Suspect Vehicle Detection using Vehicle Reputation with Association Analysis Concept

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Abstract. The suspect vehicle detection system normally compares the list of criminal license plates and vehicle license plates gathering from various sensors in order to identify the criminal or suspect vehicles. However, the traditional process of comparing those license plates utilizing the matching of alphabet character is not effective. In traditional methods, the system unable to detect the criminal/suspect vehicles if the characters of the licence plate do not totoally match with the blacklisted license plates. This paper proposes the use of reputation algorithm to detect the criminal/suspect vehicles that crossing the checkpoint which license plates match with the blacklist in the checkpoint database. In addition, we also use association analysis concept to detect the vehicles crossing the checkpoint that might relate to the criminal activity records. Our method can detect the suspect vehicles with forged license plate by using color, brand and type of the vehicles instead of only the license plate number matching method. These two techniques use a blacklist of criminal vehicles and criminal activity recorded in a criminal report database of Defence Technology Institute (DTI), Thailand, to help facilitate the detection process. From our extensive experiments, the results show that the reputation algorithm and the association analysis concept can improve the detection capability of the suspect vehicle detection system.

Keywords: Reputation Algorithm, Association Analysis, Suspect Vehicle Detection

1 Introduction

Reputation concept is a technique to classify object that commonly applied to various systems to make effective automatic detection, such as vehicle-to-vehicle communication [10–12], filtering email spam [13–16], ecommerce [17–19], etc. In addition, vehicle detection by only data classification process may be insufficient. Therefore, the association analysis process should be used together to increase the detection accuracy. The traditional suspect vehicle detection process of comparing criminal license plates and vehicle license plates utilizing the matching of alphabet character is not effective. If the characters do not

match any one character, the system can not detect criminal or suspect vehicles with fake license plate.

In this paper, we propose the approach using reputation concept to detect criminal vehicles crossing the checkpoint whose license plates match the blacklist. In addition, we use association analysis concept to detect the suspect vehicles which license plates do not match the blacklist, however this method uses color, brand and type of vehicles matching the blacklist to identify the vehicles that potentially involve in criminal activity. The aim of this work is to improve the detection capability of suspect vehicle detection system.

In the next section, we discuss background information and previous studies using reputation algorithm and association analysis concept. Section III explains the research testbed and research design. Experimental results are shown in Section IV, and discussed in Section V. Section VI concludes and presents future directions.

2 Literature Review

The literature reviews of related our research is divided into three subsections.

2.1 The Vehicle Recognition and Detection

There are several research works about efficient vehicle detection and classification. For example, Chen et al. [1] propose two processes to segment moving road vehicles and classify those vehicles in terms of type (car, van and heavy goods vehicle) and dominant colour (black, white, red). For the segmentation, they have improved the Gaussian mixture model (GMM) approach proposed by Friedman and Russell [2] and refined for real-time tracking by Stauffer and Grimson [3] with a multi-dimensional smoothing transform. For vehicle classification [1], they use a kernelised support vector machine (SVM) to classify vehicle types and colours. The classification process uses size, width, aspect ratio and solidity of the foreground vehicle to recognise vehicle type and uses 8-bin 3D colour histogram as the vector for SVM classification to recognise vehicle colour. Hsieh et al. [4] propose a new symmetrical Speeded-Up Robust Features (SURF) descriptor applied to vehicle make and model recognition (MMR) system to detect vehicles and recognize their make and model.

In the field of suspect vehicle detection, Kaza and Chen [5] research the border safety to help Customs and Border Protection (CBP) agents, USA, to search vehicles entering the country at land borders that potentially involved in criminal activity. They can identify the criminal or suspect vehicles and other partner vehicles that crossing together and potentially involved in criminal activities. This literature review use association analysis by using mutual information (MI) and modify the MI formulation to incorporate domain heuristics by using cross-jurisdictional criminal data from border-area jurisdictions. The heuristic-enhanced MI performs significantly batter than classical MI [6] in identifying partner of potentially criminal or suspect vehicles. Umedu et al. [7] propose the

dangerous-vehicle-detection protocol (DVDP) to detect dangerous vehicles on roads and highways that violate the permitted speed limit. In DVDP, they use ad hoc communications to forward hop-by-hop warning information (including its position, speed, time, and collected IDs). When a vehicle receives warning information, it will start to observe its surrounding vehicle and it is estimated the speed. If the estimated speed exceeds the permitted speed, such vehicle is considered as a suspected vehicles and the updated warning information is then further propagated to vehicles ahead. The suspected vehicle will be considered as a dangerous vehicle by the suspected vehicle where multiple other vehicles witnessed the speed violation. Kaza et al. [8] use the combination analysis of law enforcement information and data generated by vehicle license plate readers at international borders to identify suspicious vehicles and people at ports of entry. They analyze the topological characteristics of criminal activity networks (CANs) of individuals and vehicles in a multiple jurisdiction scenario. The vehicular relationships and border-crossing information can aid in securing the border and transportation infrastructure. Furthermore, Thiel [9] use The VIRTUAL GUARD system for detecting potential criminal activity in public areas. This system will alarm when the observed activities of particular vehicles and pedestrians match any of the pre-defined suspect behaviour criteria programmed into the system. In addition, the system uses computer-controlled Pan Tilt Zoom (PTZ) cameras to obtain close-up video recordings of any vehicles and pedestrians at the scene.

Although the above proposals are useful for vehicle detection to detect the suspect vehicle, we focus on the detection of suspect vehicles with fake license plate. Therefore, we review studies about reputation algorithm and association analysis concept which we will discuss in the next subsection.

2.2 Reputation Algorithm

The concept of reputation has been used to classify objects in a domain or community. An object with a higher reputation score gain more attraction than an object with a lower reputation score. Reputation concept has been applied to the several problems in vehicle-to-vehicle communication system. In [10], it works well for allowing evaluation of message reliability in vehicular ad hoc network (VANET) environments. If the vehicle that generates this message has a sufficiently high reputation, A message is considered reliable. Dhurandher et al. [11] propose vehicular security to detect and isolate malicious nodes in VANET. Ayday et al. [12] develop the Iterative Trust and Reputation Mechanism (ITRM) for DELAY-TOLERANT Networks (DTNs) which enables every node to evaluate other nodes based on their past behavior. ITRM takes advantage of an iterative mechanism to detect and isolate the malicious nodes from the network even in the presence of the attacks on the trust and detection mechanisms.

The reputation concept is also be applied to other practical applications. For example, Xie and Wang [13] present a Collaboration-based Autonomous email REputation (CARE) system to rate both spam domains and nonspam domains

in an autonomous manner. Altman and Tennenholtz [17] uses the axiomatic approach to deal PageRank, the most famous page ranking algorithm.

We propose the use of this concept to identify criminal vehicles that crossing the checkpoint. A high reputation score represents a criminal vehicle, whereas low reputation score represents a normal vehicle.

2.3 Association Analysis Concept

Association analysis concept has been widely applied in various systems in previous research. For example, the concept of mutual information have been used to estimate word association norms between words in English texts [20] and to extract a triple of binary strings a, b, c [21]. Kaza et al. [6] used association analysis by using the concept of mutual information measurement to identify potentially target vehicles that cross the border frequently with the vehicles which are involved in criminal activity. In addition, association analysis by using the idea of association rule has also been used to automatically detect the ischemic beats in long duration electrocardiographic (ECG) recordings [22] and to extract valuable industrial data from massive data storage [23]. G. Miao et al. [24] used a new ranking algorithm, based on Latent Association Analysis (LAA) by considering the semantic associations among document pairs to rank target documents using the latent factor.

3 Research Testbed and Design

3.1 Research Testbed

The testbed for this research includes the blacklist of the criminal vehicle data set and the criminal activity data set obtained from criminal report database of Defence Technology Institute (DTI), Thailand. Moreover, this testbed consists of the lists of the checkpoint crossing data set from various sensors includes the license plate, vehicle brand, vehicle color, vehicle type, checkpoint, crossing date and time. The checkpoint crossing data set is divided into two categories: 1) The one year records. 2) The real time checkpoint crossing records in three months. Details of these data sets are shown in Table 1.

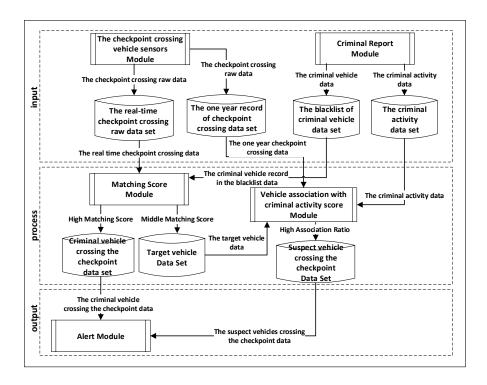
3.2 Research Design

Fig. 1 shows the research design and the evolution process of criminal or suspect vehicle detection at the checkpoint. This diagram is divided into three sections:

1) Input section consists of the real time checkpoint crossing data set in three months, the one year records of checkpoint crossing data set, the blacklist of criminal vehicle data set, and criminal activity data set. 2) Processing section consists of matching score module to detect the criminal vehicles that crossing the checkpoint and vehicle association with criminal activity score module to detect the suspect vehicles that crossing the checkpoint. In this research, we focus

Table 1. Summary of Input Data Set

InputDataSet	Summary
Number of the criminal vehicles in blacklist	4801
Criminal activity records	1972
The one year checkpoint crossing records	992017
The real time checkpoint crossing records in three months	281089
Number of the vehicles crossing the checkpoint in three months	90563
Number of criminal vehicles crossing the checkpoint in three months	513



 ${\bf Fig.\,1.}$ Research design and process diagram.

on the processing section shown in Fig.1 which is explained in the following subsections. 3) Output section serves as the alert of the criminal vehicle or suspect vehicle if the system detects the criminal vehicles or suspect vehicles that crossing the checkpoint.

```
MODULE: MatchingScore
  FOR i := 1 TO n STEP 1 DO
     IF (VCDataLicenseplate = CVDataLicenseplate;) THEN
        Score = Score + (1 * WLicenseplate)
     END IF
     IF (VCDataColor = CVDataColor i) THEN
        Score = Score + (1 * WColor)
     END IF
     IF (VCDataBrand = CVDataBrand<sub>i</sub>) THEN
        Score = Score + (1 * WBrand)
     END IF
     IF (VCDataType = CVDataType i) THEN
        Score = Score + (1 * WType)
     END IF
     IF (Score > HScore) THEN
        Call AlertModule
     ELSE IF (Score > LScore) THEN
        Call CriminalActivityScore
     END IF
  END FOR
END.
```

Fig. 2. Matching score module algorithm.

Matching Score Module Matching Score Module is criminal vehicle detection process. First, we define attributes for classification and assign weight to each of the attributes. Higher weight is assigned to higher significant attributes. In this research, we select the license plate, vehicle color, vehicle brand, and vehicle type to be used in the classification and we assign higher weight to license plate than vehicle color, vehicle brand, and vehicle type. The system compares the real time checkpoint crossing records in three months and criminal vehicle records in the blacklist by using following attributes: license plate, vehicle color, vehicle brand, and vehicle type. Subsequently, it computes the sum of all of the weighted attribute. The weighted sum is a single number to compare with the threshold. If weighted sum is greater than the high score threshold, referred to as High Matching Score, vehicle crossing the checkpoint will be considered as criminal vehicle and will be processed in the Alert Module. If weighted sum is less than the high score threshold and also greater than the low score threshold, referred

to as Middle Matching Score, vehicle crossing the checkpoint will be considered as target vehicle and will be processed in the Vehicle Association with Criminal Activity Score Module.

Table 2. Variable Description for Matching Score Module

Variables	Description
VCDataLicenseplate	The license plate of vehicle that crossing the checkpoint.
VCDataColor	The color of vehicle that crossing the checkpoint.
VCDataBrand	The brand of vehicle that crossing the checkpoint.
VCDataType	The type of vehicle that crossing the checkpoint.
CVDataLicenseplate	The license plate of the criminal vehicle.
CVDataColor	The color of the criminal vehicle.
CVDataBrand	The brand of the criminal vehicle.
CVDataType	The type of the criminal vehicle.
WLicenseplate	The weight of license plate.
WColor	The weight of vehicle color.
WBrand	The weight of vehicle brand.
WType	The weight of vehicle type.
Score	The sum of all of the weighted attribute.
HScore	The high score threshold.
LScore	The low score threshold.

High Matching Score is calculated by the following attribute-matching condition: at least license plate matches with the blacklist. Middle Matching Score is calculated by the following attribute-matching condition: vehicle color and vehicle brand and vehicle type match with the blacklist. Algorithm of Matching Score Module is shown in Fig. 2. Table 2 summarizes the notation for Matching Score Module.

Vehicle Association with Criminal Activity Score Module This module is a suspect vehicle detection process using association analysis concept to identify the vehicles that are potentially involved in criminal activities. We determine the number of all the one year checkpoint crossing lists of target vehicle by considering the matching of license plate, vehicle color, vehicle brand, and vehicle type. Consequently, we analyze the relationship between each of the criminal

activity with all the one year checkpoint crossing records of target vehicle, and we further restricted the set to contain only checkpoint crossing records of target vehicle that already crossed the checkpoint near the location, date, and time of criminal activities. Such set can be indicated the number of involvement in criminal activities of target vehicle. Then we can calculated the association ratio by using in (1) by computing the fraction of number of involvement in criminal activities of target vehicle and number of the checkpoint crossing records of target vehicle to compare with the defined threshold.

$$\alpha = \frac{\nu}{\varsigma} \tag{1}$$

where

 $\alpha = association ratio.$

 ν = number of involvement in criminal activities of target vehicle.

 $\varsigma = \text{total of the 1 year checkpoint crossing records of target vehicle.}$

If the vehicles with higher ratio than the threshold, they are considered potential suspect vehicles, and then the vehicle data will be processed in the Alert Module. Algorithm of Vehicle association with Criminal Activity Score Module is shown in Fig. 3. Table 3 summarizes the notation for Vehicle Association with Criminal Activity Score Module.

```
MODULE: VehicleAssocCriminalActScore
  ActivityLoop = 0
  FOR x := 1 TO n STEP 1 DO
     FOR i := 1 TO m STEP 1 DO
        IF (TVData = VCHData i) THEN
          IF (ActivityLoop = 0) THEN
            NTVLog = NTVLog + 1
          IF (CAChcekpoint x = VCHCheckpoint i) &
           (VCHTime x < mxTimeRang) & (VCHTime x > mnTimeRang) THEN
             NData = NData + 1
            NData = NData + 0
          END IF
        END IF
     END FOR
     ActivityLoop = 1
  END FOR
  IF ((NData / NTVLog) > HScore) THEN
     Call AlertModule
  END IF
END.
```

Fig. 3. Vehicles association with criminal activity score module algorithm.

Table 3. V	ariable	Description	for	Vehicle	Association	with	Criminal	Activity	Score
Module									

Variables	Description	
ActivityLoop	The variable that used to check first iteration in x loop.	
TVData	The target vehicle data includes license plate, vehicle color,	
	vehicle brand, and vehicle type.	
VCHData	The one year record of checkpoint crossing data set includes	
	license plate, vehicle color, vehicle brand, and vehicle type.	
NTVLog	Total of one year checkpoint crossing records of target vehicle.	
CAChcekpoint	The checkpoint near the location of the criminal activity.	
VCHCheckpoint	The checkpoint that target vehicle has ever passed.	
VCHTime	Date and time of the checkpoint crossing record.	
mxTimeRang	Date and time of the criminal activity plus 1 hour.	
mnTimeRang	Date and time of the criminal activity minus 1 hour.	
NData	Number of involvement in criminal activities of target vehicle.	
HScore	The defined threshold.	

4 Experimental Results

To analyze system performance, there are four factors for analysis as follows:

1) True positive (TP) is the number of the criminal and suspect vehicles that are analyzed as the criminal and suspect vehicles. 2) True negative (TN) is the number of the normal vehicles that are analyzed as the normal vehicles. 3) False positive (FP) is the number of the normal vehicles that are analyzed as the criminal and suspect vehicles. 4) False negative (FN) is the number of the criminal and suspect vehicles that are analyzed as the normal vehicles. Such factors can be calculated by using this formula:

$$\label{eq:total_relation} \text{TP Rate} = \frac{\text{NofCSVDetectedAsCSV}}{\text{TofCSV}}$$

$$\label{eq:fn_rate} \text{FN Rate} = \frac{\text{NofCSVDetectedAsNV}}{\text{TofCSV}}$$

$$\label{eq:total_rate} \text{TN Rate} = \frac{\text{NofNVDetectedAsNV}}{\text{TofNV}}$$

$$\text{FP Rate} = \frac{\text{NofNVDetectedAsCSV}}{\text{TofNV}}$$

$$\mbox{Detection Accurate Rate} = \frac{\mbox{TP Rate} + \mbox{TN Rate}}{2}$$

Table 4. Variable Description for The System Performance Analysis

Variables	Description	
NofCSVDetectedAsCSV	The number of the criminal and suspect vehicles that	
	are detected as the criminal and suspect vehicle.	
TofCSV	The total of all the criminal and suspect vehicles.	
NofCSVDetectedAsNV	The number of the criminal and suspect vehicles that	
	are detected as the normal vehicle.	
${\bf Nof NV Detected As NV}$	The number of the normal vehicles that are detected	
	as the normal vehicle.	
TofNV	The total of all the normal vehicles.	
${\bf Nof NV Detected As CSV}$	The number of the normal vehicles that are detected	
	as the criminal and suspect vehicle.	

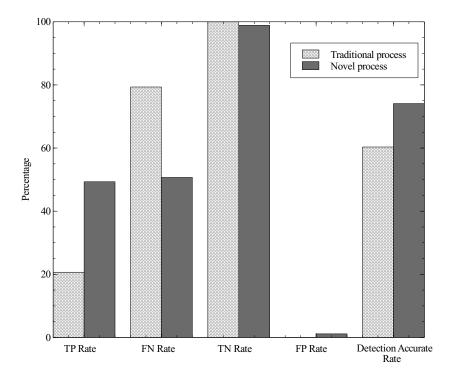
Table 5. Summary of The Vehicles Detected in Three Months

Vehicle Detection	Traditional Process	Novel Process
Criminal Vehicles	106	106
Suspect Vehicles	0	147

Table 4 summarizes the notation for The System Performance Analysis. The results obtained from the vehicle detection tests in three months is shown in Table 5. As a results, this novel process can detect 147 suspect vehicles more than the traditional process or equal to 138.68% higher. Fig. 4 and Table 6 show

 ${\bf Table~6.}$ The Results of The System Performance Analysis

AnalysisRate	Traditional Process	Novel Process
TP Rate	20.66%	49.32%
FN Rate	79.34%	50.68%
TN Rate	100%	98.87%
FP Rate	0%	1.13%
Detection Accurate Rate	60.33%	74.09%



 ${\bf Fig.\,4.}$ The results of the system performance analysis.

the results of the system performance analysis of the novel process that have the criminal or suspect vehicle detection rate is equal to 49.32% and detection accurate rate is equal to 74.09% which is an acceptable accurate rate. These results show that this technique can improve the detection capability of the suspect vehicle detection process.

5 Discussion

The novel process still gain higher FP rate than the traditional process because using only color, brand and type of vehicles matching the blacklist can not separate the normal vehicles out of the target vehicles. However, we intend to improve the normal vehicle separation process by using the target vehicle data from Matching Score Module matching the vehicle database of Department of Land Transport (DLT), Thailand. If the target vehicle data do not match the DLT database, it is considered as the illegal vehicles and processed in the Vehicle Association with Criminal Activity Score Module. In addition, the use of the DLT database can improve the FN rate.

6 Conclusion and Future Directions

This research proposes the use of vehicle reputation in couple with association analysis concept to improve the detection capability of suspect vehicle detection system. The testing results from the previous section shows that the blacklist of criminal vehicles and criminal activity records obtained from criminal report database of DTI can be used to enhance the detection capability of suspect vehicle detection system and can address the limitations existing in the traditional process. In the future work, we plan to test this algorithm with the real scenario to compare with the formula in this research. In addition, we intend to explore the behavior of criminal vehicles crossing the checkpoint. This will allow us to analyze the crossing the checkpoint patterns of criminal vehicles and improve the suspect vehicle detection. Additionally, we intend to extend the suspect vehicle detection by using the vehicle crossing the checkpoint matching the vehicle database of DLT. This can be used to detect the illegal vehicles for reducing error of the normal vehicles detected as the suspect vehicles.

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