



**Workshop**

# Capstone Project

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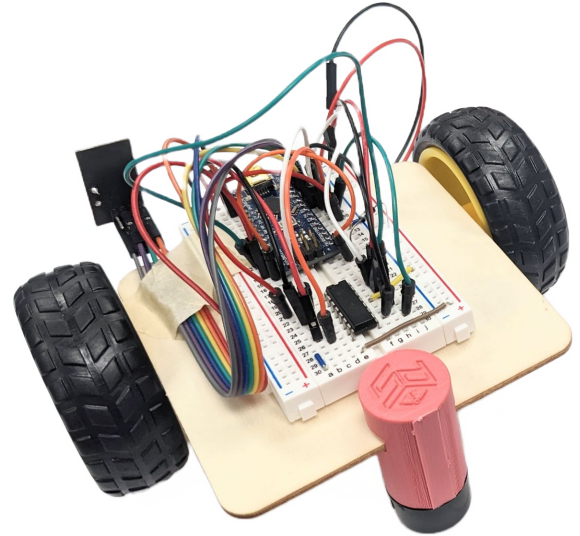
## SECTION I

# Capstone Overview

# Capstone Project Requirements

## Build a **remote-controlled rover**

- The rover must be controlled wirelessly via the remote control
- The remote control should use a joystick for user input
- A user should be able to intuitively use the joystick to control the rover
  - This means that pivoting the joystick left should move the rover left, not backward



# Capstone Project Requirements (Cont.)

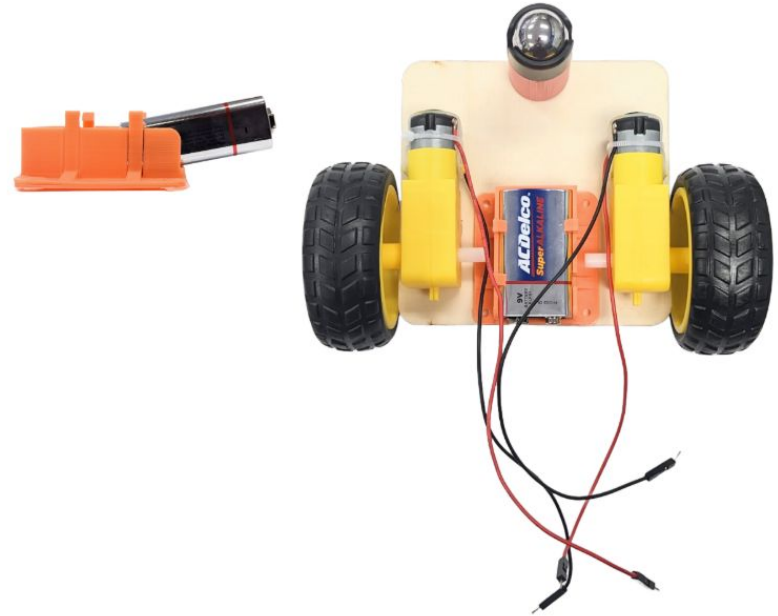
- You must design a PCB for the remote control
  - The PCB must adhere to the provided manufacturer constraints.
  - The PCB must be **less than 100x100mm in size**
- The rover must be able to move forward, backward, left, and right in response to commands sent by the remote
- Lastly, the rover must be stable and reliable
  - There should be no spontaneous movement, no wireless connection issues, and absolutely no sparks.

# Capstone Project Schedule

Week	Suggested Activity	Workshop
1	Capstone PCB Design (Due <b>April 4th, 2025 at 11:59 PM</b> ) Attend Lecture: Capstone Project: Getting Started	
2		Capstone Rover Assembly
3	Attend Lecture: Senior Design Project Showcase	
4		Capstone PCB Assembly
5	Start Working on Capstone Programming Independently (Lecture Tentative)	
6		Capstone Programming
7	Attend Lecture: End of the Year Review/Reflection	
8	Suggested Capstone Project Submission Date: <b>May 23rd</b>	
9	Rover Competition	
10	OFFICIAL Capstone Project Submission Deadline: <b>June 6th, 2025 at 11:59PM</b>	

# Capstone Rover Assembly (Week 2)

- We will be assembling the rover first w/ a Hot Glue Gun
- Parts needed:
  - x2 Gearbox Motor
  - x2 Wheel
  - x1 Ball Caster + Mount
  - x1 9V Battery Holder
  - x1 4" x 4" Wood Plate
  - x1 Breadboard
  - x1 Battery (If your battery is weak, stop by lab hours for a new one)
  - x1 9V Battery Snap Connector with Dupont Terminals



# Capstone Project Deadlines

## Deadlines

- PCB Design Submission: **April 4th, 2025 at 11:59 PM**
- Suggested Capstone Submission: **May 23rd at 11:59PM**
- Final Submission: **June 6th, 2025 at 11:59 PM**

# One More Thing...

- **Raffle Prizes for Completing Projects!**
  - Each completed project = 1 Raffle Ticket
  - Completed Capstone Project = 3 Raffle Tickets
- Tickets will be drawn for:
  - Gaming Keyboard + Mouse (1 Winner)
  - Soldering Kits (2-5 Winners)
  - ESP-C6s (10 winners)





## **SECTION II**

# **Capstone Rover Assembly**

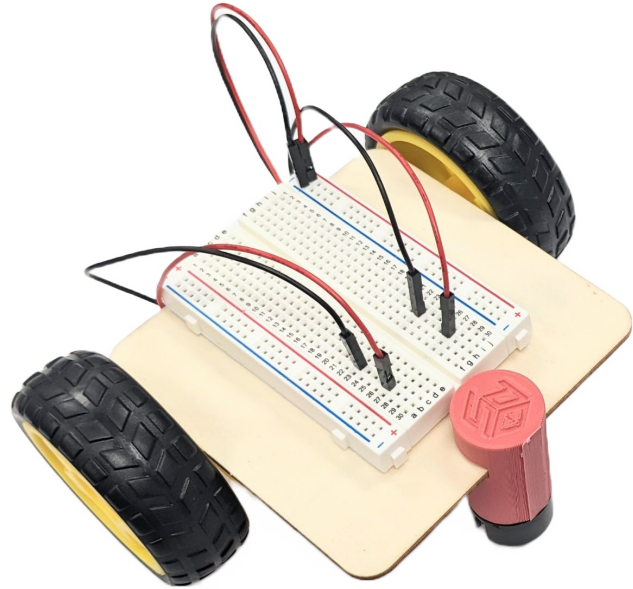
# Capstone Project Rover Assembly

- Build the rover any way you like!
  - As long as it meets the requirements, you're good to go!
- **Recommended:** Hot Glue Gun
  - Available at the IEEE Room



# Capstone Project Rover Assembly

- There is no schematic for the rover, so **you will have to design the circuit yourself**
- The L293D motor driver datasheet is linked in the project specifications
- **Recommended:** Read the datasheet to help you design the circuit
  - NOTE: VCC1 pin can be supplied 9V (from the 9V Battery)
  - DO NOT CONNECT 9V BATTERY TO 5V, connect it to VB of the ESP32



# Capstone Project Rover Assembly

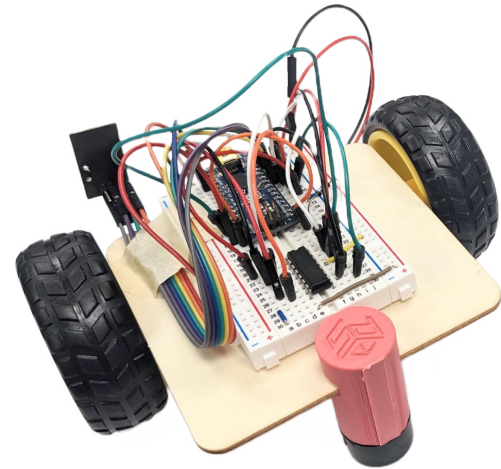
- Remember how to solder? No?
  - Review the Fall soldering workshop slides
- Solder only the header components to the PCB
- **Do not solder** the transceiver, the ESP32, or the joystick to the board
- If the remote does not work later, check the solder joints and your PCB design for errors

## **SECTION III**

# **Capstone PCB Assembly**

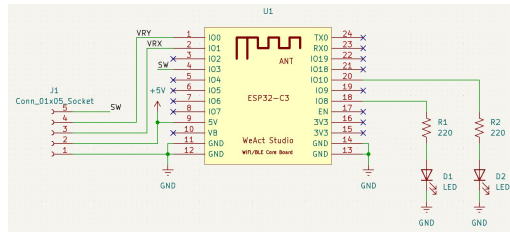
# Required Components

- What you'll need:
  - **x1** 1x5 Pin Female Header (Bent)
  - **x2** 1x12 Pin Female Header
  - **x1** Analog Joystick
  - **x1** ESP32
  - **x1** PCB
  - **x2** 220 $\Omega$  Resistor
  - **x2** LED



# Assembly Steps

1. Place the headers onto your PCB. Remember, **don't solder the ESP32 or Analog Joystick** onto the board, just the headers.
  - a. If you need a soldering review, check out the Fall soldering workshop slides!
2. Solder the headers to the PCB.
3. Solder the LEDs and resistors onto the PCB.
  - a. Long lead goes into the circle, shorter lead goes into the square!
4. Place the ESP32 and Analog Joystick on the headers. You're done!



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