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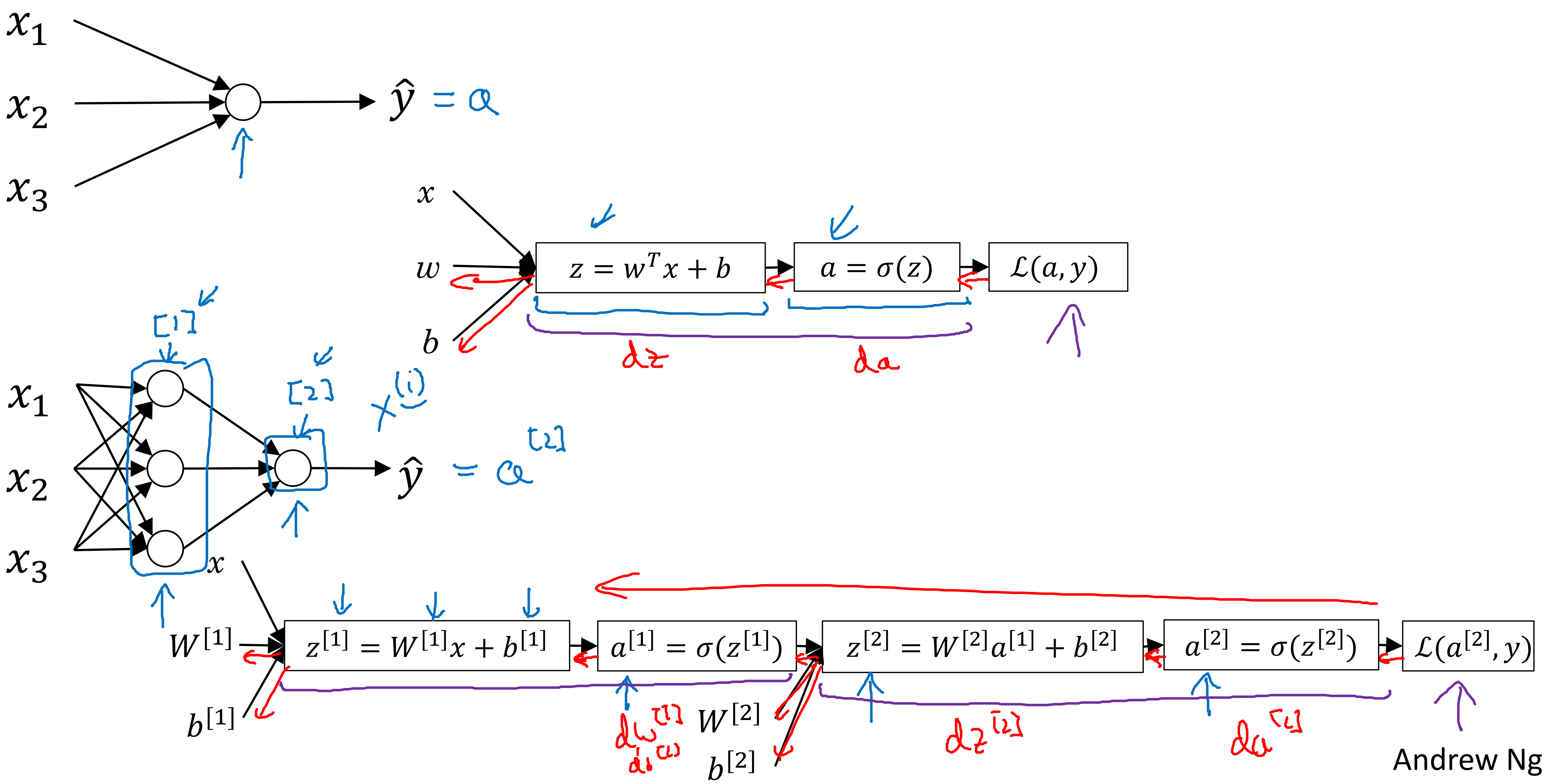
One hidden layer Neural Network

Neural Networks Overview

What is a Neural Network?



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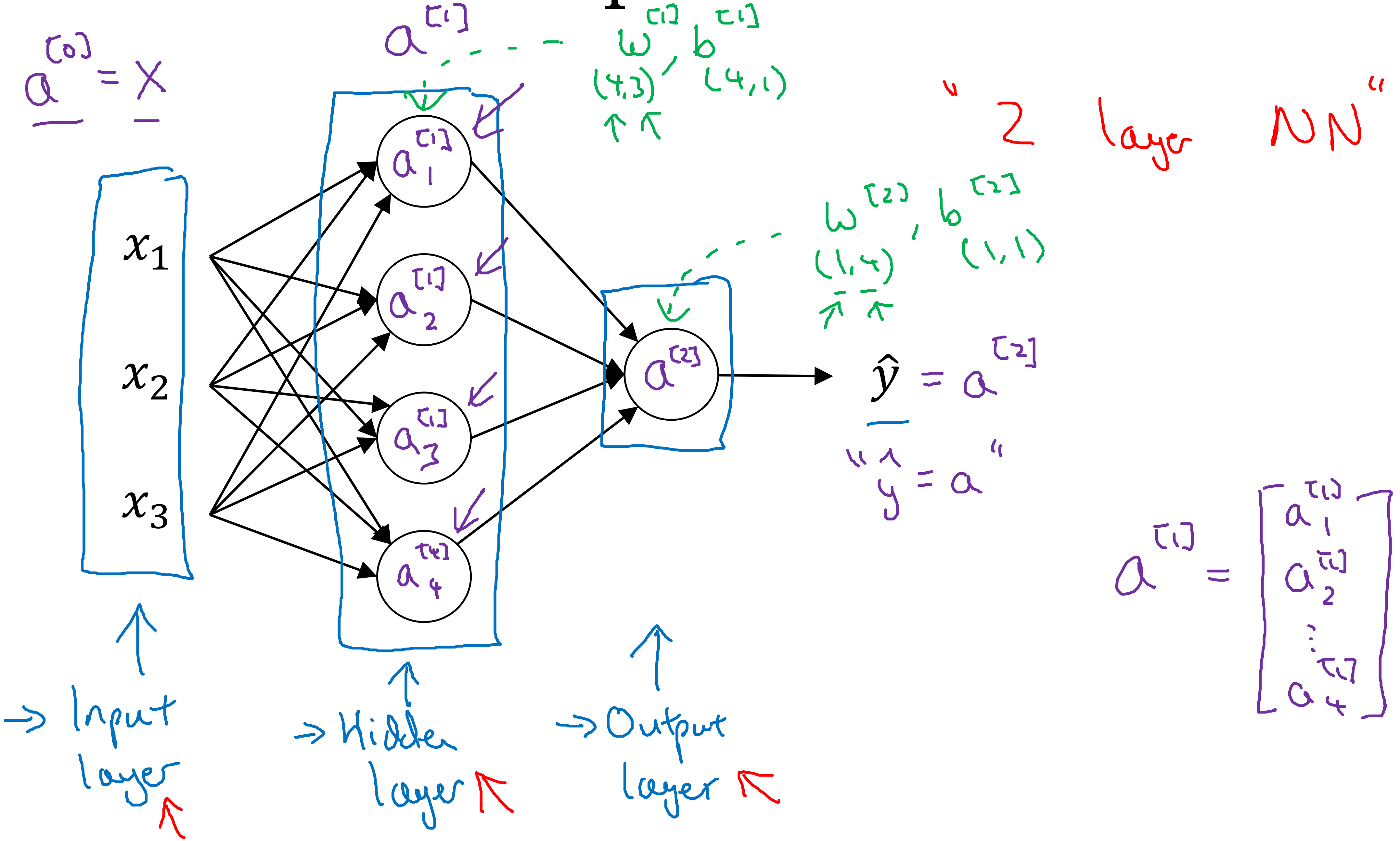
Neural Network Representation

Neural Network Representation



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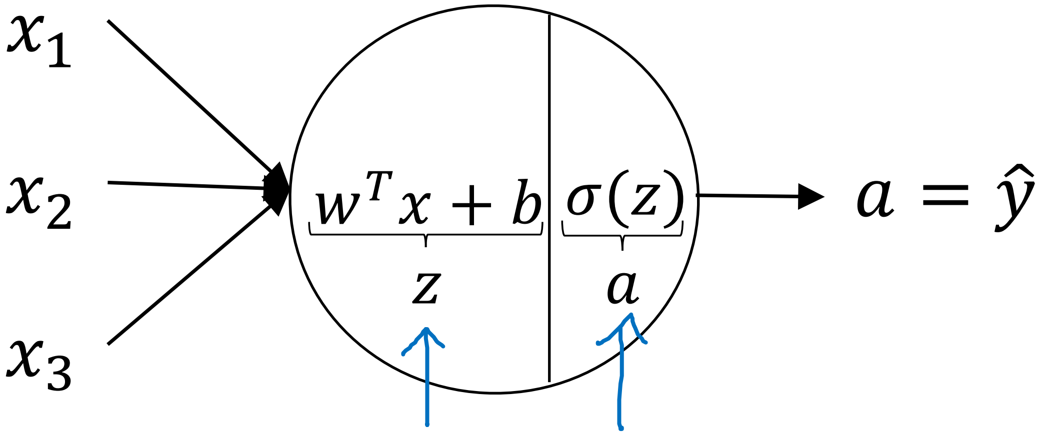
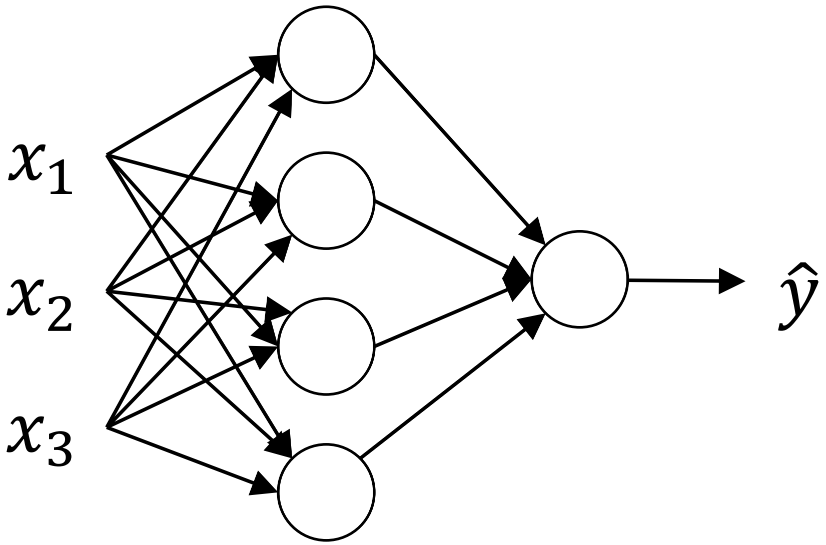
Computing a Neural Network's Output

Neural Network Representation

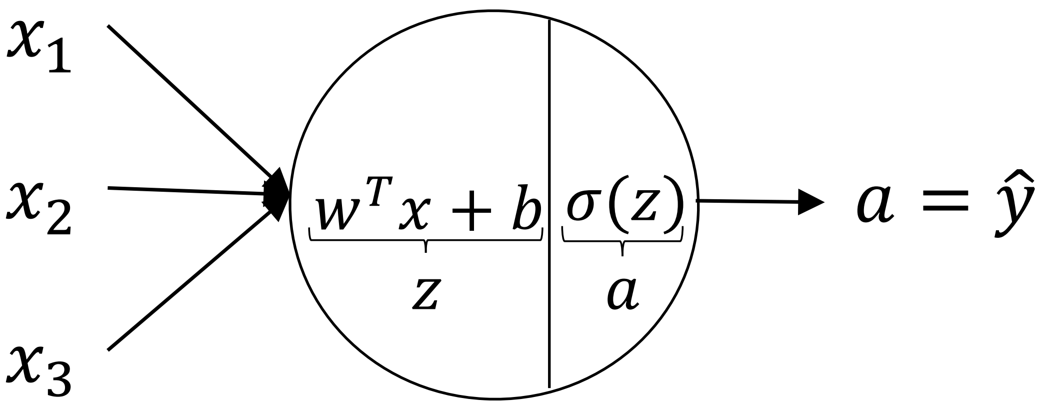




$$z = w^T x + b$$

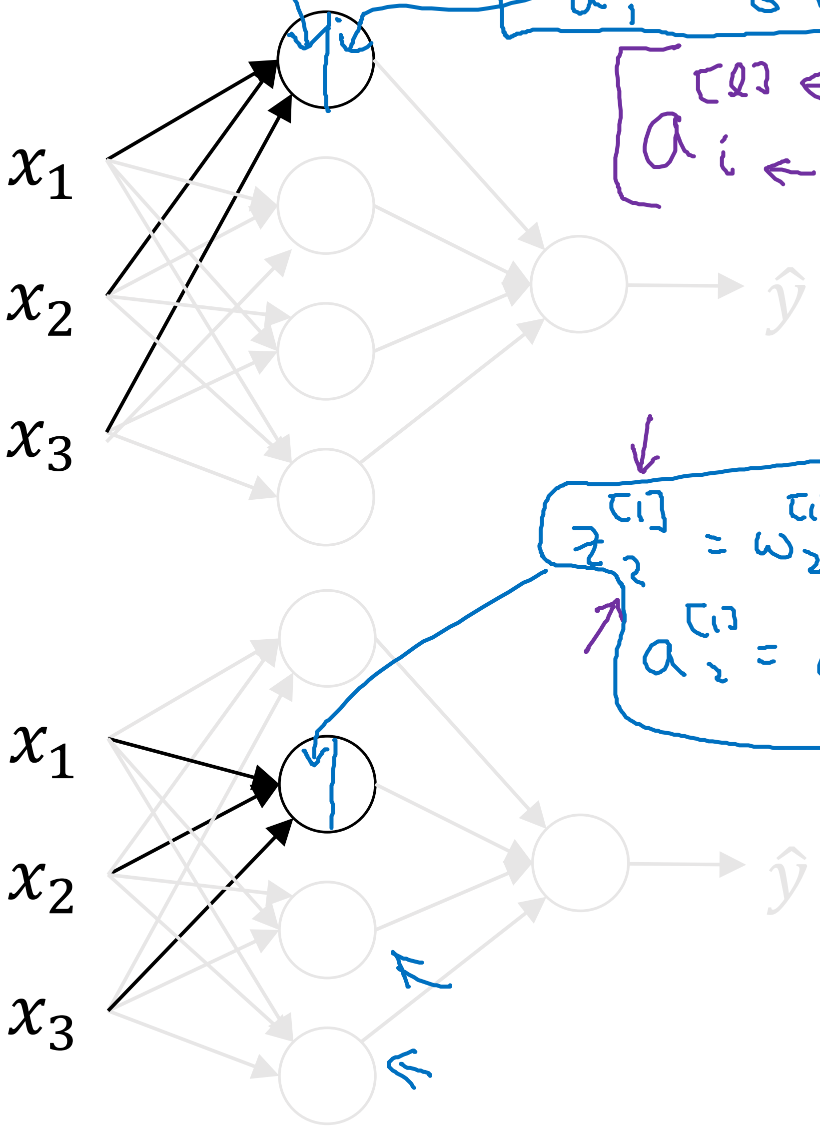
$$a = \sigma(z)$$

Neural Network Representation



$$z = w^T x + b$$

$$a = \sigma(z)$$



$z_1^{[1]} = w_1^{[1]T} x + b_1^{[1]}$

$a_1^{[1]} = \sigma(z_1^{[1]})$

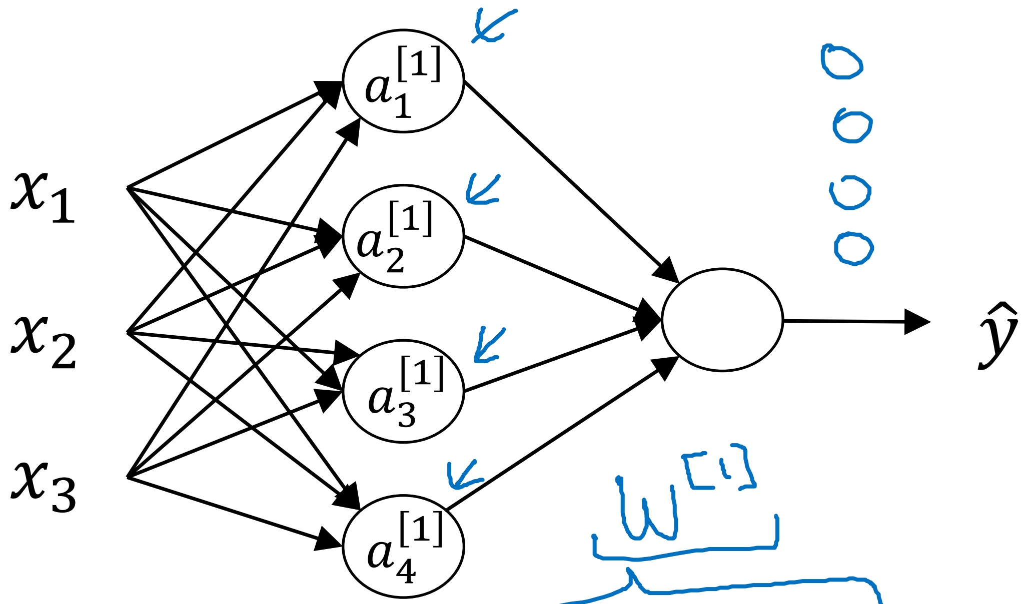
$a_i^{[l]}$ ← layer, ← node in layer.

$z_2^{[1]} = w_2^{[1]T} x + b_2^{[1]}$

$a_2^{[1]} = \sigma(z_2^{[1]})$

Neural Network Representation

$(w_1^{[1]})^T x \qquad a^{[1]}$



$$z_1^{[1]} = w_1^{[1]T}x + b_1^{[1]}, \quad a_1^{[1]} = \sigma(z_1^{[1]})$$

$$z_2^{[1]} = w_2^{[1]T}x + b_2^{[1]}, \quad a_2^{[1]} = \sigma(z_2^{[1]})$$

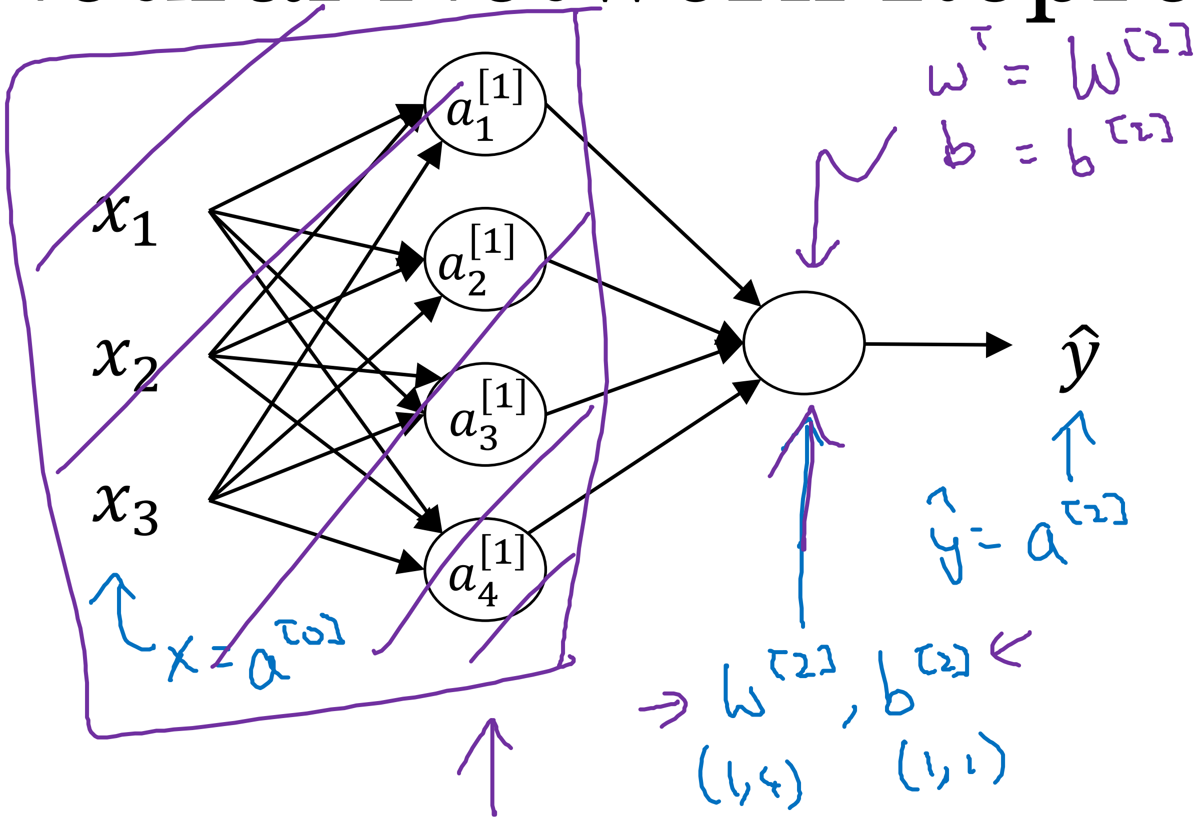
$$z_3^{[1]} = w_3^{[1]T}x + b_3^{[1]}, \quad a_3^{[1]} = \sigma(z_3^{[1]})$$

$$z_4^{[1]} = w_4^{[1]T}x + b_4^{[1]}, \quad a_4^{[1]} = \sigma(z_4^{[1]})$$

$$z^{[1]} = \overbrace{\underbrace{\begin{bmatrix} — w_1^{[1]T} — \\ — w_2^{[1]T} — \\ — w_3^{[1]T} — \\ — w_4^{[1]T} — \end{bmatrix}}_{(4,3)}}^{W^{[1]}} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} + \underbrace{\begin{bmatrix} b_1^{[1]} \\ b_2^{[1]} \\ b_3^{[1]} \\ b_4^{[1]} \end{bmatrix}}_{b^{[1]} \; (4,1)} = \begin{bmatrix} w_1^{[1]T}x + b_1^{[1]} \\ w_2^{[1]T}x + b_2^{[1]} \\ w_3^{[1]T}x + b_3^{[1]} \\ w_4^{[1]T}x + b_4^{[1]} \end{bmatrix} = \begin{bmatrix} z_1^{[1]} \\ z_2^{[1]} \\ z_3^{[1]} \\ z_4^{[1]} \end{bmatrix}$$

$$a^{[1]} = \begin{bmatrix} a_1^{[1]} \\ \vdots \\ a_4^{[1]} \end{bmatrix} = \sigma(z^{[1]})$$

Neural Network Representation learning



$z = w^T x + b$

$\hat{y} = a = \sigma(z)$

Changed: Transpose(W) to W

Given input x:

$$\underset{(4,1)}{z^{[1]}} = \underset{(4,3)}{W^{[1]}} \underset{(3,1)}{\overset{a^{[0]}}{\cancel{x}}} + \underset{(4,1)}{b^{[1]}}$$

$$\underset{(4,1)}{a^{[1]}} = \sigma(\underset{(4,1)}{z^{[1]}})$$

$$\underset{(1,1)}{z^{[2]}} = \underset{(1,4)}{W^{[2]}} \underset{(4,1)}{a^{[1]}} + \underset{(1,1)}{b^{[2]}}$$

$$\underset{(1,1)}{a^{[2]}} = \sigma(\underset{(1,1)}{z^{[2]}})$$

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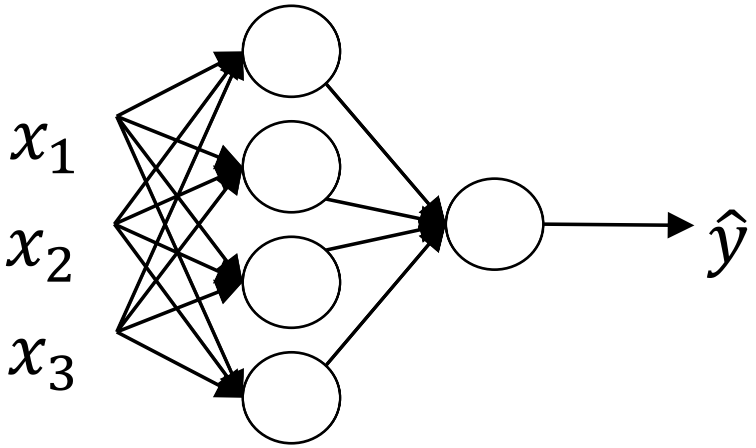
Vectorizing across multiple examples

Vectorizing across multiple examples



$$z^{[1]} = W^{[1]}x + b^{[1]}$$
$$a^{[1]} = \sigma(z^{[1]})$$
$$z^{[2]} = W^{[2]}a^{[1]} + b^{[2]}$$
$$a^{[2]} = \sigma(z^{[2]})$$

$x \longrightarrow a^{[2]} = \hat{y}$

$x^{(1)} \longrightarrow a^{[2](1)} = \hat{y}^{(1)}$

$x^{(2)} \longrightarrow a^{[2](2)} \quad \hat{y}^{(2)}$

$\vdots$

$x^{(m)} \longrightarrow a^{[2](m)} \quad \hat{y}^{(m)}$

$a^{[2](i)}$ ← example i, ← layer 2

for $i = 1$ to m,

$$z^{[1](i)} = W^{[1]}x^{(i)} + b^{[1]}$$
$$a^{[1](i)} = \sigma(z^{[1](i)})$$
$$z^{[2](i)} = W^{[2]}a^{[1](i)} + b^{[2]}$$
$$a^{[2](i)} = \sigma(z^{[2](i)})$$

Vectorizing across multiple examples

for i = 1 to m:

$$\boxed{z^{[1](i)}} = W^{[1]}x^{(i)} + b^{[1]}$$

$$\boxed{a^{[1](i)}} = \sigma(z^{[1](i)})$$

$$\boxed{z^{[2](i)}} = W^{[2]}a^{[1](i)} + b^{[2]}$$

$$\boxed{a^{[2](i)}} = \sigma(z^{[2](i)})$$

$$Z^{[1]} = W^{[1]}X + b^{[1]}$$

$$A^{[1]} = \sigma(Z^{[1]})$$

$$Z^{[2]} = W^{[2]}A^{[1]} + b^{[2]}$$

$$A^{[2]} = \sigma(Z^{[2]})$$

$$X = \begin{bmatrix} | & | & & | \\ x^{(1)} & x^{(2)} & \cdots & x^{(m)} \\ | & | & & | \end{bmatrix} \quad (n_x, m)$$

training examples

hidden units

$$Z^{[1]} = \begin{bmatrix} | & | & & | \\ z^{[1](1)} & z^{[1](2)} & \cdots & z^{[1](m)} \\ | & | & & | \end{bmatrix}$$

$$A^{[1]} = \begin{bmatrix} | & | & & | \\ a^{[1](1)} & a^{[1](2)} & \cdots & a^{[1](m)} \\ | & | & & | \end{bmatrix}$$

#hidden units

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One hidden layer Neural Network

Explanation for vectorized implementation

Justification for vectorized implementation

$$z^{[1](1)} = W^{[1]} x^{(1)} + \cancelto{0}{b^{[1]}}, \qquad z^{[1](2)} = W^{[1]} x^{(2)} + \cancelto{0}{b^{[1]}}, \qquad z^{[1](3)} = W^{[1]} x^{(3)} + \cancelto{0}{b^{[1]}}$$

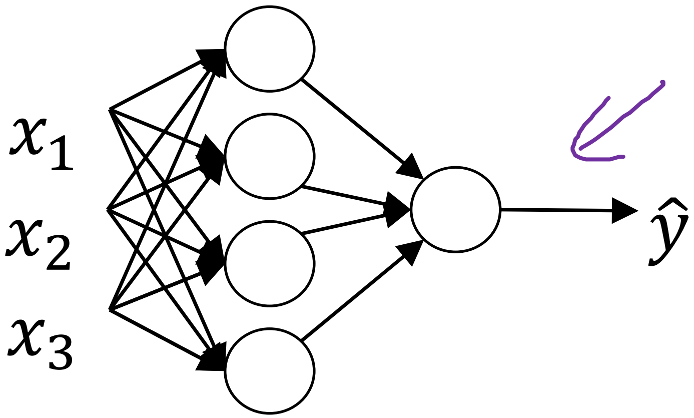
$$W^{[1]} = \begin{bmatrix} \text{---} \\ \text{---} \\ \text{---} \\ \text{---} \end{bmatrix} \qquad W^{[1]} x^{(1)} = \begin{bmatrix} \cdot \\ \cdot \\ \cdot \\ \cdot \end{bmatrix} \qquad W^{[1]} x^{(2)} = \begin{bmatrix} \cdot \\ \cdot \\ \cdot \\ \cdot \end{bmatrix} \qquad W^{[1]} x^{(3)} = \begin{bmatrix} \cdot \\ \cdot \\ \cdot \\ \cdot \end{bmatrix}$$

$$W^{[1]} \underbrace{\begin{bmatrix} | & | & | & \\ x^{(1)} & x^{(2)} & x^{(3)} & \cdots \\ | & | & | & \end{bmatrix}}_{X} = \begin{bmatrix} \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot \end{bmatrix} = \begin{bmatrix} | & | & | & \\ z^{[1](1)} & z^{[1](2)} & z^{[1](3)} & \cdots \\ | & | & | & \\ +b^{[1]} & +b^{[1]} & +b^{[1]} & \end{bmatrix} = Z^{[1]}$$

$$Z^{[1]} = W^{[1]} X + b^{[1]}$$

$$W^{[1]} x^{(i)} = z^{[1](i)}$$

Recap of vectorizing across multiple examples




```
for i = 1 to m
```

$$\boxed{z^{[1](i)} = W^{[1]}x^{(i)} + b^{[1]}}$$
$$a^{[1](i)} = \sigma(z^{[1](i)})$$
$$z^{[2](i)} = W^{[2]}a^{[1](i)} + b^{[2]}$$
$$a^{[2](i)} = \sigma(z^{[2](i)})$$

$$X = \begin{bmatrix} | & | & & | \\ x^{(1)} & x^{(2)} & \cdots & x^{(m)} \\ | & | & & | \end{bmatrix}$$

$$A^{[1]} = \begin{bmatrix} | & | & & | \\ a^{[1](1)} & a^{[1](2)} & \cdots & a^{[1](m)} \\ | & | & & | \end{bmatrix}$$

$A^{[0]}$ $X = a^{[0]}$ $x^{(i)} = a^{[0](i)}$

$$Z^{[1]} = W^{[1]}X + b^{[1]} \leftarrow W^{[1]}A^{[0]} + b^{[1]}$$
$$A^{[1]} = \sigma(Z^{[1]})$$
$$Z^{[2]} = W^{[2]}A^{[1]} + b^{[2]}$$
$$A^{[2]} = \sigma(Z^{[2]})$$

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One hidden layer Neural Network

Activation functions

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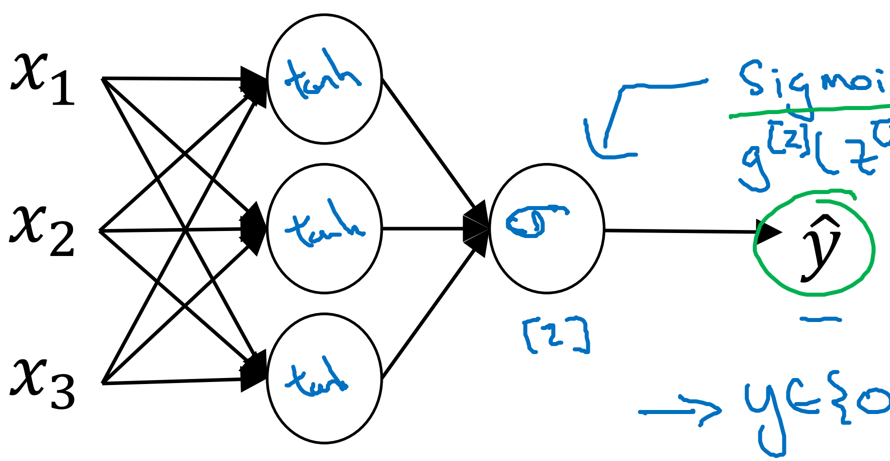
Activation functions

$g^{[1]}(z^{[1]}) = \tanh(z^{[1]})$

Sigmoid

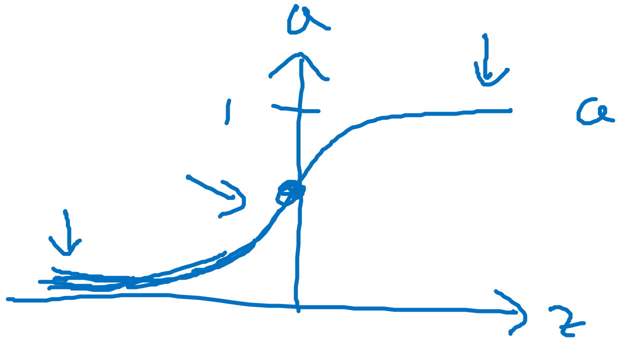
$g^{[2]}(z^{[2]}) = \sigma(z^{[2]})$



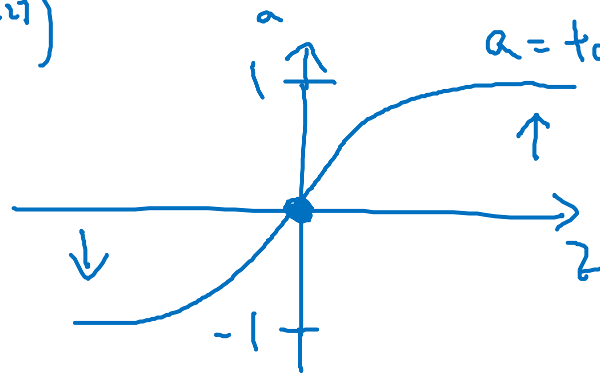
$\rightarrow y \in \{0, 1\}$

$0 \le \hat{y} \le 1$

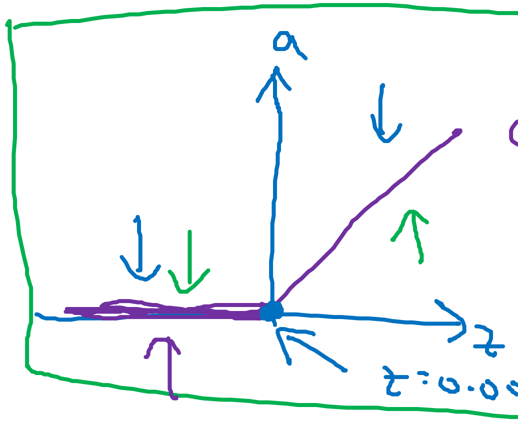
$-1 \quad 1$



$a = \frac{1}{1+e^{-z}}$



$a = \tanh(z) = \frac{e^z - e^{-z}}{e^z + e^{-z}}$

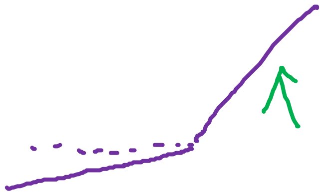


$z > 0$

$a = \max(0, z)$

ReLU

Rectified Linear Unit



Leaky ReLU

Given x:

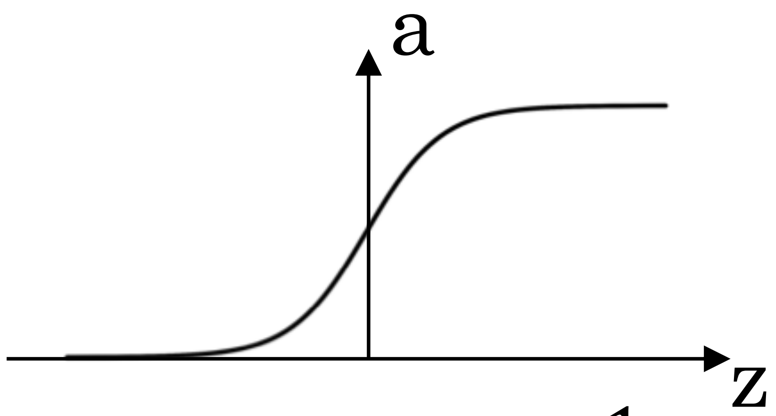
$$z^{[1]} = W^{[1]}x + b^{[1]}$$

$$\rightarrow a^{[1]} = \cancel{\sigma(z^{[1]})}\ g^{[1]}(z^{[1]})$$

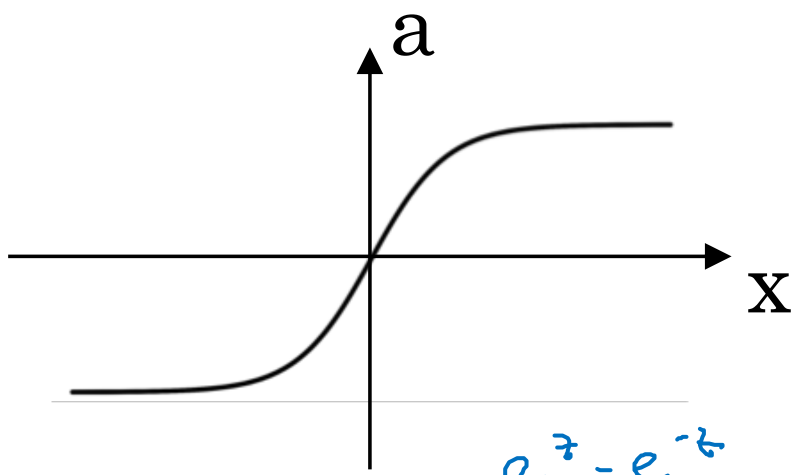
$$z^{[2]} = W^{[2]}a^{[1]} + b^{[2]}$$

$$\rightarrow a^{[2]} = \cancel{\sigma(z^{[2]})}\ g^{[2]}(z^{[2]})$$

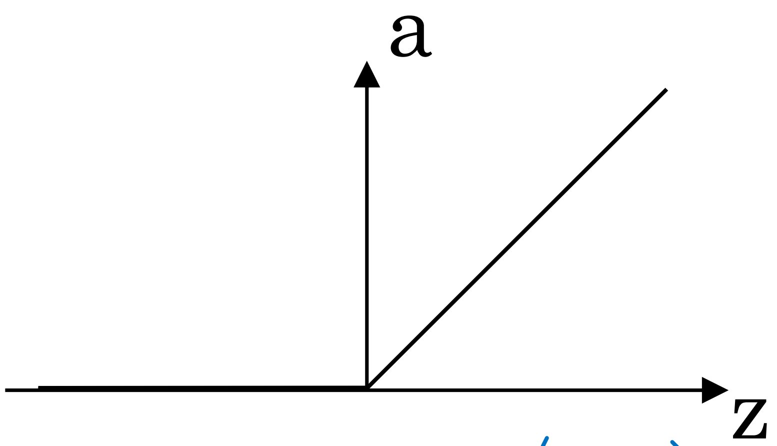
Pros and cons of activation functions



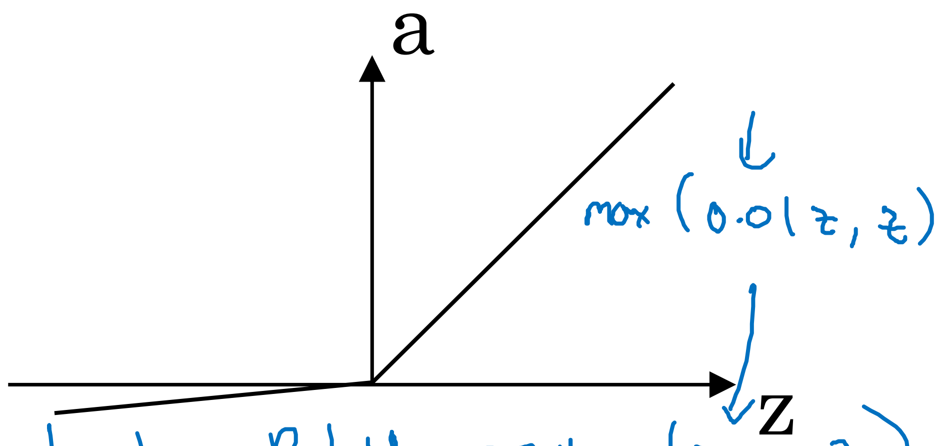
sigmoid: $a = \dfrac{1}{1+e^{-z}}$



tanh: $a = \dfrac{e^{z} - e^{-z}}{e^{z} + e^{-z}}$



ReLU $\quad a = \max(0, z)$



Leaky ReLU $\quad a = \max(0.01z, z)$

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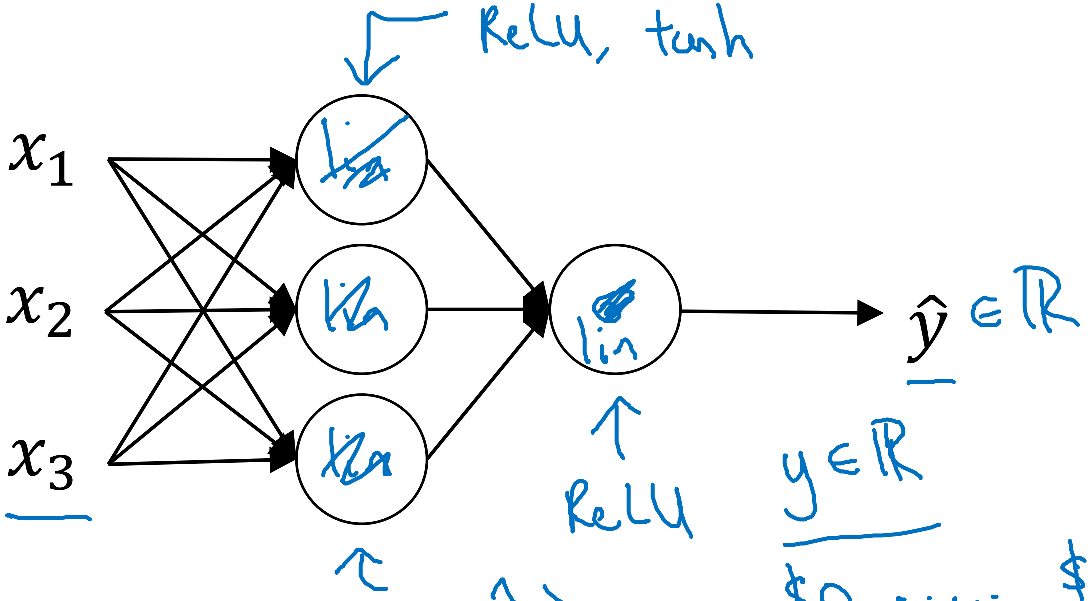
Why do you need non-linear activation functions?

Activation function



$y \in \mathbb{R}$

\$0 ..... \$1,000,000s

$\hat{y} \geq 0$.

Given x:

$$z^{[1]} = W^{[1]}x + b^{[1]}$$

$$a^{[1]} = \cancel{g^{[1]}(z^{[1]})} \; z^{[1]}$$

$$z^{[2]} = W^{[2]}a^{[1]} + b^{[2]}$$

$$a^{[2]} = \cancel{g^{[2]}(z^{[2]})} \; z^{[2]}$$

$g(z) = z$

"linear activation function"

$$a^{[1]} = z^{[1]} = W^{[1]}x + b^{[1]}$$

$$a^{[2]} = z^{[2]} = W^{[2]}a^{[1]} + b^{[2]}$$

$$a^{[2]} = W^{[2]}\underbrace{(W^{[1]}x + b^{[1]})}_{a^{[1]}} + b^{[2]}$$

$$= \underbrace{(W^{[2]}W^{[1]})}_{W'}x + \underbrace{(W^{[2]}b^{[1]} + b^{[2]})}_{b'}$$

$$= W'x + b'$$

$g(z) = z$

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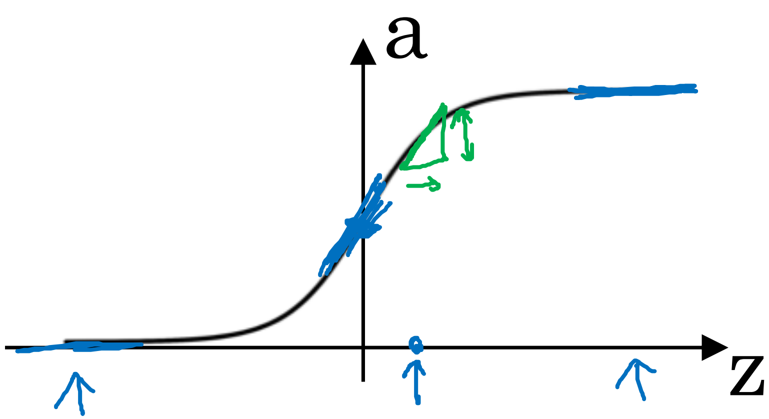
One hidden layer Neural Network

Derivatives of activation functions

Sigmoid activation function



$$g(z) = \frac{1}{1+e^{-z}}$$

$$a = g(z) = \frac{1}{1+e^{-z}}$$

$$\boxed{g'(z)} = \boxed{\frac{d}{dz} g(z)} = \text{slope of } g(x) \text{ at } z$$

$$= \frac{1}{1+e^{-z}}\left(1 - \frac{1}{1+e^{-z}}\right)$$

$$= \underbrace{g(z)\left(1 - g(z)\right)}$$

$$= \boxed{a(1-a)}$$

$$g'(z) = a(1-a)$$

$z = 10.$ $\quad g(z) \approx 1$

$$\frac{d}{dz} g(z) \approx 1(1-1) \approx 0$$

$z = -10$ $\quad g(z) \approx 0$

$$\frac{d}{dz} g(z) \approx 0 \cdot (1-0) \approx 0$$

$z = 0$ $\quad g(z) = \frac{1}{2}$

$$\frac{d}{dz} g(z) = \frac{1}{2}\left(1 - \frac{1}{2}\right) = \frac{1}{4}$$

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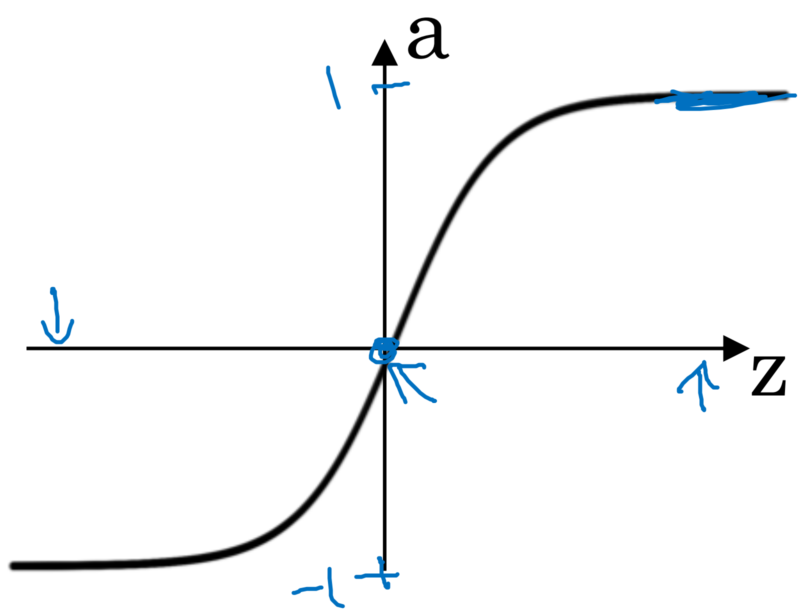
Tanh activation function



$$g(z) = \tanh(z) = \frac{e^{z} - e^{-z}}{e^{z} + e^{-z}}$$

$$g'(z) = \frac{d}{dz} g(z) = \text{slope of } g(z) \text{ at } z$$

$$= 1 - (\tanh(z))^2$$

$$a = g(z), \quad g'(z) = 1 - a^2$$

$z = 10 \quad \tanh(z) \approx 1$

$g'(z) \approx 0$

$z = -10 \quad \tanh(z) \approx -1$

$g'(z) \approx 0$

$z = 0 \quad \tanh(z) = 0$

$g'(z) = 1$

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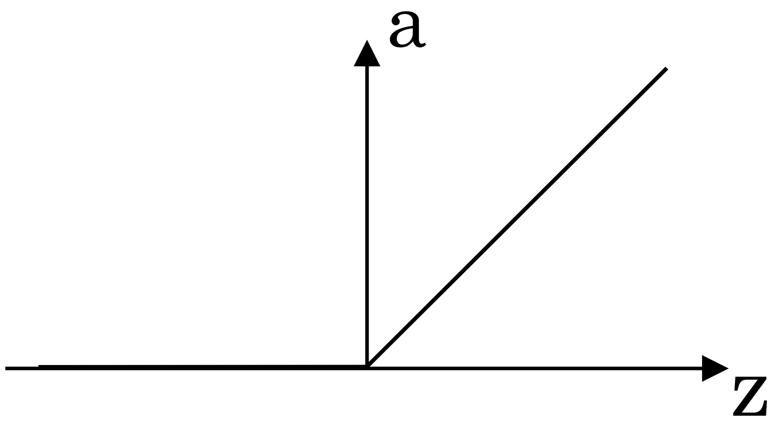
ReLU and Leaky ReLU

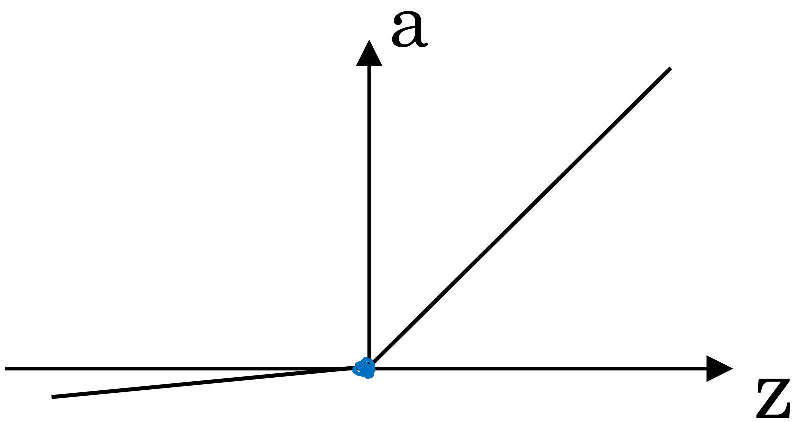


ReLU

$$g(z) = \max(0, z)$$

$$g'(z) = \begin{cases} 0 & \text{if } z < 0 \\ 1 & \text{if } z \geq 0 \\ \cancel{\text{undef}} & \cancel{\text{if } z = 0} \end{cases}$$

$$z = 0.00000\ldots0$$



Leaky ReLU

$$g(z) = \max(0.01z, z)$$

$$g'(z) = \begin{cases} 0.01 & \text{if } z < 0 \\ 1 & \text{if } z \geq 0 \end{cases}$$

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One hidden layer Neural Network

Gradient descent for neural networks

Gradient descent for neural networks

Parameters: $W^{[1]}$, $b^{[1]}$, $W^{[2]}$, $b^{[2]}$
$(n^{[1]}, n^{[0]})$ $(n^{[1]}, 1)$ $(n^{[2]}, n^{[1]})$ $(n^{[2]}, 1)$

$n_x = n^{[0]}, n^{[1]}, n^{[2]} = 1$

Cost function: $J(W^{[1]}, b^{[1]}, W^{[2]}, b^{[2]}) = \frac{1}{m} \sum_{i=1}^{n} \mathcal{L}(\hat{y}, y)$

$\hat{y} \leftarrow a^{[2]}$

Gradient descent:

→ Repeat {

→ Compute predicts $(\hat{y}^{(i)}, i = 1 \ldots, m)$

$dW^{[1]} = \frac{\partial J}{\partial W^{[1]}}$, $db^{[1]} = \frac{\partial J}{\partial b^{[1]}}$, ...

$W^{[1]} := W^{[1]} - \alpha \, dW^{[1]}$

$b^{[1]} := b^{[1]} - \alpha \, db^{[1]}$

$W^{[2]} := \ldots$ $b^{[2]} := \ldots$

}

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Formulas for computing derivatives

A-Y: derivation shown in Logistic case

Forward propagation:

$Z^{[1]} = W^{[1]}X + b^{[1]}$

$A^{[1]} = g^{[1]}(Z^{[1]})$

$Z^{[2]} = W^{[2]}A^{[1]} + b^{[2]}$

$A^{[2]} = g^{[2]}(Z^{[2]}) = \sigma(Z^{[2]})$

Back propagation:

$dZ^{[2]} = A^{[2]} - Y$

$Y = [y^{(1)} \; y^{(2)} \; \ldots, y^{(m)}]$

$(n^{[2]},)$

$dW^{[2]} = \frac{1}{m} dZ^{[2]} A^{[1]T}$

$(n^{[2]}, 1)$

$db^{[2]} = \frac{1}{m}$ np.sum($dZ^{[2]}$, axis=1, keepdims=True)

$dZ^{[1]} = \underbrace{W^{[2]T} dZ^{[2]}}_{(n^{[1]}, m)} * \underbrace{g^{[1]\prime}(Z^{[1]})}_{(n^{[1]}, m)}$

element-wise product

$dW^{[1]} = \frac{1}{m} dZ^{[1]} X^T$

$db^{[1]} = \frac{1}{m}$ np.sum($dZ^{[1]}$, axis=1, keepdims=True)

$(n^{[1]}, 1)$ $\quad$ $(n^{[1]},)$ $\quad$ reshape

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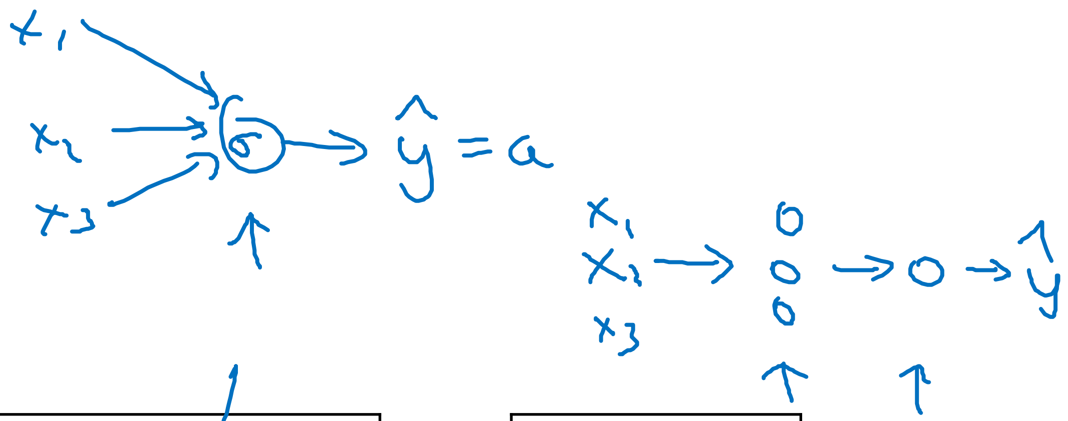
Backpropagation intuition (Optional)

Computing gradients



Logistic regression

$$x,\ w,\ b \rightarrow \boxed{z = w^T x + b} \rightarrow \boxed{a = \sigma(z)} \rightarrow \boxed{\mathcal{L}(a, y)}$$

$dz = a - y$

$da = \frac{d}{da}\mathcal{L}(a,y) = \underline{-y\log a - (1-y)\log(1-a)}$

$= -\frac{y}{a} + \frac{1-y}{1-a}$

$dw = dz \cdot x$

$db = dz$

$\boxed{dz = da \cdot g'(z)}$

$g(z) = \sigma(z)$

$\boxed{\frac{\partial \mathcal{L}}{\partial z} = \frac{\partial \mathcal{L}}{\partial a} \cdot \boxed{\frac{da}{dz}}}$

"dz" = "da"

$\frac{d}{dz} g(z) = \underline{g'(z)}$

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for single example

Neural network gradients

$x_1, x_2, x_3 \rightarrow \circ \rightarrow \circ \rightarrow \hat{y}$

$n_x = n^{[0]}$ $\quad n^{[1]}$ $\quad n^{[2]} = 1$

x, $W^{[1]}$, $b^{[1]}$ → $z^{[1]} = W^{[1]}x + b^{[1]}$ → $a^{[1]} = \sigma(z^{[1]})$ → ($W^{[2]}$, $b^{[2]}$) → $z^{[2]} = W^{[2]}x + b^{[2]}$ → $a^{[2]} = \sigma(z^{[2]})$ → $\mathcal{L}(a^{[2]}, y)$

$dW^{[1]}$, $db^{[1]}$, $dW^{[2]}$, $db^{[2]}$

$dz^{[1]} = W^{[2]T} dz^{[2]} * g^{[1]\prime}(z^{[1]})$ ← element wise product

$da^{[1]} = \dots$

$dz^{[2]} = a^{[2]} - y$

$da^{[2]}$

$dW^{[2]} = dz^{[2]} a^{[1]T}$

$db^{[2]} = dz^{[2]}$

→ "$dw = dz \cdot x$"

$w^{[1]}: [\quad]$

$w^{[2]}$ $\quad (n^{[2]}, n^{[1]})$

$z^{[2]}, dz^{[2]}$ $\quad (n^{[2]}, 1)$ $\quad - (1,1)$

$z^{[1]}, dz^{[1]}$ $\quad (n^{[1]}, 1)$

$dz^{[1]} = \boxed{W^{[2]T} dz^{[2]}} * \boxed{g^{[1]\prime}(z^{[1]})}$

$(n^{[1]}, 1) = (n^{[1]}, n^{[2]}) \; (n^{[2]}, 1) * (n^{[1]}, 1)$

foo $\quad$ $W^{[1]}$

dfoo $\quad$ $dW^{[2]}$

$dW^{[1]} = dz^{[1]} \cdot x^T$ ← $a^{[0]T}$

$db^{[1]} = dz^{[1]}$

var & d(var) have same dimension

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Summary of gradient descent

$$dz^{[2]} = a^{[2]} - y$$

$$dW^{[2]} = dz^{[2]} a^{[1]^T}$$

$$db^{[2]} = dz^{[2]}$$

$$dz^{[1]} = W^{[2]T} dz^{[2]} * g^{[1]\prime}(\mathrm{z}^{[1]})$$

$$dW^{[1]} = dz^{[1]} x^T$$

$$db^{[1]} = dz^{[1]}$$

Vectorized Implementation:

$$z^{[1]} = W^{[1]} x + b^{[1]}$$

$$a^{[1]} = g^{[1]}(z^{[1]})$$

$$Z^{[1]} = \begin{bmatrix} | & | & & | \\ z^{[1](1)} & z^{[1](2)} & \cdots & z^{[1](m)} \\ | & | & & | \end{bmatrix}$$

$$Z^{[1]} = W^{[1]} X + b^{[1]}$$

$$A^{[1]} = g^{[1]}(Z^{[1]})$$

Andrew Ng

Summary of gradient descent

$$\underline{dz^{[2]}} = \underline{a^{[2]}} - \underline{y}$$

$$dW^{[2]} = dz^{[2]} a^{[1]^T}$$

$$db^{[2]} = dz^{[2]}$$

$$\underbrace{dz^{[1]}}_{(n^{[1]},1)} = W^{[2]T} dz^{[2]} * g^{[1]\prime}(z^{[1]})$$

$$dW^{[1]} = dz^{[1]} x^T$$

$$db^{[1]} = dz^{[1]}$$

$$\underline{dZ^{[2]} = A^{[2]} - Y}$$

$$J(\ldots) = \frac{1}{m} \sum_{i=1}^{n} \mathcal{L}(\hat{y}, y)$$

$$dW^{[2]} = \frac{1}{m} dZ^{[2]} A^{[1]^T}$$

$$db^{[2]} = \frac{1}{m} np.sum(dZ^{[2]}, axis = 1, keepdims = True)$$

elementwise product

$$\underbrace{dZ^{[1]}}_{(n^{[1]},m)} = \underbrace{W^{[2]T} dZ^{[2]}}_{(n^{[1]},m)} * \underbrace{g^{[1]\prime}(Z^{[1]})}_{(n^{[1]},m)}$$

$$dW^{[1]} = \frac{1}{m} dZ^{[1]} X^T$$

$$db^{[1]} = \frac{1}{m} np.sum(dZ^{[1]}, axis = 1, keepdims = True)$$

Andrew Ng

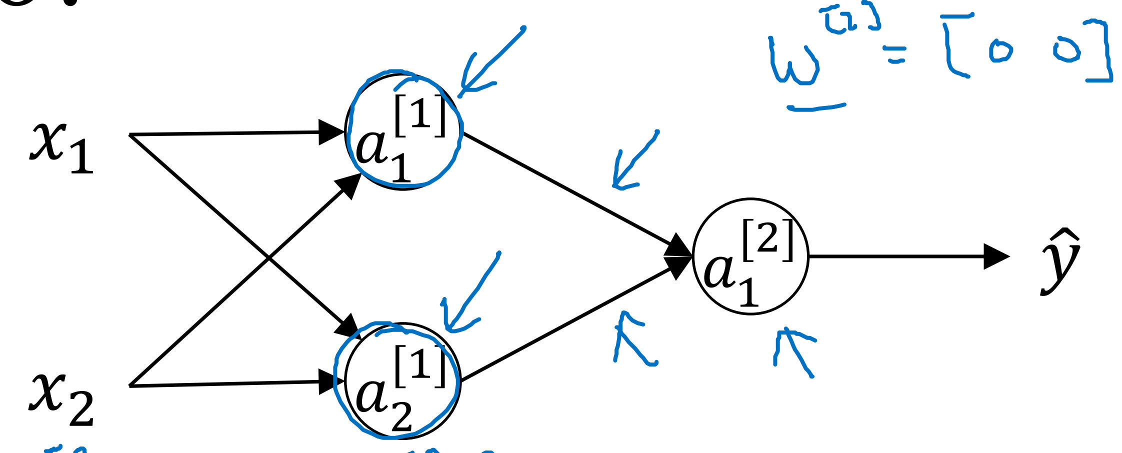
One hidden layer Neural Network

Random Initialization

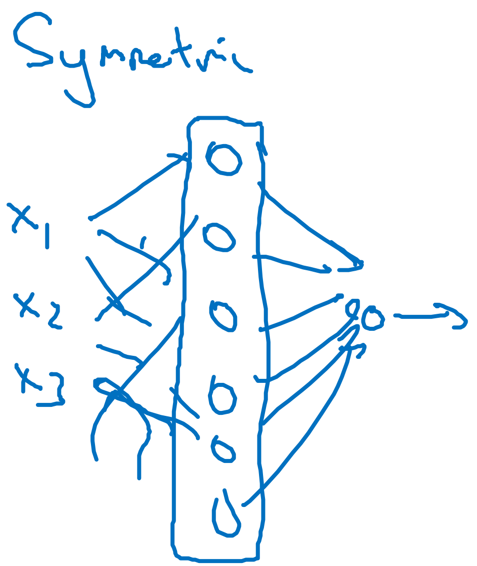
deeplearning.ai

What happens if you initialize weights to zero?

Every node in a layer becomes symmetric and changes together at each iteration.



$n^{[0]} = 2$ $\quad$ $n^{[1]} = 2$



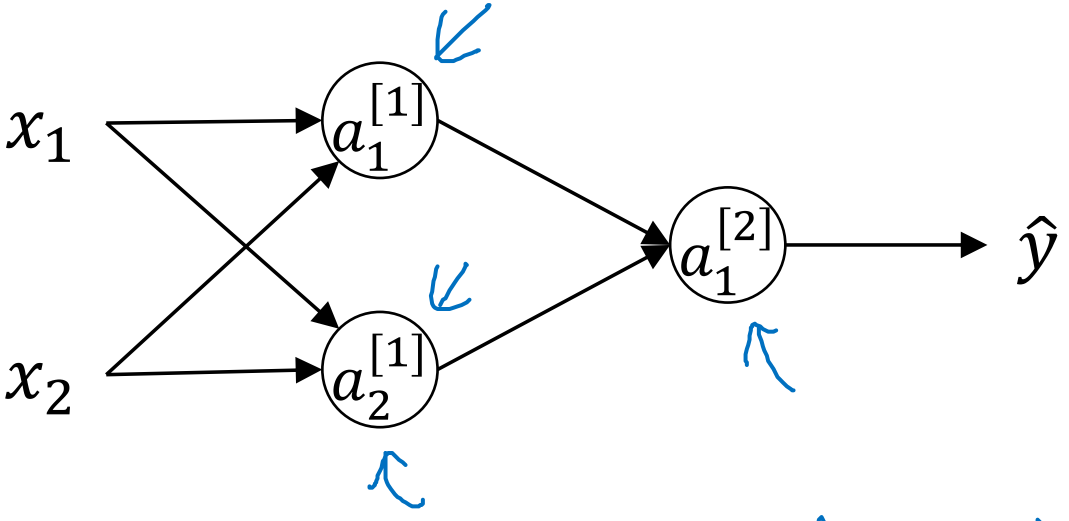
$W^{[1]} = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$ $\quad$ $b^{[1]} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$

$W^{[1]} = \begin{bmatrix} - - - - \\ - - - - \end{bmatrix}$

$a_1^{[1]} = a_2^{[1]}$ $\quad$ $dz_1^{[1]} = dz_2^{[1]}$

$dw = \begin{bmatrix} u & v \\ u & v \end{bmatrix}$ $\quad$ $W^{[1]} = W^{[1]} - \alpha dW$

Random initialization



→ $W^{[1]}$ = np.random.randn((2,2)) * 0.01

100?

$b^{[1]}$ = np.zeros((2,1))

$W^{[2]}$ = np.random.randn((1,2)) * 0.01

$b^{[2]} = 0$

→ $z^{[1]} = W^{[1]}x + b^{[1]}$

$a^{[1]} = g^{[1]}(z^{[1]})$