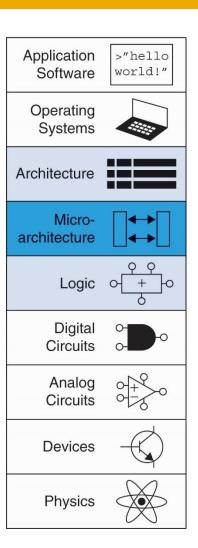
Digital Design & Computer Architecture Sarah Harris & David Harris

Chapter 7: Microarchitecture

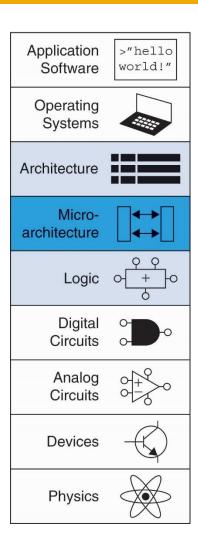
Chapter 7 :: Topics

- Introduction
- Performance Analysis
- Single-Cycle Processor
- Multicycle Processor
- Pipelined Processor
- Advanced Microarchitecture



Introduction

- Microarchitecture: how to implement an architecture in hardware
- Processor:
 - Datapath: functional blocks
 - Control: control signals



Microarchitecture

- Multiple implementations for a single architecture:
 - Single-cycle: Each instruction executes in a single cycle
 - Multicycle: Each instruction is broken up into series of shorter steps
 - Pipelined: Each instruction broken up into series of steps & multiple instructions execute at once

Processor Performance

Program execution time

Execution Time = (#instructions)(cycles/instruction)(seconds/cycle)

Definitions:

- CPI: Cycles/instruction
- clock period: seconds/cycle
- IPC: instructions/cycle = IPC

Challenge is to satisfy constraints of:

- Cost
- Power
- Performance

RISC-V Processor

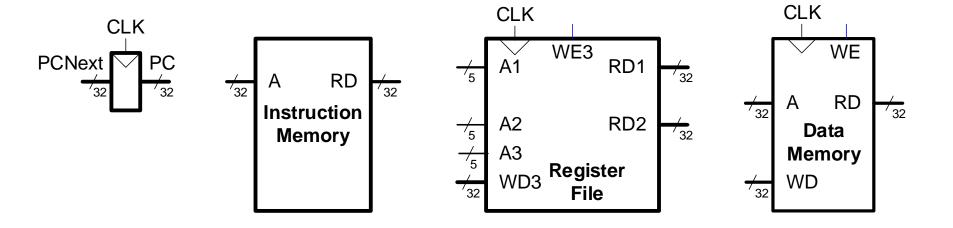
- Consider subset of RISC-V instructions:
 - R-type ALU instructions:
 - add, sub, and, or, slt
 - Memory instructions:
 - lw, sw
 - Branch instructions:
 - beq

Architectural State Elements

Determines everything about a processor:

- Architectural state:
 - 32 registers
 - PC
 - Memory

RISC-V Architectural State Elements



Chapter 7: Microarchitecture

Single-Cycle RISC-V Processor

Single-Cycle RISC-V Processor

- Datapath
- Control

Example Program

- Design datapath
- View example program executing

Example Program:

Address	Instruction	Type		Fiel	ds		Ma	chine Language
0x1000 L7:	lw x6, -4(x9)	I	imm_{11:0} 1111111111	rs1	f3 010	rd 00110	op 0000011	FFC4A303
0x1004	sw x6, 8(x9)	S	imm _{11:5} rs	s2 rs1 0110 01001	f3 010	imm _{4:0} 01000	op 0100011	0064A423
0x1008	or x4, x5, x6	5 R	funct7 rs	s2 rs1 0110 00101	f3 110	rd 00100	op 0110011	0062E233
0x100C	beq x4, x4, L	7 B		s2 rs1 0100 00100	f3 000	imm _{4:1,11} 10101	op 1100011	FE420AE3

Single-Cycle RISC-V Processor

Datapath: start with 1w instruction

• Example:
$$lw x6, -4(x9)$$

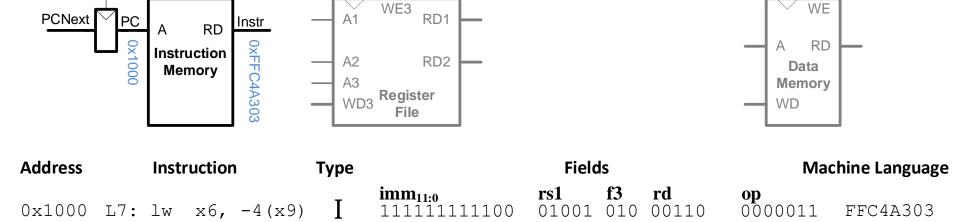
 $lw rd, imm(rs1)$

I-Type

31:20	19:15	14:12	11:7	6:0
imm _{11:0}	rs1	funct3	rd	op
12 bits	5 bits	3 bits	5 bits	7 bits

Single-Cycle Datapath: 1w fetch

STEP 1: Fetch instruction



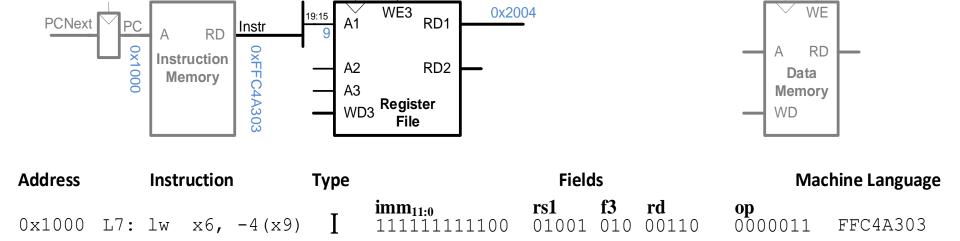
CLK

CLK

Single-Cycle Datapath: 1w Reg Read

STEP 2: Read source operand (**rs1**) from RF

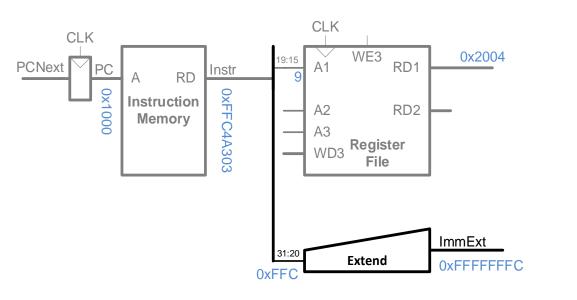
CLK

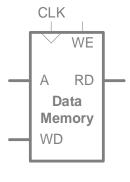


CLK

Single-Cycle Datapath: 1w Immediate

STEP 3: Extend the immediate

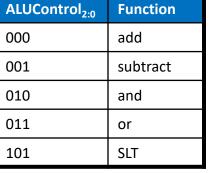


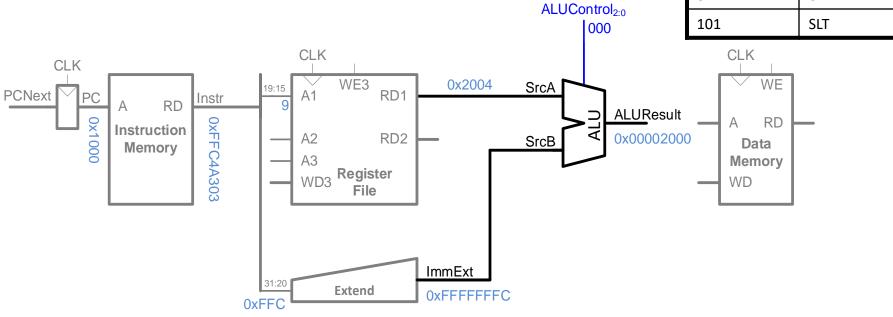


Address	Instruction	Type	Fields				Ma	chine Language
0x1000 L7:	lw x6, -4(x9	I	imm_{11:0} 111111111100	rs1 01001	f3 010	rd 00110	op 0000011	FFC4A303

Single-Cycle Datapath: 1w Address

STEP 4: Compute the memory address

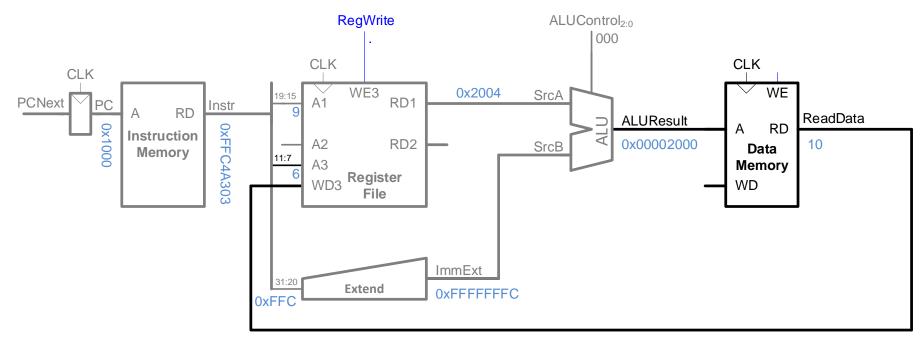


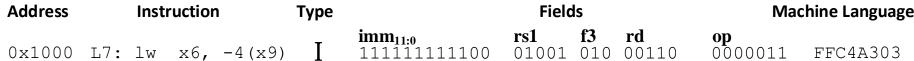


Address	Instruction	Type	Fields				Ma	chine Language
0x1000 L7:	lw x6, -4(x9)	Ţ	imm_{11:0} 111111111100	rs1 01001	f3	rd 00110	op 0000011	FFC4A303

Single-Cycle Datapath: 1w Mem Read

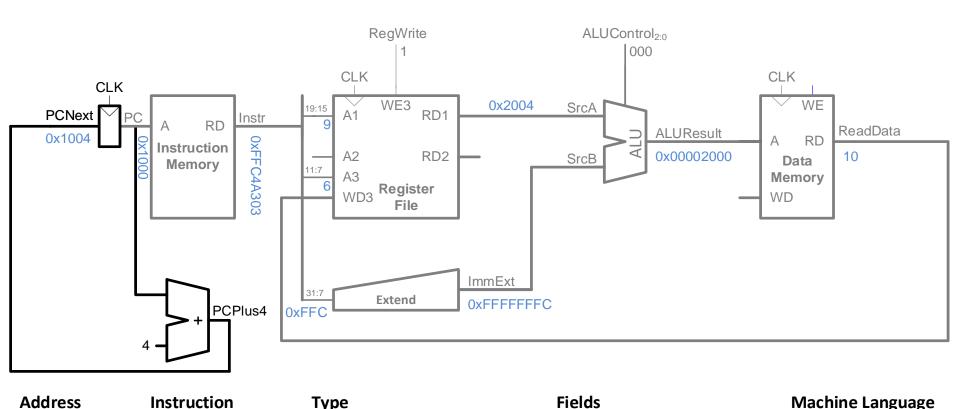
STEP 5: Read data from memory and write it back to register file





Single-Cycle Datapath: PC Increment

STEP 6: Determine address of next instruction



x6, -4(x9)

rd

00110

op 0000011

FFC4A303

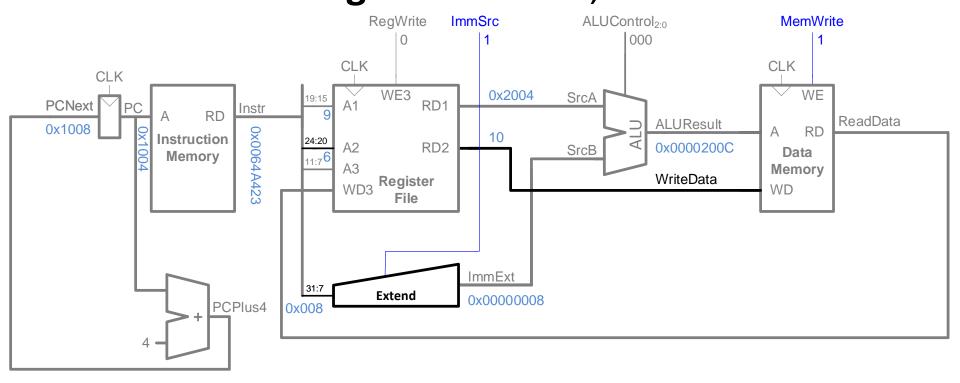
0x1000

Chapter 7: Microarchitecture

Single-Cycle Datapath: Other Instructions

Single-Cycle Datapath: sw

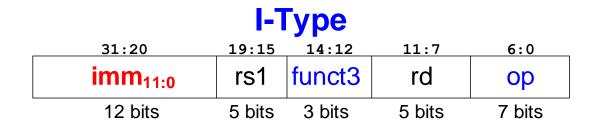
- Immediate: now in {instr[31:25], instr[11:7]}
- Add control signals: ImmSrc, MemWrite

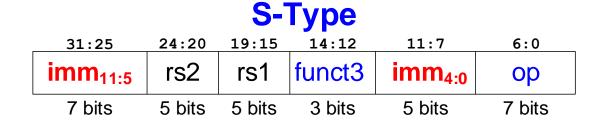


Address	Instruction	Type		Field	ls		Mad	chine Language
0x1004	sw x6, 8(x9)	S	imm _{11:5} 1		f3 010	imm_{4:0} 01000	op 0100011	0064A423

Single-Cycle Datapath: Immediate

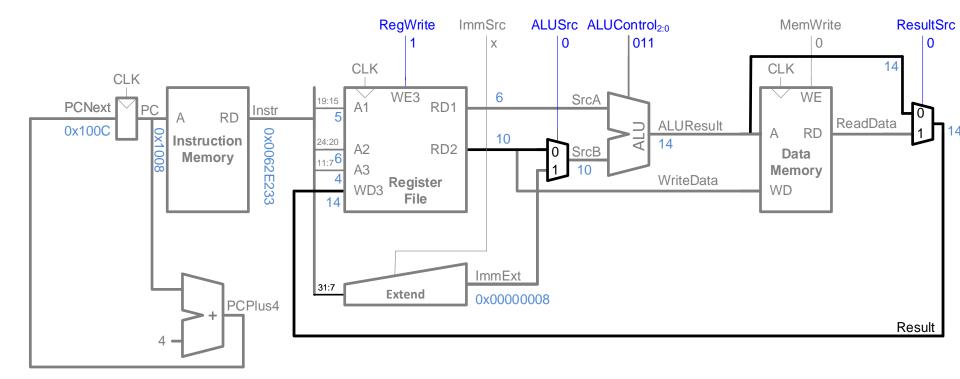
ImmSrc	ImmExt	Instruction Type
0	{{20{instr[31]}}, instr[31:20]}	I-Type
1	{{20{instr[31]}}, instr[31:25], instr[11:7]}	S-Type





Single-Cycle Datapath: R-type

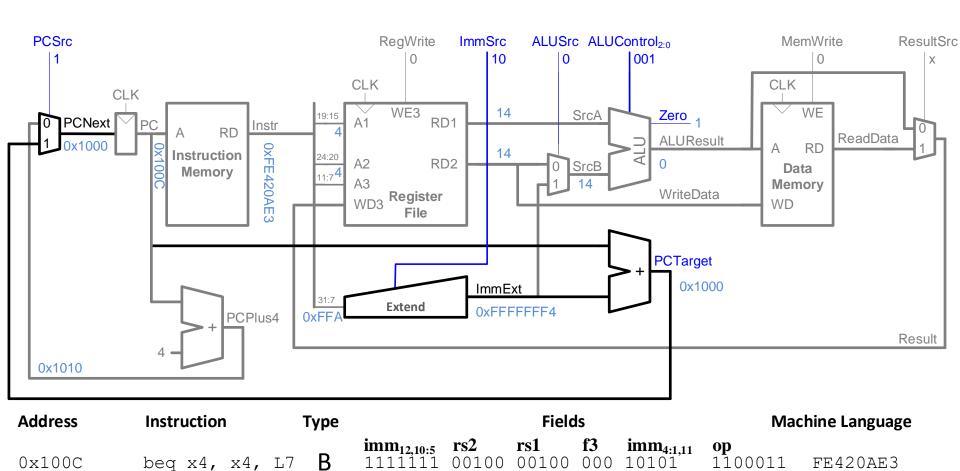
- Read from rs1 and rs2 (instead of imm)
- Write ALUResult to rd



Address	Instruction	Type			Field	ls		Mad	chine Language
0x1008	or x4, x5	5, x6 R	funct7	rs2 00110	rs1 00101	f3 110	rd 00100	op 0110011	0062E233

Single-Cycle Datapath: beq

Calculate target address: PCTarget = PC + imm



00100

00100

beg x4, x4, L7

10101

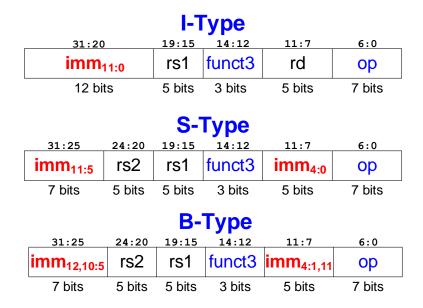
FE420AE3

000

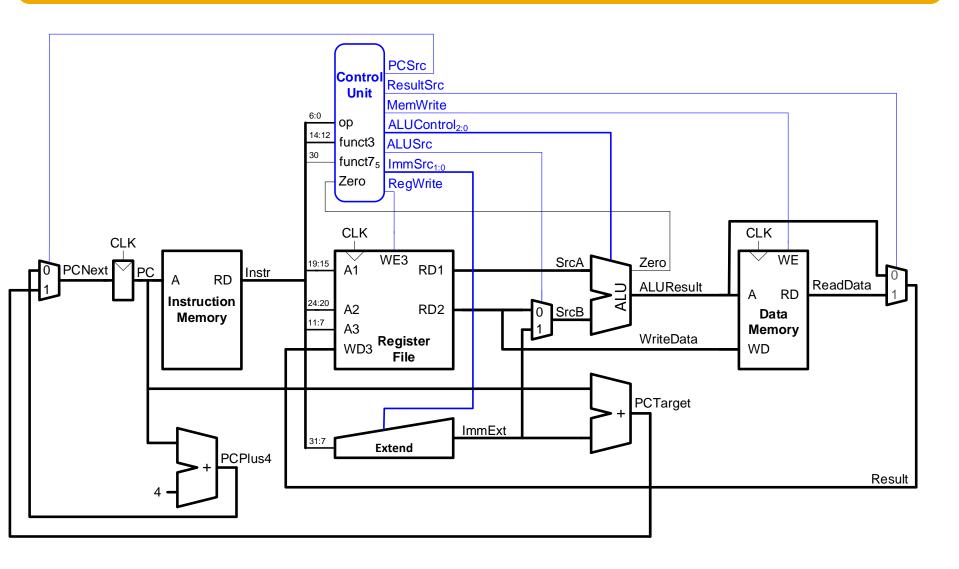
0x100C

Single-Cycle Datapath: ImmExt

ImmSrc _{1:0}	ImmExt	Instruction Type
00	{{20{instr[31]}}, instr[31:20]}	I-Type
01	{{20{instr[31]}}, instr[31:25], instr[11:7]}	S-Type
10	{{19{instr[31]}}, instr[31], instr[7], instr[30:25], instr[11:8], 1'b0}	B-Type



Single-Cycle RISC-V Processor



Chapter 7: Microarchitecture

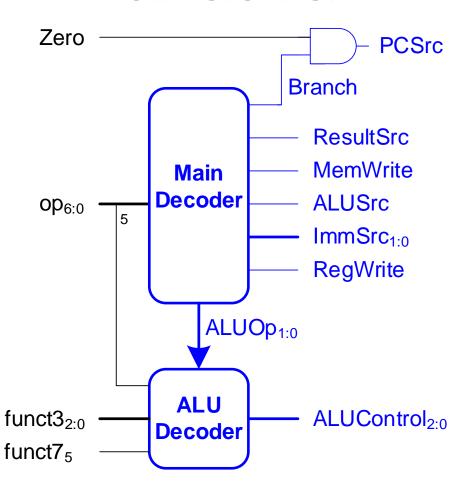
Single-Cycle Control

Single-Cycle Control

High-Level View

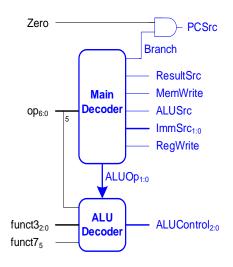
PCSrc Control ResultSrc Unit **MemWrite** Instr 6:0 op ALUControl_{2:0} 14:12 funct3 **ALUSrc** 30 funct7₅ ImmSrc_{1:0} Zero Zero RegWrite

Low-Level View



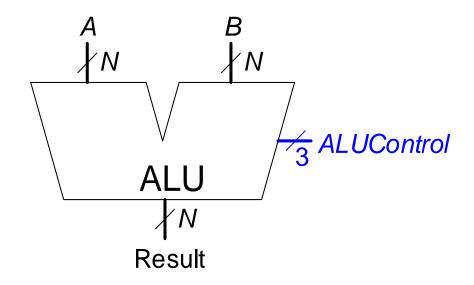
Single-Cycle Control: Main Decoder

ор	Instr.	RegWrite	ImmSrc	ALUSrc	MemWrite	ResultSrc	Branch	ALUOp
3	lw							
35	sw							
51	R-type							
99	beq							



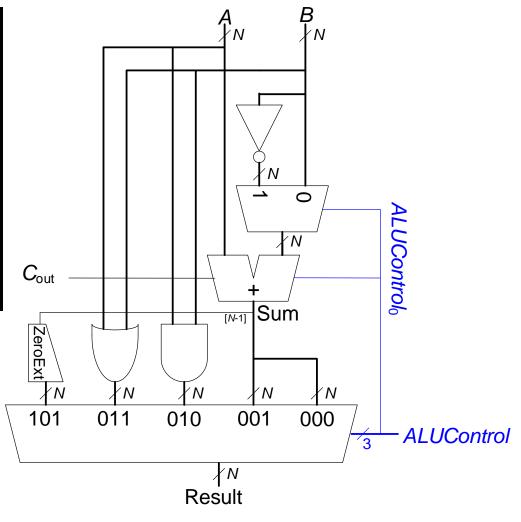
Review: ALU

ALUControl _{2:0}	Function
000	add
001	subtract
010	and
011	or
101	SLT

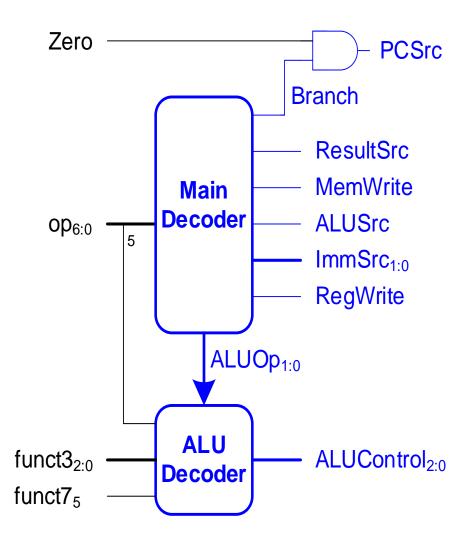


Review: ALU

ALUControl _{2:0}	Function
000	add
001	subtract
010	and
011	or
101	SLT

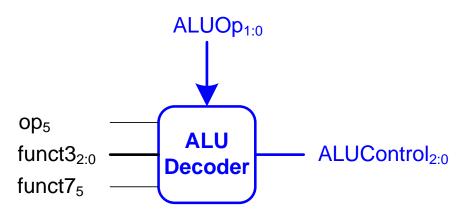


Single-Cycle Control: ALU Decoder



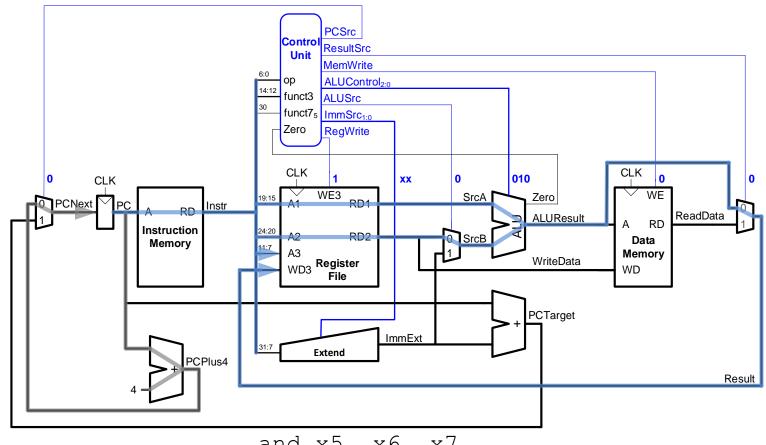
Single-Cycle Control: ALU Decoder

ALUOp	funct3	op ₅ , funct7 ₅	Instruction	ALUControl _{2:0}
00	х	х	lw, sw	000 (add)
01	х	x	beq	001 (subtract)
10	000	00, 01, 10	add	000 (add)
	000	11	sub	001 (subtract)
	010	х	slt	101 (set less than)
	110	х	or	011 (or)
	111	x	and	010 (and)



Example: and

ор	Instruct	RegWrite	ImmSrc	ALUSrc	MemWrite	ResultSrc	Branch	ALUOp
51	R-type	1	XX	0	0	0	0	10



and x5, x6, x7

Chapter 7: Microarchitecture

Extending the Single-Cycle Processor

Extended Functionality: I-Type ALU

Enhance the single-cycle processor to handle I-Type ALU instructions: addi, andi, ori, and slti

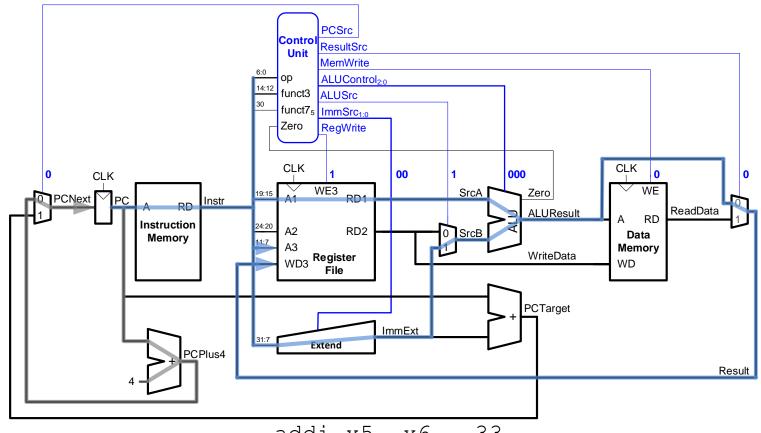
- Similar to R-type instructions
- But second source comes from immediate
- Change ALUSrc to select the immediate
- And *ImmSrc* to pick the correct immediate

Extended Functionality: I-Type ALU

ор	Instruct.	RegWrite	ImmSrc	ALUSrc	MemWrite	ResultSrc	Branch	ALUOp
3	lw	1	00	1	0	1	0	00
35	sw	0	01	1	1	Х	0	00
51	R-type	1	XX	0	0	0	0	10
99	beq	0	10	0	0	X	1	01
19	I-type	1	00	1	0	0	0	10

Extended Functionality: addi

ор	Instruct.	RegWrite	ImmSrc	ALUSrc	MemWrite	ResultSrc	Branch	ALUOp
19	I-type	1	00	1	0	0	0	10

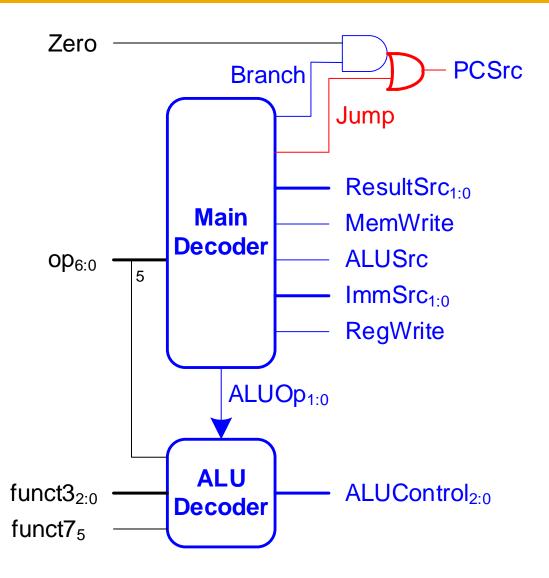


Extended Functionality: jal

Enhance the single-cycle processor to handle jal

- Similar to beq
- But jump is always taken
 - PCSrc should be 1
- Immediate format is different
 - Need a new *ImmSrc* of 11
- And jal must compute PC+4 and store in rd
 - Take PC+4 from adder through ResultMux

Extended Functionality: jal



Extended Functionality: ImmExt

ImmSrc _{1:0}	ImmExt	Instruction Type
00	{{20{instr[31]}}, instr[31:20]}	I-Type
01	{{20{instr[31]}}, instr[31:25], instr[11:7]}	S-Type
10	{{19{instr[31]}}, instr[31], instr[7], instr[30:25], instr[11:8], 1'b0}	В-Туре
11	{{12{instr[31]}}, instr[19:12], instr[20], instr[30:21], 1'b0}	J-Type

I-Type

31:20	19:15	14:12	11:7	6:0
imm _{11:0}	rs1	funct3	rd	op
12 bits	5 bits	3 bits	5 bits	7 bits

B-Type

31:25	24:20	19:15	14:12	11:7	6:0
imm _{12,10:5}	rs2	rs1	funct3	imm _{4:1,11}	op
7 bits	5 bits	5 bits	3 bits	5 bits	7 bits

S-Type

31:25	24:20	19:15	14:12	11:7	6:0
imm _{11:5}	rs2	rs1	funct3	imm _{4:0}	ор
7 bits	5 bits	5 bits	3 bits	5 bits	7 bits

J-Type

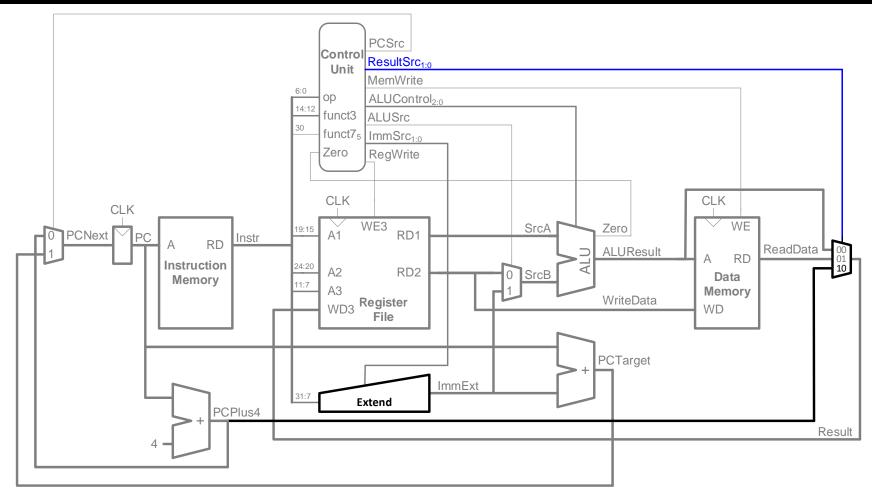
31:12	11:7	6:0	
imm _{20,10:1,11,19:12}	rd	op	
20 bits	5 bits	7 bits	

Extended Functionality: jal

ор	Instruct.	RegWrite	ImmSrc	ALUSrc	MemWrite	ResultSrc	Branch	ALUOp	Jump
3	lw	1	00	1	0	01	0	00	0
35	sw	0	01	1	1	XX	0	00	0
51	R-type	1	XX	0	0	00	0	10	0
99	beq	0	10	0	0	XX	1	01	0
19	I-type	1	00	1	0	00	0	10	0
111	jal	1	11	X	0	10	0	XX	1

Extended Functionality: jal

ор	Instruct.	RegWrite	ImmSrc	ALUSrc	MemWrite	ResultSrc	Branch	ALUOp	Jump
111	jal	1	11	X	0	10	0	XX	1



Chapter 7: Microarchitecture

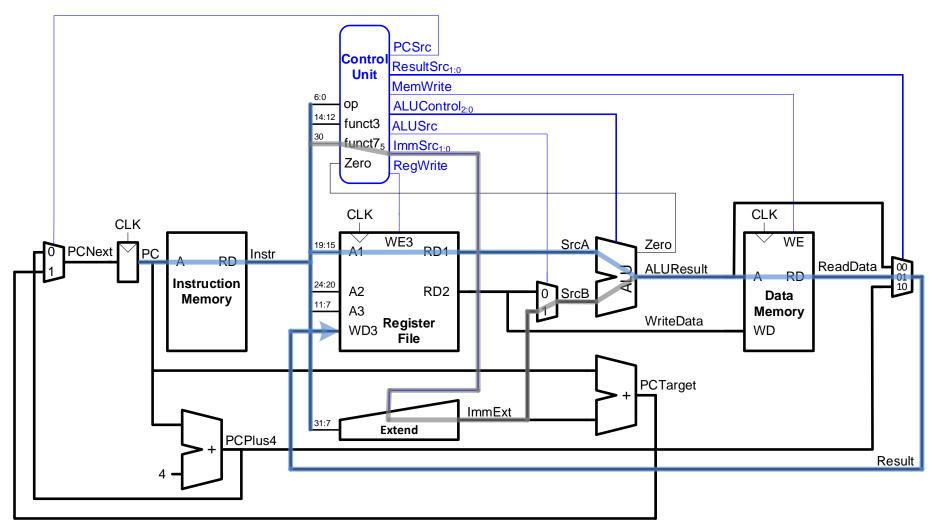
Single-Cycle Performance

Processor Performance

Program Execution Time

- = (#instructions)(cycles/instruction)(seconds/cycle)
- = # instructions x CPI x T_C

Single-Cycle Processor Performance



 T_c limited by critical path (1w)

Single-Cycle Processor Performance

Single-cycle critical path:

$$T_{c_single} = t_{pcq_PC} + t_{\text{mem}} + \max[t_{RF\text{read}}, t_{dec} + t_{ext} + t_{\text{mux}}] + t_{\text{ALU}} + t_{\text{mem}} + t_{\text{mux}} + t_{RF\text{setup}}]$$

Typically, limiting paths are:

- memory, ALU, register file

- So,
$$T_{c_single} = t_{pcq_PC} + t_{mem} + t_{RFread} + t_{ALU} + t_{mem} + t_{mux} + t_{RFsetup}$$

= $t_{pcq_PC} + 2t_{mem} + t_{RFread} + t_{ALU} + t_{mux} + t_{RFsetup}$

Single-Cycle Performance Example

Element	Parameter	Delay (ps)
Register clock-to-Q	t_{pcq_PC}	40
Register setup	$t_{ m setup}$	50
Multiplexer	$t_{ m mux}$	30
AND-OR gate	$t_{ m AND-OR}$	20
ALU	$t_{ m ALU}$	120
Decoder (Control Unit)	$t_{ m dec}$	25
Extend unit	$t_{ m ext}$	35
Memory read	$t_{ m mem}$	200
Register file read	t_{RF} read	100
Register file setup	t_{RF} setup	60

$$T_{c_single} = t_{pcq_PC} + 2t_{mem} + t_{RFread} + t_{ALU} + t_{mux} + t_{RFsetup}$$

Single-Cycle Performance Example

Program with 100 billion instructions:

Execution Time = # instructions x CPI x T_C

Chapter 7: Microarchitecture

Multicycle RISC-V Processor

Single- vs. Multicycle Processor

- Single-cycle:
 - + simple
 - cycle time limited by longest instruction (lw)
 - separate memories for instruction and data
 - 3 adders/ALUs
- Multicycle processor addresses these issues by breaking instruction into shorter steps
 - shorter instructions take fewer steps
 - o can re-use hardware
 - o cycle time is faster

Single- vs. Multicycle Processor

Single-cycle:

- + simple
- cycle time limited by longest instruction (lw)
- separate memories for instruction and data
- 3 adders/ALUs

Multicycle:

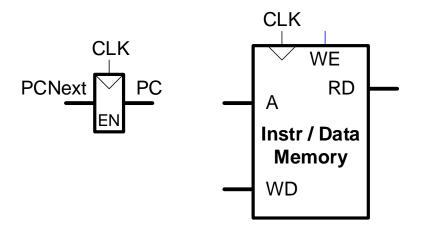
- + higher clock speed
- + simpler instructions run faster
- + reuse expensive hardware on multiple cycles
- sequencing overhead paid many times

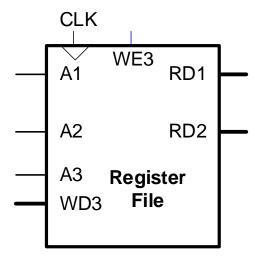
Same design steps as single-cycle:

- first datapath
- then control

Multicycle State Elements

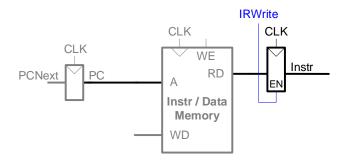
Replace separate Instruction and Data memories with a single unified memory – more realistic

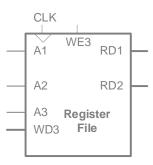




Multicycle Datapath: Instruction Fetch

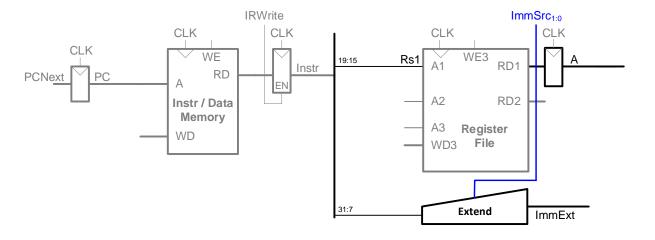
STEP 1: Fetch instruction





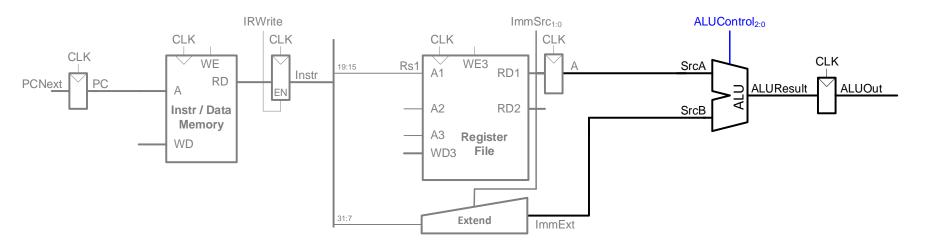
Multicycle Datapath: 1w Get Sources

STEP 2: Read source operand from RF and extend immediate



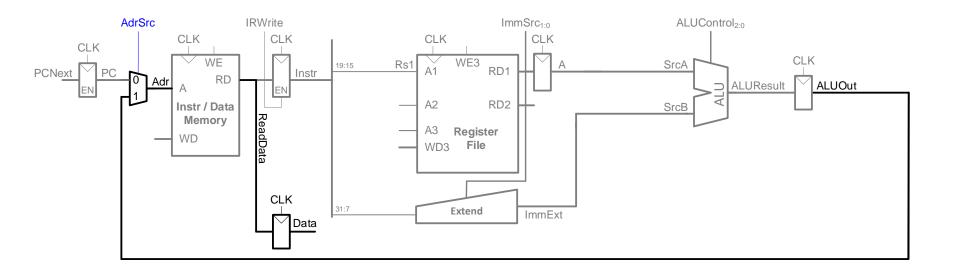
Multicycle Datapath: 1w Address

STEP 3: Compute the memory address



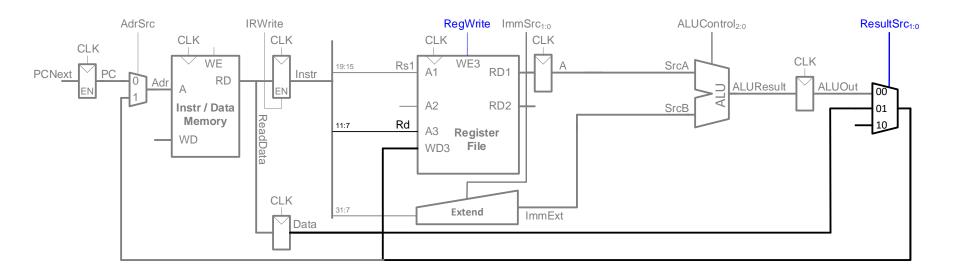
Multicycle Datapath: 1w Memory Read

STEP 4: Read data from memory



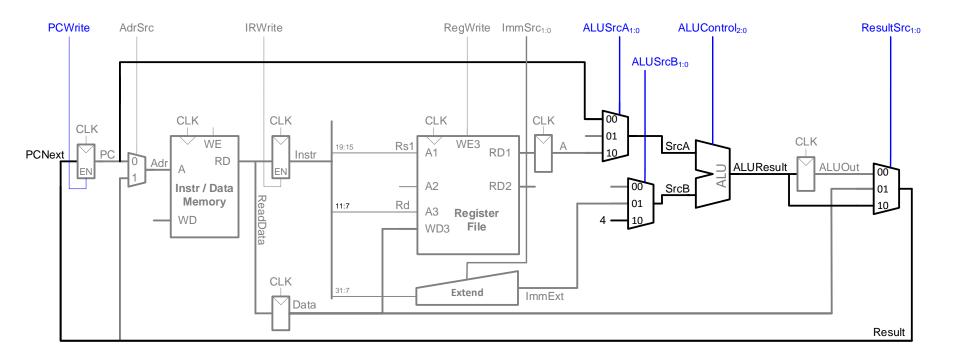
Multicycle Datapath: 1w Write Register

STEP 5: Write data back to register file



Multicycle Datapath: Increment PC

STEP 6: Increment PC: PC = PC+4

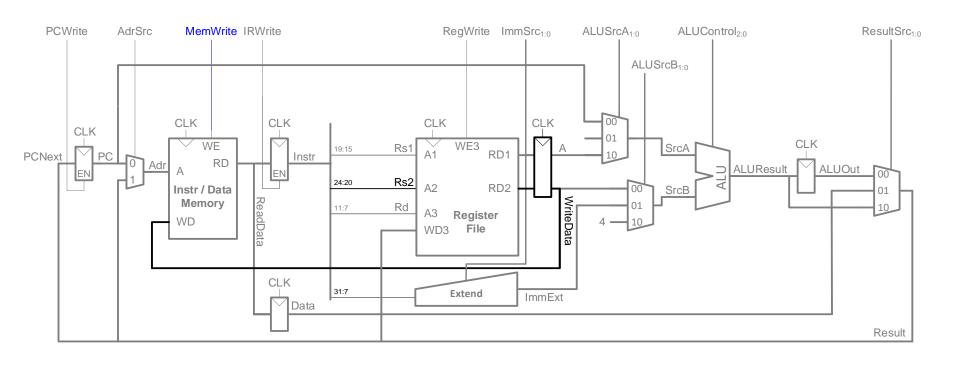


Chapter 7: Microarchitecture

Multicycle Datapath: Other Instructions

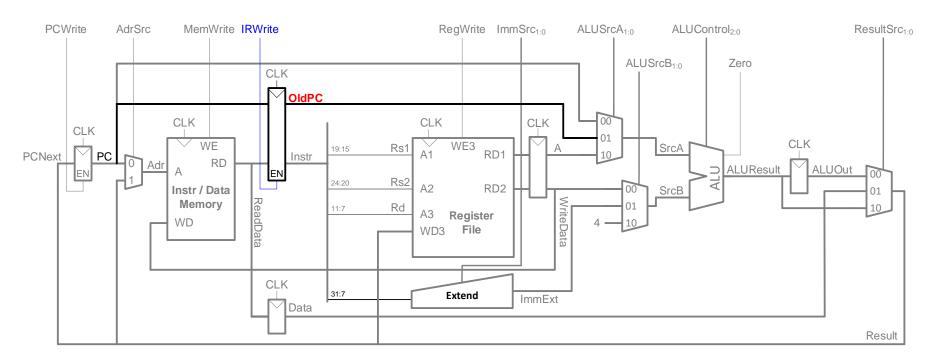
Multicycle Datapath: sw

Write data in rs2 to memory



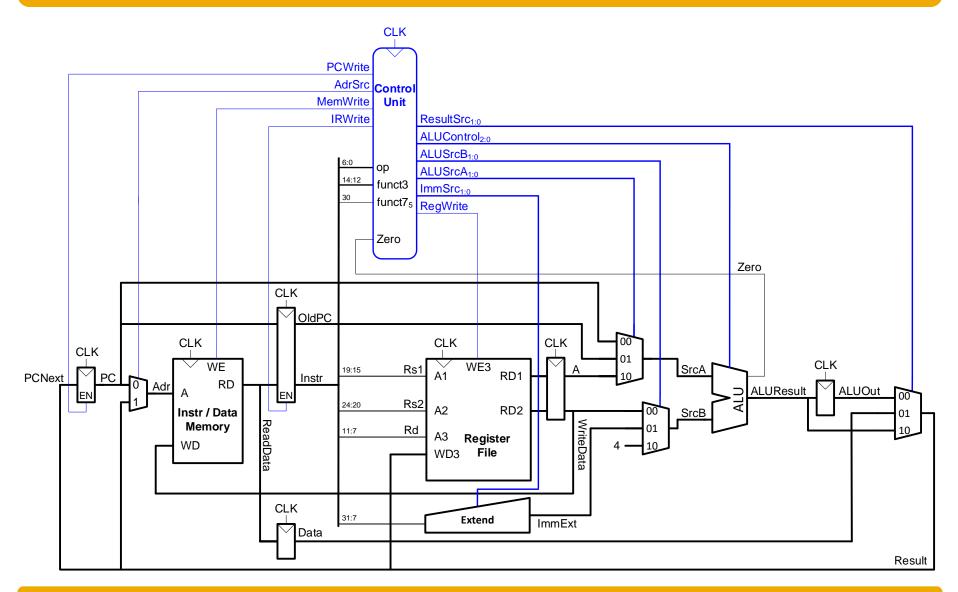
Multicycle Datapath: beq

Calculate branch target address: BTA = PC + imm



PC is updated in Fetch stage, so need to save old (current) PC

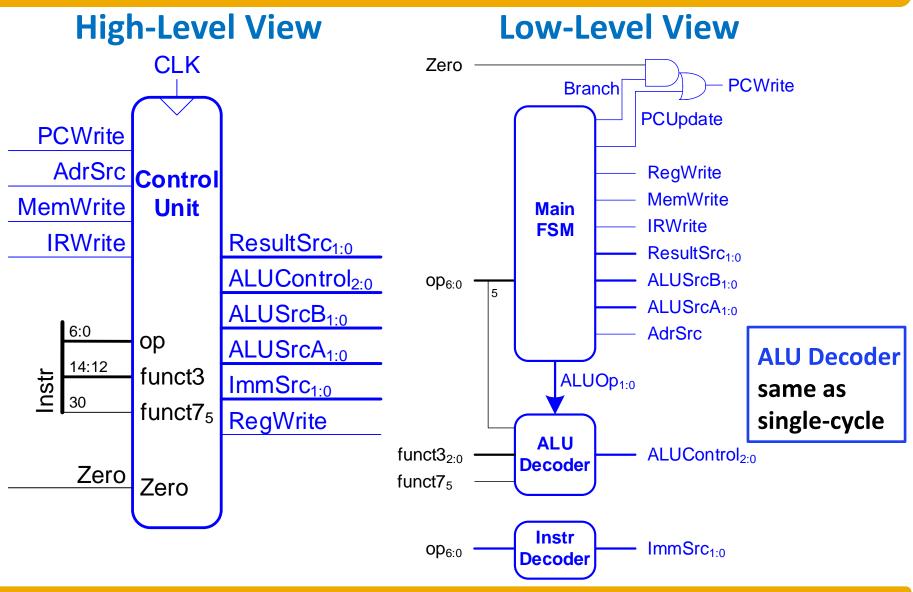
Multicycle RISC-V Processor



Chapter 7: Microarchitecture

Multicycle Control

Multicycle Control

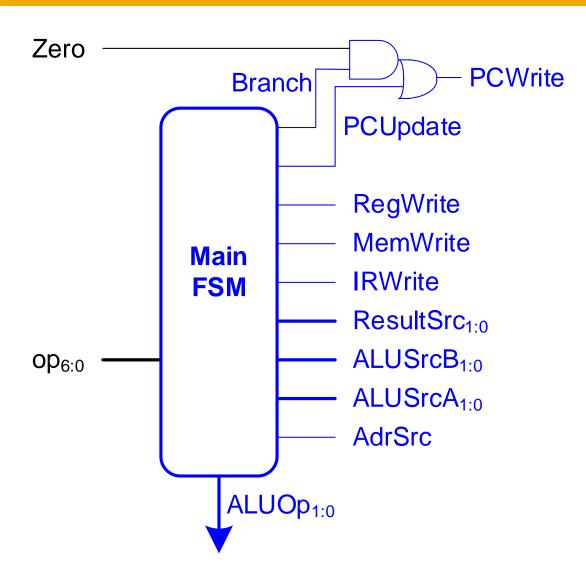


Multicycle Control: Instruction Decoder



ор	Instruction	ImmSrc
3	lw	00
35	sw	01
51	R-type	XX
99	beq	10

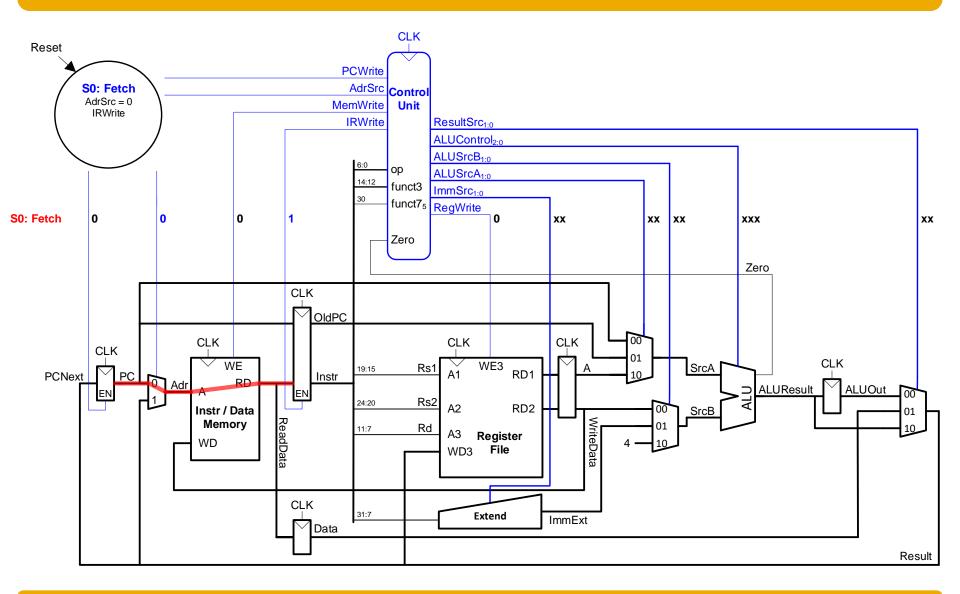
Multicycle Control: Main FSM



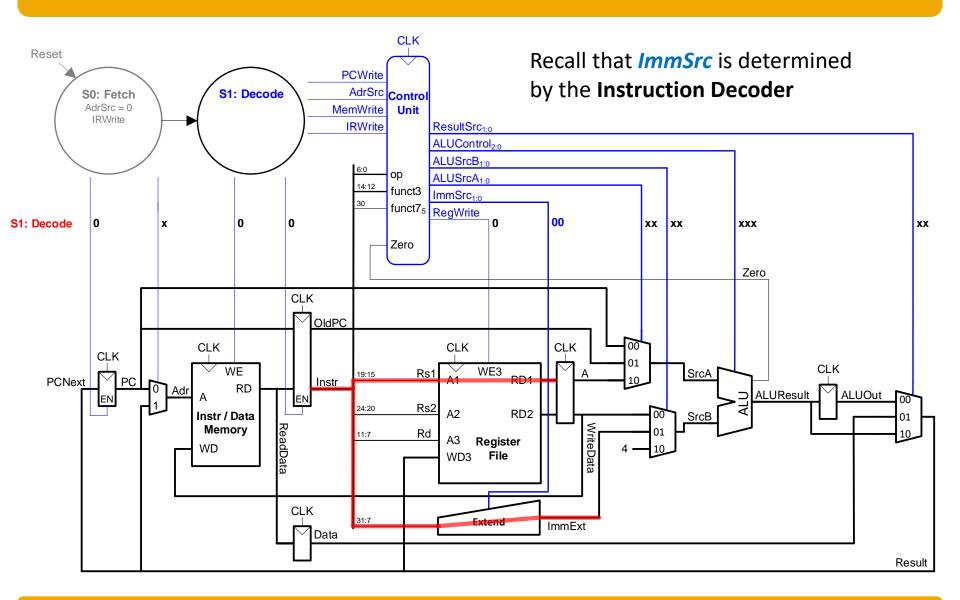
To declutter FSM:

- Write enable
 signals (RegWrite,
 MemWrite,
 IRWrite,
 PCUpdate, and
 Branch) are 0 if not
 listed in a state.
- Other signals are don't care if not listed in a state

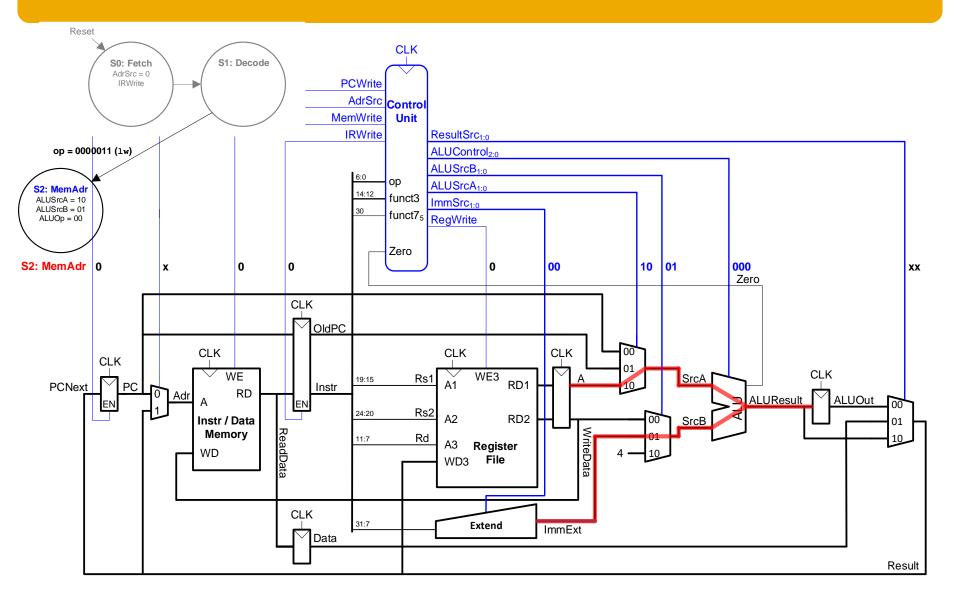
Main FSM: Fetch



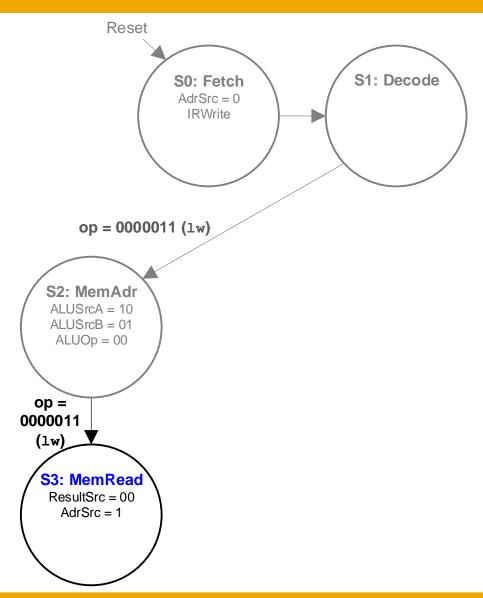
Main FSM: Decode



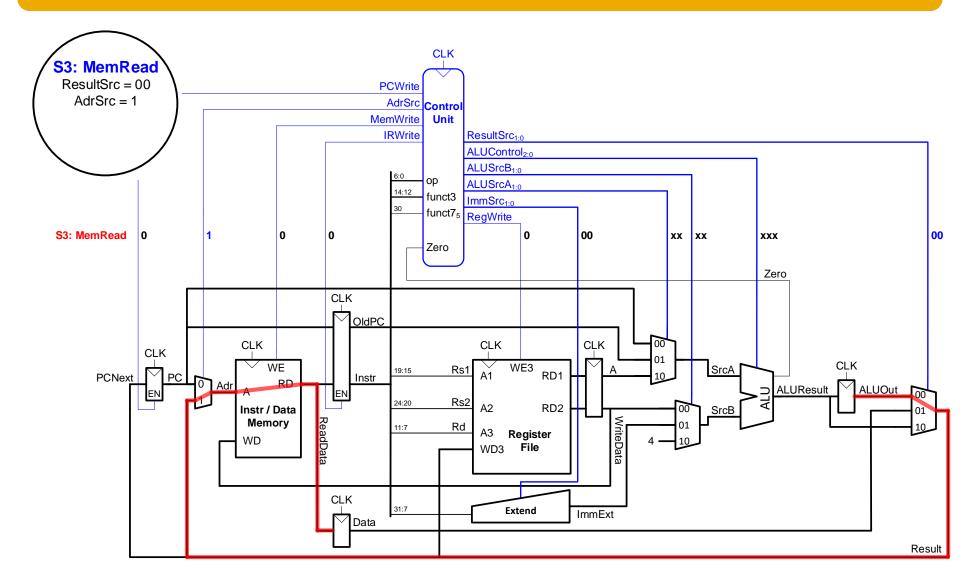
Main FSM: Address



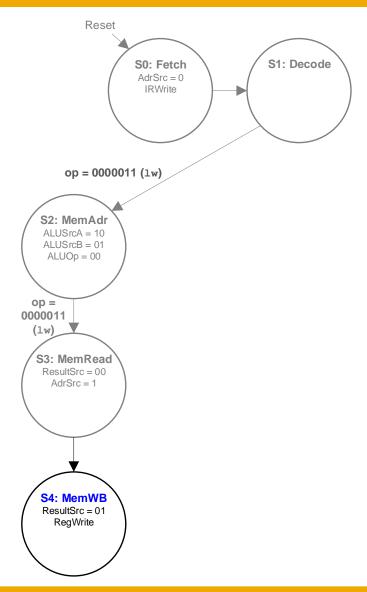
Main FSM: Read Memory



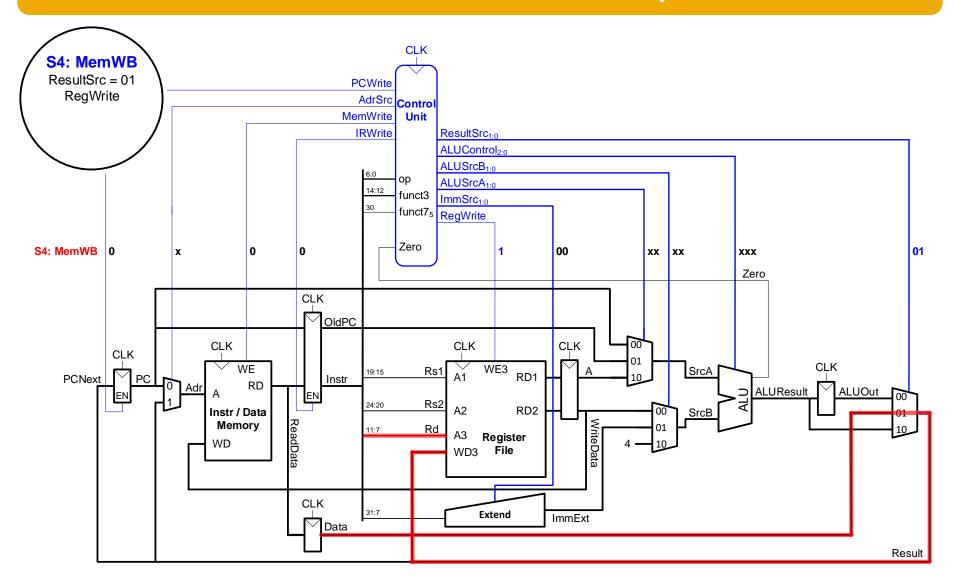
Main FSM: Read Memory Datapath



Main FSM: Write RF

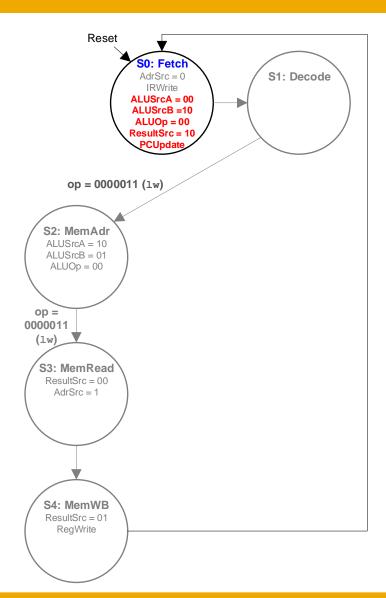


Main FSM: Write RF Datapath

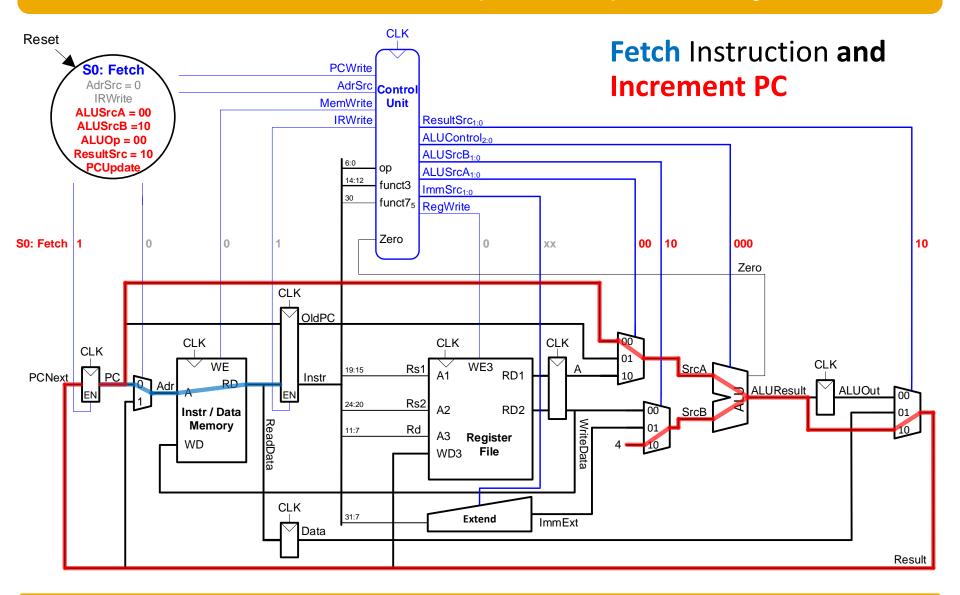


Main FSM: Fetch Revisited

Calculate PC+4
during Fetch stage
(ALU isn't being used)



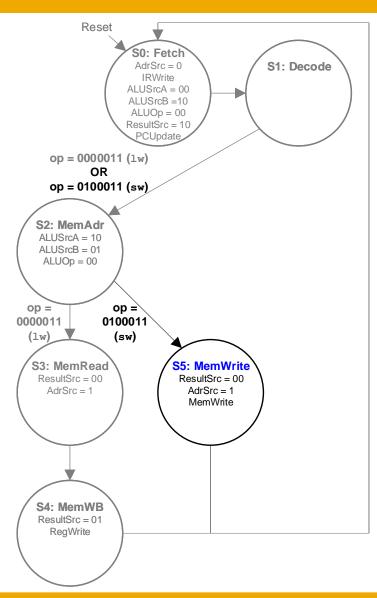
Main FSM: Fetch (PC+4) Datapath



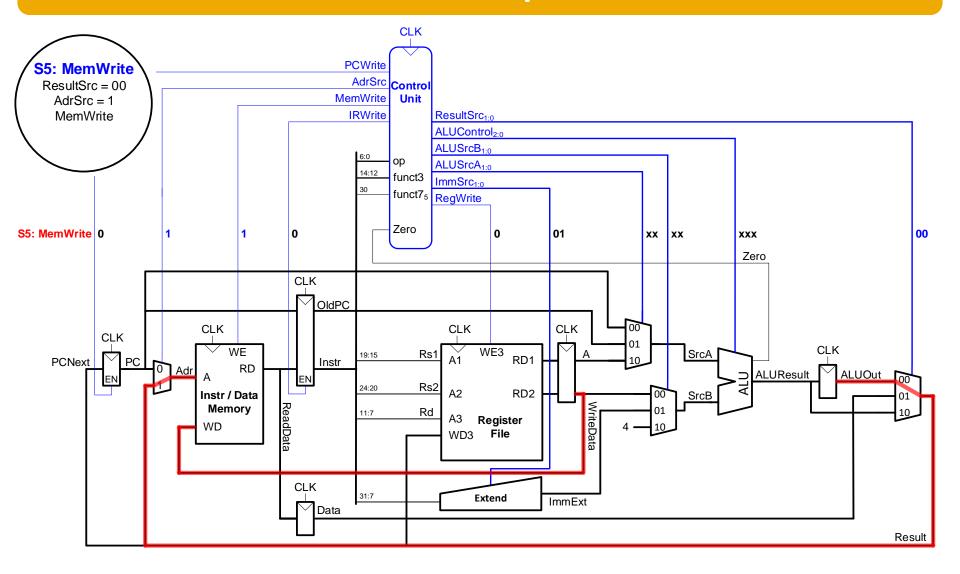
Chapter 7: Microarchitecture

Multicycle Control: Other Instructions

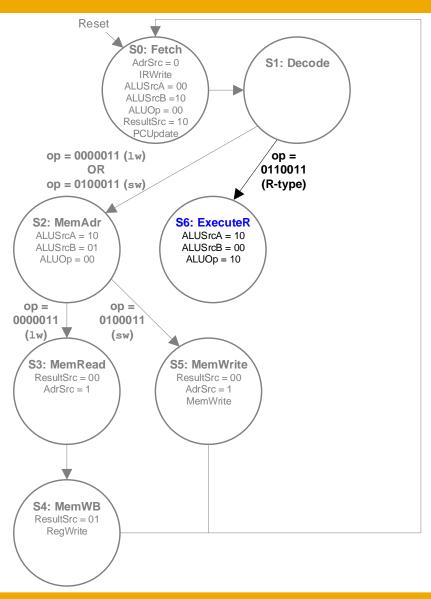
Main FSM: sw



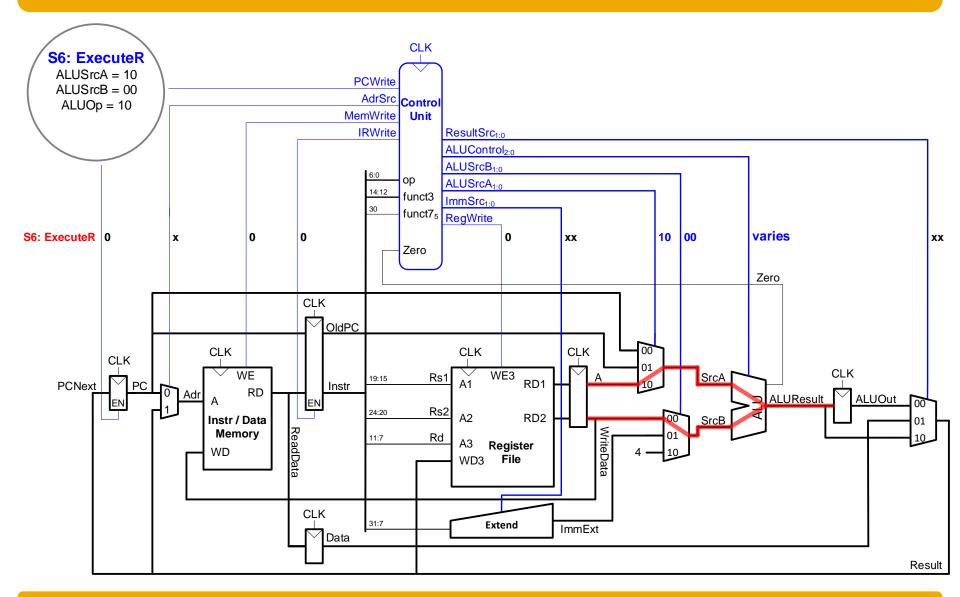
Main FSM: sw Datapath



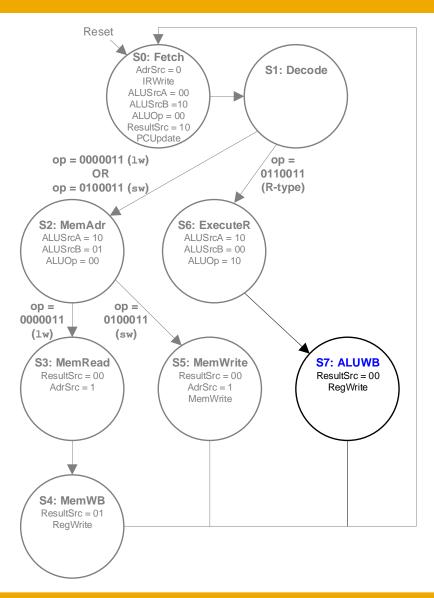
Main FSM: R-Type Execute



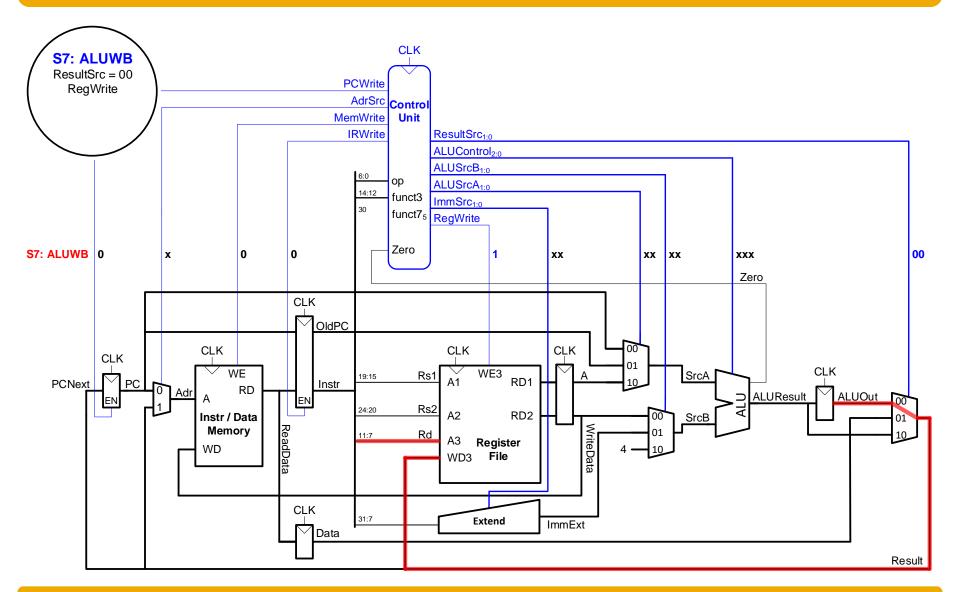
Main FSM: R-Type Execute Datapath



Main FSM: R-Type ALU Write Back



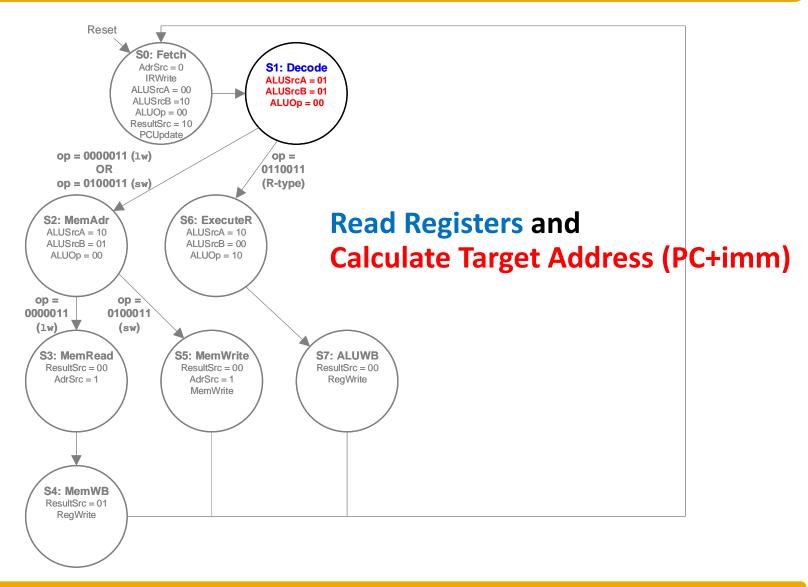
Main FSM: R-Type ALU Write Back



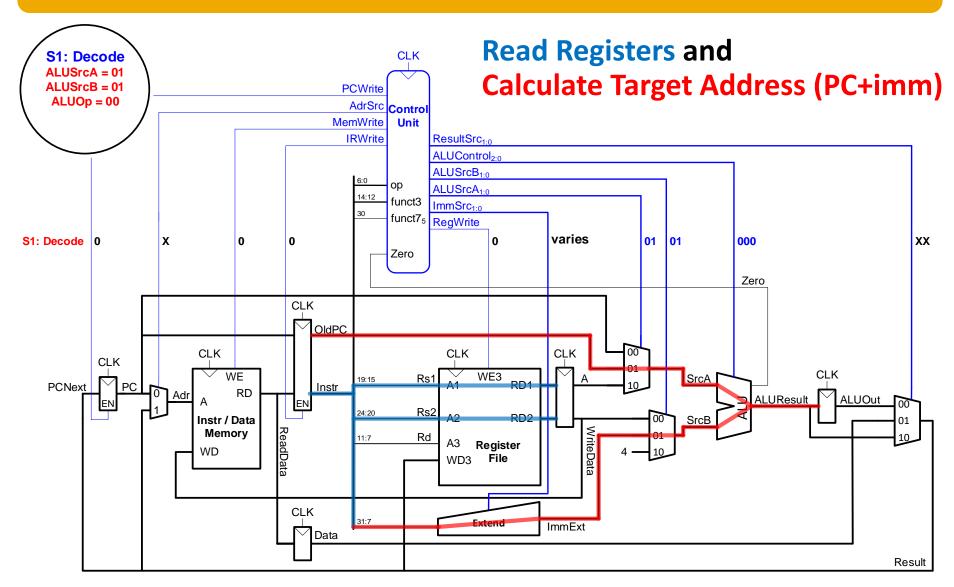
Main FSM: beq

- Need to calculate:
 - Branch Target Address
 - rs1 rs2 (to see if equal)
- ALU isn't being used in Decode stage
 - Use it to calculate Target Address (PC + imm)

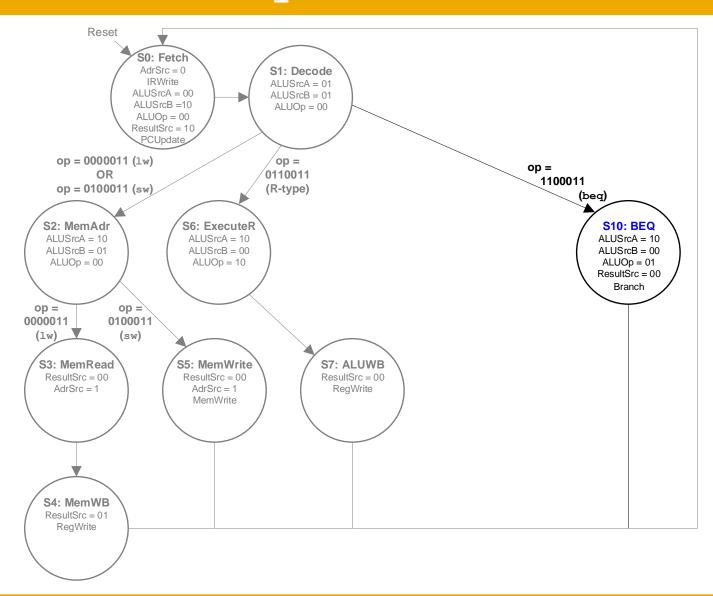
Main FSM: Decode Revisited



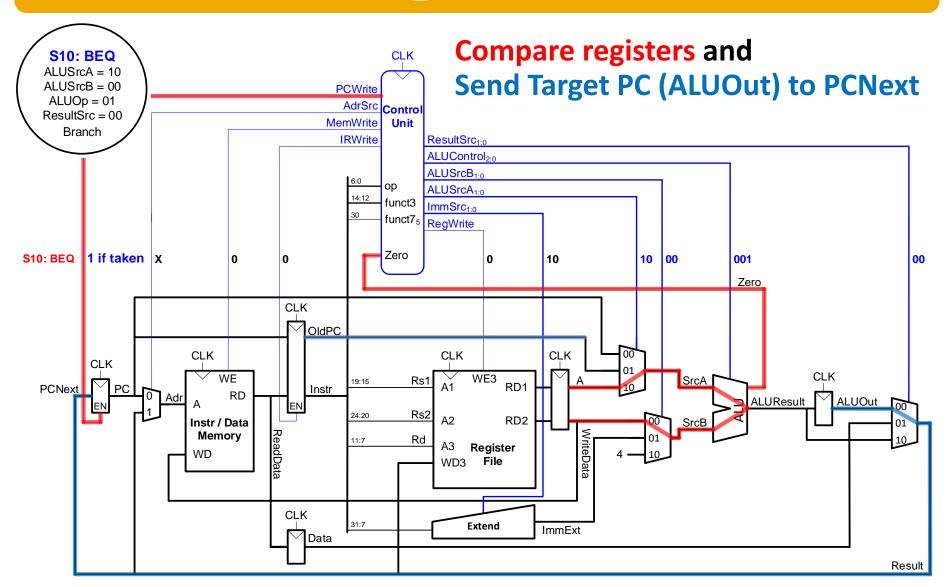
Main FSM: Decode (Target Address)



Main FSM: beq



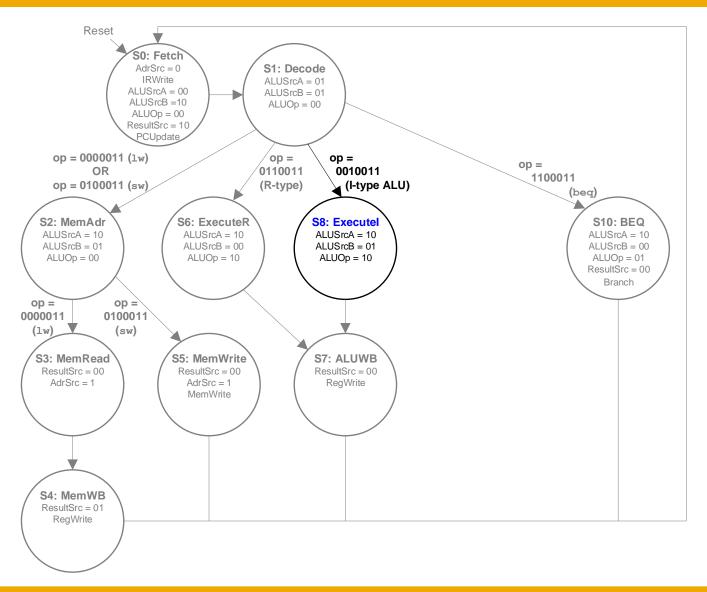
Main FSM: beq Datapath



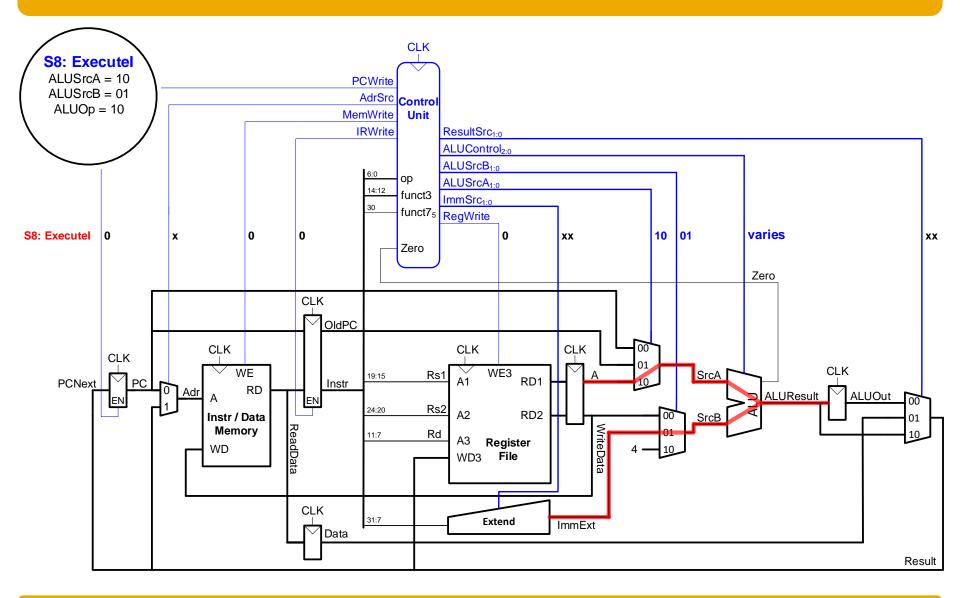
Chapter 7: Microarchitecture

Extending the RISC-V Multicycle Processor

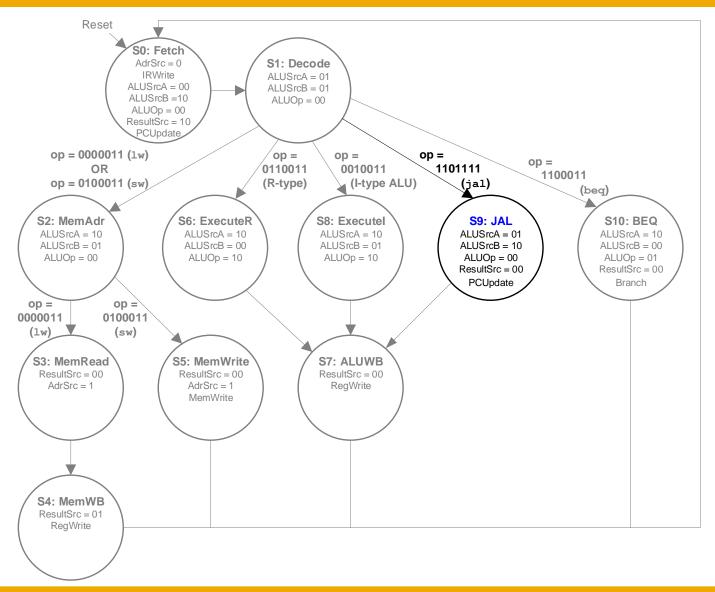
Main FSM: I-Type ALU Execute



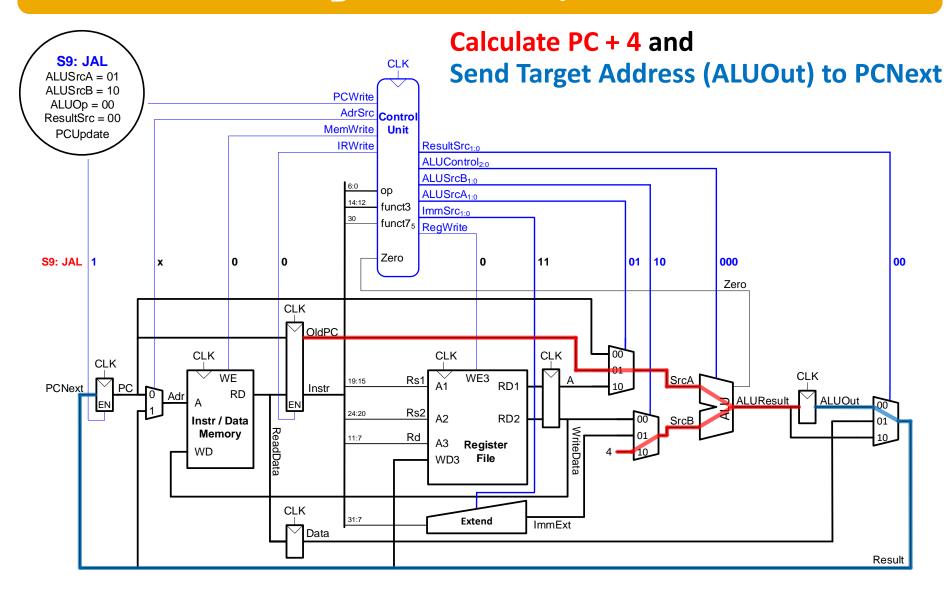
Main FSM: I-Type ALU Exec. Datapath



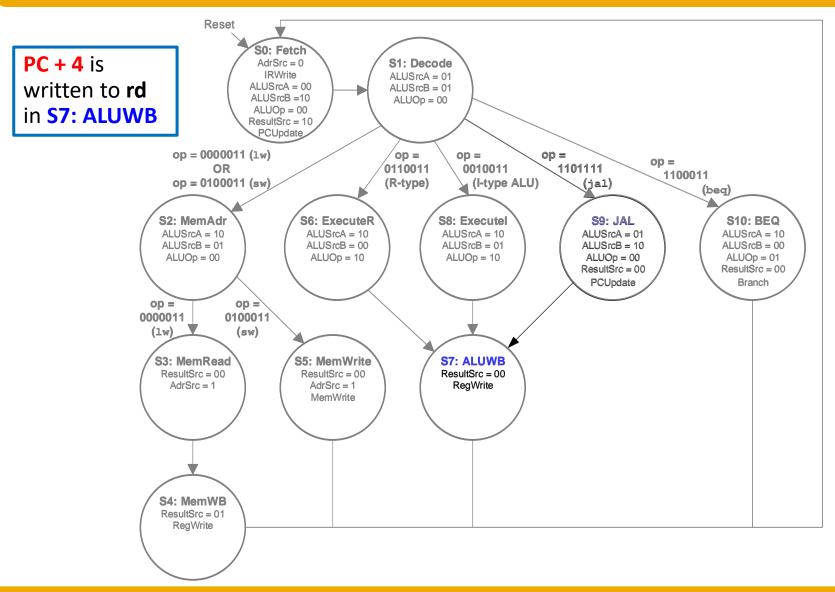
Main FSM: jal



Main FSM: jal Datapath



Main FSM: jal



Multicycle Processor Main FSM

State Datapath µOp **Fetch** Instr ←Mem[PC]: PC ← PC+4 Decode ALUOut ← PCTarget Reset MemAdr ALUOut ← rs1 + imm Data ← Mem[ALUOut] MemRead S0: Fetch AdrSrc = 0S1: Decode **MemWB** rd ← Data **IRWrite** ALUSrcA = 01 MemWrite Mem[ALUOut] ← rd ALUSrcA = 00ALUSrcB = 01 **ExecuteR** ALUOut ← rs1 op rs2 ALUSrcB =10 ALUOp = 00ALUOp = 00**Executel** ALUOut ← rs1 op imm ResultSrc = 10 **ALUWB** rd ← ALUOut PCUpdate BEQ ALUResult = rs1-rs2: if Zero. PC ← ALUOut op = 0000011 (1w)op = = qo = go JAL PC ← ALUOut: ALUOut ← PC+4 = qo0110011 0010011 1101111 1100011 (R-type) (I-type ALU) op = 0100011 (sw)(jal) (beq) S2: MemAdr S6: ExecuteR S8: Executel S9: JAL **S10: BEQ** ALUSrcA = 10 ALUSrcA = 10 ALUSrcA = 10ALUSrcA = 01 ALUSrcA = 10ALUSrcB = 01 ALUSrcB = 00ALUSrcB = 01ALUSrcB = 10 ALUSrcB = 00ALUOp = 00ALUOp = 10ALUOp = 10ALUOp = 00ALUOp = 01ResultSrc = 00 ResultSrc = 00 **PCUpdate** Branch op = op =0000011 0100011 (lw) (sw) S3: MemRead S5: MemWrite S7: ALUWB ResultSrc = 00ResultSrc = 00 ResultSrc = 00 AdrSrc = 1 AdrSrc = 1RegWrite MemWrite S4: MemWB ResultSrc = 01 RegWrite

Chapter 7: Microarchitecture

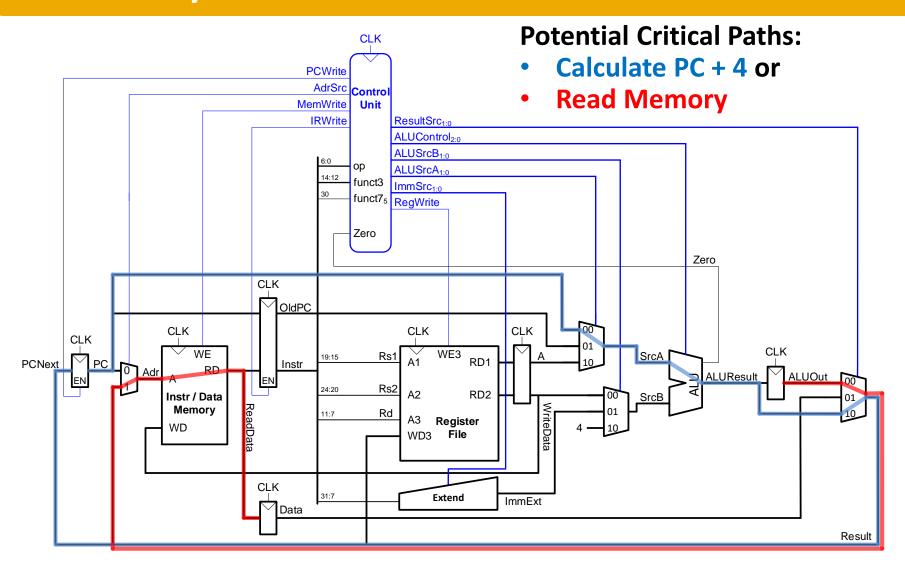
Multicycle Performance

Multicycle Processor Performance

- Instructions take different number of cycles:
 - 3 cycles: beq
 - 4 cycles: R-type, addi, sw, jal
 - − 5 cycles: lw
- CPI is weighted average
- SPECINT2000 benchmark:
 - **25**% loads
 - 10% stores
 - 13% branches
 - 52% R-type

Average CPI = (0.13)(3) + (0.52 + 0.10)(4) + (0.25)(5) = 4.12

Multicycle Critical Path



Multicycle Processor Performance

Multicycle critical path:

- Assumptions:
 - RF is faster than memory
 - Writing memory is faster than reading memory

$$T_{c_multi} = t_{pcq} + t_{dec} + 2t_{mux} + \max(t_{ALU}, t_{mem}) + t_{setup}$$

Multicycle Performance Example

Element	Parameter	Delay (ps)
Register clock-to-Q	t_{pcq_PC}	40
Register setup	$t_{ m setup}$	50
Multiplexer	$t_{ m mux}$	30
AND-OR gate	$t_{ m AND-OR}$	20
ALU	$t_{ m ALU}$	120
Decoder (Control Unit)	$t_{ m dec}$	25
Extend unit	$t_{ m dec}$	35
Memory read	$t_{ m mem}$	200
Register file read	t_{RF} read	100
Register file setup	t_{RF} setup	60

$$T_{c_multi} = t_{pcq} + t_{dec} + 2t_{mux} + \max(t_{ALU}, t_{mem}) + t_{setup}$$

Multicycle Performance Example

For a program with **100 billion** instructions executing on a **multicycle** RISC-V processor

- CPI = 4.12 cycles/instruction
- Clock cycle time: T_{c_multi} = 375 ps

Execution Time = (# instructions) \times CPI \times T_c

Chapter 7: Microarchitecture

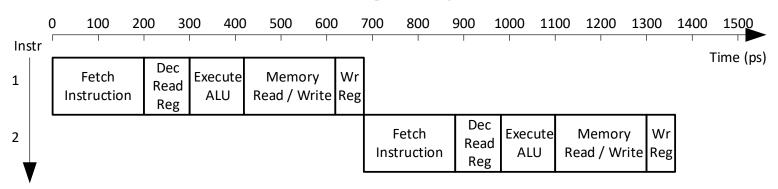
Pipelined RISC-V Processor

Pipelined RISC-V Processor

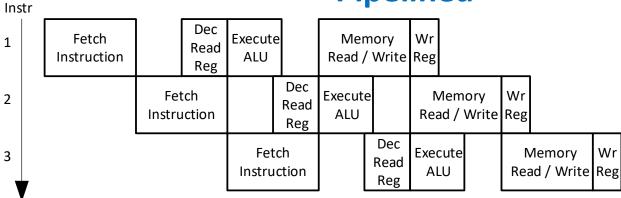
- Temporal parallelism
- Divide single-cycle processor into 5 stages:
 - Fetch
 - Decode
 - Execute
 - Memory
 - Writeback
- Add pipeline registers between stages

Single-Cycle vs. Pipelined Processor

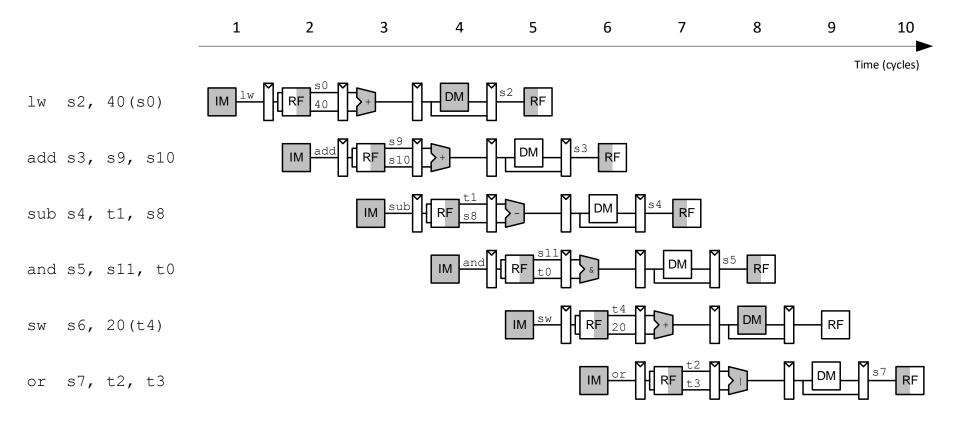
Single-Cycle



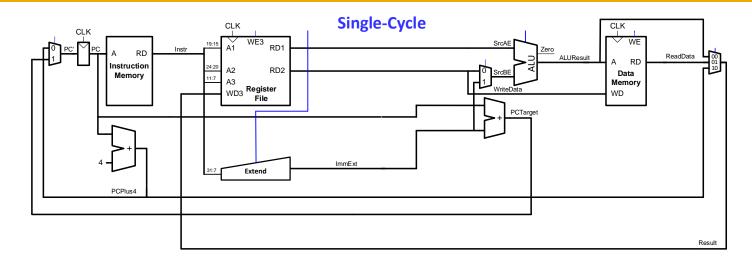
Pipelined



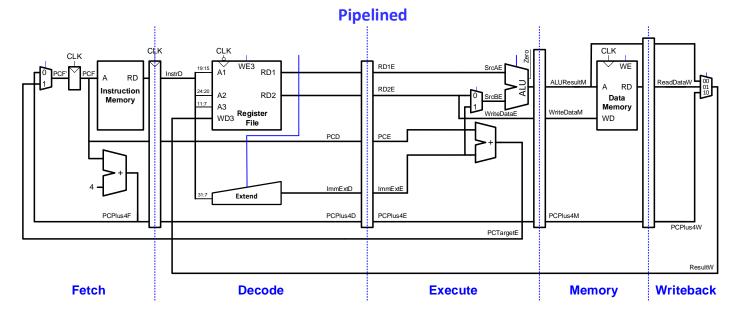
Pipelined Processor Abstraction



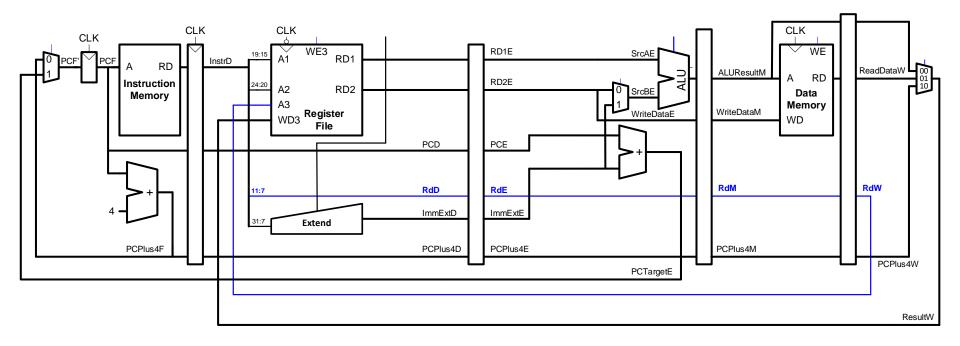
Single-Cycle & Pipelined Datapaths



Signals in Pipelined Processor are appended with first letter of stage (i.e., PCF, PCD, PCE).

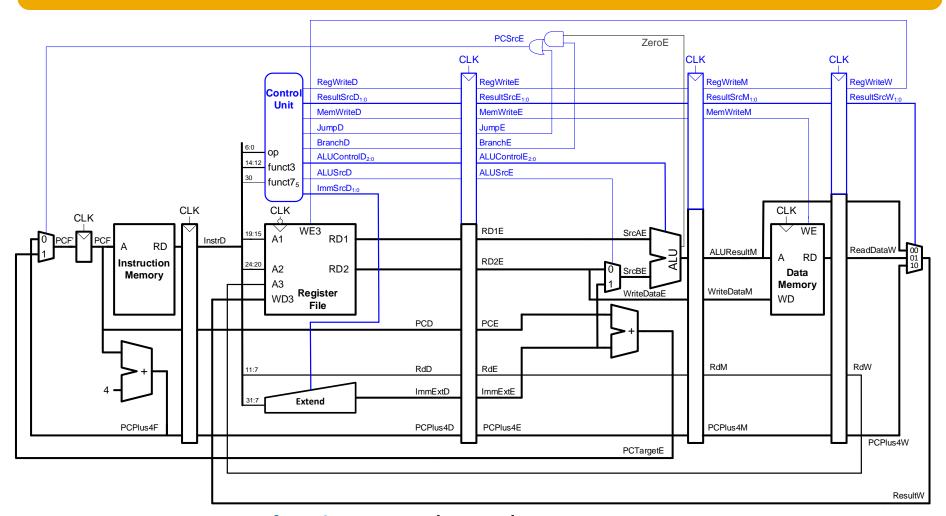


Corrected Pipelined Datapath



- Rd must arrive at same time as Result
- Register file written on falling edge of CLK

Pipelined Processor with Control



- Same control unit as single-cycle processor
- Control signals travel with the instruction (drop off when used)

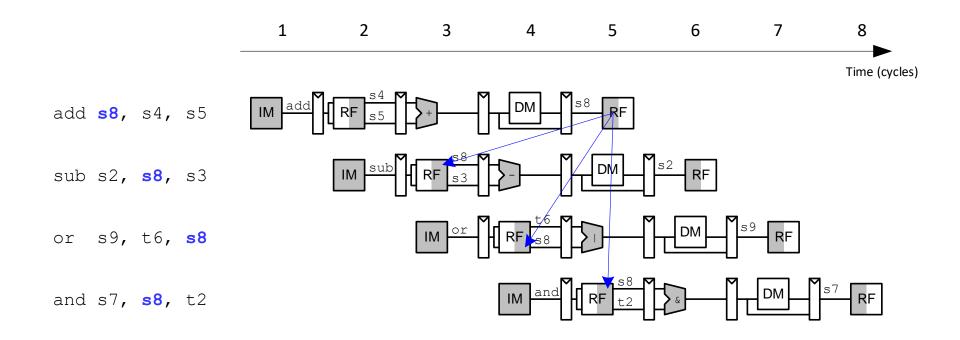
Chapter 7: Microarchitecture

Pipelined Processor Hazards

Pipelined Hazards

- When an instruction depends on result from instruction that hasn't completed
- Types:
 - Data hazard: register value not yet written back to register file
 - Control hazard: next instruction not decided yet (caused by branch)

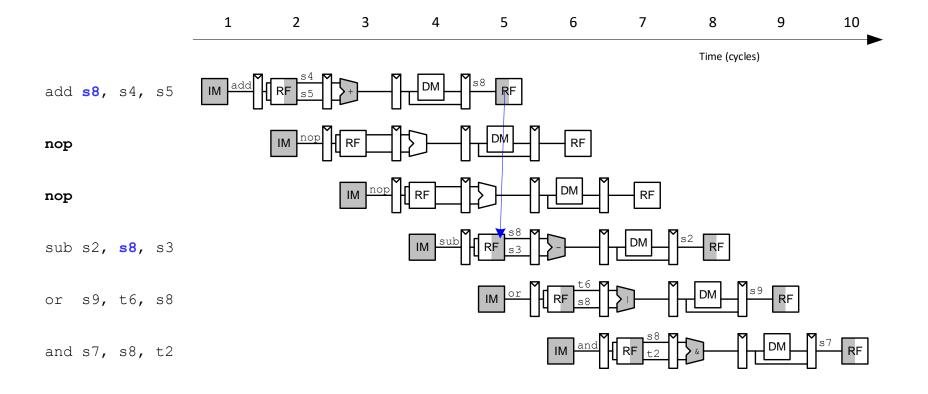
Data Hazard



Handling Data Hazards

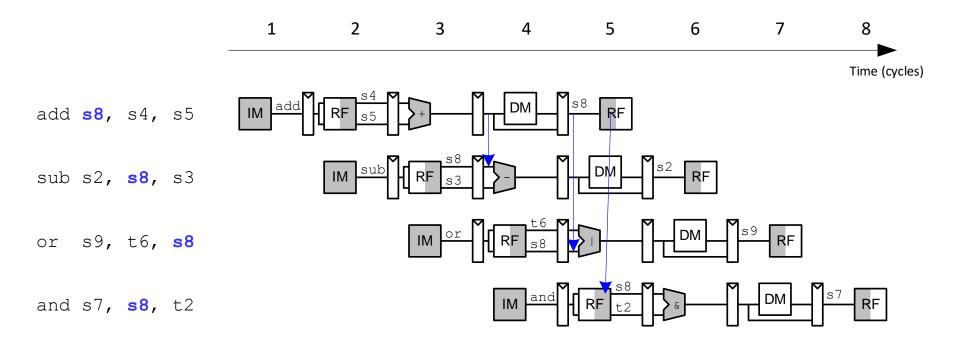
Handling Data Hazards

- Insert enough nops for result to be ready
- Or move independent useful instructions forward



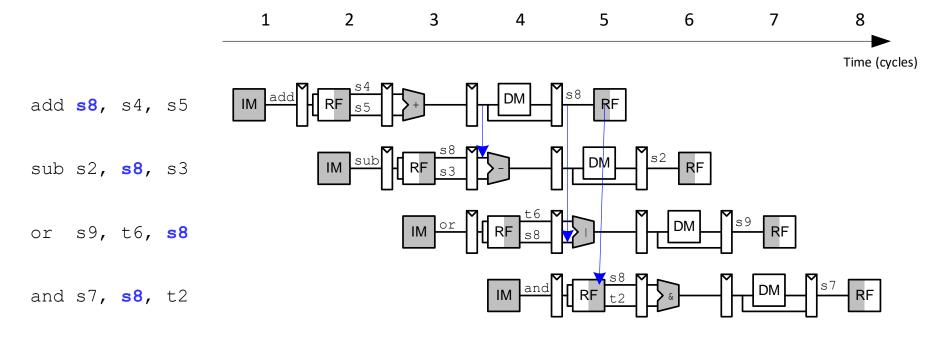
Data Forwarding

- Data is available on internal busses before it is written back to the register file (RF).
- Forward data from internal busses to Execute stage.

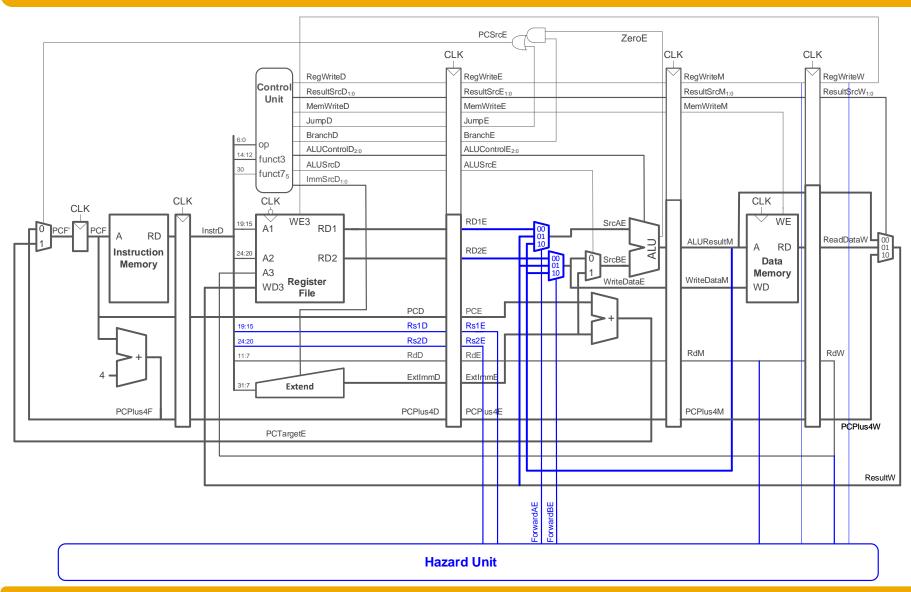


Data Forwarding

- Check if source register in Execute stage matches destination register of instruction in Memory or Writeback stage.
- If so, forward result.



Data Forwarding: Hazard Unit



Data Forwarding

- Case 1: Execute stage Rs1 or Rs2 matches Memory stage Rd?
 Forward from Memory stage
- Case 2: Execute stage Rs1 or Rs2 matches Writeback stage Rd?
 Forward from Writeback stage
- Case 3: Otherwise use value read from register file (as usual)

Equations for Rs1:

```
if ((Rs1E == RdM) \text{ AND } RegWriteM) // Case 1

ForwardAE = 10

else if ((Rs1E == RdW) \text{ AND } RegWriteW) // Case 2

ForwardAE = 01

else ForwardAE = 00 // Case 3
```

ForwardBE equations are similar (replace Rs1E with Rs2E)

Data Forwarding

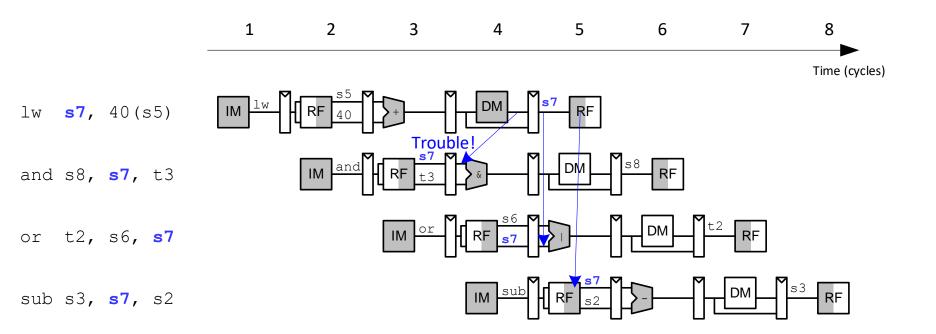
- Case 1: Execute stage Rs1 or Rs2 matches Memory stage Rd?
 Forward from Memory stage
- Case 2: Execute stage Rs1 or Rs2 matches Writeback stage Rd?
 Forward from Writeback stage
- Case 3: Otherwise use value read from register file (as usual)

Equations for Rs1:

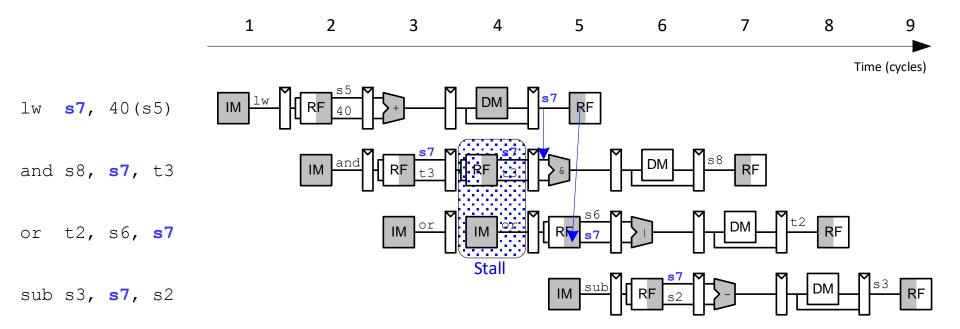
```
if ((Rs1E == RdM) \text{ AND } RegWriteM) \text{ AND } (Rs1E != 0) // \text{ Case 1}
ForwardAE = 10
else if ((Rs1E == RdW) \text{ AND } RegWriteW) \text{ AND } (Rs1E != 0) // \text{ Case 2}
ForwardAE = 01
else ForwardAE = 00 	 // \text{ Case 3}
```

ForwardBE equations are similar (replace Rs1E with Rs2E)

Data Hazard due to 1w Dependency



Stalling to solve 1w Data Dependency



Stalling Logic

 Is either source register in the Decode stage the same as the destination register in the Execute stage?

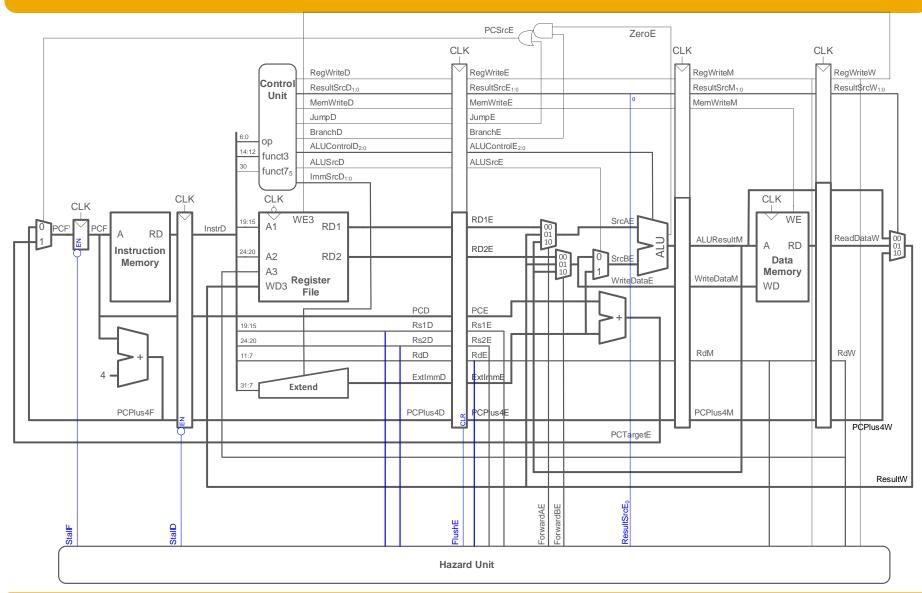
AND

Is the instruction in the Execute stage a lw?

```
IwStall = ((Rs1D == RdE) OR (Rs2D == RdE)) AND ResultSrcE<sub>0</sub>
StallF = StallD = FlushE = IwStall
```

(Stall the Fetch and Decode stages, and flush the Execute stage.)

Stalling Hardware



Chapter 7: Microarchitecture

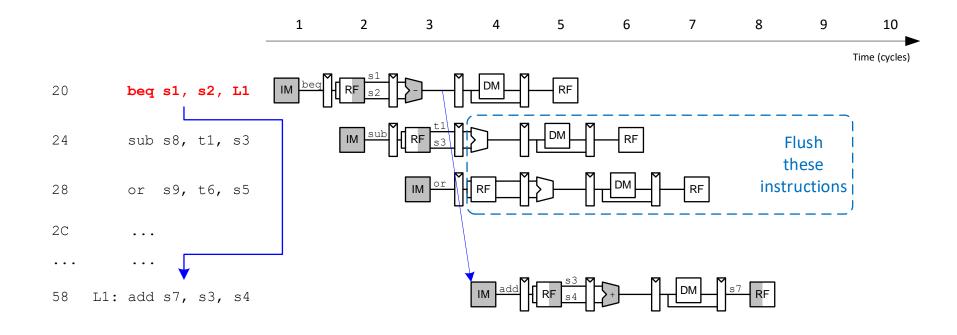
Pipelined Processor Control Hazards

Control Hazards

beq:

- Branch not determined until the Execute stage of pipeline
- Instructions after branch fetched before branch occurs
- These 2 instructions must be flushed if branch happens

Control Hazards



Branch misprediction penalty:

The number of instructions flushed when a branch is taken (in this case, 2 instructions)

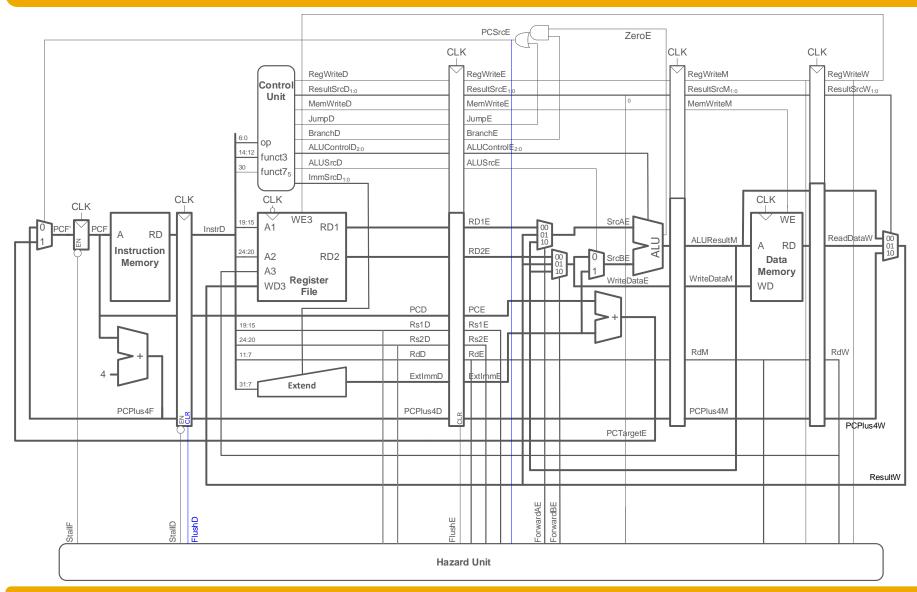
Control Hazards: Flushing Logic

- If branch is taken in execute stage, need to flush the instructions in the Fetch and Decode stages
 - Do this by clearing Decode and Execute Pipeline registers using FlushD and FlushE

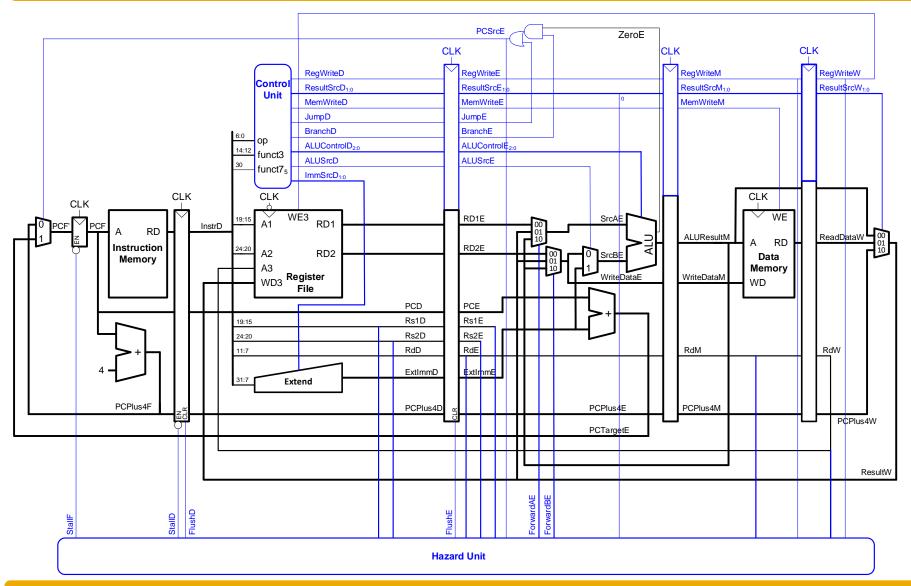
Equations:

```
FlushD = PCSrcE
FlushE = IwStall OR PCSrcE
```

Control Hazards: Flushing Hardware



RISC-V Pipelined Processor with Hazard Unit



Summary of Hazard Logic

Data hazard logic (shown for SrcA of ALU):

```
((Rs1E == RdM) AND RegWriteM) AND (Rs1E != 0) // Case 1
                ForwardAF = 10
else if ((Rs1E == RdW) \text{ AND } RegWriteW) \text{ AND } (Rs1E != 0) // Case 2
                ForwardAE = 01
else
                ForwardAE = 00
                                                            // Case 3
```

Load word stall logic:

```
IwStall = ((Rs1D == RdE)) OR (Rs2D == RdE)) AND ResultSrcE_0
StallF = StallD = lwStall
```

Control hazard flush:

```
FlushD = PCSrcE
FlushE = lwStall OR PCSrcE
```

Chapter 7: Microarchitecture

Pipelined Performance

Pipelined Processor Performance Example

SPECINT2000 benchmark:

- 25% loads
- 10% stores
- 13% branches
- 52% R-type

Suppose:

- 40% of loads used by next instruction
- 50% of branches mispredicted
- What is the average CPI? (Ideally it's 1, but...)

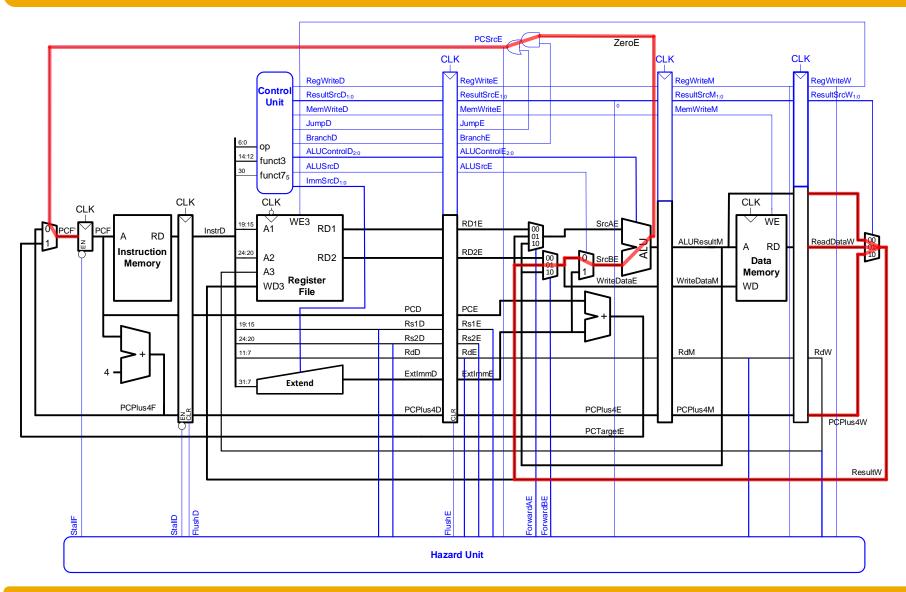
Pipelined Processor Performance Example

Pipelined processor critical path:

```
T_{c\_pipelined} = \max \text{ of}
t_{pcq} + t_{mem} + t_{setup} \qquad \qquad \text{Fetch}
2(t_{RFread} + t_{setup}) \qquad \qquad \text{Decode}
t_{pcq} + 4t_{mux} + t_{ALU} + t_{AND-OR} + t_{setup} \qquad \qquad \text{Execute}
t_{pcq} + t_{mem} + t_{setup} \qquad \qquad \text{Memory}
2(t_{pcq} + t_{mux} + t_{RFwrite}) \qquad \qquad \text{Writeback}
```

- Decode and Writeback stages both use the register file in each cycle
- So each stage gets half of the cycle time $(T_c/2)$ to do their work
- Or, stated a different way, 2x of their work must fit in a cycle (T_c)

Pipelined Critical Path: Execute Stage



Pipelined Performance Example

Element	Parameter	Delay (ps)
Register clock-to-Q	t_{pcq_PC}	40
Register setup	$t_{ m setup}$	50
Multiplexer	$t_{ m mux}$	30
AND-OR gate	$t_{ m AND-OR}$	20
ALU	$t_{ m ALU}$	120
Decoder (Control Unit)	$t_{ m dec}$	25
Extend unit	$t_{ m dec}$	35
Memory read	$t_{ m mem}$	200
Register file read	t_{RF} read	100
Register file setup	t_{RF} setup	60

$$T_{c_pipelined} = t_{pcq} + 4t_{mux} + t_{ALU} + t_{AND-OR} + t_{setup}$$

Pipelined Performance Example

Program with 100 billion instructions

```
Execution Time = (# instructions) × CPI × T_c
= (100 \times 10^9)(1.23)(350 \times 10^{-12})
= 43 seconds
```

Processor Performance Comparison

Processor	Execution Time (seconds)	Speedup (single-cycle as baseline)
Single-cycle	75	1
Multicycle	155	0.5
Pipelined	43	1.7

Chapter 7: Microarchitecture

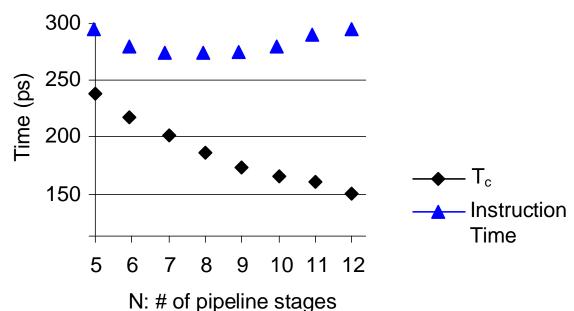
Advanced Microarchitecture

Advanced Microarchitecture

- Deep Pipelining
- Micro-operations
- Branch Prediction
- Superscalar Processors
- Out of Order Processors
- Register Renaming
- SIMD
- Multithreading
- Multiprocessors

Deep Pipelining

- 10-20 stages typical
- Number of stages limited by:
 - Pipeline hazards
 - Sequencing overhead
 - Power
 - Cost



Micro-operations

- Decompose complex instructions into series of simple instructions called *micro-operations* (*micro-ops* or μ-ops)
- At run-time, complex instructions are decoded into one or more micro-ops
- Used heavily in CISC (complex instruction set computer) architectures (e.g., x86)

Complex Op

lw s1, 0(s2), postincr 4

Micro-op Sequence

lw s1, 0(s2) addi s2, s2, 4

Without μ -ops, would need 2nd write port on the register file

Branch Prediction

- Guess whether branch will be taken
 - Backward branches are usually taken (loops)
 - Consider history to improve guess
- Good prediction reduces fraction of branches requiring a flush

Branch Prediction

- Ideal pipelined processor: CPI = 1
- Branch misprediction increases CPI
- Static branch prediction:
 - Check direction of branch (forward or backward)
 - If backward, predict taken
 - Else, predict not taken
- Dynamic branch prediction:
 - Keep history of last several hundred (or thousand)
 branches in branch target buffer, record:
 - Branch destination
 - Whether branch was taken

Dynamic Branch Prediction

- 1-bit branch predictor
- 2-bit branch predictor

Branch Prediction Example

```
addi s1, zero, 0 # s1 = sum
 addi s0, zero, 0 \# s0 = i
 addi t0, zero, 10 \# t0 = 10
For:
                     # for (i=0; i<10; i=i+1)
 bge s0, t0, Done
 add s1, s1, s0 # sum = sum + i
 addi s0, s0, 1 # i = i + 1
 j For
```

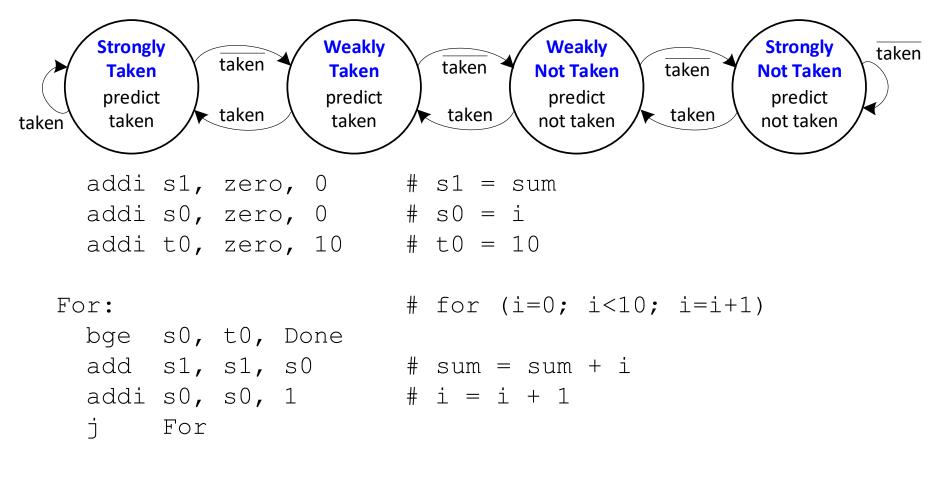
Done:

1-Bit Branch Predictor

- Remembers whether branch was taken the last time and does the same thing
- Mispredicts first and last branch of loop

Done:

2-Bit Branch Predictor



Done:

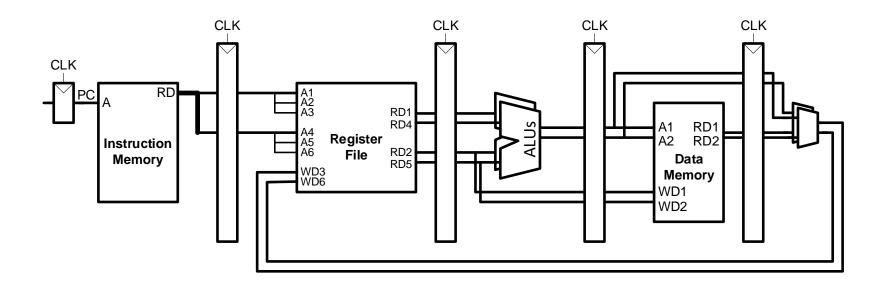
Only mispredicts last branch of loop

Chapter 7: Microarchitecture

Superscalar & Out of Order Processors

Superscalar Processors

- Multiple copies of datapath execute multiple instructions at once
- Dependencies make it tricky to issue multiple instructions at once



Superscalar Example

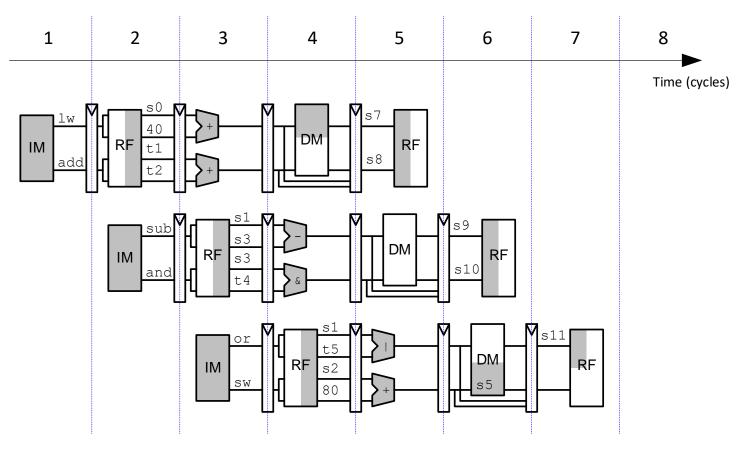
Ideal IPC: 2

Actual IPC: 2

lw s7, 40(s0)
add s8, t1, t2

sub s9, s1, s3
and s10, s3, t4

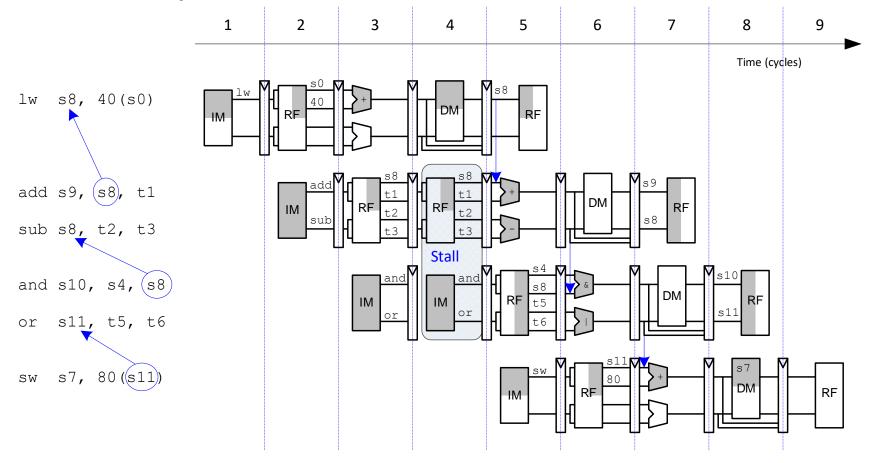
or s11, s1, t5
sw s5, 80(s2)



Superscalar with Dependencies

Ideal IPC: 2

Actual IPC: 6/5 = 1.2



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Out of Order (OOO) Processor

- Looks ahead across multiple instructions
- Issues as many instructions as possible at once
- Issues instructions out of order (as long as no dependencies)

Dependencies:

- RAW (read after write): one instruction writes, later instruction reads a register
- WAR (write after read): one instruction reads, later instruction writes a register
- WAW (write after write): one instruction writes, later instruction writes a register

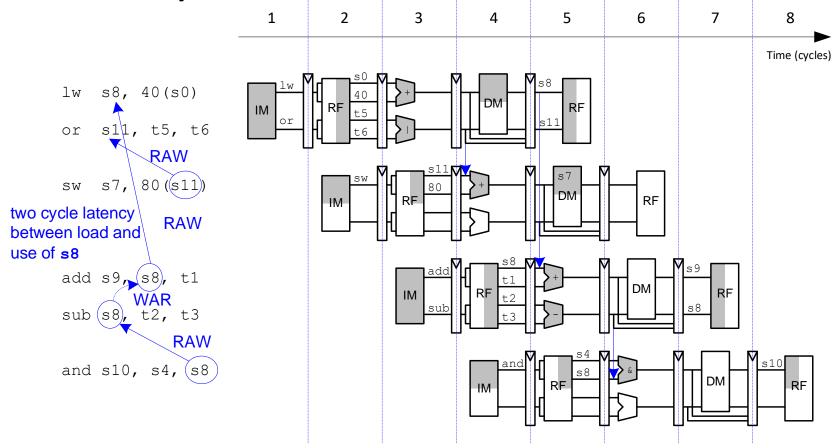
Out of Order (OOO) Processor

- Instruction level parallelism (ILP): number of instruction that can be issued simultaneously (average < 3)
- Scoreboard: table that keeps track of:
 - Instructions waiting to issue
 - Available functional units
 - Dependencies

Out of Order Processor Example

Ideal IPC: 2

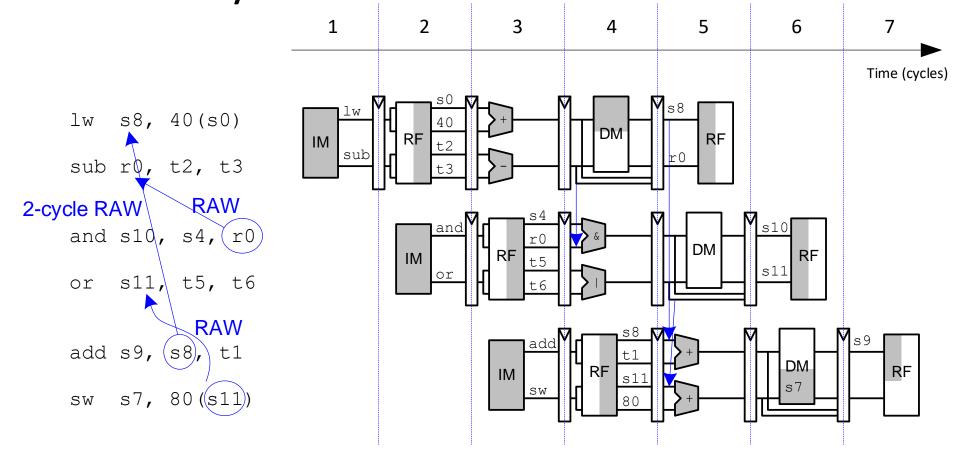
Actual IPC: 6/4 = 1.5



Register Renaming

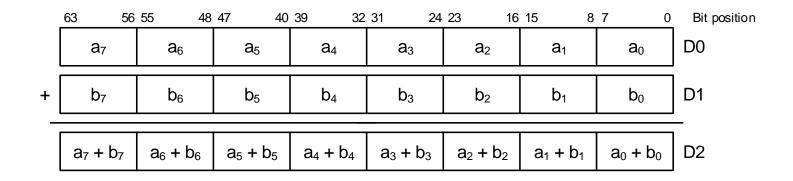
Ideal IPC: 2

Actual IPC: 6/3 = 2



SIMD

- Single Instruction Multiple Data (SIMD)
 - Single instruction acts on multiple pieces of data at once
 - Common application: graphics
 - Can apply to short arithmetic operations (also called packed arithmetic)
- For example, add eight 8-bit elements



Chapter 7: Microarchitecture

Multithreading & Multiprocessors

Advanced Architecture Techniques

Multithreading

Wordprocessor: thread for typing, spell checking, printing

Multiprocessors

Multiple processors (cores) on a single chip

Threading: Definitions

- Process: program running on a computer
 - Multiple processes can run at once: e.g., surfing
 Web, playing music, writing a paper
- Thread: part of a program
 - Each process has multiple threads: e.g., a word processor may have threads for typing, spell checking, printing

Threads in a Conventional Processor

Single-core system:

- One thread runs at once
- When one thread stalls (for example, waiting for memory):
 - Architectural state of that thread stored
 - Architectural state of waiting thread loaded into processor and it runs
 - Called context switching
- Appears to user like all threads running simultaneously

Multithreading

- Multiple copies of architectural state
- Multiple threads active at once:
 - When one thread stalls, another runs immediately
 - If one thread can't keep all execution units busy, another thread can use them
- Does not increase instruction-level parallelism (ILP) of single thread, but increases throughput

Intel calls this "hyperthreading"

Multiprocessors

- Multiple processors (cores) with a method of communication between them
- Types:
 - Homogeneous: multiple cores with shared main memory
 - Heterogeneous: separate cores for different tasks (for example, DSP and CPU in cell phone)
 - Clusters: each core has own memory system

About these Notes

Digital Design and Computer Architecture Lecture Notes

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