Message Passing

Loïc Guégan

Adapted from P. Ha @ UiT, K. Li @ Princeton, A. S. Tanenbaum @ 2008, A. Silberschatz @ 2009 and B. Wilkinson @ 2004

UiT The Arctic University of Norway

Spring - 2024

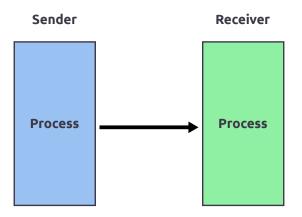
Outline

- What is message passing ?
 - Semantics
 - How to use
- How to implement message passing?
 - ► Implementation issues
- Examples of message passing systems

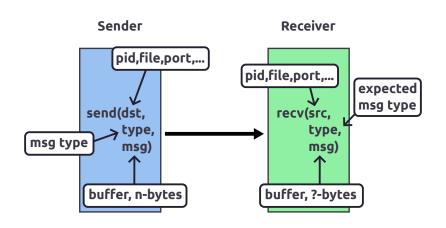
Overview of communication mechanisms

Programs	Concurrent Programs
Higher- level API	Shared Variables Message Passing Locks Semaphores Monitors Send/Receive
Hardware	Load/Store Disable Ints Test&Set Comp&Swap

Big picture



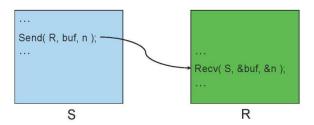
Send and Receive primitives



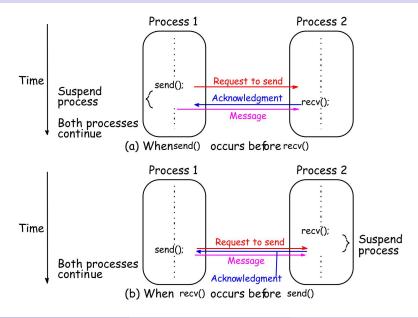
Many ways to design the message passing API

Synchronous Message Passing

- Synchronizing processes
 - Sender: signal the receiver process that a particular event happens
 - Receiver: blocked until the event has happened
- Moving data between processes
 - Sender: send data to the receiver when data is ready
 - ▶ Receiver: collect data when the data has arrived and process is ready



Synchronous send() and recv() using 3-way protocol



Example: Producer-Consumer

```
Producer() {
    ...
    while (1) {
        produce item;
        recv(Consumer, &credit);
        send(Consumer, item);
    }
}
```

```
Consumer() {
    ...
    for (i=0; i<N; i++)
        send(Producer, credit);
    while (1) {
        recv(Producer, &item);
        send(Producer, credit);
        consume item;
    }
}</pre>
```

- Questions
 - ▶ Would it work with multiple producers and 1 consumer?
 - ▶ Would it work with 1 producer and multiple consumers?
 - What about multiple producers and multiple consumers?

Summary

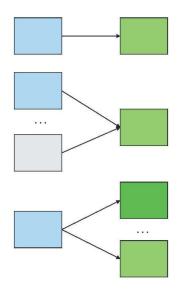
- Mechanism for processes to communicate and to synchronize their actions
- Allows to avoid using shared variables
- If P and Q wish to communicate:
 - Establish a communication link between them
 - Exchange messages via send/receive
- Layers:
 - physical (e.g. main memory, hardware bus)
 - 2 logical (e.g. logical properties)
 - ★ Direct vs. indirect communication
 - ★ Synchronous vs. asynchronous communication
 - ★ Automatic vs. explicit buffering

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Implementation issues

- Buffering messages
- Direct vs. indirect
- Asynchronous vs. synchronous
- How to handle exceptions?

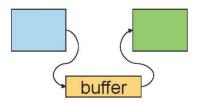


Buffering messages

- No buffering
 - ► Sender must wait until the receiver receives the message
 - Rendezvous on each message
- Bounded buffer
 - Finite size
 - Sender is blocked on buffer full



- Unbounded buffer
 - "Infinite" size
 - Sender is never blocked

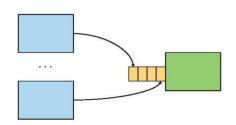


Direct communication

- Processes must name each other explicitly:
 - send(P,message) send a message to process P
 - ► receive(Q,message) receive a message from process Q
- Properties of communication link
 - ▶ A link is associated with exactly one pair of communicating processes
 - Links are established automatically

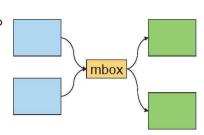
Direct communication with buffer

- A single buffer at the receiver
 - More than one process may send messages to the receiver
 - recv(ANY,msg)
 - To broadcast a message, a sender must send separate messages to receivers
- A buffer at each sender
 - A sender may send a message to multiple receivers
 - To get a message, it requires searching through the whole buffer
- What if process id/name changes?



Indirect communication

- Use mailbox as the abstraction
 - send(A, message) send a message to mailbox A
 - recv(A, message) receive a message from mailbox A
 - Require create/destroy a mailbox
 - ► Allow many-to-many communication
- Mailbox sharing
 - ▶ P1, P2, and P3 share mailbox A. P1 sends, P2 and P3 receive.
 - Who gets the message?
- Mailbox vs. pipe
 - A mailbox allows many to many communication
 - A pipe implies one sender and one receiver



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- Message Passing
- Implementation issues
 - Buffering
 - Indirection
 - ▶ Blocking vs. nonblocking
 - Exceptions

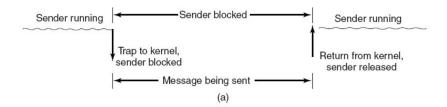
Blocking vs. Nonblocking: Send

- Blocking
 - Initiate data transfer
 - Fither:
 - Block until data is out of its source memory (buffering)
 - Block until data is received (no buffering)
- Nonblocking
 - Initiate data transfer and return
 - Completion
 - Require applications to check status
 - ★ Notify or signal the application

```
send(dest, type, msg)
msg transfer resource
```

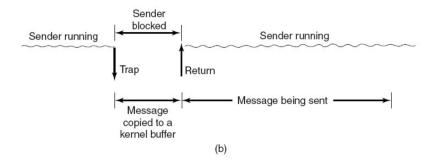
```
status = async_send( dest, type, msg )
...
if !send_complete( status )
    wait for completion;
...
use msg data structure;
...
```

Blocking versus Nonblocking: Send (2)



A blocking send call

Blocking versus Nonblocking: Send (3)



A nonblocking send call

Blocking vs. Nonblocking: Receive

- Blocking
 - ▶ Block until a message is available
- Nonblocking
 - Return either a valid message or a null
 - Null: probe(src)

msg transfer resource

```
recv( src, type, msg )
```

```
status = async_recv( src, type, msg );
if ( status == SUCCESS )
    consume msg;
...
while ( probe(src) != HaveMSG )
    wait for msg arrival
recv( src, type, msg );
consume msg;
```

Event Handler vs. Receive

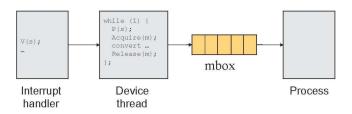
- hrecv(src, type, msg, func)
 - msg is an arg of func
 - Execute "func" on a message arrival

- Which one is more powerful?
 - Recv with a thread can emulate a Handler
 - Handler can be used to emulate recv by using Monitor

```
void func( char * msg ) {
     hrecv( src, type, msg, func)
     ...
                           program
            Create a thread
while(1) {
  recv(src,type, msg);
  func(msg);
```

Example: Keyboard Input

- How do you implement keyboard input?
 - Need an interrupt handler
 - Generate a mbox message from the interrupt handler
- Suppose a keyboard device thread converts input characters into an mbox message
 - How would you synchronize between the keyboard interrupt handler and device thread?
 - ▶ How can a device thread convert input into mbox messages?



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Exception: Process Termination

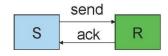
- R waits for a message from S, but S has terminated
 - Problem: R may be blocked forever



- S sends a message to R, but R has terminated
 - Problem: S has no buffer and will be blocked forever



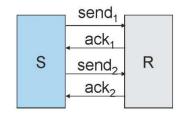
Exception: Message Loss



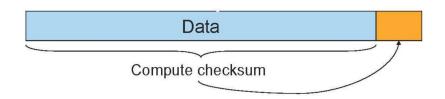
- Use ack and timeout to detect and retransmit a lost message
 - Receiver sends an ack message for each message
 - Sender is blocked until an ack message is back or timeout status = send(dest, msg, timeout);
 - ▶ If timeout happens and no ack, sender retransmits the message
- Issues
 - Losing ack messages
 - Duplicates

Exception: Message Loss (2)

- Retransmission must handle
 - Duplicate messages on receiver side
 - Out-of-sequence ack messages on sender side
- Retransmission
 - Use sequence number for each message to identify duplicates
 - Remove duplicates on receiver side
 - Sender retransmits on an out-of-sequence ack
- Reduce ack messages
 - Bundle ack messages
 - Receiver sends NOACK messages: can be complex
 - ▶ Piggy-back acks in send messages



Exception: Message Corruption



Detection

- Compute a checksum over the entire message and send the checksum (e.g. CRC) as part of the message
- ► Recompute a checksum at receiver and compare with the checksum in the message

Correction

- Trigger retransmission
- ▶ Use correction codes (e.g. ECC) to recover

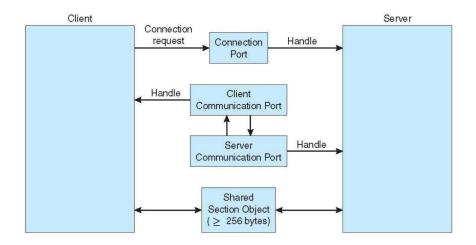
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Mach microkernel (Mac OS X)

- Mach communication is message based
 - System calls are messages
 - Each task gets two mailboxes at creation- Kernel and Notify
 - Only three system calls needed for message transfer msg_send(), msg_receive(), msg_rpc()
 - Mailboxes needed for communication, created via port_allocate()

Local Procedure Calls in Windows XP



References

- A. S. Tanenbaum, Modern Operating Systems.
- A. Silberschatz et. al., Operating System Concepts.
- B. Wilkinson et. al., Parallel Programming: Techniques and Applications Using Networked Workstations and Parallel Computers.
- B. Barney, "Message Passing Interface (MPI)", Livermore Computing.

Thanks for your attention!

Questions?