LECTURE VII

Timers and Interrupts

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SECTION I

Project VI Review

Project 6 Review

- Build a weather station that wirelessly transmits temperature and humidity data to an indoor display.
- Due date: 2/14/2025 at 11:59PM

Learning Concepts:

- Communication Protocols Pt. 2
- I²C Protocol
- SPI Protocol
- Arduino IDE Libraries (Continued)

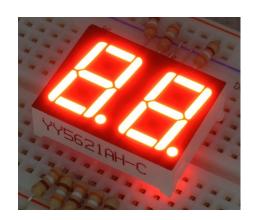


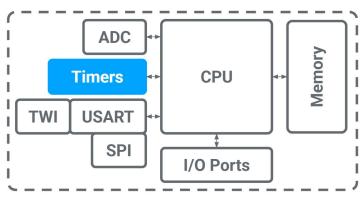
Project 7

- Create a digital stopwatch using interrupts, timers, and a 7-segment display
- Due date: 2/28/2025 at 11:59PM

Learning Concepts:

- Interrupts
- Timers
- Arduino IDE Libraries (Continued)

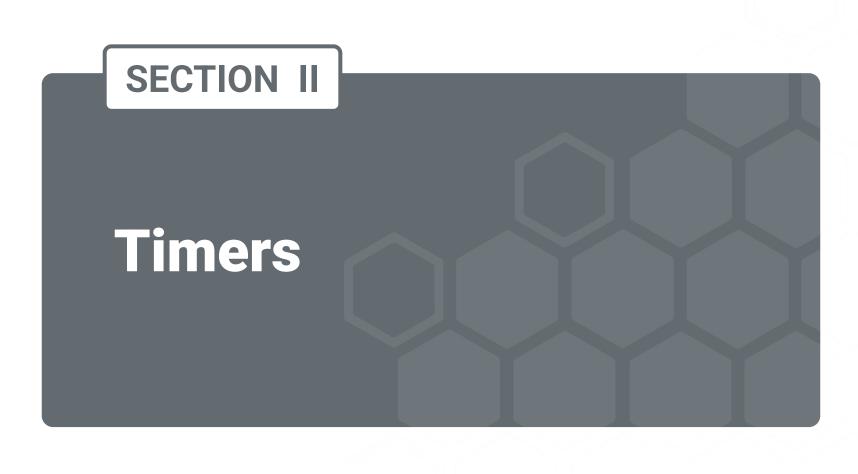




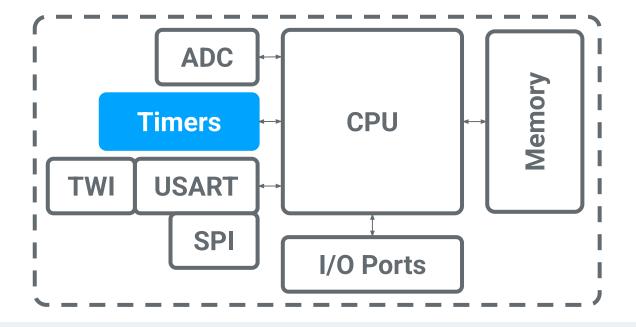
IEEE Board Applications

- IEEE board applications are now open!
- If you have enjoyed OPS or are interested in gaining leadership experience in a teaching role, look no further!
- We urge those of you with a passion for learning to apply for either OPS Lab Supervisor or OPS Lab Instructor
- Applications are due February 19th at 11:59PM





Timers



Timers are used by the microcontroller to **control the timing** of program execution or output signals and to **measure time**. Based on microcontroller's clock cycle

Types of Timers

- Timer types can be distinguished by when the timeout triggers
 - A timeout is an event that occurs after a preset period of time
- A one-shot timer has a single timeout
 - For the timer to be run again, it must be reloaded manually
 - Ex) A countdown timer runs just once, stopping when it reaches zero
- A periodic (or auto-reload) timer has periodic timeouts that occur at a fixed interval
 - The timer reloads automatically
 - Ex) An alarm clock rings once every morning

Timer Use Cases

Pausing/delaying the program

- delay uses a timer to suspend code execution for a specific period of time (Arduino)
- This is considered a blocking timer function since it blocks program execution

Measuring time

- millis uses a timer to count the number of milliseconds since the program began (Arduino)
- This is a non-blocking timer function since the program continues to execute as the timer runs

Timer Use Cases (Cont'd)

Calling a function upon timeout

- When the timer suspends, we may want specific instructions to occur. In which case, we call a function to handle the event
- We'll discuss this use case in the Interrupts section...

Generating a PWM signal

- analogWrite uses a timer to time the rising and falling edges of the PWM waveform (Arduino)
- See more in the Microcontroller Architecture and Arduino lecture...

ESP32c3 Timers

Timer Group 0

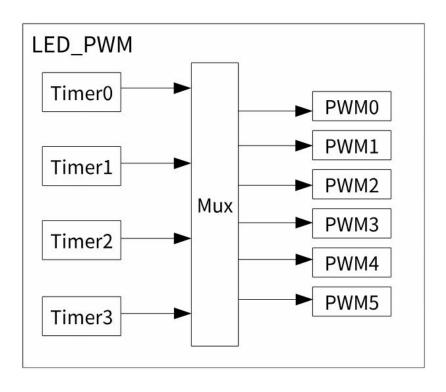
Timer 0 (T0) Watchdog Timer (WDT)

Timer Group 1

Timer 0 (T0) Watchdog Timer (WDT)

- The ESP32c3 has two general purpose timers (GPTs)
 - These timers are modules in the MCU used for various functions, PWM, and delays
 - Digital pins are capable of carrying the output of the timer to which they are connected
 - A pin used for timer output cannot also be used for a different purpose at the same time
 - There are more timers than this for other functions!

Arduino Nano Timers (Cont'd)



Some other timers

- System timer
 - o 52 bit timer
 - Used for interrupts
 - Used by delay and millis
- LED_PWM
 - For duty cycle and frequency
 - 16-bit resolution

Arduino Nano Timers (Cont'd)

- A watchdog timer (WDT) is used to detect and recover from software or hardware errors
 - How it works:
 - The WDT counts down to zero
 - ii. Each time the program's main loop is run, the timer is reset
 - iii. If the WDT reaches zero before its reset, then the WDT resets the entire processor
 - This is not a perfect solution! If a program loop takes a long time to execute, the WDT incorrectly assumes a fault, and the program is reset

SECTION III

Arduino Timer Library

Arduino Timer Library

- We will use one of the Arduino's internal timers to measure time
 - To do so, we will enlist the help of the <u>Timer library</u>, which will need to be downloaded and installed to the Arduino IDE
 - Make sure to use #include <Timer.h>
- If you would like to explore how timers can be used to call other functions, check out the <u>TimerInterrupt</u> library
 - We will not discuss it in this lecture

Arduino Timer Library (Cont'd)

- First, instantiate a Timer object as Timer timer;
 - Each of the following are member functions that can be called from this object
 - Time is measured in milliseconds by default
 - Alternatively, you can pass MICROS as a single argument to the constructor to measure in microseconds
- timer.start() starts the timer
 - The timer is in the RUNNING state

Arduino Timer Library (Cont'd)

- timer.pause() pauses the timer
 - The timer is in the PAUSED state
 - The time elapsed since timer.start() freezes
- timer.resume () resumes the timer from the PAUSED state
 - The timer is in the **RUNNING** state
 - The time elapsed since timer.start() resumes counting

Arduino Timer Library (Cont'd)

- timer.stop() stops the timer
 - The timer is in the **STOPPED** state
 - The time elapsed since timer.start() will be the reset the next time the timer.start() is called
- timer.read() returns the time elapsed since timer.start()
 - Measured in milliseconds
- timer.state() returns the state as one of three predefined constants
 - The state can be RUNNING, PAUSED, or STOPPED

SECTION IV Interrupts

Interrupts

- An interrupt is a request for the CPU to halt the currently executing code when an event occurs
 - The CPU suspends the current program to handle the event by executing a function called an interrupt handler or interrupt service routine (ISR)
 - When an interrupt halts the current code, a separate program / function can be called and run.
 - When the interrupt handler finishes execution, the CPU returns to the old program

Polling

- Polling is a method of periodically checking the status of a device
 - o Ex) A person checking their phone for new messages every 10 minutes
 - We have been using polling in the void loop ()
 - Polling loops cost additional CPU time
- Should we use interrupts instead of polling?
 - Interrupts signal when an event occurs whereas polling checks to see if an event occured
 - Ex) A person reading their phone upon receiving a push notification
 - Use interrupts when an event is urgent and/or infrequent

Types of Interrupts

- A software interrupt is triggered by an instruction
 - Also called a trap or exception
 - Often caused by an illegal operation
 - Ex) Dividing by zero, Accessing memory without permission
- A hardware interrupt is triggered by devices external to the CPU
 - Also called an external interrupt
 - Caused when a devices sends an interrupt request (IRQ) signal to the CPU
 - Ex) Timer timeout, button press, power failure

Interrupt Use Cases

Servicing timers

- When a timeout occurs, the programmer may want specific code to be run
 - This is when the timer sends an IRQ and an interrupt handler is called

Handling peripheral device events

- Ex) When a key is pressed, the keyboard sends an IRQ to the computer
 - An interrupt handler then responds to the event

SECTION V

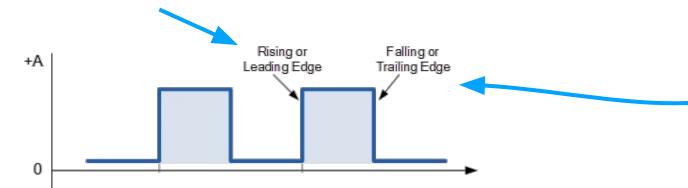
Interrupts with Arduino

attachInterrupt

- Any GPIO pin on the ESP32 can be an interrupt pin
- void attachInterrupt(interrupt, ISR, mode)
 - This function initializes an interrupt
 - interrupt the interrupt number); only one interrupt can be initialized per interrupt number
 - The interrupt # should be the same for ESP32, but this is not always true.
 - ISR the name of the function to call as the interrupt handler
 - You need to define a function and pass its name as ISR
 - mode configures the timing of the IRQ
 - You will set the mode to one of the following constants...

attachInterrupt (Cont'd)

- The options for mode are...
 - Low when the pin is a LOW voltage
 - CHANGE when the pin changes value
 - FALLING when the pin voltage changes from HIGH to LOW
 - RISING when the pin voltage changes from LOW to HIGH



attachInterrupt (Cont'd)

- void digitalPinToInterrupt(pin)
 - This function converts a digital pin number to its corresponding interrupt number
- It is recommended that you call attachInterrupt as follows:
 - o attachInterrupt(digitalPinToInterrupt(pin), ISR, mode)
 - This approach avoids confusion involving digital pin and interrupt numbers

SECTION VI

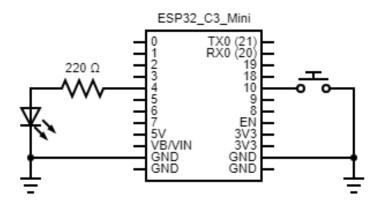
ESP32 Interrupt Exercise

ESP32 LED Toggle Button



Write a program that satisfies the following requirements:

- You must write a program in which the ESP32 board toggles the state of its LED (on pin 4) when a button is pressed
- The state of the LED must toggle only once for each button press
 - Meaning... The LED should not flicker ON and OFF
 if the button is held down
- This program must be implemented with attachInterrupt
- No loops may be used (that includes the main loop)
- No starter code!



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