

## Lesson 7. A General Stochastic Process Model

Course standards covered in this lesson: C2 – Constructing and interpreting stochastic process models.

### 1 A general stochastic process model

- Let's generalize the Bit Bucket example from last time
- Notation:  $\mathbf{S}_n = \begin{pmatrix} S_{1,n} \\ \vdots \\ S_{m,n} \end{pmatrix}$  is a vector of  $m$  random variables
- $\{\mathbf{S}_n; n = 0, 1, 2, \dots\}$  is the **state-change process**
  - Represents all relevant information about system status
- $\{T_n; n = 0, 1, 2, \dots\}$  is the **event-epoch process**
  - $T_n$  is the time of the  $n$ th system event
- $\{\mathbf{Y}_t; t \geq 0\}$  is the **output process**, defined by  $\mathbf{Y}_t \leftarrow \mathbf{S}_n$  for  $t \in [T_n, T_{n+1})$ 
  - Connects state changes with times that they occur
- **System events**  $e_1, e_2, \dots, e_k$ 
  - Update the new system state  $\mathbf{S}_{n+1}$  from previous system state  $\mathbf{S}_n$
  - Reset **clocks**  $\mathbf{C} = (C_1, C_2, \dots, C_k)$  if necessary
- Initial system event  $e_0$
- **Simulation algorithm**

algorithm Simulation:

- |   |   |
|---|---|
| 1: $n \leftarrow 0$                             | (initialize system event counter)           |
| $T_0 \leftarrow 0$                              | (initialize event epoch)                    |
| $e_0()$   | (execute initial system event)              |
| 2: $T_{n+1} \leftarrow \min\{C_1, \dots, C_k\}$ | (advance time to next pending system event) |
| $I \leftarrow \arg \min\{C_1, \dots, C_k\}$     | (find index of next system event)           |
| 3: $\mathbf{S}_{n+1} \leftarrow \mathbf{S}_n$   | (temporarily maintain previous state)       |
| $C_I \leftarrow \infty$                         | (event $I$ no longer pending)               |
| 4: $e_I()$                                      | (execute system event $I$ )                 |
| $n \leftarrow n + 1$                            | (update event counter)                      |
| 5: go to line 2                                 |   |

- $\mathbf{S}_{n+1} \leftarrow \mathbf{S}_n$  in Step 3 is for convenience
  - ◊ With this, system event functions only need to specify changes in system state

- A **stochastic process** is a model describing a collection of time-ordered random variables that represent possible sample paths
- A **sample path** is a collection of time-ordered data describing how a stochastic process actually behaved in one instance

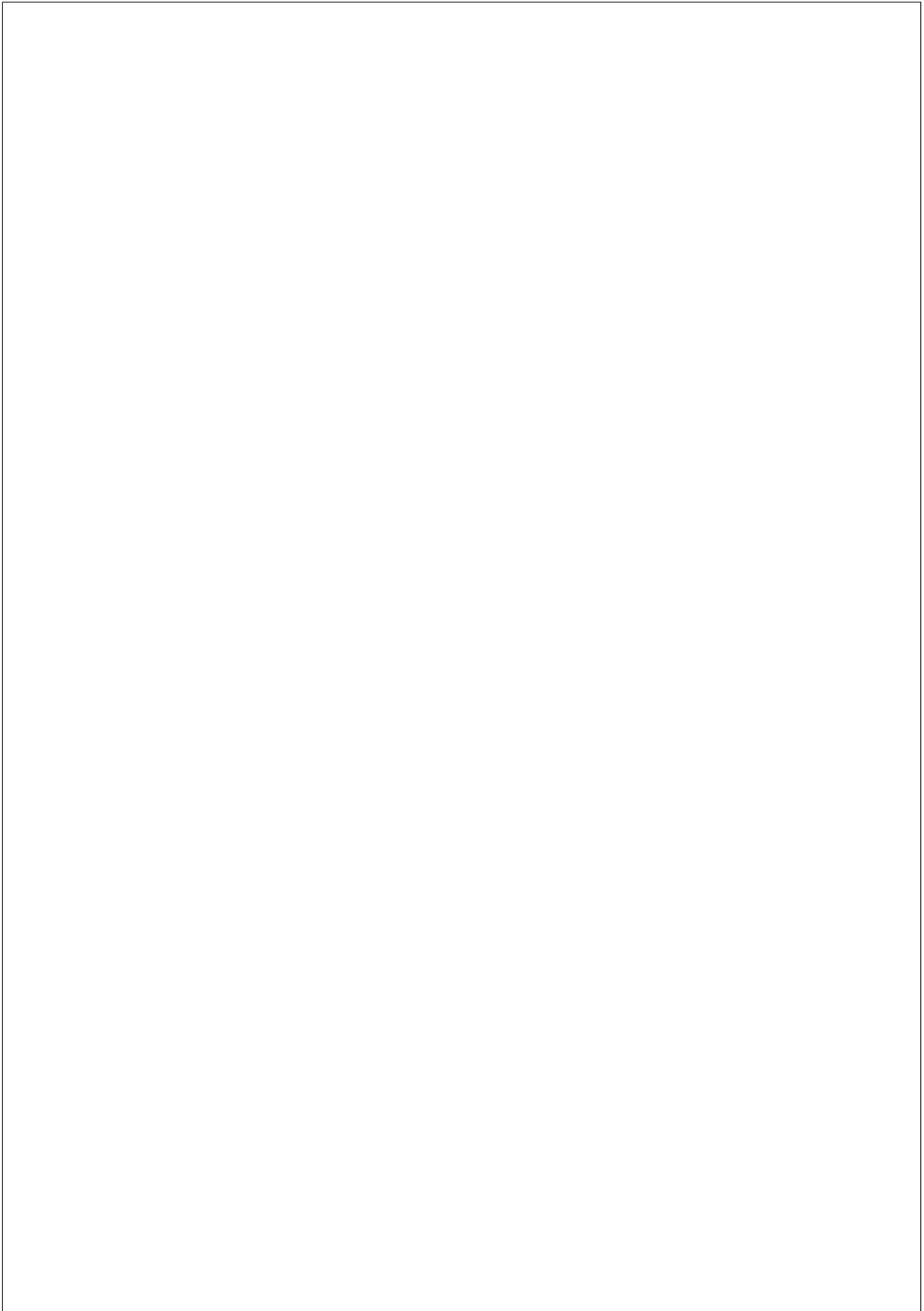
## 2 The Case of Copy Enlargement, revisited

The Darker Image, a national chain of small photocopying shops, currently configures each store with one photocopying machine and one clerk. Arriving customers stand in a single line to wait for the clerk. The clerk completes the customers' photocopying jobs one at a time, first-come-first-served, including collecting payment for the job.

- Let's formulate a stochastic process model for the copy shop as it currently operates
- Assumptions:
  - Interarrival times are independent with common cdf  $F_G$
  - Service times are independent with common cdf  $F_X$
  - Interarrival times and service times are independent
- System events:

- System state:

- System event algorithms:



- Output process:

- Time-average number of customers waiting for service over the first 6 hours:

- Time-average number of copiers in use – the **utilization** of the copier – over the first 6 hours:

- In words, what is  $\int_0^6 Y_{1,t} dt$ ?