# ACM TEMPLATE



UESTC\_Jungle

Last build at October 25, 2018

## Contents

I	Data	astructure 3				
	I.I	Fenwick				
	I.2	BST in pb_ds				
	1.3	Segment Tree				
	I.4	Sparse Table				
	I.5	Treap				
	1.6	Leftist Heap				
	I.7	Splay				
	1.8	Persistent Segment Tree				
	_					
2	•	amic Programming				
	2.I	LIS $O(n \log n)$				
	2.2	$LCS O(n \log n) \dots 15$				
	2.3	Improved by quadrilateral inequality				
	2.4	Improved by Slope				
	2.5	Steiner Tree				
3	Geometry 19					
,	3.I	2D				
	,	3.1.1 Point				
		3.I.2 Circle				
		3.1.3 Convex hull				
		3.I.4 Intersect Area				
		3.1.5 Universe				
		3.1.6 Largest empty convex				
4	Graph 37					
	4.I	Tree				
		4.I.I Universe				
		4.1.2 Point Divide and Conquer				
		4.1.3 Hevay chain decompostion				
	4.2	2-SAT				
	4.3	Cut Edge and Point				
	4.4	Euler Path				
	4.5	Shortest Path				
		4.5.1 Dijkstra				
		4.5.2 Shortest Path Fast Algorithm				
		4.5.3 $K$ -th shortest path				
	4.6	Maxflow				
	4.7	Strongly Connected Component				
	4.8	Perfect elimination ordering				
5	Mat	h 64				
)	5.I	Euler Function				
	5.2	Möbius Function				
	5.4 5.3	Number Theory Inverse				
		Chinese Remainder Theorem				
	5.4	3				
	5·5	0				
	5.6	·				
	5.7	NTT				
	5.8	Fast Walsh—Hadamard transform				

			UESTC_Jungle
	5.9	Lucas	74
	5.10	Linear Programming	74
	5.11	Big Prime Test	77
		5.II.I Miller Rabin	79
		5.11.2 Pollard's rho	80
	5.12	Montgomery modular multiplication	81
	5.13	Berlekamp Massey	82
	5.14	Inclusion—exclusion principle	
		5.14.1 General form	84
		5.14.2 A generalization	84
		5.14.3 Applications	84
	5.15	Lindström—Gessel—Viennot lemma	84
6	Stri	ng	85
	6.I	Hash	•
	6.2	KMP	•
	6.3	exKMP	
	6.4	Suffix Array	
	6.5	Aho-Corasick Automata	•
	6.6	Manacher	91
7	Utili	ity	92
•	7.I	IO plug-in	
	7.2	Random Numbers	
	•		
8		pendix	96
	8.1	C++ Reference	
		8.1.1 Debug	
		8.1.2 STL	•
	8.2	Java Reference	
		8.2.1 Basic	· ·
		8.2.2 BigInteger	-
		8.2.3 BigDecimal	
		8.2.4 Sorting	IOO

#### I Datastructure

#### 1.1 Fenwick

```
/* Fenwick Tree (Binary Indexed Tree), by Abreto <m@abreto.net>. */
   #include <cstring>
 3
 4
   using namespace std;
 5
 6
    template <class T = int, int MAXN = 100001>
 7
   struct fenwick {
 8
      static inline int lowbit(int x) {
 9
        return (x&(-x));
10
      int N;
11
      T f[MAXN]; /* 1=based. */
12
13
      fenwick(void):N(MAXN) {
14
        init();
15
16
      fenwick(int n):N(n) {
17
        init();
18
      }
19
      void init(void) {
20
        memset(f,0,sizeof(f));
21
      void upd(int i, T dx) {
22
23
        while(i <= N) {</pre>
24
          f[i] += dx;
25
          i += lowbit(i);
        }
26
27
28
      T sum(int i) {
29
        T ret = 0;
30
        while(i) {
31
          ret += f[i];
32
          i -= lowbit(i);
33
34
        return ret;
35
36
   };
   /* Fenwick Tree (Binary Indexed Tree), by Abreto <m@abreto.net>. */
 2
 3
   #define MAXN 100001
 4
   #define LOWBIT(x)
                         ((x)&(-(x)))
 5
 6
   int N;
 7
   int fen[MAXN];
 8
 9
   void update(int i, int dx) {
10
      while(i <= N) {</pre>
        fen[i] += dx;
11
12
        i += LOWBIT(i);
13
14
15
16
   int sum(int i) {
      int s = 0;
17
18
      while(i > 0) {
19
        s += fen[i];
20
        i -= LOWBIT(i);
21
22
      return s;
23
```

#### 1.2 BST in pb\_ds

```
/* Red-Black tree via pb_ds. */
   #include<bits/stdc++.h>
 3
   #include<ext/pb_ds/assoc_container.hpp>
 4
   #include<ext/pb_ds/tree_policy.hpp>
 5
   using namespace __gnu_pbds;
   using namespace std;
 7
   template <typename T>
 8
   using ordered_set = tree<T, null_type, less<T>, rb_tree_tag,
       tree_order_statistics_node_update>;
 9
10
   int main() {
11
     ordered_set<int> s;
12
     s.insert(1);
13
     s.insert(3);
     cout << s.order_of_key(2) << endl; // the number of elements in the s less than 2
14
      cout << *s.find_by_order(0) << endl; // print the 0-th smallest number in s(0-based</pre>
15
16 | }
```

#### 1.3 Segment Tree

```
//* Segment tree (Interval tree, range tree), by Abreto <m@abreto.net>. */
 3
    template <int STMAX = 1000000>
 4
    struct segment_tree {
 5
      struct node_t {
 6
        static inline node_t merge(node_t n1, node_t n2) {
 7
          node_t ans;
 8
          ans.l = n1.l;
 9
          ans.r = n2.r;
          /* merge n1 and n2 to ans. */
10
11
          return ans;
        }
12
13
14
        /* Data field */
15
        int l,r;
16
      } nodes[(STMAX+1)<<2];</pre>
17
18
      struct lazy_t {
19
        int marked; /* Optional */
20
        /* lazy mark. */
21
22
        lazy_t(void) {
23
          clear();
24
25
        void clear(void) {
26
          marked=0;
27
      } marks[(STMAX+1)<<2];</pre>
28
29
30
      inline void maintain_leaf(int o, int idx) {
31
        nodes[o].l = nodes[o].r = idx;
32
        /* Operations to single elements ... */
33
34
      inline void maintain(int o) {
35
        nodes[o] = node_t::merge(nodes[o<<1], nodes[o<<1|1]);</pre>
36
37
38
      /* Usage: build(1,1,n); */
39
      void build(int o, int l, int r) \{ /* [l,r] */
```

```
40
         if( r <= l ) {
 41
           maintain_leaf(o, 1);
 42
         } else {
 43
           int mid = 1+r>>1;
 44
           build(o<<1, 1, mid);
           build(o<<1|1, mid+1, r);
 45
 46
           maintain(o);
 47
       }
 48
 49
 50
       /* Modify all elements in [l,r] */
 51
       void mark(lazy_t act, int o) {
 52
         /* do something .. */
         marks[o].marked = 1;
 53
 54
 55
 56
       /* Pass cached updates. */
 57
       void pushdown(int o) {
 58
         if( marks[o].marked ) {
 59
           mark(marks[o], o<<1);</pre>
 60
           mark(marks[o], o<<1|1);
 61
           marks[o].clear();
 62
 63
       }
 64
 65
       /* Do act on all elements in [L,R] */
 66
       void upd(int L, int R, lazy_t act, int o, int l, int r) {
 67
         if( L <= 1 && r <= R ) {
 68
           mark(act, o);
         } else if (L <= R) {</pre>
 69
           int mid = (l+r)>>1;
 70
 71
           pushdown(o);
           if( L <= mid ) upd(L, R, act, o<<1, l, mid);
 72
 73
           if( R > mid ) upd(L, R, act, o<<1|1, mid+1, r);
 74
           maintain(o);
 75
 76
       }
 77
 78
       node_t qry(int L, int R, int o, int l, int r) {
 79
         if(L \le 1 \& r \le R)
 80
           return nodes[o];
 81
         else if (L \ll R) {
 82
           int mid = (l+r)>>1;
 83
           pushdown(o);
 84
           if(R <= mid) return qry(L,R,o<<1,l,mid);</pre>
 85
           if(L > mid) return qry(L,R,o<<1|1,mid+1,r);
 86
           return node_t::merge(qry(L,R,o<<1,l,mid),qry(L,R,o<<1|1,mid+1,r));</pre>
 87
         }
 88
       }
 89
 90
       int N;
 91
 92
       segment_tree(void):N(STMAX) {}
93
       segment_tree(int n):N(n) {}
 94
       void build(int n) {
 95
         N = n;
 96
         build(1,1,N);
 97
       }
 98
       void update(int L, int R, lazy_t act) {
 99
         upd(L,R,act,1,1,N);
100
       node_t query(int L, int R) {
101
102
         return qry(L,R,1,1,N);
103
       }
```

```
104 | };
    |/* Segment tree (Interval tree, range tree), by Abreto <m@abreto.net>. */
  1
  3
    #define MAXN
                      1000001
  4
  5
     typedef struct {
       int l,r;
  6
       /* Data field */
  7
  8
    } node_t;
  9
 10
    node_t merge(node_t n1, node_t n2) {
 11
       node_t ans;
 12
       ans.l = n1.l;
 13
       ans.r = n2.r;
 14
       /* merge n1 and n2 to ans. */
 15
       return ans;
 16
    }
 17
     typedef struct {
 18
 19
       int marked; /* Optional */
 20
       /* lazy mark. */
 21
    } lazy_t;
 22
 23
    int A[MAXN];
 24
    node_t nodes[MAXN<<2];</pre>
 25
    lazy_t marks[MAXN<<2];</pre>
 26
 27
    void maintain_leaf(int o, int idx) {
 28
       nodes[o].l = nodes[o].r = idx;
 29
       /* Operations to single elements ... */
 30
 31
    void maintain(int o) {
       nodes[o] = merge(nodes[o << 1], nodes[o << 1|1]);
 32
 33
    }
 34
 35
     /* Usage: build(1,1,n); */
 36
    void build(int o, int l, int r) \{ /* [l,r] */
 37
       if( r <= l ) {
 38
         maintain_leaf(o, 1);
 39
       } else {
 40
         int mid = 1+r>>1;
 41
         build(o<<1, 1, mid);
         build(o<<1|1, mid+1, r);
 42
 43
         maintain(o);
 44
 45
       marks[o].marked = 0;
 46
 47
 48
    /* Modify all elements in [l,r] */
 49
    void mark(lazy_t act, int o) {
       /* do something .. */
 50
 51
       marks[o].marked = 1;
 52
 53
 54
    /* Pass cached updates. */
 55
    void pushdown(int o) {
 56
       if( marks[o].marked ) {
 57
         mark(marks[o], o<<1);</pre>
 58
         mark(marks[o], o<<1|1);
 59
         marks[o].marked = 0;
 60
       }
    }
 61
 62
```

```
/* **DISCARDED** */
63
   /* Set A[p]=v. Usage: modify(p, v, 1, 1, n);
65
   void modify(int p, int v, int o, int l, int r)
66
        if(r-1 < 2)
67
68
69
            maintain_leaf(o, v);
70
        } else {
71
            int mid = (l+r)/2;
72
            pushdown(o);
73
            if( p \le mid ) modify(p, v, o*2, l, mid);
74
            else modify(p, v, o*2+1, mid, r);
75
            maintain(o);
76
   }*/
77
78
79
   /* Do act on all elements in [L,R] */
80
   void update(int L, int R, lazy_t act, int o, int l, int r) {
81
     if( L <= 1 && r <= R ) {
82
        mark(act, o);
83
     } else if (L <= R) {</pre>
84
        int mid = (l+r)>>1;
85
        pushdown(o);
86
        if( L <= mid ) update(L, R, act, o<<1, l, mid);</pre>
        if( R > mid ) update(L, R, act, o<<1|1, mid+1, r);
87
88
        maintain(o);
89
     }
90 | }
```

#### 1.4 Sparse Table

```
/* RMQ with Sparse Table, by Abreto <m@abreto.net>. */
 1
 2
 3
   int min(int a, int b) {
 4
     return (a<b)?a:b;
 5
 6
 7
   #define MAXN
                    100001
 8
   #define MAXLOG
 9
10
   int N;
11
   int A[MAXN];
                    /* indexed from 0. */
12
   int st[MAXN][MAXLOG];
13
14
   void st_init() {
15
     int i = 0, j = 0, t = 0;
16
     for(i = 0; i < N; ++i) st[i][0] = A[i];
17
     for(j = 1; (t=(1<<j)) <= N; ++j)
18
        for(i = 0; (i+t-1) < N; ++i)
19
          st[i][j] = min(st[i][j-1], st[i+(t>>1)][j-1]);
20
     /* st(i,j) = min(st(i,j-1), st(i+2^(j-1),j-1)). */
21
22
   int st_query(int l, int r) {
23
24
     int k = 0;
25
     while((1 << (k+1)) <= (r-l+1)) k++;
      return min(st[l][k], st[r-(1 << k)+1][k]);
26
27 |}
```

#### 1.5 Treap

```
|#include <bits/stdc++.h>
 1
 2
 3
   using namespace std;
 5
   #define MAXN (2560000)
 6
 7
   int __treap_mem[MAXN];
 8
   void init_treap_mem(void) {
9
      for( int i = 1; i < MAXN; i++)
10
       \_treap\_mem[i-1] = i;
11
12
   int alloc_address(void) {
13
     int ret = __treap_mem[0];
14
      __treap_mem[0] = __treap_mem[ret];
15
      return ret;
16
17
   void free_address(int p) {
18
     _{\text{treap\_mem}[p]} = _{\text{treap\_mem}[0]};
19
      \_treap_mem[0] = p;
20
21
22
   typedef int key_t;
23
   typedef int val_t;
24
   struct treap {
25
     key_t x;
26
     val_t v;
27
               /* random priority */
     int r;
28
     int eq, s; /* number of equal ones, size of subtree (include root itself) */
     treap *fa; /* point to its father */
29
     treap *ch[2]; /* 0 for left child, 1 for right child. */
30
31
32
     treap(void);
33
     inline void maintain(void); /* update s */
34
     inline void set_child(int d, treap *child);
35
     inline int which(void); /* determine which child this is of its father */
36
     inline int cmp(key_t ox); /* determine which child to insert ox */
37
     treap *rotate(void); /* rotate this to its father, return this */
38
   } treap_nodes[MAXN];
39
40
   treap *new_treap(key_t x, val_t v, treap *f) {
41
     treap *ret = treap_nodes + alloc_address();
42
      ret->x = x;
43
      ret -> v = v;
44
      ret->eq = ret->s = 1;
45
      ret->fa=f;
46
      ret->ch[0] = ret->ch[1] = NULL;
47
48
   void free_treap(treap *p) {
49
      free_address( p - treap_nodes );
50
51
   void treap_clear(void) {
52
     init_treap_mem();
53
54
55
   treap::treap(void) {
56
     r = rand();
57
     eq = s = 0;
58
     fa = ch[0] = ch[1] = NULL;
59
60
   inline void treap::maintain(void) {
61
      s = eq;
     for( int i = 0 ; i < 2 ; i++ )
62
63
       if( ch[i] )
64
          s += ch[i]->s;
```

```
65
 66
    inline void treap::set_child(int d, treap *child) {
 67
       ch[d] = child;
 68
       maintain();
 69
       if( child ) child->fa = this;
 70
 71
    inline int treap::which(void) {
 72
       if( NULL == fa ) return -1; /* this is not a child */
 73
       else return ( fa->ch[1] == this );
 74
 75
    inline int treap::cmp(key_t ox) {
 76
       if( ox == x ) return -1; /* equal */
 77
       else return ( ox > x ); /* left less, right more */
 78
 79
     treap *treap::rotate(void) {
 80
       if ( NULL == fa ) return this; /* no father, already global root. */
       int d = which();
 81
 82
       fa->set_child(d, ch[d^1]);
 83
       set_child(d^1, fa);
 84
       return this;
 85
 86
 87
     // --- deprecated |
 88
    typedef int T;
 89
 90
    struct node {
91
       T v; /* value of this node */
 92
       int r; /* random priority */
 93
       int eq; /* the number of equal things */
 94
       int s; /* the size of subtree rooted at this */
       node *ch[2]; /* 0 for left child, 1 for right child. */
 95
       node(void) {
 96
 97
         r = rand();
 98
         ch[0] = ch[1] = NULL;
 99
100
      /* return where to insert x */
101
       int cmp(T x) {
102
         if(v == x) return -1;
103
         else return (x < v) ? 0 : 1;
104
105
       /* return 1 if this node is prior to other */
106
       int pri(node *o) {
107
         return (r > (o->r));
108
109
       /* maintain the s field */
110
       void maintain(void) {
111
         s = eq;
112
         if(NULL != ch[0]) s += ch[0]->s;
113
         if(NULL != ch[1]) s += ch[1]->s;
      }
114
115
116
117
     /* move o to ch[d] of o->ch[d^1] */
118
    void rotate(node *&o, int d) {
119
       node *k = o \rightarrow ch[d^1];
120
       o\rightarrow ch[d^1] = k\rightarrow ch[d];
121
       o->maintain();
122
       k\rightarrow ch[d] = o;
123
       k->maintain();
124
       o = k;
125
```

#### 1.6 Leftist Heap

```
|/* HDU 1512 Monkey King (左偏树模板题) */
   #include<iostream>
3
   #include<cstdio>
4
   using namespace std;
5
   const int maxn = 100000+5;
6
7
   int n, m;
8
9
   struct Heap {
10
     int l,r,fa,val,dis;
11
   } t[maxn];
12
13
14
   int finds(int x) {
15
     return t[x].fa == -1? x:t[x].fa = finds(t[x].fa);
16
17
   int merge(int x, int y) {
18
     if(x == 0) return y;
                            //如果为0的话,就说明是空子树,根节点当然就是另一节点了
19
20
     if(y == 0) return x;
21
     if(t[y].val>t[x].val) swap(x,y); //始终往右子树进行插入
22
     t[x].r = merge(t[x].r,y);
23
     t[t[x].r].fa = x;
24
     if(t[t[x].l].dis < t[t[x].r].dis) swap(t[x].l,t[x].r); //是否需要左右子树的对换,
        这样是为了右子树尽量短
25
     if(t[x].r == 0) t[x].dis = 0;
                                   //距离的重新分配
26
     else t[x].dis = t[t[x].r].dis + 1;
27
     return x;
   }
28
29
30
   int pop(int &root) {
31
     int l = t[root].l;
32
     int r = t[root].r;
33
     t[root].l = t[root].r = t[root].dis = 0;
34
     t[root].fa = -1;
35
     t[1].fa = t[r].fa = -1; //删除root根节点
36
                             //这样一来相当于分裂成了两棵子树,重新进行合并,最后返回值
     return merge(l,r);
        为合并后的根节点
37
   }
38
39
   int push(int x, int y) {
40
     return merge(x,y);
41
   }
42
43
   int main() {
     //freopen("in.txt","r",stdin);
44
     while(~scanf("%d",&n)) {
45
       for(int i=1; i<=n; i++) {
46
47
         t[i].l=t[i].r=t[i].dis=0;
48
         t[i].fa=-1;
49
         scanf("%d",&t[i].val);
50
       }
       scanf("%d",&m);
51
52
       while(m--) {
53
         int a,b;
         scanf("%d%d",&a,&b);
54
55
         int x=finds(a);
56
         int y=finds(b);
57
         if(x!=y) {
58
           t[x].val/=2;
59
           int xx = push(pop(x),x);
```

```
60
            t[y].val/=2;
61
            int yy = push(pop(y),y);
            printf("%d\n",t[merge(xx,yy)].val);
62
63
          } else puts("-1");
64
65
66
      return 0;
67
   1.7 Splay
   /* splay, by Abreto<m@abreto.net>. */
 2
 3
   #ifndef NULL
 4
   #define NULL 0
 5
   #endif
 6
 7
   struct node {
 8
      node *f, *ch[2];
 9
      int sz;
      node(node *fa = NULL, node *lc = NULL, node *rc = NULL) {
10
        f = fa;
11
        ch[0] = lc;
12
        ch[1] = rc;
13
14
        maintain();
15
16
      inline int szof(const int d) const {
17
        return ch[d] ? ch[d]->sz : 0;
18
19
      inline void maintain(void) {
20
        sz = szof(0) + szof(1) + 1;
21
22
      inline int which(void) {
23
        if (NULL == f) return 0;
24
        return (f\rightarrow ch[1] == this); /* f[which()] == this */
25
26
      inline node *setf(node *fa, int d = 0) {
27
        f = fa;
        if (f) {
28
          f\rightarrow ch[d] = this;
29
30
          f->maintain();
        }
31
32
        return f;
33
34
      inline node *setc(node *son, int d = 0) {
35
        ch[d] = son;
36
        if (son) son—>f = this;
37
        maintain();
38
        return this;
39
40
      /* rotate this to its fater, return this. */
41
      inline node *rotate(void) {
        if (f != NULL) {
42
          node *ff = f \rightarrow f;
43
44
          int d = which(), fd = f->which();
          setc(f->setc(ch[d \land 1], d), d \land 1);
45
46
          setf(ff, fd);
        }
47
48
        return this;
49
50
      /* splay this to child of target */
51
      inline node *splay(node * const target = NULL) {
```

```
52
        while (f != target) {
53
          if (target != f \rightarrow f) {
54
            ((which() == f->which()) ? f : this )->rotate();
55
56
          rotate();
57
58
        return this;
59
60
      /* 0-based rank */
61
      inline node *get_k_th(unsigned k) {
62
        node *p = this;
63
        int rank;
        while (k != (rank = (p->szof(0))))  {
64
          if (k < rank) {
65
66
            p = p - sh[0];
          } else {
67
68
            k = (rank + 1);
69
            p = p - > ch[1];
70
71
72
        return p->splay(f);
73
   };
74
 1
   //* HDU 3487 - Play with Chain, by Abreto<m@abreto.net>. */
   #include <bits/stdc++.h>
 3
 4
   using namespace std;
 5
   #define MAXN
                     300300
 6
 7
 8
   int n, m;
9
10
   #define LC(p)
                     ch[p][0]
11
   #define RC(p)
                     ch[p][1]
   #define TARGET(p) LC(RC(p))
12
13
14
   int nodes;
15
    int val[MAXN], ch[MAXN][2], fa[MAXN], sz[MAXN];
16
   int rev[MAXN];
17
18
   inline int new_node(int v, int f) {
19
      int p = (++nodes);
20
      val[p] = v;
      fa[p] = f;
21
22
      ch[p][0] = ch[p][1] = rev[p] = 0;
23
      sz[p] = 1;
24
      return p;
25
   inline void maintain(int p) {
26
27
      if (p) {
28
        sz[p] = sz[LC(p)] + sz[RC(p)] + 1;
29
30
31
   inline void make_child(int f, int d, int p) { /* make p the d-th ch of f */
32
      ch[f][d] = p;
33
      if(p) fa[p] = f;
34
35
   inline void myrev(int p) {
36
      if (p) {
        rev[p] ^= 1;
37
38
        swap(LC(p), RC(p));
39
40 }
```

```
inline void pushdown(int p) {
 41
 42
       if(p && rev[p]) {
 43
         if(LC(p)) myrev(LC(p));
 44
         if(RC(p)) myrev(RC(p));
 45
         rev[p] = 0;
 46
 47
 48
     int build(int f = 0, int l = 0, int r = n+1) {
 49
       if(r < l) return 0;
 50
       if(l == r) return new_node(l, f);
 51
       int mid = 1+r>>1;
 52
       int p = new_node(mid, f);
 53
       LC(p) = build(p, l, mid-1);
 54
       RC(p) = build(p, mid+1, r);
 55
       maintain(p);
 56
       return p;
 57
    inline int which(int p) { /* return 1 if p is a right child or 0 if p is a left
 58
        child. */
 59
       return (RC(fa[p]) == p);
 60
    inline int rotate(int p) { /* rotate p to its father. [!] make sure p is not global
 61
 62
       int f = fa[p], ff = fa[f];
 63
       if(0 == f) return p; /* p is global root */
 64
       pushdown(f);
 65
       pushdown(p);
 66
       int d = which(p), df = which(f);
 67
       make\_child(f, d, ch[p][d^1]);
       make\_child(p, d^1, f);
 68
 69
       maintain(f);
 70
       maintain(p);
 71
       fa[p] = ff;
       if(ff) ch[ff][df] = p;
 72
 73
       return p;
 74
 75
     inline int splay(int p, int fr) \{ /* \text{ splay p to the son of fr, return p. } */
 76
       pushdown(p);
 77
       while(fa[p] != fr) {
 78
         int f = fa[p], dp = which(p);
 79
         if(fa[f] == fr) {
 80
           return rotate(p);
 81
         } else {
 82
           int df = which(f);
 83
           if(dp == df) {
 84
             rotate(f);
 85
           } else {
 86
             rotate(p);
 87
 88
           rotate(p);
 89
         }
 90
 91
       return p;
 92
 93
     inline int get_k_th(int root, int k) {
 94
       int p = root;
 95
       int rank;
 96
       while(k != (rank = (sz[LC(p)] + 1))) {
 97
         pushdown(p);
 98
         if(k < rank) p = LC(p);
 99
         else {
100
           k = rank;
101
           p = RC(p);
         }
102
```

```
103
      return splay(p, fa[root]);
104
105
106
    inline int merge(int left, int right) {
107
      pushdown(left);
108
      if(RC(left)) left = get_k_th(left, sz[left]);
109
      RC(left) = right;
110
      maintain(left);
111
      fa[right] = left;
112
       return left;
113
    inline int split(int root, int d) { /* split ch[root][d], return the root of splited
114
        out. */
115
      pushdown(root);
116
      int child = ch[root][d];
117
       ch[root][d] = 0;
118
      maintain(root);
119
      fa[child] = 0;
120
       return child;
121
122
    inline int concat(int root, int d, int p) { /* make p be ch[root][d], return root */
123
      pushdown(root);
124
      ch[root][d] = p;
125
      fa[p] = root;
126
      maintain(root);
127
      return root;
128
129
130
    void myclear(void) {
131
      nodes = 0;
132
133
134
     int ans[MAXN];
135
    void inorder(int p, int &pos) {
136
      if(0 == p) return;
137
      pushdown(p);
138
      inorder(LC(p), pos);
139
      if( (0 < val[p]) \&\& (val[p] < n+1) ) ans[pos++] = val[p];
140
       inorder(RC(p), pos);
141
142
143
    void handle() {
144
      int i;
145
      int root;
146
      myclear();
147
       root = build(0);
148
      while(m--) {
149
         char command[8];
150
         int a, b, c;
151
         int tar;
         scanf("%s%d%d", command, &a, &b);
152
         if('C' == command[0]) {
153
           scanf("%d", &c);
154
155
           root = get_k_th(root, a);
           RC(root) = get_k_t(RC(root), b-a+2);
156
157
           tar = split(RC(root), 0);
158
           maintain(root);
159
           root = get_k_th(root, c+1);
160
           RC(root) = get_k_t(RC(root), 1);
161
           RC(root) = concat(RC(root), 0, tar);
162
           maintain(root);
163
         } else {
164
           root = get_k_th(root, a);
165
           RC(root) = get_k_t(RC(root), b-a+2);
```

```
166
           myrev(TARGET(root));
         }
167
168
169
       int pos = 0;
170
       inorder(root, pos);
       for(i = 0; i < n; i++) printf("%s%d", i ? "_{\bot}":"", ans[i]);
171
172
       puts("");
173
174
175
     int main(void) {
       while( scanf("\%d\%d\%d", &n, &m) && (n > 0) && (m > 0) )
176
177
         handle();
178
       return 0;
179 |}
```

#### 1.8 Persistent Segment Tree

- I. 首先, 给你一颗值为横坐标的线段树, 每个节点上存着该值出现了多少次, 这样的一颗线段树 你会求区间 k 大值吧. 二分即可.
- 2. 然后, 假设区间是数组 arr[n], 区间长度是 n, 那么给你 n 颗线段树, 第 i 颗线段树是第 i-1 颗线段树插入 arr[i] 得到.
- 3. 如果你有了这 n 颗线段树, 想求区间 [l,r] 中的第 k 大值, 那么你需要在第 r 颗和第 l-1 颗线段 树的差线段树上作二分, 就可以求得区间第 k 大值.
- 4. 差线段树很好理解, 比如你有一个部分和数组 sum, sum[r] sum[l-1] 就是部分和的差, 代表区间 [l,r] 的和, 差线段树同理.
- 5. 现在,可持久化线段树出现为你解决最后一个问题,空间问题. 内存很小,不能够存下 n 颗线段树. 但是,第 2 条中提到,由于第 i 颗线段是是第 i-1 颗线段是插入仅一个值得到的,两颗线段树的区别不大,仅有  $\log(n)$  个节点发生了改变,我们仅仅需要记录这  $\log(n)$  的数据就可以记录这个增量,这就是可持久化线段树.

### 2 Dynamic Programming

#### **2.1** LIS $O(n \log n)$

```
1
2
   int top = 0;
3
   for( int i=1; i<=n; i++ ) {
4
     if( ap[i] > dp[top] ) { // 如果大于 "模拟栈" 的栈顶元素直接 入栈 长度加 1
5
       dp[top] = ap[i];
6
7
       continue;
8
     int m = ap[i];
9
     // lower_bound 前闭后开 返回不小于 m 的最小值的位置
10
     pos = lower_bound(dp,dp+top,m)-dp; // 注意减去dp
11
12
     if(dp[pos] > ap[i])
13
       dp[pos] = ap[i];
14
```

#### **2.2** LCS $O(n \log n)$

总的来说,就是把 LCS 转化成 LIS,然后用 LIS 的  $O(N \log N)$  算法来求解。

实现如下: (引用)

假设有两个序列  $s_1[1...6] = abcadc, s_2[1...7] = cabedab.$ 

记录  $s_1$  中每个元素在  $s_2$  中出现的位置, 再将位置按降序排列, 则上面的例子可表示为:  $loc(a) = \{6,2\}, loc(b) = \{7,3\}, loc(c) = \{1\}, loc(d) = \{5\}.$  (倒着扫一遍  $s_2$  即可把位置扔进 vector). 将  $s_1$  中每个元素的位置按  $s_1$  中元素的顺序排列成一个序列  $s_3 = \{6,2,7,3,1,6,2,5,1\}$ . 在对  $s_3$  求 LIS 得到的值即为求 LCS 的答案。

#### 2.3 Improved by quadrilateral inequality

```
1
   /*
 2
    * 四边形不等式
 3
 4
    * 如果 dp(i,j) 满足 dp(i,j)<=dp(i,j+1)<=dp(i+1,j+1)
 5
    * 那么决策 s(i,j) 满足 s(i,j)<=s(i,j+1)<=s(i+1,j+1)
 6
    * 可以变形为:
 7
            s(i-1,j) <= s(i,j) <= s(i,j+1) // dp方向: i增j减
    *
 8
       或
    *
 9
            s(i,j-1) \ll s(i,j) \ll s(i+1,j) // dp方向: 区间长度L增
    *
10
    */
11
   #include <bits/stdc++.h>
12
13
   using namespace std;
14
15
   #define MAXN
16
   #define inf
                    (0x3fffffff)
17
18
   int n, m;
19
   int v[MAXN];
20
   int s[MAXN];
   int w[MAXN][MAXN];
21
22
   int dp[MAXN][MAXN];
23
   int c[MAXN][MAXN];
24
25
   int wa(void) {
26
     int i, j, k;
27
     for(i = 1; i \le n; ++i) {
        scanf("%d", v+i);
28
        s[i] = v[i] + s[i-1];
29
30
31
     for(i = 1; i <= n; ++i) {
32
       w[i][i] = 0;
33
       for(j = i+1; j \le n; ++j)
         w[i][j] = w[i][j-1] + v[j] * (s[j-1] - s[i-1]);
34
35
36
     /* doing dp */
37
     for(i = 1; i \le n; ++i) {
38
       dp[i][0] = w[1][i];
39
       c[i][0] = 1;
40
        c[i][i] = i-1;
41
        for(j = i-1; j > 0; j---) {
42
          dp[i][j] = inf;
43
         for(k = c[i-1][j]; k \le c[i][j+1]; ++k)
44
            if(dp[k][j-1]+w[k+1][i] \le dp[i][j]) {
45
              dp[i][j] = dp[k][j-1] + w[k+1][i];
46
              c[i][j] = k;
            }
47
48
       }
49
50
     /* dp done */
51
     return dp[n][m];
52
53
54
   int main(void) {
55
     while(EOF != scanf("%d%d", &n, &m) && n && m) {
```

#### 2.4 Improved by Slope

```
/* type 1: */
 2
   /* bzoj 1010 */
 3
   #include <bits/stdc++.h>
   using namespace std;
   typedef long double 11;
 6
 7
   #define MAXN
                     50050
 8
   #define eps
                     (1e-8)
 9
10
   int N;
   11 L;
11
12
   11 S[MAXN];
13
   11 f[MAXN];
   11 dp[MAXN];
14
15
   inline ll k(int j) {
16
      return (-2.0) * (f[j] + L);
17
18
19
   inline ll b(int j) {
20
      return dp[j] + f[j]*f[j] + 2ll*f[j]*L;
21
22
   inline ll g(int j, int i) {
23
      return k(j) * f[i] + b(j);
24
25
26
   /* check if l1 & l3 <= l2 */
   inline int check(int l1, int l2, int l3) {
27
28
      /*ll\ left = b(13)*k(11)+b(11)*k(12)+b(12)*k(13);
29
      ll right = b(l1)*k(l3)+b(l3)*k(l2)+b(l2)*k(l1);*/
30
      ll\ left = b(l3)*k(l1)-b(l1)*k(l3)
31
      ll right = k(l2)*(b(l3)-b(l1))+b(l2)*(k(l1)-k(l3));
32
      return (left <= right);
33
34
35
   int Q[MAXN], ql, qr;
36
37
    int main(void) {
38
      int i;
      scanf("%d%Lf", &N, &L);
39
40
      L += 1.0;
      for(i = 1; i \le N; ++i) {
41
        scanf("%Lf", S+i);
42
43
        S[i] += S[i-1];
44
        f[i] = S[i] + (double)i;
45
46
      Q[qr++] = 0;
      for(i = 1; i <= N; ++i) {
/* <!-- STARED */
47
48
49
        for(; ql+1 < qr && g(Q[ql],i) >= g(Q[ql+1],i); ql++);
        dp[i] = g(Q[ql], i) + f[i]*f[i] + L*L; //printf("%d: %lld,%lld\n", i, dp[i], dp[i]
50
           ]-f[i]*f[i]);
51
        for(; ql+1 < qr \&\& check(Q[qr-2], Q[qr-1], i); qr--);
52
        Q[qr++] = i;
53
        /* --> */
      }
54
```

```
55 | printf("%lld\n", (long long int)round(dp[N]));
56 | return 0;
57 |}
```

#### 2.5 Steiner Tree

令 f[i][sta] 表示 i 号节点,与其他节点的连通性为 sta 时的最小代价,这里 sta 是一个二进制数,在它二进制下的每一位中,0 表示不连通,1 表示联通 状态转移:

• 由子集转移而来

$$f[i][sta] = \min_{s \subseteq sta} \{f[i][s] + f[i][sta \setminus s] - val[i]\}$$

• 由不含该节点的状态转移而来

```
f[i][j] = \min\{f[k][j] + val[i]\}
```

```
流程:
   枚举状态集S
 2
   {
 3
         枚举S的子集s
 4
 5
             更新f[S][1~n]
 6
 7
         将 f[S][x]<inf 的x入队
 8
         spfa(S)
 9
   代码:
   |int f[1<<M][N];
   queue<int> q;
 3
   bool in[N];
 4
 5
   void spfa(int S) {
 6
     while (!q.empty()) {
 7
       int now=q.front();
 8
       q.pop();
 9
       in[now]=0;
10
        for (int i=st[now]; i; i=way[i].nxt) {
11
          int y=way[i].y;
          if (f[S][y]>f[S][now]+val[y]) {
12
13
            f[S][y]=f[S][now]+val[y];
14
            if (!in[y]) q.push(y),in[y]=1;
15
16
       }
17
     }
18
19
20
   void work() {
21
      int cnt=0;
22
     memset(f,0x7f,sizeof(f));
23
24
     for (int i=1; i<=n; i++)
25
       if (!val[i]) f[1<<cnt][i]=0,cnt++;
     for (int S=1; S<(1<<cnt); S++) {
26
27
       for (s=(S-1)\&S; s; s=(s-1)\&S)
          for (int i=1; i<=n; i++)
28
29
            f[S][i]=min(f[S][i],f[s][i]+f[S^s][i]-val[i]);
30
       for (int i=1; i<=n; i++)
31
          if (f[S][i]<INF&&!in[i])
```

```
32
           q.push(i),in[i]=1;
33
       spfa(S);
34
35
36
     int ans=INF;
37
     for (int i=1; i<=n; i++) ans=min(ans,f[(1<<cnt)-1][i]);
38
     printf("%d\n",ans);
39
40
   //
41
   // 作者: Coco_T_
42
   // 来源: CSDN
43
   |// 原文: https://blog.csdn.net/wu_tongtong/article/details/78992913
44 // 版权声明:本文为博主原创文章,转载请附上博文链接!
       Geometry
   3
   3.1 2D
   3.1.1 Point
   /* 2D Point Class, by Abreto<m@abreto.net> */
 2
   #include <cmath>
 3
 4
   /**
 5
    * Define ABG2d_USE_LL if you want to use long long int for cordnates.
 6
    */
 7
 8
   namespace ab_geometry_2d {
 9
10
   using namespace std;
11
12
   typedef double ab_float;
13
14
   const ab_float pi = acos(-1.);
15
   #ifdef ABG2d_USE_LL
16
   typedef long long int T;
17
18
   #else
19
   typedef ab_float T;
20
   const ab_float eps = 1e-8;
21
   #endif
22
23
   inline T myabs(T x) {
24
     if(x < 0) return (-x);
25
     return x;
26
   }
27
28
   inline int sgn(T x) {
     /* no difference'' in fact */
29
30
   #ifdef ABG2d_USE_LL
31
     if (0 == x) return 0;
32
   #else
33
     if (myabs(x) < eps) return 0;
34
   #endif
35
     return (x > 0) ? 1 : -1;
36
37
38
   inline T sqr(T x) {
39
     return (x * x);
40
41
42 | struct point {
```

```
43
     Tx,y;
44
     point(void):x(T()),y(T()) {}
45
     point(T xx, T yy):x(xx),y(yy) {}
46
      inline T norm2(void) {
47
        return sqr(x) + sqr(y);
48
49
     inline ab_float norm(void) {
50
        return sqrt((ab_float)(norm2()));
51
52
     inline point rotate(const ab_float &cost, const ab_float &sint) {} // TODO:
53
     inline point operator—(void) const {
54
        return point(-x,-y);
55
     inline point operator+(const point& b) const {
56
57
        return point(x+b.x,y+b.y);
58
59
     inline point operator-(const point& b) const {
        return point(x-b.x,y-b.y);
60
61
62
     inline point operator->*(const point &b) const {
63
        return (b-(*this));
64
     inline T operator*(const point& b) const {
65
66
        return ((x)*(b.x))+((y)*(b.y)); /* inner product */
67
     inline T operator^(const point& b) const {
68
69
        return ((x)*(b.y))-((b.x)*(y)); /* outter product */
70
71
     inline point& operator+=(const point& b) {
72
        point tmp=(*this)+b;
73
        (*this)=tmp;
74
        return (*this);
75
     inline point& operator—=(const point& b) {
76
77
       point tmp=(*this)_b;
78
        (*this)=tmp;
79
        return (*this);
80
81
     inline bool operator==(const point& b) const {
82
        return (0==sgn(x-b.x))&(0==sgn(y-b.y));
83
84
     inline bool operator!=(const point& b) const {
85
        return !((*this)==b);
86
87
     inline point operator<<(const ab_float& theta) const {
88
       ab_float ct = cos(theta), st = sin(theta); /* rotate counter-clockwise in radian
89
        return point(ct*x - st*y, st*x + ct*y);
90
     }
91
   };
92
93
   typedef point vec;
94
95
96 | }
       // namespace ab_geometry_2d
   3.1.2 Circle
   Base
   /* 2D Circle Base Class, by Abreto<m@abreto.net>. */
 3
   /* requirement: point.cc */
```

```
|#include "point.cc"
 5
 6
   #include <utility>
 7
 8
   namespace ab_geometry_2d {
 9
10
   using namespace std;
11
12
    struct circle {
13
      point o;
14
      Tr;
15
      circle(void) : r(T()) {}
      circle(point center, T radius) : o(center), r(radius) {}
16
17
      inline ab_float arclen(ab_float theta) {
18
19
        return theta * r;
20
21
      inline ab_float circumference(void) {
22
        return 2. * pi * r;
23
24
      inline ab_float area(void) {
25
        return pi * r * r;
26
27
28
      /* bool contain(const circle &C, const bool including_touch = false) const
29
30
          T dis2 = (o \rightarrow *(C.o)).norm2();
31
          T raw_diff = r - C.r;
32
          if (-1 == sgn(raw\_diff)) return false;
33
          T dr2 = sqr(raw_diff);
          return (dis2 < dr2) || (including_touch && (dis2 == dr2));
34
35
      inline bool in(const circle &C, const bool including_touch = false) const
36
37
38
        return C.contain(*this, including_touch);
39
      } */
40
      enum relation_t {
41
        same = 0 \times 000000,
42
        contain = 0 \times 00001,
43
        intouch = 0 \times 00010,
44
        intersect = 0x00100,
45
        outtouch = 0x01000,
46
        separate = 0x10000.
47
        unknow_relation = 0xfffff
48
      relation_t with(const circle &C) const {
49
50
        T dis2 = (o \rightarrow *(C.o)).norm2();
51
        T dr2 = sqr(r - C.r), rs2 = sqr(r + C.r);
52
        if (0 == sgn(dis2) \&\& 0 == sgn(dr2)) return same;
        if (-1 == sqn(dis2 - dr2)) return contain;
53
        if (0 == sgn(dis2 - dr2)) return intouch;
54
        if (-1 == sgn(dr2 - dis2) \&\& -1 == sgn(dis2 - rs2)) return intersect;
55
        if (0 == sgn(dis2 - rs2)) return outtouch;
56
57
        if (-1 == sgn(rs2 - dis2)) return separate;
58
        return unknow_relation;
59
      }
60
61
      enum point_relation_t {
62
        in = 0x001,
63
        on = 0 \times 010,
64
        out = 0x100,
65
        unknow_point_relation = 0xfff
66
      point_relation_t with(const point &P) const {
67
```

```
68
        T dis2 = (o\rightarrow *P).norm2();
69
        T r2 = sqr(r);
70
        int type = sgn(dis2 - r2);
71
        if (-1 == type) return in;
72
        if ( 0 == type) return on;
73
        if (+1 == type) return out;
74
        return unknow_point_relation;
75
76
77
     ab_float central_angle(const point &A, const point &B, const bool reflex = false)
         const {
78
        T dot = (A * B);
79
        if (0 == sgn(dot)) return 1. * (A != B) * pi;
80
        ab_float angle = ((ab_float)(dot)) / r / r;
81
        if (reflex) angle = 2. * pi - angle;
82
        return angle;
83
     }
84
85
     /* be sure (*this) intersect with C */
86
     pair<point, point> crosspoint(const circle &C) const {
87
        ab_float d = (o \rightarrow * (C.o)).norm();
        // TODO:
88
89
90
   };
91
92 |}
   k 次圆交
 1 | // china no.1
 2
   #pragma comment(linker, "/STACK:1024000000,1024000000")
 3
   #include <vector>
   |#include <iostream>
   #include <string>
 5
   |#include <map>
 7
   |#include <stack>
 8
   #include <cstring>
   #include <queue>
 9
   |#include <list>
10
11
   #include <stdio.h>
12 |#include <set>
13 |#include <algorithm>
14 |#include <cstdlib>
15 |#include <cmath>
16 | #include <iomanip>
17
   #include <cctype>
18
   |#include <sstream>
19
   #include <functional>
20
   #include <stdlib.h>
21
   #include <time.h>
22
   #include <bitset>
23
   using namespace std;
24
25
   #define pi acos(-1)
   #define PI acos(-1)
26
   #define endl '\n'
27
28
   #define srand() srand(time(0));
29
   #define me(x,y) memset(x,y,sizeof(x));
   #define foreach(it,a) for(__typeof((a).begin()) it=(a).begin();it!=(a).end();it++)
31
   #define close() ios::sync_with_stdio(0); cin.tie(0);
   #define FOR(x,n,i) for(int i=x;i<=n;i++)</pre>
32
   #define F0r(x,n,i) for(int i=x;i<n;i++)</pre>
33
34
   #define W while
35
   #define sgn(x) ((x) < 0 ? -1 : (x) > 0)
36 |#define bug printf("********\n");
```

```
37
    |#define db double
38
    typedef long long LL;
39
    const int INF=0x3f3f3f3f3f;
    const LL LINF=0x3f3f3f3f3f3f3f3f3f1LL;
    const int dx[] = \{-1,0,1,0,1,-1,-1,1\};
41
42
    const int dy [] = \{0,1,0,-1,-1,1,-1,1\};
43
    const int maxn=1e3+10;
44
    const int maxx=1e6+100;
    const double EPS=1e-8;
45
46
    const double eps=1e-8;
47
    const int mod=10000007;
48
    template<class T>inline T min(T a,T b,T c) {
49
       return min(min(a,b),c);
50
51
    template<class T>inline T max(T a,T b,T c) {
52
      return max(max(a,b),c);
53
54
    template<class T>inline T min(T a,T b,T c,T d) {
55
       return min(min(a,b),min(c,d));
56
57
    template<class T>inline T max(T a,T b,T c,T d) {
58
      return max(max(a,b),max(c,d));
59
60
    template <class T>
61
    inline bool scan_d(T &ret) {
62
      char c;
63
       int sgn;
64
      if (c = getchar(), c == EOF) {
65
         return 0;
66
      while (c != '-' \&\& (c < '0' || c > '9')) 
 67
68
         c = getchar();
69
70
      sgn = (c == '-') ? -1 : 1;
      ret = (c == '-') ? 0 : (c - '0');
71
72
      while (c = getchar(), c >= '0' && c <= '9') {
73
         ret = ret * 10 + (c - '0');
74
 75
      ret *= san;
 76
       return 1;
77
78
 79
    inline bool scan_lf(double &num) {
       char in;
80
      double Dec=0.1;
81
82
      bool IsN=false, IsD=false;
83
       in=getchar();
84
      if(in==EOF) return false;
85
      while(in!='-'&&in!='.'&&(in<'0'||in>'9'))in=getchar();
      if(in=='-') {
86
87
         IsN=true;
88
         num=0;
       } else if(in=='.') {
89
         IsD=true;
90
91
         num=0;
       } else num=in-'0';
92
93
      if(!IsD) {
94
         while(in=getchar(),in>='0'&&in<='9') {
95
           num*=10;
96
           num+=in-'0';
97
         }
98
99
      if(in!='.') {
100
         if(IsN) num=-num;
```

```
101
         return true;
102
       } else {
103
         while(in=getchar(),in>='0'&&in<='9') {</pre>
104
            num+=Dec*(in-'0');
105
            Dec*=0.1;
106
         }
107
       if(IsN) num=-num;
108
109
       return true;
110
111
     void Out(LL a) {
112
113
       if(a < 0) {
         putchar('-');
114
115
         a = -a;
116
117
       if(a >= 10) Out(a / 10);
118
       putchar(a % 10 + '0');
119
120
     void print(LL a) {
       Out(a),puts("");
121
122
     //freopen( "in.txt" , "r" , stdin );
//freopen( "data.txt" , "w" , stdout );
//cerr << "run time is " << clock() << endl;</pre>
123
124
125
126
     /*struct Point
127
     {
128
         double x, y;
129
         Point(const Point& rhs): x(rhs.x), y(rhs.y) { } //拷贝构造函数
130
         Point(double x = 0, double y = 0) : x(x), y(y) { }
131
         inline void input()
132
133
              scanf("%lf%lf",&x,&y);
134
135
         inline void print()
136
137
              printf("%.6lf %.6lf\n",x,y);
138
139
     };*/
140
     db sqr(db x) {
141
       return x*x;
142
143
     int dcmp(double x) {
       if(fabs(x) < EPS) return 0;
144
145
       else return x < 0 ? -1 : 1;
146
     struct Circle {
147
148
       double x, y, r, angle;
149
       int d;
150
       Circle() {}
151
       Circle(double xx, double yy, double ang = 0, int t = 0) {
152
         X = XX;
153
         y = yy;
154
         angle = ang;
155
         d = t;
156
       }
157
       void get() {
         scanf("%lf%lf%lf", &x, &y, &r);
158
159
         d = 1;
160
       }
161
162
     Circle cir[maxn],tp[maxn*2];
163
     double area[maxn];
164
     double dis(Circle a,Circle b) {
```

```
165
      return sqrt(sqr(a.x - b.x) + sqr(a.y - b.y));
166
167
    double cross(Circle p0,Circle p1,Circle p2) {
168
       return (p1.x - p0.x) * (p2.y - p0.y) - (p1.y - p0.y) * (p2.x - p0.x);
169
170
    //圆相交
    int CirCrossCir(Circle p1, double r1, Circle p2, double r2, Circle &cp1, Circle &cp2) {
171
172
      double mx = p2.x - p1.x, sx = p2.x + p1.x, mx2 = mx * mx;
173
      double my = p2.y - p1.y, sy = p2.y + p1.y, my2 = my * my;
      double sq = mx2 + my2, d = -(sq - sqr(r1 - r2)) * (sq - sqr(r1 + r2));
174
175
      if (d + eps < 0) return 0;
176
      if (d < eps) d = 0;
177
      else d = sqrt(d);
178
      double x = mx * ((r1 + r2) * (r1 - r2) + mx * sx) + sx * my2;
179
      double y = my * ((r1 + r2) * (r1 - r2) + my * sy) + sy * mx2;
180
      double dx = mx * d, dy = my * d;
181
      sq *= 2;
      cp1.x = (x - dy) / sq;
182
183
       cp1.y = (y + dx) / sq;
       cp2.x = (x + dy) / sq;
184
      cp2.y = (y - dx) / sq;
185
186
      if (d > eps) return 2;
187
      else return 1;
188
189
    bool circmp(const Circle& u, const Circle& v) {
190
      return dcmp(u.r - v.r) < 0;
191
192
    bool cmp(const Circle& u, const Circle& v) {
193
       if (dcmp(u.angle - v.angle)) return u.angle < v.angle;
194
       return u.d > v.d;
195
196
    //0.5*r*r*(K-sin(K))
197
    double calc(Circle cir,Circle cp1,Circle cp2) {
198
       double ans = (cp2.angle - cp1.angle) * sqr(cir.r)
199
                     - cross(cir, cp1, cp2) + cross(Circle(0, 0), cp1, cp2);
200
       return ans / 2;
201
202
203
    void CirUnion(Circle cir□, int n) {
204
      Circle cp1, cp2;
205
       sort(cir, cir + n, circmp);
206
       for (int i = 0; i < n; ++i)
         for (int j = i + 1; j < n; ++j)
207
208
           if (dcmp(dis(cir[i], cir[j]) + cir[i].r - cir[j].r) <= 0)</pre>
209
             cir[i].d++;
210
      for (int i = 0; i < n; ++i) {
211
        int tn = 0, cnt = 0;
212
         for (int j = 0; j < n; ++j) {
213
           if (i == j) continue;
           if (CirCrossCir(cir[i], cir[i].r, cir[j], cir[j].r,
214
215
                           cp2, cp1) < 2) continue;
216
           cp1.angle = atan2(cp1.y - cir[i].y, cp1.x - cir[i].x);
217
           cp2.angle = atan2(cp2.y - cir[i].y, cp2.x - cir[i].x);
           cp1.d = 1;
218
219
           tp[tn++] = cp1;
220
           cp2.d = -1;
221
           tp[tn++] = cp2;
222
           if (dcmp(cp1.angle - cp2.angle) > 0) cnt++;
223
224
        tp[tn++] = Circle(cir[i].x - cir[i].r, cir[i].y, pi, -cnt);
225
        tp[tn++] = Circle(cir[i].x - cir[i].r, cir[i].y, -pi, cnt);
226
         sort(tp, tp + tn, cmp);
227
        int p, s = cir[i].d + tp[0].d;
228
         for (int j = 1; j < tn; ++j) {
```

```
229
           p = s;
230
           s += tp[j].d;
231
           area[p] += calc(cir[i], tp[j - 1], tp[j]);
232
233
       }
234
235
     int n;
     void solve() {
236
237
       for(int i=0; i<n; i++)
238
         cir[i].get();
239
       me(area, 0);
240
       CirUnion(cir,n);
241
       for(int i=1; i<=n; i++) {
242
         area[i]-=area[i+1];
         printf("[%d]_{\square}=_{\square}%.3f\n", i, area[i]);
243
244
       }
245
246
    int main() {
       while(scanf("%d",&n)!=EOF)
247
248
         solve();
249 |}
    universe
  1
  2
    Point CircumCenter(Point a, Point b, Point c) { //三角形的外心
  3
       Point cp;
  4
       double a1 = b.x-a.x, b1 = b.y-a.y, c1 = (a1*a1 + b1*b1)/2;
  5
       double a2 = c.x-a.x,b2 = c.y-a.y,c2 = (a2*a2 + b2*b2)/2;
  6
       double d = a1*b2 - a2*b1;
  7
       cp.x = a.x + (c1*b2-c2*b1)/d;
  8
       cp.y = a.y + (a1*c2-a2*c1)/d;
  9
       return cp;
 10 | }
    3.1.3 Convex hull
    /* 2D Convex Hull, by Abreto <m@abreto.net>. */
  2
    #include "2d_base.hh"
  3
    #include <cmath>
    #include <algorithm>
  6
    using namespace std;
  7
  8
    point 0;
  9
 10
    bool comp_angle(point_t a, point_t b) {
       double t = (a-0).X(b-0);
 11
 12
       if(fe(t,0.0)) return fl((b-0).mag2(),(a-0).mag2());
 13
       else return fl(0.0,t);
 14
 15
     void convex_hull_graham(vp& convex, vp src) {
 16
       int i = 0, top = 0;
 17
 18
       0 = src[0];
 19
       for(auto pt : src)
 20
         if( pt.x < 0.x || (pt.x == 0.x && pt.y < 0.y))
 21
           0 = pt;
 22
       sort(src.begin(), src.end(), comp_angle);
       convex.push_back(src[0]);
 23
 24
       convex.push_back(src[1]);
       top = 1;
 25
 26
       for(i = 2; i < src.size(); ++i) {
```

```
while(top>1 && fle((convex[top]-convex[top-1]).X(src[i]-convex[top]),0.0)) {
27
28
          convex.pop_back();
29
          --top;
30
        }
31
        convex.push_back(src[i]);
32
        ++top;
33
34
    3.1.4 Intersect Area
   |#include <cstdio>
 2
   #include <cmath>
   #include <algorithm>
 3
 4
 5
   using namespace std;
 6
 7
   //#define inf 1000000000000
 8
   #define M 8
 9
   #define LL long long
10
   #define eps 1e-12
11
   #define PI acos(-1.0)
12
   using namespace std;
13
   struct node {
14
     double x,y;
15
     node() {}
16
     node(double xx,double yy) {
17
        X=XX;
18
        y=yy;
19
20
     node operator -(node s) {
21
        return node(x-s.x,y-s.y);
22
23
     node operator +(node s) {
24
        return node(x+s.x,y+s.y);
25
26
     double operator *(node s) {
27
        return x*s.x+y*s.y;
28
29
     double operator ^(node s) {
30
        return x*s.y-y*s.x;
31
32
33
   double max(double a,double b) {
34
     return a>b?a:b;
35
36
   double min(double a,double b) {
37
      return a<b?a:b;
38
39
   double len(node a) {
40
      return sqrt(a*a);
41
42
    double dis(node a, node b) { //两点之间的距离
43
      return len(b-a);
44
45
   double cross(node a, node b, node c) { //叉乘
46
     return (b-a)^(c-a);
47
48
   double dot(node a, node b, node c) { //点成
49
     return (b-a)*(c-a);
50
51
   int judge(node a,node b,node c) { //判断c是否在ab线段上(前提是c在直线ab上)
     if(c.x = min(a.x,b.x)
```

```
53
          \&c.x \le max(a.x,b.x)
 54
          \&c.y = min(a.y,b.y)
 55
          \&c.y \le max(a.y,b.y)
 56
        return 1;
 57
      return 0;
 58
 59
    double area(node b,node c,double r) {
 60
      node a(0.0,0.0);
 61
      if(dis(b,c)<eps)
 62
        return 0.0;
 63
      double h=fabs(cross(a,b,c))/dis(b,c);
      if(dis(a,b)>r-eps\&dis(a,c)>r-eps) { //两个端点都在圆的外面则分为两种情况
 64
 65
        double angle=acos(dot(a,b,c)/dis(a,b)/dis(a,c));
 66
        if(h>r-eps) {
          return 0.5*r*r*angle;
 67
 68
        } else if(dot(b,a,c)>0\&dot(c,a,b)>0) {
 69
          double angle1=2*acos(h/r);
 70
          return 0.5*r*r*fabs(angle-angle1)+0.5*r*r*sin(angle1);
 71
        } else {
 72
          return 0.5*r*r*angle;
 73
 74
      } else if(dis(a,b)<r+eps&dis(a,c)<r+eps) { //两个端点都在圆内的情况
 75
        return 0.5*fabs(cross(a,b,c));
 76
      } else { //一个端点在圆上一个端点在圆内的情况
 77
        if(dis(a,b)>dis(a,c)) { //默认b在圆内
 78
          swap(b,c);
 79
 80
        if(fabs(dis(a,b))<eps) { //ab距离为0直接返回0
 81
          return 0.0;
 82
        if(dot(b,a,c)<eps) {
 83
 84
          double angle1=acos(h/dis(a,b));
 85
          double angle2=acos(h/r)-angle1;
 86
          double angle3=acos(h/dis(a,c))-acos(h/r);
 87
          return 0.5*dis(a,b)*r*sin(angle2)+0.5*r*r*angle3;
 88
 89
        } else {
 90
          double angle1=acos(h/dis(a,b));
 91
          double angle2=acos(h/r);
 92
          double angle3=acos(h/dis(a,c))-angle2;
 93
          return 0.5*r*dis(a,b)*sin(angle1+angle2)+0.5*r*r*angle3;
 94
        }
 95
      }
 96
 97
 98
    node A, B, C;
 99
    int R;
100
101
    bool compar(node &p1, node &p2) {
102
      return (p1^p2)>eps;
103
104
105
    double f(double x, double y) {
      node 0(x,y);
106
107
      node p[8];
108
      p[0] = A-0;
109
      p[1] = B-0;
110
      p[2] = C-0;
111
      sort(p, p+3, compar);
112
      p[3] = p[0];
113
      0 = node(0,0);
114
      double sum=0;
115
      /* <!-- 求面积交部分 */
      for(int i=0; i<3; i++) { /* 按顺或逆时针顺序最后取绝对值就好 */
116
```

```
117
         int j=i+1;
118
         double s=area(p[i],p[j],(double)R);
         if(cross(0,p[i],p[j])>0)
119
120
           sum+=s;
121
         else
122
           sum-=s;
123
124
       if(sum < -eps) sum = -sum;
125
       /* --> */
126
       return sum;
127
128
129
    double trifind(double x, double y1, double y2) {
130
       double l = y1, r = y2;
131
       while(r-l>eps) {
132
         double mid = (1+r)/2.0;
         double mmid = (mid+r)/2.0;
133
134
         if( f(x,mmid) > f(x,mid) + eps )
135
           l = mid;
136
         else
137
           r = mmid;
138
139
       return f(x,l);
140
141
142
     double findmin(double x1, double x2, double y1, double y2) {
143
       double l = x1, r = x2;
144
       while(r-l>eps) {
145
         double mid = (1+r)/2.0;
         double mmid = (mid+r)/2.0;
146
147
         if( trifind(mmid,y1,y2) > trifind(mid,y1,y2)+eps )
148
           l = mid;
149
         else
150
           r = mmid;
151
152
       return trifind(l,y1,y2);
153
154
155
     double ans(int a, int b, int c, int r) {
156
       A = node(0,0);
157
       B = node((double)c, 0);
158
       R = r;
159
       double da = a, db = b, dc = c;
       double cosa = (db*db+dc*dc-da*da)/(2.0*db*dc);
160
161
       double alpha = acos(cosa);
162
       C = node(db*cosa, db*sin(alpha));
163
       return findmin(0.0, c, 0.0, db*sin(alpha));
164
165
166
     int main(void) {
       int a = 0, b = 0, c = 0, r = 0;
167
       while(EOF != scanf("%d%d%d%d",&a,&b,&c,&r) && (allbliclir))
168
         printf(%.81f\n, ans(a,b,c,r));
169
170
       return 0;
171 |}
    3.1.5 Universe
  1 |#include <bits/stdc++.h>
  2
    using namespace std;
  3
  4
    struct Point {
      double x, y;
```

```
6
     Point(double x = 0, double y = 0) : x(x), y(y) {}
 7
   };
 8
 9
   typedef Point Vector;
10
11
   Vector operator + (Vector A, Vector B) {
12
     return Vector(A.x + B.x, A.y + B.y);
13
14
   Vector operator - (Vector A, Vector B) {
15
     return Vector(A.x - B.x, A.y - B.y);
16
17
   Vector operator * (Vector A, double p) {
18
     return Vector(A.x*p, A.x*p);
19
   Vector operator / (Vector A, double p) {
20
21
     return Vector(A.x/p, A.x/p);
22
23
24
   bool operator < (const Point& a, const Point b) {
25
     return a.x < b.x | | (a.x == b.x && a.y < b.y);
26
27
28
   const double EPS = 1e-10;
29
30
   int dcmp(double x) {
31
     if(fabs(x) < EPS) return 0;
32
     else return x < 0 ? -1 : 1;
33
34
35
   bool operator == (const Point& a, const Point& b) {
36
     return dcmp(a.x-b.x) == 0 \& dcmp(a.y-b.y);
37
38
39
   //向量a的极角
   double Angle(const Vector& v) {
41
     return atan2(v.y, v.x);//\share\CodeBlocks\templates\wizard\console\cpp
42
43
44
   //向量点积
45
   double Dot(Vector A, Vector B) {
46
     return A.x*B.x + A.y*B.y;
47
48
49
   //向量长度\share\CodeBlocks\templates\wizard\console\cpp
   double Length(Vector A) {
50
51
     return sqrt(Dot(A, A));
52
53
54
   //向量夹角
   double Angle(Vector A, Vector B) {
55
     return acos(Dot(A, B) / Length(A) / Length(B));
56
57
58
59
   //向量叉积
60
   double Cross(Vector A, Vector B) {
61
     return A.x*B.y - A.y*B.x;
62
63
64
   //三角形有向面积的二倍
   double Area2(Point A, Point B, Point C) {
65
     return Cross(B-A, C-A);
66
67
68
69 | //向量逆时针旋转rad度(弧度)
```

```
| Vector Rotate(Vector A, double rad) {
     return Vector(A.x*cos(rad)-A.y*sin(rad), A.x*sin(rad)+A.y*cos(rad));
71
72
   }
73
74
   //计算向量A的单位法向量。左转90°,把长度归一。调用前确保A不是零向量。
75
   Vector Normal(Vector A) {
76
     double L = Length(A);
77
     return Vector(-A.y/L, A.x/L);
78
79
80
   81
   使用复数类实现点及向量的简单操作
82
   #include <complex>
83
84
   typedef complex<double> Point;
85
   typedef Point Vector;
86
87
   double Dot(Vector A, Vector B) { return real(conj(A)*B)}
88
   double Cross(Vector A, Vector B) { return imag(conj(A)*B);}
89
   Vector Rotate(Vector A, double rad) { return A*exp(Point(0, rad)); }
90
91
   92
93
   94
   * 用直线上的一点p0和方向向量v表示一条指向。直线上的所有点P满足P = P0+t*v;
95
   * 如果知道直线上的两个点则方向向量为B-A, 所以参数方程为A+(B-A)*t;
96
   * 当t 无限制时, 该参数方程表示直线。
97
   * 当t > 0时, 该参数方程表示射线。
98
   * 当 0 < t < 1时, 该参数方程表示线段。
99
   100
101
   //直线交点,须确保两直线有唯一交点。
102
   Point GetLineIntersection(Point P, Vector v, Point Q, Vector w) {
103
     Vector u = P - Q;
104
     double t = Cross(w, u)/Cross(v, w);
105
     return P+v*t;
106
   }
107
   //点到直线距离
108
109
   double DistanceToLine(Point P, Point A, Point B) {
110
     Vector v1 = B - A, v2 = P - A;
111
     return fabs(Cross(v1, v2) / Length(v1)); //不取绝对值, 得到的是有向距离
112
113
114
   //点到线段的距离
115
   double DistanceToSegmentS(Point P, Point A, Point B) {
116
     if(A == B) return Length(P-A);
     Vector v1 = B-A, v2 = P-A, v3 = P-B;
117
118
     if(dcmp(Dot(v1, v2)) < 0) return Length(v2);</pre>
119
     else if(dcmp(Dot(v1, v3)) > 0) return Length(v3);
120
     else return fabs(Cross(v1, v2)) / Length(v1);
121
122
123
   //点在直线上的投影
124
   Point GetLineProjection(Point P, Point A, Point B) {
125
     Vector v = B - A;
126
     return A+v*(Dot(v, P-A)/Dot(v, v));
127
128
129
   //线段相交判定,交点不在一条线段的端点
   bool SegmentProperIntersection(Point a1, Point a2, Point b1, Point b2) {
130
     double c1 = Cross(a2-a1, b1-a1), c2 = Cross(a2-a1, b2-a1);
131
132
     double c3 = Cross(b2-b1, a1-b1), c4 = Cross(b2-b1, a2-b1);
133
     return dcmp(c1)*dcmp(c2) < 0 && dcmp(c3)*dcmp(c4) < 0;
```

```
134
   |}
135
136
    //判断点是否在点段上,不包含端点
    bool OnSegment(Point P, Point a1, Point a2) {
137
138
      return dcmp(Cross(a1-P, a2-P) == 0 \& dcmp((Dot(a1-P, a2-P)) < 0));
139
140
141
    //计算凸多边形面积
    double ConvexPolygonArea(Point *p, int n) {
142
     double area = 0;
143
144
      for(int i = 1; i < n-1; i++)
145
       area += Cross(p[i] - p[0], p[i+1] - p[0]);
146
      return area/2;
147
148
149
    //计算多边形的有向面积
150
    double PolygonArea(Point *p, int n) {
151
     double area = 0;
152
     for(int i = 1; i < n-1; i++)
153
       area += Cross(p[i] - p[0], p[i+1] - p[0]);
154
      return area/2;
155
156
157
    158
    * Morley定理: 三角形每个内角的三等分线, 相交成的三角形是等边三角形。
159
    * 欧拉定理: 设平面图的定点数, 边数和面数分别为V,E,F。则V+F-E = 2;
160
    161
162
    struct Circle {
163
     Point c;
164
     double r;
165
166
     Circle(Point c, double r) : c(c), r(r) {}
     //通过圆心角确定圆上坐标
167
168
     Point point(double a) {
169
       return Point(c.x + cos(a)*r, c.y + sin(a)*r);
170
     }
171
    };
172
173
    struct Line {
174
     Point p;
175
     Vector v;
176
     double ang;
177
     Line() {}
178
     Line(Point p, Vector v) : p(p), v(v) {}
179
     bool operator < (const Line& L) const {</pre>
180
       return ang < L.ang;</pre>
181
     }
182
    };
183
    //直线和圆的交点,返回交点个数,结果存在sol中。
184
185
    //该代码没有清空sol。
    int getLineCircleIntersecion(Line L, Circle C, double& t1, double& t2, vector<Point>&
186
        sol) {
187
     double a = L.v.x, b = L.p.x - C.c.x, c = L.v.y, d = L.p.y - C.c.y;
     double e = a*a + c*c, f = 2*(a*b + c*d), g = b*b + d*d - C.r*C.r;
188
     double delta = f*f - 4*e*g;
189
190
     if(dcmp(delta) < 0) return 0; //相离
191
     if(dcmp(delta) == 0) {
                                //相切
192
       t1 = t2 = -f / (2*e);
193
       sol.push_back(C.point(t1));
194
       return 1;
195
196
     //相交
```

```
197
      t1 = (-f - sqrt(delta)) / (2*e);
198
      sol.push_back(C.point(t1));
199
      t2 = (-f + sqrt(delta)) / (2*e);
200
      sol.push_back(C.point(t2));
201
      return 2;
202
203
204
    //两圆相交
205
    int getCircleCircleIntersection(Circle C1, Circle C2, vector<Point>& sol) {
206
      double d = Length(C1.c - C2.c);
207
      if(dcmp(d) == 0) {
208
        if(dcmp(C1.r - C2.r == 0)) return -1;
                                                //两圆完全重合
209
                                                //同心圆,半径不一样
        return 0;
210
211
      if(dcmp(C1.r + C2.r - d) < 0) return 0;
212
      if(dcmp(fabs(C1.r - C2.r) == 0)) return -1;
213
214
      double a = Angle(C2.c - C1.c);
                                                  //向量C1C2的极角
215
      double da = acos((C1.r*C1.r + d*d - C2.r*C2.r) / (2*C1.r*d));
216
      //C1C2到C1P1的角
217
      Point p1 = C1.point(a-da), p2 = C1.point(a+da);
218
      sol.push_back(p1);
219
      if(p1 == p2) return 1;
220
      sol.push_back(p2);
221
      return 2;
222
223
224
    const double PI = acos(-1);
225
    //过定点做圆的切线
226
    //过点p做圆C的切线,返回切线个数。v[i]表示第i条切线
    int getTangents(Point p, Circle C, Vector* v) {
227
228
      Vector u = C.c - p;
229
      double dist = Length(u);
230
      if(dist < C.r) return 0;
231
      else if(dcmp(dist - C.r) == 0) {
232
        v[0] = Rotate(u, PI/2);
233
        return 1;
234
      } else {
235
        double ang = asin(C.r / dist);
236
        v[0] = Rotate(u, -ang);
237
        v[1] = Rotate(u, +ang);
238
        return 2;
239
      }
240
241
242
    //两圆的公切线
243
    //返回切线的个数,-1表示有无数条公切线。
244
    //a[i], b[i] 表示第i条切线在圆A, 圆B上的切点
245
    int getTangents(Circle A, Circle B, Point *a, Point *b) {
246
      int cnt = 0;
247
      if(A.r < B.r) {
        swap(A, B);
248
249
        swap(a, b);
250
      int d2 = (A.c.x - B.c.x)*(A.c.x - B.c.x) + (A.c.y - B.c.y)*(A.c.y - B.c.y);
251
252
      int rdiff = A.r - B.r;
253
      int rsum = A.r + B.r;
254
      if(d2 < rdiff*rdiff) return 0;
                                      //内含
255
      double base = atan2(B.c.y - A.c.y, B.c.x - A.c.x);
256
      if(d2 == 0 && A.r == B.r) return -1; //无限多条切线
257
                                     //内切一条切线
      if(d2 == rdiff*rdiff) {
258
        a[cnt] = A.point(base);
259
        b[cnt] = B.point(base);
260
        cnt++;
```

```
261
       return 1;
262
263
      //有外共切线
264
      double ang = acos((A.r-B.r) / sqrt(d2));
265
      a[cnt] = A.point(base+ang);
266
      b[cnt] = B.point(base+ang);
267
      cnt++:
      a[cnt] = A.point(base-ang);
268
269
      b[cnt] = B.point(base-ang);
270
      cnt++;
271
      if(d2 == rsum*rsum) { //一条公切线
272
       a[cnt] = A.point(base);
273
       b[cnt] = B.point(PI+base);
274
       cnt++;
275
      } else if(d2 > rsum*rsum) { //两条公切线
276
       double ang = acos((A.r + B.r) / sqrt(d2));
277
       a[cnt] = A.point(base+ang);
278
       b[cnt] = B.point(PI+base+ang);
279
       cnt++;
280
       a[cnt] = A.point(base-ang);
281
       b[cnt] = B.point(PI+base-ang);
282
       cnt++;
283
284
      return cnt;
285
286
287
    typedef vector<Point> Polygon;
288
289
    //点在多边形内的判定
290
    int isPointInPolygon(Point p, Polygon poly) {
291
      int wn = 0;
292
      int n = poly.size();
293
      for(int i = 0; i < n; i++) {
294
       if(OnSegment(p, poly[i], poly[(i+1)%n])) return -1; //在边界上
295
       int k = dcmp(Cross(poly[(i+1)%n]-poly[i], p-poly[i]));
       int d1 = dcmp(poly[i].y - p.y);
296
297
       int d2 = dcmp(poly[(i+1)%n].y - p.y);
298
       if(k > 0 \&\& d1 \le 0 \&\& d2 > 0) wn++;
299
       if(k < 0 \&\& d2 <= 0 \&\& d1 > 0) wn++;
300
301
      if(wn != 0) return 1;
                               //内部
302
                               //外部
      return 0;
303
304
305
    //凸包
306
    307
    * 输入点数组p, 个数为p, 输出点数组ch。 返回凸包顶点数
308
    * 不希望凸包的边上有输入点, 把两个<= 改成 <
309
    * 高精度要求时建议用dcmp比较
310
    * 输入点不能有重复点。函数执行完以后输入点的顺序被破坏
311
    312
    int ConvexHull(Point *p, int n, Point* ch) {
                       // 先比较x坐标, 再比较y坐标
313
      sort(p, p+n);
314
      int m = 0;
315
      for(int i = 0; i < n; i++) {
       while(m > 1 && Cross(ch[m-1] - ch[m-2], p[i]-ch[m-2]) <= 0) m--;
316
317
       ch[m++] = p[i];
318
      }
319
      int k = m;
320
      for(int i = n-2; i >= 0; i++) {
       while(m > k && Cross(ch[m-1] - ch[m-2], p[i]-ch[m-2]) <= 0) m--;
321
322
       ch[m++] = p[i];
323
      if(n > 1) m—;
324
```

```
325
      return m;
326
    }
327
328
    //用有向直线A->B切割多边形poly,
                                    返回"左侧"。 如果退化,可能会返回一个单点或者线段
329
    //复杂度0(n2);
330
    Polygon CutPolygon(Polygon poly, Point A, Point B) {
331
      Polygon newpoly;
332
      int n = poly.size();
      for(int i = 0; i < n; i++) {
333
334
        Point C = poly[i];
335
        Point D = poly[(i+1)\%n];
336
        if(dcmp(Cross(B-A, C-A)) >= 0) newpoly.push_back(C);
337
        if(dcmp(Cross(B-A, C-D)) != 0) {
338
          Point ip = GetLineIntersection(A, B-A, C, D-C);
339
          if(OnSegment(ip, C, D)) newpoly.push_back(ip);
340
        }
341
342
      return newpoly;
343
344
345
    //半平面交
346
347
    // 点p再有向直线L的左边。(线上不算)
348
    bool Onleft(Line L, Point p) {
349
      return Cross(L.v, p-L.p) > 0;
350
351
352
    //两直线交点,假定交点唯一存在
353
    Point GetIntersection(Line a, Line b) {
354
      Vector u = a.p - b.p;
355
      double t = Cross(b.v, u) / Cross(a.v, b.v);
356
      return a.p+a.v*t;
357
    }
358
359
    int HalfplaneIntersection(Line* L, int n, Point* poly) {
360
      sort(L, L+n);
                                  //按极角排序
361
362
      int first, last;
                                  //双端队列的第一个元素和最后一个元素
363
      Point *p = new Point[n];
                                  //p[i]为q[i]和q[i+1]的交点
364
      Line *q = new Line[n];
                                  //双端队列
365
      q[first = last = 0] = L[0]; //队列初始化为只有一个半平面L[0]
366
      for(int i = 0; i < n; i++) {
367
        while(first < last && !Onleft(L[i], p[last-1])) last--;</pre>
        while(first < last && !Onleft(L[i], p[first])) first++;</pre>
368
369
        q[++last] = L[i];
370
        if(fabs(Cross(q[last].v, q[last-1].v)) < EPS) {
371
          if(Onleft(q[last], L[i].p)) q[last] = L[i];
372
373
374
        if(first < last) p[last-1] = GetIntersection(q[last-1], q[last]);
375
      while(first < last && !Onleft(q[first], p[last-1])) last--;</pre>
376
377
      //删除无用平面
      if(last-first <= 1) return 0;</pre>
378
379
      p[last] = GetIntersection(q[last], q[first]);
380
381
      //从deque复制到输出中
382
      int m = 0;
383
      for(int i = first; i \le last; i++) poly[m++] = p[i];
384
      return m;
385 | }
```

## 3.1.6 Largest empty convex

```
1
   /* POJ 1259 */
   #include <iostream>
 3
   #include <cmath>
   #include <cstdio>
 4
 5
   #include <algorithm>
   using namespace std;
 7
   typedef double type_p;
 8
   const double eps = 1e-6;
 9
   const int maxn = 510;
   double dp[maxn][maxn];
10
11
   inline double eq(double x, double y) {
12
      return fabs(x-y)<eps;</pre>
13
14
   inline int eq(int x, int y) {
15
      return x==y;
16
17
    struct point {
18
     type_p x,y;
19
   };
20
   type_p xmult(point a, point b, point o) {
21
      return (a.x-o.x)*(o.y-b.y)-(a.y-o.y)*(o.x-b.x);//b at ao left if negative, at right
          if positive
22
23
   type_p dist(point a, point b) {
24
      return (a.x-b.x)*(a.x-b.x)+(a.y-b.y)*(a.y-b.y);
25
26
   point o;
27
   bool cmp_angle(point a,point b) {
28
      if(eq(xmult(a,b,o),0.0)) {
29
        return dist(a,o)<dist(b,o);</pre>
30
31
      return xmult(a,o,b)>0;
32
33
    /*
34
   Input:
            p: Point set
35
            pn: size of the point set
36
37
   Output: the area of the largest empty convex
38
39
   double empty_convex(point *p, int pn) {
      double ans=0;
40
41
      for(int i=0; i<pn; i++) {
42
        for(int j=0; j<pn; j++) {
43
          dp[i][j]=0;
44
        }
      }
45
46
47
      for(int i=0; i<pn; i++) {
48
        while(j \ge 0 && eq(xmult(p[i], p[j], o),0.0))j = \frac{1}{2}//coline
49
50
51
        bool flag= j==i-1;
52
53
        while(j \ge 0) {
54
          int k = j-1;
55
          while(k \geq 0 && xmult(p[i],p[k],p[j])>0)k—;
          double area = fabs(xmult(p[i],p[j],o))/2;
56
57
          if(k \ge 0)area + = dp[j][k];
58
          if(flag) dp[i][j]=area;
59
          ans=max(ans, area);
60
          j=k;
```

```
61
        if(flag) {
 62
 63
           for(int j=1; j<i; j++) {
 64
             dp[i][j] = max(dp[i][j],dp[i][j-1]);
 65
 66
        }
 67
 68
      return ans;
 69
    double largest_empty_convex(point *p, int pn) {
 70
 71
      point data[maxn];
 72
      double ans=0;
 73
      for(int i=0; i<pn; i++) {
 74
        o=p[i];
 75
        int dn=0;
        for(int j=0; j<pn; j++) {</pre>
 76
 77
           if(p[j].y>o.y||(p[j].y=o.y&p[j].x>=o.x)) {
 78
             data[dn++]=p[j];
 79
        }
 80
 81
        sort(data, data+dn, cmp_angle);
 82
        ans=max(ans, empty_convex(data, dn));
 83
 84
      return ans;
 85
 86
    int main() {
 87
    #ifndef ONLINE_JUDGE
       freopen("in.txt","r",stdin);
 88
    #endif // ONLINE_JUDGE
 89
 90
      point p[110];
 91
      int t
      scanf("%d",&t);
 92
 93
      while(t--) {
 94
        int pn;
         scanf("%d",&pn);
 95
 96
         for(int i=0; i<pn; i++) {
          scanf("%lf%lf",&p[i].x,&p[i].y);
 97
 98
 99
        printf("%.1f\n",largest_empty_convex(p,pn));
100
101
      return 0;
102
103
104
    // 作者: nyroro
    // 来源: CSDN
105
106
    // 原文: https://blog.csdn.net/nyroro/article/details/45268767
107
    |// 版权声明:本文为博主原创文章,转载请附上博文链接!
        Graph
         Tree
    4.I
    4.1.1 Universe
  2
    /* find root(重心) */
  3
  4
    void findroot(int u, int fa) {
  5
      int i;
  6
      size[u] = 1;
  7
      f[u] = 0;
```

for  $(i = last[u]; i; i = e[i][2]) {$ 

```
9
        if (!vis[e[i][0]] && e[i][0] != fa) {
10
          findroot(e[i][0], u);
11
          size[u] += size[e[i][0]];
12
          if (f[u] < size[e[i][0]])
13
            f[u] = size[e[i][0]];
14
        }
15
     if (f[u] < ALL - size[u])
16
17
        f[u] = ALL - size[u];
18
      if (f[u] < f[root]) root = u;
19
20
21
   /* ---- da ---- */
22
23
   int dep[MAXN+1];
24
   int ancestor[MAXN+1][MAXLGN];
25
   int minw[MAXN+1][MAXLGN];
26
27
   void dfs(int u, int fa) {
28
     ancestor[u][0] = fa;
29
     dep[u] = dep[fa] + 1;
30
     for(int e = u[front]; e; e = E[e].n) {
        int v = E[e].v, w = E[e].w;
31
        if(v != fa) {
32
          minw[v][0] = w;
33
34
          dfs(v, u);
35
        }
36
     }
37
38
39
   void init_system(void) {
40
     int i = 0, w = 0;
41
     int t = 0;
42
     dep[0] = -1;
43
     dfs(1,0);
     for(w = 1; (t=(1 << w)) < N; ++w)
44
45
        for(i = 1; i \le N; ++i) if(dep[i] >= t) {
46
            ancestor[i][w] = ancestor[ancestor[i][w-1]][w-1];
47
            minw[i][w] = min(minw[i][w-1], minw[ancestor[i][w-1]][w-1]);
48
49
50
51
   int query(int a, int b) {
52
     if(dep[a] < dep[b]) return query(b,a);</pre>
     else { /* now dep[s] > dep[t] */
53
54
        int i = 0;
55
        int maxbit = MAXLGN-1;
56
        int ret = INF;
57
        //while((1<<maxbit) <= dep[a]) maxbit++;</pre>
58
        /* first up a to same dep with b. */
59
        for(i = maxbit; i >= 0; i---)
          if(dep[a] - (1 << i) >= dep[b]) {
60
61
            ret = min(ret, minw[a][i]);
62
            a = ancestor[a][i];
63
64
        if(a == b) return ret;
        for(i = maxbit; i \ge 0; i—)
65
          if(dep[a] - (1 << i) >= 0 \& ancestor[a][i] != ancestor[b][i]) {
66
67
            ret = min(ret, min(minw[a][i], minw[b][i]));
            a = ancestor[a][i];
68
69
            b = ancestor[b][i];
70
71
        ret = min(ret, min(minw[a][0], minw[b][0]));
72
        return ret;
```

```
73 | }
74 |}
```

## 4.1.2 Point Divide and Conquer

```
Version 1
```

```
//* Tree::Point divide and conquer, by Abreto<m@abreto.net>. */
 2
   #include <bits/stdc++.h>
 3
 4
   using namespace std;
 5
   typedef long long int ll;
 6
 7
   #define MAXN
                     (100001)
 8
   #define MAXV
                     (MAXN+1)
9
   #define MAXE
                     (MAXN << 1)
10
   struct edge {
11
      int v;
12
      edge *n;
13
      edge(void):v(0),n(NULL) {}
14
      edge(int vv,edge *nn):v(vv),n(nn) {}
15
16
   int nE:
17
   edge E[MAXE];
   edge *front[MAXV];
18
                        /* 0 for '(', 1 for ')' */
19
   int label[MAXV];
20
   void add_edge(int u, int v) {
21
      int ne = ++nE;
22
      E[ne] = edge(v, u[front]);
23
      u[front] = \&(E[ne]);
24
25
26
   int n;
27
   ll ans;
28
29
   char del[MAXV];
   namespace findroot {
30
31
   int ALL;
32
   int nfind;
   int vis[MAXV];
33
   int size[MAXV];
34
35
   int f[MAXV];
36
   int root;
37
    void __find(int u, int fa) {
38
      vis[u] = nfind;
39
      size[u] = 1;
40
      f[u] = 0;
41
      for(edge *e=u[front]; e; e = e->n) {
42
        int v = e \rightarrow v;
43
        if((!del[v]) && (vis[v] != nfind) && (v != fa)) {
44
           _find(v, u);
45
          size[u] += size[v];
46
          if(f[u] < size[v]) f[u] = size[v];</pre>
47
        }
48
49
      if(f[u] < ALL - size[u]) f[u] = ALL - size[u];
50
      if(f[u] < f[root]) root = u;
51
52
    int find(int u, int all) {
53
      ++nfind;
54
      ALL = all;
55
      f[root = 0] = MAXV;
56
      __find(u,0);
```

```
57
       return root;
    }
 58
 59
    }
 60
 61
    namespace workspaces {
 62
     int maxdep;
     int dep[MAXV]:
 63
     ll cntin[MAXV], cntout[MAXV];
int in[2][MAXV]; /* 0 for
 64
                          /* 0 for '(', 1 for ')' */
 65
 66
     int out[2][MAXV];
 67
     void getdeep(int u, int fa) {
 68
       dep[u] = dep[fa] + 1;
       if(dep[u] > maxdep) maxdep = dep[u];
 69
 70
       for(edge *e = u[front]; e; e = e->n)
         if((!del[e->v]) && (fa != e->v))
 71
 72
           getdeep(e->v, u);
 73
 74
     void dfs(int u, int fa) {
 75
 76
         /* out from root */
 77
         out[0][u] = out[0][fa];
 78
         out[1][u] = out[1][fa];
 79
         if(0 == label[u]) { /* meet '(' */
           out[0][u]++;
 80
                      /* meet ')' */
 81
         } else {
 82
           if(out[0][u]) out[0][u]--;
 83
           else out[1][u]++;
 84
 85
         if(out[0][u] == 0)
           cntout[out[1][u]]++;
 86
 87
 88
 89
         /* in to root */
 90
         in[0][u] = in[0][fa];
 91
         in[1][u] = in[1][fa];
 92
         if(0 == label[u]) { /* meet '(' */
           if(in[1][u]) in[1][u]--;
 93
 94
           else in[0][u]++;
 95
         } else {
                      /* meet ')' */
 96
           in[1][u]++;
 97
 98
         if(0 == in[1][u])
 99
           cntin[in[0][u]]++;
100
101
       /* do something */
102
       for(edge *e = u[front]; e; e = e \rightarrow n) {
103
         int v = e \rightarrow v;
104
         if((!del[v]) && (v != fa)) {
105
           dfs(v, u);
106
         }
107
       }
108
109
     inline void init_maxdep(void) {
110
       maxdep = 0;
111
112
     inline void update_maxdep(int u) {
113
       dep[u] = 1;
114
       if(dep[u] > maxdep) maxdep = dep[u];
115
       for(edge *e = u[front]; e; e = e \rightarrow n)
116
         if((!del[e->v]))
117
           getdeep(e->v, u);
118
119
    inline void clear(void) {
120
       for(int i = 0; i \le maxdep+1; ++i)
```

```
121
         cntin[i] = cntout[i] = 0;
122
123
    inline void work(int u) {
124
       in[0][u] = in[1][u] = out[0][u] = out[1][u] = 0;
125
       in[label[u]][u] = out[label[u]][u] = 1;
126
       if(out[0][u] == 0) cntout[out[1][u]]++;
       if(0 == in[1][u]) cntin[in[0][u]]++;
127
128
       /* update in and out if neccessary */
129
       for(edge *e = u[front]; e; e = e->n)
130
         if(!(del[e->v]))
131
           dfs(e\rightarrow v, u);
132
133
    };
134
135
     11 count(int u, int p) {
136
       ll ret = 0;
137
       workspace::init_maxdep();
138
       workspace::update_maxdep(u);
139
       workspace::clear();
       if(-1 == p) {
140
141
         for(edge *e = u[front]; e; e = e->n)
142
           if((!(del[e->v])))
143
             workspace::work(e->v);
         p = label[u];
144
145
         /* single end */
146
         if(0 == p) ret = workspace::cntout[1];
147
         else ret = workspace::cntin[1];
148
       } else {
149
         workspace::work(u);
150
151
       if(0 == p) { /* p is '(' */
152
         for(int i = 0; i < workspace::maxdep; ++i) /* concatenation */
153
           ret += workspace::cntin[i] * workspace::cntout[i+1];
154
                  /* p is ')' */
155
         for(int i = 0; i < workspace::maxdep; ++i) /* concatenation */
156
           ret += workspace::cntin[i+1] * workspace::cntout[i];
157
158
       return ret;
159
160
161
    void handle(int u) {
162
       del[u] = 1; /* delete current root. */
       ans += count(u, -1);
163
164
       /* do something */
165
       for(edge *e = u[front]; e; e = e \rightarrow n) {
166
         int v = e \rightarrow v;
167
         if(!del[v]) {
           ans -= count(v, label[u]);
168
169
           /* do something */
170
           int r = findroot::find(v, findroot::size[v]);
171
           handle(r);
172
         }
173
174
175
     void proc(void) {
176
177
       int r = findroot::find(1,n);
178
       handle(r);
179
180
181
    char ls[MAXV+1];
182
    int main(void) {
183
       int i = 0;
184
       scanf("%d", &n);
```

```
scanf("%s", ls);
for(i = 0; i < n; ++i)</pre>
185
186
         label[i+1] = ls[i] - '(';
187
188
       for(i = 1; i < n; ++i) {
189
         int ai, bi;
         scanf("%d⊔%d", &ai, &bi);
190
191
         add_edge(ai, bi);
192
         add_edge(bi, ai);
193
194
       proc();
       printf("%lld\n", ans);
195
196
       return 0;
197
     Version 2
  1 | /* 2016 ACM/ICPC Asia Regional Dalian. Problem , by Abreto<m@abreto.net>. */
  2
    |#include <bits/stdc++.h>
  3
  4
    using namespace std;
  5
    typedef long long int ll;
  7
     /* offset in [1,k] */
                               (((i)>>((offset)-1))&1)
     #define GET(i,offset)
                               ((i)|(1<<((offset)-1)))
  9
     #define SET(i,offset)
 10
    #define REV(i,offset)
                               ((i)^{(1<<((offset)-1))})
 11
 12
    #define MAXN
                      (50005)
 13
    #define MAXV
                      (MAXN+1)
 14
    #define MAXE
                      (MAXN << 1)
 15
    struct edge {
 16
       int v;
 17
       edge *n;
 18
       edge(void):v(0),n(NULL) {}
 19
       edge(int vv,edge *nn):v(vv),n(nn) {}
 20
    };
 21
    int nE;
     edge E[MAXE];
 22
     edge *front[MAXV];
 23
     int label[MAXV];
 24
                          /* each kind */
 25
     void add_edge(int u, int v) {
 26
       int ne = ++nE;
 27
       E[ne] = edge(v, u[front]);
 28
       u[front] = \&(E[ne]);
 29
 30
 31
     int n, k;
 32
     ll ans;
 33
    int all_kind;
 34
 35
    int ndel:
    int del[MAXV];
 36
 37
    namespace findroot {
 38
    int ALL;
 39
     ll nfind;
     ll vis[MAXV];
 40
 41
    int size[MAXV];
 42
    int f[MAXV];
    int root;
 43
 44
     void __find(int u, int fa) {
       vis[u] = nfind;
 45
 46
       size[u] = 1;
 47
       f[u] = 0;
 48
       for(edge *e=u[front]; e; e = e->n) {
 49
         int v = e \rightarrow v;
```

```
50
         if((del[v] != ndel) && (vis[v] != nfind) && (v != fa)) {
 51
            __find(v, u);
 52
           size[u] += size[v];
 53
           if(f[u] < size[v]) f[u] = size[v];
 54
         }
 55
 56
       if(f[u] < ALL - size[u]) f[u] = ALL - size[u];
 57
       if(f[u] < f[root]) root = u;
 58
 59
     int find(int u, int all) {
 60
       ++nfind;
 61
       ALL = all;
       f[root = 0] = MAXV;
 62
 63
       __find(u,0);
 64
       return root;
 65
    }
 66
 67
 68
    namespace workspace {
 69
    ll cnt[1024];
 70
     int dp[MAXV];
 71
     void dfs(int u, int fa) {
 72
       dp[u] = dp[fa] \mid label[u];
       cnt[dp[u]] ++;
 73
 74
       /* dig into children */
 75
       for(edge *e = u[front]; e; e = e \rightarrow n) {
 76
         int v = e \rightarrow v;
 77
         if((del[v] != ndel) && (v != fa)) {
 78
           dfs(v, u);
 79
       }
 80
 81
82
     inline void clear(void) {
 83
       for(int i = 1; i \le all_kind; ++i)
 84
         cnt[i] = 0;
 85
 86
     inline void work(int u) {
 87
       dp[u] = label[u];
 88
       cnt[dp[u]] ++;
 89
       for(edge *e = u[front]; e; e = e->n)
 90
         if((del[e\rightarrow v] != ndel))
 91
           dfs(e\rightarrow v, u);
 92
 93
     inline void show(void) {
       for(int i = 0; i \leftarrow all_kind; ++i)
 94
         printf("cnt[%d]_=_%lld\n", i, cnt[i]);
 95
 96
       for(int i = 1; i <= n; ++i)
 97
         printf("dp[%d]_{\square}=_{\square}%d\n", i, dp[i]);
 98
 99
     };
100
101
102
     11 count(int u, int p) {
       ll ret = 0;
103
104
       workspace::clear();
105
       //printf("%d,%d :\n", u, p);
106
       if(-1 == p) {
107
         for(edge *e = u[front]; e; e = e->n)
108
           if(((del[e->v]) != ndel))
109
             workspace::work(e->v);
110
         p = label[u];
111
         /* single end */
112
         for(int i = 1; i <= all_kind; i++)
           if(all\_kind == (i|p))
113
```

```
114
              ret += (workspace::cnt[i]<<1);</pre>
115
       } else {
116
         workspace::work(u);
117
       //workspace::show();
118
119
       for(int i = 1; i \leftarrow all_kind; ++i)
120
         if( workspace::cnt[i] > 0 )
            for(int j = 1; j <= all_kind; ++j) if(all_kind == (i|p|j))
121
122
123
                ret += workspace::cnt[i] * workspace::cnt[j];
124
       //printf("%lld\n", ret);
125
       return ret;
126
127
128
     void handle(int u) {
129
       //printf("proccessing %d\n", u);
130
       del[u] = ndel; /* delete current root. */
131
       ans += count(u, -1);
132
       /* do something */
133
       for(edge *e = u[front]; e; e = e \rightarrow n) {
134
         int v = e \rightarrow v;
         if(del[v] != ndel) {
135
           ans -= count(v, label[u]);
136
137
           /* do something */
138
           int r = findroot::find(v, findroot::size[v]);
139
           handle(r);
140
         }
141
       }
142
143
144
     void proc(void) {
145
       int r = findroot::find(1,n);
146
       handle(r);
147
148
149
     void clear(void) {
150
       int i;
151
       ans = 0;
152
       nE = 0;
153
       for(i = 0; i \le n; ++i) {
154
         front[i] = NULL;
155
156
       //findroot::nfind = 0;
157
       ndel++;
158
159
160
     void mozhu(void) {
       int i = 0;
161
162
       int li;
163
       for(i = 1; i \le n; ++i) 
164
         scanf("%d", &li);
         label[i] = 1 << (li-1);
165
166
       for(i = 1; i < n; ++i) {
167
168
         int ai, bi;
         scanf("%d<sub>\\\\</sub>%d", &ai, &bi);
169
170
         add_edge(ai, bi);
171
         add_edge(bi, ai);
172
173
       all_kind = (1 << k)-1;
174
       proc();
175
       if(1 == k) ans += n;
       printf("%lld\n", ans);
176
177 | }
```

```
178
179
    int main(void) {
180
       while( EOF != scanf("%d%d", &n, &k) ) {
181
         clear();
182
         mozhu();
183
184
       return 0;
185
```

## 4.1.3 Hevay chain decompostion

```
/* bzoj 1036 */
    /* 树链剖分 */
 2
   #include <bits/stdc++.h>
 3
 4
 5
   using namespace std;
 6
 7
   #define MAXN
                     30030
 8
   #define MAXM
                     (MAXN << 1)
9
   struct edge {
10
      int v;
11
      edge *n;
12
      edge(void) {}
      edge(int vv, edge *nn):v(vv),n(nn) {}
13
14
   };
15
   typedef edge *ep;
16
   int nE;
17
    edge E[MAXM];
18
   ep front[MAXN];
19
    void add_edge(int u, int v) {
20
      int ne = ++nE;
21
      E[ne] = edge(v, u[front]);
22
      u[front] = \&(E[ne]);
23
    }
24
25
    int n;
    int fa[MAXN], son[MAXN], sz[MAXN], dep[MAXN];
26
27
    int top[MAXN];
28
    int id[MAXN];
29
   int tot;
30
31
    void calc(int u, int uf) {
32
      dep[u] = dep[uf] + 1;
33
      fa[u] = uf;
34
      sz[u] = 1;
35
      son[u] = -1;
36
      for(ep e = u[front]; e; e = e \rightarrow n) {
37
        if(e->v != uf) {
38
          calc(e\rightarrow v, u);
39
          sz[u] += sz[e->v];
          if(-1 == son[u] | sz[son[u]] < sz[e->v])
40
41
            son[u] = e \rightarrow v;
42
43
44
45
    void link(int u, int f) {
46
      id[u] = (++tot);
47
      top[u] = f;
48
      if(son[u] > 0) {
49
        link(son[u], f);
50
51
      for(ep e = u[front]; e; e = e \rightarrow n) {
52
        if(e->v != fa[u] \&\& e->v != son[u]) {
```

```
53
           link(e->v, e->v);
 54
 55
       }
 56
    }
 57
 58
    /* 其实是树链剖分 */
 59
     void make_link_cut_tree(void) {
 60
       calc(1, 0);
 61
       link(1, 1);
 62
 63
 64
    int w[MAXN];
 65
    int sum[MAXN<<2], mx[MAXN<<2];</pre>
 66
     void maintain(int o, int l, int r) {
 67
 68
       sum[o] = sum[o <<1] + sum[o <<1|1];
 69
       mx[o] = max(mx[o << 1], mx[o << 1|1]);
 70
 71
    void build(int o = 1, int l = 1, int r = n) {
 72
       if(r == 1) {
 73
         sum[o] = w[l];
 74
         mx[o] = w[l];
 75
       } else {
 76
         int mid = 1+r>>1;
 77
         build(o<<1, 1, mid);</pre>
 78
         build(o<<1|1, mid+1, r);
 79
         maintain(o, l, r);
 80
       }
 81
     void update(int p, int x, int o = 1, int l = 1, int r = n) {
 82
 83
       if(p \ll 1 \& r \ll p) {
 84
         sum[o] = x;
 85
         mx[o] = x;
 86
       } else {
         int mid = 1+r>>1;
 87
 88
         if(p \le mid) update(p,x,o \le 1,l,mid);
 89
         else update(p,x,o <<1 | 1,mid+1,r);
 90
         maintain(o,l,r);
 91
 92
 93
     int qs(int L, int R, int o = 1, int l = 1, int r = n) {
 94
       if(R < l | l | r < L) return 0;
 95
       else if (L \le l \& r \le R) {
 96
         return sum[o];
 97
       } else {
 98
         int mid = 1+r>>1;
 99
         return qs(L,R,o<<1,1,mid)+qs(L,R,o<<1|1,mid+1,r);
100
       }
101
102
     int qm(int L, int R, int o = 1, int l = 1, int r = n) {
       if(L \le 1 \& r \le R) {
103
104
         return mx[o];
105
       } else {
106
         int mid = 1+r>>1;
107
         if(R \le mid) return qm(L, R, o \le 1, l, mid);
108
         else if (L > mid) return qm(L, R, o<<1|1, mid+1, r);
109
         else return max(qm(L, R, o <<1, l, mid), qm(L, R, o <<1|1, mid+1, r));
110
111
112
113
     void change(int u, int t) {
114
       update(id[u], t);
115
116 | int qmax(int u, int v) \{
```

```
117
       int ret = -10000000000;
118
       while(top[u] != top[v]) {
119
         if( dep[top[u]] > dep[top[v]] ) {
120
           /* jump u */
121
           ret = max(ret, qm(id[top[u]], id[u]));
           u = fa[top[u]];
122
123
         } else {
124
           ret = max(ret, qm(id[top[v]], id[v]));
125
           v = fa[top[v]];
126
127
       }
128
       ret = max(ret, qm(min(id[u],id[v]),max(id[u],id[v])));
129
       return ret;
130
131
     int qsum(int u, int v) {
       int ret = 0;
132
133
       while(top[u] != top[v]) {
134
         if( dep[top[u]] > dep[top[v]] ) {
135
           /* jump u */
136
           ret += qs(id[top[u]], id[u]);
           u = fa[top[u]];
137
138
         } else {
           ret += qs(id[top[v]], id[v]);
139
140
           v = fa[top[v]];
141
142
       }
143
       ret += qs(min(id[u],id[v]),max(id[u],id[v]));
144
       return ret;
145
146
147
     int main(void) {
148
       int i;
       scanf("%d", &n);
149
150
       for(i = 1; i < n; ++i) {
         int a, b;
151
         scanf("%d%d", &a, &b);
152
153
         add_edge(a, b);
154
         add_edge(b, a);
155
       }
156
       make_link_cut_tree();
157
       for(i = 1; i <= n; ++i) {
158
         scanf("%d", &(w[id[i]]));
159
160
       build();
       scanf("%d", &i);
161
       while(i--) {
162
163
         char command[8];
164
         int a, b;
165
         scanf("%s_{\perp}%d'', command, &a, &b);
         if('C' == command[0]) change(a, b);
166
         else if ('M' == command[1]) printf("%d\n", qmax(a, b));
167
         else if ('S' == command[1]) printf("%d\n", qsum(a, b));
168
169
170
       return 0;
171 | }
     4.2 2-SAT
    |#include <bits/stdc++.h>
  3
    using namespace std;
  4
```

```
5
   |namespace two_sat {
 6
   const int maxn = 100000;
 7
   const int maxm = 1000000;
   struct edge {
 9
      int v;
10
      edge *n;
      edge(void):v(0),n(NULL) {}
11
12
      edge(int vv, edge *nn):v(vv),n(nn) {}
13
14
   typedef edge *ep;
15
   int n;
16
   int nE;
17
   edge E[maxm];
18
   ep front[maxn];
19
   void add_edge(int u, int v) {
      int ne = ++nE;
20
21
      E[ne] = edge(v, u[front]);
22
      u[front] = \&(E[ne]);
23
24
   /* (x = xval or y = yval), indexed from 0 */
   void add_clause(int x, int xv, int y, int yv) {
25
26
      x = x*2 + xv;
27
      y = y*2 + yv;
      add_edge(x^1, y);
28
29
      add_edge(y^1, x);
30
31
32
   char mark[maxn<<1];</pre>
33
   int S[maxn << 1], c;
34
   void init(int N) {
35
      n = N;
36
      for(int i = 0; i < n*2; ++i) {
37
        i[front] = NULL;
38
        i[mark] = 0;
39
40
     nE = 0;
41
42
    int dfs(int x) {
43
44
      if(mark[x^1]) return 0;
45
      if(mark[x]) return 1;
46
      mark[x] = 1;
47
      S[c++] = x;
48
      for(ep e = x[front]; e; e = e->n)
49
        if(!dfs(e->v)) return 0;
50
      return 1;
51
   }
52
53
    int solve(void) {
      for(int i = 0; i < n*2; i += 2)
54
55
        if(!mark[i] && !mark[i+1]) {
56
          c = 0;
          if(!dfs(i)) {
57
            while(c > 0) mark[S[--c]] = 0;
58
59
            if(!dfs(i+1)) return 0;
60
61
      return 1;
62
63
64
```

## 4.3 Cut Edge and Point

```
1
   Finding cut edges
 2
   The code below works properly because the lemma above (first lemma):
 3
     h[root] = 0
 4
                par[v] = -1
 5
                          dfs (v):
 6
                          d[v] = h[v]
 7
                                 color[v] = gray
 8
                                           for u in adj[v]:
 9
                                               if color[u] == white
                                                 then par[u] = v and dfs(u) and d[v] = min(
10
                                                    d[v], d[u]
11
                                                     if d[u] > h[v]
12
                                                       then the edge v—u is a cut edge
13
                                                       else if u != par[v])
              then d[v] = min(d[v], h[u])
14
15
                           color[v] = black
16
                                      In this code, h[v] = 1 height of vertex v in the DFS
                                          tree and d[v] = min(h[w] where there is at least
                                          vertex u in subtree of v in the DFS tree where
                                          there is an edge between u and w).
17
18
                                           Finding cut vertices
19
                                           The code below works properly because the lemma
                                              above (first lemma):
20
                                           h[root] = 0
21
                                                     par[v] = -1
22
                                                         dfs (v):
23
                                                         d[v] = h[v]
24
                                                             color[v] = gray
25
                                                       for u in adj[v]:
26
                                                                  if color[u] == white
                                                                    then par[u] = v and dfs(
27
                                                                       u) and d[v] = min(d[v])
                                                                       ], d[u])
28
                                                                          if d[u] >= h[v]
                                                                              and (v != root
                                                                              number_of_children
                                                                              (v) > 1)
                                                                            then the edge \nu
29
                                                                                is a cut
                                                                                vertex
30
                                                                            else if u != par
                                                                                [v])
                    then d[v] = min(d[v], h[u])
31
32
                                 color[v] = black
33
                                             In this code, h[v] = 1 height of vertex v in
                                                the DFS tree and d[\sqrt{n}] = min(h[w]) where
                                                there is at least vertex u in subtree of v
                                                in the DFS tree where there is an edge
                                                between u and w).
```

#### 4.4 Euler Path

```
/* Euler path, by Abreto<m@abreto.net>. */
1
  #define MAXV
                    (1024)
2
                   (MAXV*MAXV)
3
  #define MAXE
4
5
  typedef struct {
6
    int id;
7
     int nxt;
8
    int del;
```

```
9 |} egde_t;
   int front[MAXV];
10
11
   egde_t edg[MAXE];
   int d[MAXV];
13
   int ind[MAXV], outd[MAXV];
14
   int nedges;
15
   void add_edge(int u, int v) {
16
      int newedge = ++nedges;
17
      edg[newedge].id = v;
      edg[newedge].nxt = u[front];
18
19
      edg[newedge].del = 0;
20
      u[front] = newedge;
21
      outd[u]++;
22
      ind[v]++;
23
      d[u]++;
24
      d[v]++;
25
26
   void del_edge(int u, int v) {
27
      int e = 0;
28
      for(e=u[front]; e; e=edg[e].nxt)
29
        if(edg[e].id==v) {
30
          edg[e].del = 1;
          outd[u]--;
31
32
          ind[v]--;
33
          d[u]--;
34
          d[v]=;
35
          return;
36
        }
37
38
39
   int path[MAXV];
40
   int l;
41
42
   void add2path(int u) {
43
      path[l++] = u;
44
45
46
   /* Directed graph */
47
   void euler(int x) {
48
      if(outd[x]) {
49
        int e = 0;
50
        for(e=x[front]; e; e=edg[e].nxt)
51
          if(!edg[e].del) {
52
            int v = edg[e].id;
53
            del_edge(x,v);
54
            euler(v);
55
          }
56
57
      add2path(x);
58
59
60
   /* Undirected graph */
61
   void euler(int x) {
      if(d[x]) {
62
63
        int e = 0;
64
        for(e=x[front]; e; e=edg[e].nxt)
65
          if(!edg[e].del) {
66
            int v = edg[e].id;
67
            del_edge(x,v);
68
            del_edge(v,x);
69
            euler(v);
70
          }
71
      add2path(x);
72
```

## 4.5 Shortest Path

## 4.5.1 Dijkstra

```
/* Shortest Path Dijstra, by Abreto<m@abreto.net>. */
   #include <cstdio>
 3
   #include <set>
 4
   #include <utility>
 5
 6
   using namespace std;
 7
   typedef set< pair<int,int> > spii;
 8
 9
   #define MAXN
                    512
10
   #define MAXV
                     (MAXN*MAXN)
11
12
   struct egde_t {
13
      int id;
14
     int nxt;
15
   };
16
   int front[MAXV];
17
   egde_t edg[MAXV<<3];
18
   int nedges;
19
   void add_edge(int u, int v) {
20
     int newedge = ++nedges;
21
     edg[newedge].id = v;
22
     edg[newedge].nxt = u[front];
23
     u[front] = newedge;
24
   }
25
   int d[MAXV];
26
27
   int vis[MAXN];
28
   int solid[MAXV];
29
30
   int dijstra(int s, int t) {
31
     int v = s[front];
32
     spii q;
33
     q.insert(make_pair(0, s));
     while(!q.empty()) {
34
35
        auto it = q.begin();
36
        int u = it->second;
37
        int v = u[front];
38
        q.erase(it);
39
        solid[u] = 1;
40
        if(u == t) break;
41
        while(v) {
42
          int w = edg[v].id;
43
          if(!solid[w]) {
            if( (0==d[w]) | | (d[u] + 1 < d[w]) ) {
44
45
              q.erase(make_pair(d[w],w));
46
              d[w] = d[u] + 1;
47
              q.insert(make_pair(d[w],w));
48
            }
49
50
          v = edg[v].nxt;
51
52
      return d[t];
53
54
```

#### 4.5.2 Shortest Path Fast Algorithm

```
/* Shortest Path Fast Algorithm, by Abreto<m@abreto.net>. */
   #include <cstdio>
 3
   #include <cstring>
 4
   #include <queue>
 5
   #include <utility>
 7
   using namespace std;
 8
 9
   #define MAXN
                     128
10
11
   struct edge {
12
      int v;
13
      int w;
14
      int n;
15
16
   edge edg[MAXN<<1];</pre>
17
   int nedg;
   int indegree[MAXN];
18
19
   int front[MAXN];
20
   int find_edge(int u, int v) {
21
      int e = u[front];
22
      while(e) {
23
        if(edg[e].v == v) return e;
24
        e = edg[e].n;
25
26
      return 0;
27
28
   void add_edge(int u, int v, int w) {
29
      int e = find_edge(u,v);
      if(0==e) {
30
31
        int newnode = ++nedg;
        edg[newnode].v = v;
32
33
        edg[newnode].w = w;
34
        eda[newnode].n = u[front];
35
        u[front] = newnode;
36
        indegree[v]++;
37
      } else {
38
        edg[e].w = (w < edg[e].w)?w:(edg[e].w);
39
   }
40
41
42
   int n;
43
44
   char inq[MAXN];
45
   int vis[MAXN];
   int d[MAXN];
46
47
    int spfa(int s) { /* return 1 if fuhuan exists. */
48
      queue<int> q;
     memset(inq, 0, sizeof(inq));
49
50
      memset(d, -1, sizeof(d));
51
      memset(vis, 0, sizeof(vis));
52
      d[s] = 0;
53
      inq[s] = 1;
54
      q.push(s);
55
      while(!q.empty()) {
56
        int u = q.front();
57
        q.pop();
58
        printf("proc<sub>\\\\</sub>d..\n", u);
59
        inq[u] = 0;
60
        if(vis[u]++ > n)
61
          return 1;
```

```
62
        for(int e = front[u]; e; e = edg[e].n) {
63
          int v = edg[e].v, w = edg[e].w;
64
          if(-1=d[v] | | d[u] + w < d[v]) 
65
            d[v] = d[u] + w;
            if(!inq[v]) {
66
              inq[v] = 1;
67
              q.push(v);
68
69
70
          }
71
        }
72
73
      return 0;
74
   4.5.3 K-th shortest path
 1 | / **
 2
    * poj
 3
    * Problem#2449
 4
    * Accepted
 5
    * Time: 250ms
 6
    * Memory: 9252k
 7
    */
 8
   #include <iostream>
 9
   #include <fstream>
10
   |#include <sstream>
   #include <algorithm>
11
12
   #include <cstdio>
   #include <cstdlib>
13
14
   |#include <cstring>
15
   |#include <ctime>
   #include <cctype>
16
17
   #include <cmath>
   |#include <vector>
19
   #include <queue>
   #include <stack>
20
21
   #include <map>
22
   #include <set>
23
   #include <bitset>
24
   using namespace std;
25
   typedef bool boolean;
26
27
   typedef class Edge {
28
   public:
29
      int end;
30
     int next;
31
     int w;
32
      Edge(int end = 0, int next = -1, int w = 0):end(end), next(next), w(w) {
33
                                                                                          }
34
   } Edge;
35
36
   const int N = 1e3, M = 1e5;
37
   typedef class MapManager {
38
39
   public:
40
      int cnt;
41
      int h[N + 5];
42
     Edge edge[M + 5];
43
44
     MapManager() {
     MapManager(int n):cnt(-1) {
45
                  h = new int[(n + 1)];
46
47
   //
                  edge = new Edge[(m + 1)];
```

```
48
        memset(h, -1, sizeof(int) * (n + 1));
 49
       }
 50
 51
       inline void addEdge(int u, int v, int w) {
 52
         edge[++cnt] = (Edge(v, h[u], w));
 53
                   h[u] = (signed)edge.size() - 1;
 54
         h[u] = cnt;
 55
 56
 57
       inline int start(int node) {
 58
         return h[node];
 59
 60
 61
       Edge& operator [] (int pos) {
 62
         return edge[pos];
 63
 64
     } MapManager;
 65
    #define m_endpos -1
 66
 67
    int n, m;
 68
    MapManager g;
 69
    MapManager rg;
 70
     int s, t, k;
    int ds[N + 5];
 71
 72
 73
    inline void init() {
 74
       scanf("%d%d", &n, &m);
 75
       memset(g.h, -1, sizeof(int) * (n + 1));
       memset(rg.h, -1, sizeof(int) * (n + 1));
 76
       for(int i = 1, u, v, w; i \le m; i++) {
 77
         scanf("%d%d%d", &u, &v, &w);
 78
 79
         g.addEdge(u, v, w);
 80
         rg.addEdge(v, u, w);
 81
      scanf("%d%d%d", &s, &t, &k);
 82
 83
           ds = new int[(n + 1)];
 84
    }
 85
    #define g rg
 86
 87
    #define f ds
 88
    #define que que1
 89
    boolean vis[N + 5];
 90
    queue<int> que;
 91
    boolean spfa(int s, int t) {
       memset(f, 0x7f, sizeof(int) * (n + 1));
 92
 93
       memset(vis, false, sizeof(boolean) * (n + 1));
 94
       que.push(s);
 95
       f[s] = 0;
 96
       while(!que.empty()) {
 97
         int e = que.front();
 98
         que.pop();
 99
         vis[e] = false;
100
         for(int i = g.start(e); i != m_endpos; i = g[i].next) {
101
           int& eu = g[i].end;
                   cout << e << " " << eu << " " << i <<endl;
102
     //
103
           if(f[e] + g[i].w < f[eu]) {
104
             f[eu] = f[e] + g[i].w;
105
             if(!vis[eu]) {
106
               que.push(eu);
107
               vis[eu] = true;
             }
108
           }
109
110
         }
       }
111
```

```
112
      return (f[t] != 0x7f7f7f7f);
113
    }
    #undef g
114
115
    #undef f
    #undef que
116
117
118
     typedef class Status {
119
    public:
120
       int node;
121
       int dis;
122
       int priority;
123
124
       Status(int node = 0, int dis = 0):node(node), dis(dis), priority(h()) {
                                                                                          }
125
126
       int h() {
127
         return dis + ds[node];
128
129
130
       boolean operator < (Status b) const {
131
         return priority > b.priority;
132
133
     } Status;
134
135
     int label[N + 5];
    priority_queue<Status> que;
136
137
     int bfs(int s, int t) {
138
       if(s == t)
                     k++;
139
           label = new int[(n + 1)];
140
       memset(label, 0, sizeof(int) * (n + 1));
141
       que.push(Status(s, 0));
142
       while(!que.empty()) {
         Status e = que.top();
143
144
         que.pop();
145
         label[e.node]++;
146
         if(e.node == t && label[e.node] == k)
147
           return e.dis;
         for(int i = g.start(e.node); i != m_endpos; i = g[i].next) {
148
149
           if(label[q[i].end] < k)
150
             que.push(Status(g[i].end, e.dis + g[i].w));
151
         }
152
153
       return -1;
154
155
156
     inline void solve() {
157
       if(!spfa(t, s)) {
158
         puts("-1");
159
         return;
160
       printf("%d", bfs(s, t));
161
162
163
164
    int main() {
       init();
165
       solve();
166
167
       return 0;
168 | }
```

## 4.6 Maxflow

```
1 |/* Max Flow Problem, by Abreto<m@abreto.net> */
```

```
3
   #include <bits/stdc++.h>
 4
   using namespace std;
 5
   #define MAXV
                     (100000)
 7
   #define MAXE
                     (1000000)
 8
   struct edge {
 9
      static int N;
10
      int v, w;
11
      edge *n;
12
      edge(void):v(0),w(0),n(NULL) {}
13
      edge(int vv, int ww, edge *nn):v(vv),w(ww),n(nn) {}
14
15
   int nE;
   edge E[MAXE];
16
17
    edge *front[MAXV];
18
   void add_edge(int u, int v, int w) {
19
      int ne = ++nE;
20
      E[ne] = edge(v, w, u[front]);
21
      u[front] = \&(E[ne]);
22
23
   edge *find_edge(int u, int v) {
24
      for(edge *e = u[front]; e != NULL; e = e->n)
25
        if(e\rightarrow v == v)
26
          return e;
27
      return NULL;
28
29
   void grant_e(int u, int v, int w) {
30
      edge *e = find_edge(u, v);
31
      if(NULL == e) add_edge(u,v,w);
32
      else e\rightarrow w += w;
33
   }
34
35
   int vis[MAXV];
36
   int path[MAXV];
37
    int dfs(int u, int t) {
38
      vis[u] = 1;
      if(u == t) return 1;
39
40
      for(edge *e = u[front]; e != NULL; e = e->n) {
41
        int v = e \rightarrow v;
42
        if(!vis[v] \&\& e->w \&\& dfs(v,t)) {
43
          path[u] = v;
44
          return 1;
45
        }
46
      }
47
      return 0;
48
49
   int find_path(int s, int t) {
50
      memset(vis, 0, sizeof(vis));
51
      return dfs(s,t);
52
53
   int max_flow(int s, int t) {
54
      int flow = 0;
55
      while(find_path(s,t)) {
        int i = 0;
56
        int minf = find_edge(s,path[s])->w;
57
58
        for(i = path[s]; i != t; i = path[i])
59
          minf = min(minf, find_edge(i,path[i])->w);
60
        for(i = s; i != t; i = path[i]) {
61
          grant_e(i, path[i], -minf);
62
          grant_e(path[i], i, minf);
63
64
        flow += minf;
65
66
      return flow;
```

```
67
   |}
68
69
    /* Dinic */
70
    #define N 1000
 71
    #define INF 100000000
 72
73
    struct Edge {
74
      int from, to, cap, flow;
 75
      Edge(int u,int v,int c,int f):from(u),to(v),cap(c),flow(f) {}
76
    };
77
78
    struct Dinic {
79
      int n,m,s,t;//结点数,边数(包括反向弧),源点编号,汇点编号
80
      vector<Edge>edges;//边表, dges[e]和dges[e^1]互为反向弧
      vector<int>G[N];//邻接表,G[i][j]表示结点i的第j条边在e数组中的编号
81
82
      bool vis[N]; //BFS的使用
83
      int d[N]; //从起点到i的距离
84
      int cur[N]; //当前弧下标
85
86
      void addedge(int from,int to,int cap) {
87
        edges.push_back(Edge(from, to, cap, 0));
88
        edges.push_back(Edge(to,from,0,0));
 89
        int m=edges.size();
90
        G[from].push_back(m-2);
91
        G[to].push_back(m-1);
92
      }
93
94
      bool bfs() {
95
        memset(vis,0,sizeof(vis));
96
        queue<int>Q;
97
        Q.push(s);
98
        d[s]=0;
99
        vis[s]=1;
100
        while(!Q.empty()) {
101
          int x=Q.front();
102
          Q.pop();
103
          for(int i=0; i<G[x].size(); i++) {
104
            Edge&e=edges[G[x][i]];
105
            if(!vis[e.to]&&e.cap>e.flow) { //只考虑残量网络中的弧
106
              vis[e.to]=1;
107
              d[e.to]=d[x]+1;
108
              Q.push(e.to);
109
           }
          }
110
111
112
113
        return vis[t];
      }
114
115
      int dfs(int x,int a) { //x表示当前结点, a表示目前为止的最小残量
116
117
        if(x==t||a==0)return a;//a等于0时及时退出,此时相当于断路了
118
        int flow=0,f;
119
        for(int&i=cur[x]; i<G[x].size(); i++) { //从上次考虑的弧开始, 注意要使用引用, 同
           时修改cur[x]
120
          Edge&e=edges[G[x][i]];//e是一条边
121
          if(d[x]+1==d[e.to]&&(f=dfs(e.to,min(a,e.cap-e.flow)))>0)  {
122
            e.flow+=f;
123
            edges[G[x][i]^1].flow==f;
124
            flow+=f;
125
            a=f;
126
            if(!a)break;//a等于0及时退出, 当a!=0,说明当前节点还存在另一个曾广路分支。
127
128
          }
        }
129
```

```
130
        return flow;
      }
131
132
133
      int Maxflow(int s,int t) { //主过程
134
        this->s=s,this->t=t;
135
         int flow=0;
136
        while(bfs()) { //不停地用bfs构造分层网络, 然后用dfs沿着阻塞流增广
137
           memset(cur,0,sizeof(cur));
138
           flow+=dfs(s,INF);
139
140
         return flow;
141
      }
142
    };
143
144
    /* ISAP */
145
    struct Edge {
146
      int from, to, cap, flow;
147
    };
148
    const int maxn=650;
149
    const int INF=0x3f3f3f3f3f;
150
    struct ISAP {
151
       int n,m,s,t;//结点数, 边数(包括反向弧), 源点编号, 汇点编号
152
      vector<Edge>edges;
153
      vector<int>G[maxn];
154
      bool vis[maxn];
155
      int d[maxn];
156
      int cur[maxn];
157
      int p[maxn];
158
      int num[maxn];
159
      void AddEdge(int from,int to,int cap) {
160
         edges.push_back((Edge) {
161
           from, to, cap, 0
162
         });
163
         edges.push_back((Edge) {
164
           to, from, 0,0
165
        });
166
        m=edges.size();
167
         G[from].push_back(m-2);
168
         G[to].push_back(m-1);
169
170
      bool RevBFS() {
171
        memset(vis,0,sizeof(vis));
172
        queue<int>Q;
173
        Q.push(t);
        d[t]=0;
174
        vis[t]=1;
175
176
        while(!Q.empty()) {
177
           int x=Q.front();
178
           Q.pop();
           for(int i=0; i<G[x].size(); i++) {
179
             Edge &e =edges[G[x][i]^1;
180
181
             if(!vis[e.from]&&e.cap>e.flow) {
182
               vis[e.from]=1;
183
               d[e.from]=d[x]+1;
184
               Q.push(e.from);
185
186
           }
187
        }
188
        return vis[s];
189
190
      int Augment() {
191
        int x=t, a=INF;
192
        while(x!=s) {
193
           Edge &e = edges[p[x]];
```

```
194
           a= min(a,e.cap-e.flow);
195
           x=edges[p[x]].from;
196
         }
197
         x=t;
198
         while(x!=s) {
199
           edges[p[x]].flow+=a;
200
           edges[p[x]^1].flow=a;
201
           x=edges[p[x]].from;
202
203
         return a;
204
205
       int Maxflow(int s,int t,int n) {
206
         this->s=s,this->t=t,this->n=n;
207
         int flow=0;
208
         RevBFS();
209
         memset(num,0,sizeof(num));
210
         for(int i=0; i<n; i++) {
211
           num[d[i]]++;
212
213
         int x=s;
214
         memset(cur,0,sizeof(cur));
215
         while(d[s]<n) {</pre>
216
           if(x==t) {
217
             flow+=Augment();
218
             x=s;
219
220
           int ok=0;
221
           for(int i=cur[x]; i<G[x].size(); i++) {
222
             Edge &e =edges[G[x][i]];
223
             if(e.cap>e.flow&d[x]==d[e.to]+1) {
224
               ok=1;
225
               p[e.to]=G[x][i];
226
               cur[x]=i;
227
               x=e.to;
228
               break;
229
             }
230
           }
231
           if(!ok) {
232
             int m=n-1;
233
             for(int i=0; i<G[x].size(); i++) {
234
               Edge &e =edges[G[x][i]];
235
               if(e.cap>e.flow)
236
                 m=min(m,d[e.to]);
237
             if(--num[d[x]]==0)
238
239
               break;
240
             num[d[x]=m+1]++;
241
             cur[x]=0;
242
             if(x!=s)
243
               x=edges[p[x]].from;
244
           }
245
246
         return flow;
247
248
249
     int main() {
250
       int n,m,a,b,c,res;
251
       while(scanf("%d%d",&m,&n)!=EOF) {
252
         ISAP tmp;
253
         for(int i=0; i<m; i++) {
254
           scanf("%d%d%d",&a,&b,&c);
255
           tmp.AddEdge(a,b,c);
256
257
         res=tmp.Maxflow(1,n,n);
```

```
258 | printf("%d\n",res);
259 | }
260 | return 0;
261 |}
```

## 4.7 Strongly Connected Component

```
//* Kosaraju */
 2
   #define MAXN
                     10010
 3
   #define MAXM
                     100010
 4
   struct edge {
 5
      int v;
 6
      edge *n;
 7
      edge(void):v(0),n(NULL) {}
 8
      edge(int vv, edge *nn):v(vv),n(nn) {}
 9
10
   int nE;
   edge E[MAXM<<1];</pre>
11
12
   edge *ori[MAXN];
13
   edge *inv[MAXN];
14
   void add_edge(edge *front[], int u, int v) {
15
      int ne = ++nE;
16
      E[ne] = edge(v, u[front]);
17
      u[front] = \&(E[ne]);
18
19
   void connect(int u, int v) {
20
      add_edge(ori, u, v);
21
      add_edge(inv, v, u);
22
23
24
   int vis[MAXN];
25
    int vst[MAXN];
   void first_dfs(int u, int &sig) {
26
27
      vis[u] = 1;
      for(edge *e = u[ori]; e; e = e \rightarrow n)
28
29
        if(!vis[e->v])
30
          first_dfs(e->v, sig);
31
      vst[++sig] = u;
32
   int mark[MAXN];
33
34
   void second_dfs(int u, int sig) {
35
      vis[u] = 1;
36
      mark[u] = sig;
37
      for(edge *e = u[inv]; e; e = e \rightarrow n)
38
        if(!vis[e->v])
39
          second_dfs(e->v, sig);
40
41
   int N, M;
42
43
44
    int kosaraju(void) {
45
      int i;
46
      int sig = 0;
      for(i = 0; i \le N; ++i) vis[i] = 0;
47
48
      for(i = 1; i <= N; ++i) {
49
        if(!vis[i])
50
          first_dfs(i, sig);
51
      }
52
      sig = 1;
      for(i = 0; i \le N; ++i) vis[i] = 0;
53
      for(i = N; i > 0; --i) {
54
55
        if(!vis[vst[i]])
```

```
56
           second_dfs(vst[i], sig++);
 57
 58
       for(i = 1; i \le N; ++i)
 59
         if(mark[i] != 1)
 60
            return 0;
 61
       return 1;
 62
 63
 64
 65
     void clear(void) {
 66
       nE = 0;
 67
       for(int i = 0; i <= N; ++i) {
 68
         ori[i] = inv[i] = NULL;
 69
 70
     }
 71
 72
     /* Tarjan */
 73
     #define MAXN
                       10010
 74
     #define MAXM
                       100010
 75
     struct edge {
 76
       int v;
 77
       edge *n;
       edge(void):v(0),n(NULL) {}
 78
 79
       edge(int vv, edge *nn):v(vv),n(nn) {}
 80
     };
 81
     typedef edge *ep;
 82
     int nE;
 83
     edge E[MAXM];
 84
     edge *front[MAXN];
 85
     void add_edge(int u, int v) {
 86
       int ne = ++nE;
       E[ne] = edge(v, u[front]);
 87
 88
       u[front] = \&(E[ne]);
 89
     }
 90
 91
     int mark[MAXN];
 92
     int dfn[MAXN], low[MAXN];
 93
     int stk[MAXN];
 94
     int stk_top;
 95
 96
     void tardfs(int u, int stamp, int &scc) {
 97
       mark[u] = 1;
 98
       dfn[u] = low[u] = stamp;
 99
       stk[stk\_top++] = u;
       for(ep e = u[front]; e; e = e \rightarrow n) {
100
         if(\emptyset == mark[e \rightarrow v]) tardfs(e \rightarrow v, ++stamp, scc);
101
102
         if(1 == mark[e \rightarrow v]) low[u] = min(low[u], low[e \rightarrow v]);
103
104
       if(dfn[u] == low[u]) {
105
         ++SCC;
106
107
            low[stk[stk_top-1]] = scc;
           mark[stk[stk_top-1]] = 2;
108
109
         } while(stk[(stk_top--)-1] != u);
110
111
112
113
     int tarjan(int n) {
114
       int scc = 0, lay = 1;
115
       for(int i = 1; i <= n; ++i)
116
         if(0 == mark[i])
117
           tardfs(i, lay, scc);
       return scc;
118
119 | }
```

```
120
121
    int N, M;
122
123
     void clear(void) {
124
       nE = 0;
125
       for(int i = 0; i <= N; ++i) {
126
         i[front] = NULL;
         mark[i] = low[i] = 0;
127
128
129
       stk\_top = 0;
130
131
132
    /* Garbow */
133
    #define MAXN
                     10010
134
    #define MAXM
                     100010
135
136
    struct edge {
137
       int v;
138
       edge *n;
139
       edge(void):v(0),n(NULL) {}
140
       edge(int vv, edge *nn):v(vv),n(nn) {}
141
142
     typedef edge *ep;
143
144
    int nE;
145
    edge E[MAXM];
146
    edge *front[MAXN];
147
    void add_edge(int u, int v) {
148
       int ne = ++nE;
149
       E[ne] = edge(v, u[front]);
150
       u[front] = \&(E[ne]);
151
    }
152
    int stk1[MAXN], stk1t;
153
154
     int stk2[MAXN], stk2t;
155
     int low[MAXN], belg[MAXN];
156
157
     void garbowdfs(int u, int lay, int &scc) {
158
       stk1[++stk1t] = u;
159
       stk2[++stk2t] = u;
160
       low[u] = ++lay;
161
       for(ep e=u[front]; e; e = e->n) {
162
         if(!low[e->v]) garbowdfs(e->v, lay, scc);
163
         else if (0 == belg[e->v])
164
           while(low[stk2[stk2t]] > low[e->v])
165
             ---stk2t;
166
167
       if(stk2[stk2t] == u) {
168
         stk2t--;
169
         SCC++;
170
         do {
171
           belg[stk1[stk1t]] = scc;
         } while(stk1[stk1t--] != u);
172
173
174
175
176
     int grabow(int n) {
177
       int i;
178
       int scc = 0, lay = 0;
179
       for(i = 0; i <= n; ++i) {
180
         belg[i] = low[i] = 0;
181
182
       for(i = 1; i \le n; ++i)
183
         if(0 == low[i])
```

```
184
           garbowdfs(i, lay, scc);
185
       return scc;
186
     }
187
188
     int N, M;
189
190
     void clear(void) {
191
       nE = 0;
192
       for(int i = 0; i <= N; ++i) {
193
         front[i] = NULL;
194
195 | }
```

## 4.8 Perfect elimination ordering

求弦图的最大团数/最小色数的时候,只要在完美消除序列上从后往前贪心染色即可。 而求最大独立集/最小团覆盖的时候,只要在完美消除序列上从前往后贪心取点即可。

```
1
   /**
 2
    * BZ0J 1006
 3
    * [HN0I2008] 神奇的国度
    * 最大势法求完美消除序列
 5
    * by Abreto<m@abreto.net>.
    **/
 6
 7
   #include <cassert>
   #include <cstdio>
9
   #include <vector>
   #include <bitset>
10
11
   #include <algorithm>
12
13 using namespace std;
14
   typedef vector<int> vi;
15
   typedef vi::iterator vii;
16
   #define pb push_back
17
   #define MAXN 10100
   #define MAXM 1000100
18
19
20
   int n;
21
   vi g[MAXN];
22
   int ans;
23
24
   struct node_t {
25
     int v;
26
     node_t *nxt;
27
   } node[MAXM << 2];</pre>
28
   |int used;
29
   |node_t *new_node(void) {
      return node + (used ++);
30
31
   }
32
33
   node_t *f[MAXN]; /* head */
34
   void lkto(int pos, int item) {
35
     node_t *t = new_node();
36
     t\rightarrow v = item;
37
      t->nxt = f[pos];
38
     f[pos] = t;
39
40
41
   |int usedby[MAXN];
42
   |int color[MAXN];
43
   bitset<MAXN> added;
44
   |int label[MAXN], max_label;
45 | void mcs(void) {
```

```
46
     for (int i = 1; i \le n; i++) lkto(0, i);
47
     for (int i = n; i > 0; i—) {
48
        node_t *cur = f[max_label];
49
        assert(cur != NULL);
        while (added.test(cur->v)) { /* already added */
50
51
          cur = cur->nxt;
52
          while (NULL == cur)
53
            cur = f[ --max_label ];
54
55
        f[ max_label ] = cur->nxt;
56
        while (max_label && NULL == f[max_label]) max_label—;
57
        int u = cur -> v;
58
        added.set(u);
59
        /* the i-th is u */
        for (vii it = g[u].begin(); it != g[u].end(); it++) {
60
61
          int v = *it;
62
          if (!added.test(v)) {
            label[v] ++;
63
            max_label = max(max_label, label[v]);
64
            lkto(label[v], v);
65
66
67
          usedby[color[v]] = i;
68
69
        for (int j = 1; j <= n; j++)
70
71
          if (usedby[j] != i) {
72
            color[u] = j;
73
            break;
74
75
        ans = max(ans, color[u]);
76
     }
77
   }
78
79
   int main(void) {
80
     int m;
     scanf("%d%d", &n, &m);
81
82
     while (m--) {
83
        int ai, bi;
        scanf("%d%d", &ai, &bi);
84
85
        g[ai].pb(bi);
86
        g[bi].pb(ai);
87
     }
88
     mcs();
89
     printf("%d\n", ans);
90
      return 0;
91 |}
```

# 5 Math

#### 5.1 Euler Function

```
| / * Euler function phi(x), by Abreto<m@abreto.net>. */
 2
 3
   #define MAXX
                    3000000
 4
 5
   int phi[MAXX];
   void get_euler(void) {
 6
 7
      int i = 0, j = 0;
     phi[1] = 1;
 8
      for(i = 2; i < MAXX; ++i)
 9
10
        if(!phi[i])
          for(j = i; j < MAXX; j += i) {
11
```

```
12 | if(!phi[j]) phi[j] = j;
13 | phi[j] = phi[j]/i * (i-1);
14 | }
15 |}
```

## 5.2 Möbius Function

```
1
   void sieve() {
 2
      fill(isPrime, isPrime + maxn, 1);
 3
     mu[1] = 1, num = 0;
 4
     for (int i = 2; i < maxn; ++i) {
 5
        if (isPrime[i]) primes[num++] = i, mu[i] = -1;
 6
        static int d;
 7
        for (int j = 0; j < num && (d = i * primes[j]) < maxn; ++j) {
          isPrime[d] = false;
 8
 9
          if (i % primes[j] == 0) {
10
            mu[d] = 0;
            break;
11
12
          else mu[d] = -mu[i];
13
14
     }
15 | }
```

## 5.3 Number Theory Inverse

```
|#include <bits/stdc++.h>
 1
 2
   using namespace std;
 3
 4
   const int n=10000000;
                               /* */
 5
   const long long mod=1e9+7; /* prime required. */
 6
 7
   long long fact[n],fiv[n],inv[n];
 8
 9
   int main() {
10
      fact[0]=fact[1]=1;
11
      fiv[0]=fiv[1]=1;
12
      inv[1]=1;
      for (int i=2; i<n; i++) {
13
        fact[i]=fact[i-1]*i%mod;
14
15
        inv[i]=(mod-mod/i)*inv[mod%i]%mod;
16
        fiv[i]=inv[i]*fiv[i-1]%mod;
17
18
      for (int i=1; i<n; i++) {
        if (fact[i]*fiv[i]%mod!=1) printf("fact_wrong:_wd\n",i);
19
                                     printf("intv_wrong:_%d\n",i);
20
        if (inv[i]*i%mod!=1)
21
22
     cout<<"complete"<<endl;</pre>
23
      return 0;
24
```

## 5.4 Chinese Remainder Theorem

```
typedef long long int ll;
 6
 7
 8
   11 quickpow(ll a, ll b, ll mod) {
9
     ll ret = 1, base = a;
10
     while(b > 0) {
11
        if(b \& 1) ret = (ret * base) % mod;
12
        base = (base * base) % mod;
13
        b >>= 1;
14
15
     return ret;
16
17
18
   11 N;
19
   ll a[MAXN], m[MAXN]; /* a and m is indexed from 0. */
   11 x, M;
20
21
22
   void naive_crt(void) {
23
     int i = 0;
24
     11 Mi[MAXN], nMi[MAXN];
25
     11 t[MAXN];
26
27
     M = 1;
     for(i = 0; i < N; ++i)
28
29
        M *= a[i];
     for(i = 0; i < N; ++i)
30
31
       Mi[i] = M / a[i];
32
     get_euler();
33
     for(i = 0; i < N; ++i)
        nMi[i] = quickpow(Mi[i], phi[a[i]]-1, a[i]);
34
35
     for(i = 0; i < N; ++i)
        t[i] = ((a[i] * Mi[i]) % M) * nMi[i] % M;
36
     for(i = 0; i < N; ++i)
37
        x = (x + t[i]) % M;
38
39 | }
```

## 5.5 Linear congruences

```
|#include <cstdio>
 1
 2
   #include <cassert>
 3
   #include <cstdlib>
 4
 5
   using namespace std;
 6
 7
   class mod_equ_resolver {
 8
     typedef long long int 11;
 9
     ll a, m;
10
     inline void gurantee(void) {
11
        if ( a < 0 ) {
12
          11 k = (-a) / m;
13
          a += (k + 111) * m;
14
          a = (a + m) \% m;
15
        } else {
16
          a \% = m;
17
18
        // printf("x = %lld (mod %lld)\n",a, m);
19
   public:
20
21
     mod_equ_resolver(void) {
        a = 011;
22
23
        m = 111;
24
25
     ll exgcd(ll m, ll n, ll &x, ll &y) {
```

```
26
        if (0 == n) {
27
          x = 1;
28
          y = 0;
29
          return m;
30
31
        ll g = exgcd(n, m \% n, x, y);
32
        ll t = x;
33
        x = y;
34
        y = t - m / n * y;
35
        return g;
36
      int onemore(ll a2, ll m2) {
37
38
        11 x, y;
39
        ll g = exgcd(m, m2, x, y);
40
        assert(x*m+y*m2==g);
41
        a2 = (a2 + m2) \% m2;
42
        if ( abs(a2 - a) \% g ) return -1;
43
        ll newm = m / g * m2;
44
        11 newa = a + (a2 - a) / g * x * m;
45
        a = newa;
46
        m = newm;
47
        gurantee();
48
        return 0;
49
50
      ll resolve(void) {
51
        return a;
52
53 | };
    Usage: For
                                           x \equiv a_1 \mod m_1
                                           x \equiv a_2
                                                   \mod m_2
                                           x \equiv a_k
                                                  \mod m_k
   run
 1 |mod_equ_resolver solver;
 2
   for (int i = 1; i <= k; i++)
        solver.onemore(a[i], m[i]);
 3
   then the solution is
                                     x \equiv solver.a \mod solver.m
   5.6 FFT
 1
   |#include <cmath>
 2
   using namespace std;
 3
   namespace fft {
 4
   #define eps (1e-9)
 5
   template < typename T = double >
 6
   struct dbl {
 7
      Tx;
      dbl(void):x(0.0) {}
 8
 9
      template <typename U>
10
      dbl(U a):x((T)a) {}
11
      inline char sgn(void) {
12
        return ((x = -eps) & (x = eps))?(0):((x > eps)?(1):(-1));
13
14
      inline T tabs(void) {
15
        return ((x \ge -eps) & (x \le -eps))?(0.0):((x \ge -eps)?(x):(-x));
16
```

inline dbl abs(void) {

17

```
18
        return dbl(tabs());
19
20
     template <typename U> inline dbl &operator=(const U b) {
21
22
        return (*this);
23
     inline T *operator&(void) {
24
25
        return &x;
26
27
     inline dbl operator—(void) const {
28
        return dbl(-x);
29
     inline dbl operator+(const dbl &b) const {
30
31
        return dbl(x+b.x);
32
33
     inline dbl operator—(const dbl &b) const {
34
        return dbl(x-b.x);
35
     inline dbl operator*(const dbl &b) const {
36
37
        return dbl(x*b.x);
38
39
     inline dbl operator/(const dbl &b) const {
40
        return dbl(x/b.x);
41
42
     template <typename U> inline dbl operator^(const U &b) const {
43
        T ret=1.0, base=x;
44
        while(b) {
45
          if(b&1)ret*=base;
46
          base*=base;
47
          b>>=1;
48
49
        return dbl(ret);
50
51
     inline dbl operator+=(const dbl &b) {
52
        return dbl(x+=b.x);
53
54
     inline dbl operator-=(const dbl &b) {
55
        return dbl(x=b.x);
56
57
     inline dbl operator*=(const dbl &b) {
58
        return dbl(x*=b.x);
59
60
     inline dbl operator/=(const dbl &b) {
        return dbl(x/=b.x);
61
62
     template <typename U> inline dbl operator^=(const U &b) {
63
64
        dbl tmp=(*this)^b;
65
        *this=tmp;
66
        return tmp;
67
     inline bool operator==(const dbl &b) const {
68
69
        return (0 == ((*this)-b).sgn());
70
     inline bool operator!=(const dbl &b) const {
71
72
        return (0 != ((*this)-b).sgn());
73
74
     inline bool operator<(const dbl &b) const {</pre>
75
        return (-1 == ((*this)-b).sgn());
76
77
     inline bool operator<=(const dbl &b) const {</pre>
78
        return (((*this)==b) || ((*this)<b));
79
80
     inline bool operator>(const dbl &b) const {
81
        return (b < (*this));
```

```
82
 83
      inline bool operator>=(const dbl &b) const {
 84
         return (((*this)==b) || ((*this)>b));
 85
      template <typename U> inline operator U() const {
 86
 87
         return (U)x;
 88
 89
       inline char operator[](unsigned n) {
         if(n \ge 0) {
 90
 91
           long long int ret=x;
 92
           while(n—) {
93
             ret/=10;
 94
 95
           return (ret%10);
 96
         } else {
           T ret=x;
 97
 98
           n=-n;
 99
           while(n-)ret*=10.0;
100
           return ((long long int)ret)%10;
101
         }
102
103
104
     template <typename T>
     struct Complex {
105
106
      T x,y;
              /* x + iy */
107
       Complex(void):x(T()),y(T()) {}
108
      Complex(T xx):x(xx) {}
109
      Complex(T xx,T yy):x(xx),y(yy) {}
       inline Complex operator—(void) const {
110
111
         return Complex(-x,-y);
112
113
      inline Complex operator+(const Complex& b) const {
114
         return Complex(x+b.x,y+b.y);
115
116
      inline Complex operator—(const Complex& b) const {
117
         return Complex(x-b.x,y-b.y);
118
119
      inline Complex operator*(const Complex& b) const {
120
         return Complex(x*b.x-y*b.y,x*b.y+y*b.x);
121
122
      inline Complex operator/(const Complex& b) const {
123
         T bo=b.x*b.x+b.y*b.y;
124
         return Complex((x*b.x+y*b.y)/bo,(y*b.x-x*b.y)/bo);
125
126
      inline Complex& operator+=(const Complex& b) {
127
         Complex tmp=(*this)+b;
128
         (*this)=tmp;
129
         return (*this);
130
131
      inline Complex& operator—=(const Complex& b) {
132
         Complex tmp=(*this)_b;
133
         (*this)=tmp;
134
         return (*this);
135
136
      inline Complex& operator*=(const Complex& b) {
137
         Complex tmp=(*this)*b;
138
         (*this)=tmp;
139
         return (*this);
140
141
      inline Complex& operator/=(const Complex& b) {
142
         Complex tmp=(*this)/b;
143
         (*this)=tmp;
144
         return (*this);
145
      }
```

```
146
      inline friend Complex operator+(const T& a, const Complex& b) {
147
         return Complex(a)+b;
148
149
      inline friend Complex operator—(const T& a, const Complex& b) {
150
         return Complex(a)-b;
151
152
      inline friend Complex operator*(const T& a, const Complex& b) {
153
         return Complex(a)*b;
154
      inline friend Complex operator/(const T& a, const Complex& b) {
155
156
         return Complex(a)/b;
157
158
    typedef dbl<> Double;
159
    typedef Complex<Double> ComplexD;
160
161
    typedef long long int ll;
162
    const int maxn = 2000000; /* !! */
163
    const Double pi(acos(-1.0));
164
    void build(ComplexD _P□, ComplexD P□, int n, int m, int curr, int &cnt) {
165
      if(m == n) {
166
167
         _P[curr] = P[cnt++];
168
      } else {
169
         build(_P, P, n, m*2, curr, cnt);
170
         build(_P, P, n, m*2, curr+m, cnt);
171
172
173
    void FFT(ComplexD P[], int n, int oper) { /* n should be 2^k. */
174
175
       static ComplexD _P[maxn];
       int cnt = 0;
176
      build(_P, P, n, 1, 0, cnt);
177
178
       copy(P, P+n, P);
       for(int d = 0; (1 << d) < n; ++d) {
179
180
         int m = 1 << d;
181
         int m2 = m*2;
182
         Double p0 = pi / m * oper;
183
         ComplexD unit_p0(cos(p0.x), sin(p0.x));
         for(int i = 0; i < n; i += m2) {
184
185
           ComplexD unit(1,0);
           for(int j = 0; j < m; ++j) {
186
             ComplexD &P1 = P[i+j+m], &P2 = P[i+j];
187
188
             ComplexD t = unit * P1;
             P1 = P2 - t;
189
190
             P2 = P2 + t;
191
             unit *= unit_p0;
192
           }
         }
193
194
195
      if(-1 == oper) {
196
         for(int i = 0; i < n; ++i)
197
           P[i] /= Double(n);
198
199
200
    5.7 NTT
    |#include<bits/stdc++.h>
```

2

#define ll long long
const int N=262144;

const ll MOD=50000000001507329LL;//998244353 1004535809

```
5
   using namespace std;
 6
   int n,m;
 7
   ll\ a[N],b[N],x[N],y[N];
   ll wn[25];
   ll Mul(ll x,ll y) { //乘法超ll用快速乘,主函数也需要用
 9
10
      ll ans=(x*y-(ll)((long double)x/MOD*y+1e-8)*MOD);
11
      return ans<0?ans+MOD:ans;
12
13
   ll Qpow(ll a, ll b, ll M) {
14
      ll\ ans=1;
15
      a\%=M;
      while(b) {
16
17
        if(b&1) ans=Mul(ans,a);
        a=Mul(a,a);
18
19
        b>>=1;
20
21
      return ans;
22
23
   void Getwn() { //主函数预处理getwn()
24
      for(int i=0; i<25; i++) {
25
        wn[i]=Qpow(3,(MOD-1)/(1<< i),MOD);
26
27
    void NTT(ll *x,int n,int rev) {
28
29
      int i,j,k,ds;
30
      ll w,u,∨;
31
      for(i=1, j=n>>1, k=n>>1; i<n-1; i++, k=n>>1) {
32
        if(i<j) swap(x[i],x[j]);
33
        while(j >= k) j == k, k >>= 1;
34
        if(j < k) j += k;
35
36
      for(i=2,ds=1; i<=n; i<<=1,ds++) {
37
        for(j=0; j<n; j+=i) {
38
          w=1;
39
          for(k=j; k< j+i/2; k++) {
40
            u=x[k];
41
            v=Mul(w,x[k+i/2]);
42
            x[k]=(u+v)\%MOD;
            x[k+i/2]=(u-v+MOD)%MOD;
43
44
            w=Mul(w,wn[ds]);
45
          }
        }
46
47
      if(rev==-1) {
48
        for(i=1; i< n/2; i++) swap(x[i],x[n-i]);
49
50
        w=Qpow(n,MOD-2,MOD);
51
        for(i=0; i<n; i++) x[i]=Mul(x[i],w);
      }
52
53
54
   int main() {
55
      Getwn();
      while(~scanf("%d%d",&n,&m)) {
56
        for(int i=0; i<n; i++)scanf("%lld",&a[i]);
57
        for(int i=0; i<m; i++)scanf("%lld",&b[i]);
58
59
        int len=1,s=n+m;
60
        while(len<s)len<<=1;</pre>
61
        for(int i=n; i<len; i++)a[i]=0;
62
        for(int i=m; i<len; i++)b[i]=0;
63
        NTT(a, len, 1);
64
        NTT(b,len,1);
        for(int i=0; i<len; i++)a[i]=Mul(a[i],b[i]);
65
        NTT(a, len, -1);
66
67
        for(int i=0; i<=s; i++)printf("%lld<sub>\\\\\\</sub>",a[i]);
68
        puts("");
```

```
69
      }
 70
    }
 71
 72
 73
    #include<cstdio>
 74
    #include<iostream>
 75
    #include<cstring>
 76
    #include<cmath>
 77
    #include<complex>
 78
    using namespace std;
 79
    typedef long long LL;
 80
    const LL MOD=998244353,g=3,gi=332748118;
 81
    const LL N=1000005;
 82
    LL n,m;
 83
    LL a[N], b[N];
    LL pow (LL x,LL y) {
 84
 85
       if (y==1) return x;
 86
       LL lalal=pow(x,y>>1);
 87
       lalal=lalal*lalal%MOD;
 88
       if (y&1) lalal=lalal*x%MOD;
 89
       return lalal;
 90
 91
    void ntt (LL *a,LL n,LL o) {
 92
       if (n==1) return;
 93
       LL k=(n>>1);
 94
       LL w=1, wn=pow(o==1?g:gi, (MOD-1)/n), a0[k], a1[k];
 95
       for (LL u=0; u< k; u++) {
 96
         LL i=u*2;
 97
         a0[u]=a[i]
98
         a1[u]=a[i+1];
 99
100
       ntt(a0,k,o);
101
       ntt(a1,k,o);
102
       for (LL u=0; u< k; u++) {
103
         a[u]=a0[u]+w*a1[u]%MOD;
         a[u]=(a[u]%MOD+MOD)%MOD;
104
105
         a[u+k]=a0[u]-w*a1[u];
106
         a[u+k]=(a[u+k]%MOD+MOD)%MOD;
107
         w=w*wn%MOD;
108
109
110
     void ntt(LL *a,LL n,LL op) {
111
       for (LL u=0; u<n; u++) bin[u]=(bin[u>>1]>>1)|((u&1)*(n>>1));
       for (LL u=0; u<n; u++) if (u<bin[u]) swap(a[u],a[bin[u]]);
112
       for (LL u=1; u<n; u<<=1) {
113
         LL wn=pow(op==1?g:gi,(MOD-1)/(u<<1)),w,t;
114
115
         for (LL i=0; i< n; i=i+(u<<1)) {
116
           w=1;
           for (LL k=0; k<u; k++) {
117
118
             t=w*a[u+i+k]%MOD;
             a[u+i+k]=(a[i+k]-t+MOD)%MOD;
119
120
             a[i+k]=(a[i+k]+t)%MOD;
121
             w=w*wn%MOD;
122
           }
123
         }
124
       if(op==-1) {
125
126
         LL Inv=pow(n,MOD-2);
127
         for(LL i=0; i<n; i++) a[i]=a[i]*Inv%MOD;
128
       }
129
    }
130
131
    int main() {
       scanf("%I64d%I64d",&n,&m);
132
```

```
133
       for (LL u=0; u<=n; u++) scanf("%I64d",&a[u]);
134
       for (LL u=0; u<=m; u++) scanf("%I64d",&b[u]);
135
       m=m+n;
136
       n=1;
137
       while (n \le m) n \le 1;
138
       ntt(a,n,1);
139
       ntt(b,n,1);
       for (LL u=0; u<=n; u++) a[u]*=b[u];
140
141
       ntt(a,n,-1);
       LL inv=pow(n,MOD-2);
142
       for (LL u=0; u<=m; u++) printf("%I64d_{\perp}",a[u]*inv%MOD);
143
144
       return 0;
145
```

# 5.8 Fast Walsh—Hadamard transform

异或

$$\mathcal{F}\{A\} = \left[\mathcal{F}\{A_0\} + \mathcal{F}\{A_1\}, \mathcal{F}\{A_0\} - \mathcal{F}\{A_1\}\right]$$
$$\mathcal{F}^{-1}\{A\} = \left[\mathcal{F}^{-1}\{\frac{A_0 + A_1}{2}\}, \mathcal{F}^{-1}\{\frac{A_0 - A_1}{2}\}\right]$$

• 按位与

$$\mathcal{F}\{A\} = [\mathcal{F}\{A_0\} + \mathcal{F}\{A_1\}, \mathcal{F}\{A_1\}]$$
$$\mathcal{F}^{-1}\{A\} = [\mathcal{F}^{-1}\{A_0\} - \mathcal{F}^{-1}\{A_1\}, \mathcal{F}^{-1}\{A_1\}]$$

• 按位或

$$\mathcal{F}\{A\} = [\mathcal{F}\{A_0\}, \mathcal{F}\{A_1\} + \mathcal{F}\{A_0\}]$$
$$\mathcal{F}^{-1}\{A\} = [\mathcal{F}^{-1}\{A_0\}, \mathcal{F}^{-1}\{A_1\} - \mathcal{F}^{-1}\{A_0\}]$$

```
void FWT(int a[],int n) {
 1
 2
      for(int d=1; d<n; d<<=1)
 3
        for(int m=d<<1, i=0; i< n; i+=m)
          for(int j=0; j<d; j++) {
 4
 5
             int x=a[i+j], y=a[i+j+d];
 6
            a[i+j]=(x+y)%mod, a[i+j+d]=(x-y+mod)%mod;
            //xor:a[i+j]=x+y,a[i+j+d]=(x-y+mod)%mod;
 7
 8
            //and:a[i+j]=x+y;
 9
            //or:a[i+j+d]=x+y;
          }
10
11
12
    void UFWT(int a[],int n) {
13
      for(int d=1; d<n; d<<=1)
14
15
        for(int m=d<<1,i=0; i<n; i+=m)
          for(int j=0; j<d; j++) {
  int x=a[i+j],y=a[i+j+d];</pre>
16
17
            a[i+j]=1LL*(x+y)*rev%mod, a[i+j+d]=(1LL*(x-y)*rev%mod+mod)%mod;
18
19
            //xor:a[i+j]=(x+y)/2,a[i+j+d]=(x-y)/2;
20
            //and:a[i+j]=x-y;
21
            //or:a[i+j+d]=y-x;
22
23
24
    void solve(int a[],int b[],int n) {
25
      FWT(a,n);
26
      FWT(b,n);
27
      for(int i=0; i<n; i++) a[i]=1LL*a[i]*b[i]%mod;
28
      UFWT(a,n);
29 | }
```

### 5.9 Lucas

```
/* Lucas, by Abreto<m@abreto.net>. */
 3
   struct __lucas {
 4
      static const int maxp = 100000;
 5
      typedef long long int 11;
 6
      int p;
 7
      int f[maxp]; // fiv[maxp], inv[maxp];
 8
      inline int mul(const int a, const int b) {
 9
        ll z = 1ll * a * b;
        z = z / p * p;
10
11
        return z;
12
13
      int qow(int a, int x) {
14
        int ret = 1;
15
        while (x) {
16
          if (1 \& x) ret = mul(ret, a);
17
          a = mul(a, a);
18
          x >>= 1;
19
20
        return ret;
21
      }
22
      void init(int np) {
23
        p = np;
24
        // return; // uncomment this line if use binom()
        f[0] = f[1] = 1;
25
        // fiv[0] = fiv[1] = 1;
26
        // inv[1] = 1;
27
28
        for (int i = 2; i < p; i++) {
          f[i] = mul(f[i - 1], i);
29
30
          // inv[i] = mul(p - p / i, inv[p % i]);
          // fiv[i] = mul(fiv[i - 1], inv[i]);
31
32
33
34
      int C(int n, int k) {
35
        if (n < k) return 0;
36
        return mul(f[n], qow(mul(f[k], f[n - k]), p - 2));
37
38
      /** use following if get TLE { */
39
      int binom(int n, int k) {
        if (n < k) return 0;
40
        if (k > n - k) k = n - k;
int a = 1, b = 1;
41
42
43
        while (k) {
44
          a = mul(a, n);
45
          b = mul(b, k);
46
          n--;
47
          k---;
48
49
        return mul(a, qow(b, p - 2));
50
51
      /** } ---- */
52
      int operator()(int n, int k) {
53
        if (0 == k) return 1;
54
        if (n  return <math>C(n, k);
55
        return mul(C(n \% p, k \% p), (*this)(n / p, k / p));
56
   |} lucas;
```

### 5.10 Linear Programming

```
|/* 线性规划 */
2
   #include<bits/stdc++.h>
3
   using namespace std;
5
   const int Maxn=110,Maxm=59;
6
   class Simplex {
7
     /*
8
9
        接受有n个约束, m个基本变量的方程组a[0~n][0~m]
10
        a[0][]存放需要最大化的目标函数, a[][0]存放常数
11
        Base □ 存放基本变量的id,初始为1~m
12
        Rest [] 存放松弛变量的id,初始为m+1~m+n
13
        返回此线性规划的最小值ans
        要求方案的话, Base[]中的变量值为0,Rest[]中的变量值为相应行的[0]
14
15
        如果solve
16
        返回1,说明运行正常ans是它的最大值
17
        返回0,说明无可行解
18
        返回-1,说明解没有最大值
19
        测 试:
        m=2, n=3
20
        double a[4][3]={
21
22
        \{0,1,3\},
        \{8,-1,1\},
23
24
        \{-3,1,1\},
25
        \{2,1,-4\}
26
        };
27
        solve=1, ans=64/3;
28
        注意ac不了可能是eps的问题
29
   public:
30
31
     static const double Inf;
32
     static const double eps;
33
     int n,m;
     double a[Maxn][Maxm];
34
35
     int Base[Maxm],Rest[Maxn];
36
     double val[Maxm];
37
     double ans;
38
     void pt() {
39
       for(int i=0; i<=n; i++) {
40
         for(int j=0; j<=m; j++)printf(\%.2f<sub>\(\sigma\)</sub>,a[i][j]);
41
         puts("");
42
       }
43
     }
44
     void pivot(int x,int y) { //将第x个非基本变量和第y个基本变量调换
45
       swap(Rest[x],Base[y]);
46
       double tmp=-1./a[x][y];
47
       a[x][y]=-1.;
48
       for(int j=0; j <= m; j++)a[x][j]*=tmp;
49
       for(int i=0; i<=n; i++) {
50
         if(i==x||fabs(a[i][y])<eps)continue;</pre>
51
         tmp=a[i][y];
52
         a[i][y]=0;
53
         for(int j=0; j<=m; j++)a[i][j]+=tmp*a[x][j];
54
55
56
     bool opt() {
       while(1) {
57
58
         int csi=0;
59
         for(int i=1; i<=m; i++)if(a[0][i]>eps&&(!csi||Base[i]<Base[csi]))csi=i;
60
         if(!csi)break;
         int csj=0;
61
62
         double cur;
63
         for(int j=1; j<=n; j++) {
64
           if(a[j][csi]>-eps)continue;
```

```
65
             double tmp=-a[j][0]/a[j][csi];
 66
             if(!csj||tmp+eps<cur||(fabs(tmp-cur)<eps&&Rest[j]<Rest[csj]))csj=j,cur=tmp;
 67
 68
           if(!csj)return 0;
 69
           pivot(csj,csi);
         }
 70
 71
         ans=a[0][0];
 72
         return 1;
 73
 74
       bool init() {
 75
         ans=0;
 76
         for(int i=1; i<=m; i++)Base[i]=i;
 77
         for(int i=1; i<=n; i++)Rest[i]=m+i;
 78
         int cs=1;
 79
         for(int i=2; i<=n; i++)if(a[i][0]<a[cs][0])cs=i;
 80
         if(a[cs][0]>=-eps)return 1;
 81
         static double tmp[Maxm];
 82
         for(int i=0; i<=m; i++)tmp[i]=a[0][i],a[0][i]=0;
 83
         for(int i=1; i<=n; i++)a[i][m+1]=1.;
 84
         a \lceil 0 \rceil \lceil m+1 \rceil = -1:
 85
         Base[m+1]=m+n+1;
 86
         pivot(cs,++m);
 87
         opt();
 88
         m--;
 89
         if(a[0][0] \leftarrow eps) return 0;
 90
         cs=-1;
 91
         for(int i=1; i<=n; i++) {
 92
           if(Rest[i]>m+n) {
 93
             cs=i;
 94
             break;
           }
 95
 96
 97
         if(cs>=1) {
98
           int nxt=-1;
 99
           m++;
100
           for(int i=1; i<=m; i++)if(a[cs][i]>eps||a[cs][i]<-eps) {
101
                nxt=i;
102
               break;
103
104
           pivot(cs,nxt);
105
           m--;
106
107
         for(int i=1; i<=m; i++) {
108
           if(Base[i]>m+n) {
109
             swap(Base[i],Base[m+1]);
110
             for(int j=0; j<=n; j++)a[j][i]=a[j][m+1];
111
             break;
           }
112
113
114
         for(int i=1; i<=m; i++)a[0][i]=0;
115
         a[0][0]=tmp[0];
116
         for(int i=1; i<=m; i++)if(Base[i]<=m)a[0][i]=tmp[Base[i]];
         for(int i=1; i<=n; i++) {
117
118
           if(Rest[i]<=m) {
119
              for(int j=0; j<=m; j++)a[0][j]+=tmp[Rest[i]]*a[i][j];
120
121
122
         return 1;
123
124
       void getval() {
125
         for(int i=1; i<=m; i++)val[i]=0;
         for(int i=1; i<=n; i++)if(Rest[i]<=m)val[Rest[i]]=a[i][0];
126
         //for(int i=1;i<=m;i++)printf("%.2f ",val[i]);puts("");
127
128
       }
```

```
int solve() {
129
130
         if(!init())return 0;
131
         if(!opt())return -1;
132
         getval();
133
         return 1;
       }
134
135
     } solver;
     const double Simplex:: Inf=1e80;
136
137
     const double Simplex:: eps=1e-8;
138
     int main() {
139
       int m,n,type;
       scanf("%d%d%d",&m,&n,&type);
140
141
       solver.a[0][0]=0;
142
       for(int i=1; i<=m; i++)scanf("%lf",&solver.a[0][i]);
       for(int i=1; i<=n; i++) {
143
144
         for(int j=1; j<=m+1; j++) {
145
           if(j==m+1)scanf("%lf",&solver.a[i][0]);
146
           else {
             scanf("%lf",&solver.a[i][j]);
147
             solver.a[i][j]=-solver.a[i][j];
148
149
150
         }
151
       }
152
       solver.m=m, solver.n=n;
       int rep=solver.solve();
153
154
       if(rep==0)puts("Infeasible");
155
       else if(rep==-1)puts("Unbounded");
156
       else {
         printf("%.12f\n", solver.ans);
157
         if(type==1) {
158
           for(int i=1; i<=m; i++)printf("%.12f%c",solver.val[i],i==m?'\n':'\_');
159
160
161
       }
162 |}
```

### 5.11 Big Prime Test

```
1 | #include <iostream>
 2
   #include <cstdlib>
 3
   using namespace std;
 4
   typedef long long LL;
 5
   LL minfactor, p[11] = \{2, 3, 5, 7, 11, 13, 17, 19, 23, 29\};
   LL gcd(LL a, LL b) {
 7
     return b? gcd(b, a \% b): a;
 8
 9
   LL qmult(LL a, LL b, LL mod) { // 快速乘模
     LL sum = 0;
10
11
     while (b) {
12
       if (b & 1) {
13
14
         if (sum >= mod) sum -= mod; // 此处无需用%, %运算比减法慢很多
15
16
       b >>= 1, a <<= 1;
17
       if (a >= mod) a == mod;
18
19
     return sum;
20
21
   LL qpow(LL a, LL b, LL mod) { // 快速幂模
22
     LL res = 1;
23
     while (b) {
24
       if (b \& 1) res = qmult(res, a, mod);
25
       b >>= 1;
```

```
26
      a = qmult(a, a, mod);
27
28
     return res;
29
   }
30
   bool prime_test(LL n, LL a) { // 对整数n, 底数a进行测试, 返回true表示通过测试
31
     LL p = apow(a, n - 1, n);
     if (p!= 1) return false;
32
     else { // 二次探测
LL s = n - 1;
33
34
35
       while (!(s & 1) && p == 1) {
36
        s >>= 1;
37
        p = qpow(a, s, n);
38
39
       if (p == 1 \mid | p == n - 1) return true;
40
       else return false;
41
     }
42
43
   bool Miller_Rabin(LL n) { // 对整数n进行Miller_Rabin素数测试,返回true表示通过测试
44
                    // if这一块其实可以不用
     if (n <= 29) {
       for (int i = 0; i < 10; i++) {
45
46
        if (n == p[i]) return true;
47
48
       return false;
49
50
     for (int i = 0; i < 10; i++) { // 利用前10个素数作为底数测试的正确率已经非常高
51
       if (gcd(n, p[i]) == 1 && !prime_test(n, p[i])) return false;
52
53
     return true;
54
   LL randf(LL x, LL n, LL c) { // 满足要求的产生伪随机数函数
55
     return (qmult(x, x, n) + c) \% n;
56
57
   LL pollard_rho(LL n, LL c) { // 查找n的因数, c为上面函数要用的随机数, c也可自己指定
58
       (但要有变化)
     LL x = rand() % n, y = x, i = 1, k = 2, p; // 随机生成随机数的初始值, 也可自己指定
59
60
     while (true) {
61
       i++;
62
       x = randf(x, n, c);
       p = gcd(y - x + n, n);
63
64
       if (p > 1 \&\& p < n) return p;
65
                           // 判圈,返回n表示查找失败,要更新随机种子重新查找
       if (y == x) return n;
66
       if (i == k) {
67
        y = x; // 更新范围和记录的数
        k \ll 1;
68
       }
69
70
     }
71
72
   void find_factor(LL n) { // 查找所有因数
73
     if (Miller_Rabin(n)) {
74
       minfactor = min(minfactor, n);
75
       return ;
76
     }
77
     LL p = n;
     while (p == n) p = pollard_rho(n, rand() % (n - 1) + 1); // 查找失败则更新随机种子
78
        重新查找,直到找到因子
79
                       // 递归查找更小因子
     find_factor(p);
80
     find_factor(n / p);
81
   }
82
83
   int main() {
84
     int t;
     cin >> t;
85
86
     while (t--) {
87
      LL N;
```

```
88
        cin >> N;
89
        if (Miller_Rabin(N)) cout << "Prime" << endl;</pre>
90
        else {
91
          minfactor = N;
92
          find_factor(N);
93
          cout << minfactor << endl;</pre>
94
95
96
      return 0;
97 | }
   5.11.1 Miller Rabin
   /* Miller-Rabin Prime Test, by Abreto<m@abreto.net>. */
 2
 3
   namespace miller_rabin {
 4
 5
   typedef long long int ll;
 6
7
    inline ll add(const ll a, const ll b, const ll mod) {
 8
      ll z = a + b;
9
      if (z \ge mod) z = mod;
10
      return z;
11
    inline ll mul(ll a, ll b, const ll mod) {
12
13
      11 z = 0;
      if (a >= mod) a %= mod;
14
15
      if (b \ge mod) b %= mod;
      while (b) {
16
17
        if (1 \& b) z = add(z, a, mod);
18
        a = add(a, a, mod);
19
        b >>= 1;
20
21
      return z;
22
23
    ll qow(ll a, ll x, ll mod) {
24
25
      ll ret = 1ll;
26
      while (x) {
27
        if (1 \& x) ret = mul(ret, a, mod);
28
        a = mul(a, a, mod);
29
        x >>= 1;
      }
30
31
      return ret;
32
33
34
    const int K = 5;
35
    const int p[] = {
36
      2, 3, 7, 61, 24251
37
38
   const ll strong = 4685624825598111;
39
    /* 46 856 248 255 981 in (0, 1e16) */
40
41
   bool mr(ll n, int k) {
42
      11 d = n - 1;
43
      int s = 0;
44
      while (d > 1 \&\& 0 == (d \& 1)) {
45
        S++;
46
        d >>= 1;
47
48
      for (int i = 0; i < k; i++) {
49
        ll a = (i < K) ? p[i] : (1 + rand() % (n - 1));
50
        11 \times = qow(a, d, n);
```

```
51
        for (int j = 0; j < s; j++) {
52
          ll xp = mul(x, x, n);
53
          if (1 == xp \&\& x != 1 \&\& x != n-1) return false;
54
55
56
        if (x != 1) return false;
57
58
     return true;
59
60
61
   /* 2,3,5,7,11,13 */
62
   const int pre[] = \{3, 5, 7, 11, 13\};
   bool test(ll n, int k = 5) {
63
64
      if (2 == n) return true;
     if (0 == (n \& 1)) return false;
65
66
     if (strong == n) return false;
67
     for (int i = 0; i < 5; i++) {
        if (n == pre[i]) return true;
68
69
        if (n == n / pre[i] * pre[i])
70
          return false;
71
72
      return mr(n, k);
73
74
75 |}
   5.11.2 Pollard's rho
   /* Pollard's rho, by Abreto<m@abreto.net>. */
 2
 3
   namespace pollards_rho {
 4
 5
   typedef long long int ll;
 6
   inline ll add(const ll a, const ll b, ll mod) {
7
 8
     11 z = a + b;
9
     if (z \ge mod) z = mod;
10
      return z;
11
12
   inline ll mul(ll a, ll b, ll mod) {
13
     ll z = 0ll;
14
     if (a >= mod) a -= a / mod * mod;
     if (b \ge mod) b = b / mod * mod;
15
     while (b) {
16
        if (1 \& b) z = add(z, a, mod);
17
18
        a = add(a, a, mod);
19
        b >>= 1;
20
21
     return z;
22
23
24
   ll gcd(ll m, ll n) {
25
      return (0 == n)? m : gcd(n, m % n);
26
27
28
   ll find(ll n, int c = -1) {
29
     ll x = rand() % n;
30
     11 y = x, k = 2;
31
     for (int i = 2; i++) {
32
        x = add(mul(x, x, n), (n + c) % n, n);
33
        ll d = gcd(y - x + n, n); // change to abs(y - x) if get WA
34
        if (1 != d && n != d) return d;
35
        if (y == x) return n;
```

```
36
        if (i == k) {
37
          y = x;
38
          k <<= 1;
39
        }
40
41
42
43
    /** usaae:
44
     * void find(ll n, int c = 107)
45
     * {
46
         if (1 == n) return;
47
         if ( miller-rabin(n) )
     *
48
     *
49
           n is a prime;
     *
50
     *
           return;
51
     *
52
         ll p = n, k = c;
     *
53
         while (p \ge n) p = pollards_rho(p, k--);
     *
54
         find(p, c);
55
         find(n/p, c);
     *
56
     * }
57
     **/
58
59 |}
```

# 5.12 Montgomery modular multiplication

```
1
 2
   /∗ — Montgomery modular algorithm { — ∗/
 3
   struct Mod64 {
 4
     typedef long long ll;
 5
     typedef unsigned long long u64;
     typedef __int128_t i128;
 6
 7
     typedef __uint128_t u128;
 8
     Mod64() :n_(0) {}
 9
     Mod64(u64 n) :n_(init(n)) {}
     static u64 init(u64 w) {
10
11
        return reduce(u128(w) * r2);
12
13
     static void set_mod(u64 m) {
14
        mod = m;
15
        assert(mod & 1);
16
        inv = m;
17
        for (int i = 0; i < 5; ++i) inv *= 2 - inv * m;
18
        r2 = -u128(m) \% m;
19
     static u64 reduce(u128 x) {
20
        u64 y = u64(x >> 64) - u64((u128(u64(x)*inv)*mod) >> 64);
21
22
        return ll(y)<0 ? y + mod : y;
23
24
     Mod64& operator += (Mod64 rhs) {
25
        n_+ = rhs.n_- - mod;
        if (ll(n_)<0) n_+ = mod;
26
27
        return *this;
28
29
     Mod64 operator + (Mod64 rhs) const {
30
        return Mod64(*this) += rhs;
31
32
     Mod64& operator -= (Mod64 rhs) {
33
        n_- = rhs.n_;
        if (ll(n_)<0) n_+=mod;
34
35
        return *this;
```

```
36
37
      Mod64 operator - (Mod64 rhs) const {
38
        return Mod64(*this) -= rhs;
39
40
      Mod64& operator *= (Mod64 rhs) {
41
        n_{-} = reduce(u128(n_{-})*rhs.n_{-});
42
        return *this;
43
44
      Mod64 operator * (Mod64 rhs) const {
45
        return Mod64(*this) *= rhs;
46
47
      u64 get() const {
48
        return reduce(n_);
49
50
      static u64 mod, inv, r2;
51
      u64 n_;
52
53
54
   Mod64::u64 Mod64::mod, Mod64::inv, Mod64::r2;
55
   /* -- } Montgomery modular algorithm -- */
56
57
   /**
58
    * usage:
59
    * First, Mod64::set_mod();
60
    * Mod64 a, b, c(init_val);
61
    *a = b * c;
62
     * printf("%llu\n", a.get());
63
    **/
```

# 5.13 Berlekamp Massey

```
1 |/* Berlekamp Massey by HoldZhu. */
 2
   #include <cstdio>
 3
   #include <vector>
 4
 5
   using namespace std;
 6
 7
   namespace BerlekampMassey {
 8
    const int mod = 1e9 + 7;
 9
   int L, m, b, n;
10
   vector<int> s, C, B;
11
   void init() {
12
      s.clear();
13
      C.clear();
14
      B.clear();
15
      C.push_back(1);
16
      B.push_back(1);
17
      L = n = 0;
18
      m = b = 1;
19
20
   int pow_mod(int a, int k) {
21
      int s = 1;
      while (k) {
22
        if (k & 1)
23
24
          s = 111 * s * a % mod;
25
        a = 111 * a * a % mod;
26
        k >>= 1;
      }
27
28
      return s;
29
30
   void update(int d) {
31
      s.push_back(d);
```

```
32
      for (int i = 1; i <= L; ++i)
33
        d = (d + 111 * C[i] * s[n - i] % mod) % mod;
34
      if (d == 0)
35
        ++m;
      else if (2 * L <= n) {
36
37
        vector<int> T = C;
38
        C.resize(n + 1 - L + 1);
39
        for (int i = L + 1; i \le n + 1 - L; ++i)
40
          C[i] = 0;
        for (int i = 0; i < B.size(); ++i)
41
42
          C[i + m] = (C[i + m] + mod - 111 * d * pow_mod(b, mod - 2) % mod * B[i] % mod)
             % mod;
        L = n + 1 - L;
43
        B = T;
44
45
        b = d;
46
        m = 1;
47
      } else {
48
        for (int i = 0; i < B.size(); ++i)
49
          C[i + m] = (C[i + m] + mod - 1ll * d * pow_mod(b, mod - 2) % mod * B[i] % mod)
             % mod;
50
        ++m;
51
      }
52
      ++n;
53
54
   void output() {
55
      printf("F(n)=");
56
      for (int i = 1; i < C.size(); ++i) {
57
        int output = (mod - C[i]) % mod;
58
        if (output > mod / 2)
59
          output -= mod;
        printf("%s%d*F(n-%d)", (output < 0 \mid i == 1)? "" : "+", output, i);
60
61
      puts("");
62
63
64
   void output_code_for() {
      static const char *name = "dp";
65
      static const char *index = "i";
66
      static const char *upperbound = "maxn";
67
      puts("//_Generated_by_Berlekamp-Massey_algorithm");
68
69
      for (int i = 1; i < C.size(); ++i) {
70
        printf("%s[%d]=%d;\n", name, i - 1, s[i - 1]);
71
72
      printf("for(int<sub>\(\)</sub>i=\(\)d;i<\(\)s;++i)\\n", (int)C.size() - 1, upperbound);</pre>
      printf("\square" \%s[%s]=((", name, index);
73
74
      for (int i = 1; i < C.size(); ++i) {
        int output = (mod - C[i]) % mod;
75
76
        if (output > mod / 2)
77
          output -= mod;
        printf("%s%d*%s[%s-%d]%mod", (output < 0 | | i == 1) ? "" : "+", output, name,
78
           index, i);
79
80
      puts(")%mod+mod)%mod;");
81
82
    void output_code_matrix() {
     // TODO
83
84
85
   };
86
87
   /** usage */
88
   int usage() {
      // int arr[12] = {2, 24, 96, 416, 1536, 5504, 18944, 64000, 212992, 702464,
89
         2301952, 7512064};
90
      int arr[] = {3, 20, 119, 696, 4059, 23660, 137903, 803760, 4684659};
91
      BerlekampMassey::init();
```

```
92
      for (auto ai : arr) {
 93
         BerlekampMassey::update(ai);
 94
 95
      printf("Formule:□");
 96
      BerlekampMassey::output();
      printf("Code: \n");
 97
 98
      BerlekampMassey::output_code_for();
99
       return 0;
100
```

# 5.14 Inclusion—exclusion principle

# 5.14.1 General form

若  $A_1, A_2, \ldots, A_n$  为有限集,则

$$\left| \bigcup_{i=1}^{n} A_i \right| = \sum_{\phi \neq J \subseteq \{1, 2, \dots, n\}} (-1)^{|J|-1} \left| \bigcap_{j \in J} A_j \right|$$

### 5.14.2 A generalization

若

$$g(A) = \sum_{S \subseteq A} f(S)$$

则

$$f(A) = \sum_{S \subseteq A} (-1)^{|A| - |S|} g(S)$$

更一般的,如果S是多重集合(multiset),那么

$$f(A) = \sum_{S \subset A} \mu(A - S)g(S)$$

其中

- 当 S 是含有偶数个元素的集合(没有重复元素)时, $\mu(S)=1$
- 当 S 是含有奇数个元素的集合(没有重复元素)时, $\mu(S)=-1$
- 当 S 含有重复元素时, $\mu(S)=0$ .

# 5.14.3 Applications

I. 乱序排列

如果集合 A 含有 n 个元素,则乱序排列的数目为 [n!/e], [x] 表示最接近 x 的整数.

# 5.15 Lindström-Gessel-Viennot lemma

对于一张无边权的 DAG 图,给定 n 个起点和对应的 n 个终点,这 n 条不相交路径的方案数为

$$\begin{vmatrix} e(a_1,b_1) & e(a_1,b_2) & \cdots & e(a_1,b_n) \\ e(a_2,b_1) & e(a_2,b_2) & \cdots & e(a_2,b_n) \\ \vdots & \vdots & \ddots & \vdots \\ e(a_n,b_1) & e(a_n,b_2) & \cdots & e(a_n,b_n) \end{vmatrix}$$
 (该矩阵的行列式)

其中 e(a,b) 为图上 a 到 b 的方案数.

# 6 String

### 6.1 Hash

```
/* Common hash for any substrings. */
 2
   typedef unsigned long long int llu;
 3
 4
   #define MAXN 1000000
   int n;
 5
   char s[MAXN];
 6
 7
   llu H[MAXN], xP[MAXN], P = 9999111;
 8
   void init(void) {
 9
     int i = 0;
10
     xP[0] = 111;
11
     for(i = 1; i < MAXN; ++i) xP[i] = xP[i-1] * P;
12
     H[n] = 0;
13
     for(i = n-1; i \ge 0; --i) H[i] = H[i+1]*P + s[i];
14
15 |#define HASH(i,l) (H[i] - H[i+l]*xP[l])
```

#### 6.2 KMP

```
/* KMP, by Abreto<m@abreto.net>. */
 2
   #include <string.h>
 3
 4
   /* !!NEED IMPROVING!! */
 5
 6
   #define MAXL (1000010)
 7
8
   char W[MAXL], T[MAXL];
    int f[MAXL];
9
10
   int lW, lT;
11
12
   int count(void) {
13
      int cnt = 0;
      int i, j;
14
      lW = strlen(W);
15
      lT = strlen(T);
16
17
      // -- self-matching
      f[0] = j = -1;
for(i = 1; i < lW; i++) {
18
19
20
        while( j \ge 0 \&\& W[j+1] != W[i] )
21
          j = f[j];
22
        if( W[j+1] == W[i] ) j++;
23
        f[i] = j;
24
      }
25
      // -
26
      j = -1;
      for(i = 0; i < lT; i++) {
27
28
        while( j \ge 0 \& W[j+1] != T[i] )
29
          j = f[j];
30
        if(W[j+1] == T[i]) j++;
        if( j == lW-1 ) {
31
32
          cnt++;
33
          j = f[j];
34
35
36
      return cnt;
37 | }
```

### 6.3 exKMP

```
|#include <bits/stdc++.h>
 2
   using namespace std;
 3
 4
   namespace exkmp {
 5
 6
   const int maxn = 1000100, maxm = 1000100;
8
   int n, m;
9
   char S[maxn], T[maxm];
10
   /* the length of longest prefix between T[i..m-1] and T[0..m-1] */
11
12
   int nxt[maxm];
   /* the length of longest prefix between S[i..n-1] and T[0..m-1] */
13
14
   int ex[maxn];
15
16
   void getsize() {
     n = strlen(S);
17
18
     m = strlen(T);
19
20
21
   void self(void) {
22
     int q = 1, p = 0;
23
     nxt[0] = m;
24
     while (1 + p < m \&\& T[1 + p] == T[p]) p++;
25
     nxt[1] = p;
     for (int i = 2; i < m; i++) {
26
27
        int l = nxt[i - q];
28
        if (i + l - 1 < p) {
29
          nxt[i] = 1;
30
        } else {
          int j = max(0, p - i + 1);
31
32
          while (i + j < m \& T[i + j] == T[j]) j++;
33
          nxt[i] = j;
34
          p = i + j - 1;
35
          q = i;
36
37
     }
38
39
40
   void run(void) {
41
     int q = 0, p = 0;
42
     self();
43
     while (p < n \&\& p < m \&\& S[p] == T[p]) p++;
44
     ex[0] = p;
45
46
      for (int i = 1; i < n; i++) {
47
        int l = nxt[i - q];
        if (i + l - 1 < p) {
48
          ex[i] = 1;
49
50
        } else {
51
          int j = max(0, p - i + 1);
52
          while (i + j < n \&\& S[i + j] == T[j]) j++;
53
          ex[i] = j;
54
          p = i + j - 1;
55
          q = i;
56
57
     }
58
59
   void inspect(void) {
60
     printf("S:□");
61
```

```
62
      for (int i = 0; i < n; i++) putchar(S[i]);
63
      puts("");
      printf("T:□");
64
65
      for (int i = 0; i < m; i++) putchar(T[i]);
      puts("");
66
      printf("next:");
67
68
      for (int i = 0; i < m; i++) printf("\lfloor \%d", nxt[i]);
      puts(""):
69
      printf("extend:");
70
71
      for (int i = 0; i < n; i++) printf("\lfloor \%d", ex[i]);
72
      puts("");
73
74
75 |} // exkmp
   6.4 Suffix Array
   /* Suffix Array, copied. */
 1
 2
 3
   #define MAXN
                     (200010)
   namespace mzry_sa {
 5
   int wx[MAXN], wy[MAXN], *x, *y, wss[MAXN], wv[MAXN];
 7
    bool dacmp(int *r,int n,int a,int b,int l) {
 8
      return a+1< n \&\& b+1< n \&\& r[a]==r[b]\&\&r[a+1]==r[b+1];
 9
10
   void da(int str[],int sa[],int rank[],int height[],int n,int m) {
11
      int *s = str;
12
      int *x=wx,*y=wy,*t,p;
13
      int i,j;
14
      for(i=0; i<m; i++)wss[i]=0;
15
      for(i=0; i<n; i++)wss[x[i]=s[i]]++;
16
      for(i=1; i<m; i++)wss[i]+=wss[i-1];
17
      for(i=n-1; i>=0; i--)sa[--wss[x[i]]]=i;
18
      for(j=1,p=1; p<n && j<n; j*=2,m=p) {
19
        for(i=n-j,p=0; i< n; i++)y[p++]=i;
20
        for(i=0; i<n; i++)if(sa[i]-j>=0)y[p++]=sa[i]-j;
        for(i=0; i<n; i++)wv[i]=x[y[i]];
21
        for(i=0; i<m; i++)wss[i]=0;
22
        for(i=0; i<n; i++)wss[wv[i]]++;
23
24
        for(i=1; i<m; i++)wss[i]+=wss[i-1];
25
        for(i=n-1; i>=0; i--)sa[--wss[wv[i]]]=y[i];
26
        for(t=x, x=y, y=t, p=1, i=1, x[sa[0]]=0; i<n; i++)
27
          x[sa[i]]=dacmp(y,n,sa[i-1],sa[i],j)?p-1:p++;
28
29
      for(int i=0; i<n; i++) rank[sa[i]]=i;
30
      for(int i=0, j=0, k=0; i< n; height[rank[i++]]=k)
31
        if(rank[i]>0)
32
          for(k?k-:0,j=sa[rank[i]-1];
33
              i+k < n \& j+k < n \& str[i+k] == str[j+k];
34
              k++);
35
36
   }
37
38
39
   Suffix array 0(n lg^2 n)
40
   LCP table O(n)
41
   */
42
   #include <cstdio>
43
   #include <algorithm>
44
   #include <cstring>
45
```

```
46
    using namespace std;
 47
 48
    #define REP(i, n) for (int i = 0; i < (int)(n); ++i)
 49
    namespace SuffixArray {
 50
 51
    const int MAXN = 1 \ll 21;
 52
    char * S;
 53
    int N, gap:
 54
    int sa[MAXN], pos[MAXN], tmp[MAXN], lcp[MAXN];
 55
 56
    bool sufCmp(int i, int j) {
 57
      if (pos[i] != pos[j])
 58
         return pos[i] < pos[j];
 59
      i += gap;
 60
       j += gap;
 61
       return (i < N && j < N) ? pos[i] < pos[j] : i > j;
 62
 63
 64
    void buildSA() {
 65
      N = strlen(S);
 66
      REP(i, N) sa[i] = i, pos[i] = S[i];
 67
      for (gap = 1; gap <<= 1) {
 68
         sort(sa, sa + N, sufCmp);
         REP(i, N-1) tmp[i+1] = tmp[i] + sufCmp(sa[i], sa[i+1]);
 69
 70
         REP(i, N) pos[sa[i]] = tmp[i];
 71
         if (tmp[N-1] == N-1) break;
 72
      }
 73
    }
 74
 75
    void buildLCP() {
       for (int i = 0, k = 0; i < N; ++i) if (pos[i] != N - 1) {
 76
 77
           for (int j = sa[pos[i] + 1]; S[i + k] == S[j + k];)
 78
             ++k;
 79
           lcp[pos[i]] = k;
 80
           if (k)—k;
 81
 82
 83
    } // end namespace SuffixArray
 84
 85
    namespace HashSuffixArray {
 86
    const int
 87
    MAXN = 1 << 21;
 88
 89
    typedef unsigned long long hash;
 90
 91
    const hash BASE = 137;
 92
 93
    int N;
 94
    char * S;
 95
    int sa[MAXN];
 96
    hash h[MAXN], hPow[MAXN];
 97
 98
    \#define getHash(lo, size) (h[lo] - h[(lo) + (size)] * hPow[size])
 99
    inline bool sufCmp(int i, int j) {
100
101
      int lo = 1, hi = min(N - i, N - j);
102
      while (lo <= hi) {
103
         int mid = (lo + hi) >> 1;
104
         if (getHash(i, mid) == getHash(j, mid))
105
           lo = mid + 1;
106
         else
107
           hi = mid - 1;
108
      return S[i + hi] < S[j + hi];</pre>
109
```

```
110 |}
111
112
    void buildSA() {
113
      N = strlen(S);
114
      hPow[0] = 1;
115
      for (int i = 1; i <= N; ++i)
116
        hPow[i] = hPow[i - 1] * BASE;
117
      h[N] = 0;
118
      for (int i = N - 1; i >= 0; —i)
119
        h[i] = h[i + 1] * BASE + S[i], sa[i] = i;
120
121
      stable_sort(sa, sa + N, sufCmp);
122
123
124
    } // end namespace HashSuffixArray
125
126
    namespace lrj_sa {
    const int MAXN = 1000;
127
    char s[MAXN]; /* 原始字符数组 (最后一个字符应必须是0, 而前面的字符必须非0) */
128
129
    int sa[MAXN], t[MAXN], t2[MAXN], c[MAXN], n; /* n seems to be the length of s. */
130
    /* every charactor is in [0,m-1] */
131
    void build_sa(int m) {
132
      int i, *x = t, *y = t2;
133
      for(i = 0; i < m; ++i) c[i] = 0;
134
      for(i = 0; i < n; i++) c[x[i]=s[i]]++;
135
      for(i = 1; i < m; ++i) c[i] += c[i-1];
      for(i = n-1; i >= 0; --i) sa[--c[x[i]]] = i;
136
137
      for(int k = 1; k <= n; k <<= 1) {
138
        int p = 0;
139
        for(i = n-k; i < n; ++i) y[p++] = i;
140
        for(i = 0; i < n; ++i) if(sa[i] >= k) y[p++] = sa[i]-k;
141
        for(i = 0; i < m; i++) c[i] = 0;
142
        for(i = 0; i < n; i++) c[x[y[i]]]++;
143
        for(i = 0; i < m; ++i) c[i]+=c[i-1];
144
        for(i = n-1; i >= 0; --i) sa[--c[x[y[i]]]] = y[i];
145
        swap(x,y);
146
        p = 1;
147
        x[sa[0]] = 0;
        for(i = 1; i < n; ++i)
148
149
          x[sa[i]] = y[sa[i-1]] = y[sa[i]] & y[sa[i-1]+k] = y[sa[i]+k] ? p-1:p++;
150
        if(p >= n) break;
151
        m = p;
152
      }
153
154
    int rank[MAXN], height[MAXN];
155
    void get_height(void) {
156
      int i,j,k = 0;
157
      for(i = 0; i < n; ++i) rank[sa[i]] = i;
      for(i = 0; i < n; ++i) {
158
        if(k) k-;
159
         j = sa[rank[i]-1];
160
161
        while(s[i+k]==s[j+k]) k++;
162
        height[rank[i]] = k;
163
164
165 |} // end namespace lrj_sa
```

#### 6.5 Aho-Corasick Automata

```
1 |/* Aho-Corasick automaton algorithm, by Abreto<m@abreto.net>. */
2 |
3 |#define MAXN 500500
```

```
#define NALPHA
 5
   #define FIRSTA
 6
 7
   /* pointer version => { */
 8
   struct vtx {
 9
      vtx *nxt[NALPHA];
10
      vtx *fail;
11
      int end;
12
    } vtxs[MAXN];
13
   int nvtxs;
14
   void myclr(void) {
15
     nvtxs = 0;
16
17
   vtx *new_vtx(void) {
18
      vtx *ret = vtxs+(nvtxs++);
19
      for(int i = 0; i < NALPHA; i++)
20
        ret->nxt[i] = NULL;
21
      ret->fail = NULL;
22
      ret->end = 0;
23
      return ret;
24
25
    void myins(vtx *root, char const *s) {
26
      for(; *s; s++) {
27
        int of = (*s) – FIRSTA;
28
        if ( NULL == root->nxt[of] ) {
29
          root->nxt[of] = new_vtx();
30
        }
31
        root = root->nxt[of];
      }
32
33
      root->end++;
34
35
   void build_ac(vtx *root) {
36
      queue<vtx *> q;
37
      q.push(root);
38
      while(!q.empty()) {
39
        vtx *p = q.front();
40
        q.pop();
41
        for(int i = 0; i < NALPHA; i++) {
42
          if( NULL == p->nxt[i] ) continue;
43
          if( root == p ) p->nxt[i]->fail = root;
44
          else {
45
            vtx *t = p->fail;
46
            while ( t && NULL == t->nxt[i] ) {
47
              t = t \rightarrow fail;
48
            if (t) p->nxt[i]->fail = t->nxt[i];
49
50
            else p->nxt[i]->fail = root;
51
52
          /* version[1] { */
          p->nxt[i]->end += p->nxt[i]->fail->end; /* update this sum, add its existing
53
             prefix to this. */
          /* } */
54
55
          q.push(p->nxt[i]);
56
57
58
59
    int qry(vtx *root, char const *s) {
60
      vtx *p = root;
61
      int cnt = 0;
62
      for(; *s; s++) {
        int of = (*s) – FIRSTA;
63
64
        while( p != root && NULL == p->nxt[of] ) {
          p = p \rightarrow fail;
65
        }
66
```

```
67
         if (p->nxt[of]) p = p->nxt[of];
 68
         cnt += p->end; // correct when version[1] exists.
 69
         // if version[1] not exists, you need to add all ends from this vertex up.
 70
         //for( vtx *t = p ; t ; t = t->fail )
 71
         // cnt += t->end;
 72
 73
      return cnt;
 74
 75
    /* } */
 76
 77
    /* -- usage (of pointer version) -- */
 78
    #include <bits/stdc++.h>
 79
    using namespace std;
 80
    char S[1000100];
 81
 82
    char pat[64];
 83
 84
    int main(void) {
 85
      int T, N;
 86
      vtx *root = NULL;
 87
      scanf("%d", &T);
      while(T--) {
 88
 89
         myclr();
 90
         root = new_vtx();
        scanf("%s", S);
 91
         scanf("%d", &N);
 92
93
         while(N—) {
           scanf("%s", pat);
 94
 95
           myins(root, pat);
 96
         build_ac(root);
 97
         printf("%d\n", qry(root, S));
 98
 99
100
       return 0;
101 | }
```

# 6.6 Manacher

```
|char t[MAXL<<1];
 2
   int p[MAXL<<1];</pre>
 3
   int manacher(char *s) {
 4
      int i;
 5
      int sl = strlen(s);
 6
      int pos = 0, mxr = 0;
 7
      int ret = 0;
      t[0] = '^';
 8
      for(i = 0; i < sl; ++i) {
 9
        t[i*2+1] = '#';
10
11
        t[i*2+2] = s[i];
12
13
      t[sl*2+1] = '#';
14
      t[sl*2+2] = '$';
15
      sl = sl*2+2;
      for(i = 1; i < sl; ++i) {
16
17
        if(i <= mxr) {
18
          p[i] = min(p[2*pos - i], mxr-i+1);
19
        } else {
20
          p[i] = 1;
21
22
        while( t[i-p[i]] == t[i+p[i]] ) p[i]++;
23
        if(i + p[i] - 1 > mxr) {
          mxr = i+p[i]-1;
24
```

# 7 Utility

# 7.1 IO plug-in

```
/* I/O Plug-in, by Abreto <m@abreto.net>. */
 2
   #include <stdio.h>
 3
 4
   #if ( _WIN32 || __WIN32__ || _WIN64 || __WIN64__ )
 5
   #define INT64 "%I64d"
   #else
 7
   #define INT64 "%lld"
 8
   #endif
 9
10
   #if ( _WIN32 || __WIN32__ || _WIN64 || __WIN64__ )
   #define UNS64 "%I64u"
11
12
   #else
   #define UNS64 "%llu"
13
14
   #endif
15
16
   #define ISDIGIT(x) ((x>='0')\&\&(x<='9'))
   int readn(int *n) {
17
18
     int c=0;
19
     *n=0;
20
     for(; !ISDIGIT(c); c=getchar());
21
     for(; ISDIGIT(c); c=getchar())*n=(*n)*10+c-'0';
22
      return (*n);
23
24
   void putn(int n) {
25
     int ns[16] = \{0, n\%10\}, nd=1;
26
     while(n/=10)ns[++nd]=n%10;
27
     while(nd)putchar(ns[nd--]+'0');
28 | }
 1
   #include <cstdio>
 2
 3
   class abio {
 4
      static const unsigned BUF_SZ = 65536;
 5
      FILE *istream, *ostream;
 6
      char ibuf[BUF_SZ], obuf[BUF_SZ];
 7
     bool reached_eof;
 8
     size_t ip, isz;
 9
     size_t op, osz;
10
      inline void clear_ibuf(void) {
11
        ip = isz = 0u;
12
     inline void clear_obuf(void) {
13
14
        op = osz = 0u;
15
16
     inline void clear_buffer(void) {
17
        reached_eof = false;
18
        clear_ibuf();
19
        clear_obuf();
20
21
     inline size_t read_buffer(void) {
        isz = std::fread(ibuf, sizeof(char), BUF_SZ, istream);
22
```

```
23
       ip = 0;
24
        return isz;
25
26
     inline size_t write_buffer(void) {
27
       if(osz) {
28
          size_t ret = std::fwrite(obuf+op, sizeof(char), osz-op, ostream);
29
          op += ret;
30
          if(op == osz) clear_obuf();
31
          return ret;
32
33
       return 0;
34
35
     inline abio &reach_eof(void) {
        reached_eof = true;
36
        return (*this);
37
38
   public:
39
40
     static const char endl = '\n':
41
     abio(FILE *input = stdin, FILE *output = stdout) {
42
        this—>istream = input;
43
        this->ostream = output;
44
        clear_buffer();
45
     abio(const char *input, const char *output) {
46
47
       this->istream = std::fopen(input, "r");
48
       this—>istream = std::fopen(output, "w+");
49
        clear_buffer();
50
     }
51
     ~abio(void) {
       write_buffer();
52
53
        std::fclose(istream);
54
       std::fclose(ostream);
55
56
     operator bool() const {
57
       return (!reached_eof);
58
59
     inline int getchar(void) {
60
       if(isz == ip) read_buffer();
61
        if(isz == ip) return EOF;
62
        return ibuf[ip++];
63
64
     inline int putchar(int ch) {
65
       if(osz == BUF_SZ) write_buffer();
       if(osz == BUF_SZ) return EOF;
66
        return (obuf[osz++] = ch);
67
68
69
     abio &read_int(int &x) {
70
       int flag = 0, ch = getchar();
        for (; (EOF!=ch)\&\&((ch<'0')||(ch>'9')); ch=getchar()) if ('-'==ch) flag = 1;
71
       if (EOF == ch) return (this->reach_eof());
72
73
       x = 0;
74
        for (; (ch>='0')&&(ch<='9'); ch=getchar()) x = x * 10 + (ch - '0');
75
        if (flag) x *= (-1);
76
        return (*this);
77
78
     abio &read_ll(long long int &x) {
79
        int flag = 0, ch = getchar();
        for (; (EOF!=ch)\&((ch<'0')||(ch>'9')); ch=getchar()) if ('-'==ch) flag = 1;
80
81
       if (EOF == ch) return (this->reach_eof());
82
       x = 011;
83
        for (; (ch>='0')&(ch<='9'); ch=getchar()) x = x * 10ll + (ch - '0');
84
       if (flag) x *= (-111);
85
        return (*this);
86
     }
```

```
87
       abio &read_unsigned(unsigned &x) {
 88
         int ch = getchar();
 89
         for(; (EOF != ch) && ((ch < '0') || (ch > '9')); ch = getchar());
 90
         if (EOF == ch) return (this->reach_eof());
 91
         x = 0u;
 92
         for(; (ch >= '0') && (ch <= '9'); ch = getchar()) x = x * 10u + (ch - '0');
 93
         return (*this);
 94
 95
       abio &read_ull(unsigned long long int &x) {
         int ch = getchar();
 96
 97
         for(; (EOF != ch) && ((ch < '0') || (ch > '9')); ch = getchar());
 98
         if (EOF == ch) return (this->reach_eof());
 99
         x = 0ull;
100
         for(; (ch >= '0') && (ch <= '9'); ch = getchar()) x = x * 10ull + (ch - '0');
101
         return (*this);
102
103
       /* set interrupt as '\n' to read a whole line. */
104
       abio &read_s(char *s, const char interrupt = ''_') {
105
         int ch = getchar();
106
         while((EOF!=ch)&&(ch<'!'||ch>'~'))ch=getchar();
107
         if(EOF==ch) return (this->reach_eof());
         for(; (EOF!=ch)&&(interrupt!=ch)&&(ch>='\'\'\'\'\', ch=getchar())(*s++)=ch;
108
109
         (*s)=0;
110
         return (*this);
111
       abio &write_int(int x, char append = 0) {
112
113
         int d[20], nd=0;
114
         if(0==x) putchar('0');
115
         if(x<0) {
116
           putchar('-');
117
           X=-X;
118
119
         while(x) {
120
           d[nd++]=x%10;
121
           x/=10;
122
123
         while(nd—)putchar('0'+d[nd]);
124
         if(append)putchar(append);
125
         return (*this);
126
127
       abio write_ll(long long int x, char append = 0) {
128
         int d[20], nd=0;
129
         if(0==x) putchar('0');
130
         if(x<0) {
131
           putchar('-');
132
           X=-X;
133
         while(x) {
134
135
           d\lceil nd++\rceil=x\%10;
136
           x/=10;
137
138
         while(nd—)putchar('0'+d[nd]);
         if(append)putchar(append);
139
140
         return (*this);
141
142
       abio \&write\_unsigned(unsigned x, char append = 0) {
143
         int d[20],nd=0;
144
         if(0==x) putchar('0');
145
         while(x) {
146
           d[nd++]=x%10;
147
           x/=10;
148
         while(nd—)putchar('0'+d[nd]);
149
150
         if(append)putchar(append);
```

```
151
         return (*this);
152
       abio &write_ull(unsigned long long int x, char append = 0) {
153
154
         int d[20],nd=0;
         if(0==x) putchar('0');
155
156
         while(x) {
157
           d[nd++]=x%10;
158
           x/=10;
159
160
         while(nd—)putchar('0'+d[nd]);
161
         if(append)putchar(append);
162
         return (*this);
       }
163
       abio &write_s(const char *s, char append = 0) {
164
165
         while(*s) putchar(*s++);
166
         if(append) putchar(append);
167
         return (*this);
168
169
       abio &operator>>(char &ch) {
170
         ch = getchar();
171
         if(E0F==ch) return (this->reach_eof());
172
         return (*this);
173
174
       abio &operator>>(int &x) {
175
         return read_int(x);
176
177
       abio &operator>>(long long int &x) {
178
         return read_ll(x);
179
       abio &operator>>(unsigned &x) {
180
181
         return read_unsigned(x);
182
183
       abio &operator>>(unsigned long long int &x) {
184
         return read_ull(x);
185
186
       abio &operator>>(char *s) {
187
         return read_s(s);
188
189
       abio &operator<<(const char ch) {
190
         putchar(ch);
191
         return (*this);
192
       abio &operator<<(const int x) {</pre>
193
194
         return write_int(x);
195
196
       abio &operator<<(const long long int x) {
197
         return write_ll(x);
198
199
       abio &operator<<(const unsigned x) {</pre>
200
         return write_unsigned(x);
201
202
       abio &operator<<(const unsigned long long int x) {</pre>
203
         return write_ull(x);
204
205
       abio &operator<<(const char *s) {</pre>
206
         return write_s(s);
207
208
    |} io;
```

### 7.2 Random Numbers

1 |#include <algorithm>

```
2
   |#include <chrono>
   #include <iostream>
 3
   #include <random>
   #include <vector>
 6
   using namespace std;
 7
 8
   const int N = 3000000;
 9
10
   double average_distance(const vector<int> &permutation) {
11
     double distance_sum = 0;
12
13
     for (int i = 0; i < N; i++)
       distance_sum += abs(permutation[i] - i);
14
15
16
      return distance_sum / N;
17
   }
18
19
   int main() {
20
     /* use mt19937_64 if you want 64-bit random numbers */
21
     mt19937 rng(chrono::steady_clock::now().time_since_epoch().count());
22
     vector<int> permutation(N);
23
24
      for (int i = 0; i < N; i++)
25
       permutation[i] = i;
26
27
     shuffle(permutation.begin(), permutation.end(), rng);
28
     cout << average_distance(permutation) << '\n';</pre>
29
30
     for (int i = 0; i < N; i++)
31
       permutation[i] = i;
32
     for (int i = 1; i < N; i++)
33
34
        swap(permutation[i], permutation[uniform_int_distribution<int>(0, i)(rng)]);
35
36
      cout << average_distance(permutation) << '\n';</pre>
37
38
39
40
   // rand() * rand() % M
41
   // or
42
   // rand() << 16 | rand()
43 // maybe also work in some scene;
       Appendix
   8
   8.1 C++ Reference
   8.1.1 Debug
 1 | #ifdef JDEBUGMODE
   #define jdebug(format, ...) fprintf(stderr, "L%d:" format, __LINE__, __VA_ARGS__)
 2
   |#define jshow(...) fprintf(stderr, "%s\n", #__VA_ARGS__)
   |#define jdebug(...) (void (0))
   #define jshow(...) (void (0))
   #endif
   8.1.2 STL
   bitset
 1 |template <size_t N> class bitset;
```

```
access
   count Count bits set
   test Return bit value
   any Test if any bit is set
   none Test if no bit is set
   all Test if all bits are set
   operations
   set Set bits 1
   reset Reset bits o
   flip Flip bits
   to_string
   to_ullong to unsigned long long
   could be used for unordered set or unordered map
 1 | template <class T> struct hash;
                                                 // unspecialized
 2 | template <size_t N> struct hash<bitset<N>>; // bitset specializatio
   unordered_map 相对于 map, 插入慢, 查询快.
   multiset 对于 erase 操作,如果传值进去,会把所有该值的元素删去;如果传迭代器,则只删一
   个元素。
   other
   template <class InputIterator1, class InputIterator2>
 1
     bool includes ( InputIterator1 first1, InputIterator1 last1,
 2
 3
                      InputIterator2 first2, InputIterator2 last2 );
 4
 5
   template <class InputIterator1, class InputIterator2, class Compare>
 6
     bool includes ( InputIterator1 first1, InputIterator1 last1,
 7
                      InputIterator2 first2, InputIterator2 last2, Compare comp );
 8
   auto il = { 10, 20, 30 }; // the type of il is an initializer_list
   8.2 Java Reference
   8.2.1 Basic
   Structure
   |import java.io.*;
   import java.util.*;
 3
   import java.math.*;
   public class Main {
 5
     public static final int maxn = 50050;
 6
 7
     public static int[] int_array = new int[maxn]; /** Array */
     public static int[] another_arr = {1, 2, 3, 5};
 8
 9
     public static void main(String[] args) throws Exception {
10
        Scanner cin = new Scanner(System.in);
11
       int a = cin.nextInt(), b = cin.nextInt();
12
       System.out.println(a + b);
       for (int i = 0; i < 4; i++)
13
14
          System.out.println(another_arr[i]);
15
     }
16 | }
```

#### Constant

```
1 | public static final int A = 0;
Array
1 | int [] a = new int[5];
2 | int [] b = {10, 35, 45, 89, 90};
```

### Bit op

The Java programming language also provides operators that perform bitwise and bit shift operations on integral types. The operators discussed in this section are less commonly used. Therefore, their coverage is brief; the intent is to simply make you aware that these operators exist.

The unary bitwise complement operator "~" inverts a bit pattern; it can be applied to any of the integral types, making every "0" a "1" and every "1" a "0". For example, a byte contains 8 bits; applying this operator to a value whose bit pattern is "00000000" would change its pattern to "11111111".

The signed left shift operator "<<" shifts a bit pattern to the left, and the signed right shift operator ">>" shifts a bit pattern to the right. The bit pattern is given by the left-hand operand, and the number of positions to shift by the right-hand operand. The unsigned right shift operator ">>>" shifts a zero into the leftmost position, while the leftmost position after ">>" depends on sign extension. The bitwise & operator performs a bitwise AND operation.

The bitwise operator performs a bitwise exclusive OR operation.

The bitwise | operator performs a bitwise inclusive OR operation.

# 8.2.2 BigInteger

Immutable arbitrary-precision integers. All operations behave as if BigIntegers were represented in two's-complement notation (like Java's primitive integer types). BigInteger provides analogues to all of Java's primitive integer operators, and all relevant methods from java.lang.Math. Additionally, BigInteger provides operations for modular arithmetic, GCD calculation, primality testing, prime generation, bit manipulation, and a few other miscellaneous operations.

#### API

- ZERO, ONE, TEN
- Constructors
- 1 |public BigInteger(String val, int radix)
  - primes

- · valueOf
- 算术运算

```
public BigInteger add(BigInteger val)
public BigInteger subtract(BigInteger val)
public BigInteger multiply(BigInteger val)
public BigInteger divide(BigInteger val)
public BigInteger[] divideAndRemainder(BigInteger val) // [quotient, remainder]
public BigInteger remainder(BigInteger val)
public BigInteger pow(int exponent)
public BigInteger gcd(BigInteger val)
public BigInteger abs()
public BigInteger negate()
public int signum() // -1, 0 or 1
```

```
12 | public BigInteger mod(BigInteger m) // always returns a non-negative BigInteger.
13 | public BigInteger modPow(BigInteger exponent, BigInteger m)
14 | public BigInteger modInverse(BigInteger m)

    位运算

 1 | public BigInteger shiftLeft(int n)
   public BigInteger shiftRight(int n)
   public BigInteger and(BigInteger val)
   public BigInteger or(BigInteger val)
   public BigInteger xor(BigInteger val)
   public BigInteger not()
   public boolean testBit(int n)
   public BigInteger setBit(int n)
   public BigInteger clearBit(int n)
10 public BigInteger flipBit(int n)
11 | public int getLowestSetBit() // lowbit
12 public int bitLength()
13 | public int bitCount()
  比较
 1 | public int compareTo(BigInteger val) // -1, 0 or 1 if this () val
  public BigInteger min(BigInteger val)
 3 | public BigInteger max(BigInteger val)

    transform

 1 | public int hashCode()
   public String toString(int radix)
 3 | public int intValue()
 4 | public long longValue()
```

#### 8.2.3 BigDecimal

Immutable, arbitrary-precision signed decimal numbers. A BigDecimal consists of an arbitrary precision integer unscaled value and a 32-bit integer scale. If zero or positive, the scale is the number of digits to the right of the decimal point. If negative, the unscaled value of the number is multiplied by ten to the power of the negation of the scale. The value of the number represented by the BigDecimal is therefore ( $unscaledValue \times 10^{-scale}$ ).

### API

Constructors

```
public BigDecimal(String val)
public BigDecimal(double val)
public BigDecimal(BigInteger val)
public BigDecimal(int val)
public static BigDecimal valueOf(long unscaledVal, int scale) // u * 10^(-scale)
public static BigDecimal valueOf(double val)

• arithmetic operation

public BigDecimal add(BigDecimal augend)
public BigDecimal subtract(BigDecimal subtrahend)
public BigDecimal multiply(BigDecimal multiplicand)
public BigDecimal divide(BigDecimal divisor)
```

- 5 | public BigDecimal divideToIntegralValue(BigDecimal divisor)
  6 | public BigDecimal remainder(BigDecimal divisor)
- 7 | public BigDecimal[] divideAndRemainder(BigDecimal divisor)
- 8 public BigDecimal pow(int n)
- 9 public BigDecimal abs()

### 8.2.4 Sorting

java.util.Arrays

### 8.3 Environment test items

• 一秒运算次数,带模一秒跑多少

public BigDecimal min(BigDecimal val)
public BigDecimal max(BigDecimal val)

- 行末空格
- assert (0) 是 WA 还是 RE
- RAND MAX大小