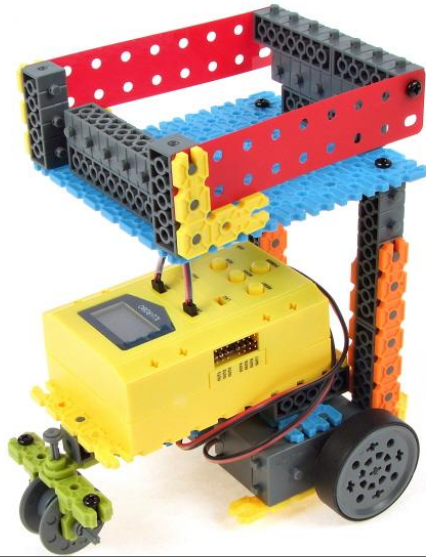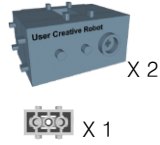# Making a Carrier robot
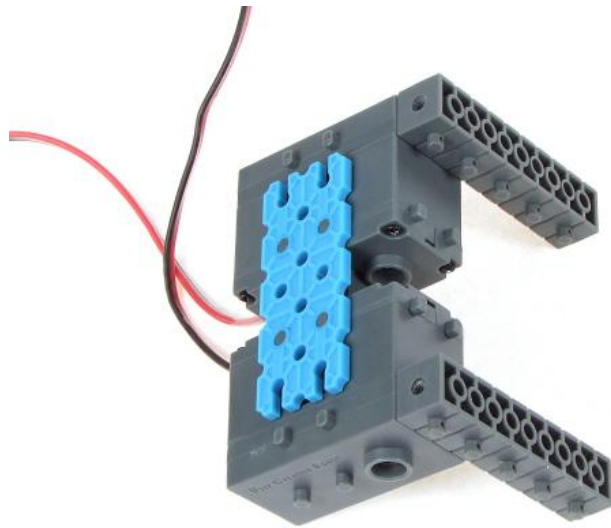
(S) : short
(M) : middle
(L) : long
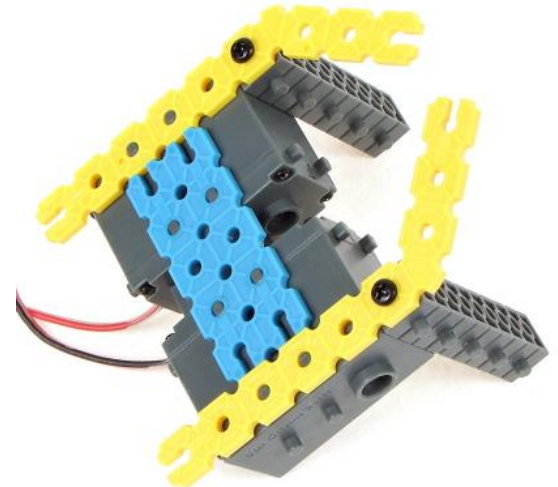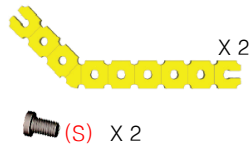
User Creative Robot   X 2

X 1

X 2

X 1

X 2

(S) X 2

4

X 1
X 1

5

X 1

6

X 1
X 1
X 1

7
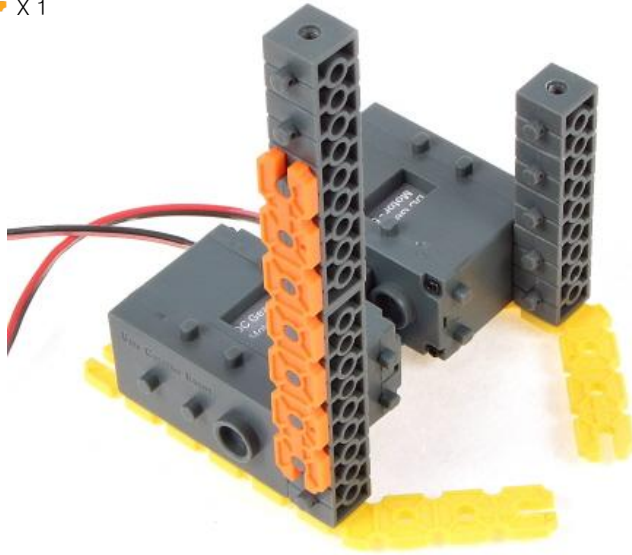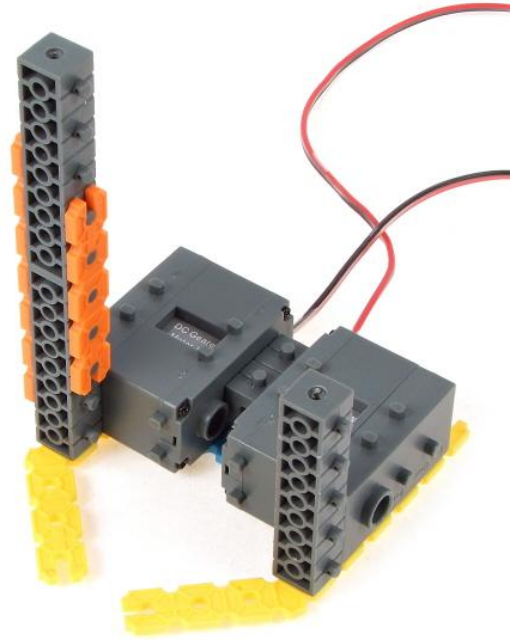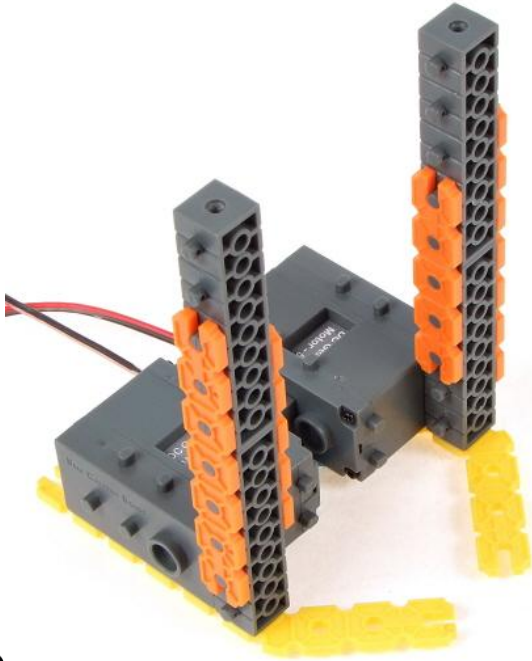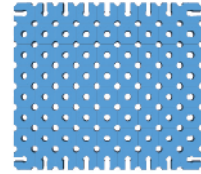
X 1
X 2
(S) X 2
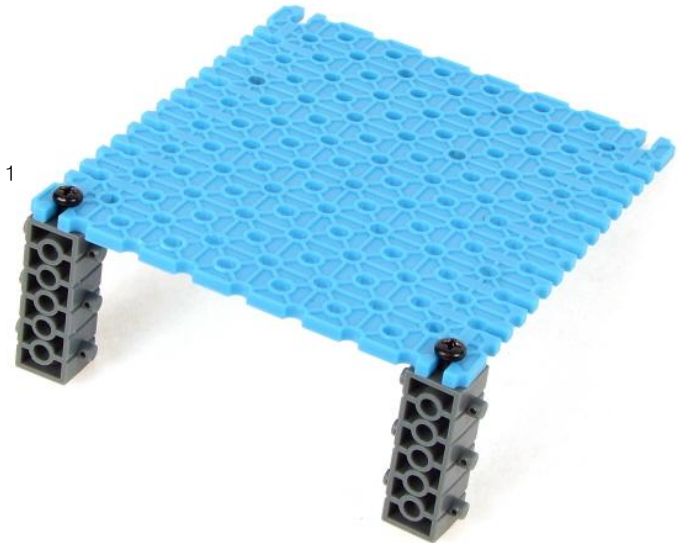
8

- X 3
- X 1
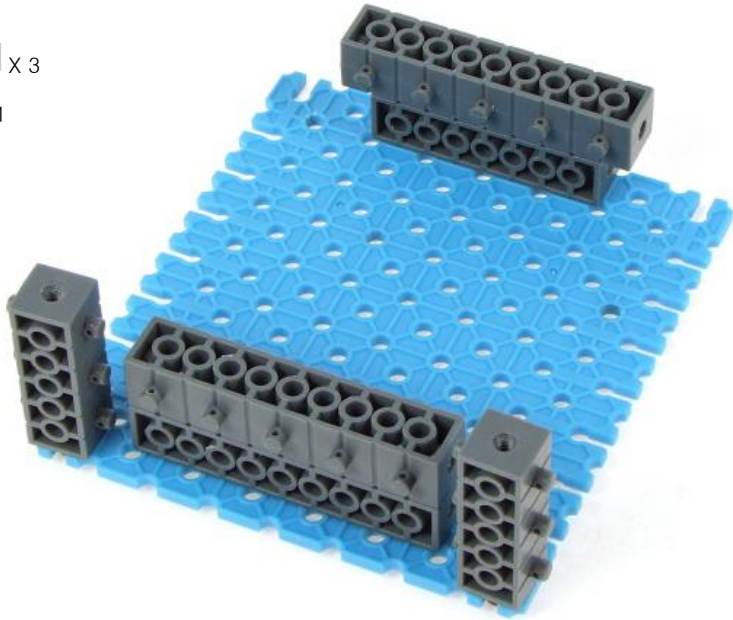
9

(S) X 2
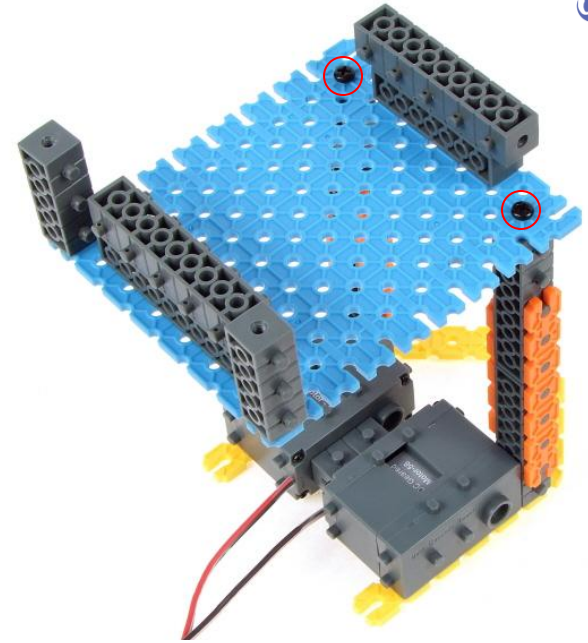
10

- X 2
- X 1
- X 1
- (S) X 2

11

12

X 1

13

X 1

14

X 2
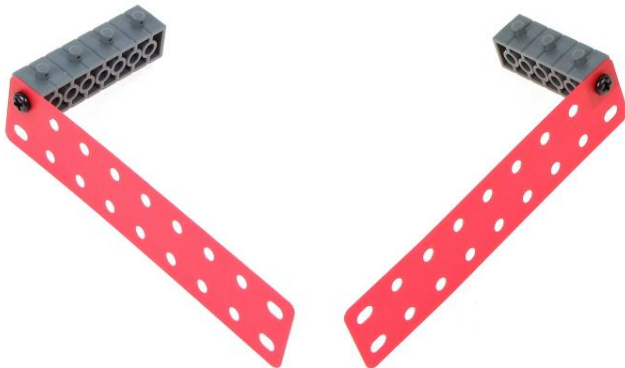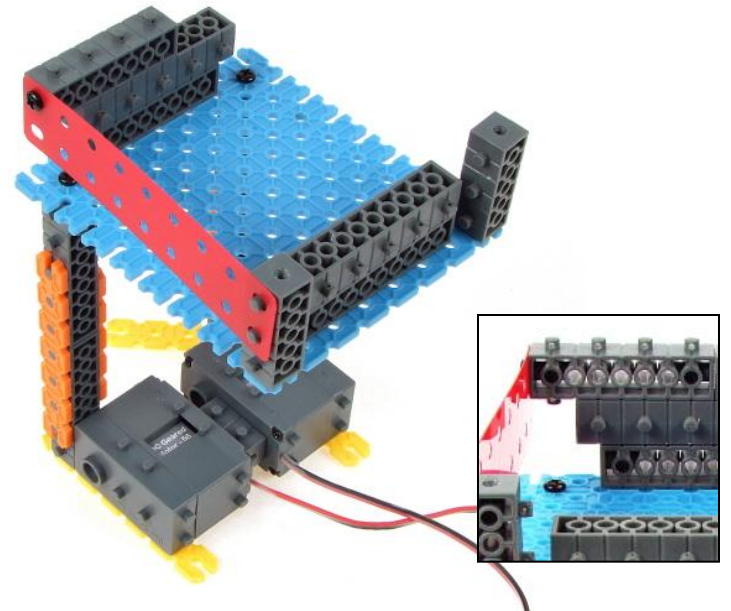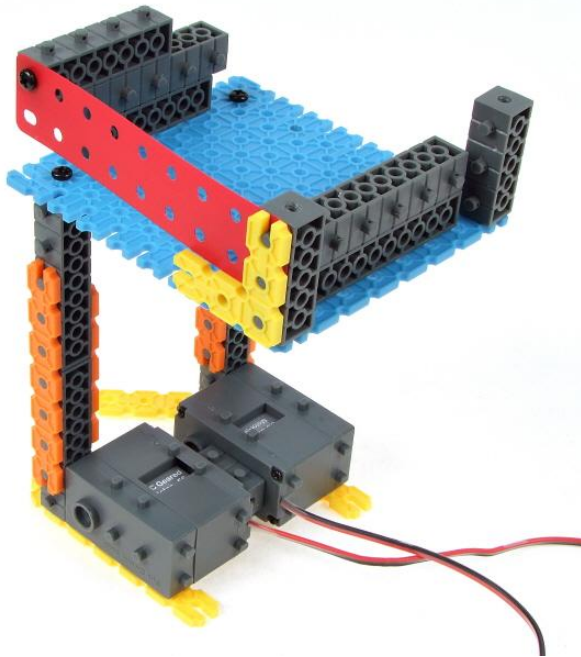
(L) X 2

X 2
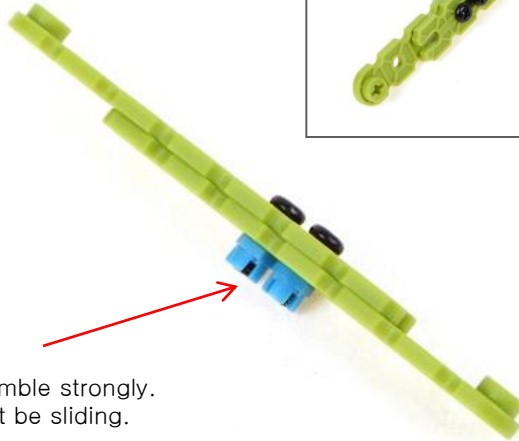
Do not assemble strongly.
Frames must be sliding.

15

X 1

16

X 1
X 2
(L) X 2
X 2

17

X 1

18
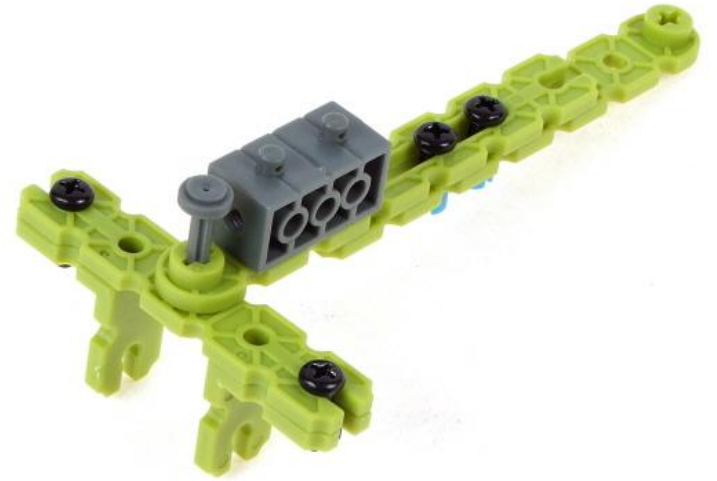
(M) X 1
X 1
X 2

19
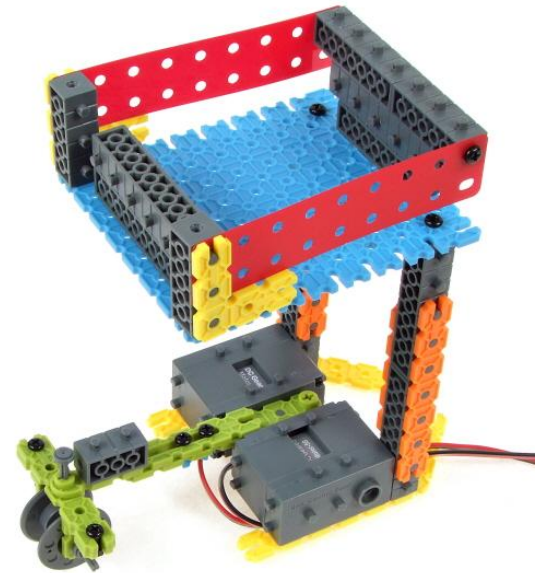
20

X 1

X 2
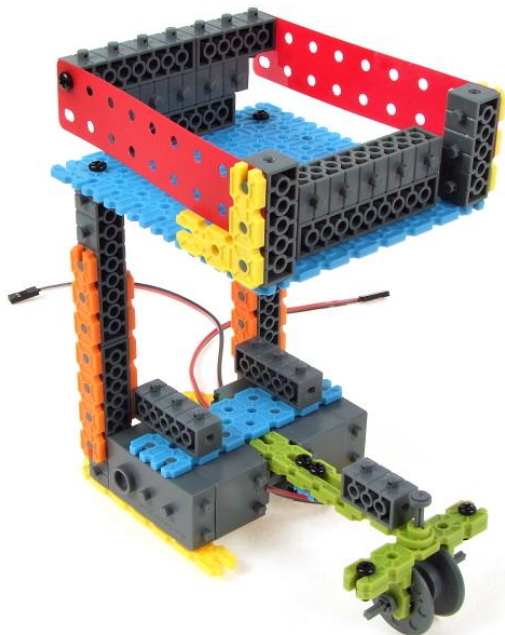
21

Motor axis X 1
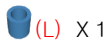
(L) X 1
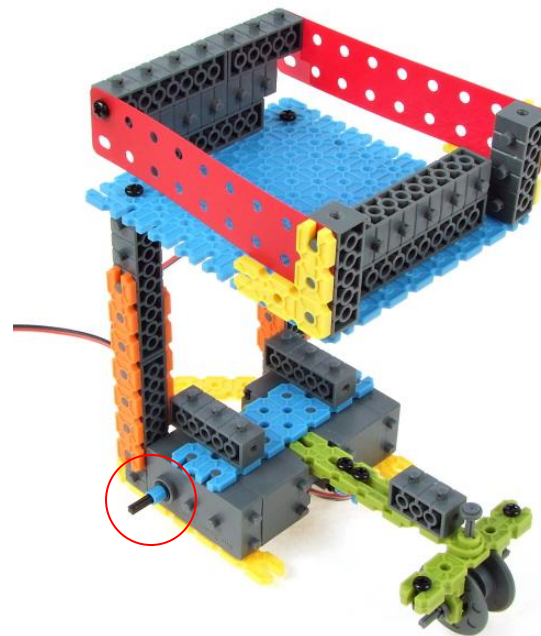
22

X 1
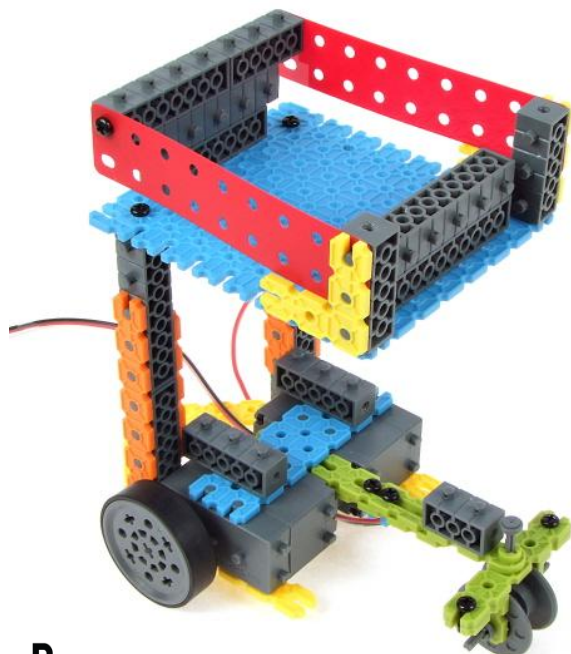
23

X 1

Motor axis X 1

(L) X 1
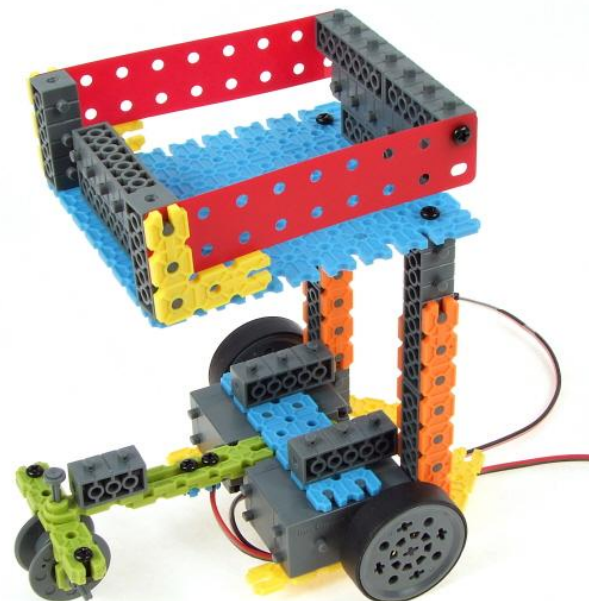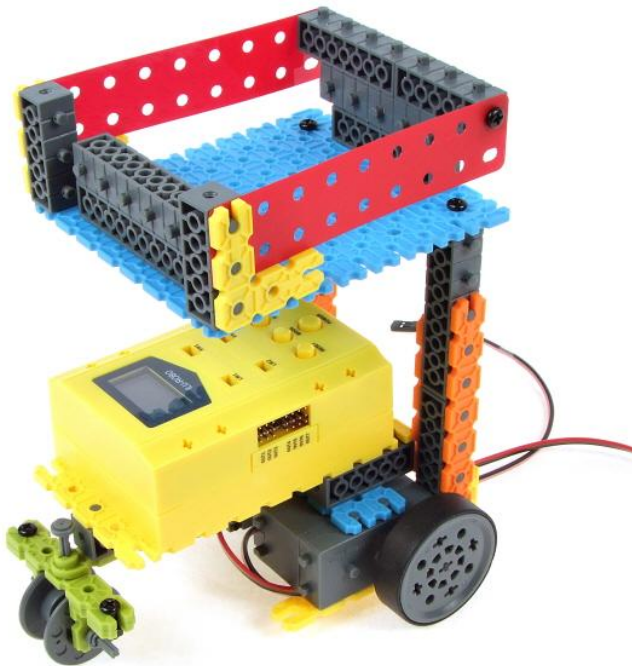
X 1
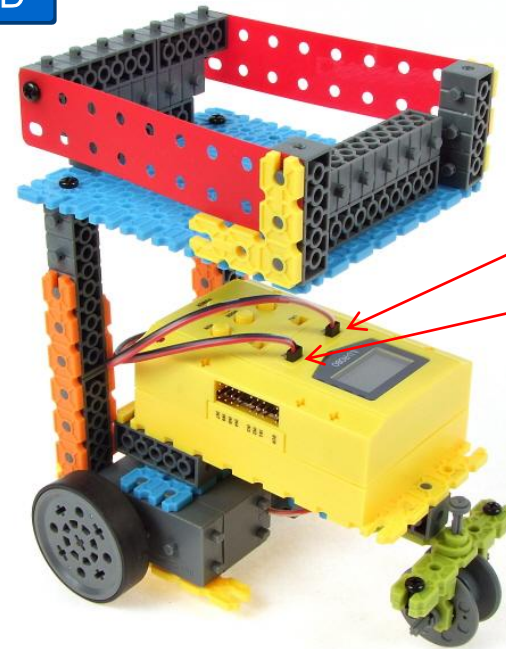
Left DC Motor
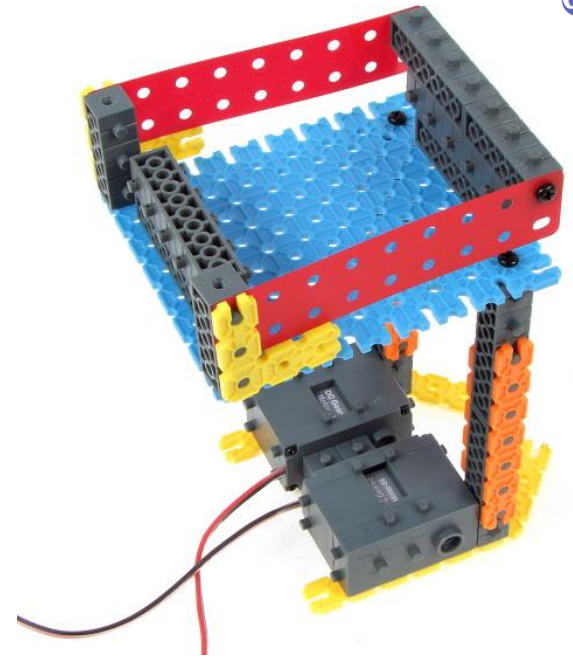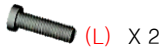
Right DC Motor

-. This carrier robot is simple model for exercising the DC motor programming.

-. You have to install the EQ-ROBO software to your computer

and making program to download and running the robot (without program, no working).

-. Download site : https://sites.google.com/site/eqrobo/eq-download

-. About the EQ-ROBO program algorithm, please refer to another manual.

UP   OK

LCD Setting
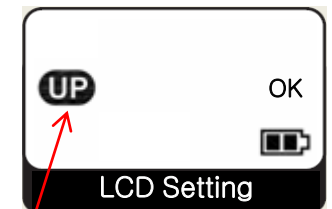
UP : User Programming mode

USER CREATIVE ROBOT

Part List of a Carrier robot

X 1

X 1

X 1

X 2

X 1

X 2

X 2

X 2

X 2

X 2

X 7

X 2

X 5

X 2

X 2

(L)　X 4

(S)　X 8

X 2

X 2

(L)　X 2

X 2

(M) X 1

X 1

Motor axis X 2

X 2

X 1

X 1