# **ASSIGNMENT 1**

### Answer to the question no. 1

We know,

$$\frac{X}{Z} = \frac{x}{f}$$
Where, X = target size,
$$Z = \text{distance from the lens}$$

$$x = \text{height of CCD array}$$

$$f = \text{distance between pinhole and CCD}$$

$$\frac{X}{500mm} = \frac{7mm}{35mm}$$

So the target size = 100mm on the size.

X = 100mm

Given that we have total of 1024 elements per line, so the resolution of 1 line will be:

$$\frac{1024}{100} \approx 10 \ elements / mm$$

For line pairs, we divide by 2. We get,  $\frac{10}{2} = 5$  line pairs / mm.

Therefore, the number of line pairs per mm is 5-line pairs / mm.

#### Answer to the question no. 2

Given, Affine transformation matrix,  $A = \begin{bmatrix} 0.25 & 0.433 & 0 \\ -0.2598 & 0.15 & 0 \\ 50 & 75 & 1 \end{bmatrix}$ 

Without homogeneous coordinates we can write,

$$\begin{bmatrix} s_x cos\theta & s_y cos\theta \\ -s_x sin\theta & s_y cos\theta \\ x_c & y_c \end{bmatrix}$$
 Where,  $x_c$  = translation in x axis 
$$y_c = \text{translation in y axis}$$
 
$$s_x = \text{scaling in x axis}$$
 
$$s_y = \text{scaling in x axis}$$
 
$$\theta = \text{angle of rotation}$$

angle of rotation,

$$\theta = \frac{0.15}{\sqrt{0.2598^2 + 0.15^2}}$$

$$\theta = \frac{0.15}{\sqrt{0.8999604}} = \frac{0.15}{0.3} = 0.5$$

Scaling in x-axis,

$$s_{\chi} = \sqrt{0.25^2 + 0.433^2} = 0.5$$

Scaling in y-axis,

$$s_y = \sqrt{0.2598^2 + 0.15^2} = 0.3$$

#### Answer to the question no. 3

Obtaining the transformation function T(r)

As we know,

$$s = T(r)$$

$$= \int_0^r p_r(w)dw$$

$$= \int_0^r (-2w + 2)dw$$

$$= -r^2 + 2r$$

Obtaining the transformation function G(z)

$$v = G(z) = \int_{0}^{z} p_{z}(w)dw = \int_{0}^{z} 2wdw = z^{2}$$

Obtaining the transformation function  $G^{-1}$ 

$$z = G^{-1}(v) = \pm \sqrt{v},$$

$$so, z = +\sqrt{v}$$

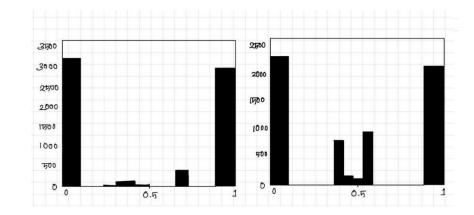
$$z = \sqrt{2r - r^2}$$

Therefore, we can say that  $0 \le z \le 1$  when  $0 \le r \le 1$ 

#### Answer to the question no: 4

- a) The boundary points number between the black and white regions is larger in the image on the right. When the images are blurred with a 3×3 averaging mask, the boundary points will increase to a larger number of different values for the image on the right, that why the histograms of the two blurred images will be different.
- b) Assume the image size is N x N, with the surrounded border of 0s. Blurring the image with a 3x3 averaging mask coefficient is 1/9. A larger N would result in a more significant number of 0/255 in the output histogram, where smaller N would result in a lower value. But we have to sure that the summation is equal to N x N.

If we consider the image as 80 x 80 and the black as 0 pixel and white as 1 pixel. The histogram can be plotted as:

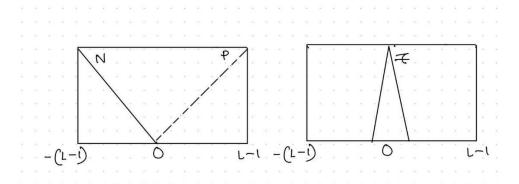


## Answer to the question no: 5

- a) If center pixel depth is > depth of all the neighbors, then it will reduce the center pixel's depth. Similarly, if center pixel depth < depth of all neighbors then it will increase the depth of the center pixel. For Z, it the pixel value will be unchanged which is V=0 and z'=z.
- b)
  The IF-THEN rules are:

Using notation for positive as P, negative as N and zero as Z. IF  $d_2$  is P AND  $d_4$  is P AND  $d_6$  is P AND  $d_8$  is P THEN v is P IF  $d_2$  is N AND  $d_4$  is N AND  $d_6$  is N AND  $d_8$  is N THEN v is negative ELSE v is zero

c) The values of  $d_i$  is from –(L-1) to (L-1) Here, we can use the triangular membership functions for P, N and Z. So, we can find the membership functions



d) graphical representation of the rule set:

