



Sören Metje

GPU Computing with Python

Python Frameworks

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Motivation

Introduction

Why Python?

- High-level programming
- Compatible with many platforms and systems
- Many high quality frameworks and libraries
- Widely distributed in many different domains
- Big community



References

Introduction

Why GPU Computing?

- Reduce wall-clock time
- Achieve higher cost-efficiency

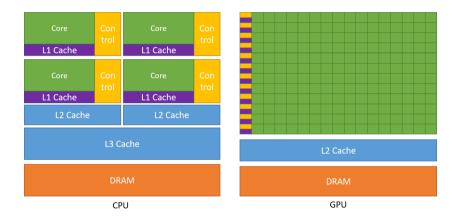


Source: NVIDIA - GPU-Accelerated Google Cloud [NVId]

Outline

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- 2 GPU Computing
- 3 Python Framework
- 4 Summary
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GPU Architecture



Source: CUDA Toolkit Documentation [NVIa]

Use Cases

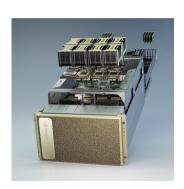
Introduction

When to use GPU Computing?

- Large data set available
- Parallel processing possible
- Use cases: Fluid dynamics, Image processing, Deep leaning, ...

When **not** to use GPU Computing?

- Data set is too small
- Data set is too big (exceeds GPU memory size)
- Large amount of small sequential operations



References

Source: NVIDIA - GPU-Accelerated Google Cloud [NVId]

CUDA

Introduction

Definition

NVIDIA CUDA (Compute Unified Device Architecture) is a **parallel computing platform** and programming model for general computing on **GPUs**.



- Initial release: June 23, 2007
- Gives access to the GPU's virtual instruction set
- Enables execution of compute kernels
- Accessible through frameworks, libraries, and compiler directives
- Closed source

CUDA Compute Kernel

Definition

Introduction

A compute kernel is a **function** compiled for accelerators (such as GPUs).

```
C++
  __qlobal__ void VecAdd(float* A, float* B, float* C) {
     int i = threadIdx.x:
     C[i] = A[i] + B[i];
 int main() {
     // ...
     VecAdd<<<1, N>>>(A, B, C); // blocks per grid, threads per block
```

Allowed operations: basic math operations, if / else, for / while loops

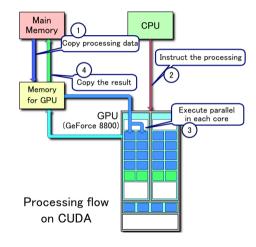
Python Frameworks

- Can not explicitly return a value
- Write results to passed array

```
C++

1   __global__ void VecAdd(float* A, float* B, float* C) {
2    int i = threadIdx.x;
3    C[i] = A[i] + B[i];
4  }
5  
6  int main() {
7    // ...
8    VecAdd<<<1, N>>>(A, B, C); // blocks per grid, threads per block
9 }
```

CUDA Processing Flow



Source: Wikipedia - CUDA [Wika]

AMD ROCm

Introduction

Definition

AMD ROCm (Radeon Open Compute) is a software stack for **GPU programming**.

- "NVIDIA CUDA for AMD GPUs"
- Initial release: November 14, 2016
- Available on GitHub (open-source)
- Supported by:
 - PyTorch
 - TensorFlow
 - CuPy
- Not as widely supported as NVIDIA CUDA
- Gaining traction in the TOP500



References

TOP 500 List

Introduction

Rank	System	Cores	Rmax (PFlop/s)	Rpeak (PFlop/s)	Power (kW)
1	Frontier - HPE Cray EX235a, AMD Optimized 3rd Generation EPYC 64C 2GHz, AMD Instinct MI250X, Stingshot-11, HPE D0E/SC/Oak Ridge National Laboratory United States	8,730,112	1,102.00	1,685.65	21,100
2	Supercomputer Fugaku - Supercomputer Fugaku, A64FX 48C 2.26Hz, Tofu interconnect D, Fujitsu RIKEN Center for Computational Science Japan	7,630,848	442.01	537.21	29,899
3	LUMI - HPE Cray EX235a, AMD Optimized 3rd Generation EPYC 64C 26Hz, AMD Instinct MI250X, Slingshot-11, HPE EuroHPC/CSC Finland	1,110,144	151.90	214.35	2,942
4	Summit - IBM Power System AC922, IBM POWER9 22C 3.076Hz, NVIDIA Volta GV100, Dual-rail Mellanox EDR Infiniband, IBM DOE/SC/Oak Ridge National Laboratory United States	2,414,592	148.60	200.79	10,096

Source: TOP 500 List - June 2022 [TOP]

Outline

- 2 GPU Computing
- 3 Python Frameworks

Python Frameworks for GPU Computing

Computing Frameworks

- Numba
- CuPy
- Scikit-cuda
- RAPIDS
- Triton (presented by Dimitris Oikonomou on 2022-05-19)
- ..

Deep Learning Frameworks

- PyTorch
- TensorFlow
- Keras
- .

Python Frameworks for GPU Computing

Computing Frameworks

Numba

Introduction

- CuPy
- Scikit-cuda
- RAPIDS
- Triton (presented by Dimitris Oikonomou on 2022-05-19)
- **.**.

Deep Learning Frameworks

- PyTorch
- TensorFlow
- Keras
- .

Numba

Introduction

Definition

Numba is a **just-in-time compiler** for numerical functions in Python.

- Translates Python functions to optimized machine code at runtime
- Compiles code for CPU and GPU
- Supports
 - NVIDIA GPUs: CUDA
 - AMD GPUs: ROCm (deprecated)
- Available on GitHub (open-source)



References

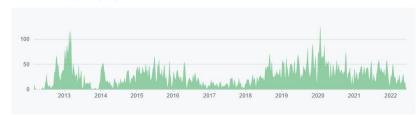
Numba - Development



Mar 4, 2012 – Jun 13, 2022

Contributions: Commits ▼

Contributions to main, excluding merge commits and bot accounts



Source: GitHub - Numba [Gita]

Numba - Programming Approaches

2 Approaches for GPU Programming

- Universal functions
- CUDA Kernels



Numba - Universal Functions

Definition

Introduction

A universal function (or ufunc for short) is a **function** that operates on arrays in an element-by-element fashion.

```
Python
 from numba import vectorize
 @vectorize(['float32(float32, float32)'])
 def add_ufunc(x, y):
     return x + v
 n = 100000
 a = np.arange(n).astvpe(np.float32)
 h = 2 * a
 out = add_ufunc(a, b)
```

Numba - Universal Functions on GPU

```
Python
 from numba import vectorize
 @vectorize(['float32(float32, float32)'], target='cuda')
 def add_ufunc(x, y):
     return x + y
```

- Compile CUDA kernel
- 2 Allocate GPU memory
- Copy data to the GPU
- Executed CUDA kernel
- 5 Copy result back to the CPU
- 6 Return the result

Numba - CUDA Kernels

```
Python
 from numba import cuda
 import numpy as np
 @cuda.jit
 def add_kernel(x, y, out):
     start, stride = cuda.grid(1), cuda.gridsize(1) # 1 = one dim. thread grid
     for i in range(start, x.shape[0], stride):
         out[i] = x[i] + y[i]
 x = np.arange(100000).astype(np.float32)
 v = np.arange(100000).astvpe(np.float32)
 out = np.emptv_like(x)
 add_kernel[30, 128](x, y, out) # blocks per grid, threads per block
 print(out) # [0.0 2.0 4.0 ... 1.99998e+05]
```

CuPy

Introduction

Definition

CuPy is a NumPy/SciPy-compatible array library for GPU-accelerated computing.

- "NumPy for GPU computing"
- Provides various math operations
- **Supports**
 - NVIDIA GPUS: CUDA
 - AMD GPUs: ROCm (experimental)
- Available on GitHub (open-source)



References

CuPy - Development



Apr 12, 2015 - Jun 13, 2022

Contributions: Commits ▼

Contributions to master, excluding merge commits and bot accounts



Source: GitHub - CuPy [Gitb]

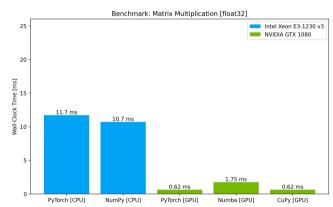
CuPy - Math Functions

```
Python
 import cupy as cp
 x = cp.arange(100000)
 y = x * 2
 out1 = cp.add(x, y) # array([ 0, 3, 6, ..., 299997])
 out2 = cp.sum(x) # array(704982704)
 out3 = cp.linalq.norm(x) # array(18257281.65280911)
 # ...
 # All common NumPy functions are supported by CuPu
```

CuPy - CUDA Kernels

```
Python
 import cupy as cp
 add = cp.RawKernel(r'''
 extern "C" __qlobal__ void add(const int* p, const int* q, int* z) {
     int tid = blockDim.x * blockIdx.x + threadIdx.x:
     z[tid] = p[tid] + q[tid];
 '''. 'add')
 x = cp.arange(100000, dtype=int)
 y = cp.arange(100000, dtype=int)
 out = cp.zeros(100000, dtype=int)
 add((250, 1), (1024, 1), (x, y, out)) # blocks per grid, threads per block
 print(out) # arrau([ 0
                                 2 4 ... 199994 199996 1999981)
```

Benchmark - Matrix Multiplication



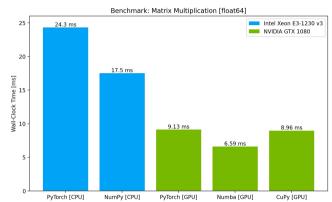
Wall-clock time in milliseconds for computing result of fast matrix multiplication. Mean of 100 loops and 4 runs.

Multiplied a 1024x2048 matrix and a 2048x512 matrix of float32.

Measured time does not count in time to copy matrices to GPU and result matrix back from GPU.

Code for benchmarking is available on GWDG GitLab

Benchmark - Matrix Multiplication Float64



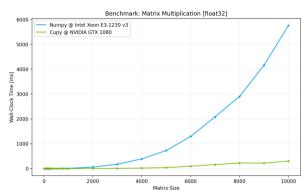
Wall-clock time in milliseconds for computing result of fast matrix multiplication. Mean of 100 loops and 4 runs.

Multiplied a 1024x2048 matrix and a 2048x512 matrix of float64.

Measured time does not count in time to copy matrices to GPU and result matrix back from GPU.

Code for benchmarking is available on GWDG GitLab

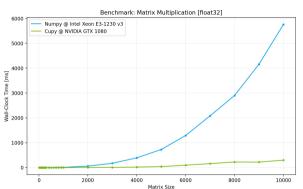
Benchmark - Matrix Multiplication



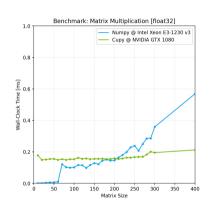
Wall-clock time in milliseconds for computing result of fast matrix multiplication. Mean of 10 loops and 3 runs. Multiplied 2 square matrices of float 32 with given size. Not measured time to copy matrices to and from GPU.

Code for benchmarking is available on GWDG GitLab

Benchmark - Matrix Multiplication



Wall-clock time in milliseconds for computing result of fast matrix multiplication. Mean of 10 loops and 3 runs. Multiplied 2 square matrices of float 32 with given size. Not measured time to copy matrices to and from GPU.



References

Code for benchmarking is available on GWDG GitLab

Outline

- 2 GPU Computing
- 4 Summary

New Trends

Introduction

What's new?

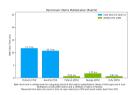
- GPUs get more powerful
- More complex models and computations
- New high-level Python frameworks provide features for various use cases
- ROCm (open-source) is gaining traction

Summary

Introduction

GPUs

- achieve massive data parallelism
- reduce wall-clock time
- ▶ increase cost efficiency

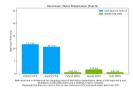


Summary

Introduction

GPUs

- achieve massive data parallelism
- reduce wall-clock time
- increase cost efficiency



■ **Numba** Advantages

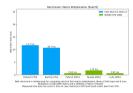
Enables implementing own universal functions & kernels in Python running on GPU

Summary

Introduction

GPUs

- achieve massive data parallelism
- reduce wall-clock time
- increase cost efficiency



References

Numba Advantages

- Enables implementing own universal functions & kernels in Python running on GPU
- CuPv Advantages
 - Easily move existing NumPy code towards GPU computing
 - Directly use NumPy-style array operations and execute them on GPU
 - Great starting-point to **learn** about GPU computing



Introduction

Avimanyu Bandyopadhyay, Hands-On GPU Computing with Python, Packt Publishing Ltd. 2019. ISBN: 9781789341072.



NVIDIA. Programming Guide:: CUDA Toolkit Documentation. URL: https://docs.nvidia.com/cuda/cuda-c-programming-guide/index.html.



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Amazon Web Services. Amazon EC2 P3 instances. URL: https://aws.amazon.com/ec2/instance-types/p3/?nc1=h_ls.

Python Frameworks



Google. Google Colab. URL: https://colab.research.google.com/.



Instance Size	GPUs - Tesla V100	GPU Peer to Peer	GPU Memory (GB)	vCPUs	Memory (GB)	Network Bandwidth	EBS Bandwidth	On-Demand Price/hr*	1-yr Reserved Instance Effective Hourly*	3-yr Reserved Instance Effective Hourly*
p3.2xlarge	1	N/A	16	8	61	Up to 10 Gbps	1.5 Gbps	\$3.06	\$1.99	\$1.05
p3.8xlarge	4	NVLink	64	32	244	10 Gbps	7 Gbps	\$12.24	\$7.96	\$4.19
p3.16xlarge	8	NVLink	128	64	488	25 Gbps	14 Gbps	\$24.48	\$15.91	\$8.39
p3dn.24xlarge	8	NVLink	256	96	768	100 Gbps	19 Gbps	\$31.218	\$18.30	\$9.64

Example Pricing: Amazon EC2 P3 instances. Source: AWS [Ama]

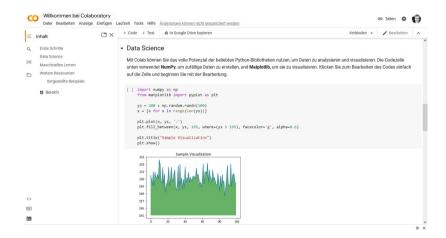
Advantages

- Scalable resources
- On-demand pricing

Disadvantages

- Expense for large periods of time
- Data confidentiality not guaranteed depending on vendor

GPU as a Service



Google Colab Jupyter Notebooks. Source: Google [Goo]

NVIDIA PTX

Introduction

Definition

NVIDIA PTX (Parallel Thread Execution) is a low-level parallel thread execution **virtual machine** and instruction set architecture (ISA)

Python Frameworks

- Exposes the GPU as a data-parallel computing device
- Interprets compiled code (analog to Java byte code interpreted by JVM)

Advantage

■ Achieves portability of source code among multiple NVIDIA GPUs