Lesson 21. Geometry and Algebra of "Corner Points", cont.

1 Warm up and overview

- Last time: "corner points" of the feasible region of an LP
- A **polyhedron** is a set of vectors **x** that satisfy a finite collection of linear constraints
 - ∘ Feasible region of an LP ⇔ polyhedron
- Given a polyhedron S, an **extreme point** is a solution $\mathbf{x} \in S$ for which any line segment through \mathbf{x} has an endpoint outside of S
- A collection of constraints defining a polyhedron are **linearly independent** if the LHS coefficient matrix of these constraints has full row rank
- Given a polyhedron S with n decision variables, \mathbf{x} is a **basic solution** if
 - (a) it satisfies all equality constraints
 - (b) at least n constraints are active at \mathbf{x} and are linearly independent
- **x** is a **basic feasible solution** if it is a basic solution and satisfies all constraints of *S*
- "Corner points" = extreme points = basic feasible solutions

Example 1. Consider the polyhedron *S* defined below.

$$S = \begin{cases} x_1 + 3x_2 \le 4 & (1) \\ \mathbf{x} = (x_1, x_2) \in \mathbb{R}^2 : & x_1 \ge 0 & (2) \\ & x_2 \ge 0 & (3) \end{cases}$$

- a. Verify that constraints (1) and (3) are linearly independent.
- b. Compute the basic solution \mathbf{x} active at constraints (1) and (3).
- c. Is **x** a basic feasible solution? Why?

• Today: When are extreme points adjacent? Is there always an optimal solution to an LP that is an extreme point?

2 Adjacency

• An **edge** of a polyhedron S with n decision variables is the set of solutions in S that are active at (n-1) linearly independent constraints

Example 2. Consider the polyhedron and its graph below.

- a. How many linearly independent constraints need to be active for an edge of this polyhedron?
- b. Describe the edge associated with constraint (2).

$$S = \begin{cases} x_1 + 3x_2 \le 15 & (1) \\ x_1 + x_2 \le 7 & (2) \\ x = (x_1, x_2) \in \mathbb{R}^2 : 2x_1 + x_2 \le 12 & (3) \\ x_1 \ge 0 & (4) \\ x_2 \ge 0 & (5) \end{cases}$$

- Two extreme points of a polyhedron S with n decision variables are **adjacent** there are (n-1) <u>common</u> linearly independent constraints at active both extreme points
 - Equivalently, two extreme points are adjacent if the line segment joining them is an edge of *S*

Example 3. Consider the polyhedron in Example 2.

- a. Verify that (3,4) and (5,2) are adjacent extreme points.
- b. Verify that (0,5) and (6,0) are not adjacent extreme points.



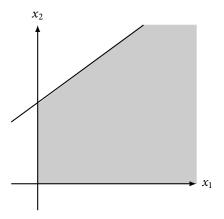
• We can move between adjacent extreme points by "swapping" active linearly independent constraints

3 Extreme points are good enough: the fundamental theorem of linear programming

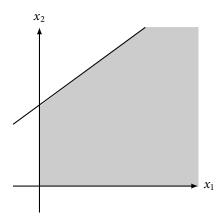
Big Theorem. Let *S* be a polyhedron with at least 1 extreme point. Consider the LP that maximizes a linear function $\mathbf{c}^\mathsf{T} \mathbf{x}$ over $\mathbf{x} \in S$. Then this LP is unbounded, or attains its optimal value at some extreme point of *S*.

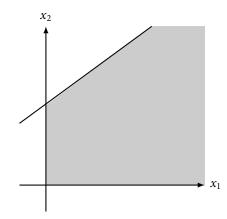
"Proof" by picture.

- Assume the LP has finite optimal value
- The optimal value must be attained at the boundary of the polyhedron, otherwise:



- ⇒ The optimal value is attained at an extreme point or "in the middle of a boundary"
- If the optimal value is attained "in the middle of a boundary", there must be multiple optimal solutions, including an extreme point





- ⇒ The optimal value is always attained at an extreme point
- For LPs, we only need to consider extreme points as potential optimal solutions
- It is still possible for an optimal solution to an LP to not be an extreme point
- If this is the case, there must be another optimal solution that is an extreme point

4 Food for thought

- Last time, we saw that a polyhedron may have no extreme points
- We need to be a little careful with these conclusions what if the Big Theorem doesn't apply?
- Next time: we will learn how to convert any LP into an equivalent LP that has at least 1 extreme point, so we don't have to be (so) careful