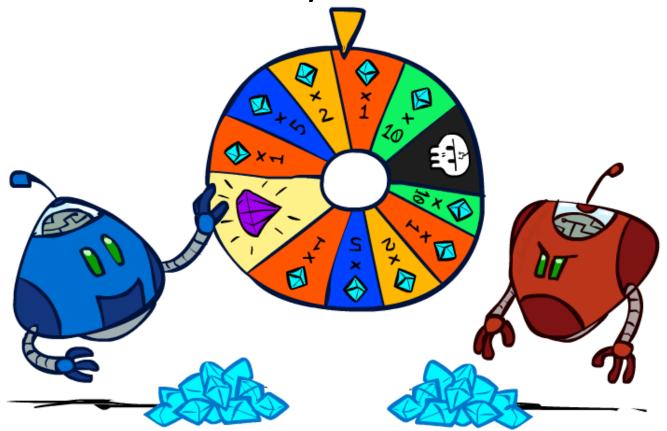
CS 188: Artificial Intelligence

Uncertainty and Utilities

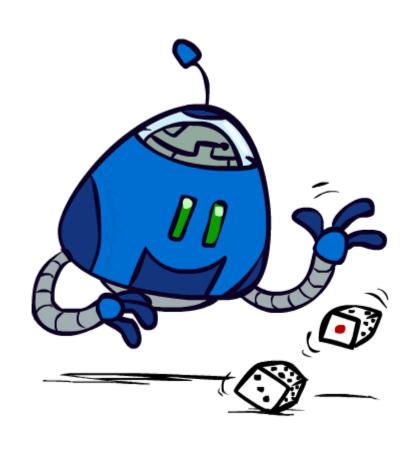


Instructors: Fatemeh Mansoori

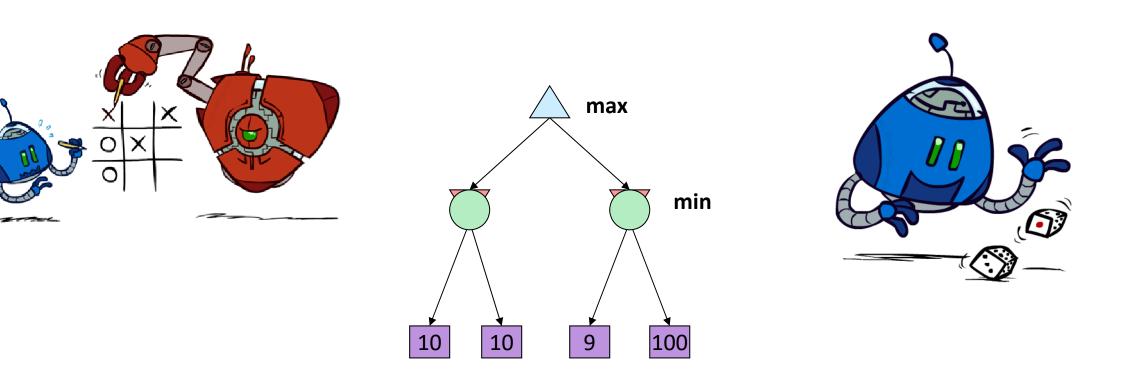
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[These slides were created by Dan Klein, Pieter Abbeel for CS188 Intro to AI at UC Berkeley (ai.berkeley.edu).]

Uncertain Outcomes



Worst-Case vs. Average Case



Idea: Uncertain outcomes controlled by chance, not an adversary!

Expectimax Search

Why wouldn't we know what the result of an action will be?

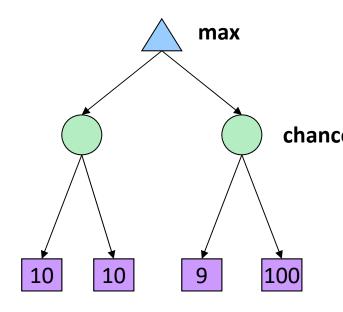
- Explicit randomness: rolling dice
- Unpredictable opponents: the ghosts respond randomly
- Actions can fail: when moving a robot, wheels might slip

Values should reflect average-case (expectimax) outcomes, not worst-case (minimax) outcomes

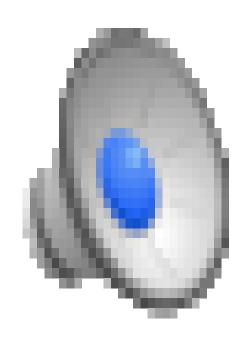
Expectimax search: compute the average score under optimal play

- Max nodes as in minimax search
- Chance nodes are like min nodes but the outcome is uncertain
- Calculate their expected utilities
- I.e. take weighted average (expectation) of children

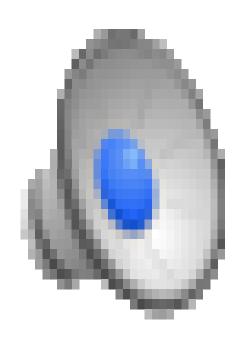
Later, we'll learn how to formalize the underlying uncertainresult problems as Markov Decision Processes



Video of Demo Minimax vs Expectimax (Min)



Video of Demo Minimax vs Expectimax (Exp)



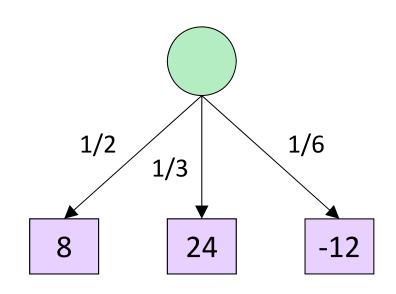
Expectimax Pseudocode

def value(state): if the state is a terminal state: return the state's utility if the next agent is MAX: return max-value(state) if the next agent is EXP: return exp-value(state) f max-value(state): def exp-value(state): initialize $v = -\infty$ initialize v = 0for each successor of state: for each successor of state: v = max(v, value(successor)) p = probability(successor return v v += p * value(successor) return v

Expectimax Pseudocode

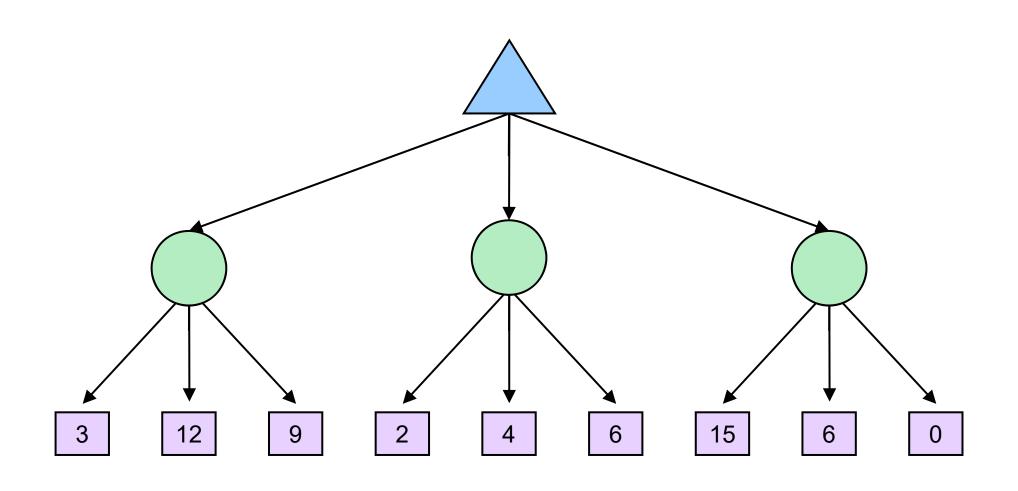
def exp-value(state): initialize v = 0 for each successor of state: p = probability(successor) v += p * value(successor)

return v

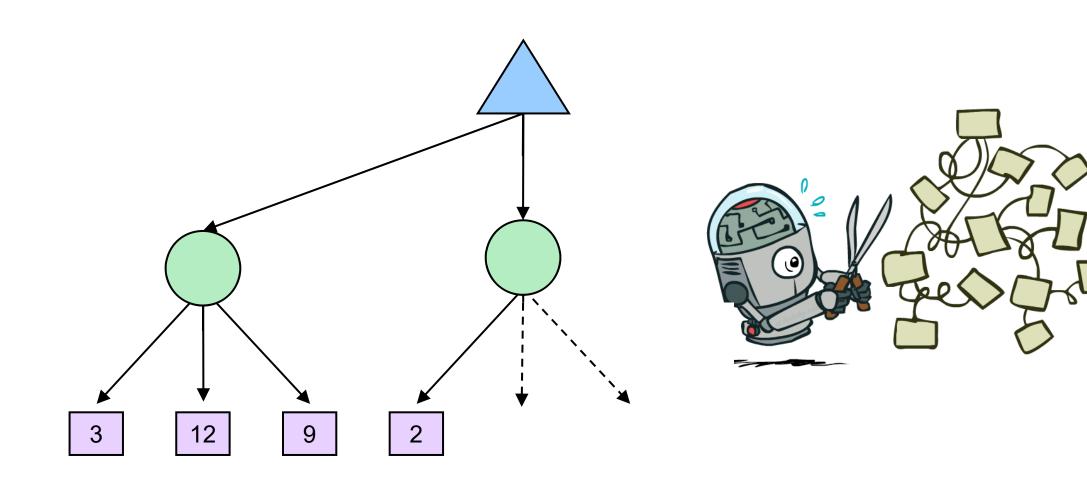


$$v = (1/2)(8) + (1/3)(24) + (1/6)(-12) = 10$$

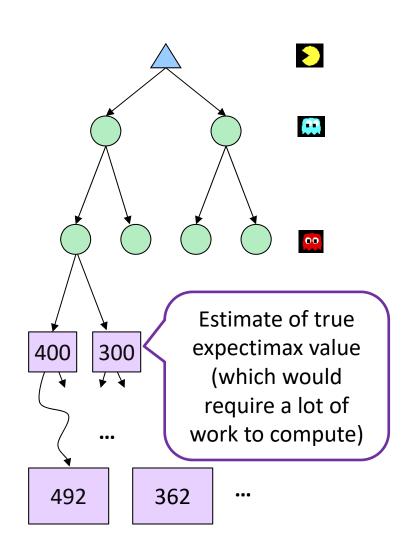
Expectimax Example



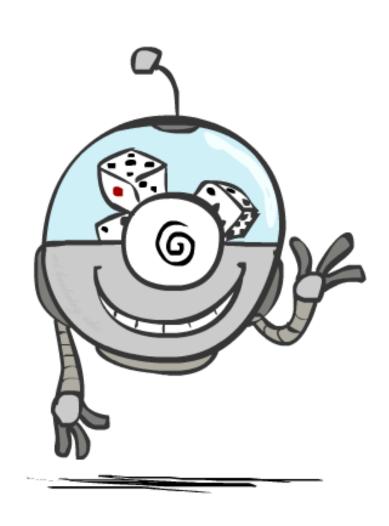
Expectimax Pruning?



Depth-Limited Expectimax



Probabilities



Reminder: Probabilities

A random variable represents an event whose outcome is unknown A probability distribution is an assignment of weights to outcomes

Example: Traffic on freeway

- Random variable: T = whether there's traffic
- Outcomes: T in {none, light, heavy}
- Distribution: P(T=none) = 0.25, P(T=light) = 0.50, P(T=heavy) = 0.25

Some laws of probability (more later):

- Probabilities are always non-negative
- Probabilities over all possible outcomes sum to one

As we get more evidence, probabilities may change:

- P(T=heavy) = 0.25, P(T=heavy | Hour=8am) = 0.60
- We'll talk about methods for reasoning and updating probabilities later



0.25



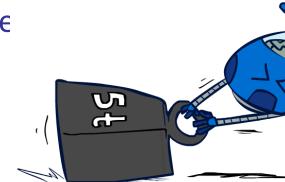
0.50



0.25

Reminder: Expectations

The expected value of a function of a random variable is the average, weighted by the probability distribution over outcomes



Example: How long to get to the airport?

Time: 20 min

Probability:

Χ

0.25

+

30 min

Χ

0.50

+

60 min

Χ

0.25



35 min





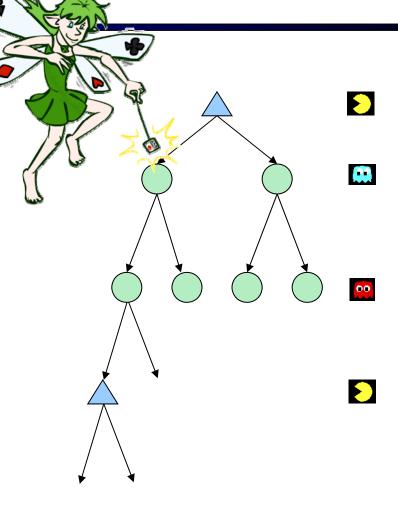


What Probabilities to Use?

In expectimax search, we have a probabilistic model of how the opponent (or environment) will behave in any state

- Model could be a simple uniform distribution (roll a die)
- Model could be sophisticated and require a great deal of computation
- We have a chance node for any outcome out of our control: opponent or environment
- The model might say that adversarial actions are likely!

For now, assume each chance node magically comes along with probabilities that specify the distribution over its outcomes

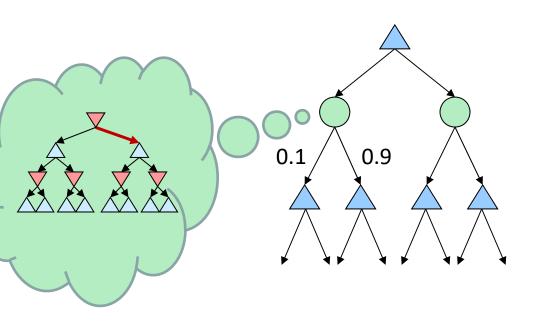


Having a probabilistic belief about another agent's action does not muthat the agent is flipping any coin

Quiz: Informed Probabilities

Let's say you know that your opponent is actually running a depth 2 minimax, using the result 80% of the time, and moving randomly otherwise

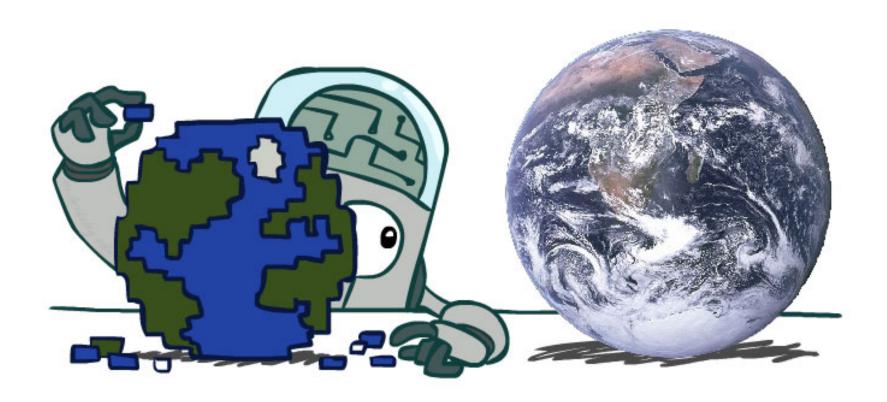
Question: What tree search should you use?



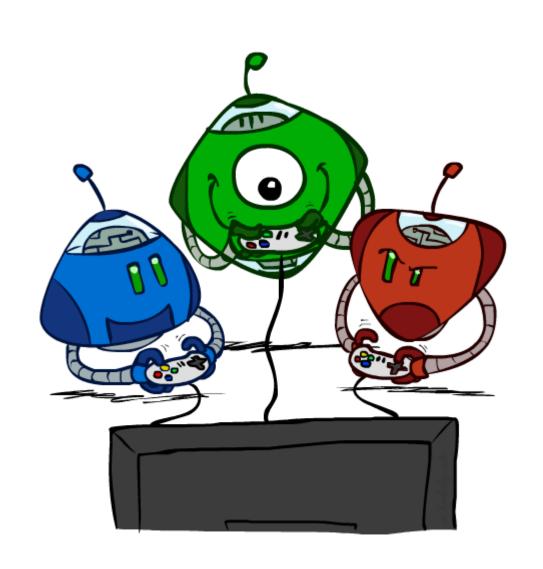
Answer: Expectimax!

- To figure out EACH chance node's probabilities you have to run a simulation of your oppone
- This kind of thing gets very slow very quickly

Modeling Assumptions



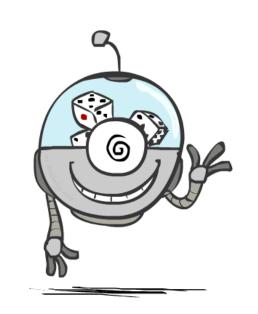
Other Game Types

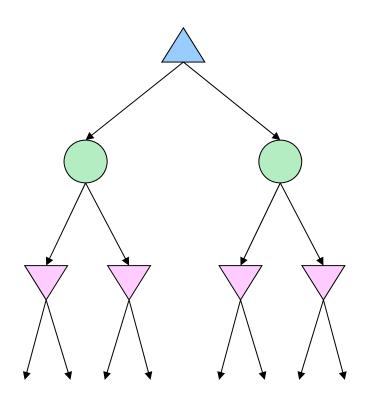


Mixed Layer Types

E.g. Backgammon Expectiminimax

- Environment is an extra "random agent" player that moves after each min/max agent
- Each node
 computes the
 appropriate
 combination of its
 children









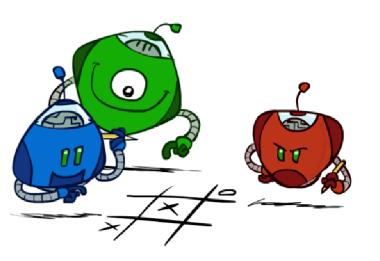


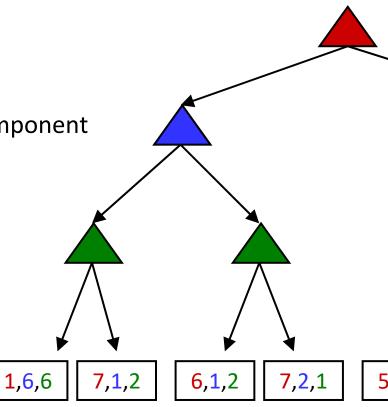


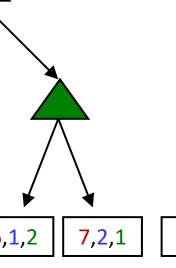
What if the game is not zero-sum, or has multiple players?

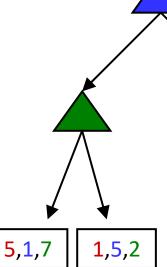
Generalization of minimax:

- Terminals have utility tuples
- Node values are also utility tuples
- Each player maximizes its own component
- Can give rise to cooperation and competition dynamically...





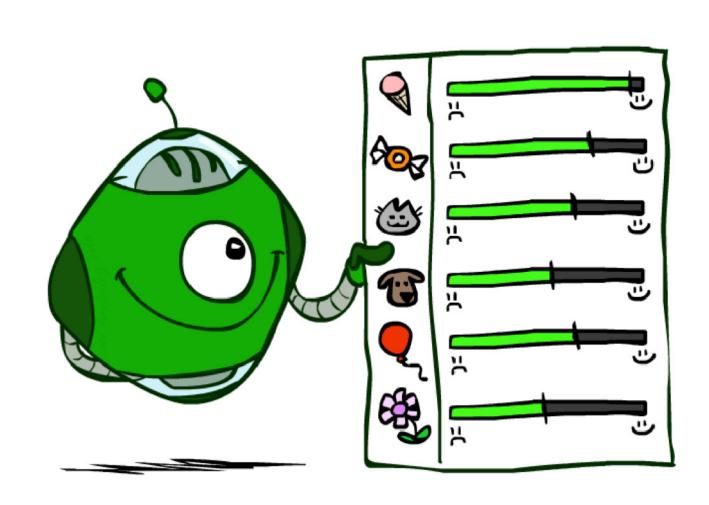




5,2,5

7,7,1

Utilities



Maximum Expected Utility

Why should we average utilities? Why not minimax?

Principle of maximum expected utility:

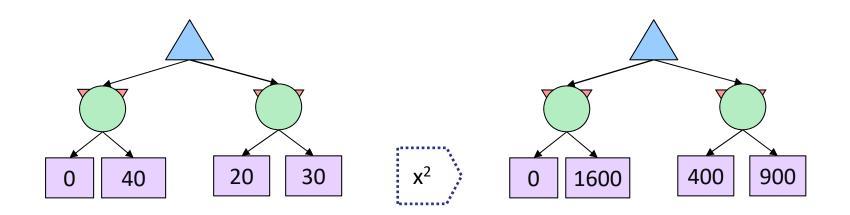
 A rational agent should chose the action that maximizes its expected utility, given its knowledge



Questions:

- Where do utilities come from?
- How do we know such utilities even exist?
- How do we know that averaging even makes sense?
- What if our behavior (preferences) can't be described by utilities?

What Utilities to Use?



For worst-case minimax reasoning, terminal function scale doesn't matter

- We just want better states to have higher evaluations (get the ordering right)
- We call this insensitivity to monotonic transformations

For average-case expectimax reasoning, we need magnitudes to be meaningful

Utilities

Utilities are functions from outcomes (states of the world) to real numbers that describe an agent's preferences

Where do utilities come from?

- In a game, may be simple (+1/-1)
- Utilities summarize the agent's goals
- Theorem: any "rational" preferences can be summarized as a utility function

We hard-wire utilities and let behaviors emerge

- Why don't we let agents pick utilities?
- Why don't we prescribe behaviors?







Utilities: Uncertain Outcomes

