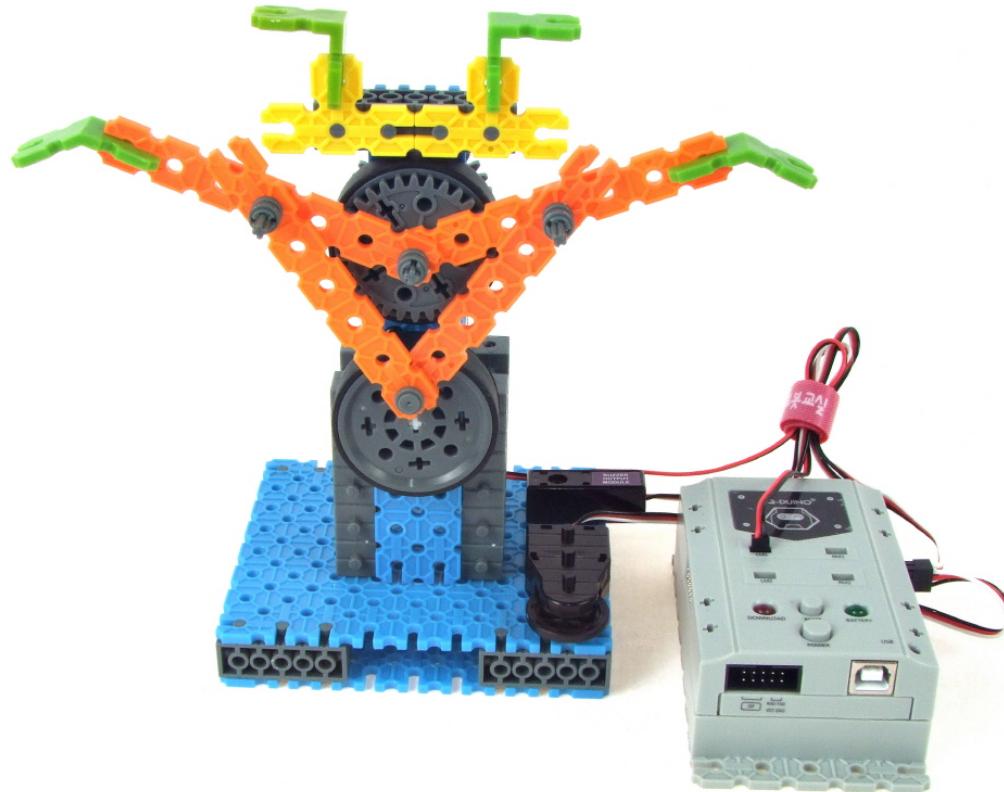
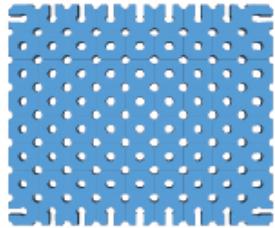


## 2. Bird Robot

If you press the touch sensor, DC motor starts to run the wing and turn on the buzzer every 0.5 second. If the touch sensor is not pressed all stop.



## Part List



X 2



X 1



X 4



X 3



X 2



X 1



X 1



X 4



X 2



X 2



X 2



X 1



DCshaft X 1



Touch X 1



Buzzer X 1



(L) X 1



X 2



X 2



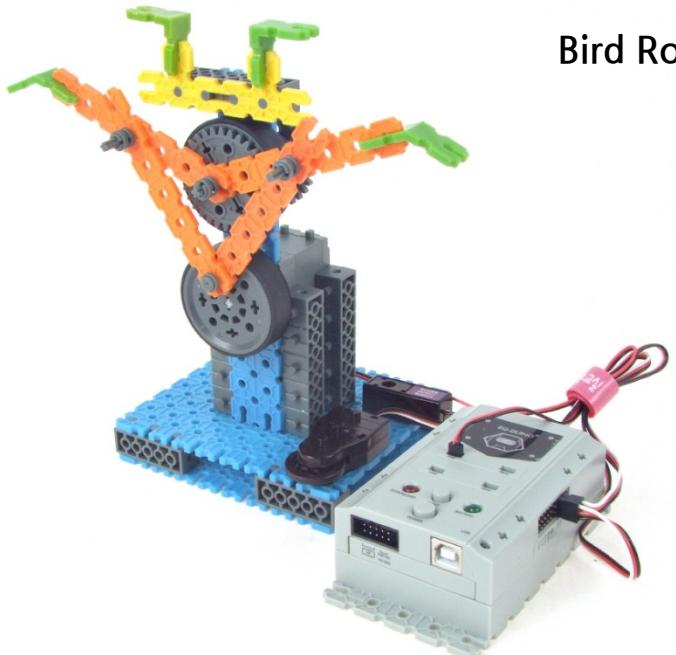
X 3



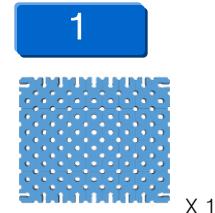
(S) X 5



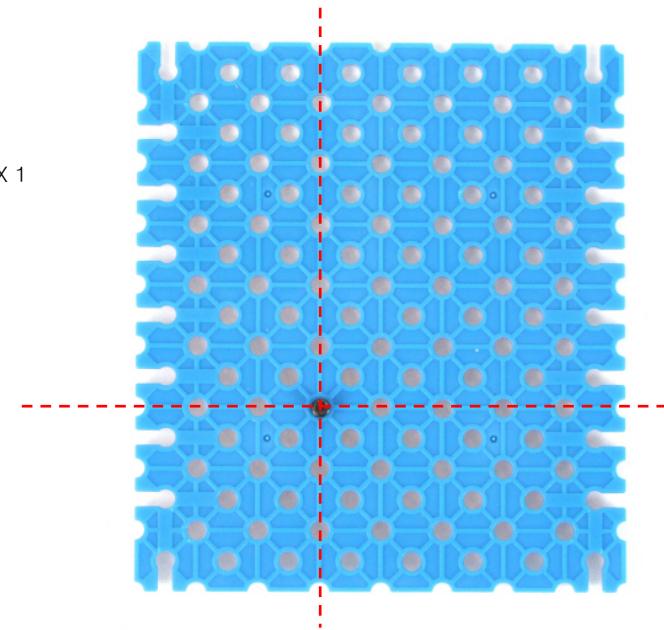
X 6



Bird Robot

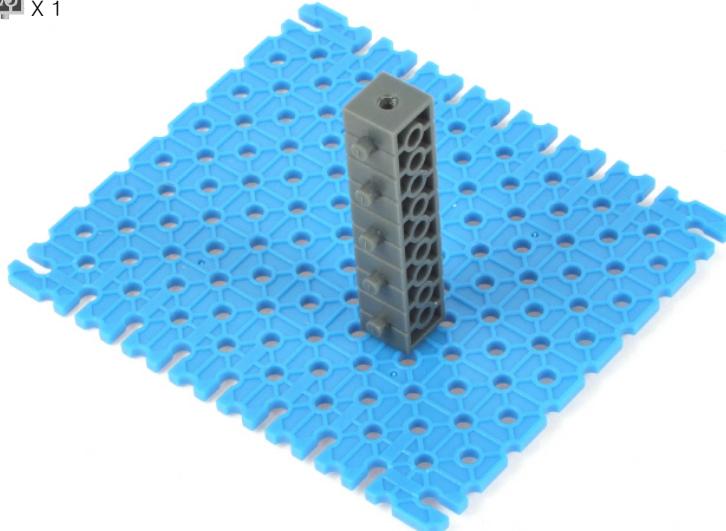


● (Short) X 1



2

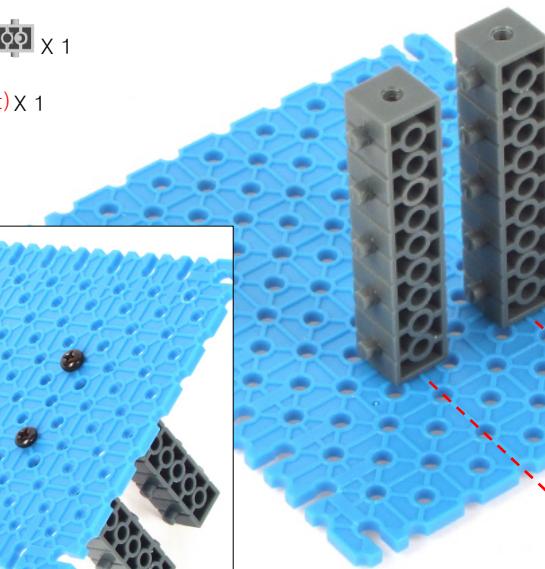
● X 1



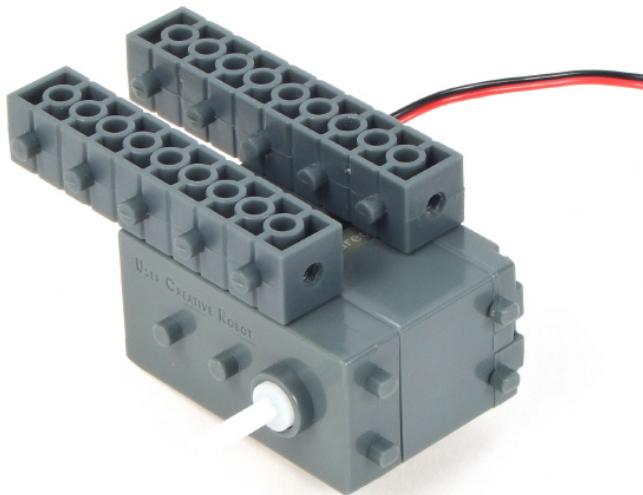
3

● X 1

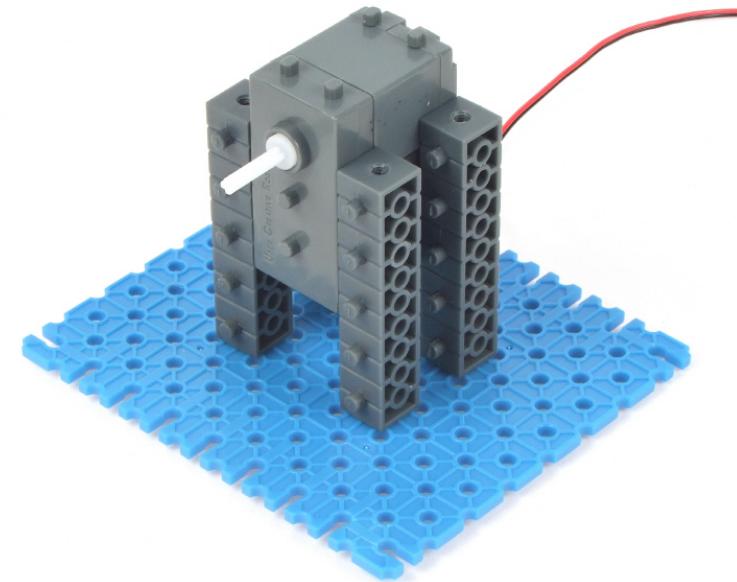
● (Short) X 1



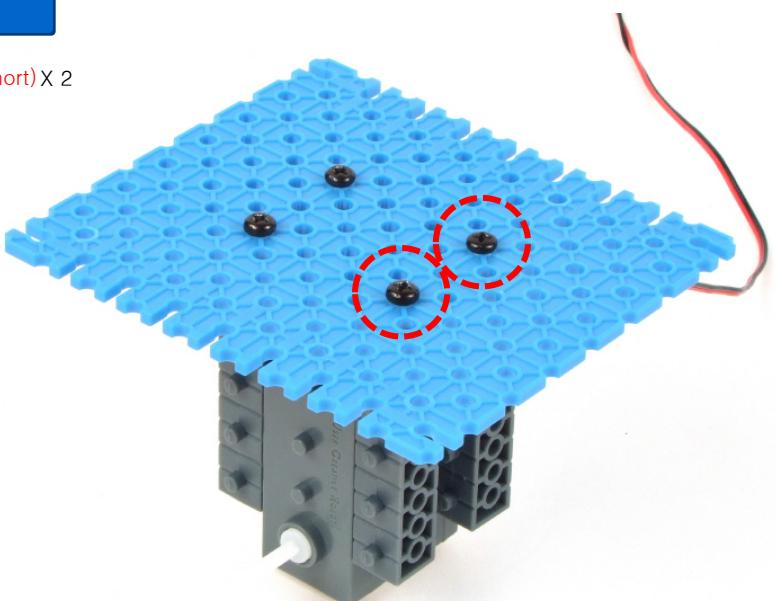
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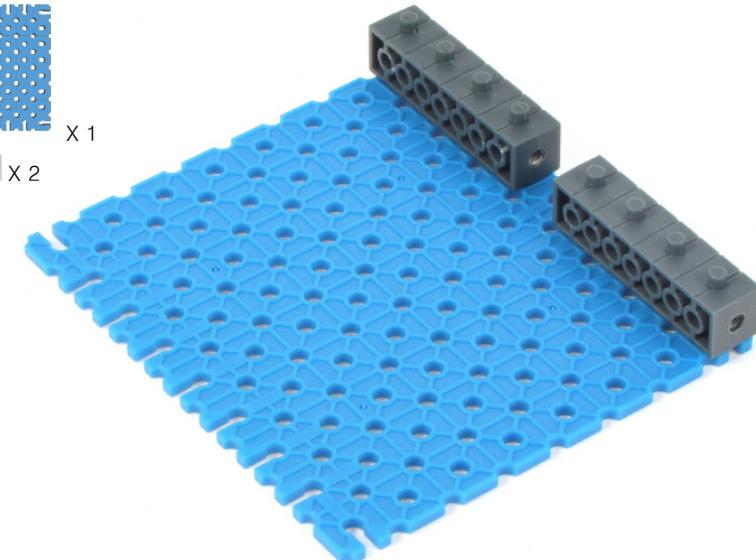
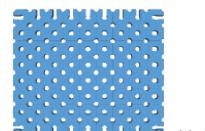
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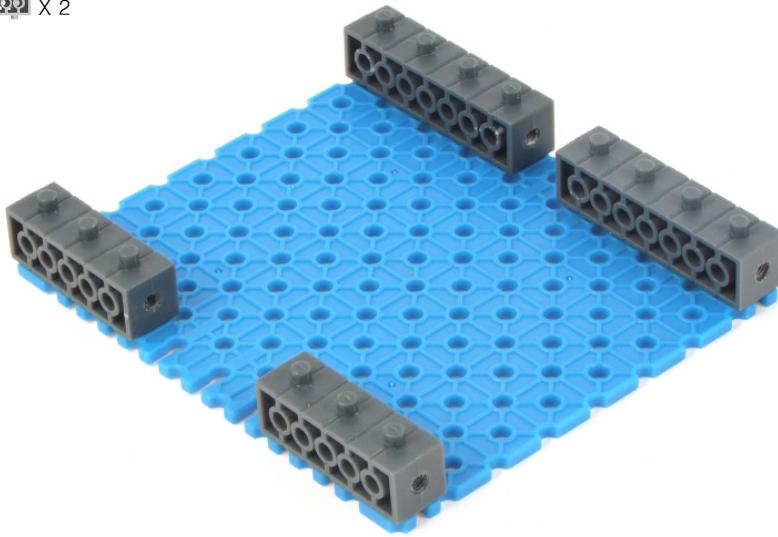
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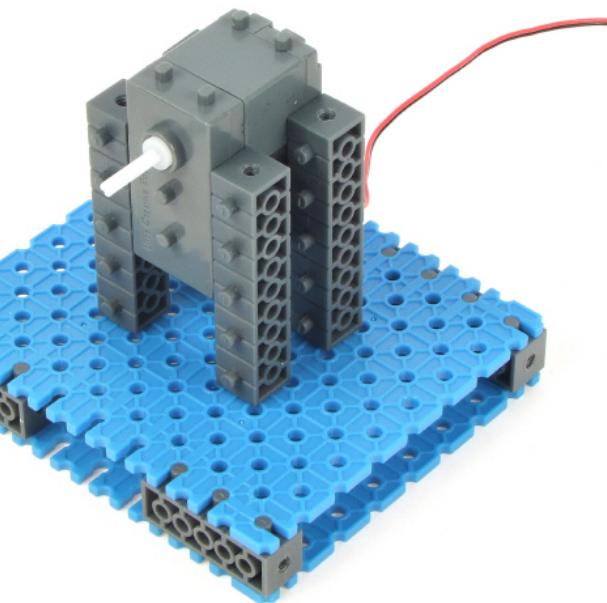
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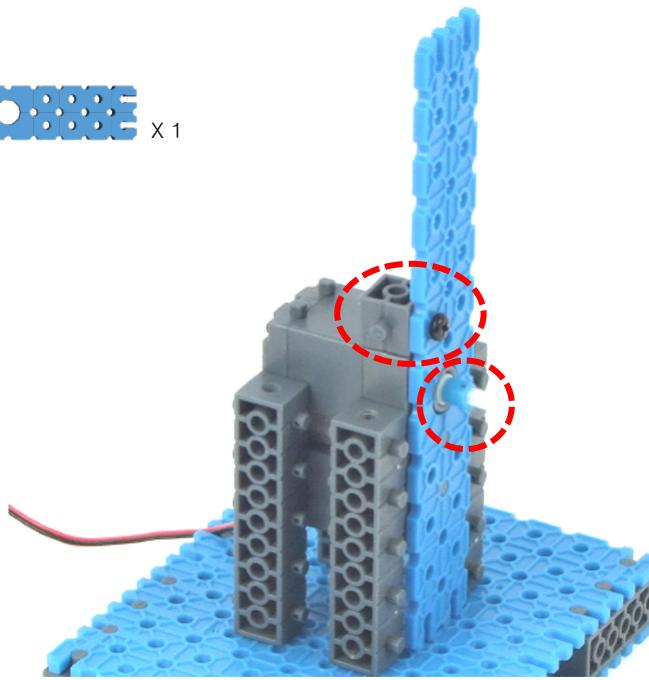
8

 X 2

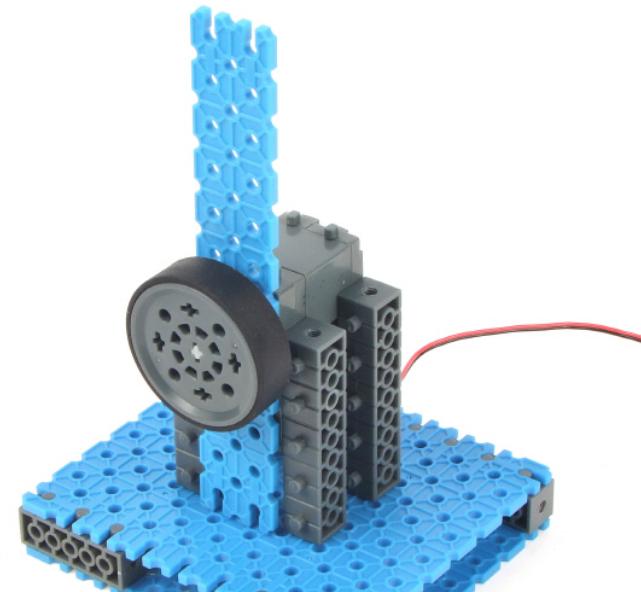
9



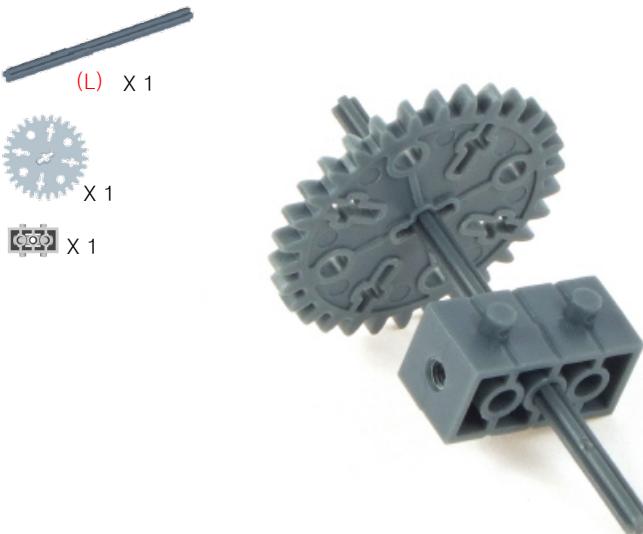
10

 X 1 (L) X 1 X 1 (Short) X 1

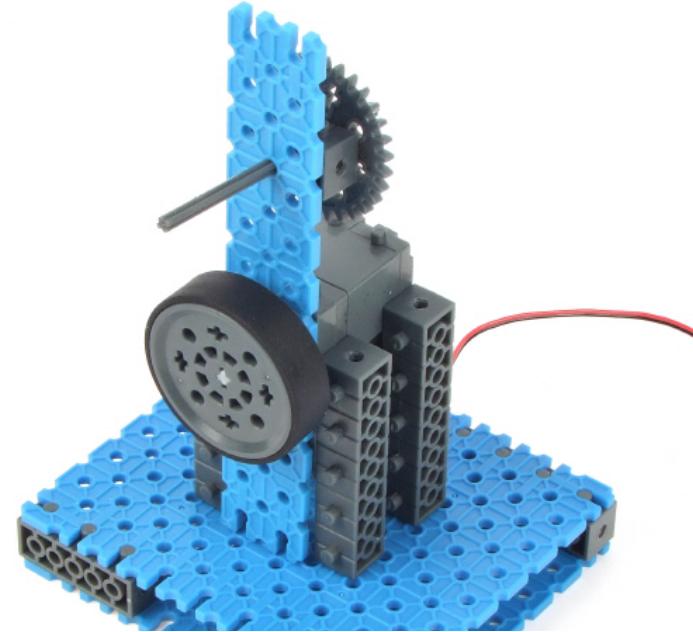
11

 X 1

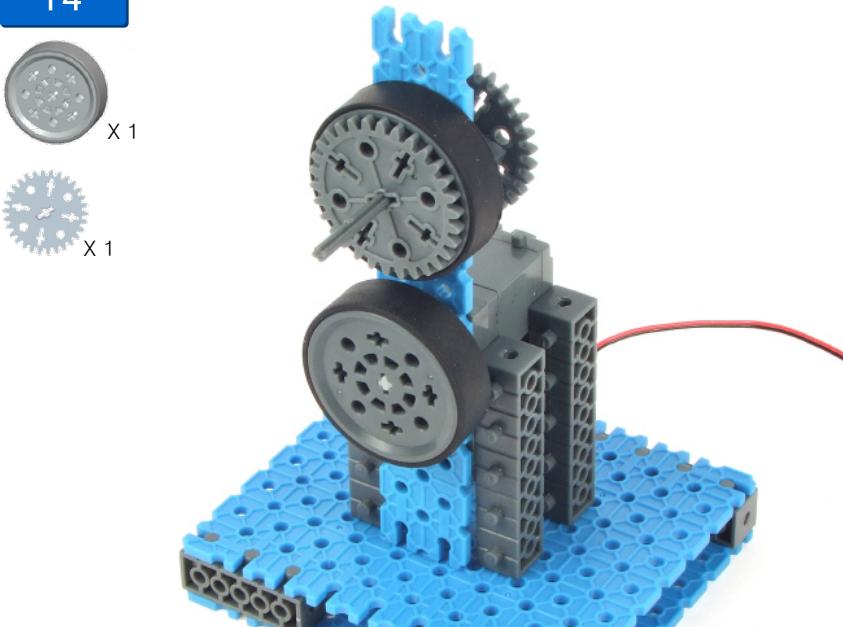
12



13



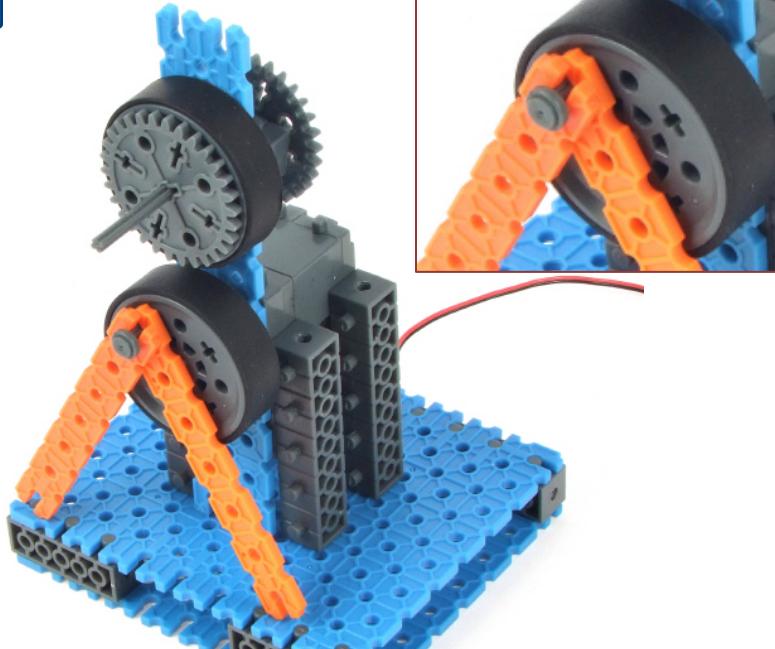
14



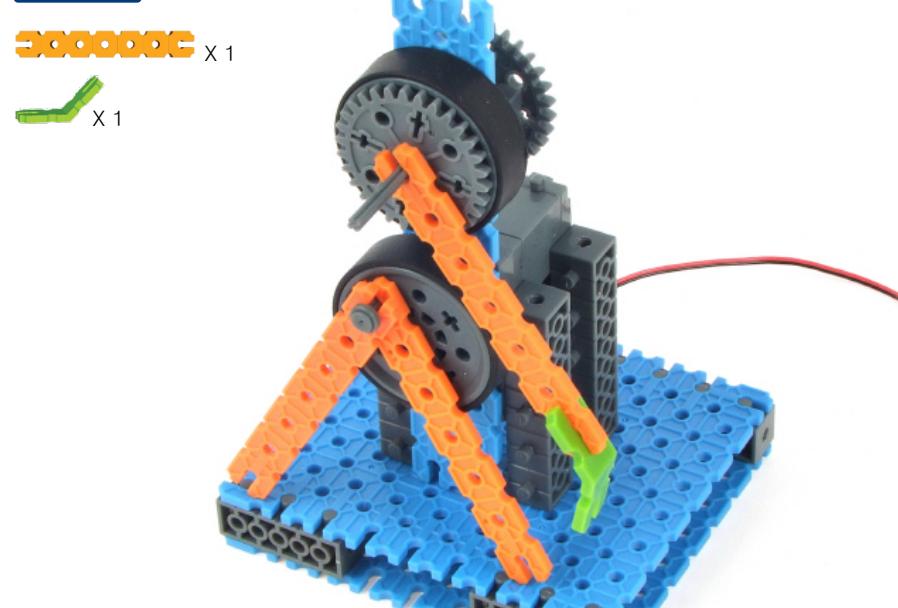
15



16

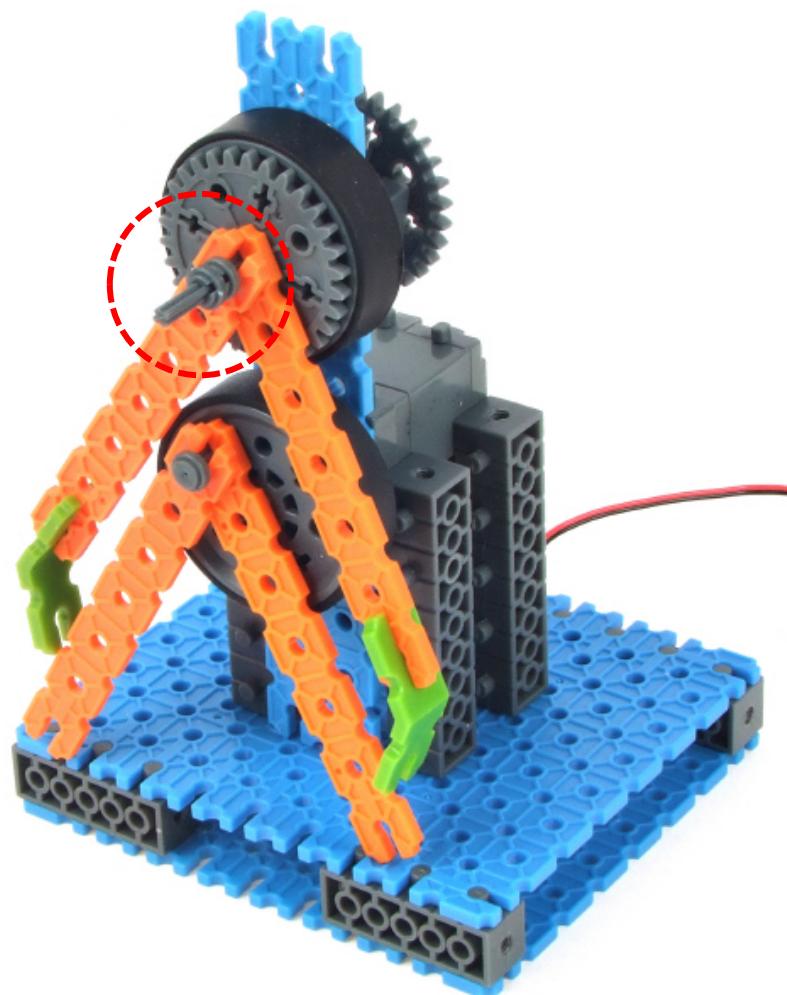


17



18

oooooooo x 1  
green L-linker x 1  
grey Technic connector x 2



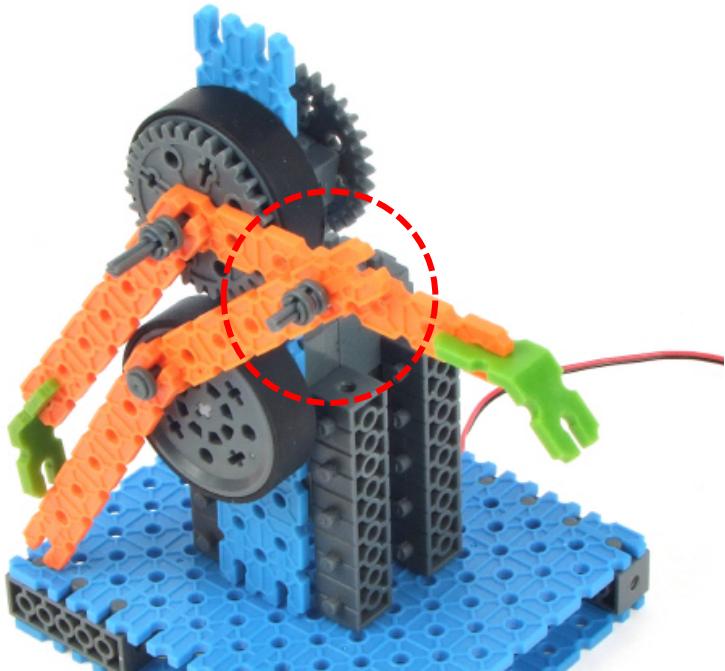
19



X 1



X 2



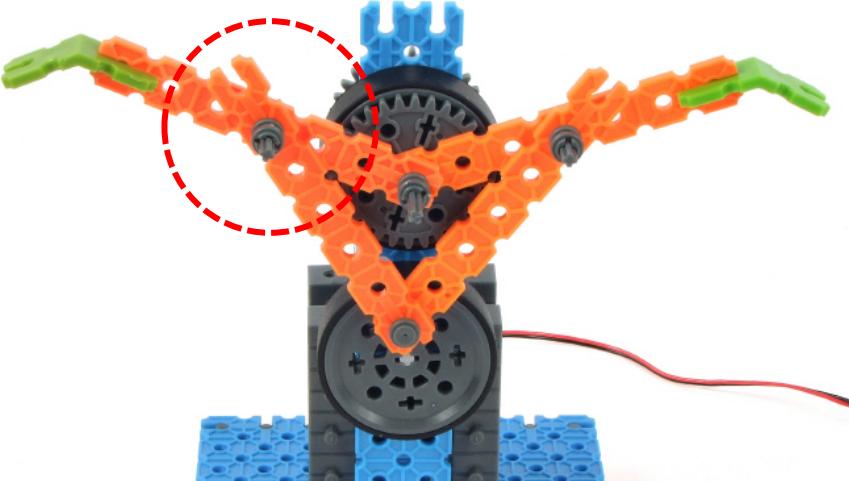
20



X 1



X 2



21



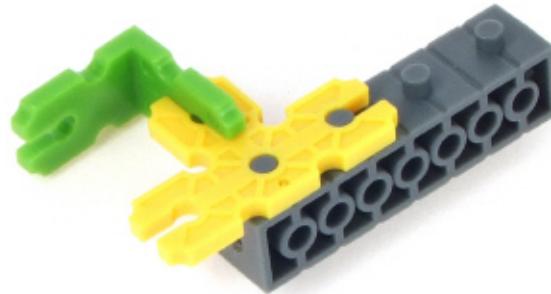
X 1



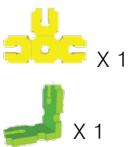
X 1



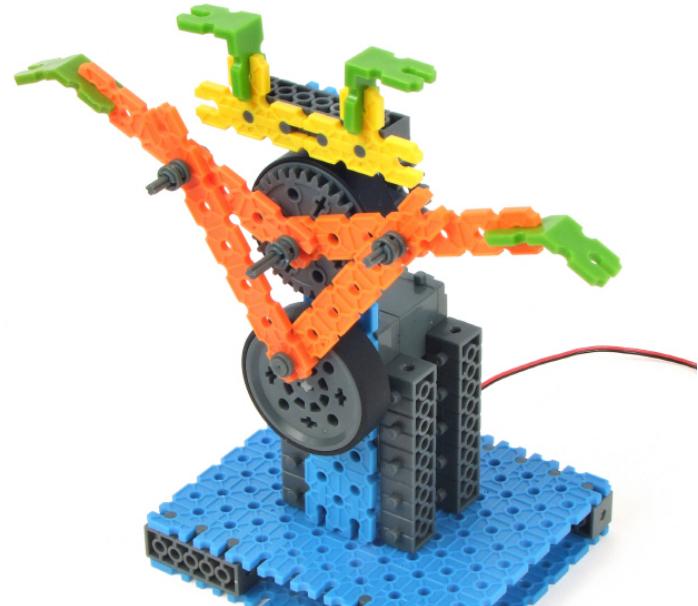
X 1



22



23



Finish



Touch X 1



Buzzer X 1



ucrobot@ucrobot.com



Connect to the main controller

