

### Solutions to Problem 1.

$$\begin{aligned} \text{a. } \Pr\{T_{300} \leq 6 \mid Y_2 = 150\} &= \Pr\{Y_6 \geq 300 \mid Y_2 = 150\} \\ &= \Pr\{Y_6 - Y_2 \geq 150 \mid Y_2 = 150\} \\ &= \Pr\{Y_6 - Y_2 \geq 150\} \\ &= \Pr\{Y_4 \geq 150\} \\ &= 1 - \sum_{j=0}^{149} \frac{e^{-40 \cdot 4} (40 \cdot 4)^j}{j!} \approx 0.7956 \end{aligned}$$

$$\begin{aligned} \text{b. } E[Y_{16} \mid Y_6 = 250] &= 250 + E[Y_{16} - Y_6 \mid Y_6 = 250] \\ &= 250 + E[Y_{16} - Y_6] \\ &= 250 + E[Y_{10}] \\ &= 250 + 40(10) = 650 \end{aligned}$$

c. The first class passengers arrive according to a Poisson process with arrival rate  $\lambda_1 = 0.15(40) = 6$ .

$$E[T_{1,60}] = \frac{60}{\lambda_1} = 10$$

### Solutions to Problem 2.

$$\begin{aligned} \text{a. If } 0 \leq \tau < 6: \quad \Lambda(\tau) &= \int_0^\tau 10 \, dt = 10\tau \\ \text{If } 6 \leq \tau \leq 12: \quad \Lambda(\tau) &= \int_0^6 10 \, dt + \int_6^\tau 4 \, dt = 4\tau + 36 \\ \Rightarrow \Lambda(\tau) &= \begin{cases} 10\tau & \text{if } 0 \leq \tau < 6 \\ 4\tau + 36 & \text{if } 6 \leq \tau \leq 12 \end{cases} \end{aligned}$$

$$\begin{aligned} \text{b. } \Pr\{Z_5 - Z_2 \leq 15 \mid Z_2 = 30\} &= \Pr\{Z_5 - Z_2 \leq 15\} \quad [Z_5 - Z_2 \sim \text{Poisson}(\Lambda(5) - \Lambda(2)) = \text{Poisson}(12)] \\ &= \sum_{j=0}^{15} \frac{e^{-12} (12)^j}{j!} \approx 0.8444 \end{aligned}$$

### Solutions to Problem 3.

In order for an arrival counting process (with arrivals one-at-a-time) to be Poisson, it must satisfy:

- Independent increments: in this context, the number of phone calls arriving at the cell tower in non-overlapping time intervals must be independent
- Stationary increments: in this context, the number of phone calls arriving at the cell tower only depends on the length of the interval, not when the time interval occurs

### Solutions to Problem 4.

$$\mathbf{P} = \begin{bmatrix} 0.5 & 0.2 & 0 & 0.3 \\ 0 & 0.5 & 0.5 & 0 \\ 0 & 0.5 & 0.5 & 0 \\ 0 & 0.4 & 0.2 & 0.4 \end{bmatrix}$$

### Solutions to Problem 5.

a. In this case, the initial state probabilities are

$$\mathbf{p} = \begin{bmatrix} 1/5 \\ 1/5 \\ 1/5 \\ 1/5 \\ 1/5 \end{bmatrix}$$

We want  $\Pr\{S_3 = 4\} = p_4^{(3)} = 4\text{th element of } \mathbf{p}^{(3)} = \mathbf{p}^T \mathbf{P}^3$ .

$$\mathbf{p}^T \mathbf{P}^3 = [0.0328 \quad 0.0172 \quad 0.37975 \quad 0.19525 \quad 0.375]$$

Therefore,  $\Pr\{S_3 = 4\} = 0.19525$ .

b. Let  $\mathcal{R} = \{2, 3\}$ . So,

$$\mathbf{P}_{\mathcal{R}\mathcal{R}} = \begin{bmatrix} 0.30 & 0 \\ 0 & 0.75 \end{bmatrix}$$

Looking at  $\mathbf{P}_{\mathcal{R}\mathcal{R}}$ , we see that  $\mathcal{R} = \{2, 3\}$  does not form a self-contained Markov chain since the rows of  $\mathbf{P}_{\mathcal{R}\mathcal{R}}$  do not sum to 1. Therefore,  $\mathcal{R} = \{2, 3\}$  is not an irreducible set of states.

c. Let  $\mathcal{R} = \{3, 4\}$ . We want  $\pi_4$ .

$$\begin{aligned} \pi_{\mathcal{R}} \mathbf{P}_{\mathcal{R}\mathcal{R}} &= \pi_{\mathcal{R}} \\ \pi_{\mathcal{R}} \mathbf{1} &= 1 \end{aligned} \Leftrightarrow \begin{aligned} 0.75\pi_3 + 0.50\pi_4 &= \pi_3 \\ 0.25\pi_3 + 0.50\pi_4 &= \pi_4 \end{aligned} \Rightarrow \begin{aligned} \pi_3 &= \frac{2}{3}, \pi_4 = \frac{1}{3} \\ \pi_3 + \pi_4 &= 1 \end{aligned}$$

So,  $\pi_4 = \frac{1}{3}$ .

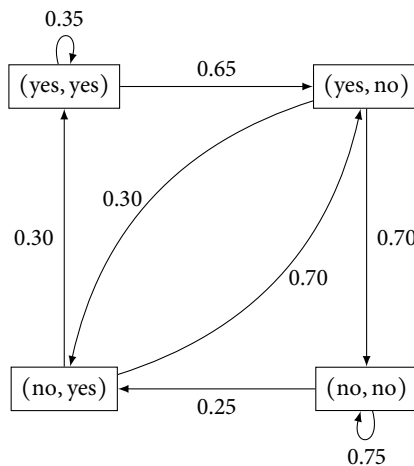
d. The set of all transient states is  $\mathcal{T} = \{1, 2\}$ . Let  $\mathcal{R} = \{5\}$ . Note that 5 is an absorbing state. We want  $\alpha_{15}$ .

$$\alpha_{\mathcal{T}\mathcal{R}} = \left( \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} - \begin{bmatrix} 0.4 & 0.1 \\ 0.2 & 0.3 \end{bmatrix} \right)^{-1} \begin{bmatrix} 0.25 \\ 0.25 \end{bmatrix} = \begin{bmatrix} 0.5 \\ 0.5 \end{bmatrix}$$

So,  $\alpha_{15} = 0.5$ .

### Solutions to Problem 6.

- State space:  $\{(\text{yes}, \text{yes}), (\text{yes}, \text{no}), (\text{no}, \text{yes}), (\text{no}, \text{no})\}$
- Time step: 1 shot
- One-step transition probabilities:



### Solutions to Problem 7.

- Markov property: the probability an officer is promoted, separated, or retired next year only depends on the officer's rank this year. For example, it does not matter how long the officer has held his or her current or previous ranks.
- Time-stationarity: the probability an officer is promoted, separated, or retired next year given the officer's rank this year stays constant from year to year.