

Memory Drawings-to-Scenes Translation

By Ran Xu and Ella Dagan

Inspired by

Drawings of real-world scenes during free recall reveal detailed object and spatial information in memory

Wilma A. Bainbridge, Elizabeth H. Hall & Chris I. Baker

Dataset of 2682 Scene Drawings

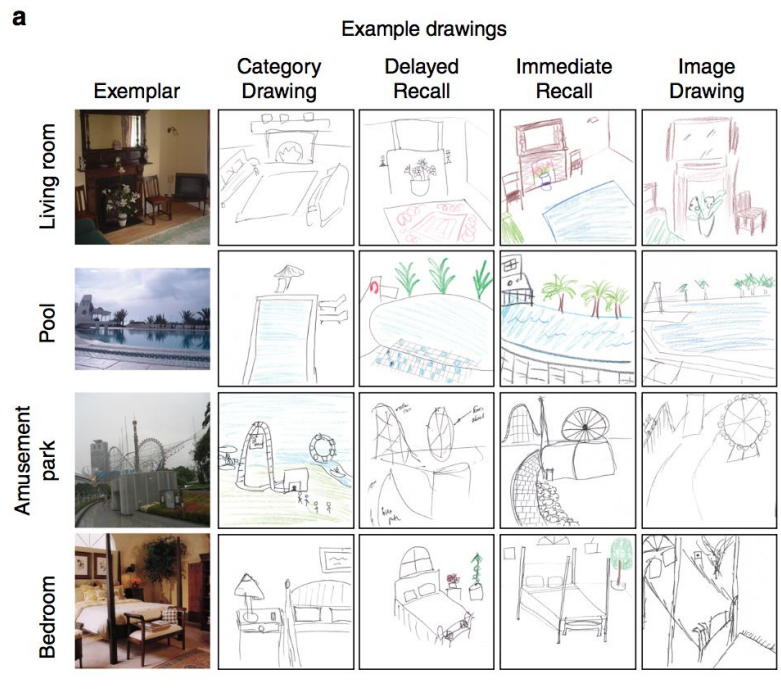


Image-to-Image Translation with Conditional Adversarial Networks

Phillip Isola, Jun-Yan Zhu, Tinghui Zhou, Alexei A. Efros

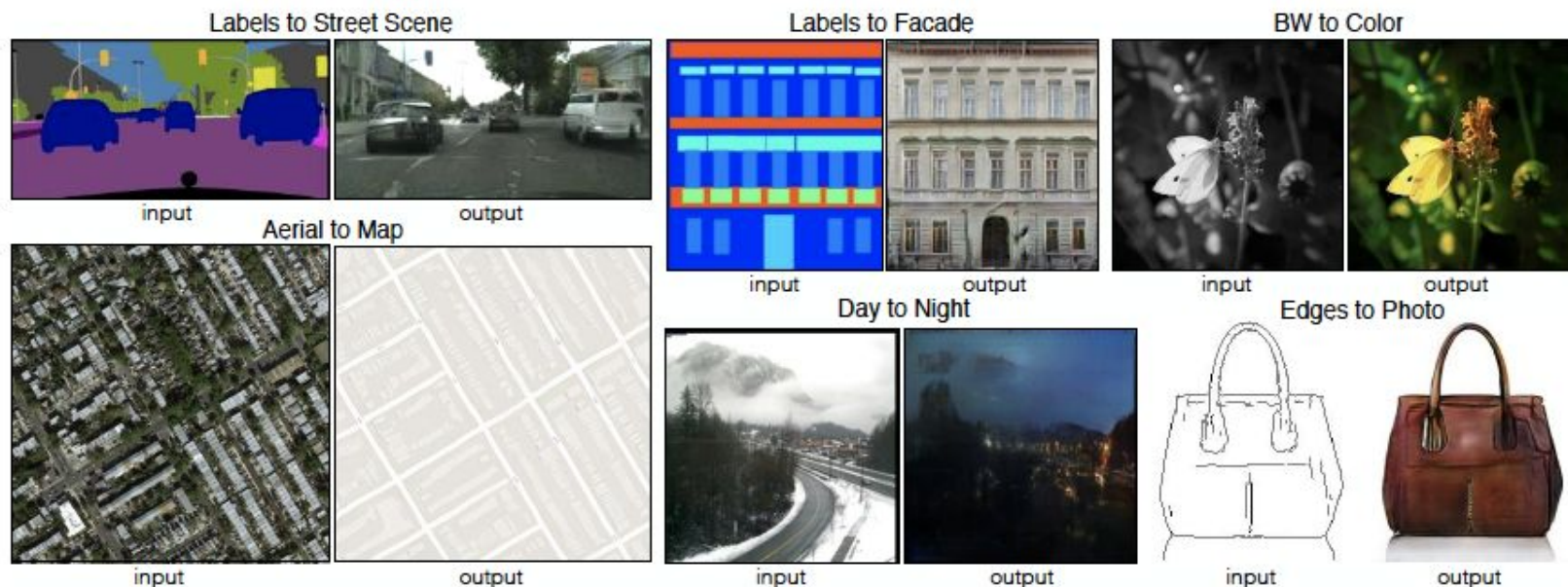
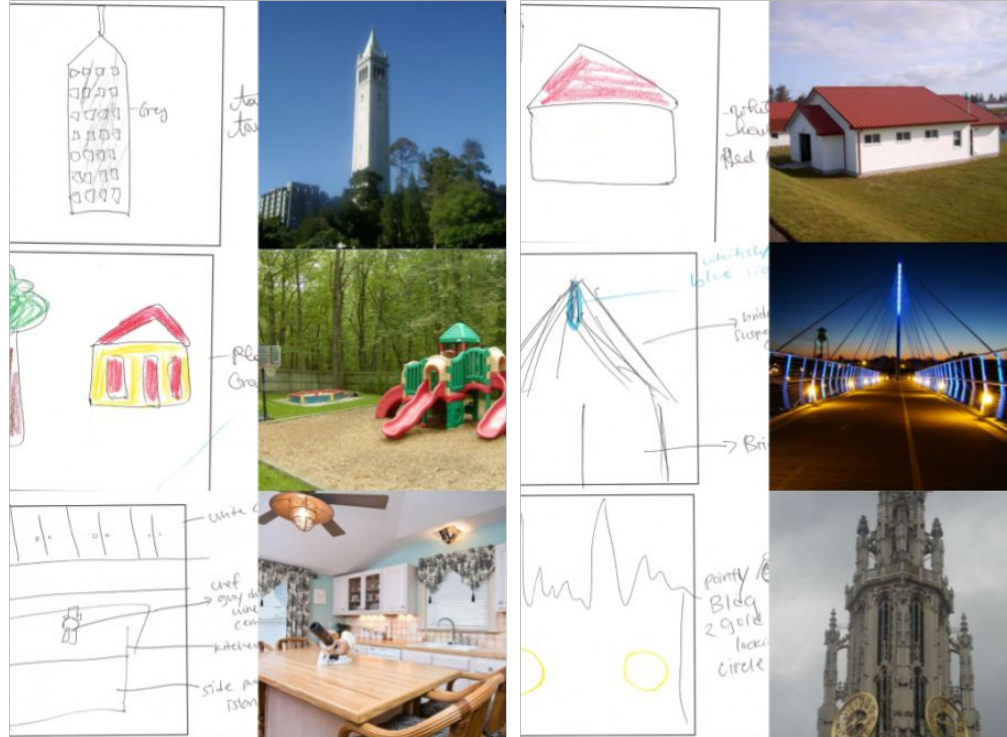
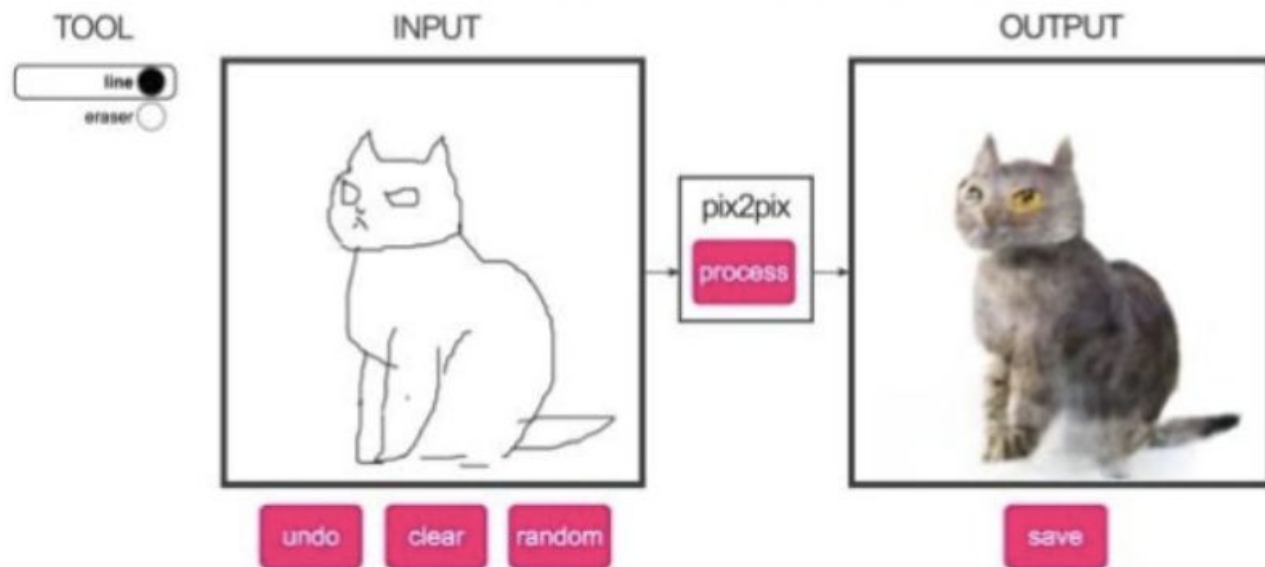


Figure 1: Many problems in image processing, graphics, and vision involve translating an input image into a corresponding output image. These problems are often treated with application-specific algorithms, even though the setting is always the same: map pixels to pixels. Conditional adversarial nets are a general-purpose solution that appears to work well on a wide variety of these problems. Here we show results of the method on several. In each case we use the same architecture and objective, and simply train on different data.

Prepared Dataset & Trained

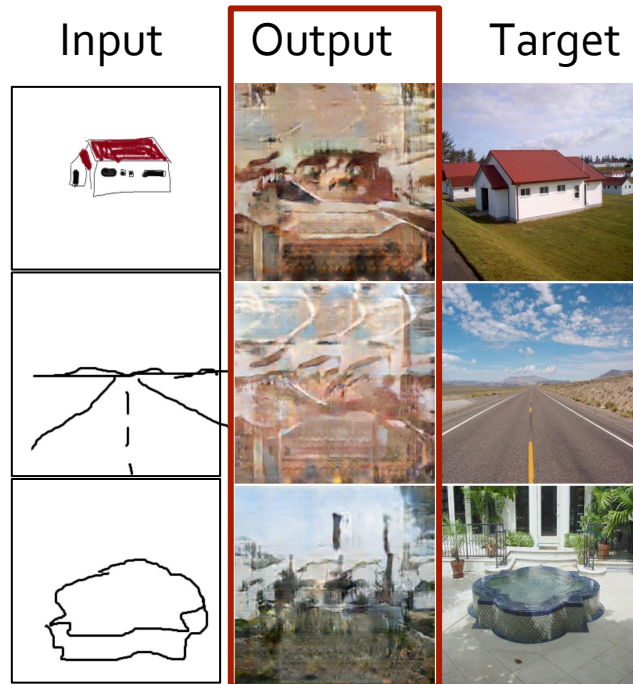
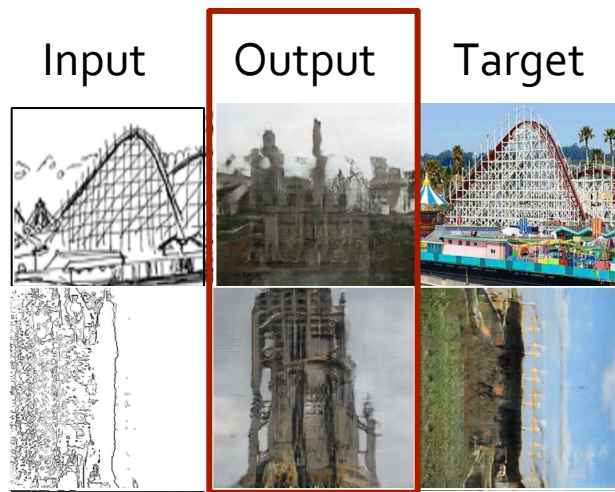


EdgesCats Demo | pix2pix-tensorflow | by Christopher Hesse

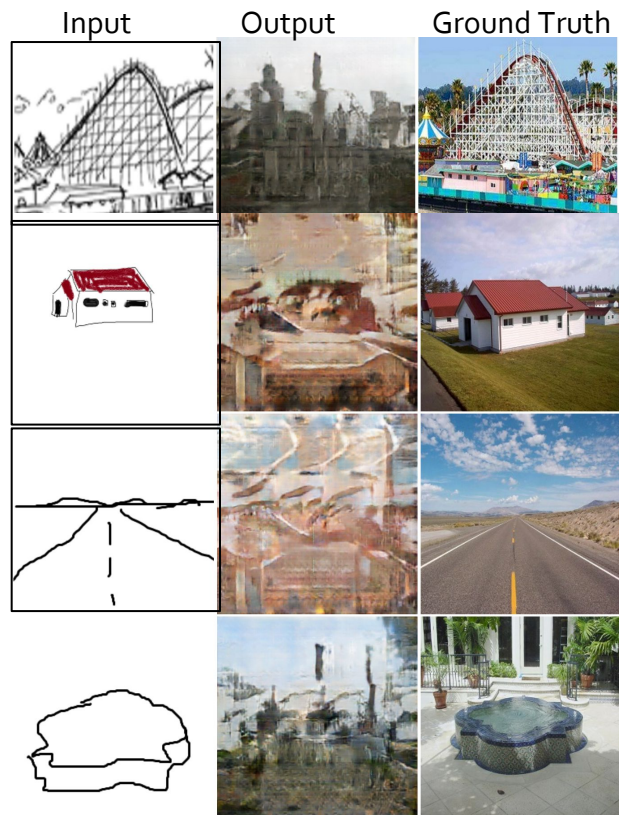


@gods_tail

Results (epoch 200)



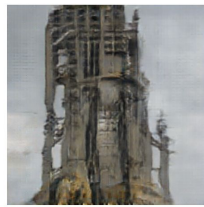
Results (epoch 200)



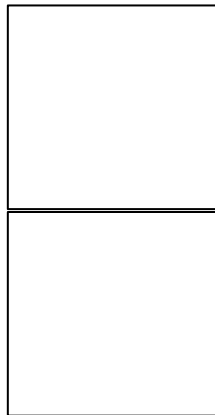
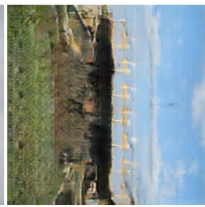
Input



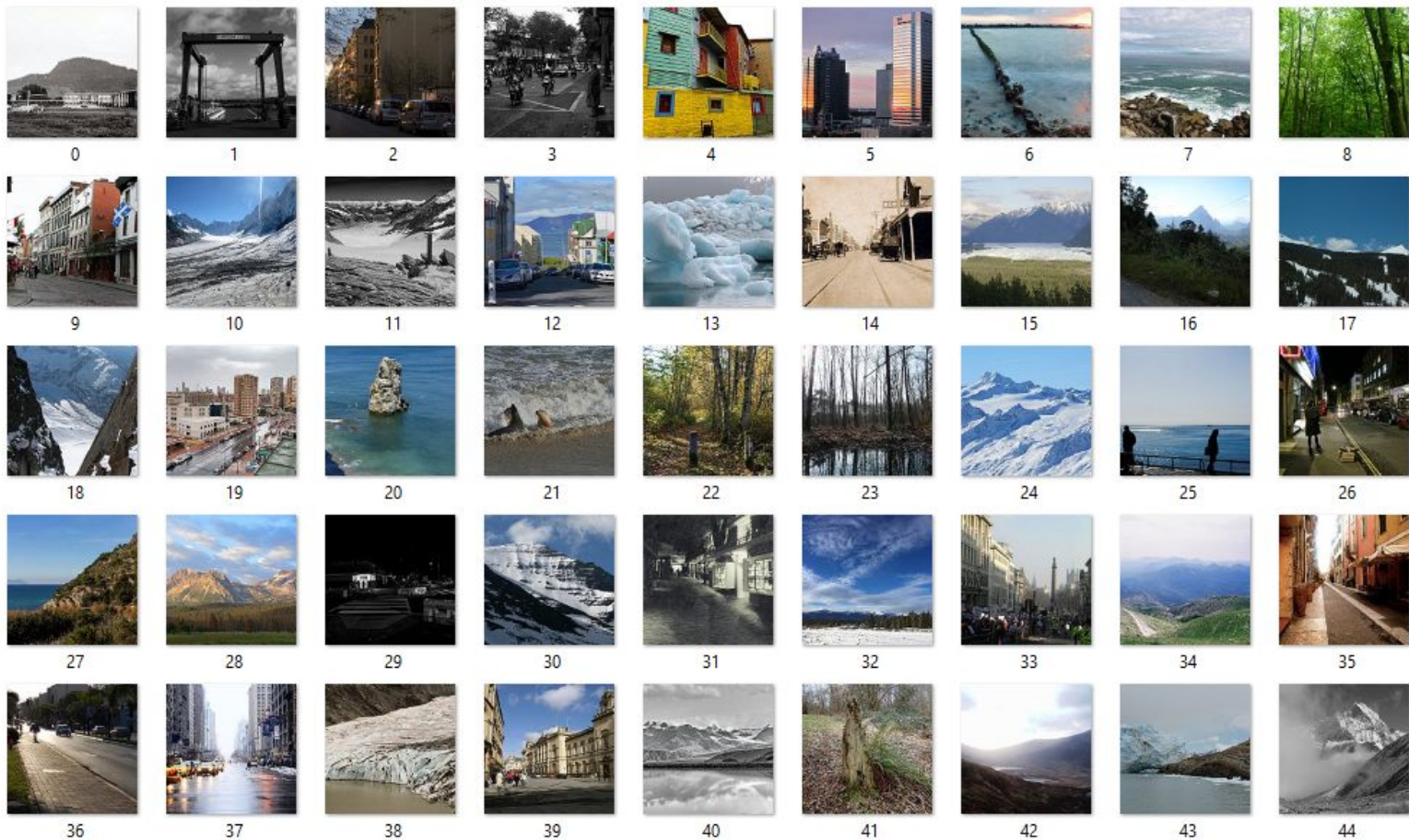
Output



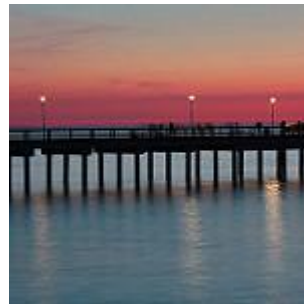
Ground Truth



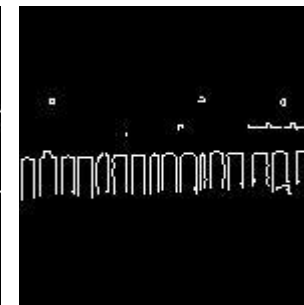
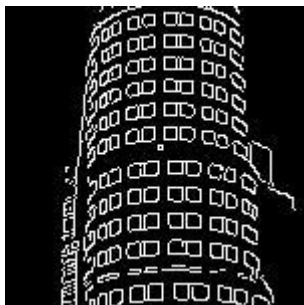
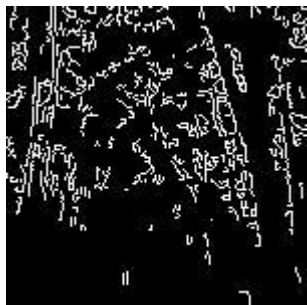
new dataset: 24,335 images of scenes



Getting Edges



↓ Canny Edge Detection



Training Output

Input

Output

Target



epoch 49

Input



what
have
Red ?

Output



Target

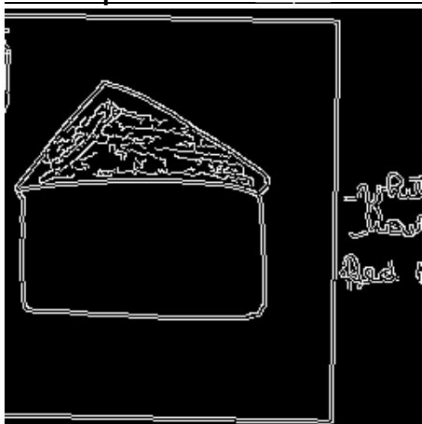


what
have
Red ?

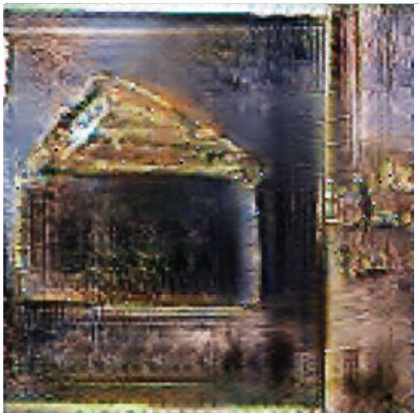
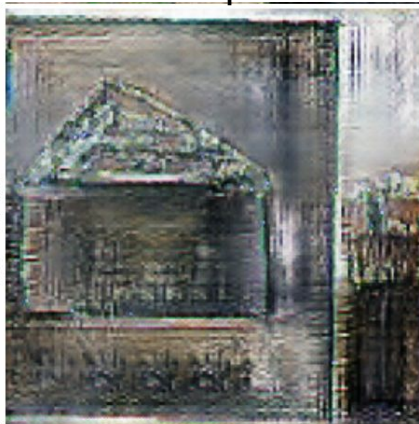


epoch 78 & epoch 112

Input



Output



Target



epoch 112

Input



Output

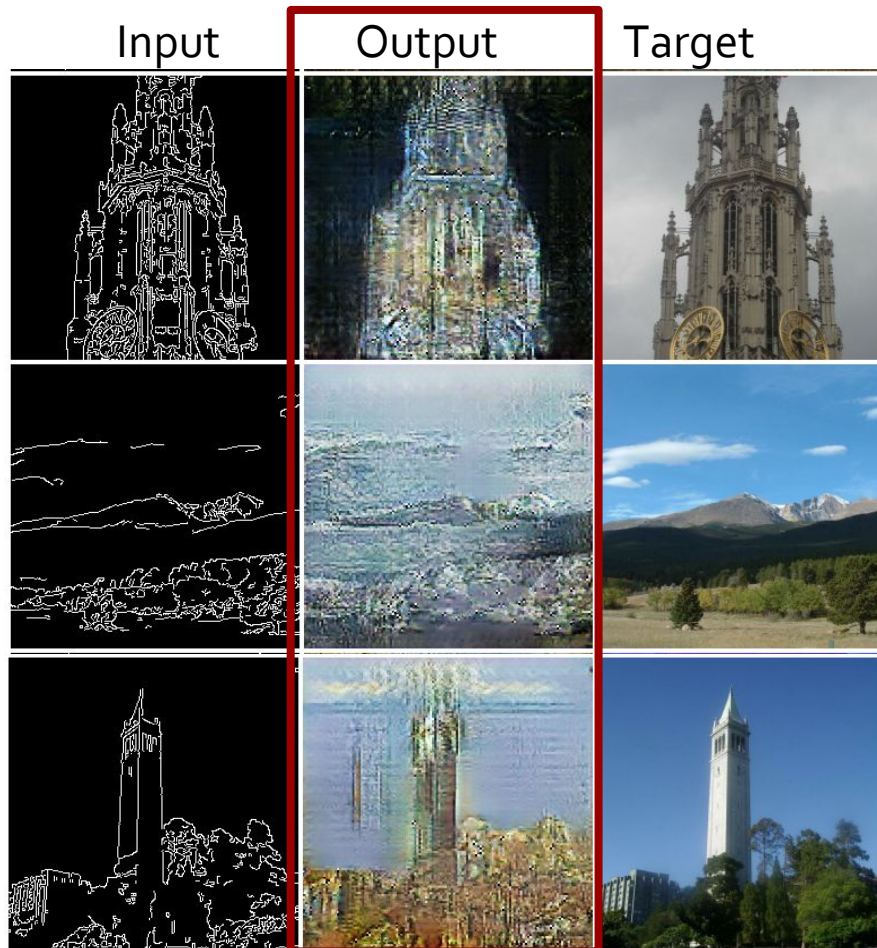


Target



What's next?

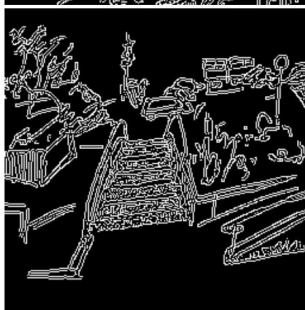
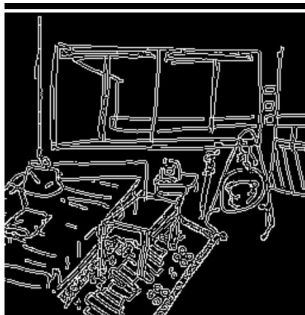
epoch 150



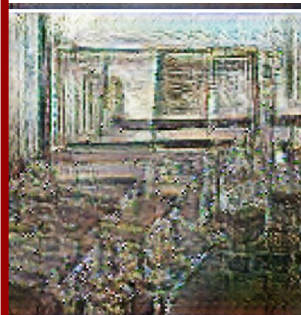
Drawing



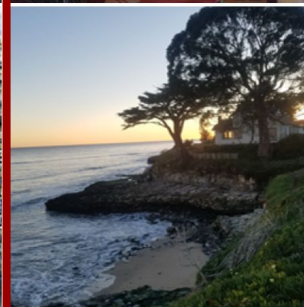
Input



Output



Target



Thank you!