Zum EEPROM (Zowi):

::	:
[9]	1st letter for custom robot and letter forcustom robot name (default value #) name (default empty)
[5]	1st letter for custom robot name (default value #)
[4]	empty
[2]	new home for right foot
[2]	new home for left foot
[1]	new home for right hip
[0]	new home for left hip

Database table columns (local and remote have same structure):

ţ <u>i</u>	id timestamp	serial_ number	e_left_hip e_right	e_right_hip	e_left_foot	t_hip e_left_foot e_right_foot state h_left_hip h_right_hip h_left_foot h_right_foot	state	h_left_hip	h_right_hip	h_left_foot	h_right_foot
id time stamp		Zum SN	calibration calibrati joint error joint err	on	calibration calibration joint error		OK/ new NOK hom	OK/ new NOK home	new home position	new home new home new home position	new home position