

view\_frames Result  
Recorded at time: 1207.590

map

odom

base\_link

body\_link

front\_left\_wheel

front\_right\_wheel

rear\_left\_wheel

rear\_right\_wheel

camera\_link

range\_fl

range\_fr

range\_rl

range\_rr

laser

top

camera\_depth\_frame

camera\_rgb\_frame

Broadcaster: /gmapping\_node  
Average rate: 20.220 Hz  
Most recent transform: 1207.610 ( -0.020 sec old)  
Buffer length: 4.550 sec

Broadcaster: /gazebo  
Average rate: 10.222 Hz  
Most recent transform: 1207.490 ( 0.100 sec old)  
Buffer length: 4.500 sec

Broadcaster: /robot\_state\_publisher  
Average rate: 10000.000 Hz  
Most recent transform: 0.000 ( 1207.590 sec old)  
Buffer length: 0.000 sec

Broadcaster: /robot\_state\_publisher  
Average rate: 49.356 Hz  
Most recent transform: 1207.580 ( 0.010 sec old)  
Buffer length: 4.660 sec

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