

Biostat 216 Homework 8

Due Nov 26 Friday @ 11:59pm

Submit a PDF (scanned/photographed from handwritten solutions, or converted from RMarkdown or Jupyter Notebook) to Gracescope on BruinLearn.

- Q1. **(MLE of multivariate normal model)** Let $\mathbf{y}_1, \dots, \mathbf{y}_n \in \mathbb{R}^p$ be iid samples from a p -dimensional multivariate normal distribution $N(\boldsymbol{\mu}, \boldsymbol{\Omega})$, where the mean $\boldsymbol{\mu} \in \mathbb{R}^p$ and covariance $\boldsymbol{\Omega} \in \mathbb{R}^{p \times p}$ are unknown parameters. The log-likelihood is

$$\ell(\boldsymbol{\mu}, \boldsymbol{\Omega}) = -\frac{n}{2} \log \det \boldsymbol{\Omega} - \frac{1}{2} \sum_{i=1}^n (\mathbf{y}_i - \boldsymbol{\mu})' \boldsymbol{\Omega}^{-1} (\mathbf{y}_i - \boldsymbol{\mu}) - \frac{n}{2} \log 2\pi.$$

Show that the maximum likelihood estimate (MLE) is

$$\begin{aligned}\widehat{\boldsymbol{\mu}} &= \frac{\sum_{i=1}^n \mathbf{y}_i}{n} \\ \widehat{\boldsymbol{\Omega}} &= \frac{\sum_{i=1}^n (\mathbf{y}_i - \widehat{\boldsymbol{\mu}})(\mathbf{y}_i - \widehat{\boldsymbol{\mu}})'}{n}.\end{aligned}$$

That is to show that $\widehat{\boldsymbol{\mu}}, \widehat{\boldsymbol{\Omega}}$ maximize ℓ .

Hint: Use the first order optimality condition to find $\widehat{\boldsymbol{\mu}}$ and $\widehat{\boldsymbol{\Omega}}$. To check the optimality of $\widehat{\boldsymbol{\Omega}}$, use its Cholesky factor.

- Q2. **(Smallest matrix subject to linear constraints)** Find the matrix \mathbf{X} with the smallest Frobenius norm subject to the constraint $\mathbf{X}\mathbf{U} = \mathbf{V}$, assuming \mathbf{U} has full column rank.

Hint: write down the optimization problem and use the method of Lagrange multipliers.

- Q3. **(Minimizing a convex quadratic form over manifold)** $\mathbf{A} \in \mathbb{R}^{n \times n}$ is a positive semidefinite matrix. Find a matrix $\mathbf{U} \in \mathbb{R}^{n \times r}$ with orthonormal columns that maximizes $\text{tr}(\mathbf{U}'\mathbf{A}\mathbf{U})$. That is to

$$\begin{aligned}\text{maximize} \quad & \text{tr}(\mathbf{U}'\mathbf{A}\mathbf{U}) \\ \text{subject to} \quad & \mathbf{U}'\mathbf{U} = \mathbf{I}_r.\end{aligned}$$

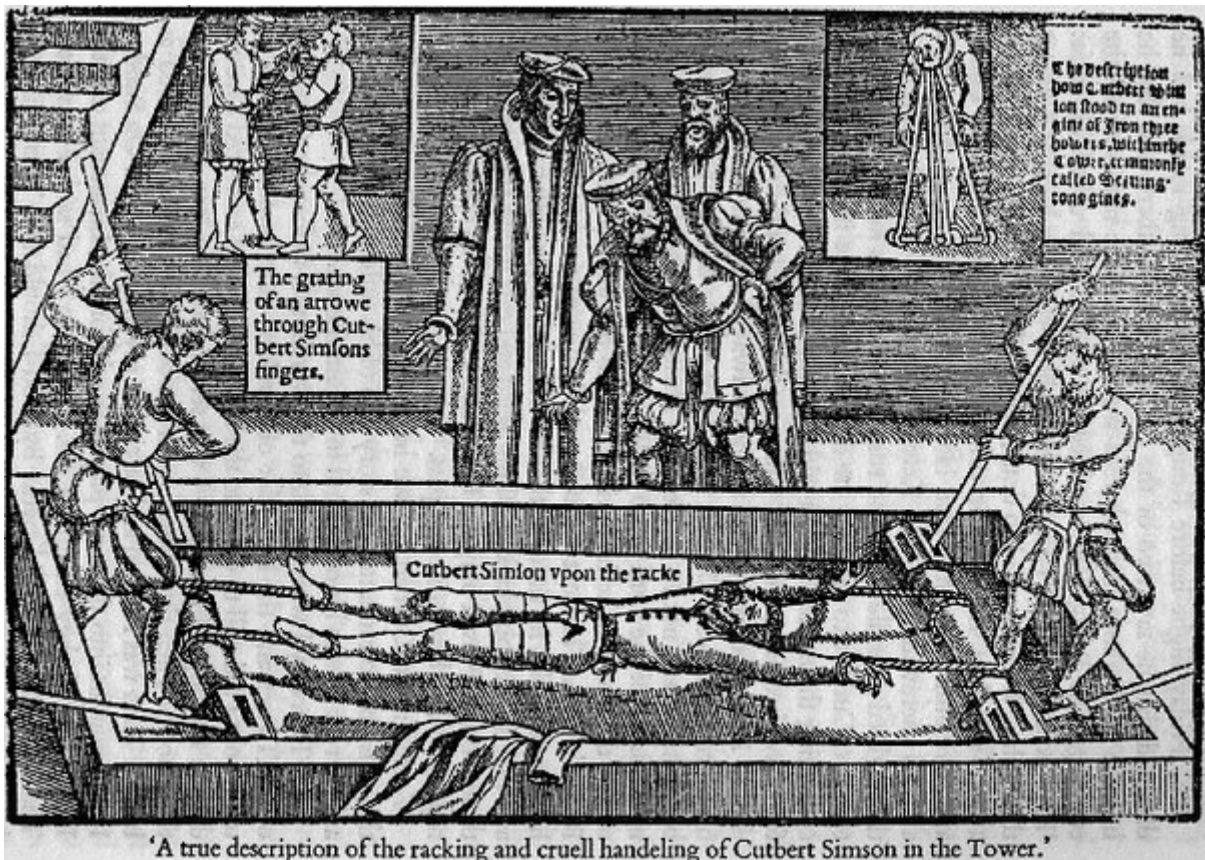
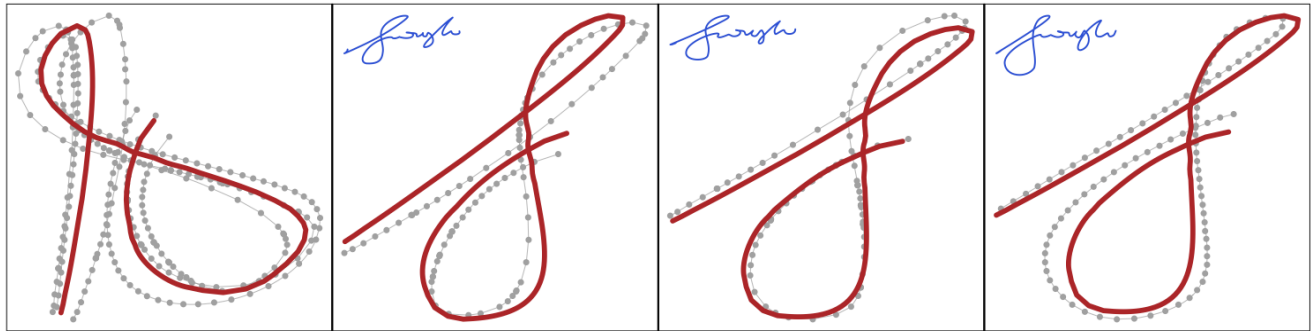
This result generalizes the fact that the top eigenvector of \mathbf{A} maximizes $\mathbf{u}'\mathbf{A}\mathbf{u}$ subject to constraint $\mathbf{u}'\mathbf{u} = 1$.

Hint: Use the method of Lagrange multipliers.

• Q4. (**Procrustes rotation**)

(https://docs.scipy.org/doc/scipy/reference/generated/scipy.linalg.orthogonal_procrustes.html#scipy.linalg.orthogonal_procrustes)

The Procrustes problem studies how to properly align images.



Let matrices $\mathbf{X}, \mathbf{Y} \in \mathbb{R}^{n \times p}$ record n points on the two shapes. Mathematically we consider the problem

$$\text{minimize}_{\beta, \mathbf{O}, \mu} \quad \|\mathbf{X} - (\beta \mathbf{Y} \mathbf{O} + \mathbf{1}_n \mu^T)\|_F^2,$$

where $\beta > 0$ is a scaling factor, $\mathbf{O} \in \mathbb{R}^{p \times p}$ is an orthogonal matrix, and $\mu \in \mathbb{R}^p$ is a vector of shifts. Here $\|\mathbf{M}\|_F^2 = \sum_{i,j} m_{ij}^2$ is the squared Frobenius norm. Intuitively we want to rotate, stretch and shift the shape \mathbf{Y} to match the shape \mathbf{X} as much as possible.

- Q4.1 Let $\bar{\mathbf{x}}$ and $\bar{\mathbf{y}}$ be the column mean vectors of the matrices and $\tilde{\mathbf{X}}$ and $\tilde{\mathbf{Y}}$ be the versions of these matrices centered by column means. Show that the solution $(\hat{\beta}, \hat{\mathbf{O}}, \hat{\mu})$ satisfies

$$\hat{\mu} = \bar{\mathbf{x}} - \hat{\beta} \cdot \hat{\mathbf{O}}^T \bar{\mathbf{y}}.$$

Therefore we can center each matrix at its column centroid and then ignore the location completely.

- Q4.2 Derive the solution to

$$\text{minimize}_{\beta, \mathbf{O}} \quad \|\tilde{\mathbf{X}} - \beta \tilde{\mathbf{Y}} \mathbf{O}\|_F^2$$

using the SVD of $\tilde{\mathbf{Y}}^T \tilde{\mathbf{X}}$.

- Q5. (**Ridge regression** (https://scikit-learn.org/stable/modules/generated/sklearn.linear_model.Ridge.html))

One popular regularization method in machine learning is the ridge regression, which estimates regression coefficients by minimizing a penalized least squares criterion

$$\frac{1}{2} \|\mathbf{y} - \mathbf{X}\boldsymbol{\beta}\|_2^2 + \frac{\lambda}{2} \|\boldsymbol{\beta}\|_2^2.$$

Here $\mathbf{y} \in \mathbb{R}^n$ and $\mathbf{X} \in \mathbb{R}^{n \times p}$ are fixed data. $\boldsymbol{\beta} \in \mathbb{R}^p$ are the regression coefficients to be estimated.

- Q5.1 Show that, regardless the shape of \mathbf{X} , there is always a unique global minimum for any $\lambda > 0$ and the ridge solution is given by

$$\widehat{\boldsymbol{\beta}}(\lambda) = (\mathbf{X}^T \mathbf{X} + \lambda \mathbf{I})^{-1} \mathbf{X}^T \mathbf{y}.$$

- Q5.2 Express ridge solution $\widehat{\boldsymbol{\beta}}(\lambda)$ in terms of the singular value decomposition (SVD) of \mathbf{X} .

- Q5.3 Show that (i) the ℓ_2 norms of ridge solution $\|\widehat{\boldsymbol{\beta}}(\lambda)\|_2$ and corresponding fitted values $\|\widehat{\mathbf{y}}(\lambda)\|_2 = \|\mathbf{X}\widehat{\boldsymbol{\beta}}(\lambda)\|_2$ are non-increasing in λ and (ii) the ℓ_2 norm of the residual vector $\|\mathbf{y} - \widehat{\mathbf{y}}(\lambda)\|_2$ is non-decreasing in λ .

- Q5.4 Let's address how to choose the optimal tuning parameter λ . Let $\widehat{\boldsymbol{\beta}}_k(\lambda)$ be the solution to the ridge problem

$$\text{minimize } \frac{1}{2} \|\mathbf{y}_{-k} - \mathbf{X}_{-k} \boldsymbol{\beta}\|_2^2 + \frac{\lambda}{2} \|\boldsymbol{\beta}\|_2^2,$$

where \mathbf{y}_{-k} and \mathbf{X}_{-k} are the data with the k -th observation taken out. The optimal λ can be chosen to minimize the cross-validation square error

$$C(\lambda) = \frac{1}{n} \sum_{k=1}^n [y_k - \mathbf{x}_k^T \widehat{\boldsymbol{\beta}}_k(\lambda)]^2.$$

However computing n ridge solution paths $\widehat{\boldsymbol{\beta}}_k(\lambda)$ is expensive. Show that, using SVD $\mathbf{X} = \mathbf{U}\Sigma\mathbf{V}^T$,

$$C(\lambda) = \frac{1}{n} \sum_{k=1}^n \left[\frac{y_k - \sum_{j=1}^r u_{kj} \tilde{y}_j \left(\frac{\sigma_j^2}{\sigma_j^2 + \lambda} \right)}{1 - \sum_{j=1}^r u_{kj}^2 \left(\frac{\sigma_j^2}{\sigma_j^2 + \lambda} \right)} \right]^2,$$

where $\tilde{\mathbf{y}} = \mathbf{U}^T \mathbf{y}$.

- Q6. (**Factor analysis** (<https://scikit-learn.org/stable/modules/generated/sklearn.decomposition.FactorAnalysis.html>)) Let $\mathbf{y}_1, \dots, \mathbf{y}_n \in \mathbb{R}^p$ be iid samples from a multivariate normal distribution $N(\mathbf{0}_p, \mathbf{F}\mathbf{F}' + \mathbf{D})$, where $\mathbf{F} \in \mathbb{R}^{p \times r}$ and $\mathbf{D} \in \mathbb{R}^{p \times p}$ is a diagonal matrix with positive entries. We estimate the factor matrix \mathbf{F} and diagonal matrix \mathbf{D} by maximizing the log-likelihood function

$$\ell(\mathbf{F}, \mathbf{D}) = -\frac{n}{2} \ln \det(\mathbf{F}\mathbf{F}' + \mathbf{D}) - \frac{n}{2} \text{tr}[(\mathbf{F}\mathbf{F}' + \mathbf{D})^{-1} \mathbf{S}] - \frac{np}{2} \ln 2\pi,$$

where $\mathbf{S} = n^{-1} \sum_{i=1}^n \mathbf{y}_i \mathbf{y}_i'$.

- Q5.1 We first show that, for fixed \mathbf{D} , we can find the maximizer \mathbf{F} explicitly using SVD by the following steps.
 - Step 1: Take derivative with respect to \mathbf{F} and set to 0 to obtain the first-order optimality condition.
 - Step 2: Reparameterize $\mathbf{H} = \mathbf{D}^{-1/2} \mathbf{F}$ and $\tilde{\mathbf{S}} = \mathbf{D}^{-1/2} \mathbf{S} \mathbf{D}^{-1/2}$, and express the first-order optimality condition in terms of \mathbf{H} and $\tilde{\mathbf{S}}$.
 - Step 3: Let $\mathbf{H} = \mathbf{U} \mathbf{\Sigma} \mathbf{V}'$ be its SVD. Show that columns of \mathbf{U} must be r eigenvectors of $\tilde{\mathbf{S}}$.
 - Step 4: Identify which r eigenvectors of $\tilde{\mathbf{S}}$ to use in \mathbf{U} and then the solution to \mathbf{F} .
- Q5.2 Show that, for fixed \mathbf{F} , we can find the maximizer \mathbf{D} explicitly. (Hint: first-order optimality condition.)

Combining Q5.1 and Q5.2, a natural algorithm to for finding the MLE of factor analysis model is to alternately update \mathbf{F} and \mathbf{D} until convergence.