Zum EEPROM (Zowi):

[0]	[1]	[2]	[3]	[4]	[5]	[6]	...
new home for left hip	new home for right hip	new home for left foot	new home for right foot	empty	1st letter for custom robot name (default value #)	2nd letter for custom robot name (default empty)	...

Database table columns (local and remote have same structure):

id	timestamp	serial_number	e_left_hip	e_right_hip	e_left_foot	e_right_foot	state	h_left_hip	h_right_hip	h_left_foot	h_right_foot
id	time stamp	Zum SN	calibration joint error	calibration joint error	calibration joint error	calibration joint error	OK/ NOK	new home position	new home position	new home position	new home position