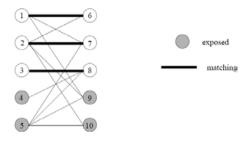
INT202 Complexity of Algorithms Minimum Spanning Tree and Network Flow

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Bipartite Matching - Definitions

- \triangleright A graph G = (V, E) is called *bipartite* if and only if
 - ➤ The set *V* can be partitioned into two sets, *X* and *Y*.
 - Every edge of G has an endpoint in X and the other endpoint in Y.
- A matching M ⊆ E is a set of edges that have no endpoints in common. Each vertex from one set has at most one "partner" in the other set.
- ➤ If a vertex *v* has no edge of *M* incident to it then *v* is said to be *exposed* (or unmatched)).
- A matching is perfect if no vertex is exposed.

Bipartite Matching - Example



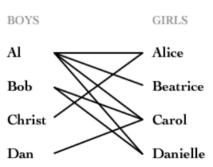
The maximum bipartite matching problem is to find a matching *M* with the greatest number of edges (over all matchings).

Maximum Bipartite Matching Given a bipartite graph $G = (A \cup B, E)$, find an $S \subseteq A \times B$ that is a matching and is as large as possible.

Notes:

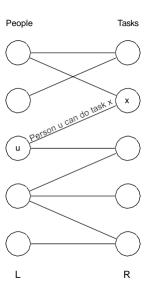
- We're given A and B so we don't have to find them.
- *S* is a **perfect matching** if every vertex is matched.

Example 1: Let G be a bipartite graph where the set X represents a group of boys and the set Y a group of girls, who are all together at a community dance. Let there be an edge joining $x \in X$ and $y \in Y$ if x and y are willing to dance with one another. A maximum matching in G corresponds to a largest set of compatible pairs of boy and girl who can all happily dancing at the same time.



Example 2: Let *G* be a bipartite graph Suppose we have a set of people *L* and set of jobs *R*.

- Each person can do only some of the jobs.
- Can model this as a bipartitegraph

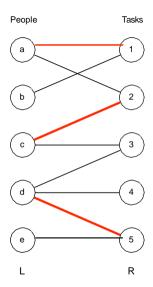


 A matching gives an assignment of peopleto tasks.

If a vertex v has no edge of M incident to it then v is said to be **exposed** (or unmatched)).

A maximal bipartite matching is the largest subset of edges in a bipartite graph such that no two selected edges share a common vertex.

· (This one is not maximum.)



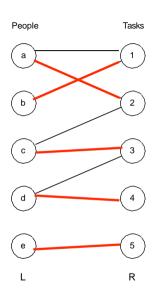
(a,1), (c,2),(d,5) are matched. b,e,3,4 are exposed.

 A matching gives an assignment of peopleto tasks.

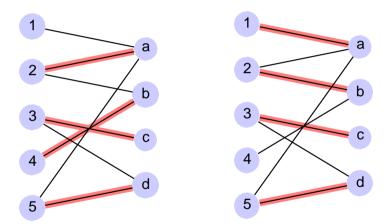
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A matching is **perfect** if no vertex is exposed.



Matching not guaranteed to be unique.

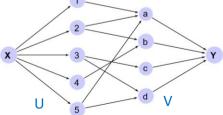


Reduce

We can solve the maximum bipartite matching problem using a *network flow* approach.

- We first ensure that all edges from U to Vare directed.
- We introduce a single source node that has outgoing edges to each node in U
- We then add a sink node that has incoming edges from each node in V.

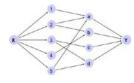
The problem now becomes finding the *maximal flow* in the graph.



We denote the source node as X and the sink node as Y



Reduce



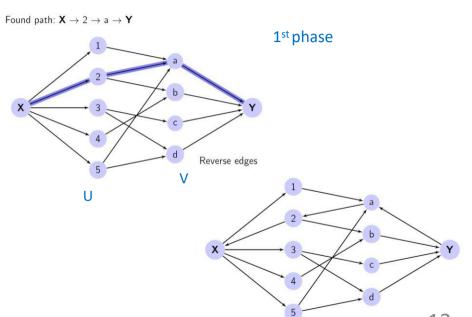
One can more intuitively consider flow as water running through pipes represented by the edges.

There are many algorithms one could use to solve *network flow* problems (such as Ford–Fulkerson algorithm). For the specific case of **bipartite graphs**, we don't need the full generality of most network flow algorithms.

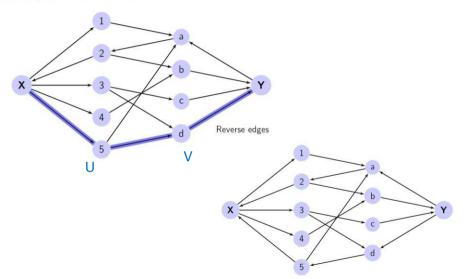
Since we've converted the problem to an unweighted directed graph, we can therefore use the following simplified algorithm which solves the max flow problem for any general unweighted directed graph.

Solving maximal flow for an unweighted directed graph:

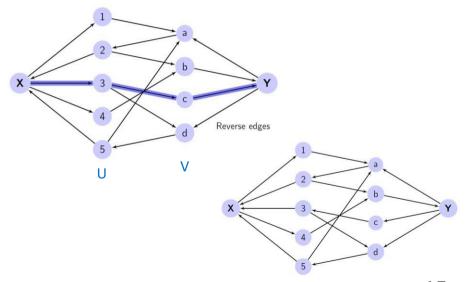
- 1. Construct the directed graph with a source and sink node.
- 2. Using a search method to find a path from the source to the sink.
- 3. Once a path is found, reverse each edge on this path.
- 4. Repeat step 2 and 3 until no more paths from the sink to source exist.
- 5. The final matching solution is then the set of edges between *U* and *V* that are reversed (i.e. run from *V* to *U*).



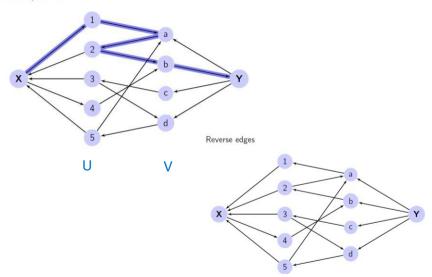
Found path: $\mathbf{X} \to \mathbf{5} \to \mathbf{d} \to \mathbf{Y}$



Found path: $\mathbf{X} \to \mathbf{3} \to \mathbf{c} \to \mathbf{Y}$



Found path: $\mathbf{X} \to \mathbf{1} \to \mathbf{a} \to \mathbf{2} \to \mathbf{b} \to \mathbf{Y}$



No more paths found. Matching is reversed edges.

