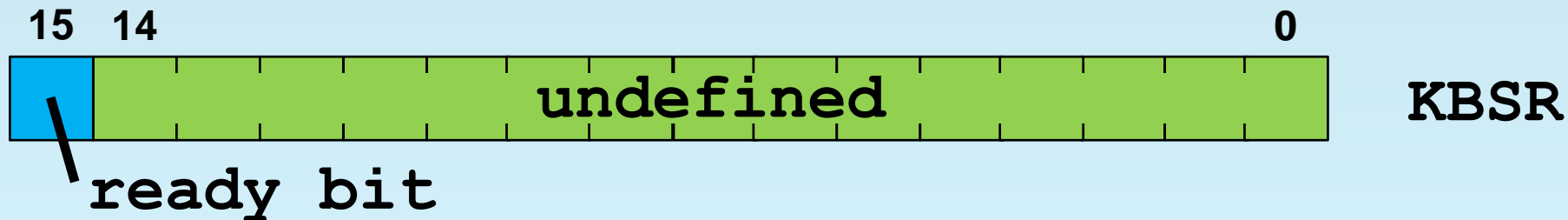
In **interrupt-driven I/O**, interaction with the I/O device is controlled by the I/O device itself

- An I/O device generates an **interrupt signal** to indicate that I/O device is ready with new I/O operation
- In response to this interrupt, the currently executed program stops its execution and the control is passed to some subroutine designed to handle the interrupt
- Once the subroutine processes the interrupt, the control is passed back to the program that was previously executed

Several things must be true for an I/O device to actually interrupt the processor

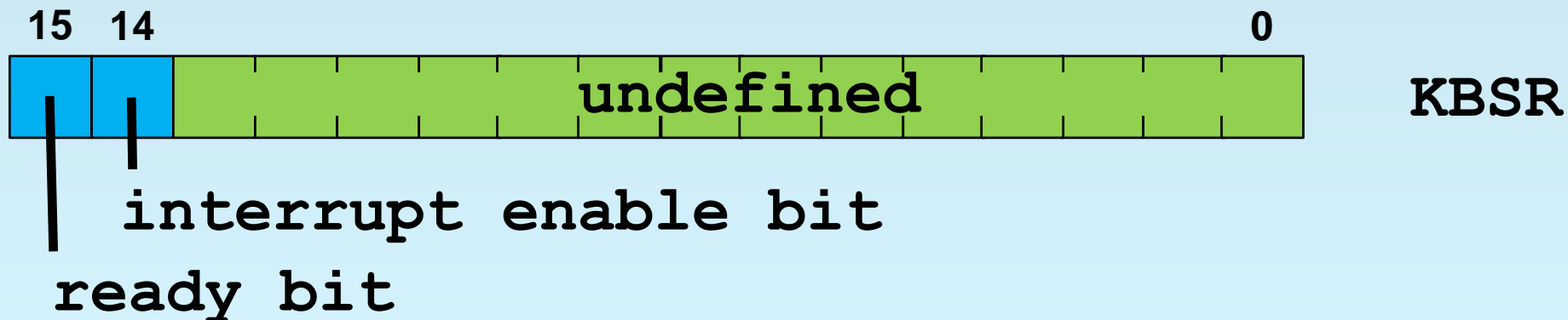
1. The device must want to request service.

This is indicated by **ready bit (KBSR[15] and DSR[15])**. If these bits are set, there is a new I/O request ready to be served



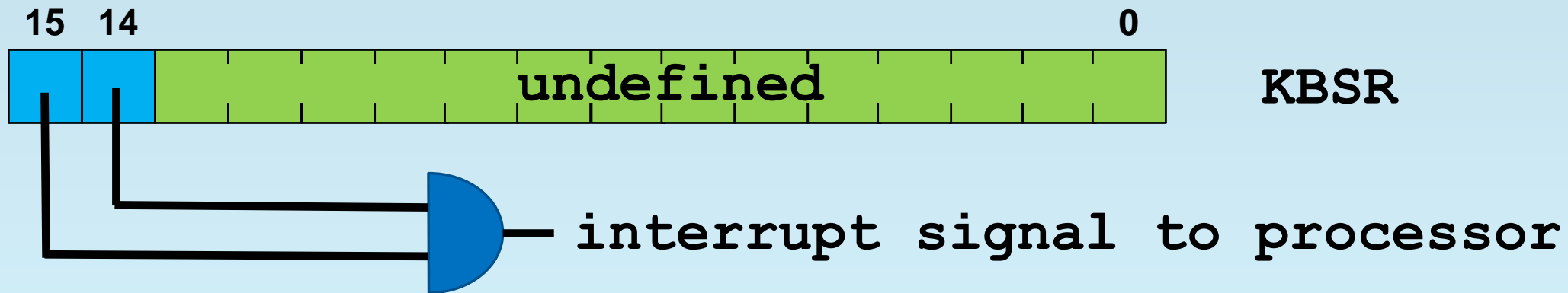
2. The device must have the right to request service.

This is indicated by an **interrupt enable bit** (KBSR[14] and DSR[14]). If such bit is set by the processor, the processor wants to give the I/O device the right to request the interrupt service



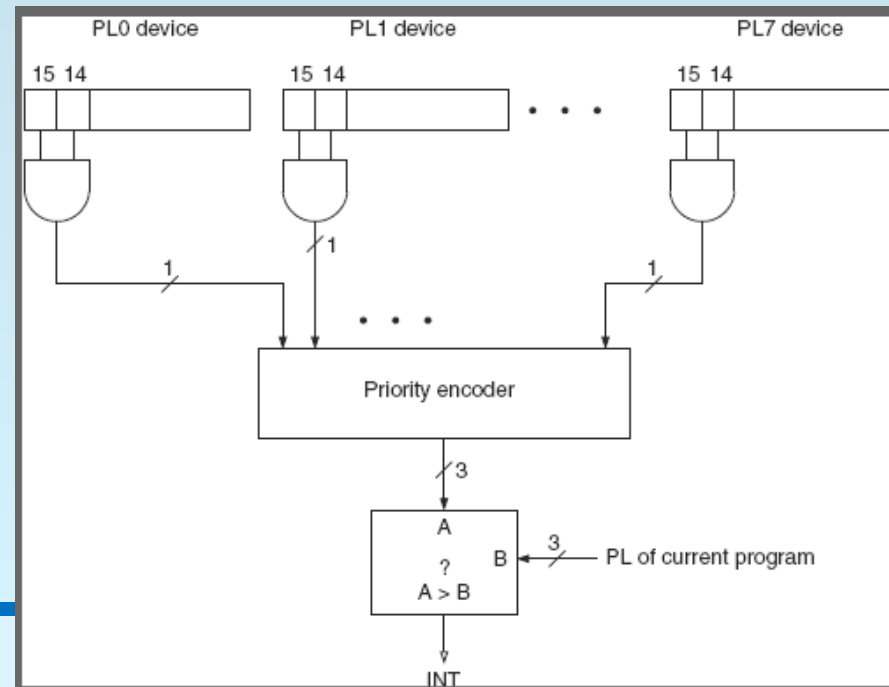
Interrupt Signal (INT)

Ready bit and interrupt enable bit together are used to generate an interrupt

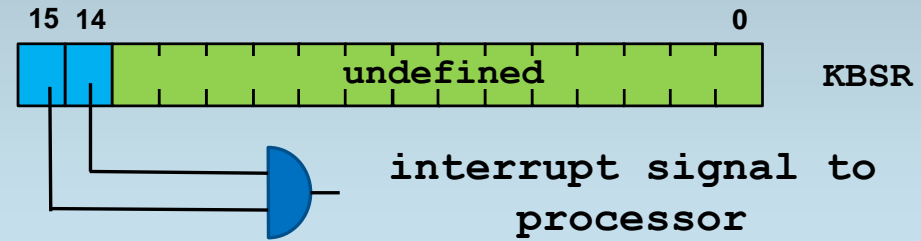
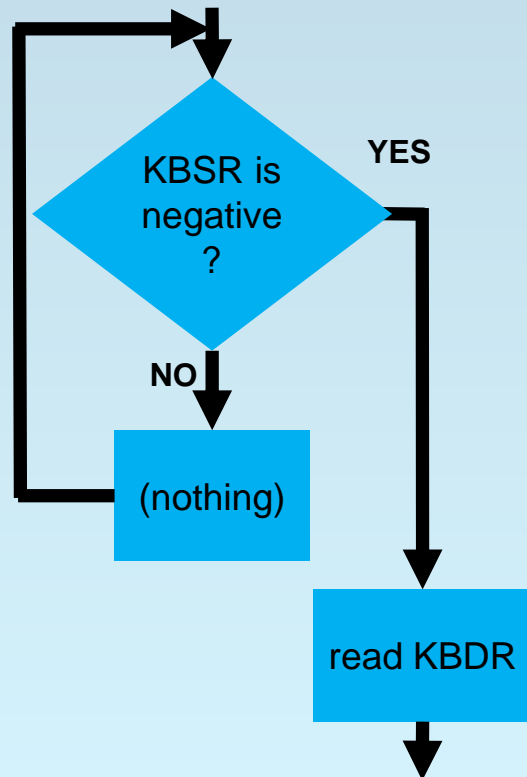
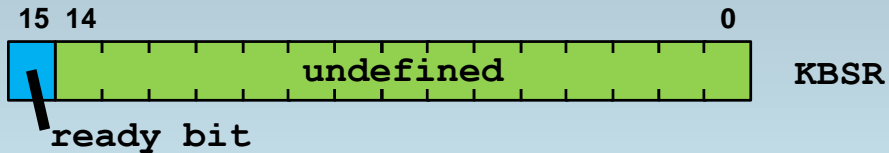


3. This request must be more urgent than the processor's current task.

A program is executed with some specified priority level, LC-3 has 8 such priority levels PL0..PL7.



Polling vs Interrupt-driven I/O



$IE = 0$

- I/O device will NOT be able to interrupt
- Have to use polling

$IE = 1$

- Interrupt-driven I/O enabled
- Interrupt request generated as soon as Ready bit sets (e.g., a key is typed)

Flow of Interrupt-driven I/O

Stage 1: **Initiate** the interrupt

- 1.1 Stop the running program on any instruction
- 1.2 Save the state of the running program
- 1.3 Generate address of the interrupt servicing subroutine

Stage 2: **Service** the interrupt

- 2.1 Transfer control to the interrupt subroutine
- 2.2 Execute the interrupt subroutine

Stage 3: **Return** from the interrupt

- 3.1 Resume right where we left off

Stage 1: Initiating the Interrupt

An I/O device generates an **interrupt signal (INT)** to indicate that I/O device is ready with a new I/O operation (e.g., a new character has been entered on the keyboard)

I/O device presents an 8-bit **interrupt vector (INTV)** which is used construct a memory address that contains the location of the interrupt handler in a **interrupt table**

Interrupt Priority

For an interrupt to be served, the request must be more urgent than the processor's current task

LC-3 priority levels are PL0-PL7

- Higher is more urgent, e.g., keyboard is PL4

LC-3 maintains an **interrupt priority** in **PSR[10:8]**

Devices wanting to interrupt also have a 3-bit priority

The interrupt will be served only when program is running at priority $< \text{PL4}$

LC-3 Interrupt Table

Each device is associated with an 8-bit vector **INTV** to index an **interrupt vector table**

Interrupt vector table is in memory between **x0100** and **x01FF**

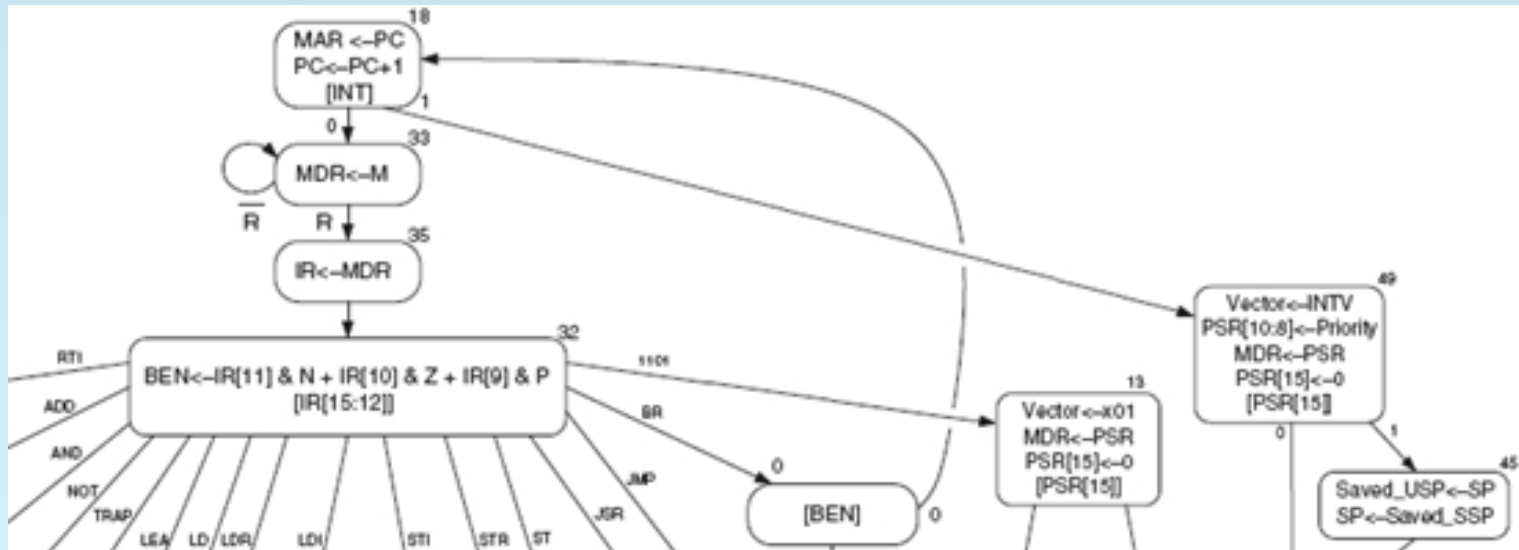
Each record in the **interrupt vector table** contains beginning address of service routine for handling interrupt

- Exception service routines (x0100-x017F)
- Interrupt service routines (x0180-x01FF)

1.1 Stopping the Execution of the Program

State 18 in LC-3 FSM is the only state in which the processor checks for interrupts

- If **INT=0** (no interrupt) go to State 33
- If **INT=1** go to State 49 (110001)

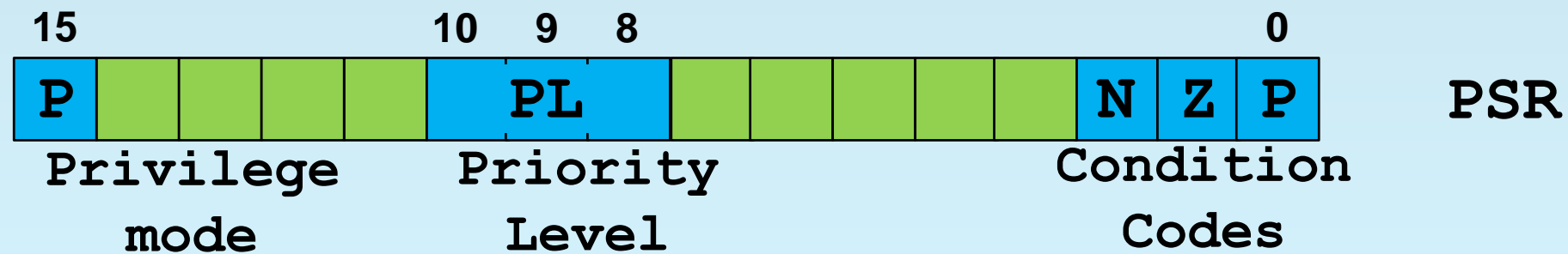


1.2 Saving the State - What

PC so that we can return to execute the next instruction after the interrupt has been served

NZP condition codes in case they are needed by a BR instruction later on

Processor Status Register (PSR)



1.2 Saving the State - Where

Supervisor Stack - a special region of memory used as the stack for serving interrupts

Supervisor Stack Pointer (SSP)

- **Saved.SSP**: Internal register to store SSP

User Stack - a stack accessed by user programs

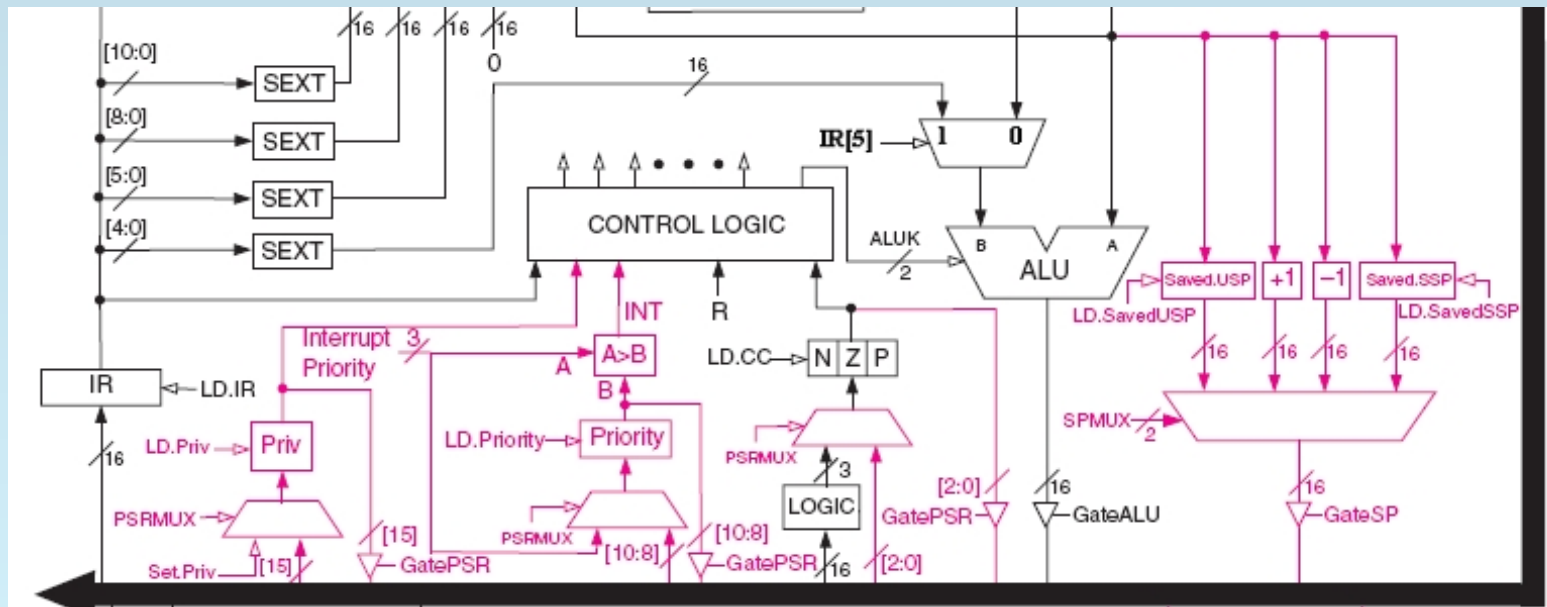
User Stack Pointer (USP)

- **Saved.USP**: Internal register to store USP

Access both stacks using R6 as the stack pointer.

When switching from **User mode** to **Supervisor mode**, save R6 to **Saved.USP**

LC-3 Hardware to Support Interrupts



1.3 Generating ISR address

Set MAR to $x01vv$, where vv is 8-bit **interrupt vector (INVT)** from interrupting device

- e.g., for keyboard $INTV=x80$, $MAR \leftarrow x0180$

Load from memory: $MDR \leftarrow MEM[x01vv]$

Set PC to MDR

LC-3 FSM for Handling an Interrupt

Load PSR to MDR in preparation for pushing into Supervisory Stack

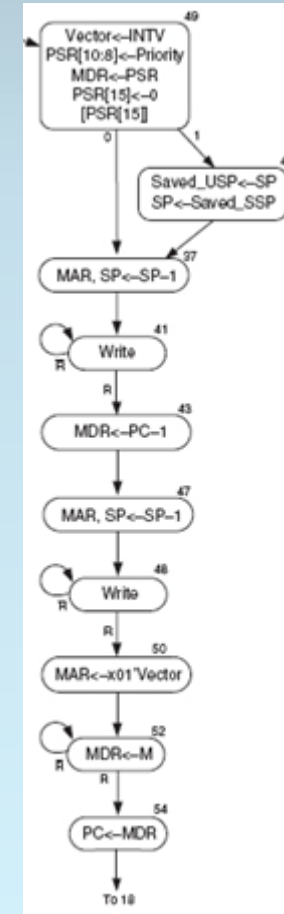
Record Priority Level and INTV provided by interrupting device

Test old PSR[15]

- If old PSR[15] = 1 then system was in User mode and hence save USP (R6) in Saved.USP, load R6 with Saved.SSP, go to state 37
- If old PSR[15] = 0 then system was in supervisory mode already

Save PSR, old PC to Supervisory Stack

Load PC with address of interrupt service routine



Stage 2: Service the interrupt

PC contains the starting address of the ISR

The ISR will execute, and the requirements of the I/O device will be served

- For example, copy KBDR into some memory location
- Callee-save for general purpose registers

Only Input from the keyboard interrupt is implemented on LC-3

Return from the Interrupt (RTI) Instruction

To return from **ISR**, we need special instruction, **RTI**

RTI is a privileged instruction

- Can only be executed in **Supervisor mode**
- If executed in **User mode**, causes an exception

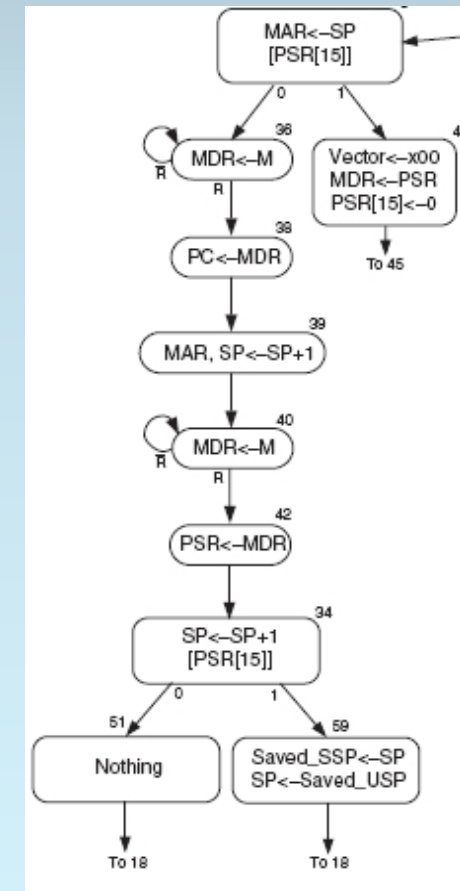
Stage 3: Return from the interrupt (RTI)

If $PSR[15] = 0$

- Restore PC and PSR
- Test old PSR[15]
 - If old PSR[15] = 1 then the system returns to User mode and hence restore USP (R6) and store SSP
 - If old PSR[15] = 0 then system continues to be in the Supervisory mode

If $PSR[15] = 1$ (Privilege Mode Exception)

- Handle condition as an privileged mode violation
- Load Interrupt Vector with starting address of Privilege mode violation
- Go to State 45 to handle interrupt as if by INT



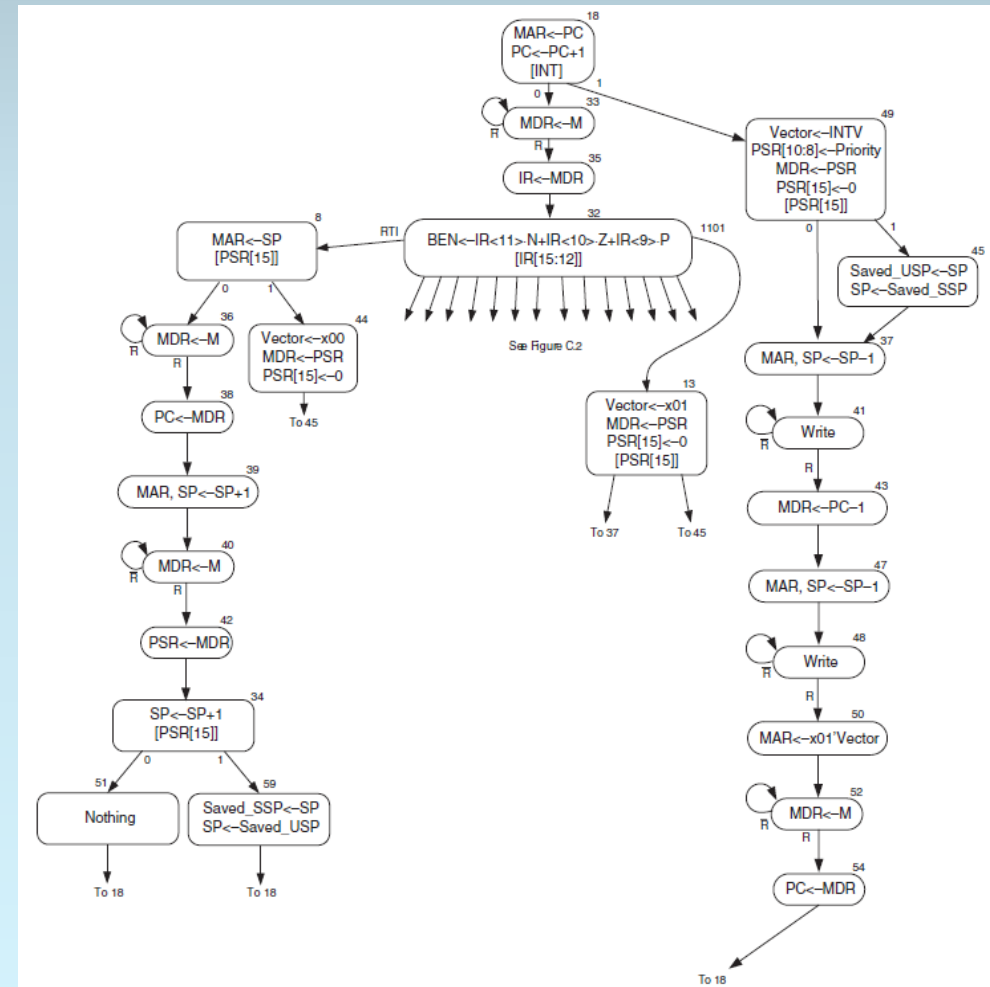
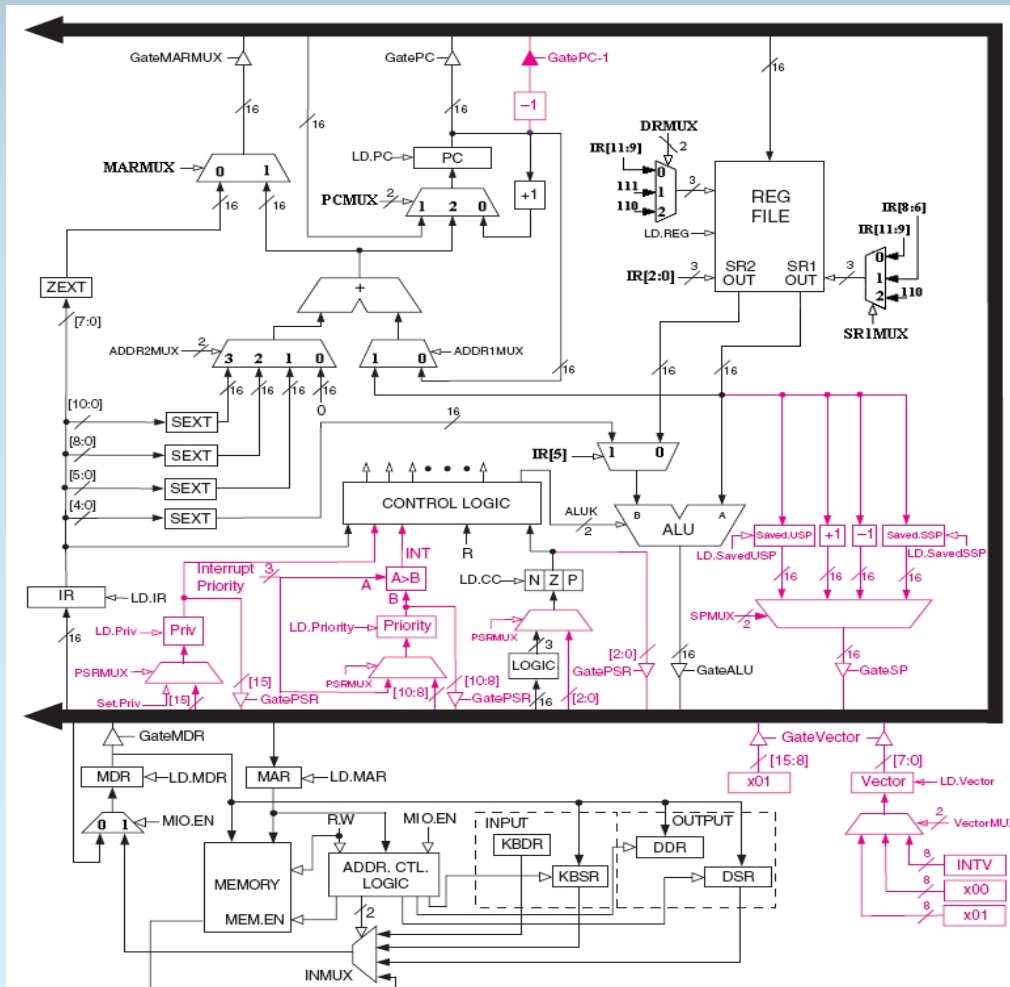
Exception Handling

Only exceptions from

- Privilege mode violation
 - If processor encounter RTI when in User mode
- Illegal opcode
 - If $IR[15:12] = 1101$ is true (unused opcode)

Exception handling is similar to interrupt handling

Extended LC-3 Datapath and FSM



Example

```
; run this with https://wchargin.github.io/lc3web
; configure interrupt subroutine
LEA R0, ISR_KB
STI R0, KBINTV ; load ISR address to INTV
LD R3, EN_IE
STI R3, KBSR ; enable IE bit of KBSR
; main code (just an infinite output loop)
AGAIN LD R0, NUM2 ; infinite loop printing '2'
OUT
BRnzp AGAIN
HALT
```


Example - continued

; Interrupt Service Routine

ISR_KB ST R0, SaveR0 ;callee-save

LDI R0, KBDR ; read a character from keyboard and clear ready bit

OUT

LD R0,SaveR0

RTI

EN_IE .FILL x4000 ; enable IE 0100_0000_0000_0000

NUM2 .FILL x0032 ; '2'

KBSR .FILL xFE00

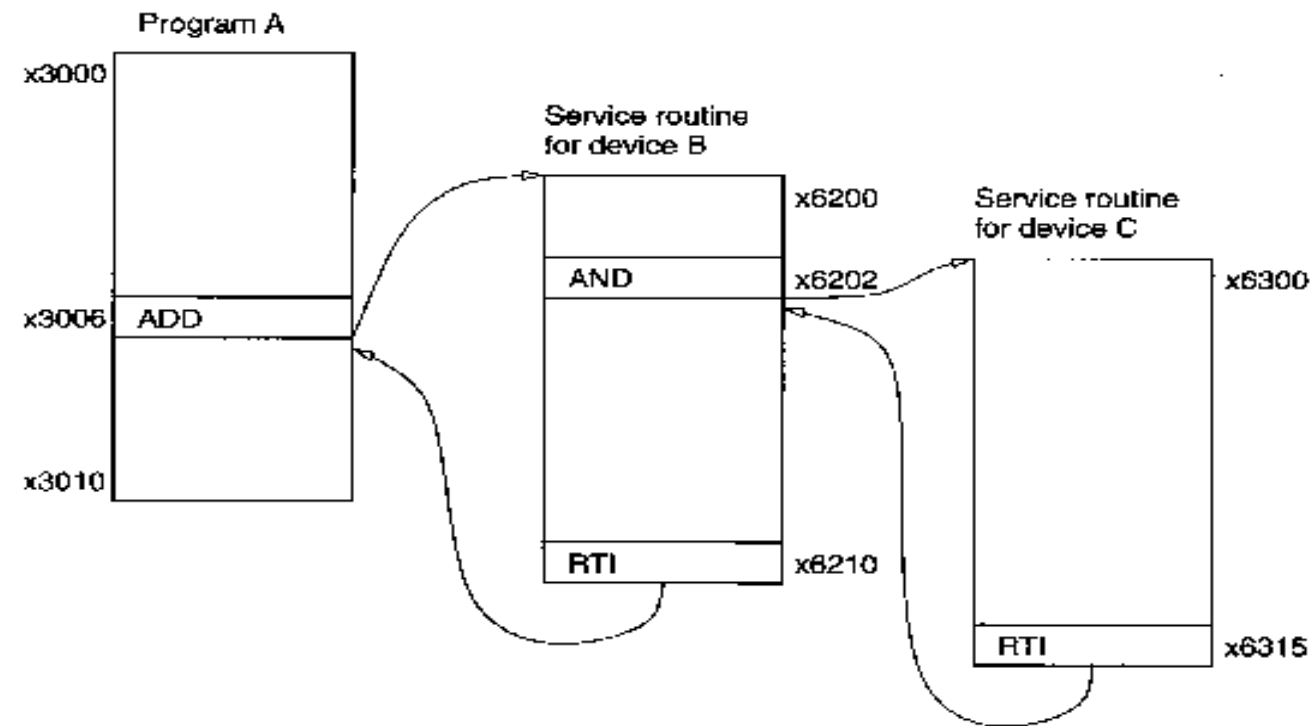
KBDR .FILL xFE02

KBINTV .FILL x0180 ; INT vector table address for keyboard

SaveR0 .BLKW #1

Nested Interrupts

Example:



Interrupt vector table

Addr	Data
x01F1	x6200
x01F2	x6300

INTV

Device B = xF1
Device C = xF2

PL: A<B<C

