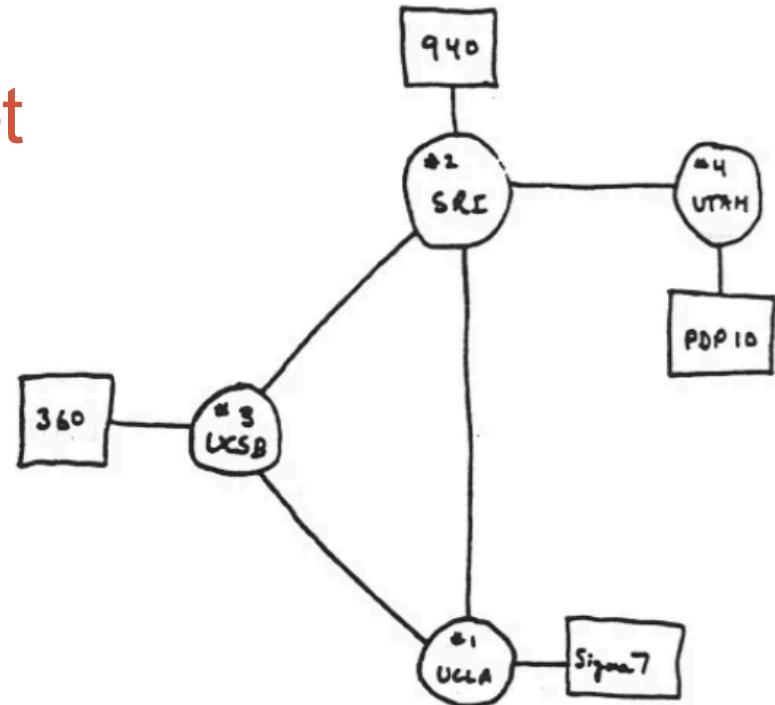


# GRAPHS

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# The first four nodes of the internet



THE ARPA NETWORK

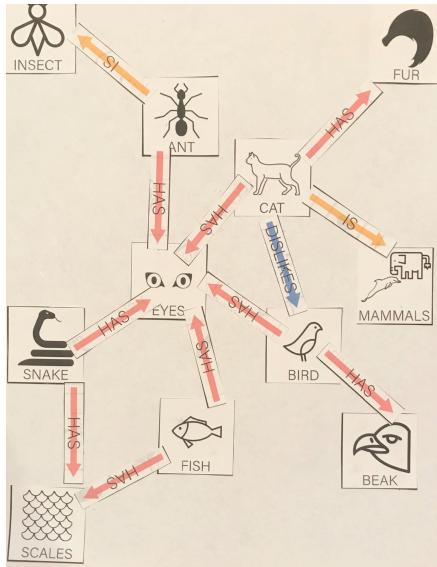
DEC 1969

The IBM 360, the IMP, and the workstations were all located in North Hall.  
<https://jeweledplatypus.org/news/text/ucsbnet.html>

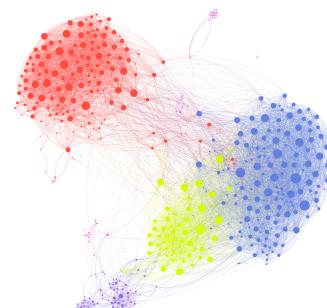
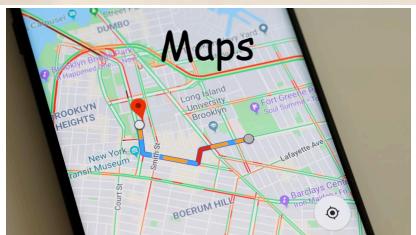
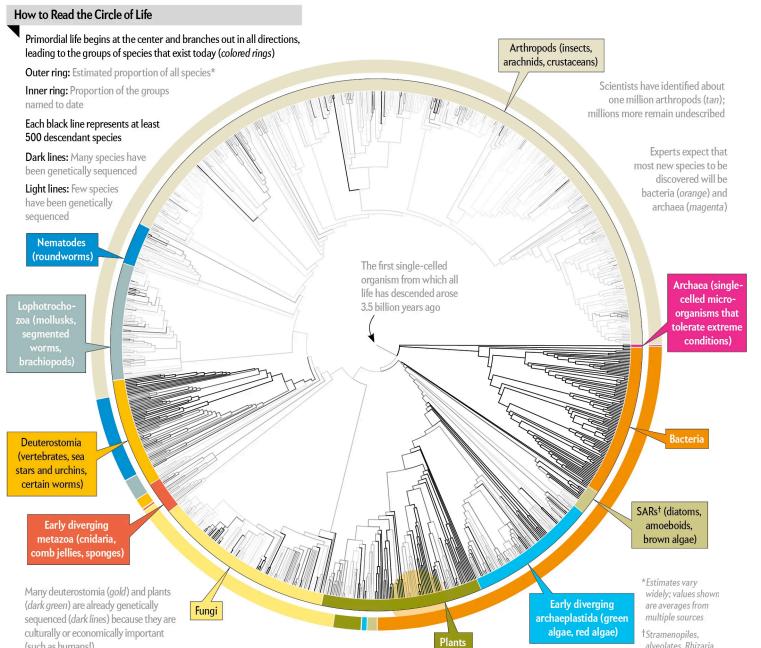
4 NODES

# Graphs: applications

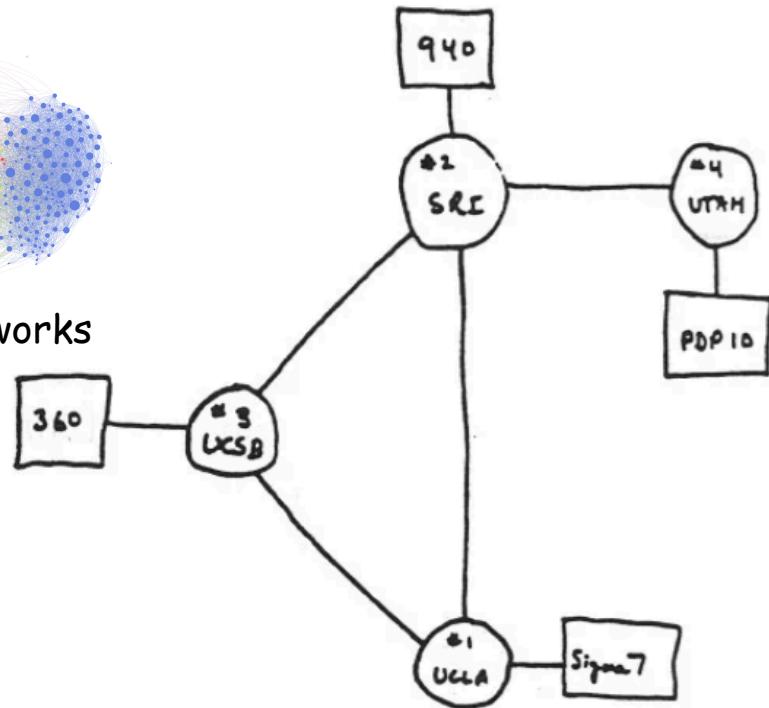
## Semantic networks



## Biological networks



## Social networks



4 NODES

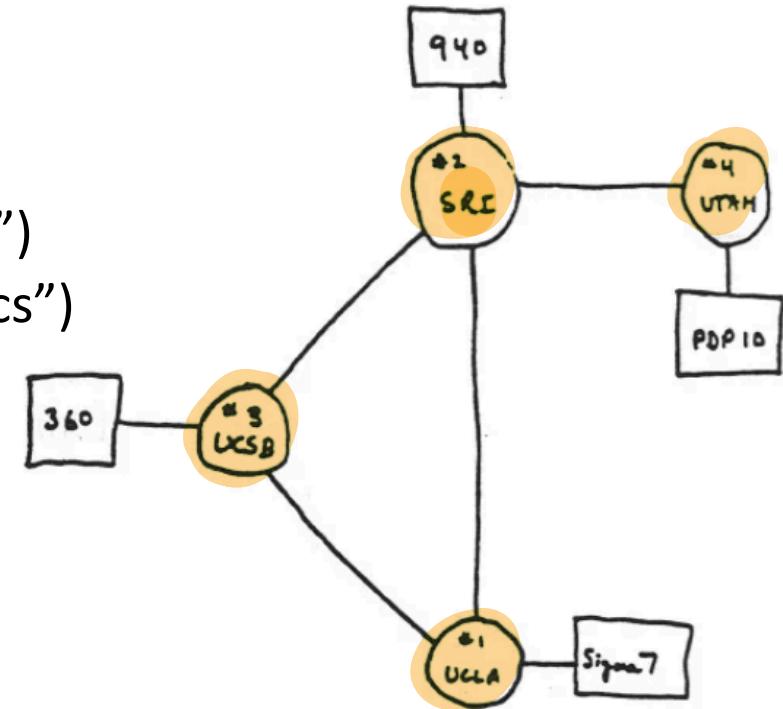
# Graphs: terminology

A collection of elements (“nodes” or “vertices”)

A set of connections (“edges” or “links” or “arcs”) between pairs of nodes.

Edges may be directed or undirected

Edges may have weight associated with them



THE ARPA NETWORK

DEC 1969

4 NODES

# Representing graphs

	0	1	2	3
0		1	1	
1	1		1	1
2	1	1		
3		1		

Adjacency Matrix

need to index into the vector to get the node's neighbors

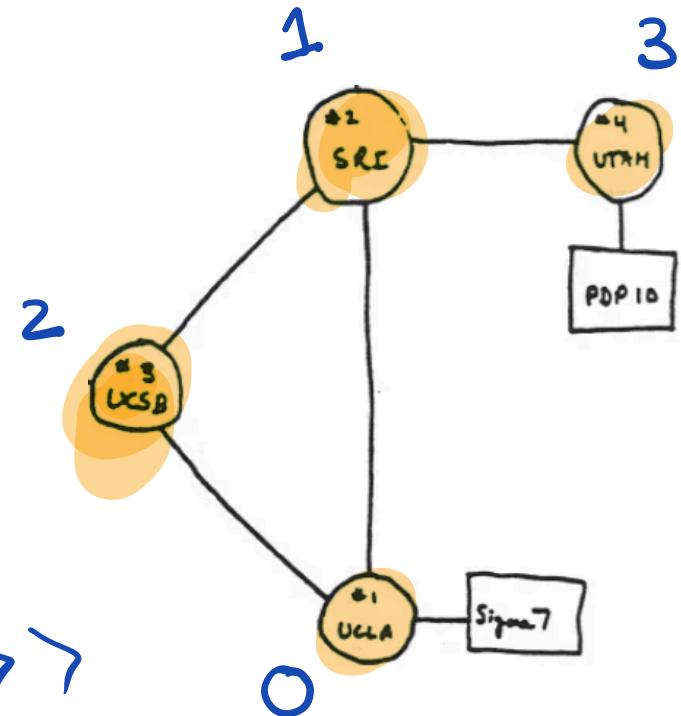
vector of list

0	: 1 → 2
1	: 0 → 2 → 3
2	: 0 → 2 → 1
3	: 1

Vector < list < int >>

Each node is identified by its index (0-3)

Adjacency List



THE ARPA NETWORK

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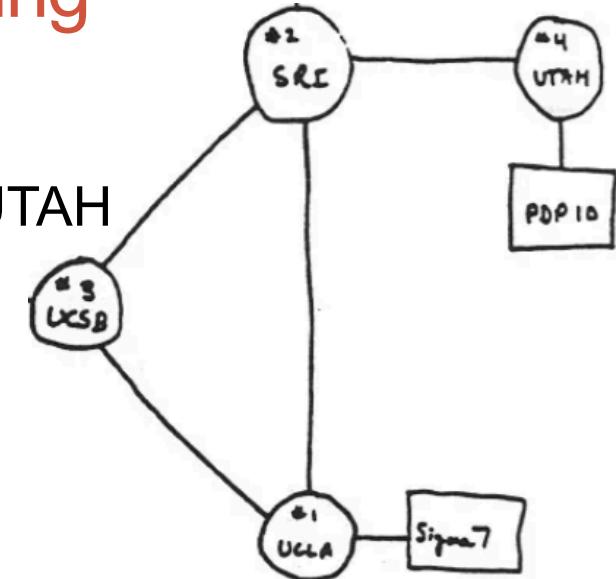
4 NODES

# Assume each node is identified by a string

```
class graph{
    private:
        _____ adjlist;
};
```

UCLA : SRI, UCSB  
 SRI : UCLA, UCSB, UTAH  
 UCSB : UCLA, SRI  
 UTAH : SRI

Adjacency List: adjlist



Choose the type for adjlist

- A. vector<string> X
- B. vector<list<string>> X
- C. set<pair<string, list<string>> ✓
- D. map<string, list<string>>
- E. priority\_queue<string>

THE ARPA NETWORK

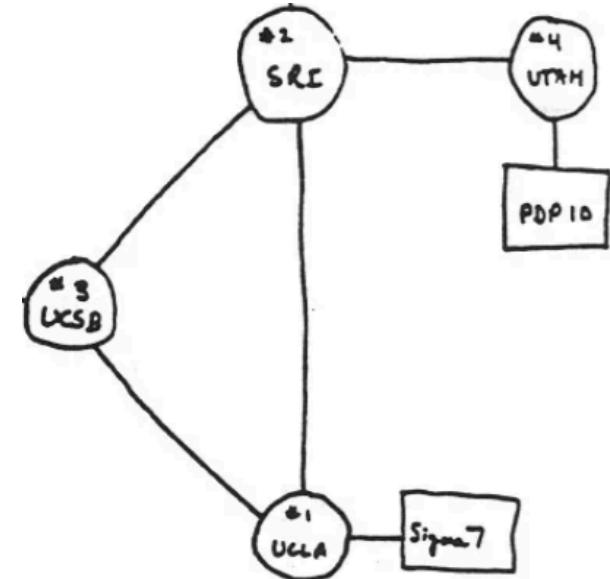
DEC 1969

4 NODES

# Graph search: general approach

Starting with a source node

- find everything that can be explored
- don't explore anything twice



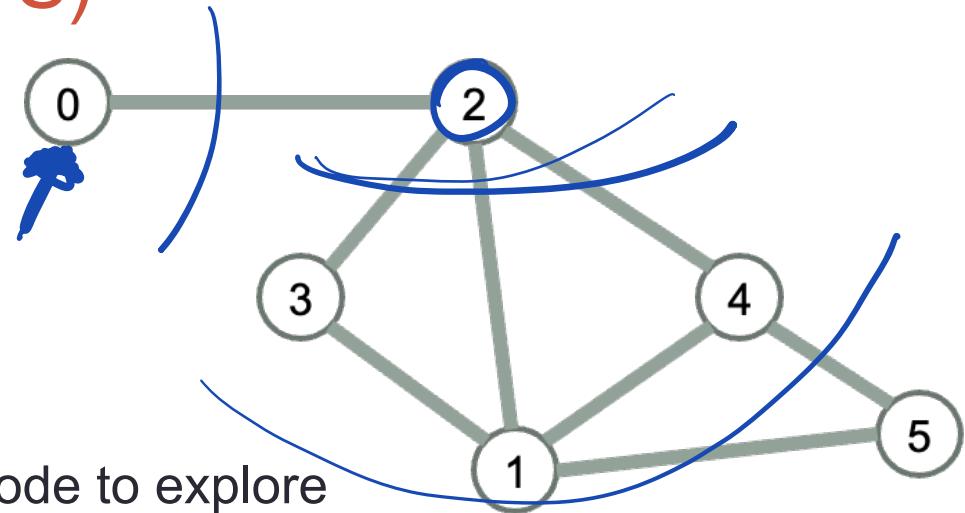
THE ARPA NETWORK

DEC 1969

4 NODES

## Graph search: breadth first (BFS)

Explore all the nodes reachable from a given node before moving on to the next node to explore



Assume BFS chooses the lower number node to explore first, in what order does BFS visit the nodes in this graph

- A. 0, 1, 2, 3, 4, 5
- B. 0, 1, 3, 2, 4, 5
- C. 0, 2, 3, 1, 4, 5
- D. 0, 2, 1, 3, 4, 5
- E. Something else

## BFS Traverse: Sketch of Algorithm

Start at source  $s$ ;

$s$  is visited,

empty queue  
others are not

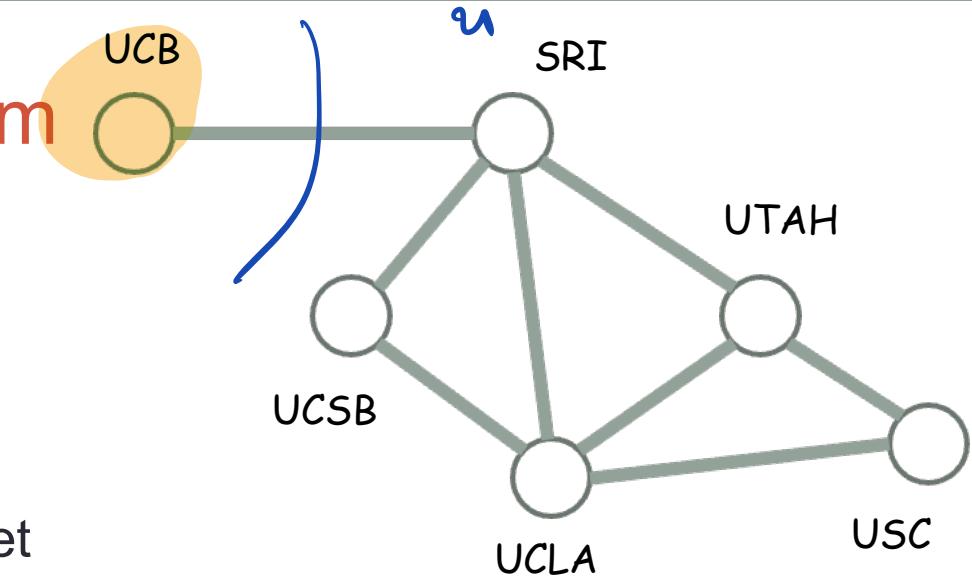
push  $s$  into a queue

while the queue is not empty:

pop the vertex  $u$  from the front of the queue

for each of  $u$ 's adjacent nodes that has not yet  
been visited ( $v$ ):

- Push  $v$  in the queue



### Questions:

-How can you tell if a node has been visited yet?

-What data do you need to keep track of for each node?

## BFS Traverse: Sketch of Algorithm

Start at source  $s$ ; give  $s$  distance = 0

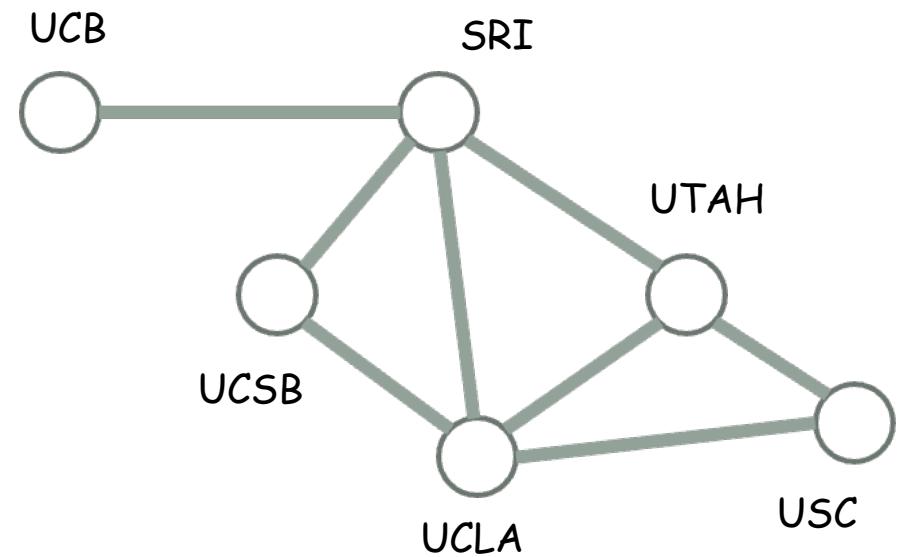
Mark  $s$  as visited

push  $s$  into a queue

while the queue is not empty:

pop the vertex  $u$  from the front of the queue  
for each of  $u$ 's adjacent nodes that has not yet  
been visited ( $v$ ):

- Mark  $v$  as visited
- Mark its distance as  $1 +$  the distance to  $u$
- Push  $v$  in the queue



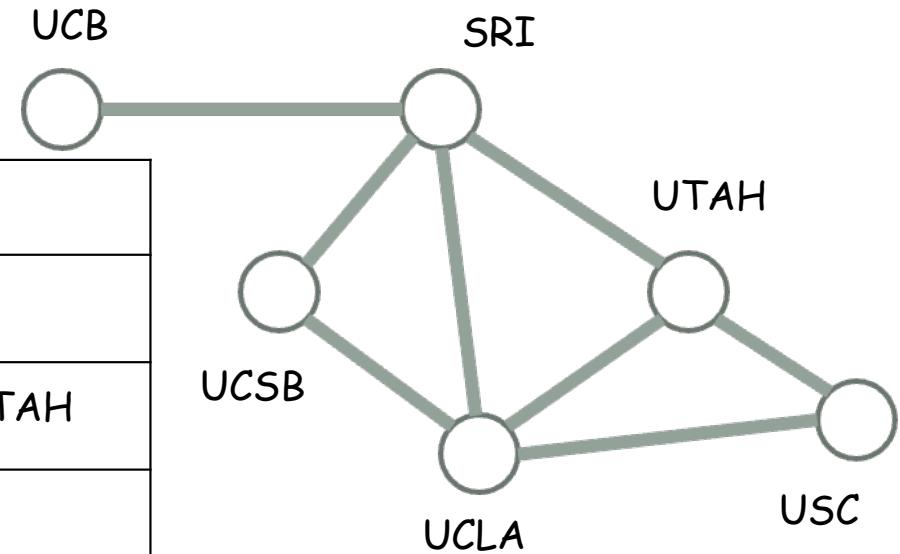
Question (discuss 1 min):

This algorithm finds the length of the shortest path from a source node to all nodes.

How can you also find the path itself?

# BFS Traverse: Trace Algorithm

Node	dist	prev	adjlist
UCB			SRI
SRI			UCB, UCSB, UCLA, UTAH
UCSB			SRI, UCLA
UCLA			UCSB, SRI, UTAH, USC
UTAH			UCLA, SRI, USC
USC			UTAH, UCLA



# GRAPHS

To model a graph and implement BFS we used all the data structures we have learned so far with the exception of priority\_queue :)

