

DSP First, 2/e



Lecture 23

Frequency Response, $H(z)$, Poles and Zeros for IIR and FIR Systems

READING ASSIGNMENTS



- This Lecture:
 - Chapter 9, Sects. 9-5 and 9-6
 - Chapter 10, Sects. 10-5 and 10-7

LECTURE OBJECTIVES

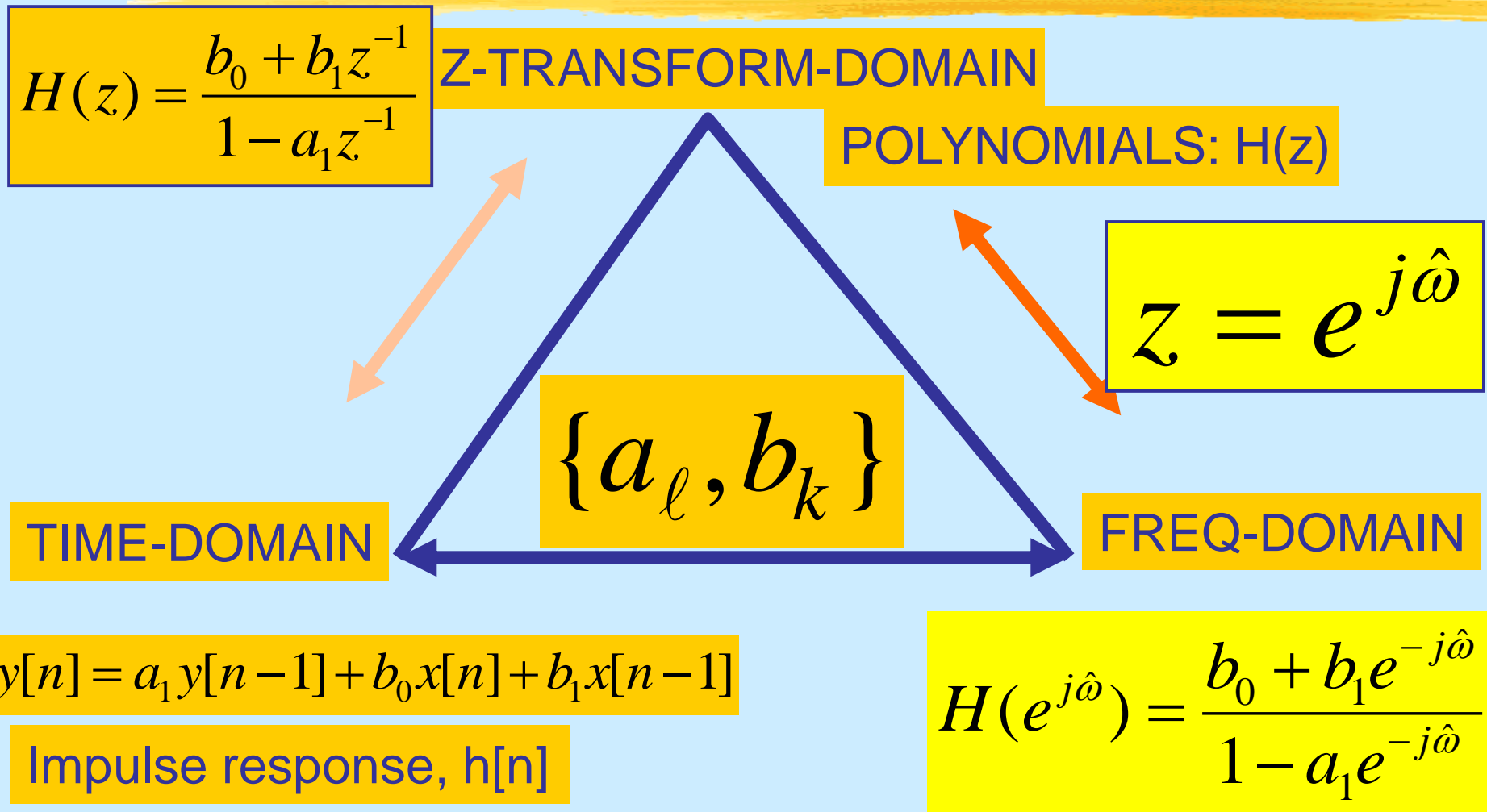


- ZEROS and POLES
- Relate $H(z)$ to FREQUENCY RESPONSE

$$H(e^{j\hat{\omega}}) = H(z) \Big|_{z=e^{j\hat{\omega}}}$$

- Four demos: PeZ, 3-Domain movies
 - Placing Poles and Zeros
- Bandpass Filters: IIR
- Nulling Filters: FIR Notch Filters: IIR

THREE DOMAINS: $H(e^{j\hat{\omega}})$



Motivation: Filter Design

- Some tasks/analysis easier in one domain
 - Freq domain: system response to sinusoids
 - Time domain: calculate output to any signal
 - Z-domain: given specs, build a filter
- Can we design a filter that removes DC and sinusoids at frequency $\hat{\omega} = \pi / 3$?
- Z-domain reduces this to polynomial roots

H(z) = Rational Function

- First Order:

$$H(z) = \frac{b_0 + b_1 z^{-1}}{1 - a_1 z^{-1}}$$

- We can also study Second-Order Systems:

$$H(z) = \frac{b_0 + b_1 z^{-1} + b_2 z^{-2}}{1 - a_1 z^{-1} - a_2 z^{-2}} = \frac{B(z)}{A(z)}$$

- Numerator & Denominator Polynomials

POLES & ZEROS of $H(z)$

- Zeros of $H(z)$, i.e., where is $H(z)=0$?

- Look for Roots of Numerator Polynomial

$$H(z) = \frac{B(z)}{A(z)}, \text{ so } B(z_0) = 0 \Rightarrow H(z_0) = 0$$

if $A(z_0) \neq 0$

- Poles of $H(z)$, i.e., where is $H(z)=\text{infinity}$?

- Look for Roots of Denominator Polynomial

$$H(z) = \frac{B(z)}{A(z)}, \text{ so } A(z_0) = 0 \Rightarrow H(z_0) \rightarrow \infty$$

if $B(z_0) \neq 0$

Poles/Zeros of 1st-order $H(z)$

- Roots of Numerator & Denominator Polys:

$$H(z) = \frac{1 + b_1 z^{-1}}{1 - 0.8 z^{-1}}$$

$$H(z) = \frac{z(1 + b_1 z^{-1})}{z(1 - 0.8 z^{-1})} = \frac{z + b_1}{z - 0.8}$$

Pole at : $z = 0.8$

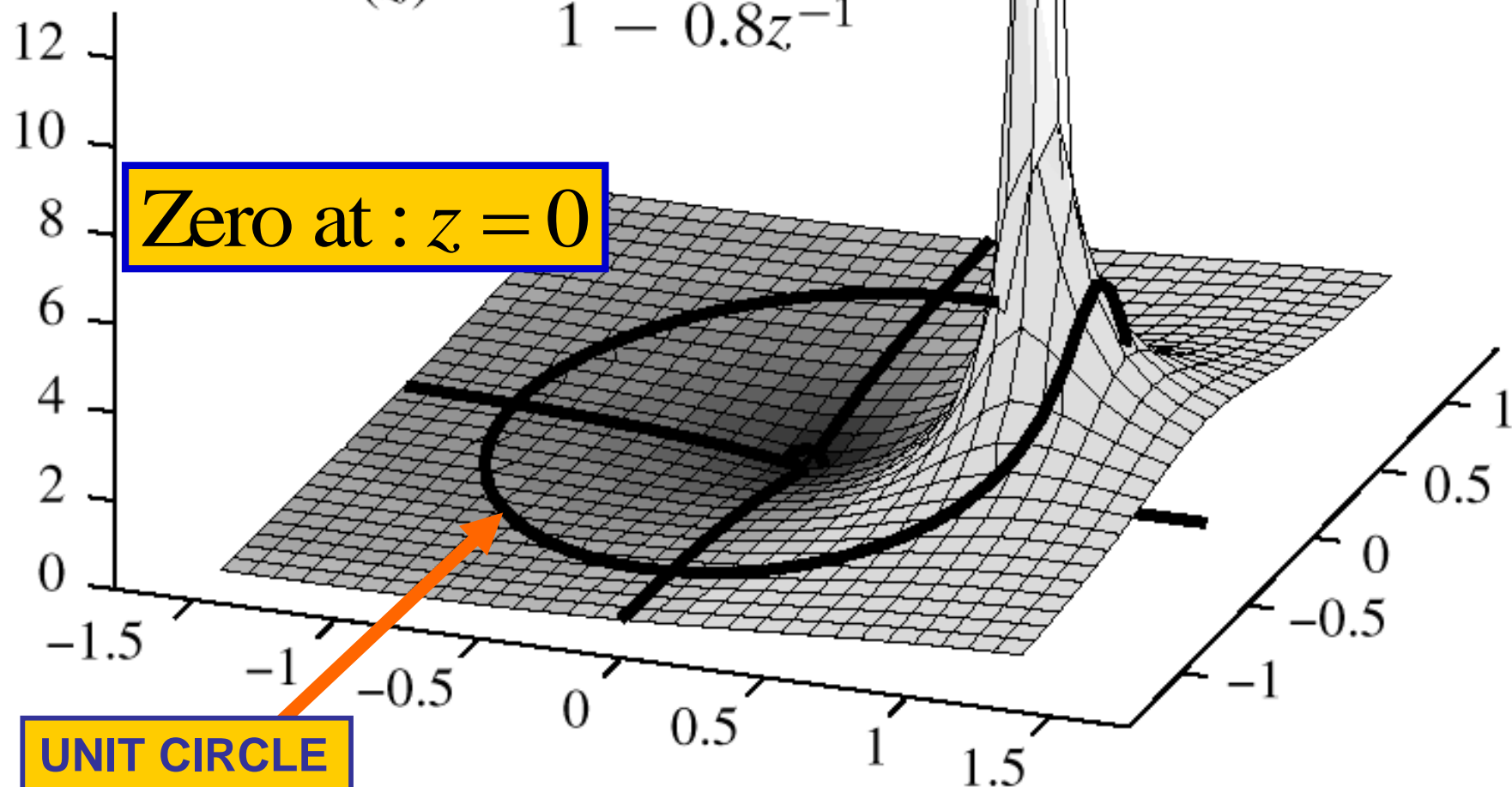
Zero at : $z = -b_1$

3-D VIEWPOINT: EVALUATE $H(z)$ EVERYWHERE

Pole at : $z = 0.8$

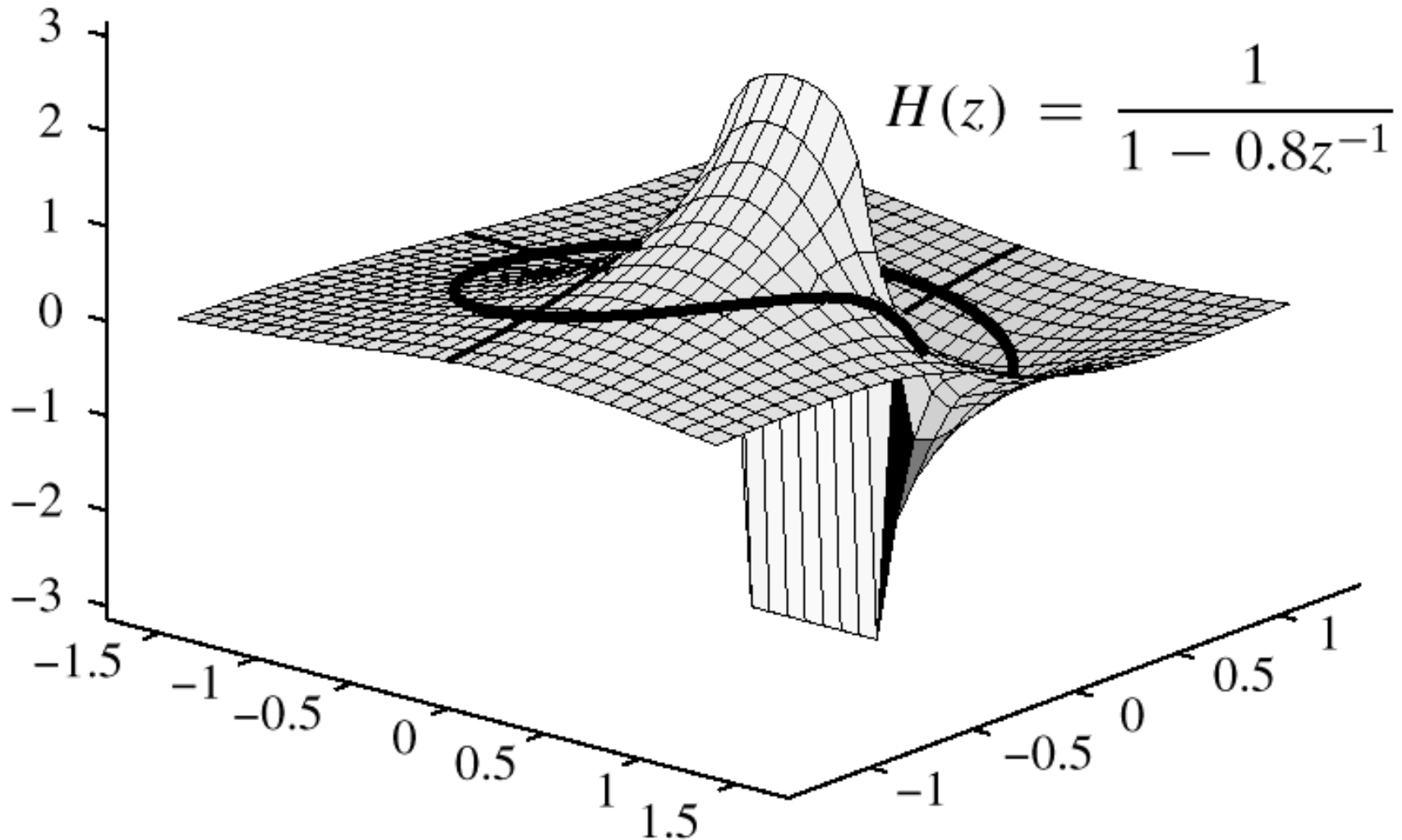
$$H(z) = \frac{1}{1 - 0.8z^{-1}}$$

Zero at : $z = 0$



UNIT CIRCLE

PHASE from 3-D PLOT



FREQ. RESPONSE from $H(z)$

$$H(e^{j\hat{\omega}}) = H(z) \Big|_{z=e^{j\hat{\omega}}}$$

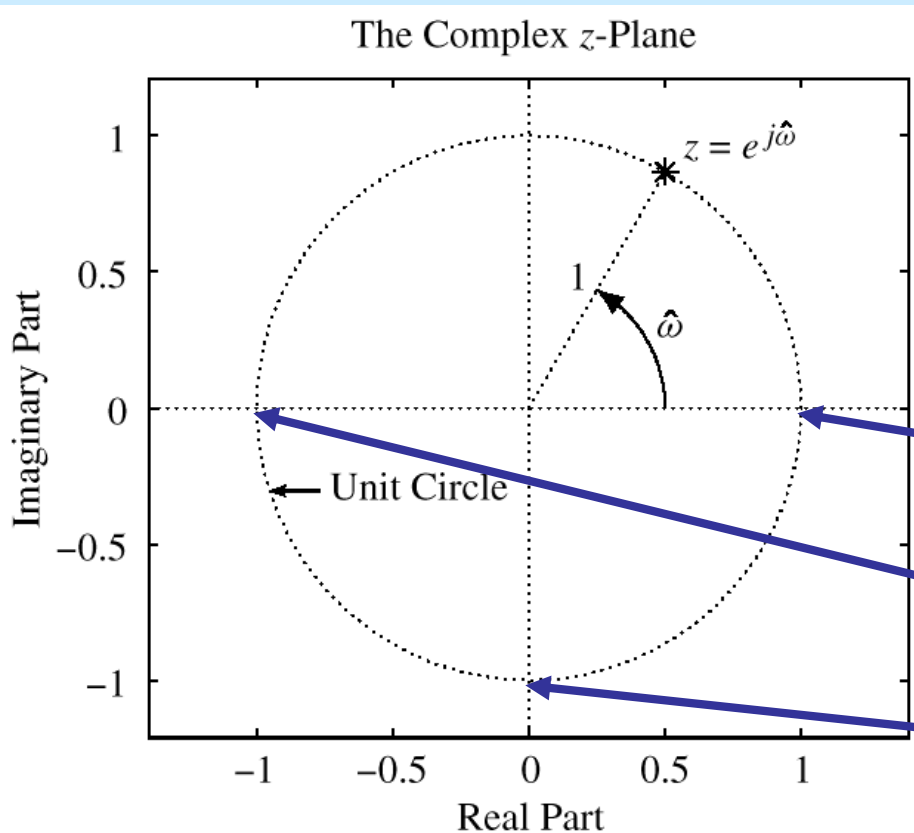
- Relate $H(z)$ to FREQUENCY RESPONSE
- EVALUATE $H(z)$ on the **UNIT CIRCLE**
 - ANGLE is same as FREQUENCY

$$z = e^{j\hat{\omega}} \quad (\text{as } \hat{\omega} \text{ varies})$$

defines a CIRCLE, radius = 1

UNIT CIRCLE: RECAP

- MAPPING BETWEEN z and $\hat{\omega}$



$$z = e^{j\hat{\omega}}$$

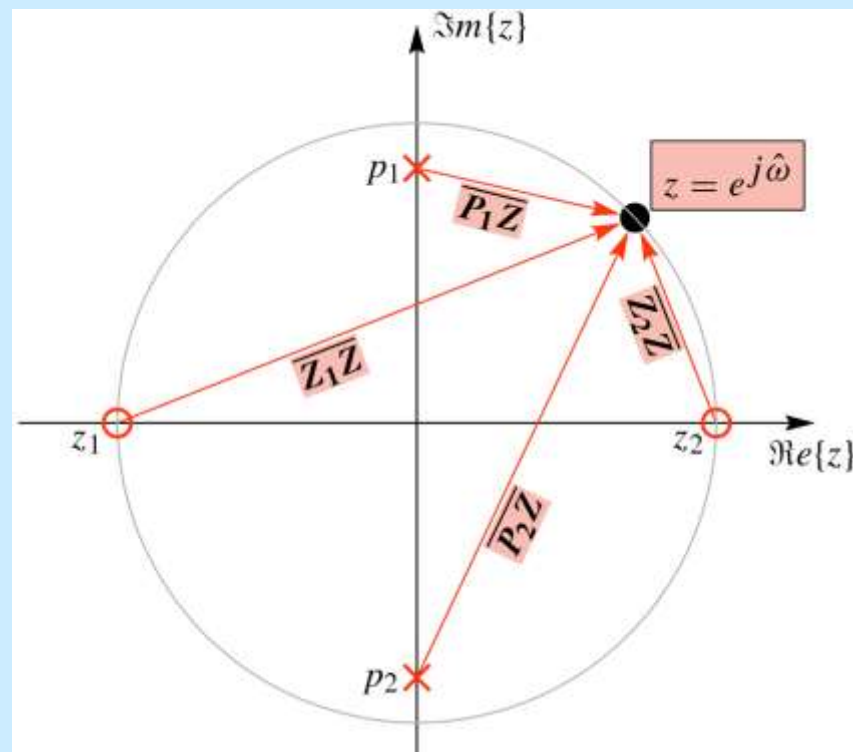
$$\begin{aligned} z = 1 &\leftrightarrow \hat{\omega} = 0 \\ z = -1 &\leftrightarrow \hat{\omega} = \pm\pi \\ z = \pm j &\leftrightarrow \hat{\omega} = \pm\frac{1}{2}\pi \end{aligned}$$

Frequency Response from poles and zeros

$$|H(e^{j\hat{\omega}})| = G \frac{|e^{j\hat{\omega}} - z_1| |e^{j\hat{\omega}} - z_2|}{|e^{j\hat{\omega}} - p_1| |e^{j\hat{\omega}} - p_2|}$$

$$|H(e^{j\hat{\omega}})| = G \frac{\overline{z_1 z} \cdot \overline{z_2 z}}{\overline{p_1 z} \cdot \overline{p_2 z}}$$

$$H(z) = G \frac{(z - z_1)(z - z_2)}{(z - p_1)(z - p_2)}$$



IIR H(z) example: two poles

- Poles just inside the unit circle (for stability)

$$H(z) = \frac{1}{1 + 0.97z^{-1} + 0.9409z^{-2}}$$

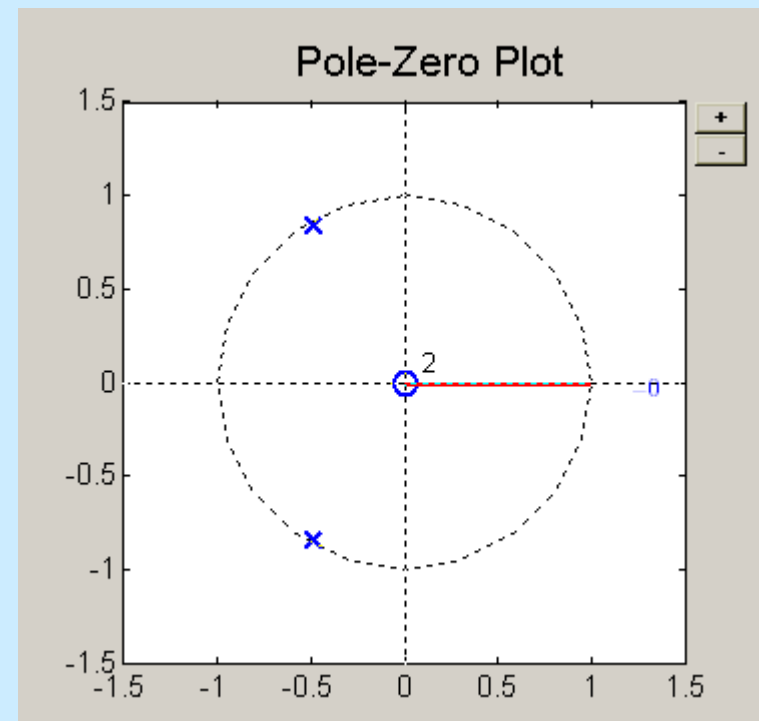
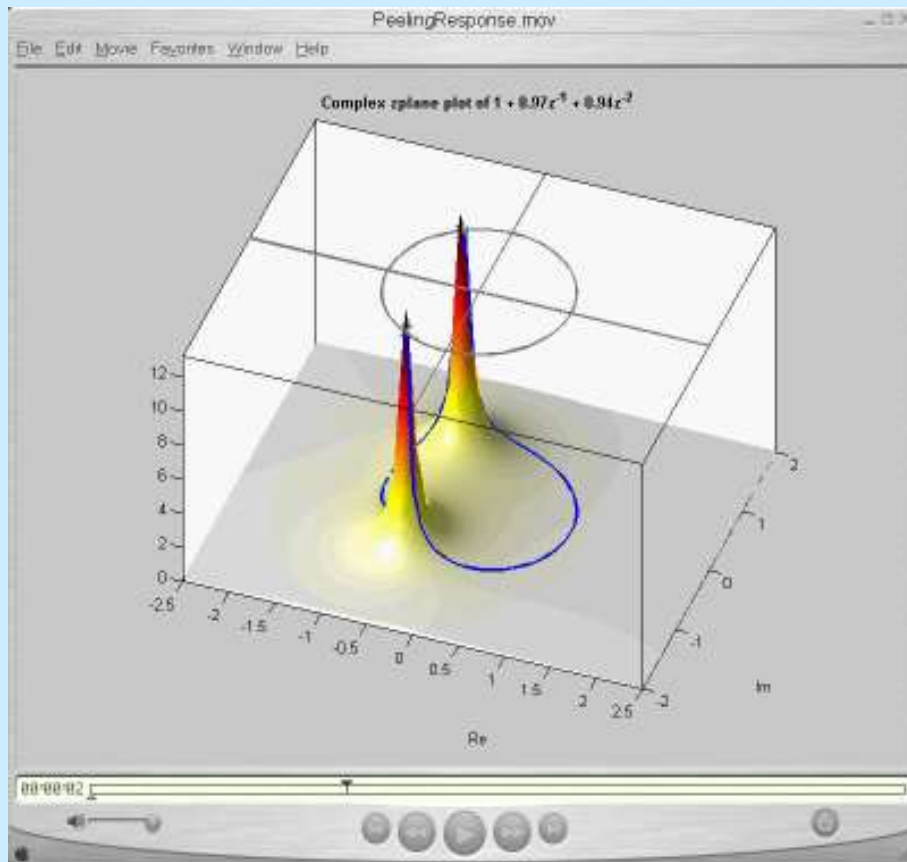
2 Poles : $z = 0.97e^{\pm j2\pi/3}$

2 Zeros : $z = 0, 0$

- MATLAB: `roots ()` and `poly ()`
 - `roots ([1, 0.97, 0.9409])`
 - `poly (0.97*exp(j*2*pi*[1,-1]/3))`

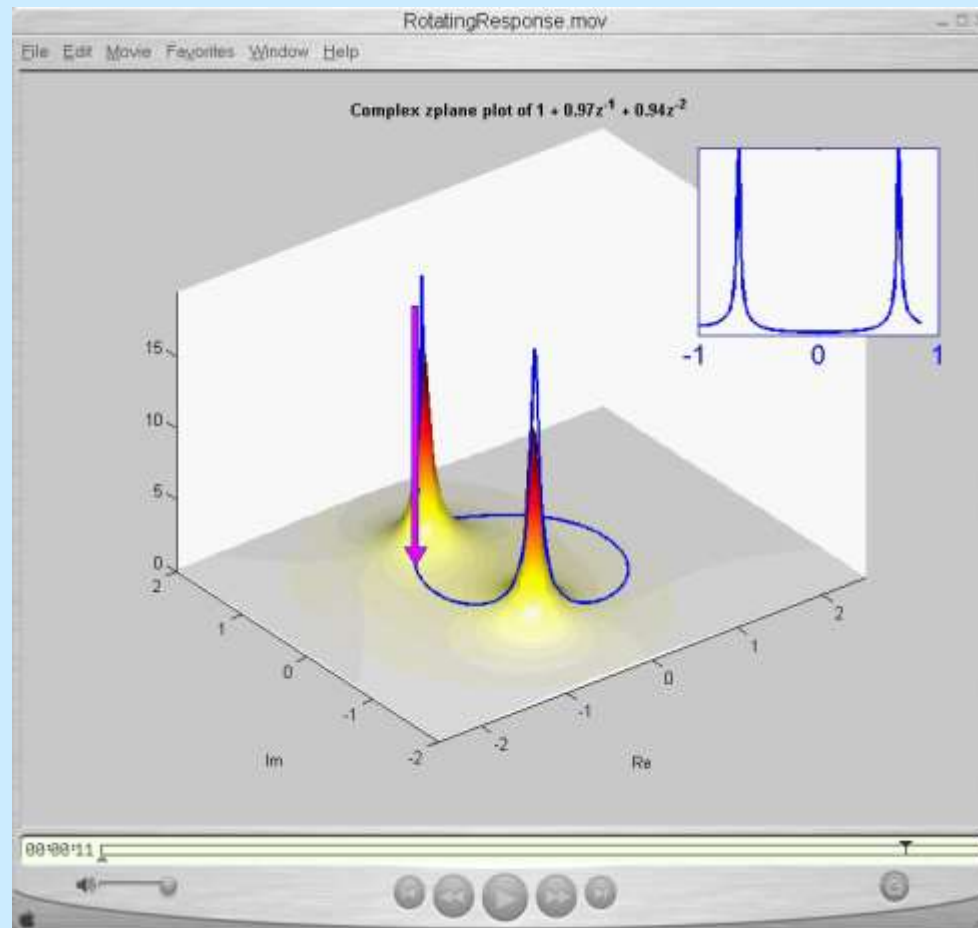
MOVIE for $H(z)$ in 3-D

- POLES to $H(z)$ to Frequency Response
- TWO POLES SHOWN

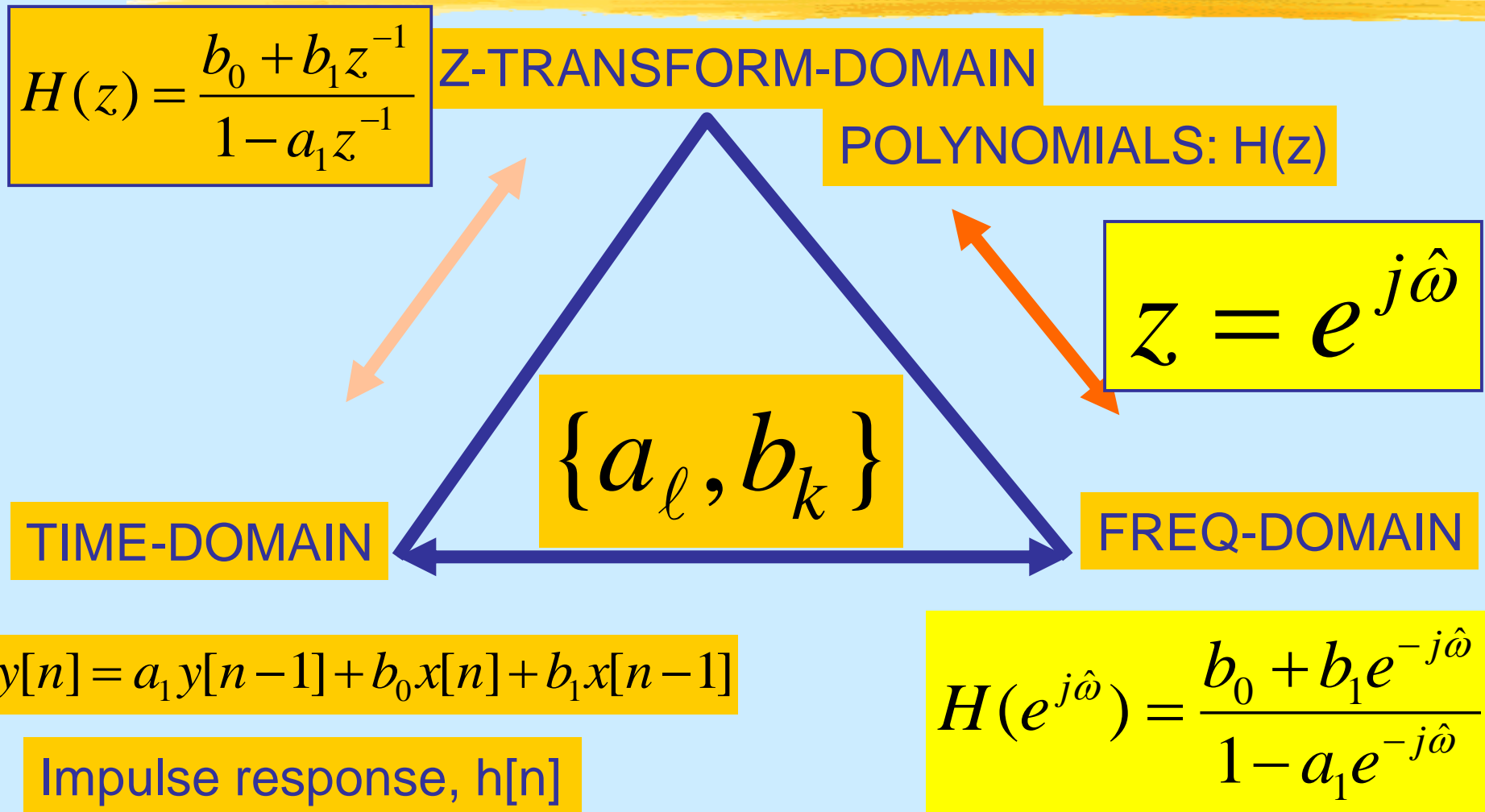


Frequency Response from $H(z)$

Walking around the Unit Circle

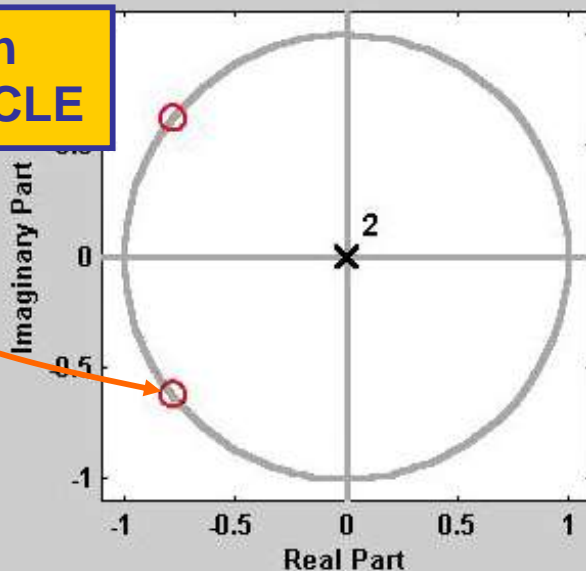


THREE DOMAINS: $H(e^{j\hat{\omega}})$



3 DOMAINS MOVIE: FIR

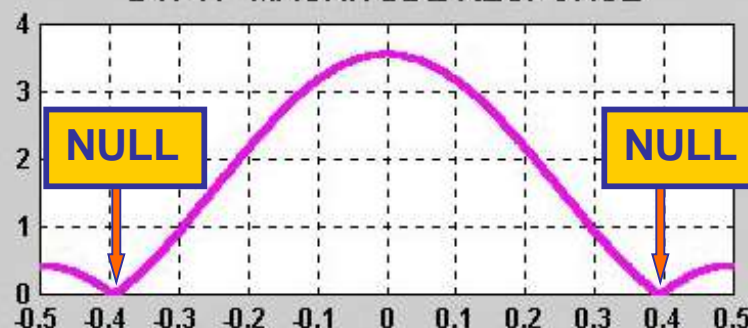
ZEROS on UNIT-CIRCLE



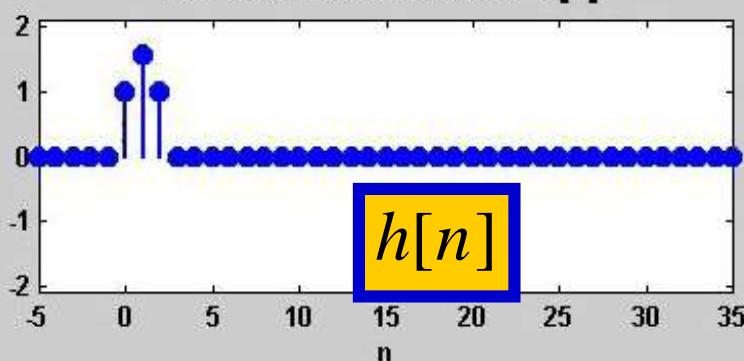
$$1 + 1.56z^{-1} + z^{-2}$$

$$H(z)$$

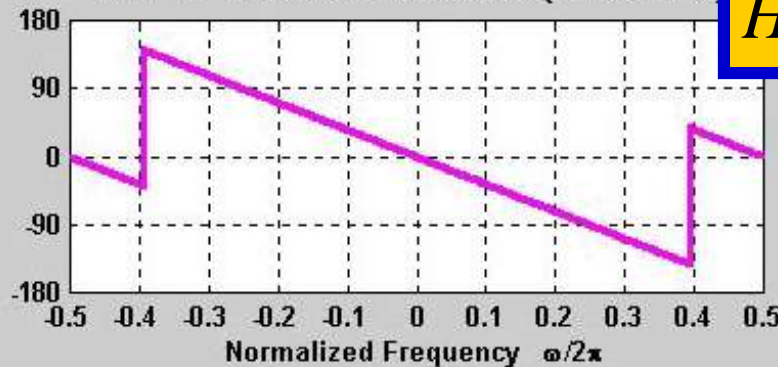
DTFT: MAGNITUDE RESPONSE



IMPULSE RESPONSE: $h[n]$

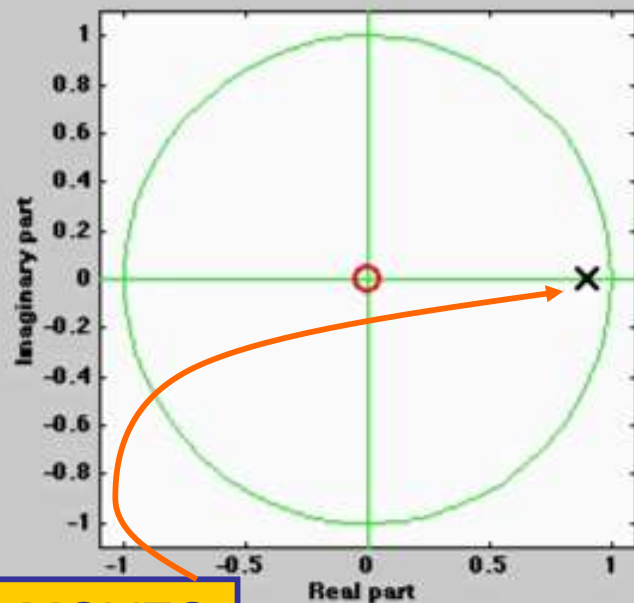


DTFT: PHASE RESPONSE (DEGREES)



$$H(e^{j\hat{\omega}})$$

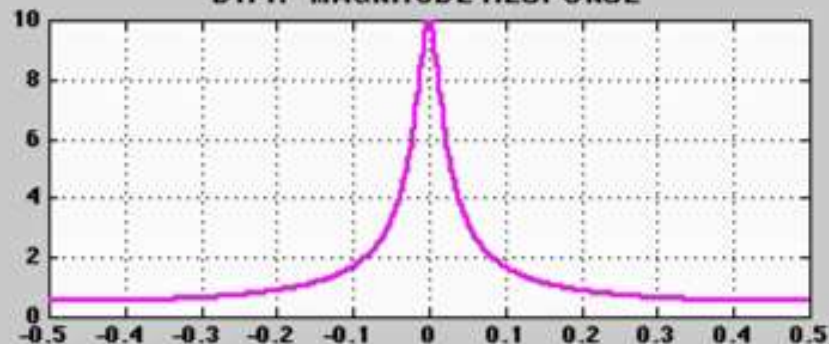
3 DOMAINS MOVIE: IIR



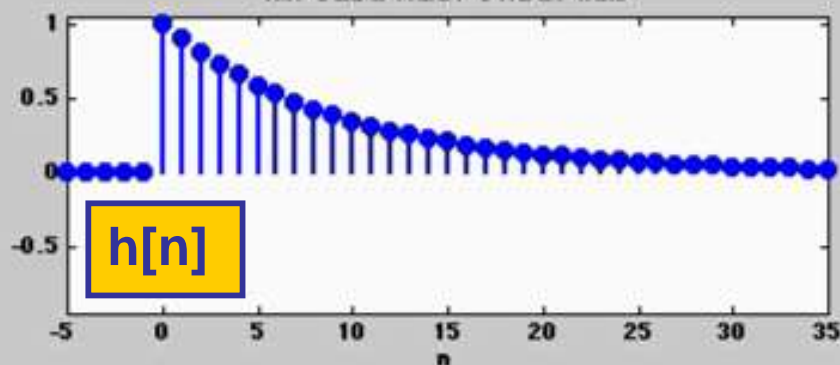
$$\frac{1}{1 - 0.9z^{-1}}$$

$H(z)$

DTFT: MAGNITUDE RESPONSE

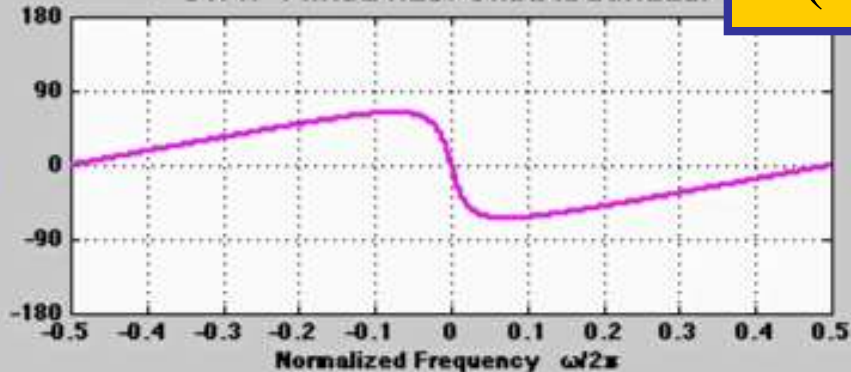


IMPULSE RESPONSE: $h[n]$



$h[n]$

DTFT: PHASE RESPONSE (DEGREES)



$H(e^{j\hat{\omega}})$

7 IIR MOVIES @ WEBSITE



- http://dspfirst.gatech.edu/chapters/08feedback/demos/3_domain/index.html
- 3 DOMAINS MOVIES: IIR Filters
 - One pole moving and a zero at the origin
 - One pole and one zero; both moving
 - Two complex-conjugate poles moving radially
 - Two complex-conjugate poles moving in angle
 - Movement of a zero in a two-pole Filter
 - Radial Movement of Two out of Four Poles
 - Angular Movement of Two out of Four Poles

Reminder:

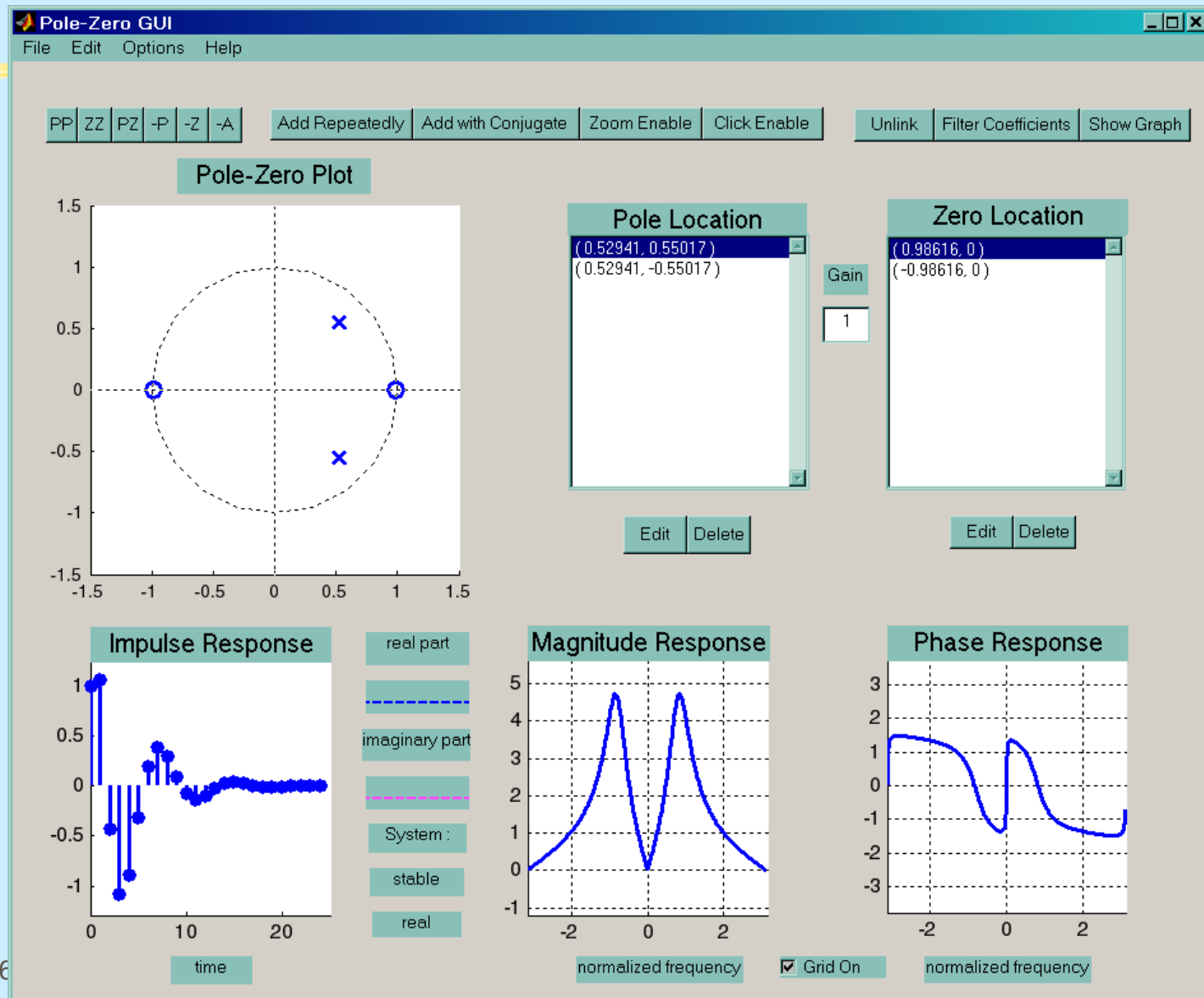
4 FIR MOVIES @ WEBSITE

- http://dspfirst.gatech.edu/chapters/08feedback/demos/3_domain/index.html
- 3 DOMAINS MOVIES: FIR Filters
 - Two zeros moving around UC and inside
 - Three zeros; one held fixed at $z = -1$
 - Ten zeros; 9 equally spaced around UC; one moving
 - Ten zeros; 8 equally spaced around UC; two moving

Remove Interference

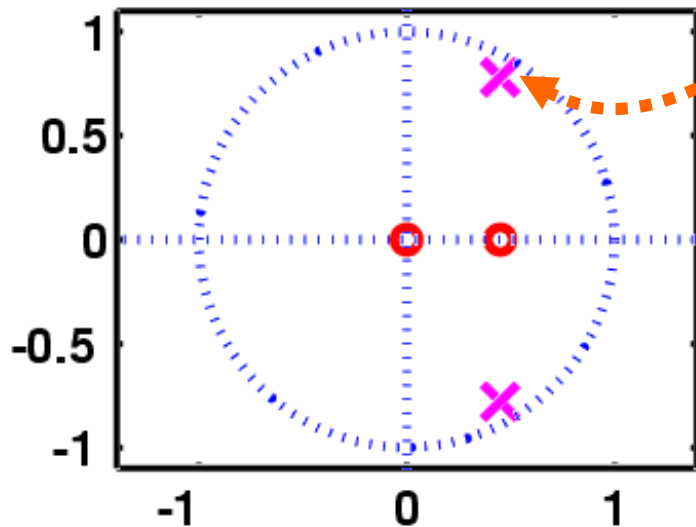
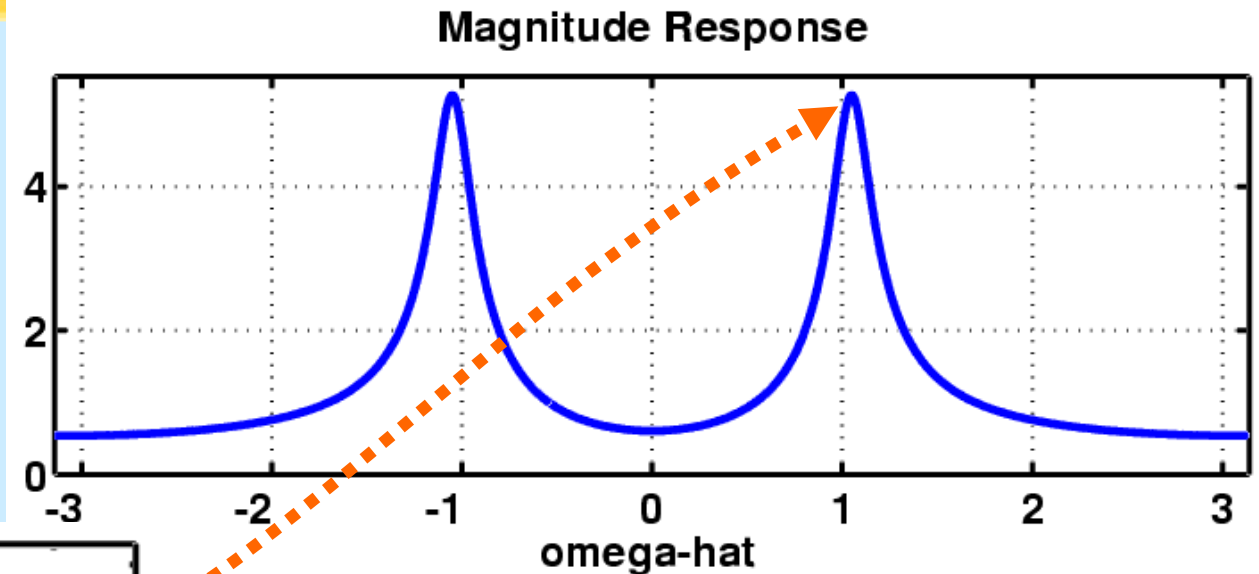
- Design a NOTCH filter (Find a_k and b_k)
 - To Reject completely 0.7π
 - This is NULLING
 - Zeros on UC $2 \text{ Zeros} : z = e^{\pm j0.7\pi}$
 - Make the frequency response magnitude FLAT away from the notch. $2 \text{ Poles} : z = 0.97e^{\pm j0.7\pi}$
 - Use poles at the same angle
- Z-POLYNOMIALS provide the TOOLS
 - PEZDEMO GUI

PeZ Demo: Pole-Zero Placing



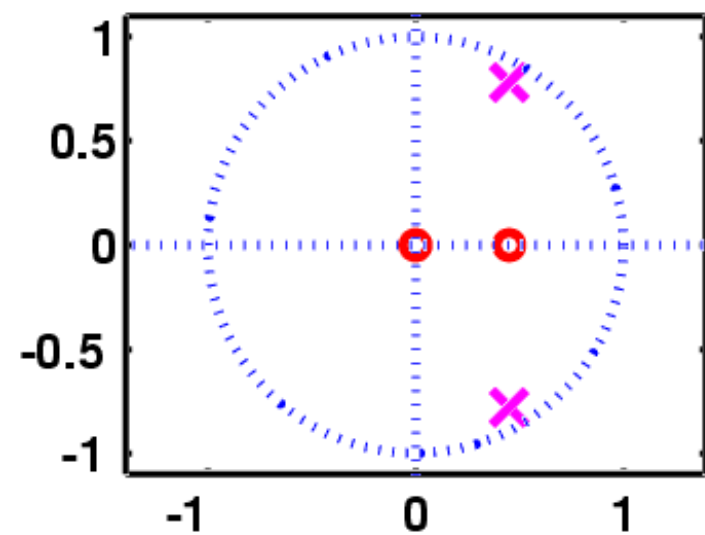
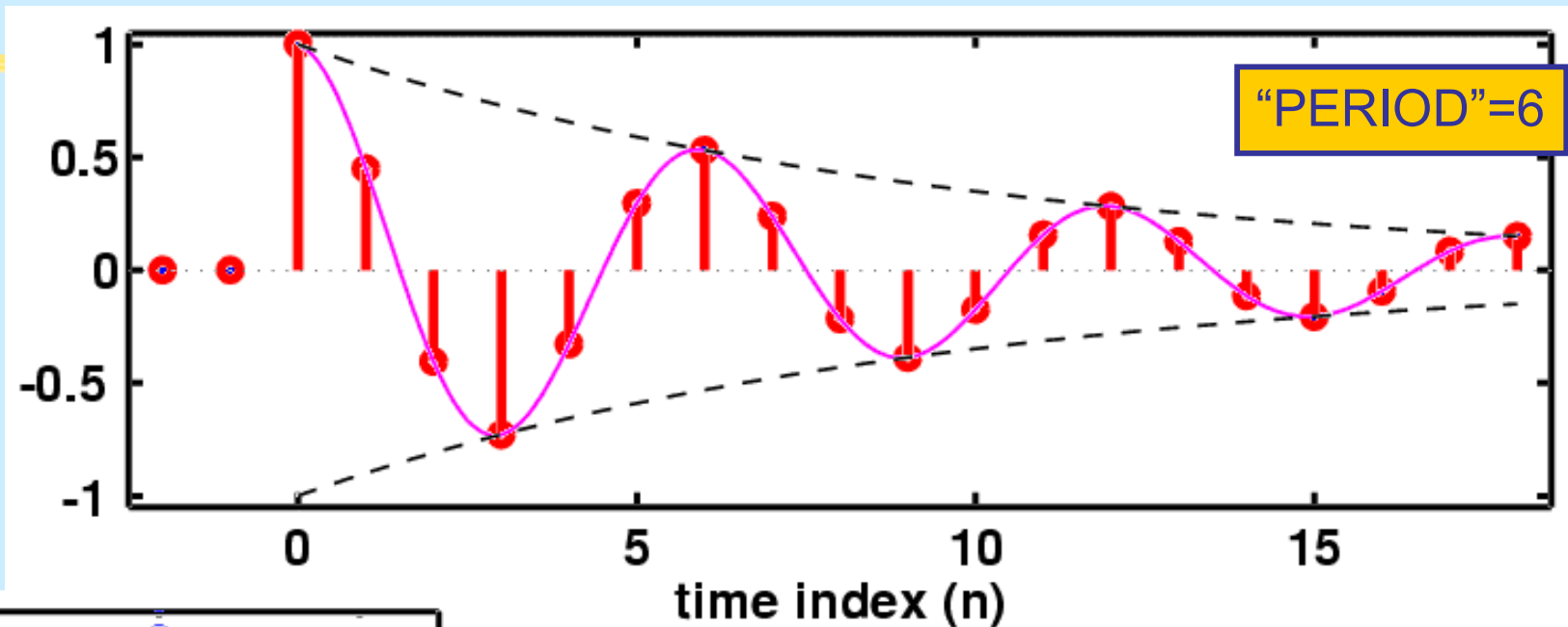
Complex POLE-ZERO PLOT

Where is the peak?



$$H(z) = \frac{1 - 0.45z^{-1}}{1 - 0.9z^{-1} + 0.81z^{-2}}$$

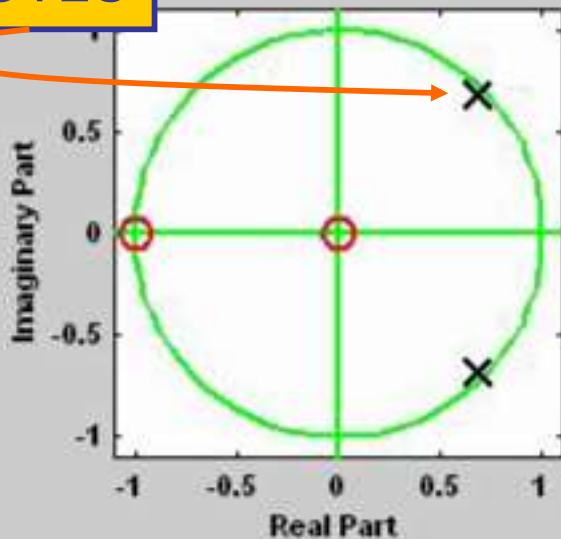
$h[n]$: Decays & Oscillates



$$h[n] = (0.9)^n \cos(\pi n / 3) u[n]$$

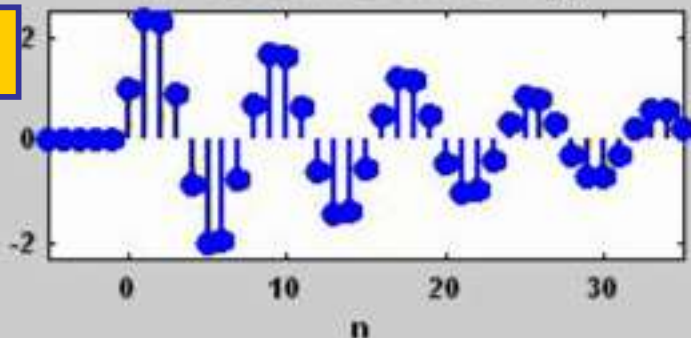
3 DOMAINS MOVIE: IIR

POLE MOVES



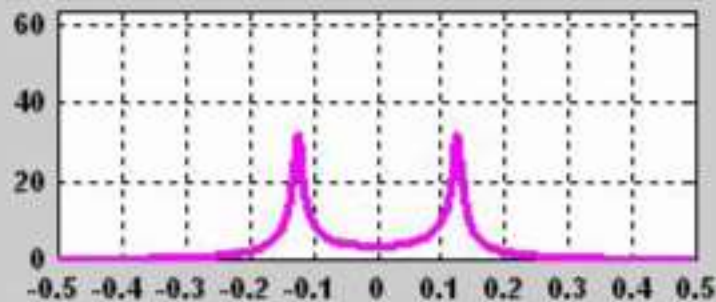
IMPULSE RESPONSE: $h[n]$

$h[n]$

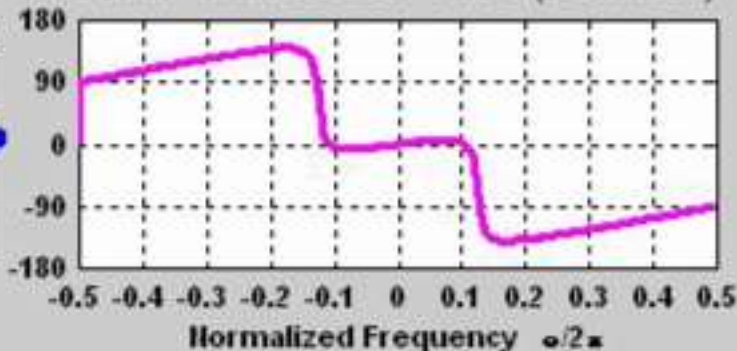


$$\frac{1 + z^{-1}}{1 - 1.36z^{-1} + 0.918z^{-2}}$$

DTFT: MAGNITUDE RESPONSE



DTFT: PHASE RESPONSE (DEGREES)



$H(z)$

$H(\omega)$


SINUSOIDAL RESPONSE

- $x[n] = \text{SINUSOID} \Rightarrow y[n]$ is SINUSOID
- Get MAGNITUDE & PHASE from $H(z)$

if $x[n] = e^{j\hat{\omega}n}$

then $y[n] = H(e^{j\hat{\omega}}) e^{j\hat{\omega}n}$

where $H(e^{j\hat{\omega}}) = H(z) \Big|_{z=e^{j\hat{\omega}}}$



POP QUIZ

- Given:

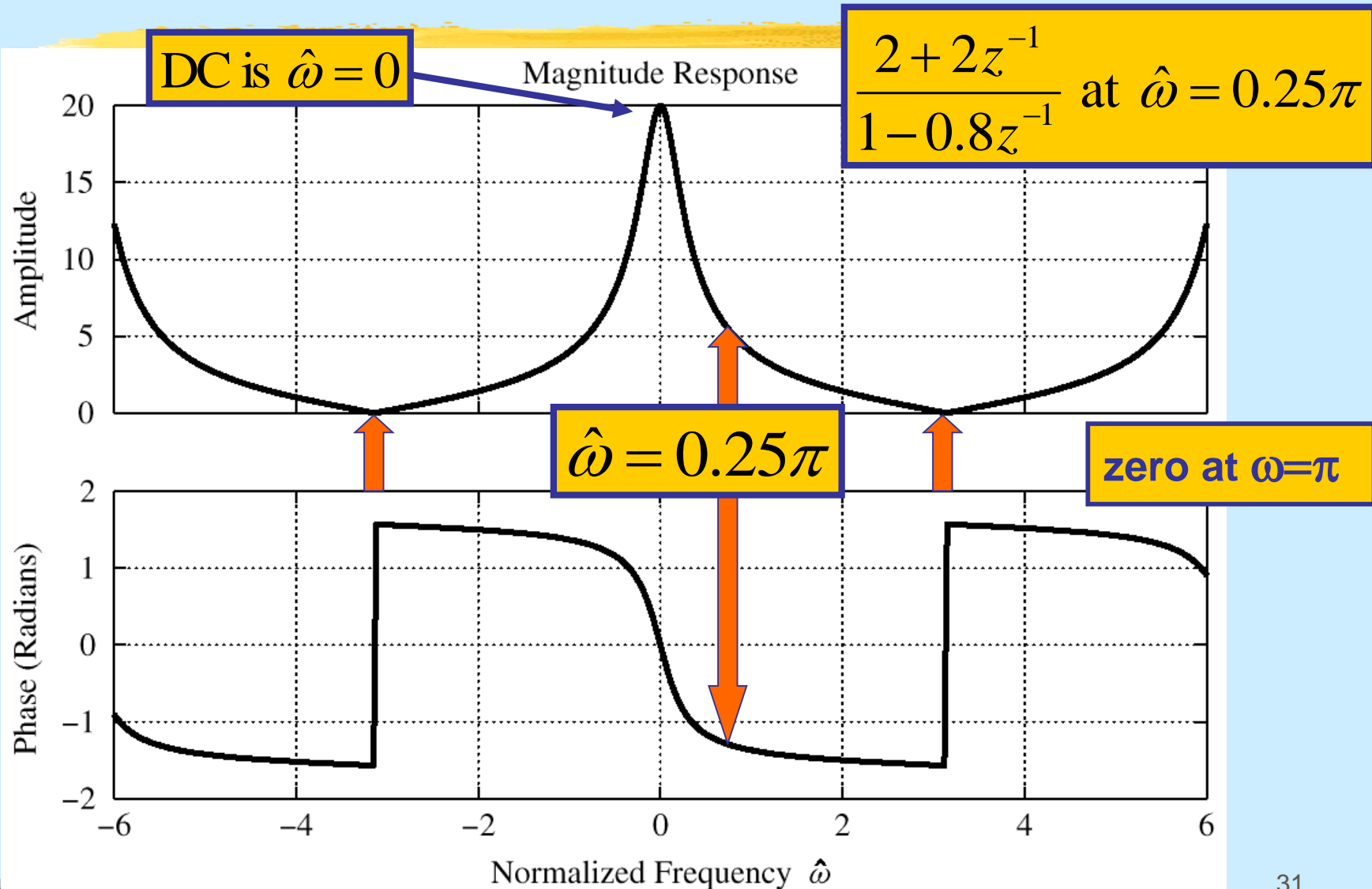
$$H(z) = \frac{2 + 2z^{-1}}{1 - 0.8z^{-1}}$$

- Find the Impulse Response, $h[n]$
- Find the output, $y[n]$

- When

$$x[n] = \cos(0.25\pi n)$$

Evaluate FREQ. RESPONSE



POP QUIZ: Eval Freq. Resp.

- Given:
$$H(z) = \frac{2 + 2z^{-1}}{1 - 0.8z^{-1}}$$

- Find output, $y[n]$, when $x[n] = \cos(0.25\pi n)$

- Evaluate at
$$z = e^{j0.25\pi}$$

$$H(z) = \frac{2 + 2(\frac{\sqrt{2}}{2} - j\frac{\sqrt{2}}{2})}{1 - 0.8e^{-j0.25\pi}} = 5.182e^{-j1.309}$$

$$y[n] = 5.182 \cos(0.25\pi n - 0.417\pi)$$