

# ***Partial Differential Equations***

- Equations that contain derivatives with respect to more than one variable
- Derivatives can be with respect to position in multiple dimensions of space
- Derivatives can be with respect to both space and time

# Navier-Stokes Equations

The diagram illustrates the Navier-Stokes equations with labels for each term. The main equation is:

$$\frac{\delta \mathbf{u}}{\delta t} = \nu \nabla \cdot (\nabla \mathbf{u}) - (\mathbf{u} \cdot \nabla) \mathbf{u} + \mathbf{F}_{body} - \frac{1}{\rho} \nabla p$$

Labels and arrows pointing to the terms:

- viscous drag** points to  $\nu \nabla \cdot (\nabla \mathbf{u})$
- convection** points to  $(\mathbf{u} \cdot \nabla) \mathbf{u}$
- gravity** points to  $\mathbf{F}_{body}$
- pressure** points to  $\frac{1}{\rho} \nabla p$
- mass conservation** points to  $\nabla \cdot \mathbf{u} = 0$
- viscosity** points to  $\nu$
- density** points to  $\rho$
- pressure** points to  $p$

The continuity equation is also shown:

$$\nabla \cdot \mathbf{u} = 0$$

The Navier-Stokes equations describe the flow of a fluid like air or water.

# Maxwell's Equations

$$\nabla \cdot \mathbf{E} = \frac{\rho_v}{\epsilon} \quad (\text{Gauss' Law})$$

$$\nabla \cdot \mathbf{H} = 0 \quad (\text{Gauss' Law for Magnetism})$$

$$\nabla \times \mathbf{E} = -\mu \frac{\partial \mathbf{H}}{\partial t} \quad (\text{Faraday's Law})$$

$$\nabla \times \mathbf{H} = \mathbf{J} + \epsilon \frac{\partial \mathbf{E}}{\partial t} \quad (\text{Ampere's Law})$$

Maxwell's equations describe the behavior of an electromagnetic field.

# ***Linear Elasticity Equations***

$$\frac{\partial \sigma_{rr}}{\partial r} + \frac{1}{r} \frac{\partial \sigma_{r\theta}}{\partial \theta} + \frac{\partial \sigma_{rz}}{\partial z} + \frac{1}{r} (\sigma_{rr} - \sigma_{\theta\theta}) + F_r = \rho \frac{\partial^2 u_r}{\partial t^2}$$

$$\frac{\partial \sigma_{r\theta}}{\partial r} + \frac{1}{r} \frac{\partial \sigma_{\theta\theta}}{\partial \theta} + \frac{\partial \sigma_{\theta z}}{\partial z} + \frac{2}{r} \sigma_{r\theta} + F_\theta = \rho \frac{\partial^2 u_\theta}{\partial t^2}$$

$$\frac{\partial \sigma_{rz}}{\partial r} + \frac{1}{r} \frac{\partial \sigma_{\theta z}}{\partial \theta} + \frac{\partial \sigma_{zz}}{\partial z} + \frac{1}{r} \sigma_{rz} + F_z = \rho \frac{\partial^2 u_z}{\partial t^2}$$

The linear elasticity equations describe vibration, stress, and strain in an elastic solid.

# Schrödinger's Equation

## Schrödinger's Equation

$$i\hbar \frac{\partial}{\partial t} \psi(\mathbf{r}, t) = -\frac{\hbar^2}{2m} \nabla^2 \psi(\mathbf{r}, t) + V(\mathbf{r}, t) \psi(\mathbf{r}, t)$$

$i$  is the imaginary number,  $\sqrt{-1}$ .

$\hbar$  is Planck's constant divided by  $2\pi$ :  $1.05459 \times 10^{-34}$  joule-second.

$\psi(\mathbf{r}, t)$  is the wave function, defined over space and time.

$m$  is the mass of the particle.

$\nabla^2$  is the Laplacian operator,  $\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2}$ .

$V(\mathbf{r}, t)$  is the potential energy influencing the particle.

Schrödinger's equation of quantum dynamics describes the wave function of a particle.