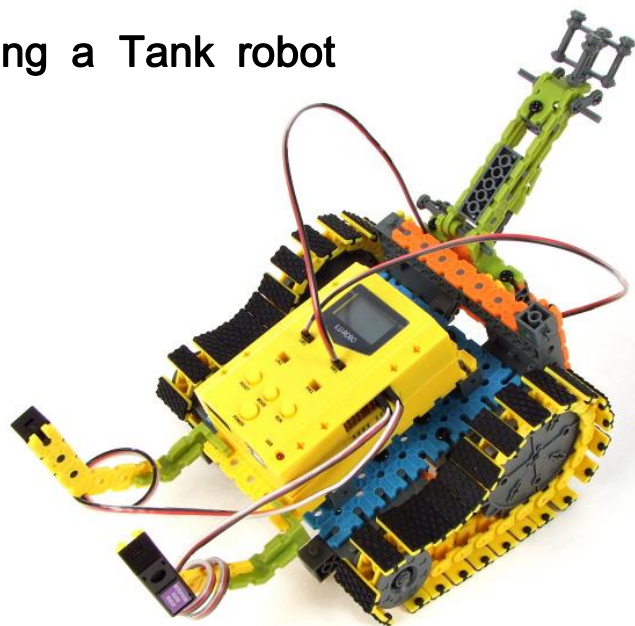


Making a Tank robot



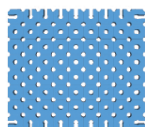
(S) : short
(M) : middle
(L) : long

1

- X 2
- X 2
- X 2
- X 1
- X 2
- (S) X 4



2

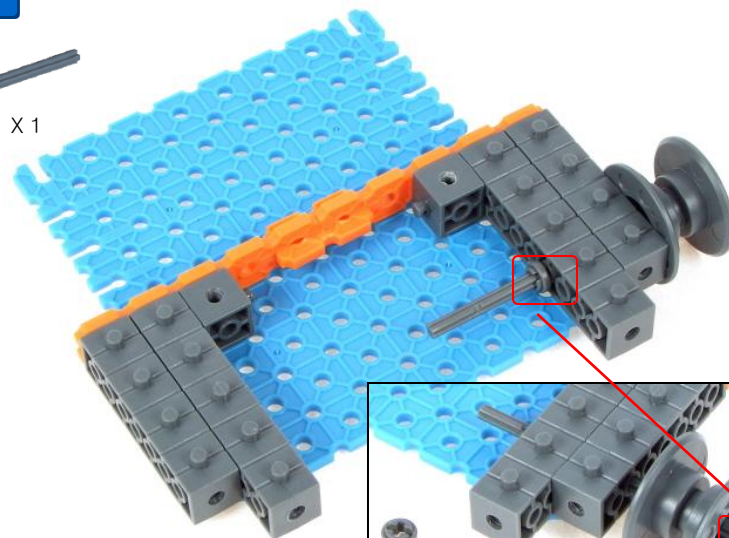


X 1

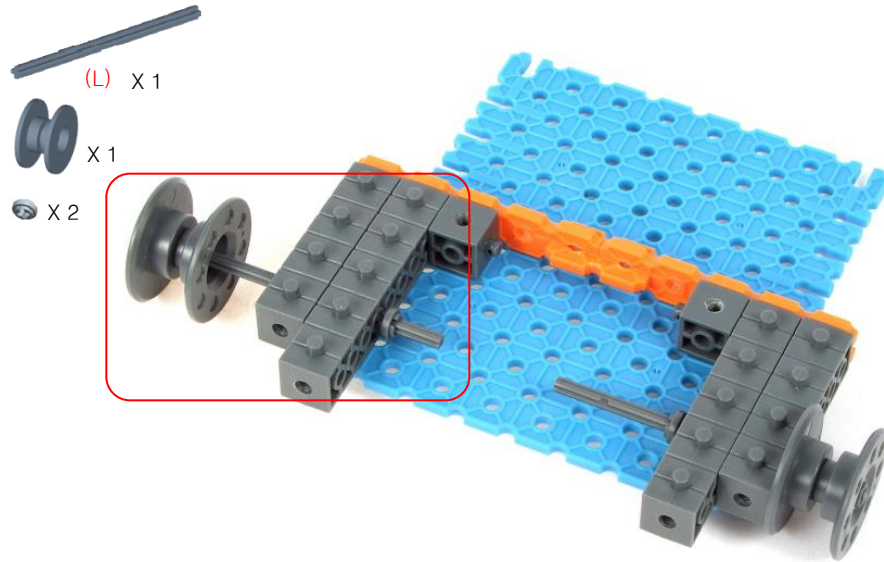


3

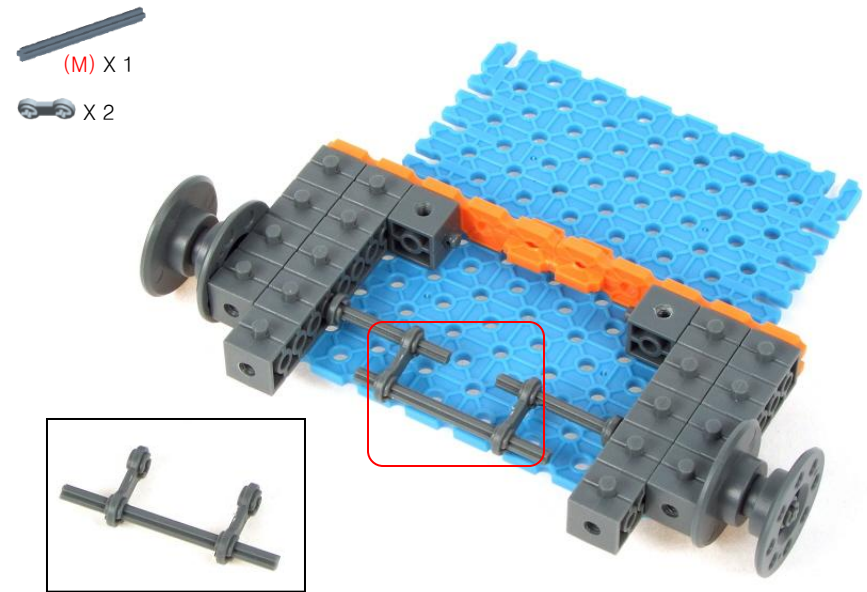
- (L) X 1
- X 1
- X 2



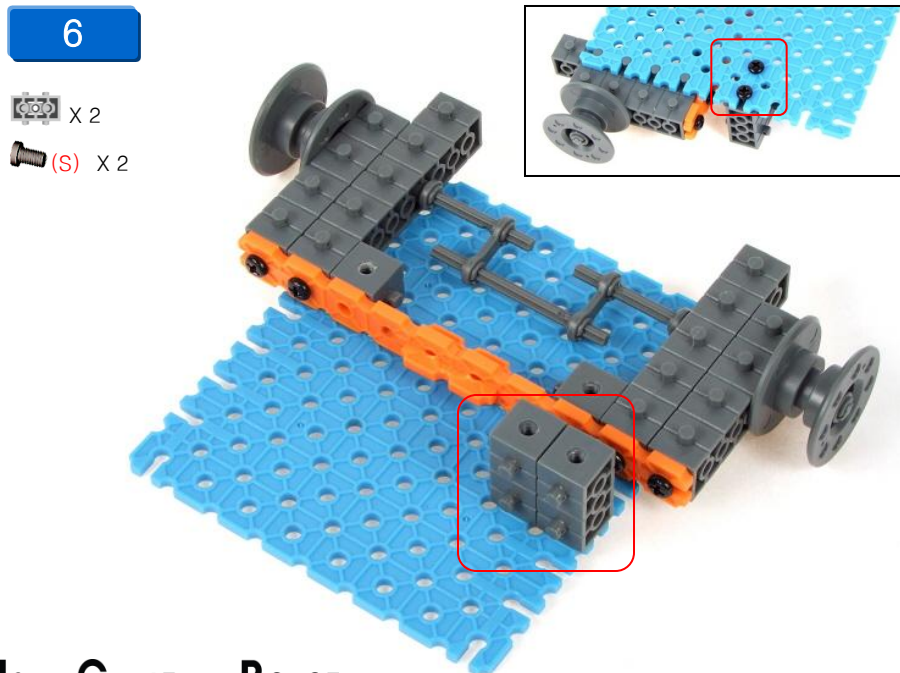
4



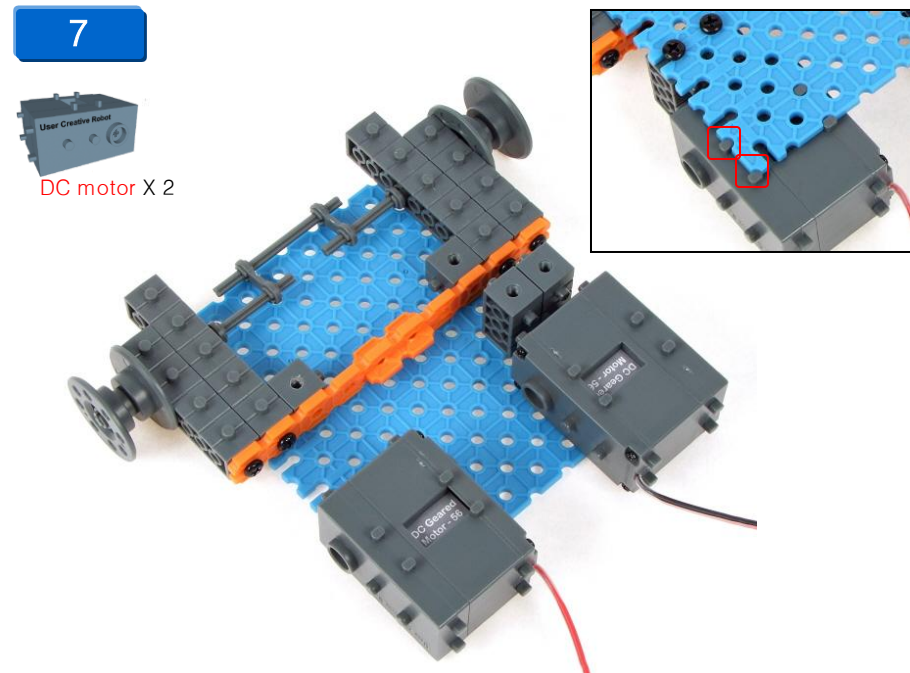
5



6



7



8

3000000C X 1

0000000 X 1

0000000 X 1

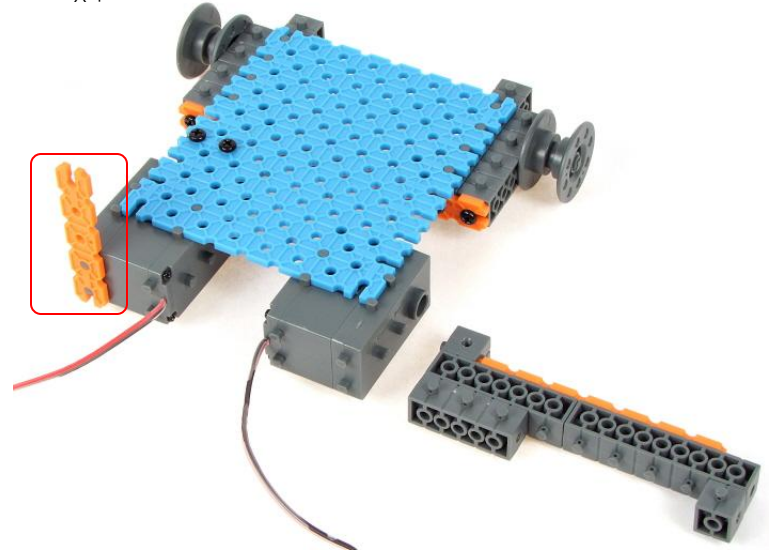
0000000 X 1

0 X 2



9

30000C X 1

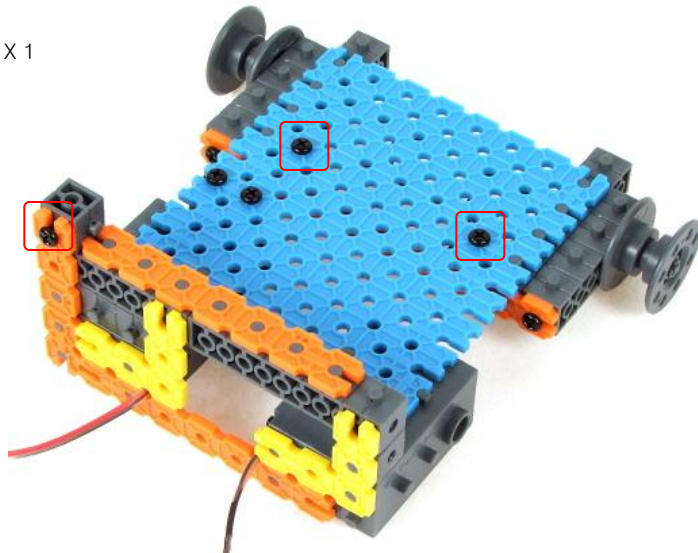


10

3000000C X 1

0000000 X 2

0 (S) X 3



11

3000000C X 1

30000C X 1

0000000 X 2

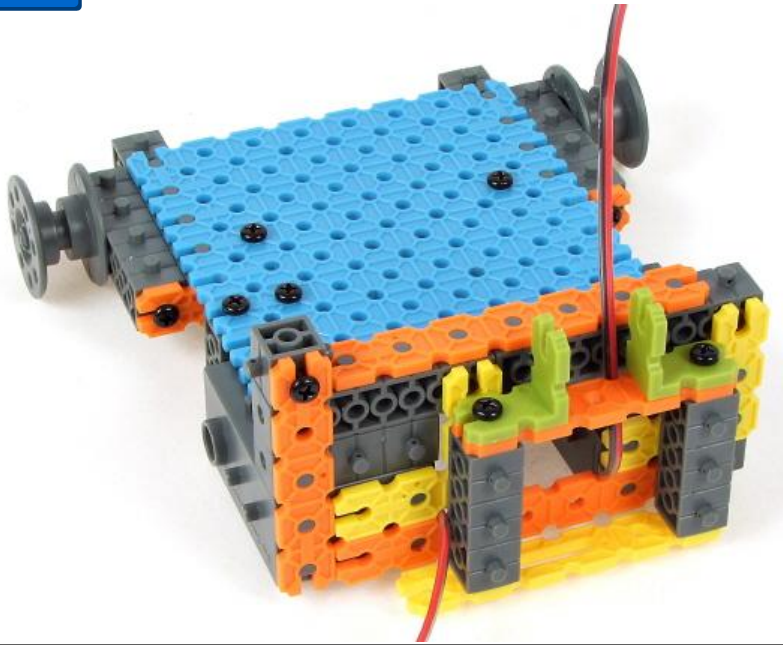
0 X 2

0 (L) X 2

0 (S) X 2



12



13

3000C X 1

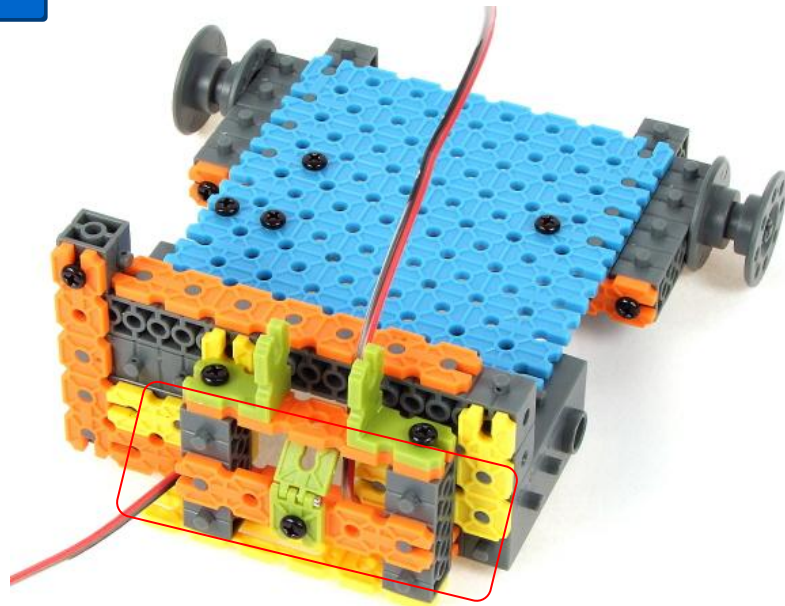
X 1

(L) X 1

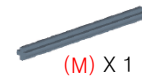
X 1



14



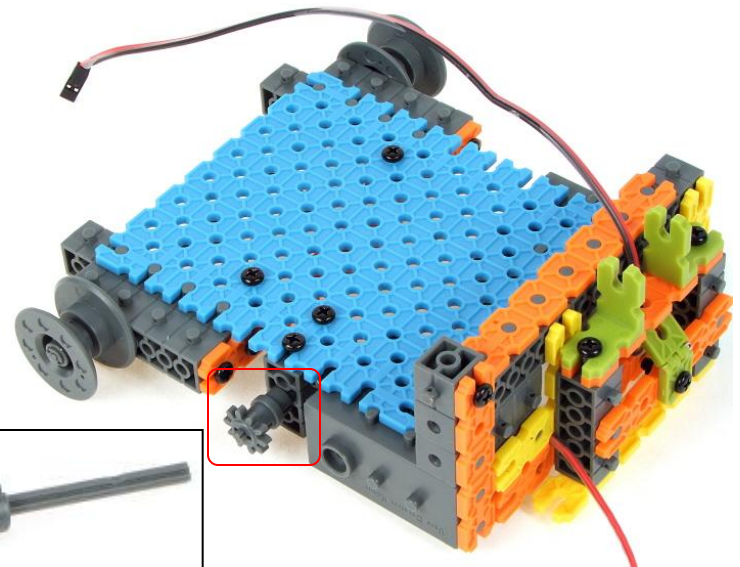
15



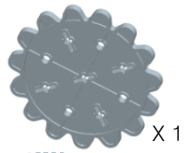
(M) X 1

X 1

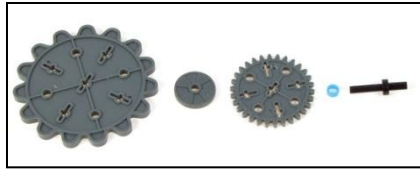
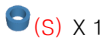
X 1



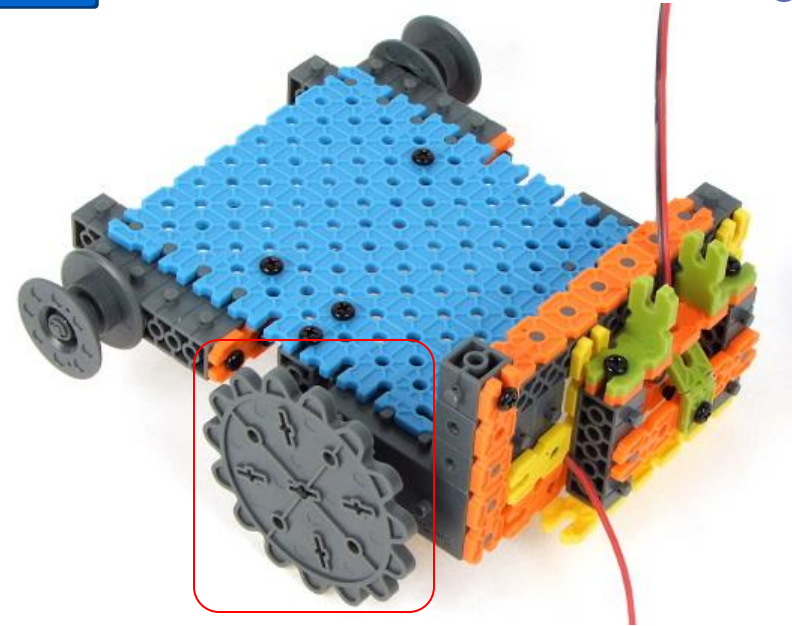
16



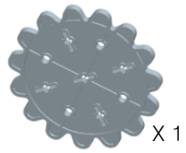
Motor axis X 1



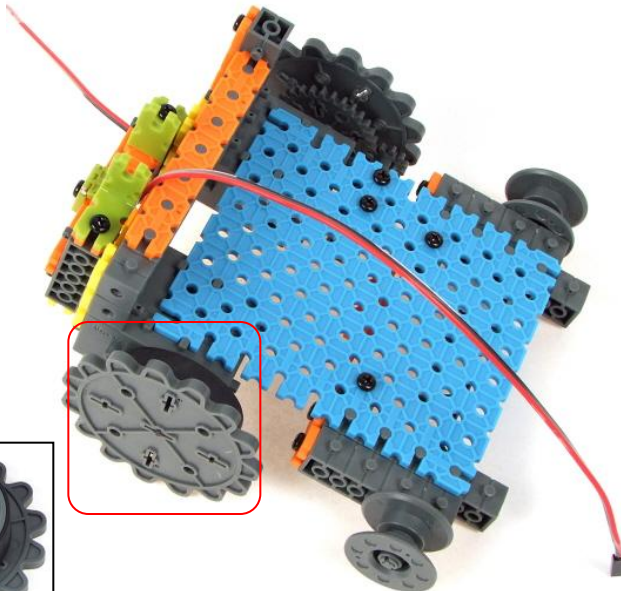
17



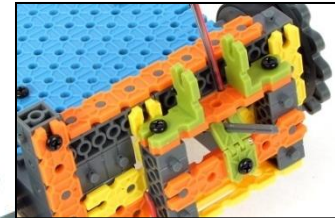
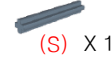
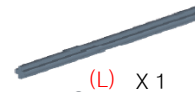
18



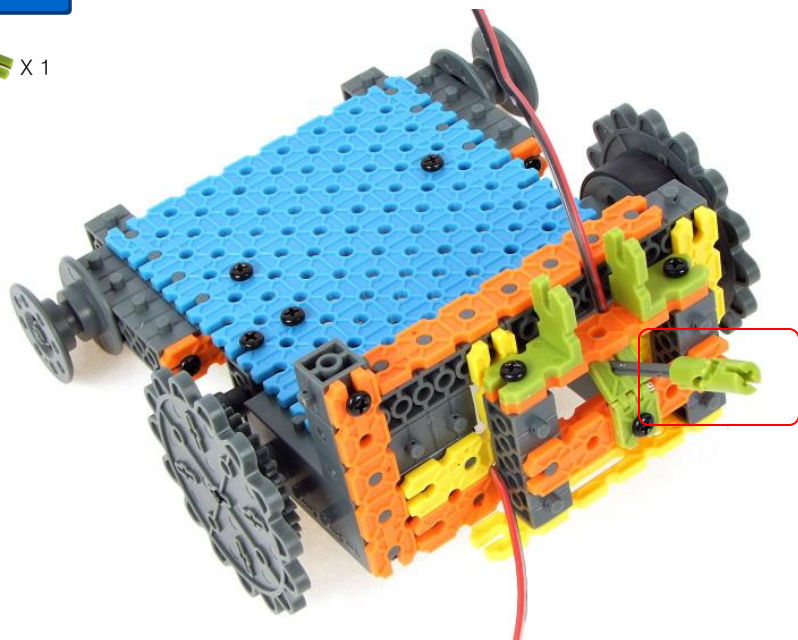
Motor axis X 1



19




20

 X 1


21


 X 2

 (M) X 1


 X 1

 X 1

 X 1

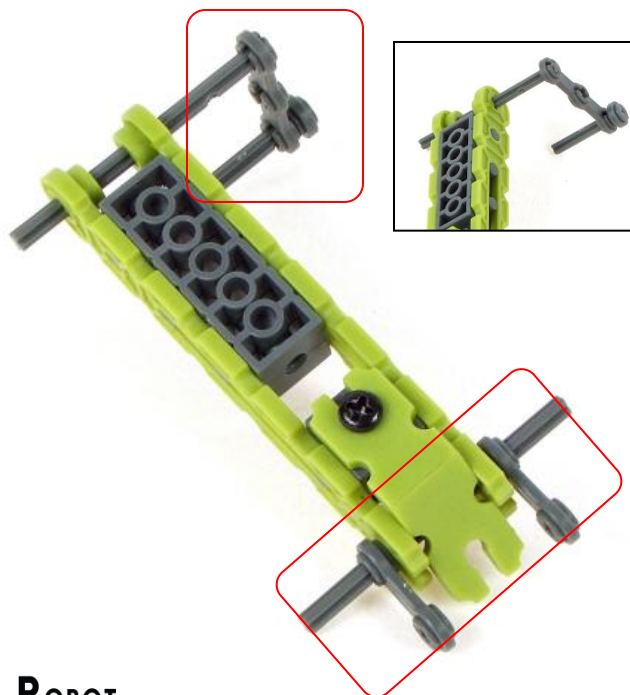
 (S) X 1


22

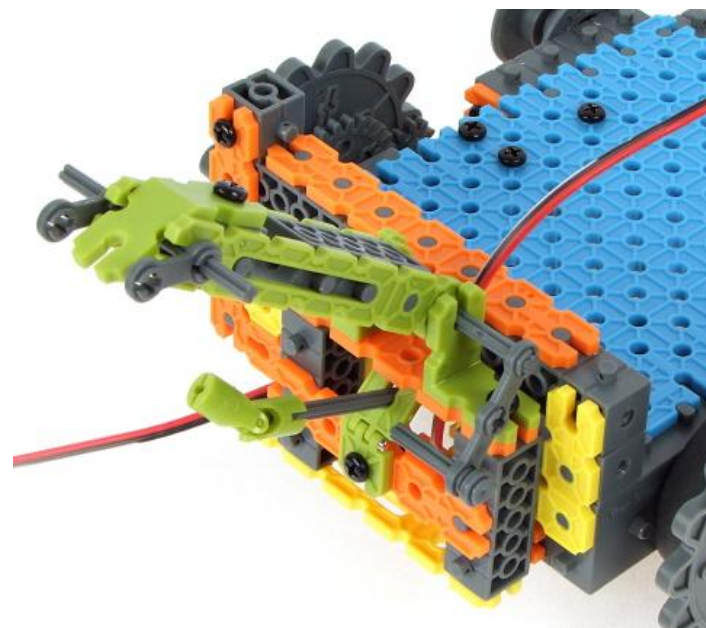
 (M) X 1

 X 1

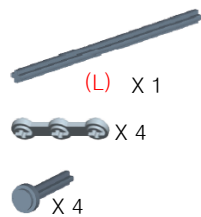
 X 2

 X 1


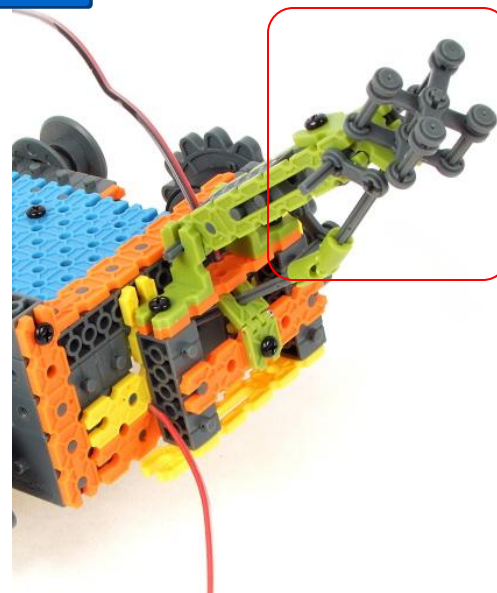
23



24



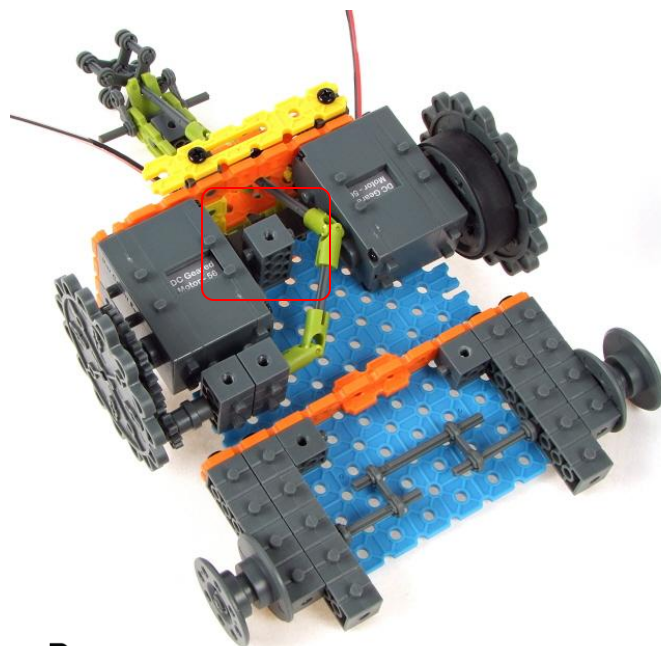
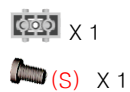
25



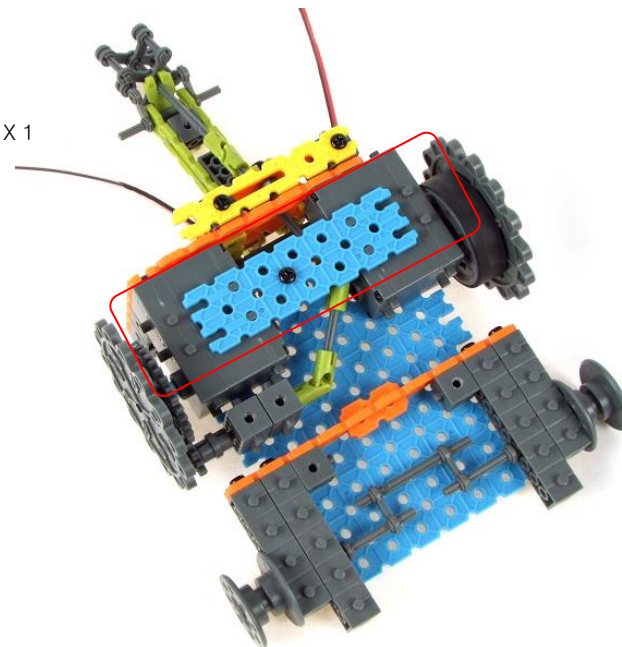
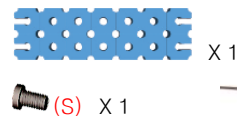
This is rotating by rotation of right wheel of tank.

Check the interruption of rotation carefully by frame.

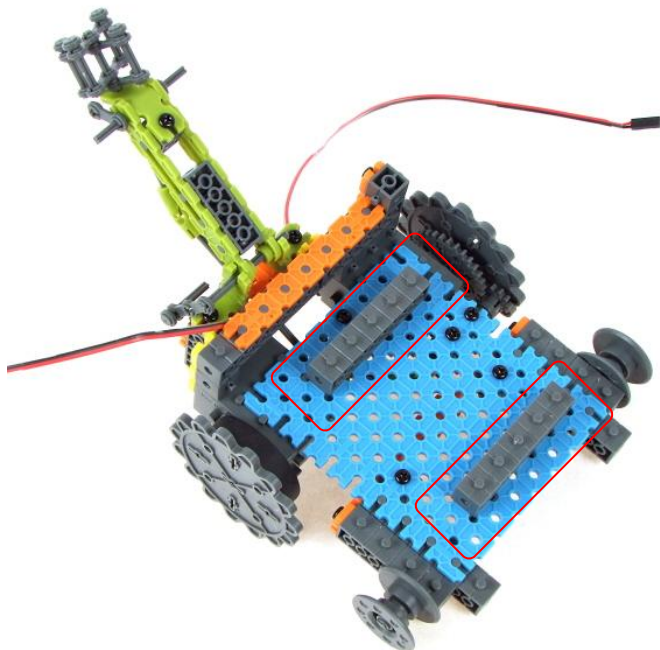
26



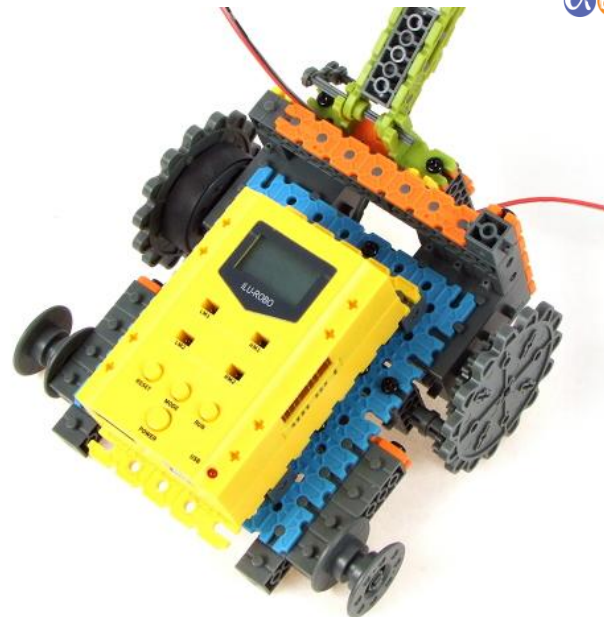
27



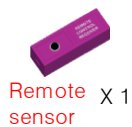
28



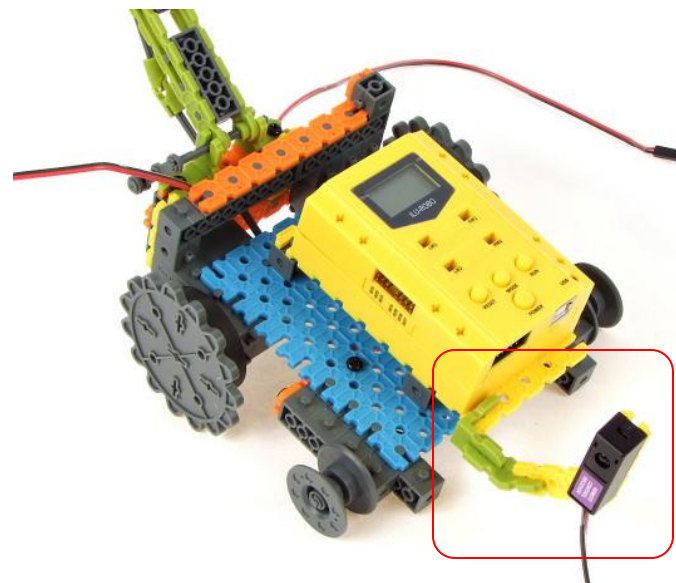
29



30



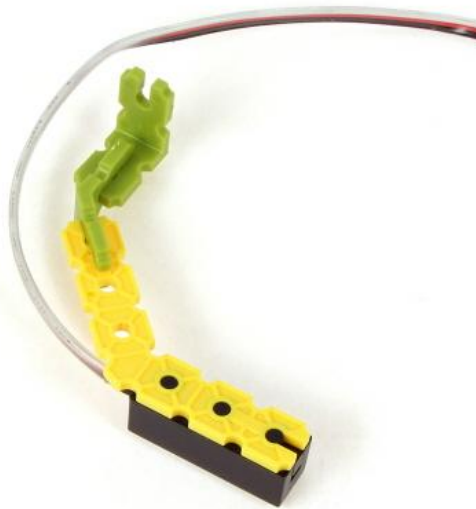
31



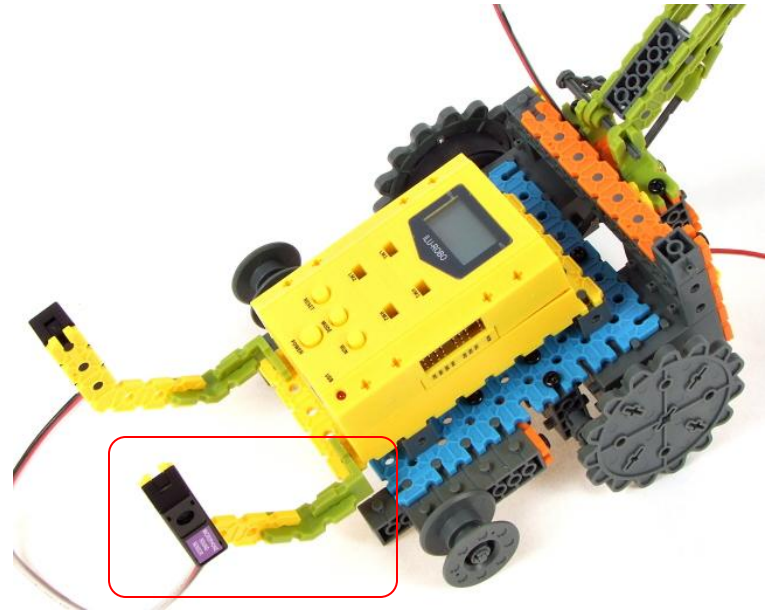
32



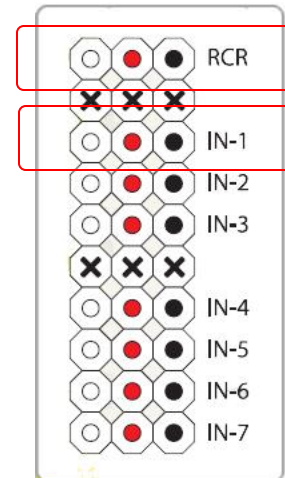
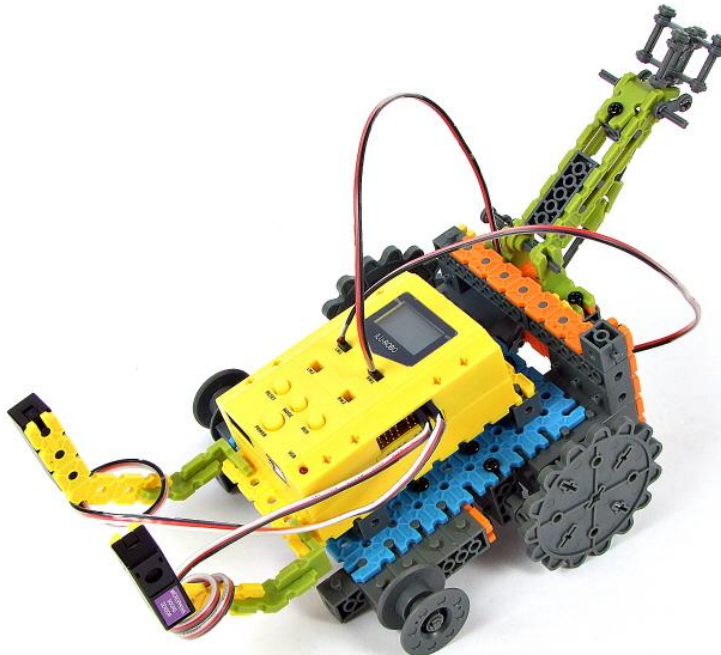
Mic sensor X 1



33



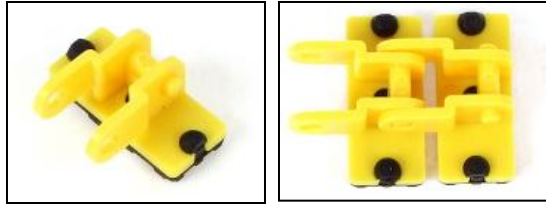
34



Connect Remote sensor

Connect Mic sensor

35

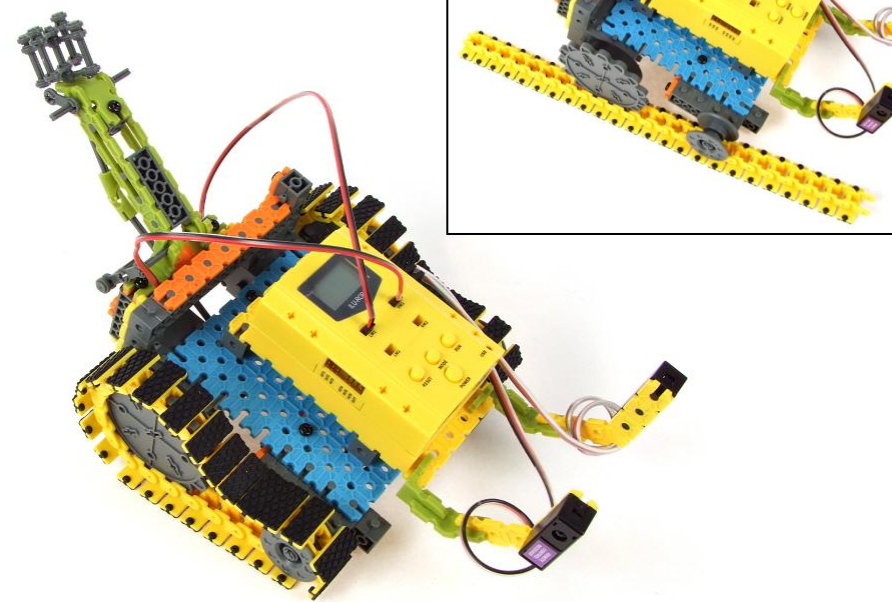


Right side : 24 ea

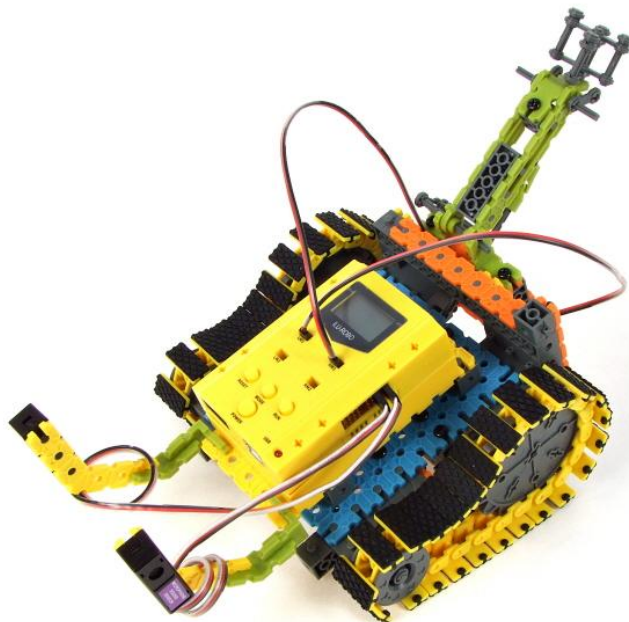


Left side : 24 ea

36



END



BP



[Remote Control]

①



LCD Setting

BP



[Sound reaction]

①



LCD Setting

Part List of a Tank robot

