

**UNIVERSITY COLLEGE TATI (UC TATI)****FINAL EXAMINATION QUESTION BOOKLET**

COURSE CODE	: BCE 3234
COURSE	: PROCESS CONTROL
SEMESTER/SESSION	: 2-2024/2025
DURATION	: 3 HOURS

Instructions:

1. This booklet contains 4 questions. Answer **ALL** questions.
2. All answers should be written in answer booklet.
3. Write legibly and draw sketches wherever required.
4. If in doubt, raise your hands and ask the invigilator.

**DO NOT OPEN THIS BOOKLET UNTIL YOU ARE TOLD TO DO SO
YOU ARE ALLOWED TO BRING TWO (2) A4 PAPER**

THIS BOOKLET CONTAINS 7 PRINTED PAGES INCLUDING COVER PAGE

QUESTION 1

a)

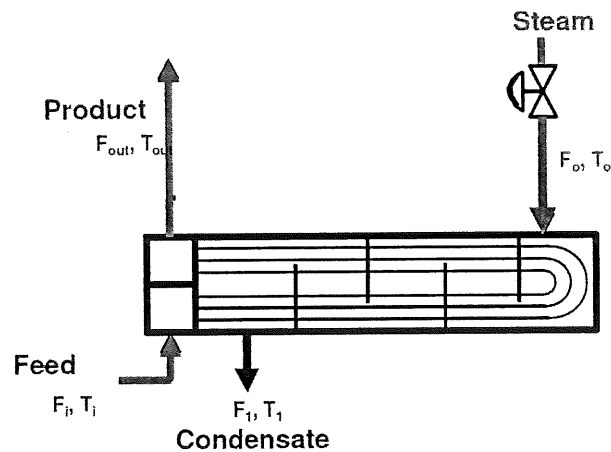


Figure 1

Figure 1 shows the heat exchanger system. This system require control system to maintain the temperature.

- i) Illustrate how the feedback control system is operated in Figure 1. Re-draw Figure 1. (4 marks)
- ii) Analyse: (5 marks)
 - a) Controlled variable
 - b) Measuring instrument
 - c) Manipulated variable
 - d) Final control element
 - e) Disturbance
- iii) Illustrate the feedback control loop for this process. (6 marks)

b) To bake cookies, an electric oven needs to be preheated to 180°C . After setting this desired temperature, a sensor measures the current temperature inside the oven. If the oven's temperature is below the set point, a signal is sent to the heater to turn on until the oven reaches the target temperature.

- i) In this scenario, diagnose:
- Control objective
 - Control variable
 - How the error of this system is calculated
- ii) Illustrate the classical control loop for this system.

(10 marks)

QUESTION 2

a)

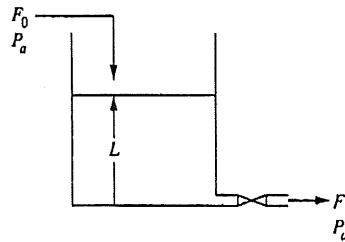


Figure 2

In Figure 2, the flow out depends on the level in the tank through a nonlinear relationship, and after linearization, the level model is:

$$\tau \frac{dL'}{dt} + L' = K_p F_0'$$

Given:

Cross-section area $A = 7 \text{ m}^2$, initial flows in and out, $= 100 \text{ m}^3/\text{min}$, initial level (L_s) $= 7 \text{ m}$, $k_{F1} = 37.8 \text{ (m}^3/\text{h)/(m}^{-0.5}\text{)}$.

$$\tau = A / (0.5 k_{F1} L_s^{-0.5})$$

$$K_p = 1 / (0.5 k_{F1} L_s^{-0.5})$$

- Find the Laplace Transform for the above equation (3 marks)
- Calculate K_p and τ (4 marks)
- Determine the transfer function $G(s)$ for this system (3 marks)

- iv) If the flow inlet is changed to $110 \text{ m}^3/\text{min}$. Find the equation for dynamic response, $L(t)$. (4 marks)
- v) Determine the level achieve in 5 hours. (4 marks)

b) A stirred tank blending system initially is full of water and is being fed pure water at a constant flowrate, q . At a particular time, an operator shuts off the pure water flow and add caustic solution at the same volumetric flowrate, q but with concentration, c . Given $V = 2 \text{ m}^3$, $q = 0.4 \text{ m}^3/\text{min}$ and $c_i = 50 \text{ kg/min}$. If the liquid volume is constant, the dynamic model for this process is:

$$V \frac{dc}{dt} + qc = qc_i \quad \text{where} \quad c(0) = 0$$

Find the concentration response of the reactor effluent stream, $c(t)$.

(7 marks)

QUESTION 3

Figure 3 shows a series configuration of two noninteracting tanks where any changes in the liquid level of Tank 1 will take 3 minutes to impact the liquid level in Tank 2. Disregard valves R_1 and R_2 .

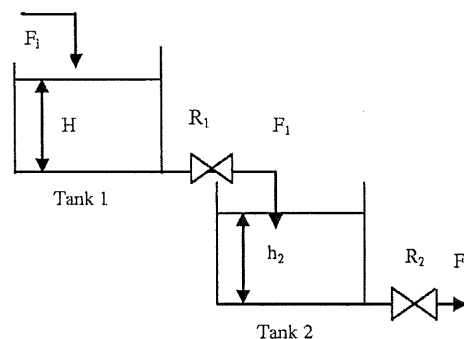


Figure 3

Given: $k_{p1} = 3 \text{ min/m}^2$, $k_{p2} = 1.5 \text{ min/m}^2$, $\tau_{p1} = 10 \text{ min}$, $\tau_{p2} = 20 \text{ min}$, $F_1 = 50 \text{ m}^3/\text{min}$

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$$\frac{h_1(s)}{F_1(s)} = \frac{k_{p1}}{\tau_{p1}s + 1}$$

$$\frac{h_2(s)}{h_1(s)} = \frac{k_{p2}e^{-tds}}{\tau_{p2}s + 1}$$

- a) Solve the transfer function for $\frac{h_2(s)}{F_1(s)}$
- b) If the operator suddenly increases the inlet flowrate, F_1 to $55 \text{ m}^3/\text{min}$, find the height response for Tank 2, $h_2(t)$.
- c) Determine the time for $h_2(t)$ to achieve in 10.5 m . Show all methods.

(25 marks)

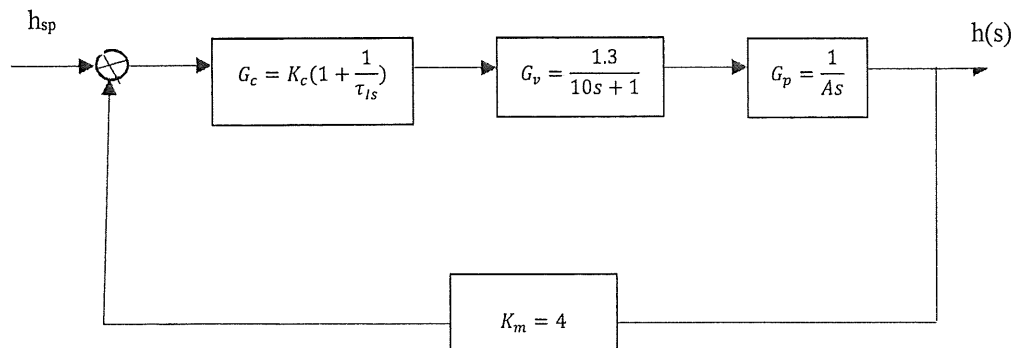
QUESTION 4

- a) Find the values of the controller gain, k_c that make the feedback control system stable using Routh-Hurwitz criterion. Given the characteristics equation:

$$10s^3 + 17s^2 + 8s + 1 + k_c = 0$$

(10 marks)

- b) Determine the range of K_c and τ_1 to form a stable system using RH method. Given $A = 3 \text{ ft}^2$



(15 marks)

-----End of question-----

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ATTACHMENTS

Table 1: Laplace transform for various time domain function

$f(t)$	$F(s)$
1. $\delta(t)$ (unit impulse)	1
2. $S(t)$ (unit step)	$\frac{1}{s}$
3. t (ramp)	$\frac{1}{s^2}$
4. t^{n-1}	$\frac{(n-1)!}{s^n}$
5. e^{-bt}	$\frac{1}{s+b}$
6. $\frac{1}{\tau} e^{-t/\tau}$	$\frac{1}{\tau s + 1}$
7. $\frac{t^{n-1} e^{-bt}}{(n-1)!} (n > 0)$	$\frac{1}{(s+b)^n}$
8. $\frac{1}{\tau^n (n-1)!} t^{n-1} e^{-t/\tau}$	$\frac{1}{(\tau s + 1)^n}$
9. $\frac{1}{b_1 - b_2} (e^{-b_2 t} - e^{-b_1 t})$	$\frac{1}{(s+b_1)(s+b_2)}$
10. $\frac{1}{\tau_1 - \tau_2} (e^{-t/\tau_1} - e^{-t/\tau_2})$	$\frac{1}{(\tau_1 s + 1)(\tau_2 s + 1)}$
11. $\frac{b_3 - b_1}{b_2 - b_1} e^{-b_1 t} + \frac{b_3 - b_2}{b_1 - b_2} e^{-b_2 t}$	$\frac{s + b_3}{(s+b_1)(s+b_2)}$
12. $\frac{1}{\tau_1} \frac{\tau_1 - \tau_3}{\tau_1 - \tau_2} e^{-t/\tau_1} + \frac{1}{\tau_2} \frac{\tau_2 - \tau_3}{\tau_2 - \tau_1} e^{-t/\tau_2}$	$\frac{\tau_3 s + 1}{(\tau_1 s + 1)(\tau_2 s + 1)}$
13. $1 - e^{-t/\tau}$	$\frac{1}{s(\tau s + 1)}$
14. $\sin \omega t$	$\frac{\omega}{s^2 + \omega^2}$

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15. $\cos \omega t$	$\frac{s}{s^2 + \omega^2}$
16. $\sin(\omega t + \phi)$	$\frac{\omega \cos \phi + s \sin \phi}{s^2 + \omega^2}$
17. $e^{-bt} \sin \omega t$	$\left. \begin{array}{l} \\ \\ \end{array} \right\} \quad b, \omega \text{ real}$
18. $e^{-bt} \cos \omega t$	
19. $\frac{1}{\tau \sqrt{1 - \zeta^2}} e^{-\zeta t / \tau} \sin(\sqrt{1 - \zeta^2} t / \tau)$ ($0 \leq \zeta < 1$)	$\frac{\omega}{(s + b)^2 + \omega^2}$
20. $1 + \frac{1}{\tau_2 - \tau_1} (\tau_1 e^{-t/\tau_1} - \tau_2 e^{-t/\tau_2})$ ($\tau_1 \neq \tau_2$)	$\frac{s + b}{(s + b)^2 + \omega^2}$
21. $1 - \frac{1}{\sqrt{1 - \zeta^2}} e^{-\zeta t / \tau} \sin[\sqrt{1 - \zeta^2} t / \tau + \psi]$ $\psi = \tan^{-1} \frac{\sqrt{1 - \zeta^2}}{\zeta}, (0 \leq \zeta < 1)$	$\frac{1}{\tau^2 s^2 + 2\zeta \tau s + 1}$
22. $1 - e^{-\zeta t / \tau} [\cos(\sqrt{1 - \zeta^2} t / \tau) + \frac{\zeta}{\sqrt{1 - \zeta^2}} \sin(\sqrt{1 - \zeta^2} t / \tau)]$ ($0 \leq \zeta < 1$)	$\frac{1}{s(\tau_1 s + 1)(\tau_2 s + 1)}$
23. $1 + \frac{\tau_3 - \tau_1}{\tau_1 - \tau_2} e^{-t/\tau_1} + \frac{\tau_3 - \tau_2}{\tau_2 - \tau_1} e^{-t/\tau_2}$ ($\tau_1 \neq \tau_2$)	$\frac{1}{s(\tau^2 s^2 + 2\zeta \tau s + 1)}$
24. $\frac{df}{dt}$	$\frac{\tau_3 s + 1}{s(\tau_1 s + 1)(\tau_2 s + 1)}$
25. $\frac{d^n f}{dt^n}$	$sF(s) - f(0)$
26. $f(t - t_0)S(t - t_0)$	$s^n F(s) - s^{n-1}f(0) - s^{n-2}f^{(1)}(0) - \dots - sf^{(n-2)}(0) - f^{(n-1)}(0)$
	$e^{-t_0 s} F(s)$

^aNote that $f(t)$ and $F(s)$ are defined for $t \geq 0$ only.

Characteristic equation:

$$1 + G_C G_V G_P G_M = 0$$

