

# ME103:: Experimentation and Measurements

## Lecture #2

- Lab Sessions do start this week
- Group forming and signature of safety forms
- Please start forming groups of four. This will be your group for all labs and final project
- When forming groups keep in mind the advantage of having members with these skills
  - Statistics
  - Electronics
  - LaTeX

## ME103:: Experimentation and Measurements

### What are measurements ?

**Measurements** are the process or result of determining the **quantity, size, amount, or degree** of something using a **standard units**. They allow us to **describe and compare** objects and phenomena in a consistent, precise way.

## ME103:: Experimentation and Measurements

### Key Components of a Measurement:

- **Quantity being measured** – What you're measuring (e.g., length, mass, time).
- **Numerical value** – The number that tells you how much.
- **Unit** – The standard you compare against (e.g., meters, kilograms, seconds).

### Examples:

- **Length:** 2 meters (means the object is two times as long as the standard meter)
- **Mass:** 5 kilograms
- **Time:** 10 seconds
- **Temperature:** 100 degrees Celsius

## ME103:: Experimentation and Measurements

Basically when we make a measurement, we are comparing it to a known standard.

Measurement is basically a comparison

Example: Standard for **length (m)** = the distance traveled by light over  $1/299,792,458$  of a second in vacuum.

Standard for **time (sec)** = 9,192,631,770 oscillations of radiation from a cesium-133 atom

## ME103:: Experimentation and Measurements

### Why Measurements Matter:

- In **science**, to perform experiments and compare results.
- In **engineering**, to build and design accurately.

**UC Berkeley**

Mechanical Engineering Department

**ME103::** Experimentation and Measurements

**What is the True Value of a  
Measurement ?**

## ME103:: Experimentation and Measurements

What does the term “error” mean in the context of measurements of a particular quantity?

Error = difference between the **measured value** and the **true value** of the quantity of interest.

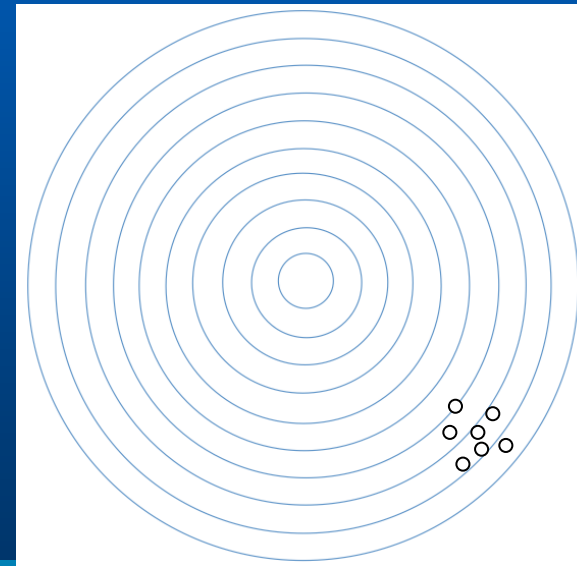
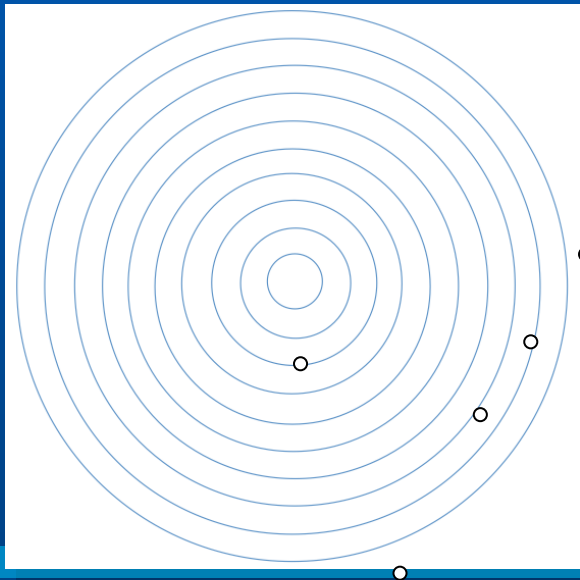
Rarely known, as true value is hardly ever known.



# Terminology: Precision

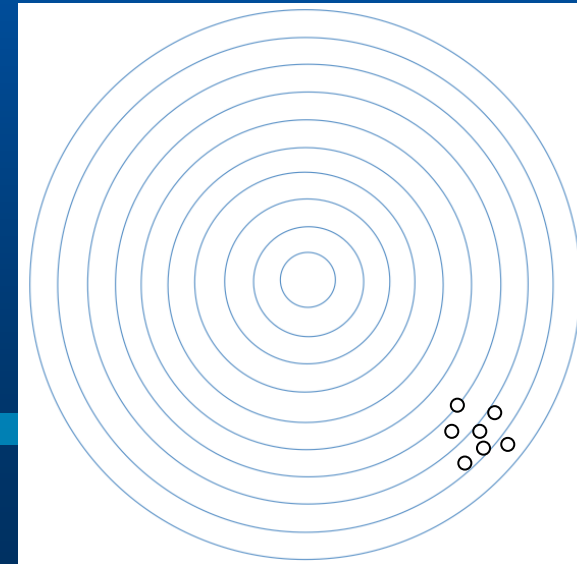
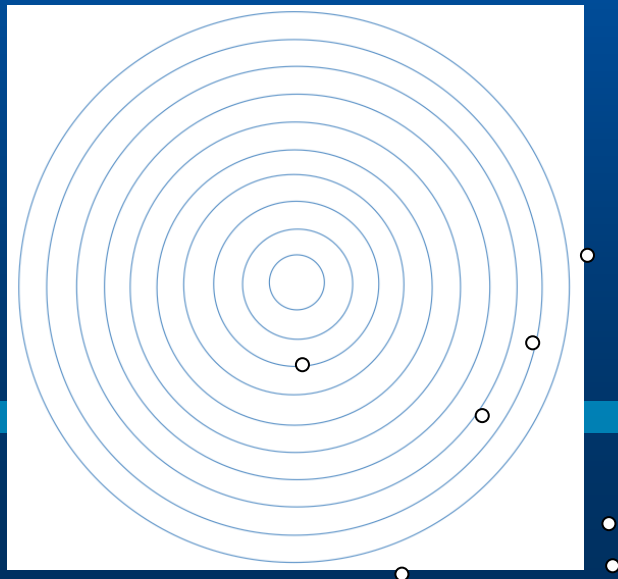
In archery, the goal is to hit the center of the target.

Which of the two archers is more precise?



# Terminology: Precision

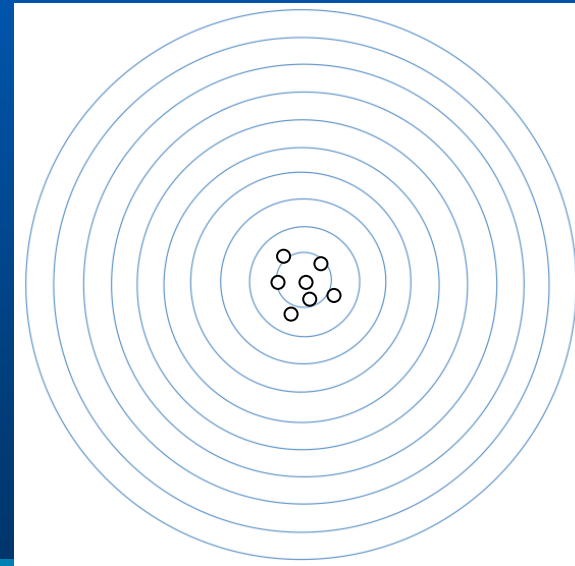
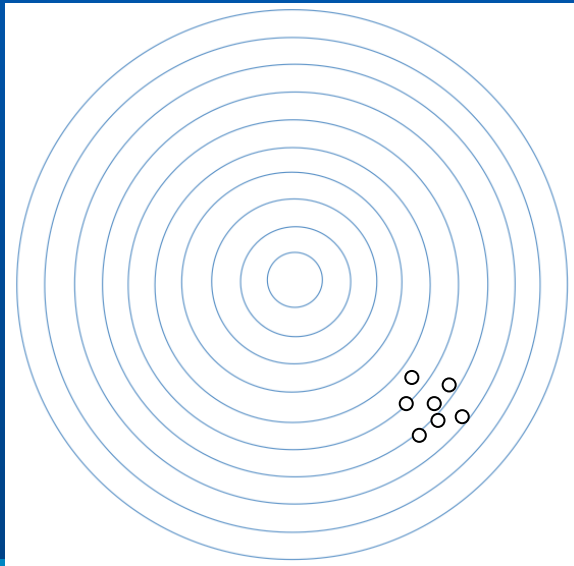
- A measure of the extent of *variation* among multiple measurements of the same quantity. Precision is often associated with *random errors* in the equipment or experimental conditions.
- Precision can be quantified through repeated measurements.



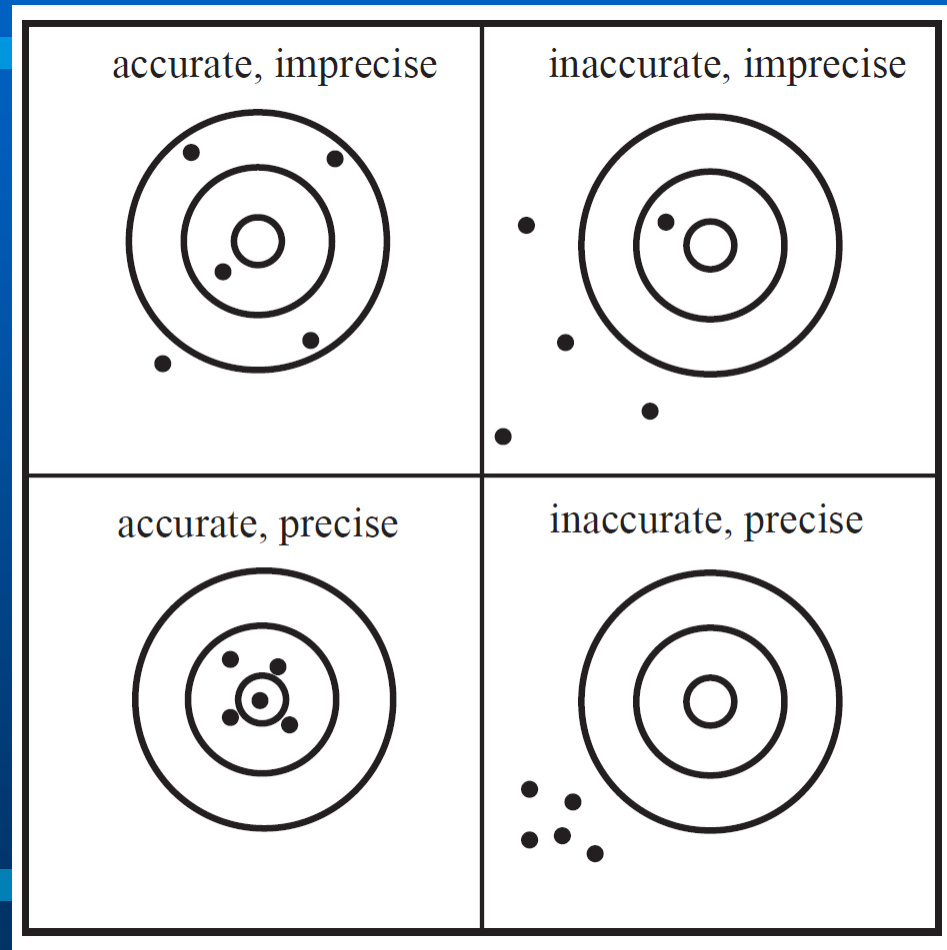
# Terminology: Accuracy

In archery, the goal is to hit the center of the target.

Which of the two archers is more accurate?

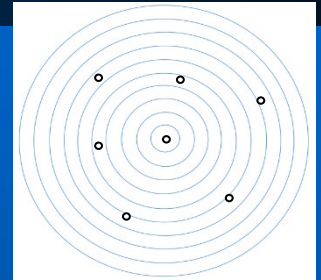


# Accuracy & Precision

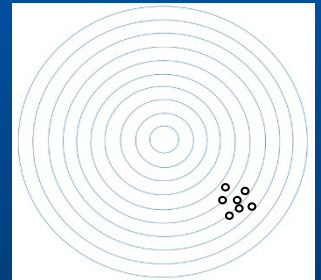


# Bias and Random Error

- Precision error = "random scatter" in the experimental results that CAN be found from repeated measurements.
  - Different for each successive measurement but have an average value of zero
- Bias error = **Systematic** errors that CANNOT be found from repeated measurements
  - Occur the same way each time a measurement is made
    - e.g. if a scale consistently reads 5% high, the entire set of measurements will be biased +5% above the true value
  - Can be estimated by comparison of the instrument to a more accurate standard, from knowledge of how the instrument was calibrated, or from experience with that specific instrument (or type of instrument)



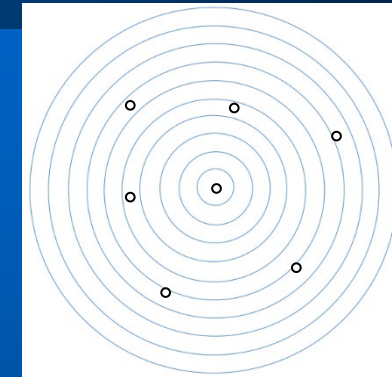
Random or  
Precision Error



Systematic  
or  
Bias Error

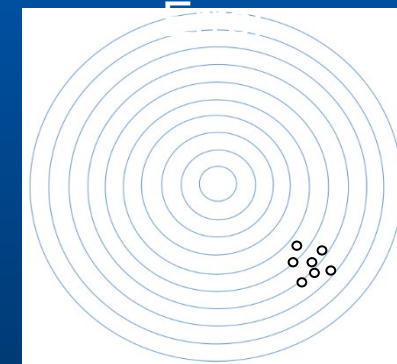
# Some Causes of Bias and Random Errors

- Precision error from:
  - disturbances (uncompensated vibrations, temperature, pressure, etc.),
  - observation errors,
  - friction,
  - not repeating experimental procedure properly,
  - etc.



Random or Precision

- Bias error from:
  - calibration
  - reoccurring human error,
  - defective equipment,
  - theoretical (e.g. incorrect system model),
  - etc.



Systematic or Bias  
Error

- Blunders
  - recording data incorrectly,
  - reading scale incorrectly,
  - etc.



Blunders

# Terminology: Uncertainty

- **Uncertainty:** A measure of the *expected error* in measurement that combines both systematic and random errors.
- For sample  $x$ , if  $B$  represents an estimate of bias (systematic) errors and  $P$  represents an estimate of precision (random) errors, then the uncertainty  $U$  is usually estimated as:

$$U_x = \left( B_x^2 + P_x^2 \right)^{1/2}$$

# Terminology: Uncertainty

- Most of the time, you will be dealing with **random** errors
- The best way to **quantify random errors** is to take a lot of measurements and perform **statistics**



# How Do We Go about Quantifying Error?

- ▶ When you make measurements and take data, you will get a **population** of data
- ▶ Within this **population**, you will have a **distribution about a mean value**

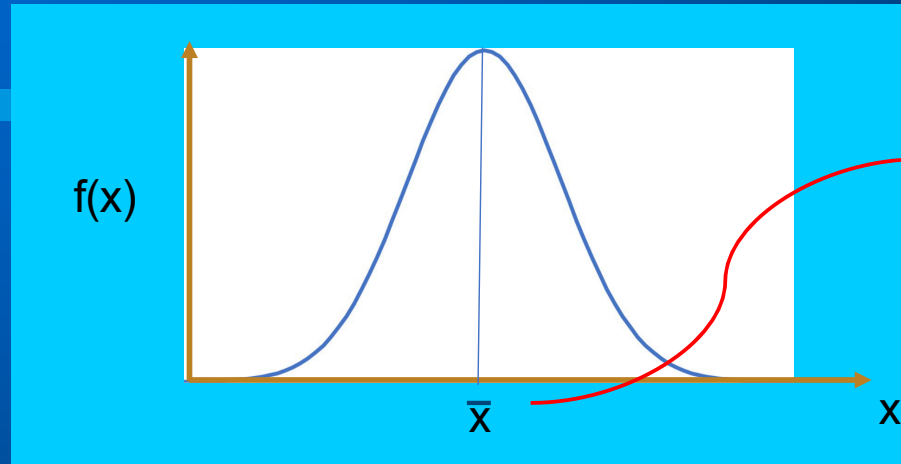
Average or mean

$$\bar{X} = \sum_{i=1}^n \frac{x_i}{n}$$

$x_i$  = data point

$n$  = number of data points

If your data are independent of one another, then the distribution about the mean is a Gaussian



Centered around the mean value

$$f(x) = \frac{1}{\sigma\sqrt{2\pi}} e^{-\frac{(x-\mu)^2}{2\sigma^2}}$$

$x$  = individual data point

$\mu$  = TRUE value

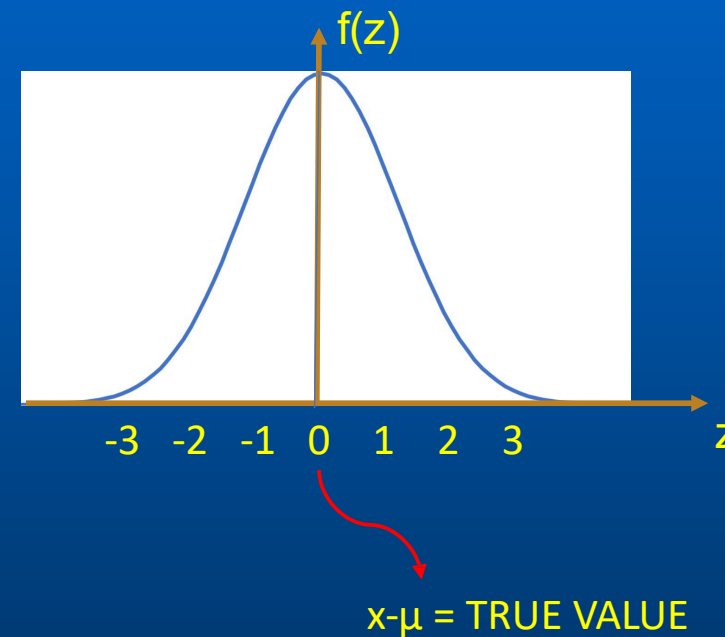
$\sigma$  = standard of deviation (gives the "spread" of the Gaussian)

$$\sigma = \sqrt{\frac{(x_1 - \mu)^2 + (x_2 - \mu)^2 + \cdots + (x_n - \mu)^2}{n}}$$

To make life easier for us, especially when we are comparing distributions, we can **re-write the Gaussian distribution**:

$$f(z) = \frac{1}{\sigma\sqrt{2\pi}} e^{-\frac{z^2}{2}}$$

$$z = \left| \frac{x - \mu}{\sigma} \right|$$



*By re-writing your Gaussian in terms of  $z$ , you have the following...*

$$z = \left| \frac{x - \mu}{\sigma} \right|$$

$$Z\sigma = |x - \mu|$$

$$x = \mu \pm Z\sigma \quad \text{or} \quad \mu = x \pm Z\sigma$$

$\mu = x \pm z\sigma$  is an important statement: If we **do not know** the true value  $\mu$ , we have at least a **range** of what the true value is

$x = \mu \pm z\sigma$  tells us how **good** our data is and tells us if our data point is an **outlier**. It helps us decide whether our data can be “tossed” if it is  $\sigma$ ,  $2\sigma$ ,  $3\sigma$  away from  $\mu$

