A versatile test bench for photomultiplier tube characterization and its application in the DAMPE-PSD

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Abstract

Performance characterization for massive photomultiplier tubes (PMT) (PMTs) is a frequently encountered procedure in large nuclear and particle experiments. To facilitate this work, a dedicated test bench system has been developed at the Institute of Modern Physics, Chinese Academy of Sciences. The two-dimensional photocathode position scanning capability is an intrinsic function of the test bench bench, and up to 25 PMTs, with the diameter smaller than \(\frac{(2"\)}{2"\)}, 2"\), can be tested simultaneously. The parameters of the light source pulses can be adjusted in a wide range, thus making it suitable for various characteristics measurements. The test bench system is highly automated with all the controlling operations integrated into a single software. Additionally, the hardware platform is extensible which allows complex testing schemes, and the modularity in the software design make makes the migration from one testing configuration to another light-weight and efficient. All these features make the test bench versatile and reusable in different experiments. It has been first used in the construction of the Plastic Scintillator Detector (PSD) plastic scintillator detector of DArk Matter Particle Explorer (DAMPE), Explorer, and a total of 570 Hamamatsu R4443 tubes were tested successfully. The performance was verified and the testing results are also reported in this aritcle.

Keywords: Photomultiplier tube, Large detector systems for particle and astroparticle physics, Test bench system, DAMPE-PSD

ArticleNote

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Introduction

Since their invention about 80 years ago, photomultiplier tubes (PMTs) have been widely used as photosensors in nuclear and particle physics experiments due to the high sensitivity, fast time response and other inherent benefits. Today, large-scale experiments may contain thousands of PMTs or more. To achieve optimal detector performance, it's it is important to characterize each PMT before they are put into usage. Sometimes, general information provided by manufacturers is not particularly useful for a specific experiment. On the other hand, some experiments may have special requirements on certain characteristics of the PMTs that are absent from the datasheets. Therefore, characterization of PMTs is a mandatory step in

setting up large-scale experiments.

Characterizing a large number of PMTs in limited time is a challenging job. Usually, a dedicated test bench is constructed to facilitate this work [1–3]. Setting up a system like this is not trivial work. It requires investment of considerable amount of time and effort. On the other hand, testing of PMTs is a common task and many components of the testing configuration can be shared among different applications. Thus, it is beneficial to build a single PMT test system that could be easily reconfigured for various experiments.

In this paper, a versatile test bench dedicated for characterization of large amount of PMTs is described. The test bench is designed to be a standard laboratory equipment for the PMT characterization tasks of several experiments prepared and planned at the Institute of Modern Physics (IMP), Chinese Academy of Sciences (CAS). To accommodate various requirements of different experiments and make the test bench reusable in different applications, great attention has been paid to the selection of hardware components and the design of the software framework (see Sect. 2). The first user of this test bench is the Plastic Scintillator Detector plastic scintillator detector (PSD), a sub-detector of the DArk Matter Particle Explorer (DAMPE) [4] which is a satellite-borne experiment. Characterization of PMTs for PSD using this test bench was very successful. The performance of the test bench has been demonstrated. Summary of the test results are is presented in Sect. 3.

Description of the test bench

The characteristics of the test bench can be summarized as follows:

- Large capacity: This is the primary driving force for developing a test bench dedicated for PMT characterization. Testing multiple tubes simultaneously can increase the efficiency tremendously, and this is a critical factor in projects involving a large number of PMTs.
- Automation: A single test run for PMT characterization usually takes several hours. Most steps of this process are routine operations such as changing voltage, voltage and sweeping light intensity and so on. intensity. Manual operations are inefficient and unreliable in such a long period. Computer controllable hardware is preferred in building the test bench, and corresponding software has been developed to automate common routine operations. Human intervention is only expected at the beginning of the test run when mounting the PMTs and configuring the software, software and at the end of the run when unmounting the PMTs and assessing the test results.
- Versatility: Various potential use cases have been considered in the design of the test bench, specifically bench; specifically, the cathode scanning capability was incorporated as an intrinsic function of the test bench. Appropriate hardware has been set up in the first place, and general-purpose general purpose devices were adopted whenever possible.
- Flexibility: The hardware platform is expandable and the components are loosely coupled, thus allowing complex testing configurations and convenient replacement or upgrade of the hardware. The software was carefully designed to provide abstract interfaces for device control. Thus, swapping hardware components has little impact on the high level functionality. This makes the software compatible across platforms.

A schematic diagram of the PMT test bench is shown in Fig. 1. Up to 25 PMTs can be characterized at the same time. Light pulses from a blue light emitting light-emitting diode (LED) are distributed to the PMTs through an integrating sphere and a transparent fiber bundle, which are mounted on a three-axes three-axis motorized stage. PMTs under test are mounted on a separate fixed stage. This allows one to scan the photocathodes of all PMTs simultaneously. There are also two monitoring PMTs fixed on the motorized stage. Their positions remained unchanged relative to the input fiber in all operations operations, and they were used to monitor the stability of the LED as well as the performance of the test bench system. Both stages are housed in a black light-tight container made of aluminum alloy (see Fig. 2(a)), with a dimension of $\frac{176 \text{ cm} \times 100 \text{ cm} \times 78 \text{ cm}}{176 \text{ cm} \times 100 \text{ cm} \times 78 \text{ cm}}$.

For the proper operation of the test bench, a variety of auxiliary devices are needed. They are divided into four functional groups according to the functions they provide: motion control (including the stepper driver), pulse generation (including the LED driver), high voltage high-voltage supply and data acquisition (DAQ). The devices for motion control and pulse generation are tightly coupled to the test bench itself, and thus the same hardware can be reused for nearly all the use cases. On the other hand, the devices for DAQ and high voltage high-voltage supply are closely related to the intended large-scale experiment which needs PMT characterization, and project-specific hardware is often chosen in different experiments. Originally, a

universal CAEN SY1527LC [6] power crate was adopted as the high voltage high-voltage supply system, and a CAMAC crate with the CC-USB crate controller [7] was used for the DAQ. All the auxiliary devices were placed outside the light-tight container, and the cables were led out through light-tight feedthroughs.

The whole test bench sits in an ISO class 8 cleanroom at IMP, and the room temperature is kept to be $(22\pm \frac{2^{\circ}}{\circ})$ all the time. In the following sections, the key components of the test bench are described in detail.

Motorized and fixed stages

The motorized and fixed stages form the main body of the test bench. All other objects inside the light-tight container are mounted on the top of these two stages. In particular, customized fixtures for the fibers, PMTs and the integration sphere have been designed for convenient and accurate positioning.

As shown in Fig. $\frac{2(b)}{b}$, b, both stages are covered with a $\frac{1560 \text{ mm} \times 250 \text{ mm}}{2.5 \text{ cm}}$ 1560 mm \times 250 mm optical breadboard. These breadboards are made of $\frac{2.5 \text{ cm}}{2.5 \text{ cm}}$ thick stainless steel, providing substantial resistance to deformation in this application. The grid pattern of tapped holes on their surface provides extra flexibility in the testing configuration as well as facilitates mounting/unmounting operations.

The load capacity of the motorized stage is 30 kg, and it can perform a three-dimensional motion driven by three stepping motors. The minimum step size is \(1.56\,{\upmu }\hbox {m}\). The stage can move up to 60 mm horizontally and 70 mm vertically. This range is large enough to cover commonly used PMTs with diameters smaller than \(2"\). The stage can also move along the third direction for 15 mm, which is to control the gap between the fiber and the input window of PMT and to protect the fibers while mounting/unmounting the tubes. All the stepping motors are controlled by a motion controller board MPC07SP from Leetro [8], which possesses a PCI (Peripheral Component Interconnect (peripheral component interconnect bus) interface for remote control.

Light source

A high-power blue LED (3 W, 465 nm to 485 nm) (3 W, 465–485 nm) is adopted as the light source of the test bench. The spectrum range of the LED is compatible with the spectral response of the most common photocathode. It has been used before in the monitoring and calibration system of Neutron Wall Detector neutron wall detector at IMP [5] and proved to be suitable for massive light distribution. The LED is fixed on a specially designed base using thermally conductive silicone rubber (see Fig. 3(a)), a) and then coupled to a 5 cm diameter 5-cm-diameter integrating sphere [9] directly. The integrating sphere is a perfect light integrator and transforms the light output of LED into a uniform distribution. Thus, the amount of photons reaching each fiber, which is a fixed fraction of the total output of the LED, is independent of position. This makes the coupling between the light source and the fiber bundle much more easier and flexible, and stable light output difference between all the fiber channels can be achieved (see next section).

For PMT characterization, light pulses of short duration are needed. The general purpose pulse generator, Tektronix AFG3252 [10], is adopted to drive the LED directly. Although it is not designed to be a dedicated LED driver, the performance of AFG3252 is quite satisfactory (an example is shown in Fig. 4). AFG3252 can adjust all the pulse parameters in a wide range with high precision. This is a critical feature for a test bench with an objective of versatility, as diverse requirements for the light pulses exist in different applications. Besides the LED driving pulse, AFG3252 can also output a synchronized pulse as the trigger signal to the DAQ, which will simplify the DAQ configuration in most cases.

The uniformity of the light source has been verified by using the same optical fiber to scan the output port surface of the integrating sphere using a three-axes three-axis alignment stage. The other end of the fiber was then coupled to a fixed PMT to measure the light output intensity. An uniformity within \(\pm 0.5\,\%\) has been reached, and this is sufficient to eliminate the spatial effect of light distribution.

Fiber bundle

A bundle of 35 plastic clad silica fibers [11] (25 for test channels, 2 for monitoring channels and 8 spares) is utilized to guide light pulses to each PMT. Each fiber is $\frac{1.5 \text{ m}}{1.5 \text{ m}}$ long and has a $\frac{400}{\text{m}}$ thick or $\frac{1.5 \text{ m}}{1.5 \text{ m}}$ thick or $\frac{1.5 \text{ m}}{1.5 \text{ m}}$

the numerical aperture (NA) is 0.37. The relatively large core and NA make the fiber an efficient light extractor of integrating sphere output.

To protect the fibers from mechanical damage, both ends of the fiber bundle are coated with stainless steel ferrules (see Fig. 3(a)). a). The bundle end is coupled to the center of the output port of the integrating sphere using a fiber alignment stage (see Fig. 3(b)). b). On the other end, each fiber is fixed using a customized fiber holder which allows two-dimensional position adjustment, and is aligned to the center of the corresponding PMT input window with a precision of 0.5 mm.0.5 mm.

After coupling the fiber bundle to the integrating sphere, the light output difference between all the fiber channels was calibrated. The light output difference $\frac{(\frac{t}{tau_\text{text} {fiberid}})}{(\frac{t}{text} {fiberid})}$ is determined by comparing the light output intensity of each fiber channel ($\frac{t}{text} {fiberid}$)(L_{\text} {ref}})) to that of a reference channel ($\frac{t}{text} {ref}$)(L_{\text} {ref}})) under the same LED output as follows:

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Software framework

The software for the test bench is developed under Windows using C++. It can be divided into three hierarchies as follows:

- 1. *Device abstraction*, which not only serves as an interface to the hardware, but also handles the abstraction of different types of devices.
- 2. *Framework libraries*, which defines a general testing procedure and provides utility classes for configuration and management.
- 3. User interface, which provides command line based or graphical executable for user interaction.

Instead of developing a dedicated program each time a hardware changes, an abstraction of the devices is adopted to separate the testing procedure from hardware implementation details. Abstract classes are defined for the four types of essential equipments as shown in the rounded boxes in Fig. 1. New hardware of each type only needs to inherit from the corresponding abstract class and implement its interface methods and then registered in the singleton device management class *PTDeviceManager* (*PT* is the abbreviation for *PMT Test*), leaving all other part of the software unchanged.

Built upon the abstract device interface, a general testing framework is defined as shown in Fig. 6. *PTVProgram* (*V* in the class name indicates that it's it is an abstract class) represents the measurement for a specific characteristic of PMT, such as cathode uniformity, gain uniformity and so on. gain. *PTVTest* is a subunit of *PTVProgram*, which encapsulates the real device operations performed under a specific condition. A *PTVProgram* may consist of a series of *PTVTest*s, which are invoked sequentially in a test loop. For example, in cathode uniformity measurement, the stepping motor will move to a series of positions and the PMT response will be recorded by the DAQ at each position. Here, device operations performed at each position constitute a *PTVTest* and tests at all positions constitute a *PTVProgram*. Additional operations may be added in the *PreTest* and *PostTest* methods of *PTVProgram*, which will be invoked before and after the test loop loop, respectively. *PTVPrograms* of various testing objectives are finally chained together to constitute a complete characterization of PMT.

For easy usage, a light-weight user interface based on PDCurses [12] has also been developed. This program features in device control, status monitoring and information logging. A decoding function from binary file to ROOT file [13] is also incorporated into it for online monitoring. However, more detailed analysis analyses based on the ROOT file are considered project-specific, project specific and thus not included in the program.

Application in the construction of DAMPE-PSD

The PSD detector of the DAMPE project is a large-area plastic scintillator array. It aims for heavy ion charge measurement up to \(Z=20\) as well as high energy e/\(\gamma \) discrimination by measuring the deposited energy. PSD adopts the Hamamatsu R4443 PMT for the scintillation light detection, which is a ruggedized version of the previous R647 [14]. The timing information from R4443 is not needed. To cover the large dynamic range, two dynodes, 5 and 8, are readout for each R4443 tube, and the signals are processed by a highly-sensitive highly sensitive ASIC chip (VA160 [15],\(\cdot(-3\), \hbox \{pC\\sim\{pC\\\}\) \{\text{to}}\\ \\ 13\\, \hbox \{pC\\\)) followed by an ADC of \(\frac{14-bits}{14-bit}\) resolution \([16]\). Both the gain of dynode8 and the gain between dynode8 and dynode5 of each PMT need to be measured during the characterization.

Concrete *PTVPrograms* for gain, dynode8/dynode5 ratio and cathode uniformity measurements have been implemented. To accommodate the low input range and obtain more realistic results, the ground test electronics system of PSD [16] are is utilized instead of the conventional CAMAC system. The ground test ground test system is mainly a copy of the real ones used in space, and a dedicated *PTVDaq* class based on the NI-VISA library [17] has been implemented for it.

About 20 tubes are tested in a single run, and it takes normally five hours 5 h for a complete characterization, including two hour's 2-h warming time. 28-Twenty-eight test runs were performed in about a month, and totally 570 R4443 tubes have been characterized. All the data and analysis results have been stored in a MySQL database for easy query, and tubes for installation will be selected based on these data.

The selection procedure is not the subject of this article. Here, only the major results are presented with a focus on the demonstration of the validity of the test bench.

Relative gain of dynode8

PSD requires a 25 % 25 % uniformity in all detection units. Therefore, a relative measurement of the gain is adopted by comparing the responses of the PMTs to the same input light intensity. A pushe pulse generator setting with an intermediate light intensity is selected for this measurement, so that the responses of all the tested PMTs are within the linear range.

Due to the light output fluctuation of the LED between different test runs and the light output difference between different fiber channels, two corrections were applied to the measured raw data of each tested PMT to normalize the input light intensity and get the real response as follows:

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 $$$ \left(\frac{A_\text{corr} = \frac{A_\text{ext {raw}}{k_\text{runid}}}{A_\text{ext {runid}}}, A_{\text{corr}} = \frac{A_\text{ext {runid}}}{A_\text{ext {runid}}}, A_{\text{corr}} = \frac{A_{\text{ext {runid}}}}{A_{\text{ext {runid}}}}, A_{\text{ext {runid}}}, A_{$

where $\frac{A_\text{text \{raw\}}}{A_\text{text \{raw\}}}\$ is the mean value of the raw ADC spectrum measured at the specified pulse generator setting, $\frac{k_\text{text \{runid\}}}{k_\text{text \{runid\}}}\$ is the fluctuation of the LED output between different test $\frac{k_\text{text \{runid\}}}{k_\text{text \{fiberid\}}}\$ runs and $\frac{\text{text \{fiberid\}}}{k_\text{text \{runid\}}}\$ is the light output difference between fibers which has been measured in Sect. 2.3. $\frac{k_\text{text \{runid\}}}{k_\text{text \{runid\}}}\$ is calculated at each test run using one of two monitoring PMTs on the fixed stage, and it is the ratio between the response of the same monitoring PMT at the current run and that at the initial run. The relative gain $\frac{k_\text{text \{relative\}}}{k_\text{text \{relative\}}}\$ can then be obtained by directly dividing the $\frac{k_\text{text \{corr\}}}{k_\text{text \{corr\}}}\$

Seven different high voltages, from 700 $\frac{V}{V}$ to $\frac{1000 \text{ V}}{V}$ 1000 $\frac{V}{V}$ with a $\frac{50 \text{ V}}{V}$ 50 $\frac{V}{V}$ step, are scanned to obtain the gain variation as a function of supply voltage for each PMT, and the results are fitted using the power law function [18]. Based on the fitting result, the relative gain at any supply voltage can be calculated. Distribution of the relative gain at $\frac{V}{V}$ 450 $\frac{V}{V}$ is shown in Fig. 7, where the $\frac{V}{V}$ where the $\frac{V}{V}$

{corr}}\) of all tubes are divided by that of the tube with the smallest gain. A maximum of about 5.5 times difference in the gain has been observed.

Gain ratio between dynode8 and dynode5

The gain ratio between dynode8 and dynode5 is measured by varying the light intensity in a large range until saturation of the dynode8 signal is observed. The same procedure is repeated at 7 different supply voltages, from 700 $\frac{1000 \text{ V}}{1000 \text{ V}}$ to $\frac{1000 \text{ V}}{1000 \text{ V}}$ with a $\frac{50 \text{ V}}{1000 \text{ V}}$ to obtain the dynode8/dynode5 dependency on voltage. As with the gain of dynode8, the dependency can be fitted accurately with a power law function, as shown in the inset graph of Fig. $\frac{8(a)}{1000 \text{ V}}$. The ratio between the gain of dynode8 and dynode5 can then be calculated at any voltage value based on the fitting result. As an example, the distribution of dynode8/dynode5 ratios at a certain supply voltage is shown in Fig. $\frac{8(b)}{1000 \text{ V}}$.

Cathode uniformity

The cathode uniformity of R4443 is also checked using the test bench, which has a minimum effective area of about 10 mm in diameter. The measurement is performed by scanning the input window of R4443 in two perpendicular directions with a step of 1 mm. 1 mm. At each position, the relative gain is measured at a fixed light source setting according to the method described in Sect. 3.1, and a typical result is shown in Fig. 9.

The relative gain at each position is proportional to the total efficiency of light transmission, photoelectric conversion and electron collection at this point. A rapid drop of this efficiency is observed at the edge of the cathode surface. Defining the uniform region as a region with the efficiency fluctuation less than $\frac{10 \text{ }\%}{75 \text{ }\%}$ of the tested PMTs can have a uniform region larger than $\frac{9 \text{ }\text{mm}}{9 \text{ }\text{mm}}$ in diameter.

Stability of the test bench

The stability of the test bench during the PMT characterization for DAMPE-PSD can be extracted using the two fixed monitoring PMTs.

Monitoring PMTs underwent the same testing procedures as the tubes under test. Measurement results of the parameters of the monitoring PMTs in different test runs can be filled together, and the spread of the distribution is an indication of the uncertainty of the testing method. In this way, the uncertainty of the dynode8/dynode5 measurement is found to be $\frac{1.59 - \%}{1.59 - \%}$, and the uncertainty of relative gain measurement is $\frac{0.53 - \%}{0.53 - \%}$.

Conclusion

A PMT test bench system based on the modular design pattern has been developed at IMP, CAS. It can characterize 25 PMTs simultaneously and features in two-dimensional photocathode position scanning, configurable light pulse setting and highly automatic software control. A total of 570 R4443 PMT for the DAMPE-PSD detector have been characterized successfully using the test bench bench, and the stability of the test bench was demonstrated to be within \(\pm 0.5\, \%\). Considering the flexible and open platform it possesses, the test bench shall be useful for any other experiments that need massive PMT characterization.

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Fig. 1 Schematic diagram of the PMT test bench system

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Fig. 2 Main body of the PMT test bench. (a) a Light-tight container. (b) Motorized and fixed stages before assembly

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Fig. 3 The light Light distribution system. (a) 1) LED; 2) Integrating sphere; 3) Fiber bundle. (b) a (1) LED; (2) integrating sphere; (3) fiber bundle. b Integration of the components

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Fig. 4 An example Example of the PMT output waveform (extracted from dynode 8) in response to the light pulse drived driven by a square pulse of AFG3252 with 30 ns width and 5 ns leading/trailing time

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Fig. 5 Up: Light Up light output of 35 fibers measured at two light intensities with an amplitude difference of about 4 times (the *error bars* are too small to be seen). Bottom: Ratio Bottom ratio between the two measurements of each fiber, fiber; the results are consistent within \(\pm 0.3\,\%\)

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Fig. 6 General PMT testing framework. Fake code for a typical *PTVTest* implementation is presented as an example

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Fig. 7 Relative gain distribution measured at 850 V (against the tube with the smallest gain)

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Fig. 8 Result of dynode8/dynode5 measurement. (a) a An example of the measurement of dynode8/dynode5 ratio (the *error bars* are to small to be seen). Correlation between dynode5 and dynode8 at 1000V, 850V 1000, 850 and 700V 700 V is presented, the saturation of dynode8 signal is clearly seen. Power law fit to the measured dynode8/dynode5 of this tube at 7 voltage steps is shown in the *inset* graph. (b) graph. b Distribution of the dynode8/dynode5 ratio measured at 850 V 850 V

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Fig. 9 A typical cathode uniformity of R4443. Relative gain at each position is normalized to the center of the input window

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