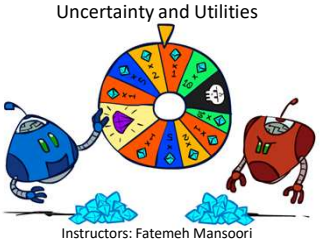
CS 188: Artificial Intelligence

Uncertainty and Utilities



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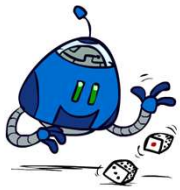
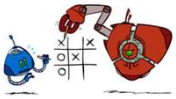
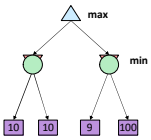
Uncertain Outcomes



Worst-Case vs. Average Case

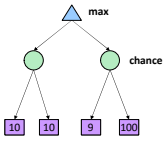




Idea: Uncertain outcomes controlled by chance, not an adversary!

Expectimax Search

- Why wouldn't we know what the result of an action will be?
  - Explicit randomness: rolling dice
  - Unpredictable opponents: the ghosts respond randomly
  - Actions can fail: when moving a robot, wheels might slip
- Values should reflect average-case (expectimax) outcomes, not worst-case (minimax) outcomes
- Expectimax search: compute the average score under optimal play
  - Max nodes as in minimax search
  - Chance nodes are like min nodes but the outcome is uncertain
  - Calculate their expected utilities
  - I.e. take weighted average (expectation) of children
- Later, we'll learn how to formalize the underlying uncertain-result problems as Markov Decision Processes



[Demo: min vs exp (L7D1,2)]

Video of Demo Minimax vs Expectimax (Min)

Video of Demo Minimax vs Expectimax (Exp)

Expectimax Pseudocode

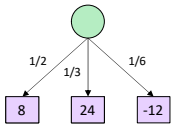
```
def value(state):
    if the state is a terminal state: return the state's utility
    if the next agent is MAX: return max-value(state)
    if the next agent is EXP: return exp-value(state)
```

```
def max-value(state):
    initialize v = -∞
    for each successor of state:
        v = max(v, value(successor))
    return v
```

```
def exp-value(state):
    initialize v = 0
    for each successor of state:
        p = probability(successor)
        v += p * value(successor)
    return v
```

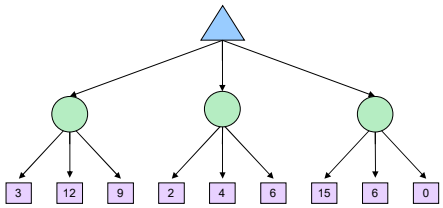
Expectimax Pseudocode

```
def exp-value(state):
    initialize v = 0
    for each successor of state:
        p = probability(successor)
        v += p * value(successor)
    return v
```

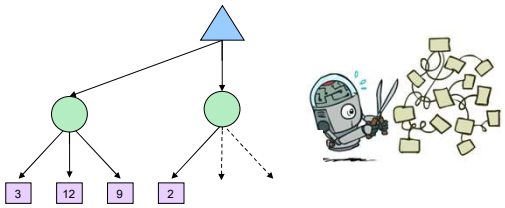


v = (1/2) (8) + (1/3) (24) + (1/6) (-12) = 10

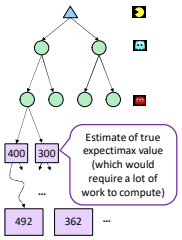
Expectimax Example



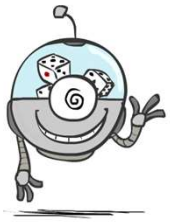
Expectimax Pruning?



Depth-Limited Expectimax



Probabilities



Reminder: Probabilities

- A random variable represents an event whose outcome is unknown
- A probability distribution is an assignment of weights to outcomes

- Example: Traffic on freeway
  - Random variable: T = whether there's traffic
  - Outcomes: T in {none, light, heavy}
  - Distribution: P(T=none) = 0.25, P(T=light) = 0.50, P(T=heavy) = 0.25

- Some laws of probability (more later):
  - Probabilities are always non-negative
  - Probabilities over all possible outcomes sum to one

- As we get more evidence, probabilities may change:
  - P(T=heavy) = 0.25, P(T=heavy | Hour=8am) = 0.60
  - We'll talk about methods for reasoning and updating probabilities later


0.25


0.50


0.25

Reminder: Expectations

- The expected value of a function of a random variable is the average, weighted by the probability distribution over outcomes

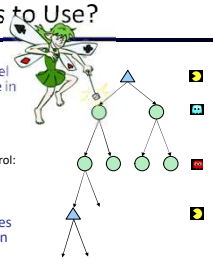
- Example: How long to get to the airport?

Time:	20 min	+	30 min	+	60 min	→ 35 min
	x		x		x	
Probability:	0.25		0.50		0.25	

What Probabilities to Use?

- In expectimax search, we have a probabilistic model of how the opponent (or environment) will behave in any state
  - Model could be a simple uniform distribution (roll a die)
  - Model could be sophisticated and require a great deal of computation
  - We have a chance node for any outcome out of our control: opponent or environment
  - The model might say that adversarial actions are likely!

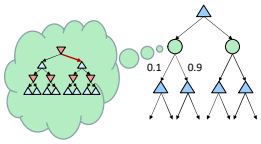
- For now, assume each chance node magically comes along with probabilities that specify the distribution over its outcomes



Having a probabilistic belief about another agent's action does not mean that the agent is flipping any coins!

Quiz: Informed Probabilities

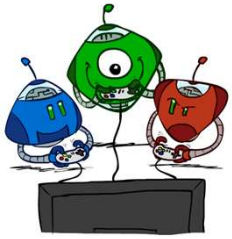
- Let's say you know that your opponent is actually running a depth 2 minimax, using the result 80% of the time, and moving randomly otherwise
- Question: What tree search should you use?



- Answer: Expectimax!
  - To figure out EACH chance node's probabilities, you have to run a simulation of your opponent
  - This kind of thing gets very slow very quickly

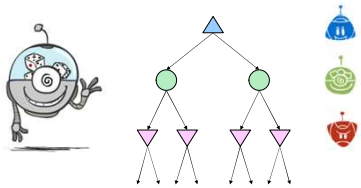
Modeling Assumptions

Other Game Types



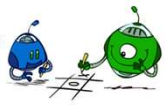
Mixed Layer Types

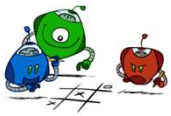
- E.g. Backgammon
- Expectiminimax
  - Environment is an extra "random agent" player that moves after each min/max agent
  - Each node computes the appropriate combination of its children

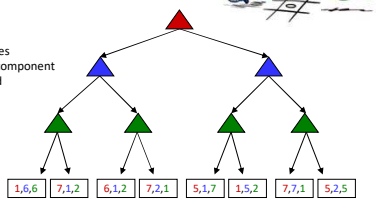


Multi-Agent Utilities

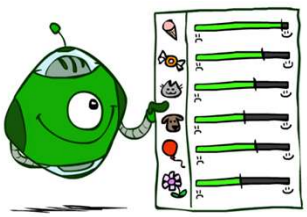
- What if the game is not zero-sum, or has multiple players?
- Generalization of minimax:
  - Terminals have utility tuples
  - Node values are also utility tuples
  - Each player maximizes its own component
  - Can give rise to cooperation and competition dynamically…







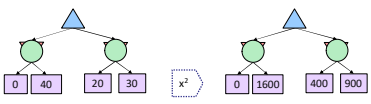
Utilities



Maximum Expected Utility

- Why should we average utilities? Why not minimax?
- Principle of maximum expected utility:
  - A rational agent should chose the action that maximizes its expected utility, given its knowledge
- Questions:
  - Where do utilities come from?
  - How do we know such utilities even exist?
  - How do we know that averaging even makes sense?
  - What if our behavior (preferences) can't be described by utilities?

What Utilities to Use?



- For worst-case minimax reasoning, terminal function scale doesn't matter
  - We just want better states to have higher evaluations (get the ordering right)
  - We call this insensitivity to monotonic transformations
- For average-case expectimax reasoning, we need *magnitudes* to be meaningful

Utilities

- Utilities are functions from outcomes (states of the world) to real numbers that describe an agent's preferences
- Where do utilities come from?
  - In a game, may be simple (+1/-1)
  - Utilities summarize the agent's goals
  - Theorem: any "rational" preferences can be summarized as a utility function
- We hard-wire utilities and let behaviors emerge
  - Why don't we let agents pick utilities?
  - Why don't we prescribe behaviors?

Utilities: Uncertain Outcomes