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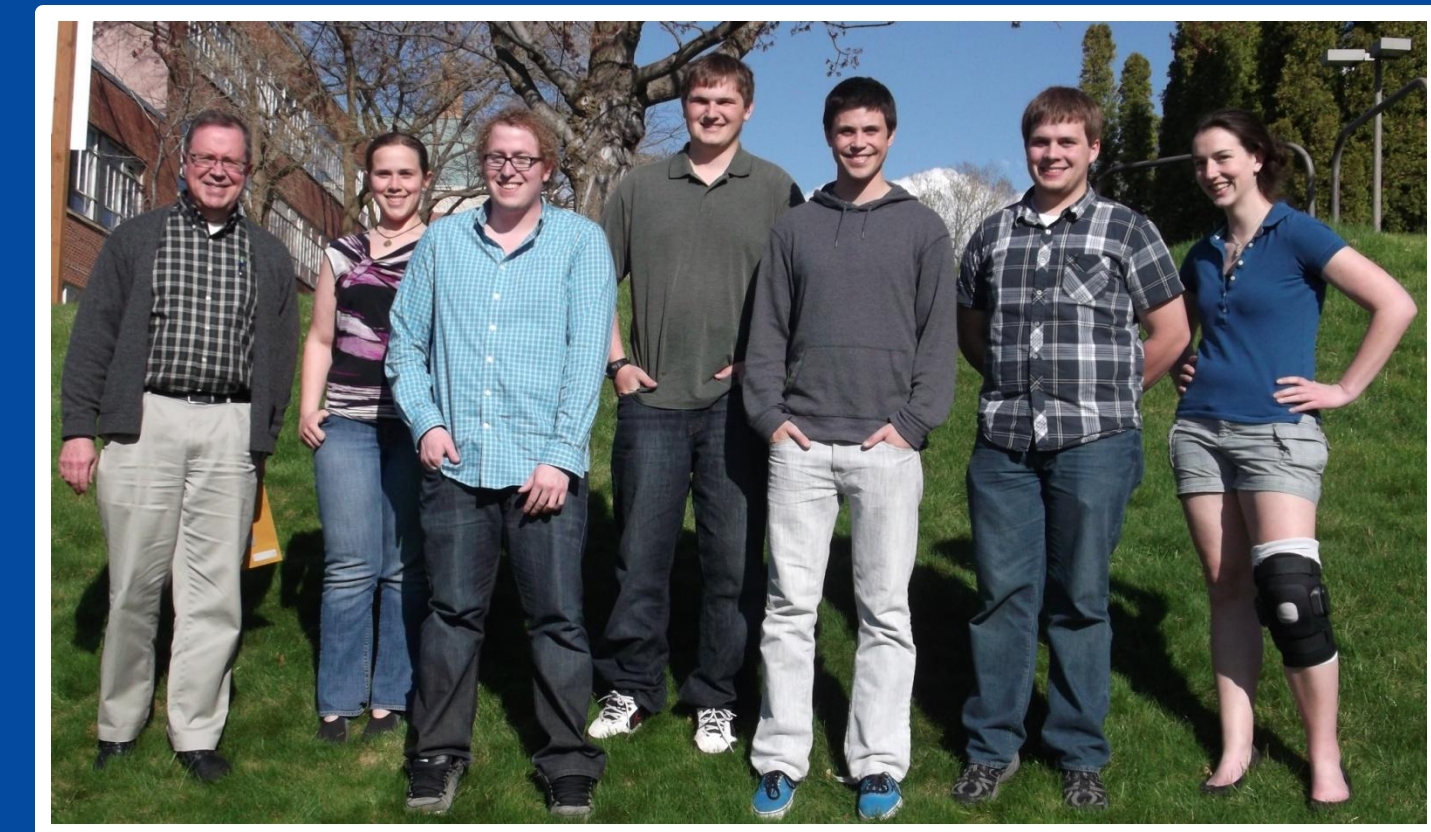
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## Mentors

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# F.E.T.C.H.

## Team Members



Kora Barnes  
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Eric Johnston  
Brian Lee  
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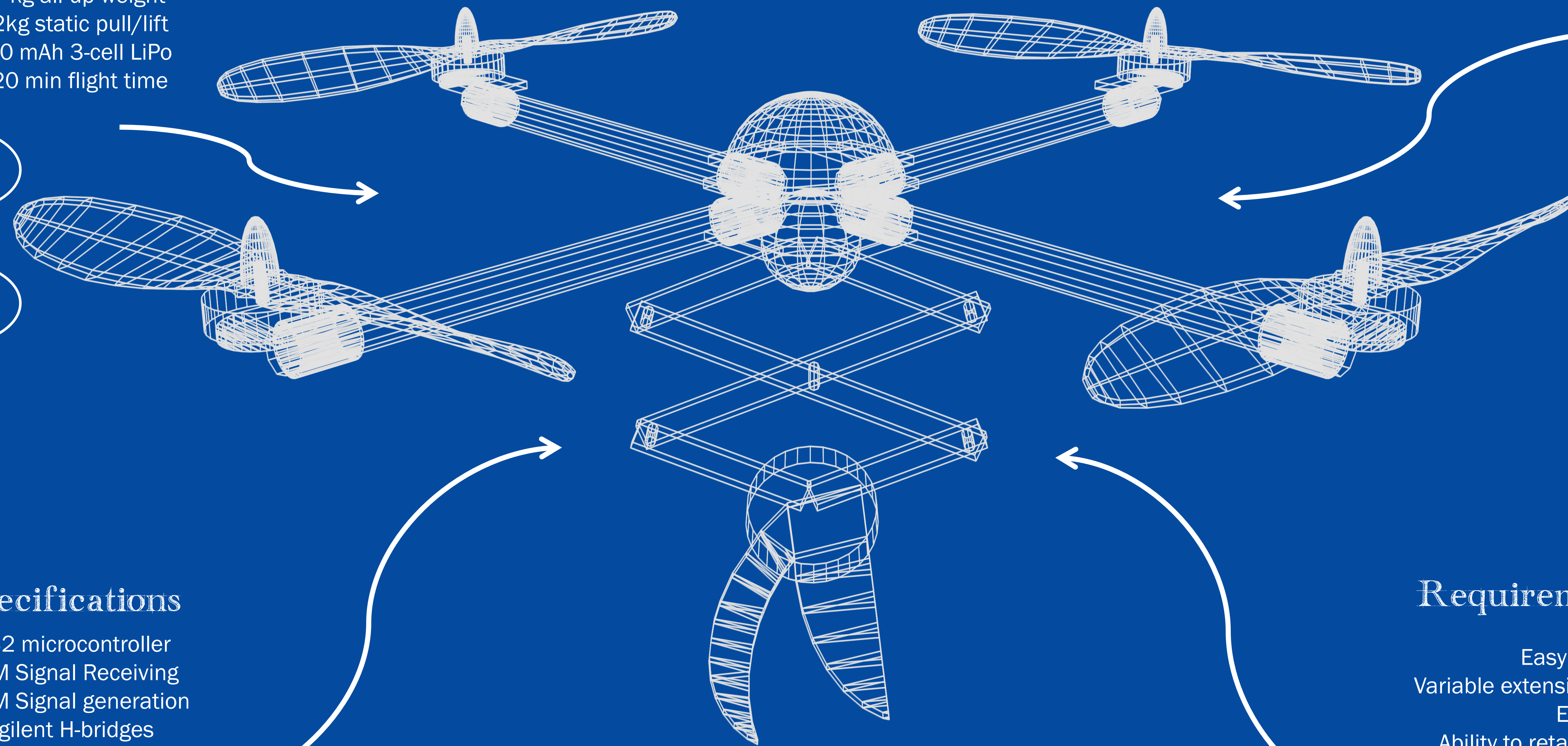
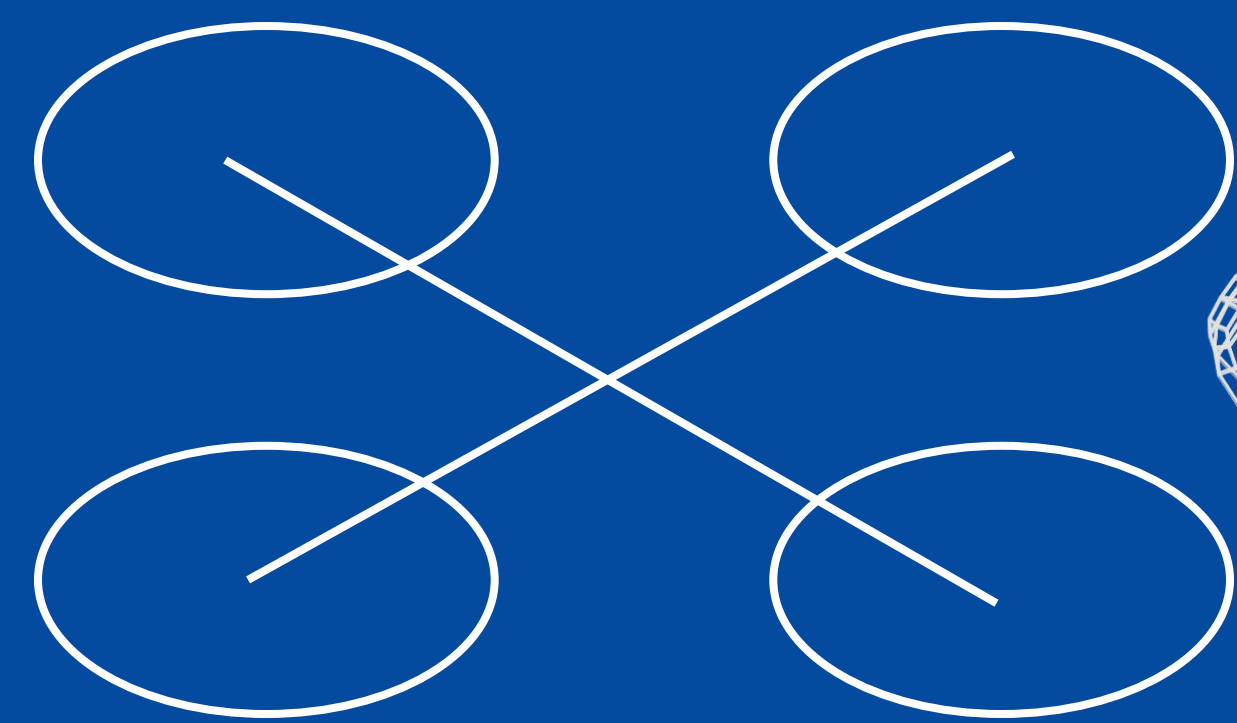
## Quad-copter

### Requirements

Portable  
Agile/Maneuverable  
Stable  
Heavy weight capable  
Easy repair/off-the-shelf  
parts

### Specifications

Ardupilot Mega 2.5 flight  
controller  
620 kV Brushless motors  
12" x 4.7° APC Propellers  
1.27 kg all up weight  
3.32kg static pull/lift  
2200 mAh 3-cell LiPo  
11-20 min flight time



## Software

### Requirements

Interpret signals from RC  
Controller  
Control LEDs  
Control arm Extension  
Control arm speed  
Control cutting  
Prevent motor damage

### Specifications

Pic32 microcontroller  
PWM Signal Receiving  
PWM Signal generation  
2 Digilent H-bridges



## Problem Statement

The College of Natural Resources is required to collect sun foliage in order to conduct their experiments. Current methods, such as cranes, climbers, and shotgun slugs are expensive and inefficient. A more practical, portable solution is needed for the future.

## Solution

Our solution is a remote controlled quad-copter equipped with an extendable arm. This arm will include an attachment capable of clipping and holding a sun foliage sample.

### Requirements

Portable  
Function in low light  
One operator  
Long range

### Specifications

2.4 GHz 8 Channel Radio  
with additional toggles  
900MHz video feed for on-  
board cameras  
Laptop for receiving/viewing  
video  
DC Battery charger and  
reserve batteries  
Laptop  
LEDs



### Requirements

Strong  
Easy to extend  
Variable extension length  
Easy to cut  
Ability to retain clipped  
sample

## Arm Specifications

DC Motors  
Worm Gears and racks  
Nut and bolts  
C-Shape plastic tubing  
Cut-and-hold sheers

