



FINAL EXAM IN INF-3201

Exam in : **INF-3201**
Date : **December 10, 2010**
Time : **09:00 – 13:00**
Place : **Åsgårdveien 9**

Approved remedies :
- **English dictionary**
- **English-Norwegian/Norwegian-English dictionary**

The exam contains 3 pages including this cover page

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Please give short and concise answers. State explicitly any assumptions you do.

1) Message-passing computing (20%)

- What is the difference between *synchronous* message passing routines and *asynchronous* message passing routines?
- What is the difference between *blocking* routines and *non-blocking* routines in MPI? When does a blocking send routine in MPI behave as a synchronous routine?
- What is collective communication in MPI?
- A master process divides a sequence of n numbers into p non-overlapping parts of n/p numbers each (assuming that n is divisible by p). It then distributes the p different parts to p slave processes using:
 - Case 1: p send() routines
 - Case 2: one scatter() routine

Let the communication time of a message with m data words be $T^{\text{comm}} = T^{\text{startup}} + m \cdot T^{\text{data}}$, where T^{startup} is the startup time and T^{data} is the transmission time to send one data word. Which case (1 or 2) will have shorter communication time? Explain your answer using T^{startup} and T^{data} .

2) Programming with shared memory (15%)

- What is “determinacy race”?
- What is Amdahl’s law? If the serial fraction of an application is 25%, what is the maximum speed-up of the application?
- Let T^p be the execution time of an application on P processors. Using Cilk++ to analyze an application, we get $T^1 = 24$ (i.e. work) and $T^\infty = 8$ (i.e. span). What is the maximum speed-up of the application on 4 processors? Explain your answer using the work law and the span law.

3) Parallelization strategies (10%)

- Give a short description of divide-and-conquer strategy.
- Give a short description of pipelined strategy.
- Present three types of computations under which pipelined strategy can provide increased execution speed.

4) Data-parallel computations (15%)

In data-parallel computations, segmented scan operations are useful building blocks. Let A and F be a data vector and a flag vector, respectively. Values 1 in the flag vector indicate the beginning of each segment.

- a) We execute the segmented scan operation with addition operator on vectors A and F given below.

Write correct values to the result vector *Segmented +-scan*.

A = [5 2 3 1 4 5 4 8]

F = [1 0 1 0 0 0 1 0]

Segmented +-scan = [? ? ? ? ? ? ? ?]

- b) How do we distribute the first element of each segment, given by vectors A and F above, to all other elements in the same segment using the segmented +-scan? Illustrate your answer by drawing relevant vectors.

5) Load balancing and Termination detection (10%)

- a) What are fundamental disadvantages of *static* load balancing compared with *dynamic* load balancing?
- b) Present the distributed termination conditions for a distributed computation at time t .

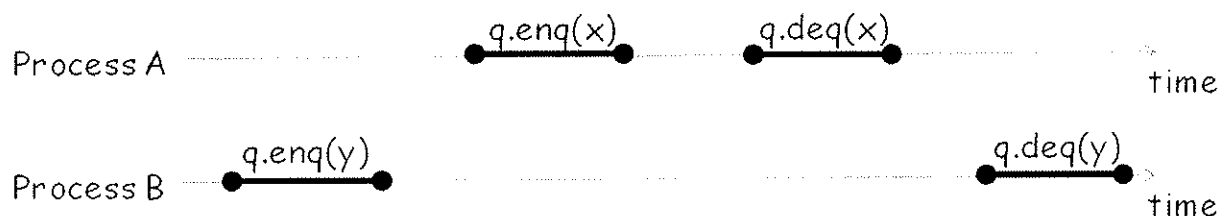
6) Distributed shared memory (15%)

- a) What is “distributed shared memory” (DSM)?
- b) In a page-based DSM using write-invalidation, one of the problems is to locate the owner of a given page p . Present concisely *four* solutions to the owner location problem, including their advantages/disadvantages.

7) Concurrent objects (15%)

Two processes A and B access a shared first-in first-out (FIFO) queue q as shown in the figure below. In the execution, process B enqueues y before process A enqueues x , and process A dequeues x before process B dequeues y .

- a) Is this execution sequentially consistent? Explain.
- b) Is this execution linearizable? Explain.



Good luck!