# CS 754: Advanced Image ProcessingAssignment 2

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February 11, 2017

## Q1

### A1.1

$$y = \Phi x, y \in \mathbb{R}^m$$

If m=1 then y is a single value. Assume  $x_i \neq 0$  for some  $i \in \{1, ..., n\}$  then  $y = \Phi_i x_i$ . Consider some other x' which has  $j^{\text{th}}$  element non-zero,  $j \neq i$ . If  $\Phi_j x'_j = \Phi_i x_i$ , then  $y = \Phi x'$  is also satisfied. We can find such a x' for all  $j \neq i$  where  $x'_j = \Phi_i/\Phi_j x_i$ . Hence there is no unique solution for this equation, and we cannot uniquely determine x from y.

For the case where we know the index of the non-zero element in x, we have been given i, and no other  $j \neq i$  will satisfy the equation, leaving behind only one solution for x. Hence now we can uniquely determine x from y.

#### A1.2

If m=2, then y is a 2D vector. Assuming i is the index of non-zero element in x

$$y = \left[ \begin{array}{c} \Phi_{1i} x_i \\ \Phi_{2i} x_i \end{array} \right]$$

We can say that y is the 2D column vector  $\Phi_i$  scaled by  $x_i$ . Assume no two columns of  $\Phi$  are parallel to each other in 2D space. Then we can say that we will find only one unique i for which the equation holds. This is because if  $y\|\Phi_i$  and  $y\|\Phi_j$ ,  $i \neq j$  then  $\Phi_i\|\Phi_j$ , which is contrary to our assumption.

If the assumption holds for some  $\Phi$ , we can obtain i by calculating normalised dot product of y with every column  $\Phi_i$ , and whichever i gives  $\frac{y\cdot\Phi_i}{|y||\Phi_i|}=1$ , we can then use it to calculate  $x_i$  by

$$x_i = |y|/|\Phi_i|$$

If there are two or more such i, we can say that our assumption doesn't hold on  $\Phi$  and no unique solution can be found.

### A1.3

For m = 3, y is a 3D vector which can be represented as the linear combination of two columns of  $\Phi$ . Take i and j to be the two indices of x which are non-zero.

$$y = \Phi_i x_i + \Phi_j x_j$$

We can see that y in 3D space will lie in the 2D plane defined by  $\Phi_i$  and  $\Phi_j$ . So to find x given y, we need to find two columns of  $\Phi$  which form  $\{\Phi_i, \Phi_j, y\}$  as a set of coplanar 3D vectors. Thus we need to find i, j s.t.

$$\frac{y \times \Phi_i}{|y||\Phi_i|} = \frac{y \times \Phi_j}{|y||\Phi_i|}$$

We will be able to find a unique pair of i, j iff no three columns of  $\Phi$  are coplanar in 3D.

Algorithm:

1. Create a binary search tree to add normalised cross products

2. Loop through the columns of  $\Phi$  and for every  $\Phi_i$ 

(a) Calculate normalised cross product  $\hat{n_i} = \frac{y \times \Phi_i}{|y| |\Phi_i|}$ 

(b) Search for  $\hat{n}_i$  in the tree and return both indices, current index and matched index if found. Break the loop.

(c) If not found, add  $\hat{n_i}$  to the tree.

3. Using the two indices we need to solve for  $x_i$  and  $x_j$  using

$$y = (\Phi_i \Phi_j) \left( \begin{array}{c} x_i \\ x_j \end{array} \right)$$

This is an over-determined system (three equations two variables) and we can use inverse to find a solution (by discarding one equation).

 $\mathbf{Q2}$ 

A2.3

We have the relation:

$$E_u = \sum_{t=1}^{T} C_t \cdot F_t$$

Consider

$$E_1 = C_1 \cdot F_1$$

and suppose that we want to construct it as a matrix product, then we can write it as

$$E_1 = \phi_1 f_1$$

where  $\phi_1 = diag(C_1)$  and  $f_1 = vec(F_1)$  Hence

$$E_u = [\phi_1 | \phi_2 | \dots | \phi_T] \begin{bmatrix} f_1 \\ f_2 \\ \dots \\ f_T \end{bmatrix}$$

Therefore

$$x = \begin{bmatrix} f_1 \\ f_2 \\ \dots \\ f_T \end{bmatrix}$$
$$y = vec(Eu)$$
$$A = [\phi_1 | \phi_2 | \dots | \phi_T]$$

 $\mathbf{Q3}$ 

**A3** 

Coherence is defined as:

$$\mu(\phi, \psi) = \sqrt{(n)} * \max_{i,j \in [0,1,\dots,n-1]} |\phi^{i^t} \psi_j|$$

- (a) Upper Bound: Consider a row of  $\phi$  matrix to be exactly same as one of the columns of  $\psi$  the inner product would be 1, because both matrices are unit normalized, and result in  $\mu_{max}(\phi,\psi) = \sqrt(n)$ .
- (b) Lower Bound: Let g be a row of the  $\phi$  matrix, which is unit normalized. g can be written with basis vectors as columns of  $\psi$ . That is

$$g = \sum_{k=1}^{n} \alpha_k \psi_k$$

Also since g is unit norm,

$$\sum_{k=1}^{n} \alpha_k^2 = 1$$

When we take the inner product of g with  $\psi_k$ , only one  $\alpha$  will remain. Now consider the coherence of g and  $\psi$ . Clearly

$$\mu(g,\psi) = \sqrt{n} * max(\alpha_j)_{j=1}^n$$

where  $\alpha_j$  is corresponds to the jth coefficient. Now we also know that

$$max(\alpha_j)_{j=1}^n \ge avg(\alpha_j)_{j=1}^n$$

and equality occurs when all  $\alpha_j$  are equal. Hence to get the minimum coherence we need all  $\alpha_j$  to be equal and using the previous constraint on unit norm we get

$$\alpha_j = \frac{1}{\sqrt{n}}$$

. This gives

$$\mu_{min}(g,\psi) = 1$$

This is the bound for all rows, and hence we have obtained

$$\mu_{min}(\phi, \psi) = 1$$

 $\mathbf{Q4}$ 

 $\mathbf{A4}$