① Form Factor

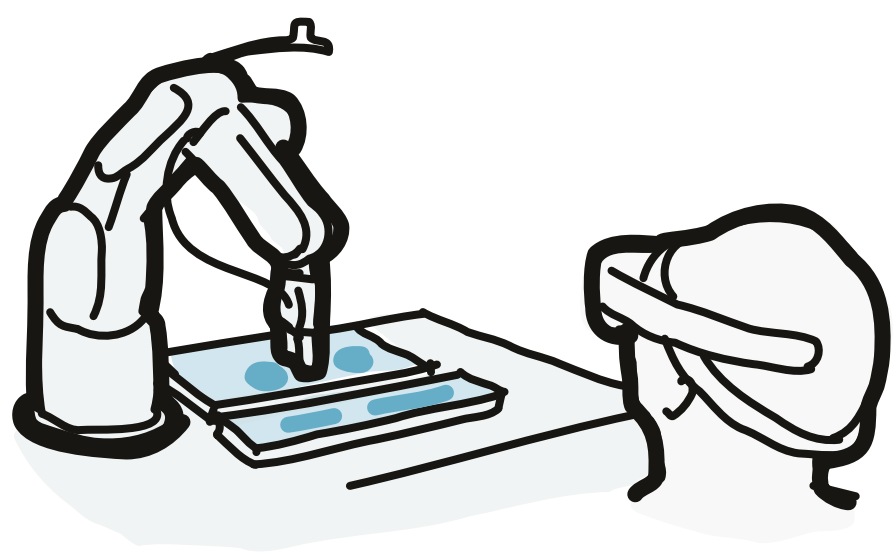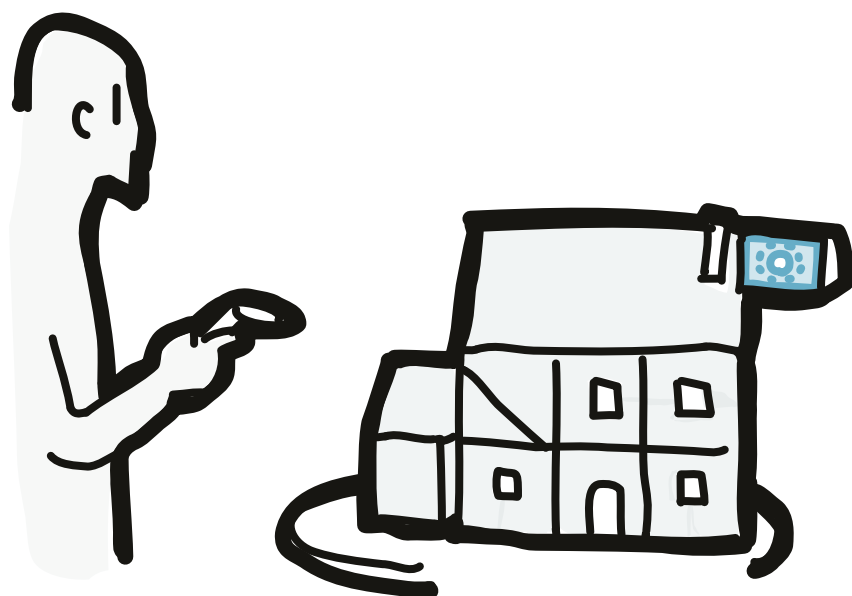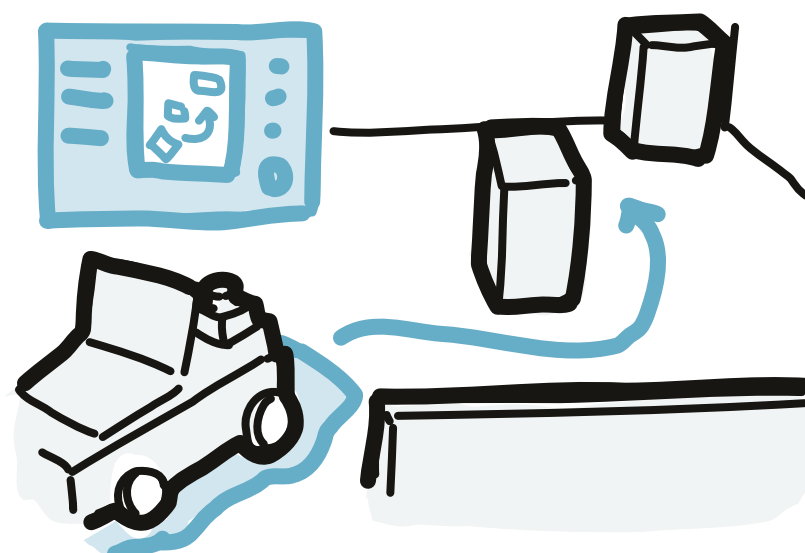**Robotic Arms**
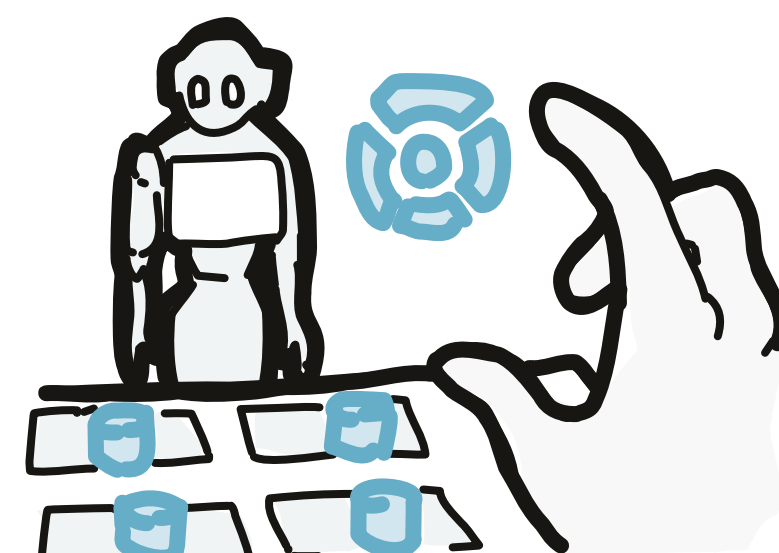[31, 49, 77, 81, 106]

Drones
[31, 49, 77, 81, 106]

Mobile Robots
[31, 49, 77, 81, 106]

Humanoid Robots
[31, 49, 77, 81, 106]

Vehicles
[31, 49, 77, 81, 106]
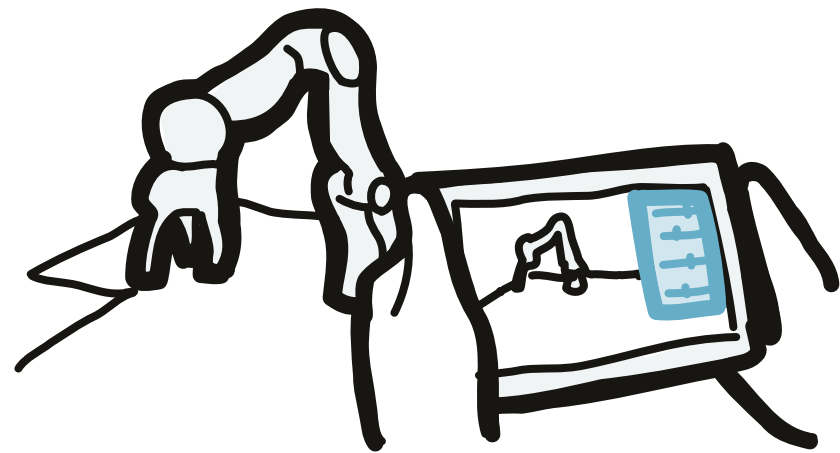
Actuated Objects
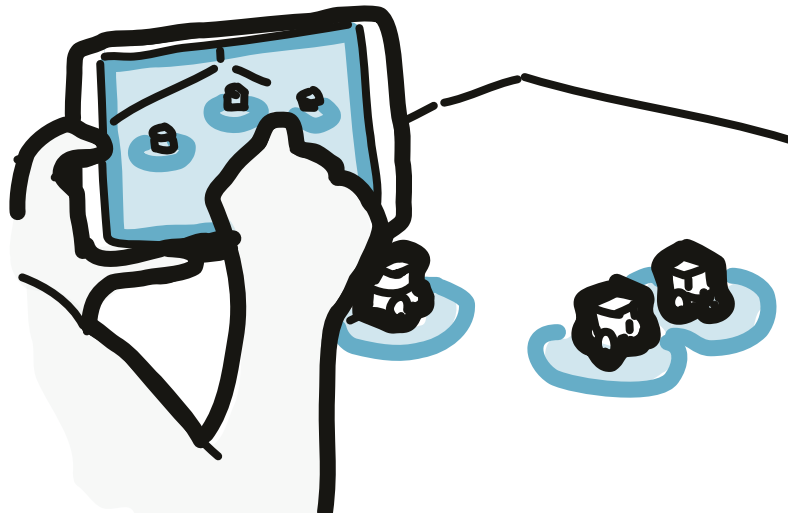[31, 49, 77, 81, 106]

Combinations
[31, 49, 77, 81, 106]

Other Types
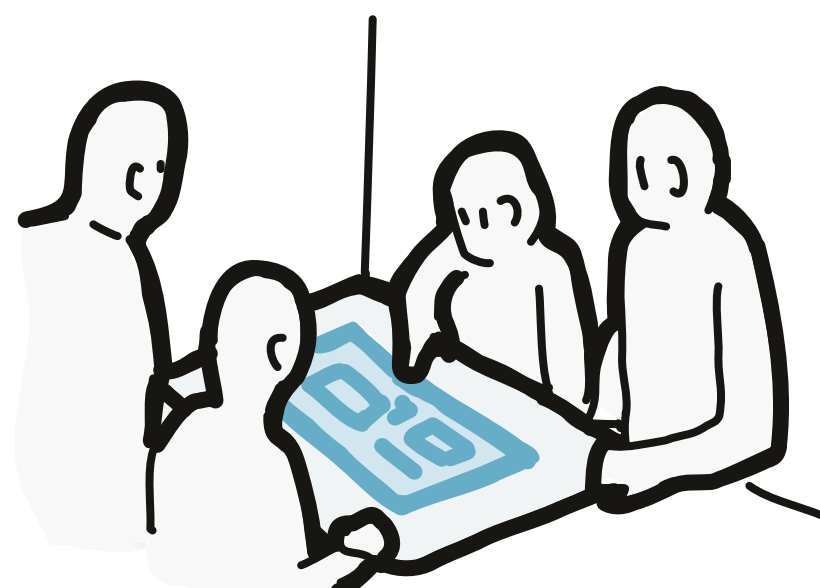[31, 49, 77, 81, 106]

② Relationship

1 : 1
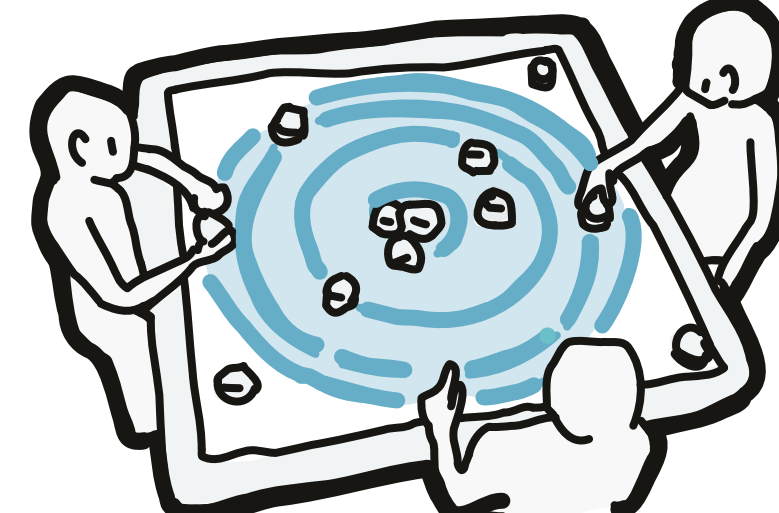Common HRI
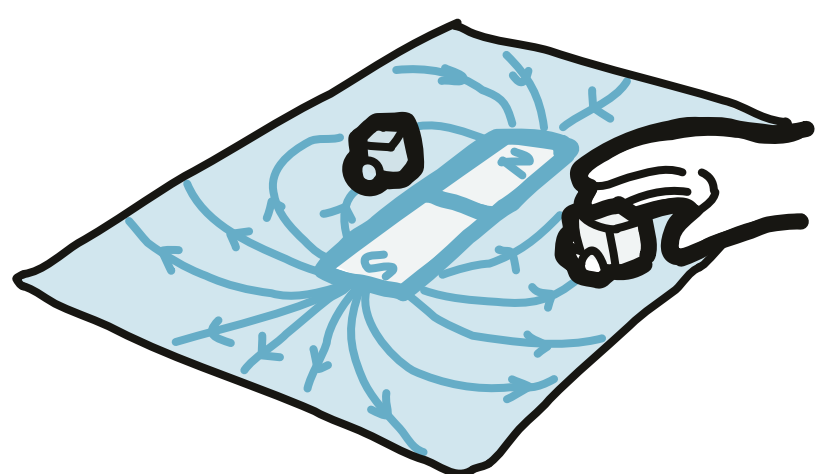[31, 49, 77, 81, 106]

1 : m
Swarm Robots
[31, 49, 77, 81, 106]

n : 1
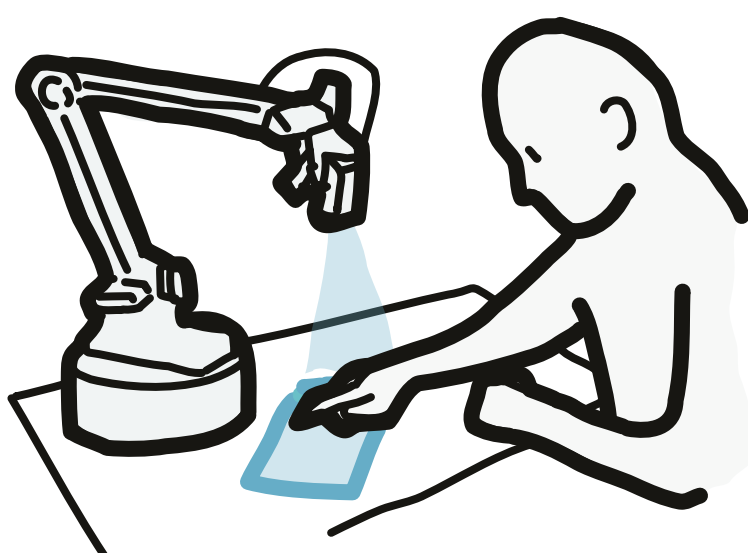Collaboration (Single Robot)
[31, 49, 77, 81, 106]

n : m
Collaboration (Multiple Robots)
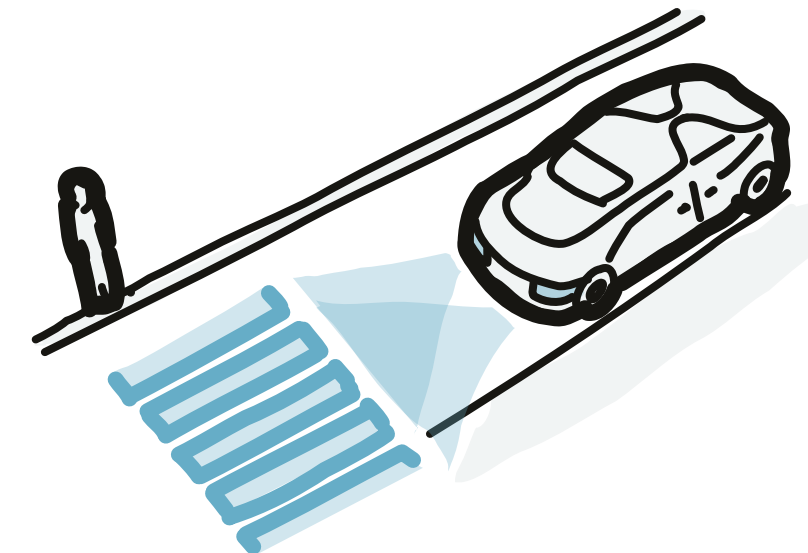[31, 49, 77, 81, 106]

③ Scale

Small

Large

Handheld-scale
[31, 49, 77, 81, 106]

Tabletop-scale
[31, 49, 77, 81, 106]

Body-scale
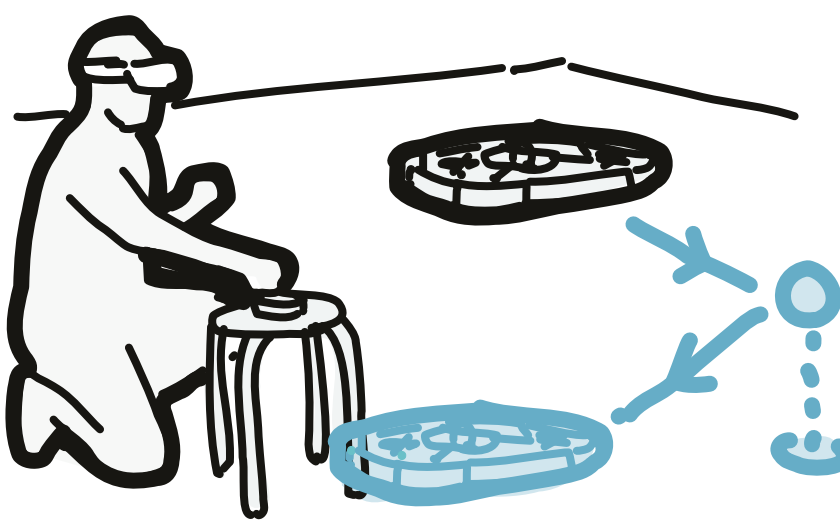[31, 49, 77, 81, 106]

City/Building-scale
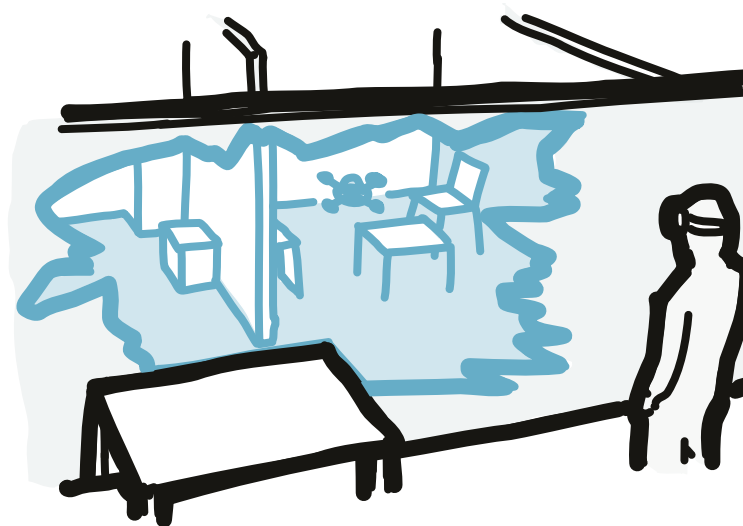[31, 49, 77, 81, 106]
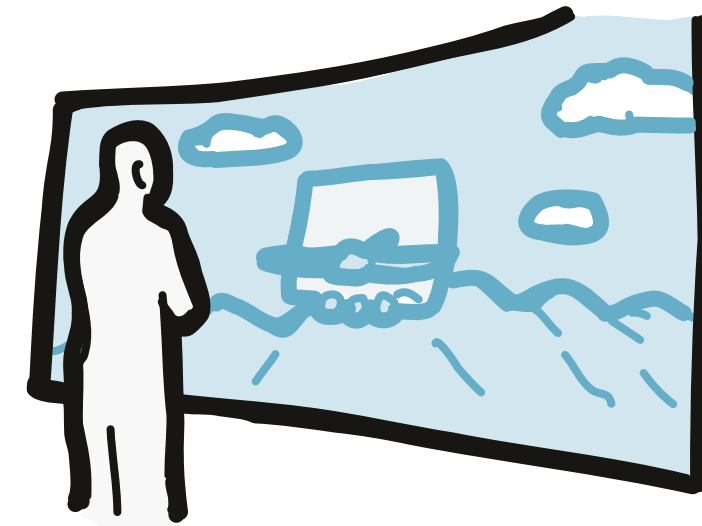
④ Proximity

Near

Far

Co-located
[31, 49, 77, 81, 106]

Co-located with Distance
[31, 49, 77, 81, 106]

Semi-Remote
[31, 49, 77, 81, 106]

Remote
[31, 49, 77, 81, 106]